

MATH-1564, K1, TA: Sam, Instructor: Nitzan, Sigal Shahaf
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1. (a) **Is a linear transformation.** We first want to prove that this satisfies the summation condition.

For $v_1, v_2 \in V$ where $v_1 = \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix}, v_2 = \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix},$

$T(v_1 + v_2) = \begin{pmatrix} (x_1 + x_2) + (y_1 + y_2) & (y_1 + y_2) - 2(z_1 + z_2) \\ 3(x_1 + x_2) + (z_1 + z_2) & 0 \end{pmatrix}.$ Through properties of real num-

bers and matrices, we arrange the statement to $\begin{pmatrix} x_1 + y_1 & y_1 - 2z_1 \\ 3x_1 + z_1 & 0 \end{pmatrix} + \begin{pmatrix} x_2 + y_2 & y_2 - 2z_2 \\ 3x_2 + z_2 & 0 \end{pmatrix}.$

This is equivalent to $T(v_1) + T(v_2)$ and therefore satisfies summation. Next we want to prove the multiplication condition. For the same v_1 and scalar $a \in \mathbb{R}$, we show that $T(av_1) = \begin{pmatrix} a(x_1 + y_1) & a(y_1 - 2z_1) \\ a(3x_1 + z_1) & 0 \end{pmatrix}.$

With the definition of matrix multiplication by scalar, this is equivalent to

$a \begin{pmatrix} x_1 + y_1 & y_1 - 2z_1 \\ 3x_1 + z_1 & 0 \end{pmatrix} = aT(v_1)$ which satisfies multiplication by scalar.

- (b) **Is a linear transformation.** To prove summation condition, for $v_1, v_2 \in V$ and $a, b \in \mathbb{R}$ where $v_1 = a_1x^2 + a_2x + a_3, v_2 = b_1x^2 + b_2x + b_3,$ we want to show that $T(v_1 + v_2) = T(v_1) + T(v_2).$

$T(v_1 + v_2) = \begin{pmatrix} 4(a_1 + b_1) + 2(a_2 + b_2) + (a_3 + b_3) \\ 4(a_1 + b_1) + (a_2 + b_2) \\ 2(a_1 + b_1) \end{pmatrix} = \begin{pmatrix} 4a_1 + 2a_2 + a_3 \\ 4a_1 + a_2 \\ 2a_1 \end{pmatrix} + \begin{pmatrix} 4b_1 + 2b_2 + b_3 \\ 4b_1 + b_2 \\ 2b_1 \end{pmatrix} =$

$T(v_1) + T(v_2).$ Next we want to prove multiplication property. Using v_1 from before and scalar

$s \in \mathbb{R}, T(sv_1) = \begin{pmatrix} s(4a_1 + 2a_2 + a_3) \\ s(4a_1 + a_2) \\ s(2a_1) \end{pmatrix} = sT(v_1).$ This satisfies the multiplication property.

- (c) **Not a linear transformation.** Say our matrix in v is $\begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}.$ $T(2v) = \begin{pmatrix} 4 & 4 \\ 0 & 0 \end{pmatrix}.$ But this is equal to $4v$, so multiplication property is incorrect.

- (d) **Is a linear transformation.** To prove summation condition, for $v_1, v_2 \in V$ and $a, b \in \mathbb{R}$ where $v_1 = a_1x^2 + a_2x + a_3, v_2 = b_1x^2 + b_2x + b_3,$ we want to show that $T(v_1 + v_2) = T(v_1) + T(v_2).$

$T(v_1 + v_2)$ evaluates to $\int_0^1 (a_1 + b_1)x^2 + (a_2 + b_2)x + (a_3 + b_3)dx.$ Since we can split integrals, this is also equivalent to $\int_0^1 a_1x^2 + a_2x + a_3dx + \int_0^1 b_1x^2 + b_2x + b_3dx = T(v_1) + T(v_2).$

Thus, summation is satisfied. Then, to prove the multiplication property, using v_1 and a scalar $s \in \mathbb{R}, T(sv_1) = \int_0^1 s(a_1x^2 + a_2x + a_3)dx = s \int_0^1 a_1x^2 + a_2x + a_3dx = sT(v_1).$ Therefore, this satisfies the multiplication property.

- (e) **Is a linear transformation.** To prove summation condition, say A_1, A_2 are ambiguous matrices and B is the fixed matrix. $T(A_1 + A_2) = (A_1 + A_2)B = (A_1B) + (A_2B) = T(A_1) + T(A_2).$ Thus it satisfies the summation condition. Next, to show that it satisfies multiplication, for some scalar $s \in \mathbb{R}, T(sA_1) = (sA_1)B = s(A_1B) = sT(A_1).$ Thus, they are the equivalent and multiplication property is satisfied.

- (f) **Not a linear transformation.** $T \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 7 \\ -8 & 2 \end{pmatrix}.$ If we scale this matrix by 2,

$T(2A) = \begin{pmatrix} 1 & 12 \\ -8 & 4 \end{pmatrix}$. However, $2T(A) = \begin{pmatrix} 2 & 14 \\ -16 & 4 \end{pmatrix}$. Thus, $T(2A) \neq 2T(A)$ and we do not have a linear transformation.

2. (a) i. The basis for the kernel is $\begin{pmatrix} -1 \\ 1 \\ -1 \end{pmatrix}$. The basis for the image is $\left(\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right)$.
- ii. The dimension of the kernel is 1, and the dimension of the image is 2.
- iii. The transformation is not onto, since according to the theorem from class, T is onto if and only if the image of T is equal to W. In this case, \mathbb{R}^4 is not spanned by the basis for the image since its dimension is only 2.
- iv. The transformation is not 1-1. From the theorem in class, T is 1-1 if and only if its kernel is equal to 0, which in this case, it is not.
- (b) i. The basis for the kernel is $\left(\begin{pmatrix} 2 & 3 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 2 & 3 \end{pmatrix} \right)$. The basis for the image is $\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right)$.
- ii. The dimension of the kernel is 2, and the dimension of the image is 2.
- iii. S is onto if and only if W equals image. This holds true, since the basis for the image spans all of \mathbb{R}^2 . Therefore, the transformation is onto.
- iv. S is 1-1 if and only if the kernel equals 0. Since the dimension of the kernel is not 0, it is not equal to 0, and thus the transformation is not 1-1.
- (c) i. The basis for the kernel is $(-\frac{3}{7}x^3 + x^2, 1)$, and the basis for the image is $\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right)$.
- ii. The dimension of the kernel is 2, and the dimension of the image is 2.
- iii. L is onto if and only if W equals image. This holds true, since the basis for the image spans all of \mathbb{R}^2 . Therefore, the transformation is onto.
- iv. L is 1-1 if and only if the kernel equals 0. Since the dimension of the kernel is not 0, it is not equal to 0, and thus the transformation is not 1-1.
- (d) i. The basis for the kernel is the empty set, and the basis for the image is $(1, x, x^2, x^3)$.
- ii. The dimension of the kernel is 0, and the dimension of the image is 4.
- iii. Onto, because W equals image. In other words, the vector space $\mathbb{R}_3[x]$ is spanned by the basis for the image.
- iv. 1-1, because the kernel equals 0, since its dimension is 0.
3. (a) This statement is false (it has to be 1-1 in order for it to be true). Let us say T is the linear transformation that maps vectors to the real number 0. The vectors $\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ are linearly independent, but the linear transformation of the two vectors are both equal to 0, meaning that they are not linearly independent.
- (b) True. Let us consider for all scalars $a \in \mathbb{R}$, $a_1v_1 + \dots + a_nv_n = 0$. Since the kernel maps over to the zero of W, we have:

$$T(0_v) = T(a_1v_1 + \dots + a_nv_n)$$

$$0_w = T(a_1v_1) + \dots + T(a_nv_n)$$

$$0_w = a_1T(v_1) + \dots + a_nT(v_n)$$

Thus, a_1, \dots, a_n is equal to zero since we are given that Tv_1, \dots, Tv_n is linearly independent. That would also imply in our original equation that v_1, \dots, v_n is linearly independent in V .

- (c) This statement is false. Let us say $\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ spans the space \mathbb{R}^2 . Now, let us define T as the linear transformation $\mathbb{R}^2 \rightarrow \mathbb{R}^2$ which maps the vector $\begin{pmatrix} a \\ b \end{pmatrix} \rightarrow \begin{pmatrix} a \\ 0 \end{pmatrix}$. Thus, the vectors we gave that span \mathbb{R}^2 now become $\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \end{pmatrix}$, but they clearly don't span W .
- (d) True. Since Tv_1, \dots, Tv_n spans W , we know that the image of V is equal to W . Therefore, from a theorem proved in class, if image of V equals W , then T is onto. Next, since Tv_1, \dots, Tv_n is a spanning set in W , we know that for some $a \in \mathbb{R}, w \in W$, $w = a_1Tv_1 + \dots + a_nTv_n$. If we recall, since T is onto, it means that every w has at least one preimage in V such that $Tv = w$. Thus, it is equivalent to say that $Tv = T(a_1v_1 + \dots + a_nv_n)$, then $v = a_1v_1 + \dots + a_nv_n$ for all $v \in V$, so it thus suffices to say that v_1, \dots, v_n spans V .
- (e) To prove that $T(U)$ is a subspace of W , we first want to show that it is not empty. We know that it is not empty because U , which is a subspace of V , must contain the 0_v which maps over to 0_w by definition. Thus $T(U)$ must contain 0_w , so it is not empty. Next, we want to show that it is closed to addition. So, say that u_1, u_2 are in $T(U)$ such that $T(v_1) = u_1$ and $T(v_2) = u_2$. We then claim that $v_1 + v_2$ is a preimage of $u_1 + u_2$. Then, $T(v_1 + v_2) = Tv_1 + Tv_2 = u_1 + u_2$. Thus, $u_1 + u_2 \in T(U)$. Finally, we want to prove that it is closed to multiplication by scalar. This is very similar, we simply take scalar $a \in \mathbb{R}$ and $u_1 \in T(U)$ such that $T(v_1) = u_1$. We then claim that av_1 is a preimage of au_1 . So, $T(av_1) = aT(v_1) = au_1$, and $au_1 \in T(U)$. Therefore, all three properties are satisfied and $T(U)$ is a subspace of W .
- (f) Let us say $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is a linear transformation given by the following: $\begin{pmatrix} a \\ b \end{pmatrix} \rightarrow \begin{pmatrix} 0 \\ 0 \end{pmatrix}$. So, a let's chose a single vector subset of V given by $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$. When we apply the linear transformation, it becomes $\begin{pmatrix} 0 \\ 0 \end{pmatrix}$ which is a subspace of \mathbb{R}^2 . However, the original vector is not a subspace of \mathbb{R}^2 .

4. and 5.

- (a) **False.** From the corollary, T is 1-1 if $\dim V \leq \dim W$. The dimension of $M_2(\mathbb{R})$ is 4 and the dimension of \mathbb{R}^3 is 3, so it does not satisfy this relationship.
- Stays false.
 - Adding the condition that T is onto will make it true. Since in this question V has dimension of 4 and W has dimension of 3, there will definitely exist some T that will be onto. This is given by the corollary that if T is onto, then $\dim V \geq \dim W$.
- (b) **True.** From the corollary, T is 1-1 if $\dim V \leq \dim W$. The dimension of \mathbb{R}^3 is 3 and the dimension of $M_2(\mathbb{R})$ is 4, so this relationship is satisfied.
- (c) **True.** An example is mapping any matrix to the zero matrix: $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \rightarrow \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$. Clearly, this relationship is not 1-1 since more than one matrix maps to the 0 matrix, and this relationship is not onto, because matrices cannot be mapped to anything other than the 0 matrix.

- (d) **False.** From the corollary, if $\dim V = \dim W$, and T is 1-1, then it must be onto. In this scenario, the dimension of $M_2(\mathbb{R})$ is 4, and the dimension of $\mathbb{R}_3[x]$ is 4. Since the dimensions are equal, and we are given that it is 1-1, it must be onto. However there is a contradiction because this question asks that it is not onto.
- i. Stays false.
 - ii. Adding the condition that T is onto makes this statement true. This is because V has a dimension of 4, and W has a dimension of 3. We know from the corollary if $\dim V > \dim W$, then there must be a possible T that is onto.
- (e) **True.** From the corollaries, T is onto if $\dim V \geq \dim W$, and T is 1-1 if $\dim V \leq \dim W$. Then the equality holds that if $\dim V > \dim W$, T is onto and not 1-1. In this scenario, the dimension of V is 4, and the dimension of W is 3. Then there are indeed many examples for T that are onto and not 1-1.
- (f) **False.** T is onto if and only if the image of V is equal to W . In this scenario, the dimension of V is equal to 3, while the dimension of W is equal to 4. Clearly, the image of V cannot equal to W because its dimension is less than that of W .
- i. Since in this case, $\dim V < \dim W$, we know that T could definitely be 1-1.
 - ii. Stays false.
- (g) **True.** An example is mapping the matrix to the zero vector: $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \rightarrow \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$. This is not onto because nothing outside of zero is mapped to, and this is not 1-1 since all matrices are mapped to the 0 vector.