

ECE 470

Introduction to Robotics

Lab Manual

ver 2.5



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UR3 Python - ROS Interface

Contents

1	Introduction to the UR3	1
1.1	LAB 1 Week One	1
1.1.1	Important	1
1.1.2	Objectives	1
1.1.3	References	1
1.1.4	Pre-Lab	2
1.1.5	Task	2
1.1.6	Procedure	2
1.1.7	Report	3
1.1.8	Demo	3
1.1.9	Grading	3
1.2	LAB 1.5 Week Two, The Tower of Hanoi using the Teach Pendant	5
1.2.1	Important	5
1.2.2	Objectives	5
1.2.3	References	5
1.2.4	Pre-Lab	6
1.2.5	Task	6
1.2.6	Procedure	7
1.2.7	Report	7
1.2.8	Grading	8
2	The Tower of Hanoi with ROS	9
2.1	Important	9
2.2	Objectives	9
2.3	Pre-Lab	10
2.4	References	10
2.5	Task	11
2.6	Procedure	12
2.7	Lab2_exec.py Explained	13
2.7.1	Report	19
2.8	Demo	20
2.9	Grading	20

CONTENTS

3	Camera Sensing and Particle Filter	21
3.1	Important	21
3.2	Motivation	21
3.3	Objectives	22
3.4	References	23
3.5	Tasks	23
3.6	Procedure	24
3.6.1	Threshold camera image to distinguish only bright orange pixels	24
3.6.2	Use the OpenCV simpleBlobdetector library function to find the centroid in pixels of one or multiple circular orange blobs	26
3.6.3	Perspective Transform	27
3.6.4	Implement particle filter HW problem with real world vision measurements	30
3.7	Report	31
3.8	Demonstration	32
3.9	Grading	32
4	Forward Kinematics	33
4.1	Important	33
4.2	Objectives	33
4.3	References	33
4.4	Tasks	33
4.4.1	Theoretical Solution	33
4.4.2	Physical Implementation	34
4.4.3	Comparison	34
4.5	Procedure	34
4.5.1	Theoretical Solution	34
4.5.2	Implementation on UR3	37
4.5.3	Comparison	38
4.6	Report	38
4.7	Demonstration	39
4.8	Grading	39
5	Inverse Kinematics	42
5.1	Important	42
5.2	Objectives	42
5.3	Reference	42
5.4	Tasks	42
5.4.1	Solution Derivation	42
5.4.2	Implementation	46
5.5	Procedure	46
5.6	Report	48
5.7	Demo	49
5.8	Grading	49

CONTENTS

6	Camera Sensing and Integration into the World Frame for a Pick and Place Task	50
6.1	Important	50
6.2	Objectives	50
6.3	References	51
6.4	Tasks	51
6.4.1	Color Thresholding and Object Centroids	51
6.4.2	Camera Setup	51
6.4.3	Pick and Place	52
6.5	Procedure	52
6.5.1	Threshold camera image to distinguish the colors of choice	52
6.5.2	Use the OpenCV simpleBlobDetector library function to find the centroids of 2 Pink and 2 Green Blocks	54
6.5.3	Camera Setup	55
6.5.4	Pick and Place	58
6.6	Report	59
6.7	Demo	60
6.8	Grading	60
A	ROS Programming with Python	61
A.1	Overview	61
A.2	ROS Concepts	61
A.3	Before we start.. . . .	62
A.4	Create your own workspace	64
A.5	Running a Node	64
A.6	More Publisher and Subscriber Tutorial	65
B	V-rep Simulation	66
B.1	Download and Install V-rep on your PC	66
B.2	Setup remote API to interface with V-rep	67
B.3	Add a robot in your scene	68
B.4	Important notes!!	68
C	Notes on Computer Vision	70
C.1	OpenCV	70
C.1.1	Camera Driver	70
C.1.2	Accessing Image Data	70
C.1.3	Some Useful OpenCV Functions	73
C.2	Camera Calibration	74
C.2.1	Camera Placement and Fish Eye Correction	74
C.3	Simplified Perspective Transform	77

Preface

This is a set of laboratory assignments designed to complement the introductory robotics lecture taught in the College of Engineering at the University of Illinois at Urbana-Champaign. Together, the lecture and labs introduce students to robot manipulators and computer vision along with the Robot Operating System (ROS) and serve as the foundation for more advanced courses on robot dynamics, control and computer vision. The course is cross-listed in three departments (Electrical & Computer Engineering, Aerospace Engineering, and Mechanical Science & Engineering) and consequently includes students from a variety of academic backgrounds.

For success in the laboratory, each student should have completed a course in linear algebra and be comfortable with three-dimensional geometry. In addition, it is imperative that all students have completed a freshman-level course in computer programming. *MODERN ROBOTICS MECHANICS, PLANNING, AND CONTROL* (Kevin M. Lynch and Frank C. Park, 2017) is required for the lectures and will be used as a reference for many of the lab assignments. We will hereafter refer to the textbook as *MR* in this lab manual.

These laboratories are simultaneously challenging, stimulating, and enjoyable. It is the author's hope that you, the reader, share a similar experience.

Enjoy the course!