1 Reversible Architectures [3pts]: In this section, we will investigate a variant for implementing reversible block with affine coupling layers. Consider the following reversible affline coupling block:

$$y_1 = \exp(\mathcal{G}(x_2)) \circ x_1 + \mathcal{F}(x_2)$$
  

$$y_2 = \exp(s) \circ x_2$$
(1)

where  $\circ$  denotes element-wise multiplication. The each inputs  $x_1, x_2 \in \mathbb{R}^{\frac{d}{2}}$ . The functions  $\mathcal{F}$  and  $\mathcal{G}$  maps from  $\mathbb{R}^{\frac{d}{2}} \to \mathbb{R}^{\frac{d}{2}}$ . This modified block is identical to the ordinary reversible block, except that the inputs  $x_1$  and  $x_2$  are multiplied element-wise by vectors  $\exp(\mathcal{F}(x_2))$  and  $\exp(s)$ .

1. (1pt) Give the equations for inverting this block, i.e. computing  $x_1$  and  $x_2$  from  $y_2$  and  $y_2$ . You may use / to denote element-wise division.

2. (1pt) Give a formula for the Jacobian  $\frac{\partial y}{\partial x}$ , where y denotes the concatenation of  $y_1$  and  $y_2$ . You may denote the solution as a block matrix, as long as you clearly define what the matrix for each block corresponds to.

$$\frac{\partial y_{l}}{\partial x_{l}} = \exp(S(x_{l})) \frac{\partial y_{l}}{\partial x_{l}} = F'(x_{l}) + S'(x_{l}) \circ \exp(S(x_{l})) \circ x_{l}$$

$$\frac{\partial x_1}{\partial x_1} = 0 \qquad \frac{\partial x_2}{\partial x_2} = 0 \times p(s)$$

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$$J = \begin{bmatrix} exp(S(x_1))/F'(x_2) + S'(x_2)oexp(S(x_2))ox_1 \\ - - - - - - - \end{bmatrix} \in \mathbb{R}^{D \times D}$$

Where all blocks are diagonal D/2 x P/2 matrices with the stated vectors as their diagonals.

Because of the element-wise nucluse,
$$all \frac{\partial x_{i}}{\partial x_{i}} = 0 \quad \text{for } i \neq j$$

3. (1pt) Give a formula for the determinant of the Jacobian from previous part, i.e. compute  $det\left(\frac{\partial y}{\partial x}\right)$ . Is this a volume preserving transformation? Justify your answer.

$$= \frac{0/2}{17} = \frac{0/2}{17} exp(S(x_{ij}) + S_{i})$$

$$= exp(S_{ij} G(x_{2i}) + S_{i}) + 1$$

$$= exp(S_{ij} G(x_$$

50 since | J| # 1 , this Evansformation is not volume preserving !

**2 Variational Free Energy [6pts]:** In this question you will derive some expressions related to variational free energy which is maximized to train a VAE. Recall that the VFE is defined as:

$$\mathcal{F}(q) = \mathbb{E}_q[\log p(\mathbf{x}|\mathbf{z})] - D_{KL}(q(\mathbf{z})||p(\mathbf{z}))$$

where KL divergence is defined as

$$D_{KL}(q(z)||p(z)) = \mathbb{E}_q[\log q(z) - \log p(z)]$$

We will assume that the prior z is a standard Gaussian:

$$p(z) = \mathcal{N}(z; 0, I) = \prod_{i=1}^{D} p_i(z_i) = \prod_{i=1}^{D} \mathcal{N}(z_i; 0, 1)$$

Similarly we will assume that the variational approximation q(z) is a fully factorized (i.e., diagonal) Gaussian:

$$q(z) = \mathcal{N}(z; \mu, \Sigma) = \prod_{i=1}^{D} q_i(z_i) = \prod_{i=1}^{D} \mathcal{N}(z_i; \mu_i, \sigma_i)$$

1. **(1pt)** Show that:

$$\mathcal{F}(q) = \log p(\mathbf{x}) - D_{KL}(q(\mathbf{z})||p(\mathbf{z}|\mathbf{x}))$$

Huha, this one feels like a Expiral physics home world /

$$F(q) = E_q \left[ \left( o_S(p(x|z)) \right] - D_{KL} \left( q(z) || p(z) \right) \right]$$

$$= E_q \left[ \left( o_S(p(x|z)) - \left( o_S(q(z)) + \left( o_S(p(z)) \right) \right) \right]$$

$$= E_q \left[ \left( o_S(p(x|z)) - \left( o_S(q(z)) \right) \right]$$

$$= E_q \left[ \left( o_S(p(x)) - \left( o_S(z) \right) \right]$$

$$= E_q \left[ \left( o_S(p(x)) + \left( o_S(p(z)) - \left( o_S(p(z)) \right) \right) \right]$$

$$= \left( o_S(p(x)) - E_q \left( o_S(p(z)) - \left( o_S(p(z)) \right) \right) \right]$$

$$= \left( o_S(p(x)) - D_{KL} \left( q(z) || p(z|x) \right) \right)$$

(1pt) Show that the KL term decomposes as a sum of KL terms for individual dimensions. In particular,

$$D_{KL}(q(z)||p(z)) = \sum_{i} D_{KL}(q_{i}(z_{i})||p_{i}(z_{i}))$$

$$\begin{aligned} & D_{KL}(q(z)||p(z)) = E_{q} \sum (o_{S} q(z) - (o_{S} p(z)) \\ & = E_{q} \sum (o_{S} (T_{i} q_{i}(z_{i})) - (o_{S} (T_{i} p_{i}(z_{i}))) \\ & = E_{q} \sum \sum_{i=1}^{S} ((o_{S} q_{i}(z_{i})) - (o_{S} p_{i}(z_{i}))) \\ & = \sum_{i=1}^{S} E_{q} \sum (o_{S} q_{i}(z_{i})) - (o_{S} p_{i}(z_{i})) \\ & = \sum_{i=1}^{S} E_{q} \sum (o_{S} q_{i}(z_{i})) - (o_{S} p_{i}(z_{i})) \\ & = \sum_{i=1}^{S} D_{KL}(q_{i}(z_{i})||p_{i}(z_{i})) \end{aligned}$$

3. (2pts) Give an explicit formula for the KL divergence  $D_{KL}(q_i(z_i)||p_i(z_i))$ . This should be a mathematical expression involving  $\mu_i$  and  $\sigma_i$ .

$$\begin{split} D_{\mu L} \left( q_{i}(z_{i}) || p_{i}(z_{i}) \right) &= E_{q} L \left( o_{g} \left( q_{i}(z_{i}) - (o_{g} \left( p_{i}(z_{i}) \right) \right) \right) \\ &= \int_{\mathbb{R}} dz \, q_{i}(z) \left( (o_{g} \, q_{i}(z_{i}) - (o_{g} \, p_{i}(z_{i}) \right) \right) \\ &= \int_{\mathbb{R}} dz \, q_{i}(z) \left( o_{g} \frac{q_{i}(z_{i})}{p_{i}(z_{i})} \right) \\ &= \int_{\mathbb{R}} dz \, q_{i}(z) \left( o_{g} \left( \frac{p_{i}(z_{i})}{p_{i}(z_{i})} - \frac{p_{i}(z_{i})}{p_{i}(z_{i})} \right) \right) \\ &= \int_{\mathbb{R}} dz \, q_{i}(z) \left( o_{g} \left( o_{i}^{-1} \right) + \left( o_{g} \left( \frac{e_{x} p_{i}}{p_{x}} - \frac{e_{x} p_{i}}{p_{x}} \right) \right) \right) \\ &= \int_{\mathbb{R}} dz \, q_{i}(z_{i}) \left( o_{g} \left( o_{i}^{-1} \right) + \left( o_{g} \left( \frac{e_{x} p_{i}}{p_{x}} - \frac{e_{x} p_{i}}{p_{x}} \right) \right) \right) \\ &= \left( o_{g} \left( o_{i}^{-1} \right) - \frac{1}{2} o_{x} \int_{\mathbb{R}} dz \, q_{i}(z_{i}) \left( z - \mu_{i} \right)^{2} + \frac{1}{2} \int_{\mathbb{R}} dz \, q_{i}(z_{i}) z^{2} \right) \\ &= \left( o_{g} \left( o_{i}^{-1} \right) - \frac{1}{2} o_{x} \int_{\mathbb{R}} dz \, q_{i}(z_{i}) \left( z - \mu_{i} \right)^{2} + \frac{1}{2} \int_{\mathbb{R}} dz \, q_{i}(z_{i}) z^{2} \right) \\ &= \left( o_{g} \left( o_{i}^{-1} \right) - \frac{1}{2} o_{x} \int_{\mathbb{R}} dz \, q_{i}(z_{i}) \left( o_{i}^{-1} + \mu_{i}^{-2} \right) V_{op}(x_{i}) z^{2} \right) \right) \\ &= \frac{1}{2} \left( \mu_{i}^{2} + \sigma_{i}^{2} - \left( o_{g} \left( \sigma_{i}^{2} \right) - 1 \right) \right) \end{split}$$

4. (2pts) One way to do gradient descent on the KL term is to apply the formula from above. Another approach is to compute stochastic gradients using the reparameterization trick:

$$\nabla_{\boldsymbol{\theta}} D_{KL}(q_i(z_i)||p_i(z_i)) = \mathbb{E}_{\epsilon}[\nabla_{\boldsymbol{\theta}} t_i]$$

, where

$$oldsymbol{ heta} = egin{bmatrix} \mu_i \ \sigma_i \end{bmatrix}$$

and

$$z_{i} = \mu_{i} + \sigma_{i} \epsilon_{i}$$

$$r_{i} = \log q_{i}(z_{i})$$

$$s_{i} = \log p_{i}(z_{i})$$

$$t_{i} = r_{i} - s_{i}$$
(2)

Show how to compute a stochastic estimate of  $\nabla_{\theta} D_{KL}(q_i(z_i)||p_i(z_i))$  by doing backpropagation on the above equations. You may find it helpful to draw the computation graph.

Let's start with 
$$\overline{O}_{i} = \frac{\partial t_{i}}{\partial O_{i}} = \int M_{i}, \overline{O}_{i}$$
:

 $\overline{C}_{i} = I$ ,  $\overline{F}_{i} = I$ ,  $\overline{S}_{i} = -I$ 
 $\overline{Z}_{i} = \overline{F}_{i} \frac{\partial^{i}_{i}}{\partial z_{i}} + \overline{S}_{i} \frac{\partial S_{i}}{\partial z_{i}} = \frac{\partial}{\partial z_{i}} (o_{S} \hat{P}_{i}(z_{i}) - \frac{\partial}{\partial z_{i}} (o_{S} \hat{P}_{i}(z_{i})))$ 
 $= \frac{\partial}{\partial z_{i}} \left[ (o_{S} \hat{Q}_{i}(z_{i}) - (o_{S} \hat{P}_{i}(z_{i}))\right]$ 
 $= \frac{\partial}{\partial z_{i}} \left[ (o_{S} (V \sum_{i} \overline{D}_{i})^{-1} + (v \sum_{i} \overline{D}_{i})^{-1} \right] - \frac{(z_{i} - M_{i})^{-1}}{2 \sigma_{i}^{-1}}$ 
 $= \frac{\partial}{\partial z_{i}} \left[ (o_{S} (V \sum_{i} \overline{D}_{i})^{-1}) - \frac{(z_{i} - M_{i})^{-1}}{2 \sigma_{i}^{-1}} \right]$ 
 $= \frac{\partial}{\partial z_{i}} \left[ (o_{S} \hat{P}_{i}(z_{i}) - \frac{\partial}{\partial z_{i}} (o_{S} \hat{P}_{i}(z_{i}) - z_{i})\right]$ 
 $= \frac{\partial}{\partial z_{i}} \left[ (o_{S} \hat{P}_{i}(z_{i}) - z_{i}) + z_{i} \right]$ 
 $= \frac{\partial}{\partial z_{i}} \left[ (o_{S} \hat{P}_{i}(z_{i}) - z_{i}) + z_{i} \right]$ 
 $= \frac{\partial}{\partial z_{i}} \left[ (o_{S} \hat{P}_{i}(z_{i}) - z_{i}) + z_{i} \right]$ 
 $= \frac{\partial}{\partial z_{i}} \left[ (o_{S} \hat{P}_{i}(z_{i}) - z_{i}) + z_{i} \right]$ 
 $= \frac{\partial}{\partial z_{i}} \left[ (o_{S} \hat{P}_{i}(z_{i}) - z_{i}) + z_{i} \right]$ 
 $= \frac{\partial}{\partial z_{i}} \left[ (o_{S} \hat{P}_{i}(z_{i}) - z_{i}) + z_{i} \right]$ 

We know that  $2i = Mi + \sigma_i \epsilon_i$ , so  $\epsilon_i = \frac{2i - Mi}{\sigma_i}$ and  $\epsilon_i = \frac{2i - Mi}{\sigma_i}$ 

$$= \sum_{i=0}^{\infty} \sum_{j=0}^{\infty} \sum_{i=0}^{\infty} \sum_{i=0}^{\infty} \sum_{i=0}^{\infty} \sum_{j=0}^{\infty} \sum_{i=0}^{\infty} \sum_{i=0}^{\infty} \sum_$$

$$\frac{\partial}{\partial \sigma_{i}} \int_{\mu} \left( \frac{\partial}{\partial x_{i}} \right) \left[ \frac{\partial}{\partial x_{i}} \right] dx = E_{\epsilon_{i}} \left[ \frac{\partial}{\partial x_{i}} + \frac{\partial}{\partial x_{i}} \right] + E_{\epsilon_{i}} \left[ \frac{\partial}{\partial x_{i}} + \frac{\partial}{\partial x_{i}} \right] + E_{\epsilon_{i}} \left[ \frac{\partial}{\partial x_{i}} + \frac{\partial}{\partial x_{i}} \right] + E_{\epsilon_{i}} \left[ \frac{\partial}{\partial x_{i}} + \frac{\partial}{\partial x_{i}} \right] = -\sigma_{i}^{2} + E_{\epsilon_{i}} \left[ \frac{\partial}{\partial x_{i}} + \frac{\partial}{\partial x_{i}} \right] + E_{\epsilon_{i}} \left[ \frac{\partial}{\partial x_{i}} + \frac{\partial}{\partial x_{i}} \right] = \sigma_{i}^{2} + E_{\epsilon_{i}} \left[ \frac{\partial}{\partial x_{i}} + \frac{\partial}{\partial x_{i}} + \frac{\partial}{\partial x_{i}} \right] = \sigma_{i}^{2} + \sigma_{i}$$

So: 
$$Svod_{O_i}$$
  $D_{KL}(q_i(z_i)||p_i(z_i)) = E_{E_i}$   $[Svad_{O_i}$   $E_i]$ 

$$= \begin{pmatrix} M_i \\ \sigma_i - \sigma_i^{-1} \end{pmatrix}$$

Tulcing the derivative of the result
from 3. Sives the exact some goodient/