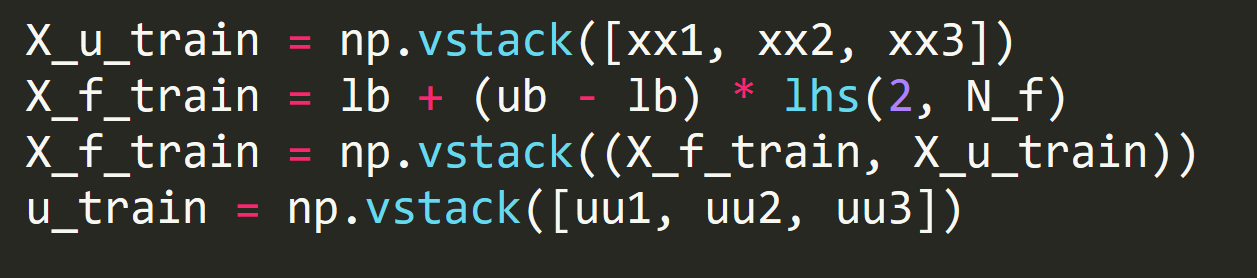
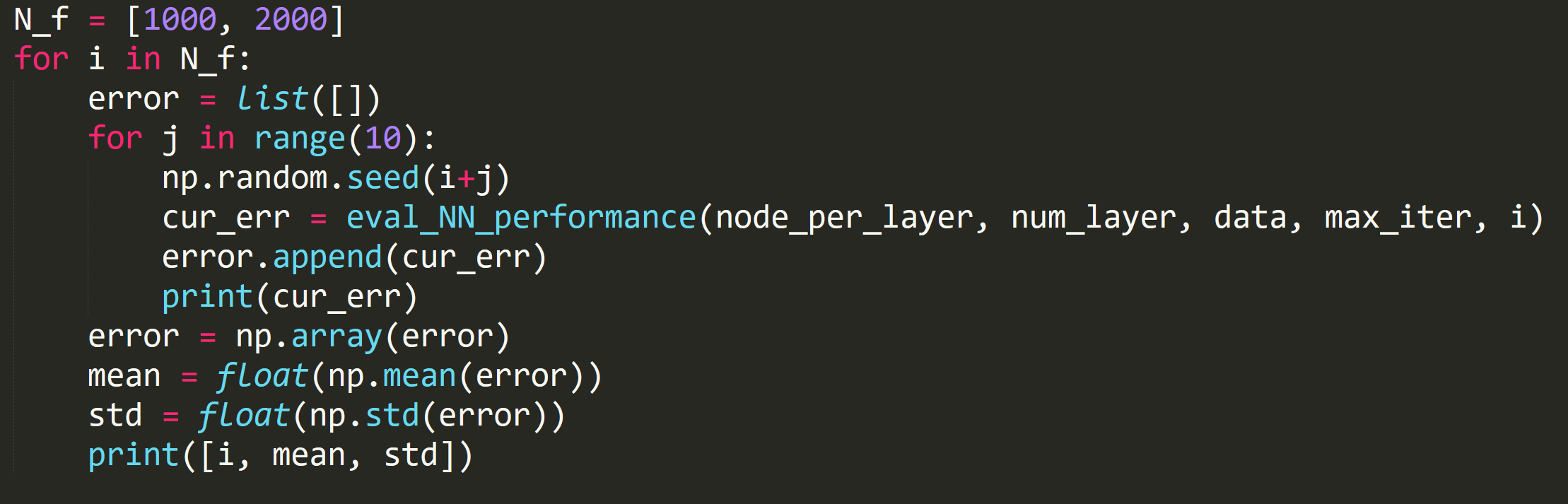
## 1. Burgers\_Nf

collocation points Nf

run Burgers\_Nf.py



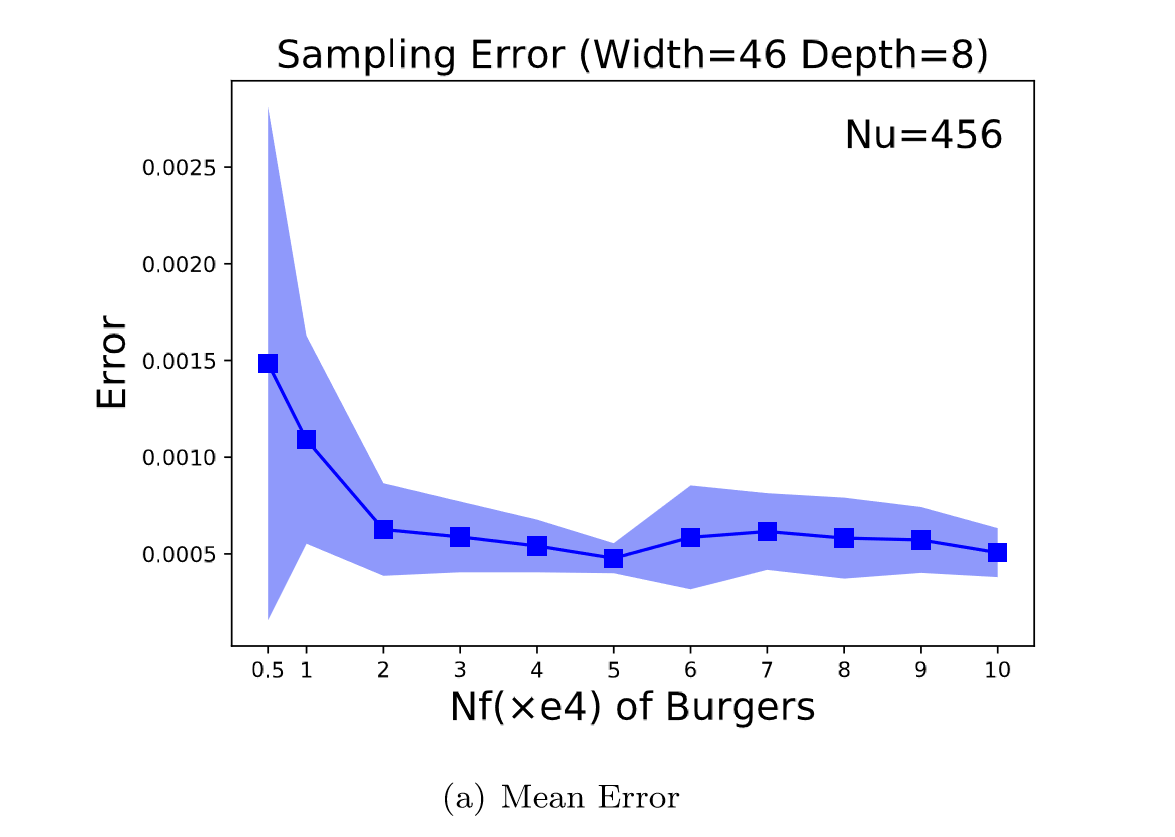


N\_f 传入的是list

输出[Nf, mean, std]

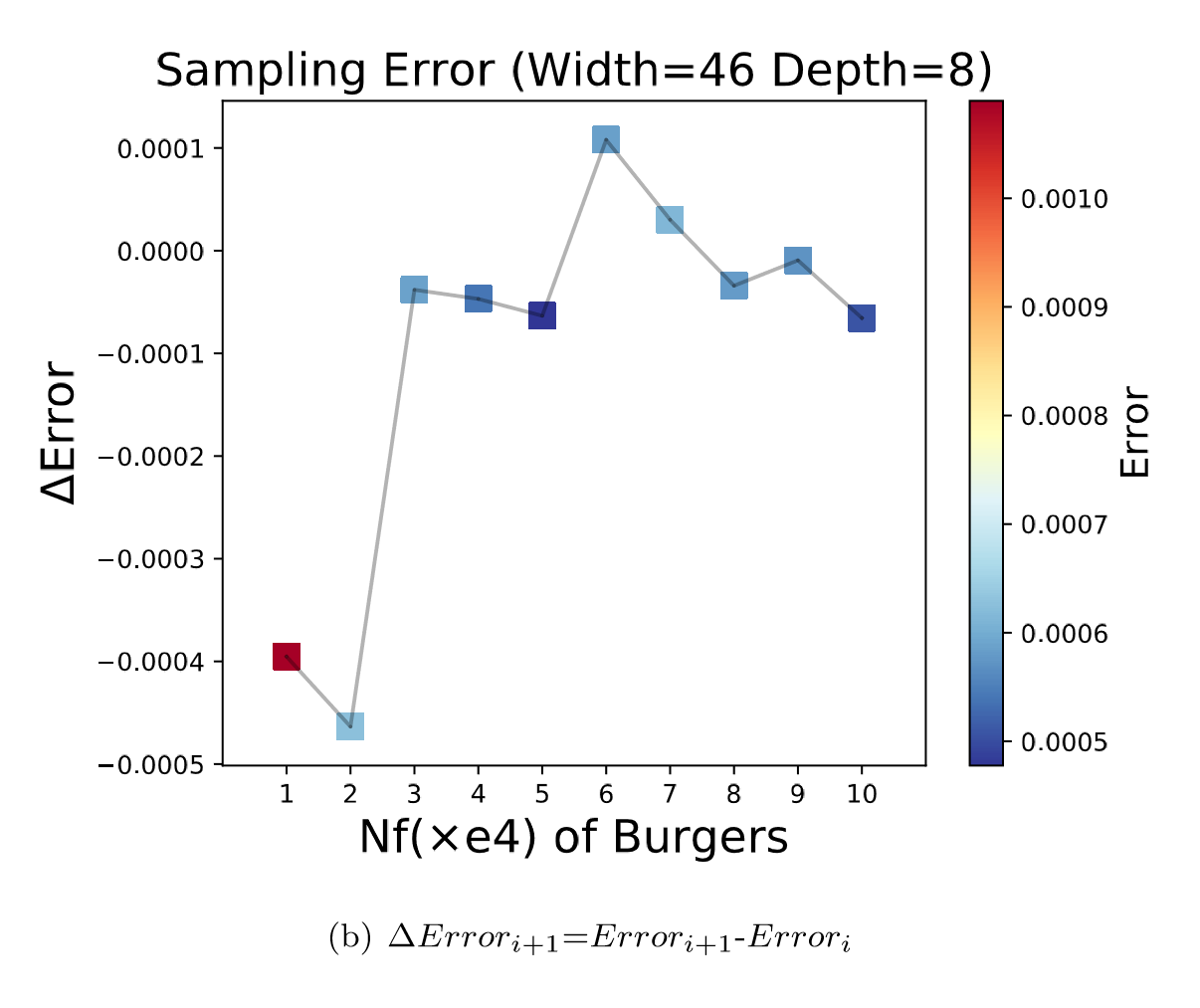
将输出复制到Plot文件夹下的txt就可以画图

**Nf.py** :



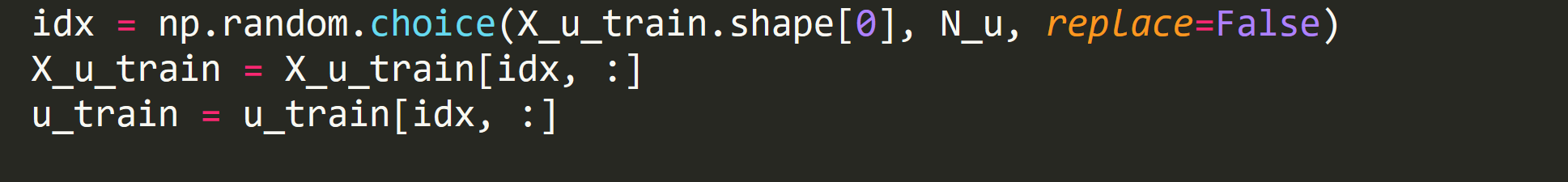
**Delta\_Nf.py :**

**误差的差值**

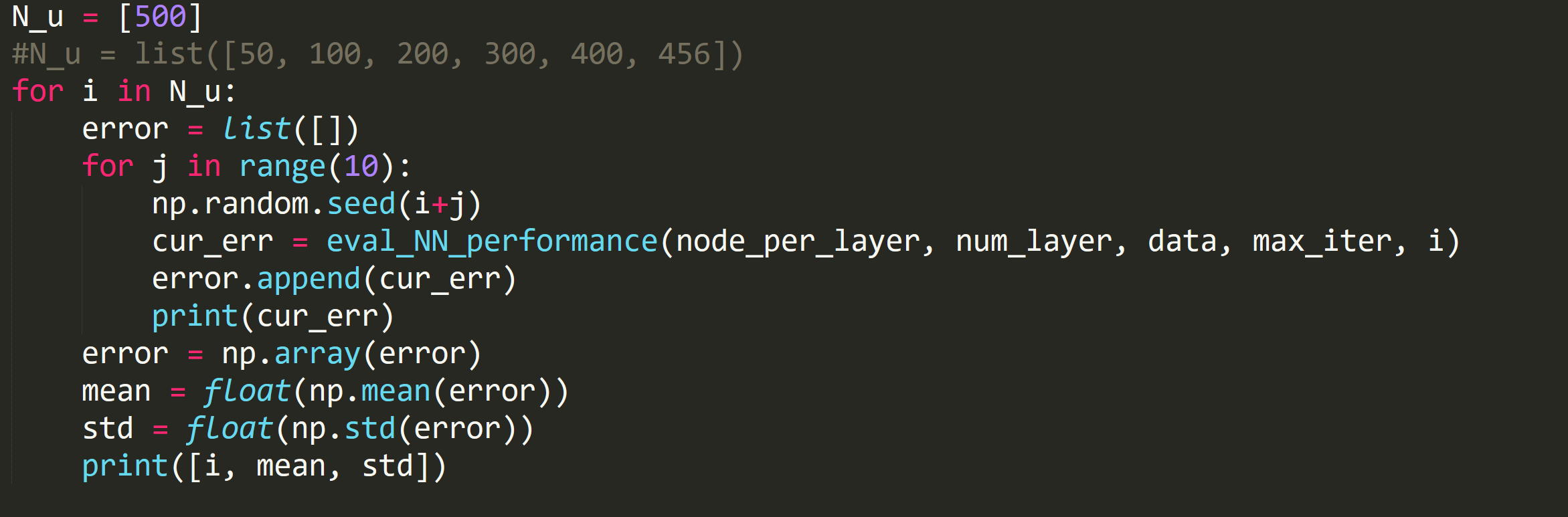


## 2. Burgers\_Nu

initial and boundary training data Nu



从456个初始点中取Nu个点

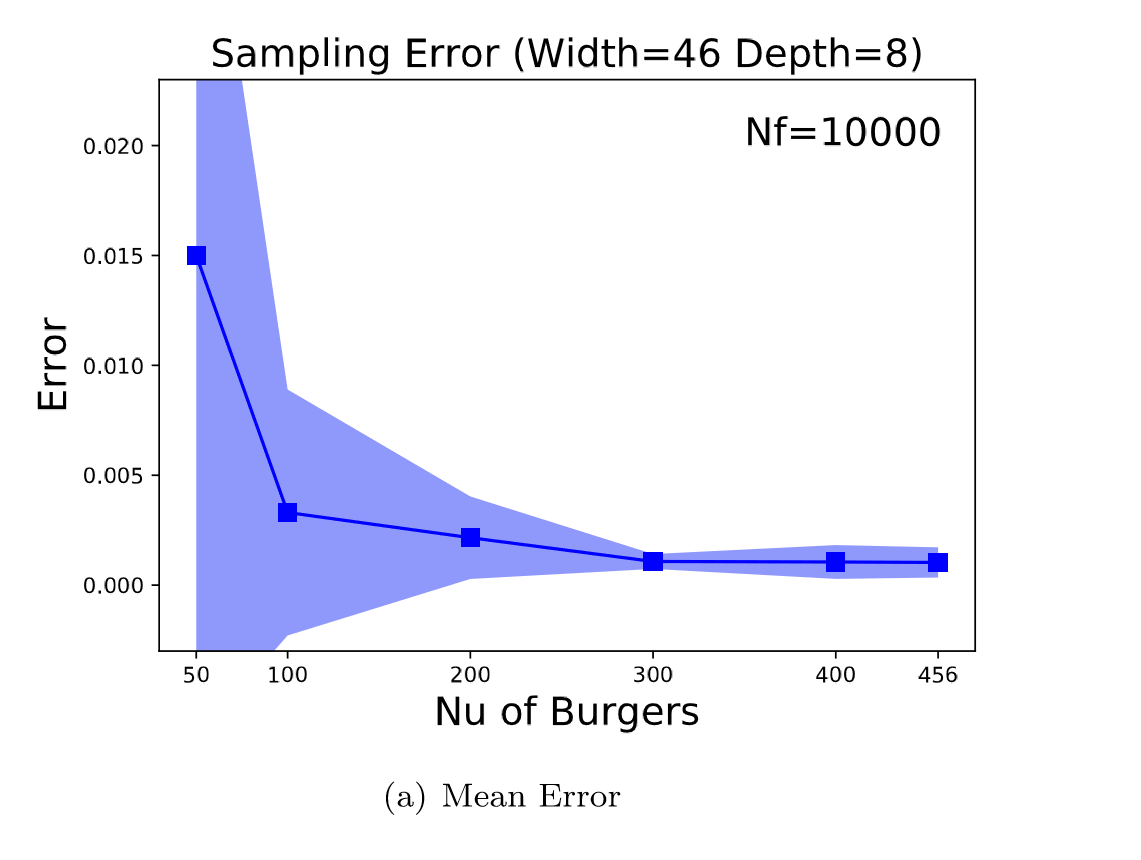


Nu 传入的是list

输出[Nu, mean, std]

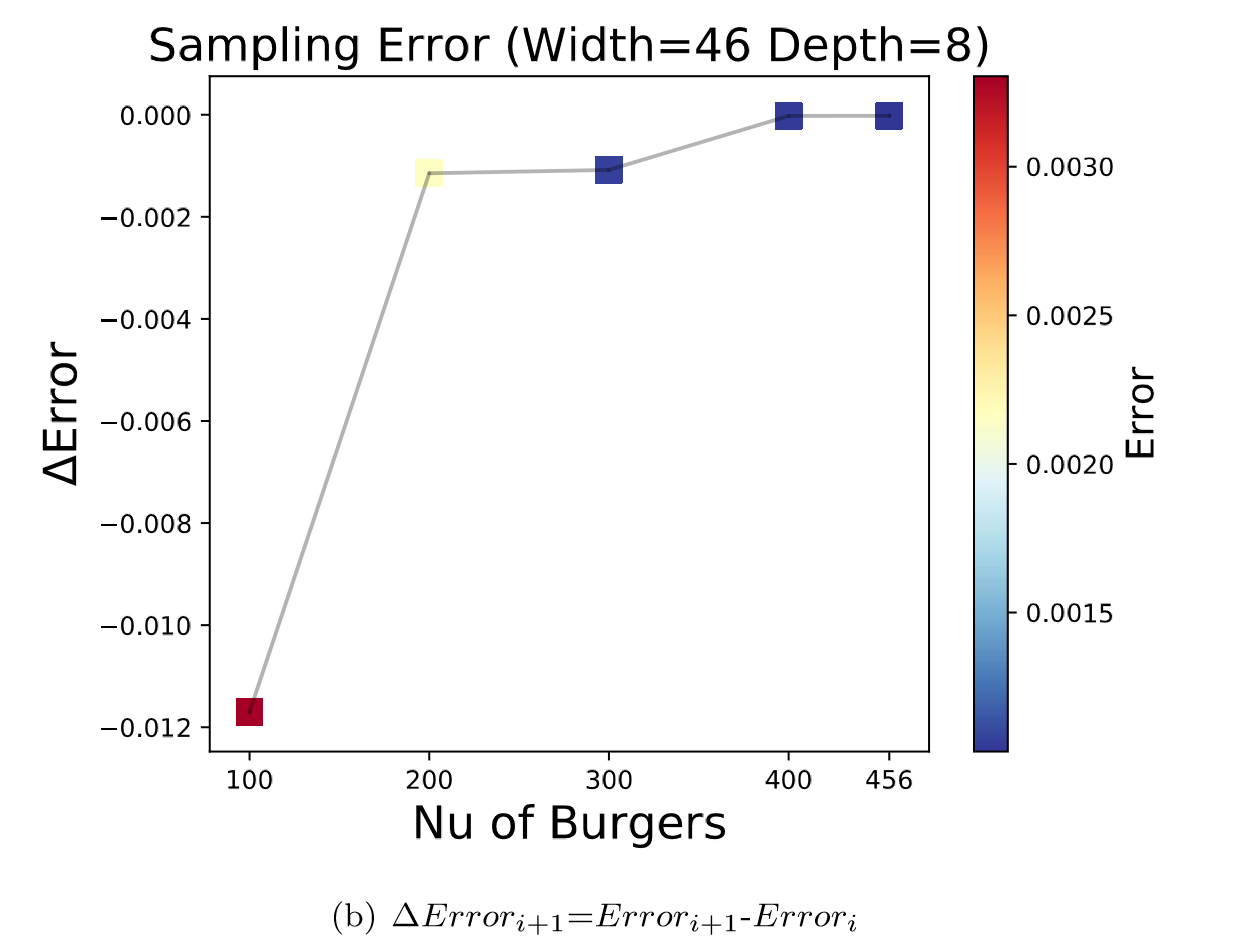
将输出复制到Plot文件夹下的txt就可以画图

**Nu.py** :



**Delta\_Nu.py :**

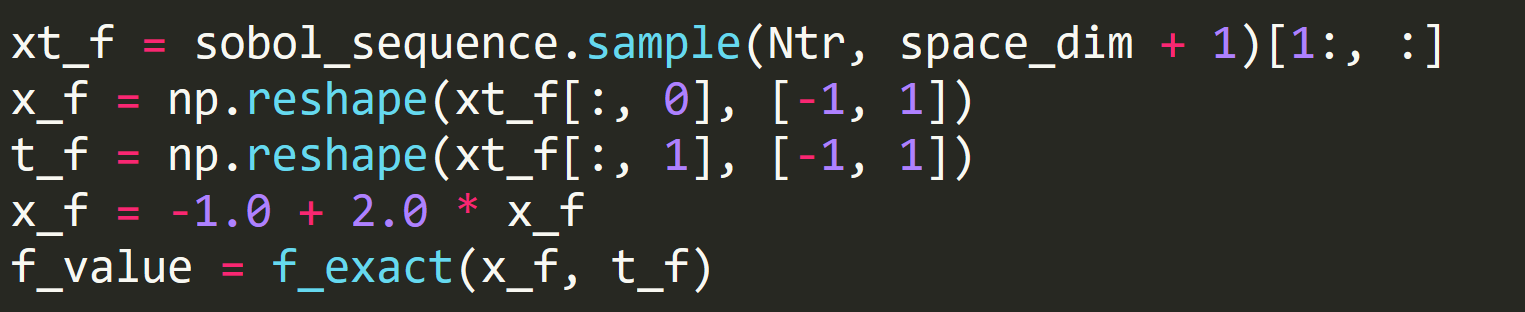
**误差的差值**

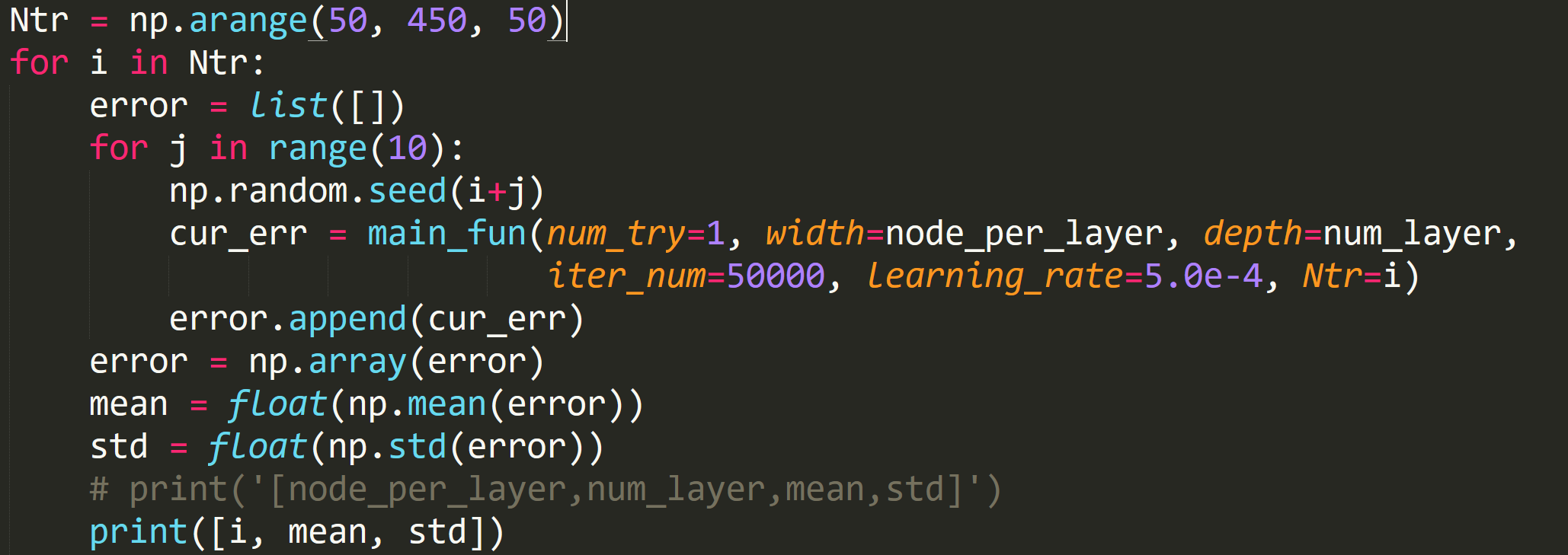


## 3. Poisson\_Ntr

**Poisson\_Ntr.py :**

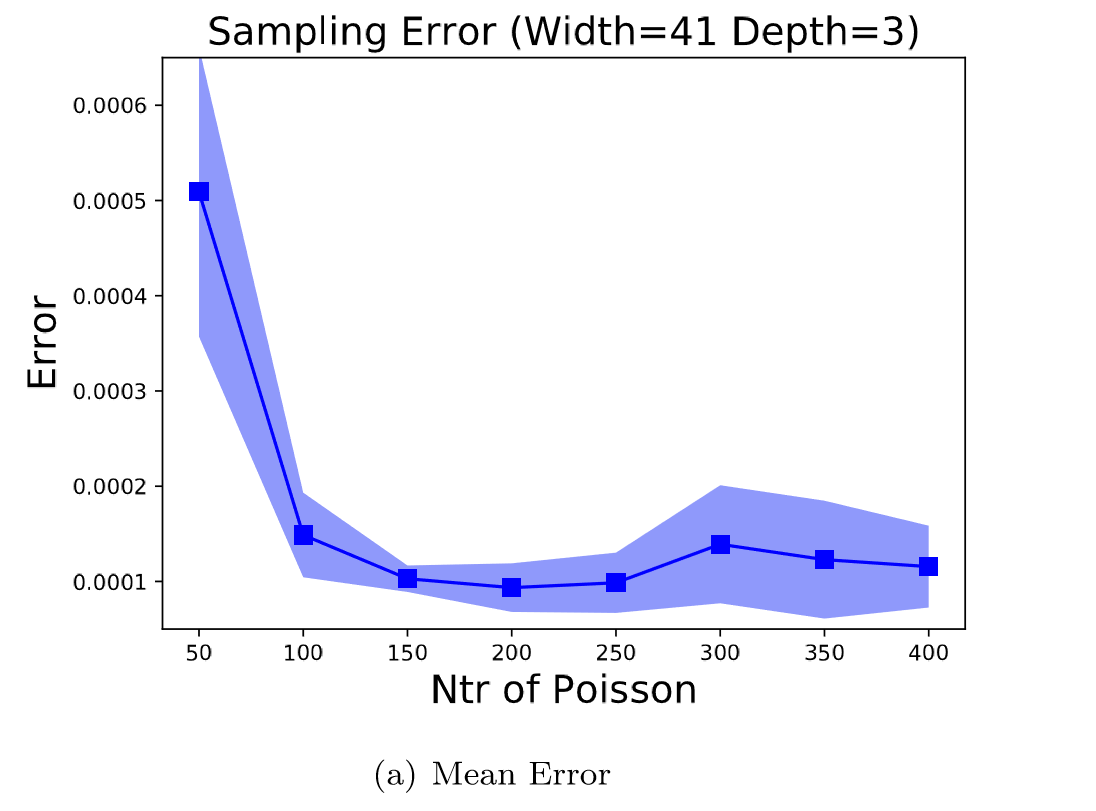
**（原始值是100）**





将输出复制到Plot文件夹下的txt就可以画图

**Ntr.py** :



**Delta\_Ntr.py :**

**误差的差值**

