

MATH-1564-K1,K2,K3 –Linear Algebra with Abstract Vector Spaces  
Homework 10 – Solutions

1. i.

$$T : \mathbb{R}^3 \mapsto M_2(\mathbb{R})$$

given by,

$$T \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x + y & y - 2z \\ 3x + z & 0 \end{pmatrix}$$

This is a linear transformation. To show this we need to show that  $T$  satisfies both of the conditions in the definition of a linear transformation.

a. Let  $a = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix}, b = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} \in \mathbb{R}^3$ . We need to show that  $T(a + b) = Ta + Tb$ . On one hand,

$$\begin{aligned} T(a + b) &= T\left(\begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} + \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}\right) = \\ &= T\left(\begin{pmatrix} a_1 + b_1 \\ a_2 + b_2 \\ a_3 + b_3 \end{pmatrix}\right) = \begin{pmatrix} a_1 + b_1 + a_2 + b_2 & a_2 + b_2 - 2(a_3 + b_3) \\ 3(a_1 + b_1) + a_3 + b_3 & 0 \end{pmatrix} = \\ &= \begin{pmatrix} a_1 + b_1 + a_2 + b_2 & a_2 + b_2 - 2a_3 - 2b_3 \\ 3a_1 + 3b_1 + a_3 + b_3 & 0 \end{pmatrix} \end{aligned}$$

While on the other hand,

$$\begin{aligned} Ta + Tb &= T\begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} + T\begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} = \\ &= \begin{pmatrix} a_1 + a_2 & a_2 - 2a_3 \\ 3a_1 + a_3 & 0 \end{pmatrix} + \begin{pmatrix} b_1 + b_2 & b_2 - 2b_3 \\ 3b_1 + b_3 & 0 \end{pmatrix} = \\ &= \begin{pmatrix} a_1 + b_1 + a_2 + b_2 & a_2 + b_2 - 2a_3 - 2b_3 \\ 3a_1 + 3b_1 + a_3 + b_3 & 0 \end{pmatrix} \end{aligned}$$

So indeed, we get that  $T(a + b) = Ta + Tb$ .

b. Let  $a = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} \in \mathbb{R}^3$  and  $\beta \in \mathbb{R}$ . We need to show that  $T(\beta a) = \beta Ta$ . Indeed,

$$T(\beta a) = T\begin{pmatrix} \beta a_1 \\ \beta a_2 \\ \beta a_3 \end{pmatrix} =$$

$$= \begin{pmatrix} \beta a_1 + \beta a_2 & \beta a_2 - 2\beta a_3 \\ 3\beta a_1 + \beta a_3 & 0 \end{pmatrix} = \beta \begin{pmatrix} a_1 + a_2 & a_2 - 2a_3 \\ 3a_1 + a_3 & 0 \end{pmatrix} = \beta Ta$$

ii.

$$T : \mathbb{R}_2[x] \mapsto \mathbb{R}^3$$

given by,

$$Tp = \begin{pmatrix} p(2) \\ p'(2) \\ p''(2) \end{pmatrix}$$

This is a linear transformation. To show this we need to show that  $T$  satisfies both of the conditions in the definition of a linear transformation.

- a. Let  $p, q \in \mathbb{R}_2[x]$ . We need to show that  $T(p + q) = Tp + Tq$ .  
Indeed, from the rules of derivatives we studied in calculus we get,

$$\begin{aligned} T(p + q) &= \begin{pmatrix} (p + q)(2) \\ (p + q)'(2) \\ (p + q)''(2) \end{pmatrix} = \begin{pmatrix} p(2) + q(2) \\ p'(2) + q'(2) \\ p''(2) + q''(2) \end{pmatrix} = \\ &= \begin{pmatrix} p(2) \\ p'(2) \\ p''(2) \end{pmatrix} + \begin{pmatrix} q(2) \\ q'(2) \\ q''(2) \end{pmatrix} = Tp + Tq. \end{aligned}$$

- b. Let  $p \in \mathbb{R}_2[x]$  and  $\beta \in \mathbb{R}$ . We need to show that  $T(\beta p) = \beta Tp$ .  
Indeed, from the rules of derivatives we studied in calculus we get,

$$\begin{aligned} T(\beta p) &= \begin{pmatrix} (\beta p)(2) \\ (\beta p)'(2) \\ (\beta p)''(2) \end{pmatrix} = \begin{pmatrix} \beta p(2) \\ \beta p'(2) \\ \beta p''(2) \end{pmatrix} = \\ &= \beta \begin{pmatrix} p(2) \\ p'(2) \\ p''(2) \end{pmatrix} = \beta Tp. \end{aligned}$$

iii.

$$T : M_2(\mathbb{R}) \mapsto M_2(\mathbb{R})$$

given by,

$$TA = A^2$$

This is not a linear transformation. Consider, for example the matrix  $I_2$  and the scalar 3. Then  $TI_2 = I_2^2 = I_2$  while  $T(3I_2) = (3I_2)^2 = 9I_2$ . So,  $T(3I_2) \neq 3TI_2$ .

iv.

$$T : \mathbb{R}_2[x] \mapsto \mathbb{R}$$

given by,

$$Tp = \int_0^1 p(x)dx$$

This is a linear transformation. To show this we need to show that  $T$  satisfies both of the conditions in the definition of a linear transformation.

a. Let  $p, q \in \mathbb{R}_2[x]$ . We need to show that  $T(p+q) = Tp + Tq$ .  
Indeed, by the rules for integration which we studied in calculus,

$$T(p+q) = \int_0^1 (p+q)(x)dx = \int_0^1 (p(x)+q(x))dx = \int_0^1 p(x)dx + \int_0^1 q(x)dx = Tp + Tq.$$

b. Let  $p \in \mathbb{R}_2[x]$  and  $\beta \in \mathbb{R}$ . We need to show that  $T(\beta p) = \beta Tp$ .  
Indeed, by the rules for integration which we studied in calculus,

$$T(\beta p) = \int_0^1 (\beta p)(x)dx = \int_0^1 \beta p(x)dx = \beta \int_0^1 p(x)dx = \beta Tp.$$

v. Fix  $B \in M_3(\mathbb{R})$  and consider the function:

$$T : M_3(\mathbb{R}) \mapsto M_3(\mathbb{R})$$

given by,

$$TA = AB$$

This is a linear transformation. To show this we need to show that  $T$  satisfies both of the conditions in the definition of a linear transformation.

a. Let  $A, C \in M_3(\mathbb{R})$ . We need to show that  $T(A+C) = TA + TC$ .  
Indeed, by the rules of matrix multiplication which we stated in class,

$$T(A+C) = (A+C)B = AB + CB = TA + TC.$$

b. Let  $A \in M_3(\mathbb{R})$ . We need to show that  $T(\beta A) = \beta TA$ . Indeed,  
by the rules of matrix multiplication which we stated in class,

$$T(\beta A) = (\beta A)B = \beta(AB) = \beta TA.$$

vi.

$$T : M_2(\mathbb{R}) \mapsto M_2(\mathbb{R})$$

given by,

$$T \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a-c+1 & 2a+3b+2 \\ d-b-8 & 2a \end{pmatrix}$$

This is not a linear transformation. Indeed, we have,

$$T \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ -8 & 0 \end{pmatrix}.$$

So, by the 'thumbs-rule' we proved in class  $T$  is not linear, as the image of the zero vector is not the zero vector.

2. i. For

$$A = \begin{pmatrix} 1 & 2 & -1 \\ 3 & 1 & 2 \\ 1 & 7 & -6 \\ 0 & 5 & -5 \end{pmatrix}$$

consider the operator

$$T_A : \mathbb{R}^3 \mapsto \mathbb{R}^4$$

where the notation  $T_A$  was defined in class.

a. We start with the kernel of  $T_A$ . We studied in class that the kernel of this transformation is equal to the null space of  $A$ . To find a basis for this space we bring the matrix to echelon form.

$$\begin{pmatrix} 1 & 2 & -1 \\ 3 & 1 & 2 \\ 1 & 7 & -6 \\ 0 & 5 & -5 \end{pmatrix} \xrightarrow{R_2-3R_1, R_3-R_1} \begin{pmatrix} 1 & 2 & -1 \\ 0 & -5 & 5 \\ 0 & 5 & -5 \\ 0 & 5 & -5 \end{pmatrix} \xrightarrow{R_3+R_2, R_4+R_2} \begin{pmatrix} 1 & 2 & -1 \\ 0 & -5 & 5 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

The corresponding linear system is:

$$\begin{cases} x + 2y - z = 0 \\ -5y + 5z = 0 \end{cases}$$

So,  $z$  is a free variable and can be any real number. We denote this by  $z = t$ ,  $t \in \mathbb{R}$ . It follows that  $y = t$  and  $x = -t$ . So the null space of  $A$  is

$$\left\{ \begin{pmatrix} -t \\ t \\ t \end{pmatrix} : t \in \mathbb{R} \right\} = \left\{ t \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} : t \in \mathbb{R} \right\} = \text{span} \left\{ \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} \right\}.$$

So  $\left\{ \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} \right\}$  is a spanning set for null  $A$ , and since it contains a single vector which is different from zero, this set is also linearly independent. So,  $\left\{ \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} \right\}$  is a basis for null  $A$ .

We now turn to the image of  $T_A$ . We studied in class that the image of this transformation is equal to the column space of  $A$ .

That is, the image of the transformation is equal to

$$\text{span}\left\{\begin{pmatrix} 1 \\ 3 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 7 \\ 5 \end{pmatrix}, \begin{pmatrix} -1 \\ 2 \\ -6 \\ -5 \end{pmatrix}\right\}.$$

To find a basis for this space we follow the algorithm described in class, write the vectors as rows of a matrix and bring it to echelon form

$$\begin{pmatrix} 1 & 3 & 1 & 0 \\ 2 & 1 & 7 & 5 \\ -1 & 2 & -6 & -5 \end{pmatrix} \xrightarrow{R_2-2R_1, R_3+R_1} \begin{pmatrix} 1 & 3 & 1 & 0 \\ 0 & -5 & 5 & 5 \\ 0 & 5 & -5 & -5 \end{pmatrix} \xrightarrow{R_3+R_2} \begin{pmatrix} 1 & 3 & 1 & 0 \\ 0 & -5 & 5 & 5 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

As we studied, a bases for the space is given by the non-zero rows:

$$\left\{\begin{pmatrix} 1 \\ 3 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ -5 \\ 5 \\ 5 \end{pmatrix}\right\}$$

- b. The kernel has a basis containing 1 element, so  $\dim(\ker T_A) = 1$ . The image has a basis containing two elements, so  $\dim(\text{Im} T_A) = 2$ . The domain is  $\mathbb{R}^3$  which has dimension 3. Indeed,  $3 = 2 + 1$ .
  - c. The transformation is not onto, as the image is not equal to the codomain. Indeed, the codomain is  $\mathbb{R}^4$  which has dimension 4 while we have seen that the dimension of the image is 2. By a result from class this means that the image is only a subspace of the codomain, and not equal to it.
- Remark:** Another way to justify: we proved in class that if the dimension of the domain is smaller then the dimension of the codomain, then the transformation cannot be onto.
- d. The transformation is not 1 – 1. Indeed, the dimension of the kernel is 1 which implies that the kernel is not equal to the set  $\{\underline{0}\}$  (The dimension of  $\{\underline{0}\}$  is zero).

ii.

$$S : M_2(\mathbb{R}) \mapsto \mathbb{R}^2$$

given by

$$SA = A \begin{pmatrix} 3 \\ -2 \end{pmatrix}$$

a. We start by rewriting the transformation:

$$S \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 3 \\ -2 \end{pmatrix} = \begin{pmatrix} 3a - 2b \\ 3c - 2d \end{pmatrix}.$$

We first consider the kernel of  $S$ . A matrix  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  is in the kernel of  $S$  iff  $SA = \underline{0}$ , that is if

$$\begin{pmatrix} 3a - 2b \\ 3c - 2d \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}.$$

We conclude that

$$\begin{aligned} \ker(S) &= \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} : 3a - 2b = 0, 3c - 2d = 0 \right\} = \\ &= \left\{ \begin{pmatrix} \frac{2}{3}b & b \\ \frac{2}{3}d & d \end{pmatrix} \right\}. \end{aligned}$$

Every vector in  $\ker S$  can therefore be written in the following way:

$$\begin{pmatrix} \frac{2}{3}b & b \\ \frac{2}{3}d & d \end{pmatrix} = b \begin{pmatrix} \frac{2}{3} & 1 \\ 0 & 0 \end{pmatrix} + d \begin{pmatrix} 0 & 0 \\ \frac{2}{3} & 1 \end{pmatrix}.$$

Both of the matrices on the RHS belong to  $\ker S$  (check!) and every other matrix in  $\ker S$  can be written as a linear combination of them. We conclude that the set

$$\left\{ \begin{pmatrix} \frac{2}{3} & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ \frac{2}{3} & 1 \end{pmatrix} \right\}$$

is a spanning set for  $\ker S$ . This set contains two vectors, and neither of these vectors is a scalar multiple of the other (which is the only way that two vectors can be linearly dependent). This means that this set is linearly independent and therefore a basis for  $\ker S$ .

We claim that the image of the transformation is equal to  $\mathbb{R}^2$  and therefore the set  $\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$  is a basis for  $\text{Im} S$ . To see that  $\text{Im} S = \mathbb{R}^2$  we first find the dimension of  $\text{Im} S$ . By the dimension formula we studied in class we know that

$$\dim(M_2(\mathbb{R})) = \dim(\ker S) + \dim(\text{Im} S).$$

We proved in class that  $\dim(M_2(\mathbb{R})) = 4$  and we just showed that  $\dim(\ker S) = 2$ . We conclude that  $\dim(\text{Im} S) = 2$ . We proved in class that  $\text{Im} S$  is a subspace of the codomain, that is,  $\text{Im} S$  is a subspace of  $\mathbb{R}^2$ . From the result we proved in class regarding the dimension of a subspace, we know that the dimension of  $\text{Im} S$  is equal to the dimension of  $\mathbb{R}^2$  iff these two spaces are equal. Since the dimension of  $\mathbb{R}^2$  is 2 we conclude that indeed  $\text{Im} S = \mathbb{R}^2$ .

b. This was done during the solution of part (a).

- c. The transformation is onto. We proved during the solution of part (a) that the image of  $S$  is equal to the codomain.
- d. The transformation is not 1 – 1. Indeed, the dimension of the kernel is 2 which implies that the kernel is not the set  $\{0\}$ , (The dimension of  $\{0\}$  is zero).
- iii.

$$L : \mathbb{R}_3[x] \mapsto \mathbb{R}^2$$

given by

$$Lp = \begin{pmatrix} p(2) - p(1) \\ p'(0) \end{pmatrix}$$

- a. We start by rewriting the transformation:

$$L(a + bx + cx^2 + dx^3) = \begin{pmatrix} b + 3c + 7d \\ b \end{pmatrix}$$

We first consider the kernel of  $L$ . A polynomial  $p$  is in the kernel iff it satisfies  $Lp = \underline{0}$ . We conclude that

$$\begin{aligned} \ker L &= \{a + bx + cx^2 + dx^3 : b + 3c + 7d = 0, b = 0\} = \\ &= \{a + cx^2 + dx^3 : 3c + 7d = 0\} = \{a - \frac{7}{3}dx^2 + dx^3\} \end{aligned}$$

So every vector in the kernel can be written as

$$a - \frac{7}{3}dx^2 + dx^3 = a \cdot 1 + d(-\frac{7}{3}x^2 + x^3).$$

Both of the vectors in the set  $\{1, -\frac{7}{3}x^2 + x^3\}$  belongs to the kernel (check!) and every other polynomial in  $\ker L$  can be written as a linear combination of them. We conclude that the set  $\{1, -\frac{7}{3}x^2 + x^3\}$  is a spanning set for  $\ker L$ . This set contains two vectors, and neither of this vectors is a scalar multiplying the other (which is the only way that two vectors can be linearly dependent). This means that this set is linearly independent and therefore a basis for  $\ker L$ .

We claim that the image of the transformation is equal to  $\mathbb{R}^2$  and therefore the set  $\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$  is a basis for  $\text{Im}L$ . To see that  $\text{Im}L = \mathbb{R}^2$  we first find the dimension of  $\text{Im}L$ . By the dimension formula we studied in class we know that

$$\dim(\mathbb{R}_3[x]) = \dim(\ker L) + \dim(\text{Im}L).$$

We proved in class that  $\dim(\mathbb{R}_3[x]) = 4$  and we just showed that  $\dim(\ker L) = 2$ . We conclude that  $\dim(\text{Im}L) = 2$ . We proved in class that  $\text{Im}L$  is a subspace of the codomain, that is,  $\text{Im}L$  is a subspace of  $\mathbb{R}^2$ . From the result we proved in class regarding the dimension of a subspace, we know that the dimension of  $\text{Im}L$  is

equal to the dimension of  $\mathbb{R}^2$  iff these two spaces are equal. Since the dimension of  $\mathbb{R}^2$  is 2 we conclude that indeed  $\text{Im}L = \mathbb{R}^2$ .

- b. This was done during the solution of part (a).
- c. The transformation is onto. We proved during the solution of part (a) that the image of  $L$  is equal to the codomain.
- d. The transformation is not 1 – 1. Indeed, the dimension of the kernel is 2 which implies that the kernel is not the set  $\{\underline{0}\}$  (The dimension of  $\{\underline{0}\}$  is zero).

iv.

$$\Phi : \mathbb{R}^3 \mapsto \mathbb{R}_3[x]$$

given by

$$\Phi \begin{pmatrix} a \\ b \\ c \end{pmatrix} = (a + b) + (a - 2b + c)x + (b - 3c)x^2 + (a + b + c)x^3$$

- a. A 3-tuple  $\begin{pmatrix} a \\ b \\ c \end{pmatrix}$  belongs to the kernel of  $\Phi$  iff its image under this transformation is the constant zero polynomial. Since two polynomials are equal iff their coefficients are equal this means that  $\begin{pmatrix} a \\ b \\ c \end{pmatrix}$  is in the kernel iff it is a solution to the following homogeneous linear system.

$$\begin{cases} a + b = 0 \\ a - 2b + c = 0 \\ b - 3c = 0 \\ a + b + c = 0 \end{cases}$$

We write this system in a matrix form and bring it to echelon form.

$$\begin{aligned} & \left( \begin{array}{ccc|c} 1 & 1 & 0 & 0 \\ 1 & -2 & 1 & 0 \\ 0 & 1 & -3 & 0 \\ 1 & 1 & 1 & 0 \end{array} \right) \xrightarrow{R_2 - R_1, R_4 - R_1} \left( \begin{array}{ccc|c} 1 & 1 & 0 & 0 \\ 0 & -3 & 1 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right) \xrightarrow{R_2 \leftrightarrow R_3} \\ & \left( \begin{array}{ccc|c} 1 & 1 & 0 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & -3 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right) \xrightarrow{R_3 + 3R_2} \left( \begin{array}{ccc|c} 1 & 1 & 0 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & -8 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right) \xrightarrow{R_4 \leftrightarrow R_3} \\ & \left( \begin{array}{ccc|c} 1 & 1 & 0 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -8 & 0 \end{array} \right) \xrightarrow{R_4 + 8R_3} \left( \begin{array}{ccc|c} 1 & 1 & 0 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right) \end{aligned}$$



All of the variables in the echelon form are leading variables so the only solution to the corresponding homogeneous linear system is the trivial solution. We conclude that  $\ker\Phi = \{0\}$  and therefore a basis for this kernel is the empty set  $\{\}$ .

We now turn to study the image of the transformation. A polynomial is in the image iff it can be expressed as  $(a+b) + (a-2b+c)x + (b-3c)x^2 + (a+b+c)x^3$  with  $a, b, c \in \mathbb{R}$ . This implies that

$$\text{Im}(\Phi) = \{(a+b) + (a-2b+c)x + (b-3c)x^2 + (a+b+c)x^3 : a, b, c \in \mathbb{R}\}$$

Every polynomial in this space can be expressed as,

$$(a+b) + (a-2b+c)x + (b-3c)x^2 + (a+b+c)x^3 = a(1+x+x^3) + b(1-2x+x^2+x^3) + c(x-3x^2+x^3)$$

Each element of the set  $\{1+x+x^3, 1-2x+x^2+x^3, x-3x^2+x^3\}$  belongs to the space  $\text{Im}\Phi$  (check!) and every other element of the space is a linear combination of these three vectors. We conclude that  $\{1+x+x^3, 1-2x+x^2+x^3, x-3x^2+x^3\}$  is a spanning set for the space. We claim that  $\dim(\text{Im}\phi) = 3$  and therefore a set of three vectors which is a spanning set for the space is a basis for the space, so  $\{1+x+x^3, 1-2x+x^2+x^3, x-3x^2+x^3\}$  is a basis for the space. To see that  $\dim(\text{Im}\phi) = 3$  we use the dimension formula,

$$\dim(\mathbb{R}^3) = \dim(\ker\Phi) + \dim(\text{Im}\Phi).$$

We proved in class that  $\dim(\mathbb{R}^3) = 3$  and we have just seen that  $\ker\Phi = \{\}$  so  $\dim(\ker\Phi) = 0$ . We conclude that indeed,  $\dim(\text{Im}\phi) = 3$  and  $\{1+x+x^3, 1-2x+x^2+x^3, x-3x^2+x^3\}$  is a basis for the space.

- b. This was done in part (a).
  - c. The transformation is not onto. We proved in class that if the dimension of the domain is smaller than the dimension of the codomain then the transformation cannot be onto.
  - d. The transformation is 1 – 1. Indeed, we proved in part (a) that  $\ker\Phi = \{0\}$ .
- 3 & 4. i.  $\diamond$ . The claim is false. Indeed, every zero transformation from a non-zero vector space will provide a counter example. Let us give a different counterexample, just for fun. Consider the linear transformation  $T : \mathbb{R}^3 \mapsto \mathbb{R}^2$  which is defined by

$$T \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 2a+b \\ c \end{pmatrix}.$$

The set  $\left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\}$  is linearly independent (why?), but the set of their images under the transformation  $T$  is  $\left\{ \begin{pmatrix} 2 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\}$  which is linearly dependent (why?).

- ◇. The answer doesn't change if we add the condition that  $T$  is onto. In fact, in the counterexample we gave above the linear transformation is onto (check!).
- ◇. The answer changes if we add the condition that  $T$  is 1 – 1. To be precise, let us formulate the statement which we claim is **true**:

If  $v_1, \dots, v_n$  is linearly independent in  $V$  and  $T$  is a linear 1 – 1 transformation then  $Tv_1, \dots, Tv_n$  is linearly independent in  $W$ .

Proof: To show that  $Tv_1, \dots, Tv_n$  is linearly independent we assume that  $a_1, \dots, a_n \in \mathbb{R}$  are such that

$$a_1Tv_1 + \dots + a_nTv_n = 0_W.$$

Our goal is to prove that  $a_1 = \dots = a_n = 0$  which will imply that the **only** linear combination of  $Tv_1, \dots, Tv_n$  which is equal to the zero of the space is the trivial linear combination. By definition this will imply that  $Tv_1, \dots, Tv_n$  are linearly independent.

So, we use the fact that  $T$  is linear and get that

$$a_1Tv_1 + \dots + a_nTv_n = T(a_1v_1 + \dots + a_nv_n).$$

We insert this relation to the equation above and get,

$$T(a_1v_1 + \dots + a_nv_n) = 0_W.$$

We proved in class that since  $T$  is 1 – 1 the only pre-image of  $0_W$  is  $0_V$ . This implies that,

$$a_1v_1 + \dots + a_nv_n = 0_V.$$

Since we are given that  $v_1, \dots, v_n$  are linearly independent, the only linear combination of them which is equal to  $0_V$  is the trivial one.

We conclude that  $a_1 = \dots = a_n = 0$  and therefore  $Tv_1, \dots, Tv_n$  are linearly independent.

- ii. The claim is true. Proof: To show that  $v_1, \dots, v_n$  is linearly independent we assume that  $a_1, \dots, a_n \in \mathbb{R}$  are such that

$$a_1v_1 + \dots + a_nv_n = 0_V.$$

Our goal is to prove that  $a_1 = \dots = a_n = 0$  which will imply that the **only** linear combination of  $v_1, \dots, v_n$  which is equal to the zero of the space is the trivial linear combination. By definition this will imply that  $v_1, \dots, v_n$  are linearly independent.

So, we apply the transformation  $T$  to both sides of the equation to get:

$$T(a_1v_1 + \dots + a_nv_n) = T(0_V).$$

we use the fact that  $T$  is linear and get that

$$T(a_1v_1 + \dots + a_nv_n) = a_1Tv_1 + \dots + a_nTv_n.$$

We insert this relation to the equation above and get,

$$a_1Tv_1 + \dots + a_nTv_n = T(0_V).$$

We insert also the 'thumbs rule' from class:  $T(0_V) = 0_W$ . We get,

$$a_1Tv_1 + \dots + a_nTv_n = 0_W.$$

Since we are given that  $Tv_1, \dots, Tv_n$  are linearly independent, the only linear combination of them which is equal to  $0_W$  is the trivial one. We conclude that  $a_1 = \dots = a_n = 0$  and therefore  $v_1, \dots, v_n$  are linearly independent.

- iii.  $\diamond$  The claim is false, in fact any transformation which is not onto will provide a counterexample. For instance, consider the transformation  $T : \mathbb{R}^2 \mapsto \mathbb{R}^3$  which is defined by

$$T \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} a \\ b \\ 0 \end{pmatrix}.$$

Then the set  $\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$  is a spanning set for  $\mathbb{R}^2$ , as we

proved in class, but the set of their images under  $T$ ,  $\left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\}$

is not a spanning set for  $\mathbb{R}^3$  ( $\mathbb{R}^3$  is of dimension 3 so by a claim we proved in class, no set of 2 vectors can be a spanning set for this space).

- $\diamond$  The answer does not change if we add the condition that  $T$  is  $1-1$ . In fact, the linear transformation in the counterexample we constructed above is  $1-1$  (check!).
- $\diamond$  The answer changes if we add the condition that  $T$  is onto. To be precise, let us formulate the statement which we claim is **true**:

If  $v_1, \dots, v_n$  is a spanning set in  $V$  and  $T$  is an onto linear transformation then  $Tv_1, \dots, Tv_n$  is a spanning set in  $W$ .

Proof: We want to show that every vector in  $W$  is a linear combination of  $Tv_1, \dots, Tv_n$ , this will imply that the set indeed spans  $W$ . So, let  $w \in W$ . Since  $T$  is onto  $w$  has a pre-image, that is, there exists  $v \in V$  such that  $Tv = w$ . Since  $v_1, \dots, v_n$  is a spanning set in  $V$  there exist  $a_1, \dots, a_n \in \mathbb{R}$  such that

$$v = a_1v_1 + \dots + a_nv_n.$$

We apply the transformation  $T$  on both sides and get,

$$Tv = T(a_1v_1 + \dots + a_nv_n).$$

We insert the relation  $Tv = w$  on the LHS and use the fact that  $T$  is linear on the RHS. We get,

$$w = a_1Tv_1 + \dots + a_nTv_n.$$

So  $w$  is a linear combination of  $Tv_1, \dots, Tv_n$ . Since this process works for every  $w \in W$ , we conclude that every vector in  $W$  is a linear combination of  $Tv_1, \dots, Tv_n$  and therefore the set indeed spans  $W$ .

- iv.  $\diamond$  The claim is false. Consider for example the transformation  $T : \mathbb{R}^3 \mapsto \mathbb{R}^2$  which is defined by

$$T \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} a \\ b \end{pmatrix}.$$

Then the set  $\left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\}$  is not a spanning set for  $\mathbb{R}^3$  ( $\mathbb{R}^3$  is of dimension 3 so by a claim we proved in class, no set of 2 vectors can be a spanning set for this space). However, the set of its images  $\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$  is a spanning set for  $\mathbb{R}^2$ , as we proved in class.

- $\diamond$  The condition we were given, that  $Tv_1, \dots, Tv_n$  is a spanning set in  $W$ , implies that  $T$  is onto. Therefore, adding the condition that  $T$  is onto is adding a redundant condition, which will not change the answer. To see that if  $Tv_1, \dots, Tv_n$  is a spanning set in  $W$  then  $T$  is onto, recall first that we proved in class that  $\text{Im}T$  is a subspace for  $W$ . Next, since  $Tv_1, \dots, Tv_n \in \text{Im}T$ , it follows from a result we proved in class that their span is a subspace of  $\text{Im}T$ . So, if  $Tv_1, \dots, Tv_n$  is a spanning set in  $W$ , it follows that  $W \subset \text{Im}T$  and therefore  $W = \text{Im}T$ . So  $T$  is indeed onto.
- $\diamond$  The answer changes if we add the condition that  $T$  is 1 – 1. To be precise, let us formulate the statement which we claim is **true**:  
If  $Tv_1, \dots, Tv_n$  is a spanning set in  $W$  and  $T$  is 1 – 1 then  $v_1, \dots, v_n$  is a spanning set in  $V$ .

Proof: We want to show that every vector in  $V$  is a linear combination of  $v_1, \dots, v_n$ , this will imply that the set indeed spans  $V$ . So, let  $v \in V$ . Since  $Tv_1, \dots, Tv_n$  is a spanning set in  $W$  there exist  $a_1, \dots, a_n \in \mathbb{R}$  such that

$$Tv = a_1Tv_1 + \dots + a_nTv_n.$$

Since  $T$  is linear we get,

$$Tv = T(a_1v_1 + \dots + a_nv_n).$$

Since  $T$  is 1 – 1 it follows that

$$v = a_1v_1 + \dots + a_nv_n.$$

So  $v$  is a linear combination of  $v_1, \dots, v_n$ . Since this process works for every  $v \in V$ , we conclude that every vector in  $V$  is a linear combination of  $v_1, \dots, v_n$  and therefore the set indeed spans  $V$ .

- v. The claim is true. To prove that  $TU$  is a subspace of  $W$  we follow the result from class and show the following three things:

$TU$  is not empty: indeed, since  $U$  is a subspace of  $V$  then  $U$  is not empty. So there exists some  $u \in U$ . Clearly,  $Tu \in TU$  so it follows that  $TU$  is not empty.

$TU$  is closed to summation: Let  $w_1, w_2 \in TU$ . By the definition of  $TU$ , there exist  $u_1, u_2 \in U$  such that  $Tu_1 = w_1$  and  $Tu_2 = w_2$ . Since we are given that  $U$  is a subspace of  $V$ , we know that  $U$  is closed to addition. It follows that  $u_1 + u_2 \in U$  and therefore  $T(u_1 + u_2) \in TU$ . Since  $T$  is linear, we know that  $T(u_1 + u_2) = Tu_1 + Tu_2 = w_1 + w_2$ . We conclude that  $w_1 + w_2 \in TU$  and therefore  $TU$  is closed to addition.

$TU$  is closed to multiplication by a scalar: Let  $w \in TU$  and  $\alpha \in \mathbb{R}$ . By the definition of  $TU$ , there exist  $u \in U$  such that  $Tu = w$ . Since we are given that  $U$  is a subspace of  $V$ , we know that  $U$  is closed to multiplication by a scalar. It follows that  $\alpha u \in U$  and therefore  $T(\alpha u) \in TU$ . Since  $T$  is linear, we know that  $T(\alpha u) = \alpha Tu = \alpha w$ . We conclude that  $\alpha w \in TU$  and therefore  $TU$  is closed to multiplication by a scalar.

- vi.  $\diamond$  The claim is false, in fact, the zero transformation allows to construct a simple counterexample. Let us construct another counterexample, just for fun. Consider for example the transformation  $T : \mathbb{R}^3 \mapsto \mathbb{R}^2$  which is defined by

$$T \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} a \\ b \end{pmatrix}.$$

The set  $U = \left\{ \begin{pmatrix} x \\ y \\ 0 \end{pmatrix} \right\} \cup \left\{ \begin{pmatrix} 0 \\ 0 \\ z \end{pmatrix} \right\}$  is not a subspace of  $\mathbb{R}^3$  since it is not closed to addition (check!). However, its image satisfies  $TU = \mathbb{R}^2$ , so  $TU$  is a subspace.

- $\diamond$  The answer does not change if we add the information that  $T$  is onto. In fact, the counterexample we gave above was of a linear transformation that is onto.

- ◇ The answer changes if we add the condition that  $T$  is  $1 - 1$ . To be precise, let us formulate the statement which we claim is **true**:

If  $U$  is a subset of  $V$ , the set  $\{Tu : u \in U\}$  is a subspace of  $W$ , and  $T$  is a  $1 - 1$  transformation, then  $U$  is a subspace of  $V$ .

Proof: To prove that  $U$  is a subspace of  $V$  we follow the result from class and show the following three things:

$U$  is not empty: indeed, since  $TU$  is a subspace of  $W$  then  $TU$  is not empty. By the definition of  $TU$  this implies that  $U$  is not empty.

$U$  is closed to summation: Let  $u_1, u_2 \in U$ . This implies that  $Tu_1, Tu_2 \in TU$ . Since we are given that  $TU$  is a subspace of  $W$ , we know that  $TU$  is closed to addition. It follows that  $Tu_1 + Tu_2 \in TU$ . Since  $T$  is linear, we know that  $T(u_1 + u_2) = Tu_1 + Tu_2$ . We find that  $T(u_1 + u_2) \in TU$ . By the definition of  $TU$ , this implies that there exists  $v \in U$  such that  $Tv = T(u_1 + u_2)$ . Since  $T$  is  $1 - 1$  we know that  $v = u_1 + u_2$  and therefore, that  $u_1 + u_2 \in U$ . So  $U$  is closed to summation.

$U$  is closed to multiplication by a scalar: Let  $u \in U$  and  $\alpha \in \mathbb{R}$ . This implies that  $Tu \in TU$ . Since we are given that  $TU$  is a subspace of  $W$ , we know that  $TU$  is closed to multiplication by a scalar. It follows that  $\alpha Tu \in TU$ . Since  $T$  is linear, we know that  $\alpha Tu = T(\alpha u)$ . We find that  $T(\alpha u) \in TU$ . By the definition of  $TU$ , this implies that there exists  $v \in U$  such that  $Tv = T(\alpha u)$ . Since  $T$  is  $1 - 1$  we know that  $v = \alpha u$  and therefore, that  $\alpha u \in U$ . So  $U$  is closed to multiplication by a scalar.

5. **Remark:** It was not explicitly stated in the formulation of this question that we are considering linear transformations. Still, while writing the answers I will assume that this is the case. Note however, that the answers can be different if one is allowed to use non-linear transformations.

- i. This claim is false. Indeed, we proved in class that  $\dim M_2(\mathbb{R}) = 4$  while  $\dim \mathbb{R}^3 = 3$ . In addition, we proved in class that if the dimension of the domain is bigger than the dimension of the codomain, then a linear transformation cannot be  $1 - 1$ .
- ii. The claim is true. Consider for example,  $T : \mathbb{R}^3 \mapsto M_2(\mathbb{R})$  which is defined by

$$T \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} a & b \\ c & 0 \end{pmatrix}.$$

One can easily check that  $\ker T = \{\underline{0}\}$  and therefore  $T$  is  $1 - 1$ .

- iii. The claim is true. Consider for example,  $T : M_2(\mathbb{R}) \mapsto M_2(\mathbb{R})$  which is defined by

$$T \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a & 0 \\ 0 & 0 \end{pmatrix}.$$

This transformation is not 1-1 since  $T \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = \underline{0}$  and we proved in class that a linear transformation is 1-1 iff the only vector in the domain whose image is  $\underline{0}$  is the zero vector. The transformation is not onto as well. For example,  $\begin{pmatrix} 0 & 0 \\ 0 & 5 \end{pmatrix}$  is not in the image since all matrices in the image have zero in their last entry.

- iv. The claim is false. Indeed, we proved in class that  $\dim M_2(\mathbb{R}) = 4$  and  $\dim \mathbb{R}_3[x] = 4$ . Moreover, we proved in class that if the domain and the codomain have the same dimension and the linear transformation between them is 1-1 then it is also onto.
- v. The claim is true. Consider for example,  $T : M_2(\mathbb{R}) \mapsto \mathbb{R}^3$  which is defined by

$$T \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a \\ b \\ c \end{pmatrix}.$$

The transformation is onto, as each  $\begin{pmatrix} a \\ b \\ c \end{pmatrix} \in \mathbb{R}^3$  has a pre-image, say  $\begin{pmatrix} a & b \\ c & 5 \end{pmatrix}$ . The transformation is not 1-1 as the zero 3-tuple has a nontrivial pre-image, say  $\begin{pmatrix} 0 & 0 \\ 0 & 5 \end{pmatrix}$  and we proved in class that this happens iff a transformation is not 1-1.

- vi. This claim is false. Indeed, we proved in class that  $\dim M_2(\mathbb{R}) = 4$  while  $\dim \mathbb{R}^3 = 3$ . In addition, we proved in class that if the dimension of the domain is smaller than the dimension of the codomain, then a linear transformation cannot be onto.
- vii. The claim is true. Indeed, consider for example  $T : M_2(\mathbb{R}) \mapsto \mathbb{R}^3$  which is defined by

$$T \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a \\ 0 \\ 0 \end{pmatrix}.$$

This transformation is not 1-1 since  $T \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = \underline{0}$  and we proved in class that a linear transformation is 1-1 iff the only vector in the domain whose image is  $\underline{0}$  is the zero vector. The transformation is not

onto as well. For example,  $\begin{pmatrix} 0 \\ 0 \\ 7 \end{pmatrix}$  is not in the image since all matrices in the image have zero in their last entry.