Robotics

Estimation and Learning with Dan Lee

Week 1. Gaussian Model Learning

1.3.2 MLE of Multivariate Gaussian



Objective

$$\widehat{\boldsymbol{\mu}}, \widehat{\boldsymbol{\Sigma}} = \arg\max_{\boldsymbol{\mu}, \boldsymbol{\Sigma}} p(\{\mathbf{x}_i\} | \boldsymbol{\mu}, \boldsymbol{\Sigma})$$

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$$\widehat{\boldsymbol{\mu}}, \widehat{\boldsymbol{\Sigma}} = \arg\max_{\boldsymbol{\mu}, \boldsymbol{\Sigma}} p(\{\mathbf{x}_i\} | \boldsymbol{\mu}, \boldsymbol{\Sigma})$$

Assuming independence of observations,

$$\widehat{\boldsymbol{\mu}}, \widehat{\boldsymbol{\Sigma}} = \arg\max_{\boldsymbol{\mu}, \boldsymbol{\Sigma}} \prod_{i=1}^{N} p(\mathbf{x}_i | \boldsymbol{\mu}, \boldsymbol{\Sigma})$$

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(1) Take the log!

 $arg max \ likelihood \leftrightarrow arg max \ln(likelihood)$

$$\log(x_1 \times x_2 \times \dots \times x_k) = \log(x_1) + \log(x_1) + \dots + \log(x_k)$$

$$\arg \max_{\boldsymbol{\mu}, \boldsymbol{\Sigma}} \prod_{i=1}^{N} p(\mathbf{x}_{i} | \boldsymbol{\mu}, \boldsymbol{\Sigma}) \implies \arg \max_{\boldsymbol{\mu}, \boldsymbol{\Sigma}} \sum_{i=1}^{N} \ln p(\mathbf{x}_{i} | \boldsymbol{\mu}, \boldsymbol{\Sigma})$$

$$\widehat{\boldsymbol{\mu}}, \widehat{\boldsymbol{\Sigma}} = \arg\max_{\boldsymbol{\mu}, \boldsymbol{\Sigma}} \sum_{i=1}^{N} \ln p(\mathbf{x}_i | \boldsymbol{\mu}, \boldsymbol{\Sigma})$$

(2) Gaussian!

$$p(\mathbf{x}) = \frac{1}{(2\pi)^{D/2} |\Sigma|^{1/2}} \exp\left\{-\frac{1}{2} (\mathbf{x} - \mathbf{\mu})^T \Sigma^{-1} (\mathbf{x} - \mathbf{\mu})\right\}$$

$$\ln p(\mathbf{x}_i|\mathbf{\mu}, \mathbf{\Sigma}) \longrightarrow \left\{ -\frac{1}{2} (\mathbf{x}_i - \mathbf{\mu})^T \mathbf{\Sigma}^{-1} (\mathbf{x}_i - \mathbf{\mu}) - \frac{1}{2} \ln|\mathbf{\Sigma}| + c \right\}$$

$$c = -D/2\ln(2\pi)$$

$$\widehat{\boldsymbol{\mu}}, \widehat{\boldsymbol{\Sigma}} = \arg\max_{\boldsymbol{\mu}, \boldsymbol{\Sigma}} \sum_{i=1}^{N} \left\{ -\frac{1}{2} (\mathbf{x}_i - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x}_i - \boldsymbol{\mu}) - \frac{1}{2} \ln|\boldsymbol{\Sigma}| + c \right\}$$



$$\widehat{\boldsymbol{\mu}}, \widehat{\boldsymbol{\Sigma}} = \arg\min_{\boldsymbol{\mu}, \boldsymbol{\Sigma}} \sum_{i=1}^{N} \left\{ \frac{1}{2} (\mathbf{x}_i - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x}_i - \boldsymbol{\mu}) + \frac{1}{2} \ln|\boldsymbol{\Sigma}| \right\}$$

$$\widehat{\boldsymbol{\mu}}, \widehat{\boldsymbol{\Sigma}} = \arg\min_{\boldsymbol{\mu}, \boldsymbol{\Sigma}} \underbrace{\sum_{i=1}^{N} \left\{ \frac{1}{2} (\mathbf{x}_i - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x}_i - \boldsymbol{\mu}) + \frac{1}{2} \ln|\boldsymbol{\Sigma}| \right\}}_{\boldsymbol{\lambda}}$$

• At optimum,

①
$$\frac{\partial J}{\partial \mathbf{\mu}} = \mathbf{0} \longrightarrow \widehat{\mathbf{\mu}}$$
 ② $\frac{\partial J(\widehat{\mathbf{\mu}}, \Sigma)}{\partial \Sigma} = \mathbf{0} \longrightarrow \widehat{\Sigma}$

In summary, we have

$$\widehat{\mathbf{\mu}} = \frac{1}{N} \sum_{i=1}^{N} \mathbf{x}_{i}$$

$$\widehat{\Sigma} = \frac{1}{N} \sum_{i=1}^{N} (\mathbf{x}_i - \widehat{\boldsymbol{\mu}}) (\mathbf{x}_i - \widehat{\boldsymbol{\mu}})^{\mathsf{T}}$$

Multi-dimension Distribution: Example

• Ball color in multi-channels

