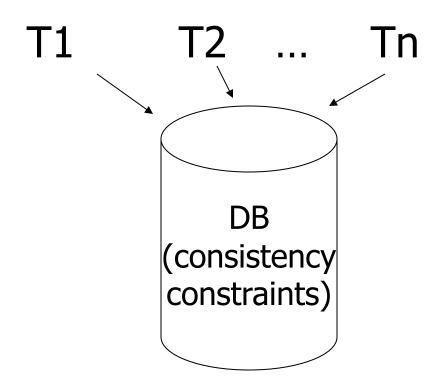
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Notes 09: Concurrency Control

Ullman et al. : Database System Principles

Chapter 18 [18] Concurrency Control



Interactions among concurrently executing transactions can cause the database state to become inconsistent, even when the transactions individually preserve correctness of the state, and there is no system failure.

Thus, the timing of individual steps of different transactions needs to be regulated in some manner.

This regulation is the job of the *scheduler component of the DBMS, and the* general process of assuring that transactions preserve consistency when executing simultaneously is called *concurrency control*.

In most situations, the scheduler will execute the reads and writes directly, first calling on the buffer manager if the desired database element is not in a buffer.

However, in some situations, it is not safe for the request to be executed immediately.

The scheduler must delay the request.

In some concurrency-control techniques, the scheduler may even abort the transaction that issued the request

Example:

T1: Read(A)

 $A \leftarrow A+100$

Write(A)

Read(B)

 $B \leftarrow B+100$

Write(B)

Constraint: A=B

T2: Read(A)

 $A \leftarrow A \times 2$

Write(A)

Read(B)

 $B \leftarrow B \times 2$

Write(B)

A schedule is a sequence of the important actions taken by one or more transactions.

When studying concurrency control, the important read and write actions take place in the main-memory buffers, not the disk.

That is, a database element *A that is brought to a* buffer by some transaction *T may be read or* written in that buffer not only by *T but by other transactions that access A.*

A schedule is serial if its actions consist of all the actions of one transaction, then all the actions of another transaction, and so on.

No mixing of the actions is allowed.

Schedule A (serial)

		Α	В
T1	T2	25	25
Read(A); $A \leftarrow A+100$			
Write(A);		125	
Read(B); B \leftarrow B+100;			
Write(B);			125
	Read(A);A \leftarrow A \times 2;		
	Write(A);	250	
	Read(B);B \leftarrow B \times 2;		
	Write(B);		250
	VVIICC(D),	250	250

Schedule B (serial)

		Α	В
T1	T2	25	25
Read(A); A ← A+100	Read(A); $A \leftarrow A \times 2$; Write(A); Read(B); $B \leftarrow B \times 2$; Write(B);	50	50
Write(A);		150	
Read(B); B \leftarrow B+100; Write(B);			150
		150	150
			1

A schedule *S* is serializable if there is a serial schedule *S'* such that for every initial database state, the effects of *S* and *S'* are the same.

Schedule C (serializable)

		Α	В
T1	T2	25	25
Read(A); $A \leftarrow A+100$			
Write(A);		125	
	Read(A);A \leftarrow A \times 2;		
	Write(A);	250	
Read(B); B \leftarrow B+100;			
Write(B);			125
	Read(B);B \leftarrow B \times 2;		
	Write(B);		250
		250	250

Schedule D (not serializable)

		Α	В
_T1	T2	25	25
Read(A); $A \leftarrow A+100$			
Write(A);		125	
	Read(A);A \leftarrow A \times 2;		
	Write(A);	250	
	Read(B);B \leftarrow B×2;		
	Write(B);		50
Read(B); B \leftarrow B+100;			
Write(B);			150
		250	150

Schedule E

Same as Schedule D but with new T2'

		Α	В
_T1	T2'	25	25
Read(A); $A \leftarrow A+100$			
Write(A);		125	
	Read(A);A \leftarrow A \times 1;		
	Write(A);	125	
	Read(B);B \leftarrow B \times 1;		
	Write(B);		25
Read(B); B \leftarrow B+100;			
Write(B);			125
		125	125

- Want schedules that are "good", regardless of
 - initial state and
 - transaction semantics
- Only look at order of read and writes

It is not realistic for the scheduler to concern itself with the details of computation undertaken by transactions.

Any database element *A that a transaction T writes is given a value* that depends on the database state in such a way that no arithmetic coincidences occur.

To make the notation precise:

- 1. An action is an expression of the form $r_i(X)$ or $W_i(X)$, meaning that transaction T_i , reads or writes, respectively, the database element X.
- 2. A transaction T_i is a sequence of actions with subscript i.
- 3. A schedule S of a set of transactions T is a sequence of actions, in which for each transaction T_i in T, the actions of T_i appear in S in the same order that they appear in the definition of T_i itself. We say that S is an interleaving of the actions of the transactions of which it is composed.

Example:

$$Sc=r_1(A)w_1(A)r_2(A)w_2(A)r_1(B)w_1(B)r_2(B)w_2(B)$$

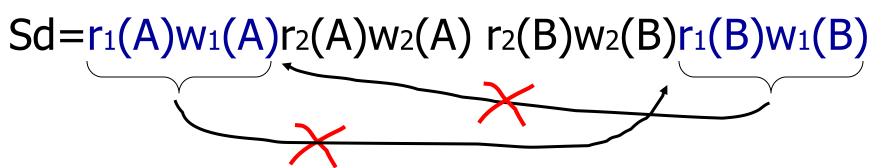
 $Sc'=r_1(A)w_1(A) r_1(B)w_1(B)r_2(A)w_2(A)r_2(B)w_2(B)$

 T_1 T_2

Sc is "equivalent" to a serial schedule.

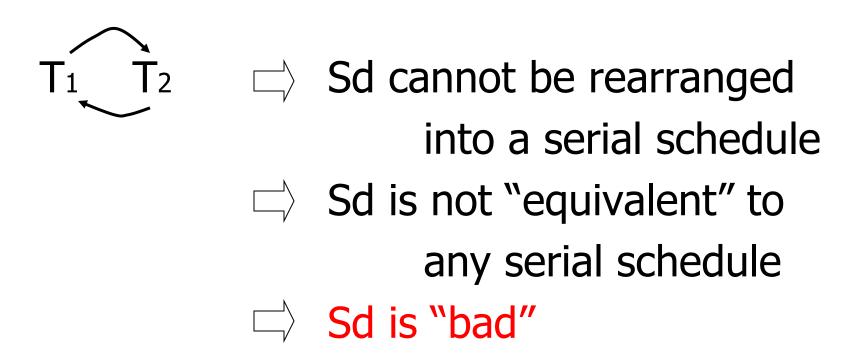
Sc is "good"

However, for Sd:



as a matter of fact,
 T₂ must precede T₁
 in any equivalent schedule,
 i.e., T₂ → T₁

- $T_2 \rightarrow T_1$
- Also, $T_1 \rightarrow T_2$



Returning to Sc

$$Sc=r_1(A)w_1(A)r_2(A)w_2(A)r_1(B)w_1(B)r_2(B)w_2(B)$$

$$T_1 \rightarrow T_2 \qquad T_1 \rightarrow T_2$$

• no cycles \Rightarrow Sc is "equivalent" to a serial schedule (in this case T₁,T₂)

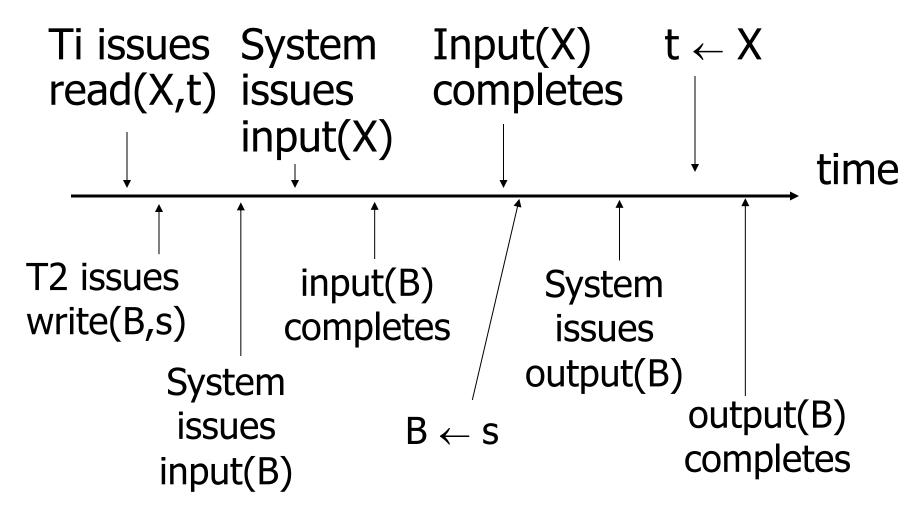
Concepts

Transaction: sequence of ri(x), wi(x) actions

Schedule: represents chronological order in which actions are executed

Serial schedule: no interleaving of actions or transactions

What about concurrent actions?

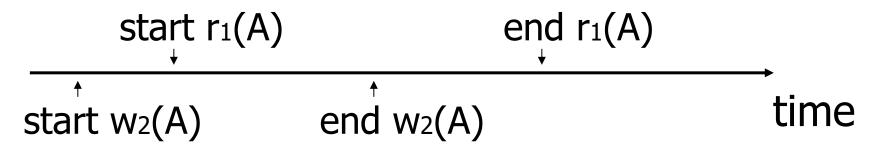


So net effect is either

- $S = ... r_1(X) ... w_2(B) ... or$
- $S = ...w_2(B)...r_1(X)...$

We assume that elementary actions are atomic, and follow each other.

What about conflicting, concurrent actions on same object?



- Assume equivalent to either r₁(A) w₂(A)
 or w₂(A) r₁(A)
- ⇒ low level synchronization mechanism
- Assumption called "atomic actions"

Definition

S₁, S₂ are <u>conflict equivalent</u> schedules if S₁ can be transformed into S₂ by a series of non-conflicting swaps of adjacent actions.

A schedule is <u>conflict serializable</u> if it is conflict equivalent to some serial schedule.

Example:

$$r_1(A)$$
; $w_1(A)$; $r_2(A)$; $w_2(A)$; $r_1(B)$; $w_1(B)$; $r_2(B)$; $w_2(B)$;

We claim this schedule is conflict-serializable.

```
1. r_1(A); w_1(A); r_2(A); w_2(A); r_1(B); w_1(B); r_2(B); w_2(B); 2. r_1(A); w_1(A); r_2(A); r_1(B); r_2(A); r_1(B); r_2(A); r_2(A); r_2(B); r_2(B);
```

 Conflict-serializability is a sufficient condition for serializability i.e., a conflict-serializable schedule is a serializable schedule.

 Conflict-serializability is not required for a schedule to be serializable.

 Schedulers in commercial systems generally use conflict-serializability when they need to guarantee serializability.

Precedence graph P(S) (S is schedule)

Nodes: transactions in S

Arcs: $Ti \rightarrow Tj$ whenever

- p_i(A), q_j(A) are actions in S
- $p_i(A) <_S q_j(A)$ (pi(A) precedes qj(A) in S)
- at least one of p_i, q_j is a write

Exercise:

What is P(S) for
 S = w₃(A) w₂(C) r₁(A) w₁(B) r₁(C) w₂(A) r₄(A) w₄(D)

• Is S serializable?

Another Exercise:

What is P(S) for
 S = w₁(A) r₂(A) r₃(A) w₄(A) ?

Lemma

 S_1 , S_2 conflict equivalent $\Rightarrow P(S_1)=P(S_2)$

<u>Lemma</u>

 S_1 , S_2 conflict equivalent $\Rightarrow P(S_1)=P(S_2)$

Proof:

Assume $P(S_1) \neq P(S_2)$

 $\Rightarrow \exists T_i: T_i \rightarrow T_j \text{ in } S_1 \text{ and not in } S_2$

$$\Rightarrow S_1 = ...p_i(A)... q_j(A)...$$

$$\int p_i, q_j$$

$$S_2 = ...q_j(A)...p_i(A)...$$
 conflict

 \Rightarrow S₁, S₂ not conflict equivalent

Note: $P(S_1)=P(S_2) \not\Rightarrow S_1$, S_2 conflict equivalent

Counter example:

$$S_1=w_1(A) r_2(A) w_2(B) r_1(B)$$
 (cannot swap)

$$S_2=r_2(A) w_1(A) r_1(B) w_2(B)$$

Theorem

 $P(S_1)$ acyclic \iff S_1 conflict serializable

- (←) Assume S₁ is conflict serializable
- $\Rightarrow \exists S_s: S_s, S_1 \text{ conflict equivalent}$
- $\Rightarrow P(S_s) = P(S_1)$
- \Rightarrow P(S₁) acyclic since P(S_s) is acyclic

Theorem

 $P(S_1)$ acyclic \iff S_1 conflict serializable

 (\Rightarrow) Assume P(S₁) is acyclic Transform S₁ as follows:

- T₁
 T₂
 T₃
 T₄
- (1) Take T1 to be transaction with no incident arcs
- (2) Move all T₁ actions to the front

$$S1 = \dots p_1(A) \dots p_1(A) \dots$$

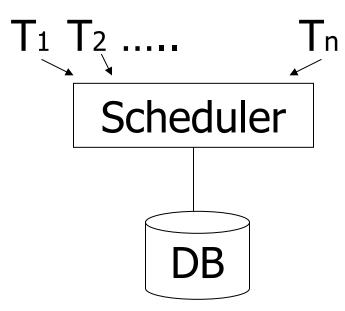
- (3) we now have $S_1 = \langle T_1 \text{ actions } \rangle \langle ... \text{ rest } ... \rangle$
- (4) repeat above steps to serialize rest!

How to enforce serializable schedules?

Option 1: run system, recording P(S); at end of day, check for P(S) cycles and declare if execution was good

How to enforce serializable schedules?

Option 2: prevent P(S) cycles from occurring

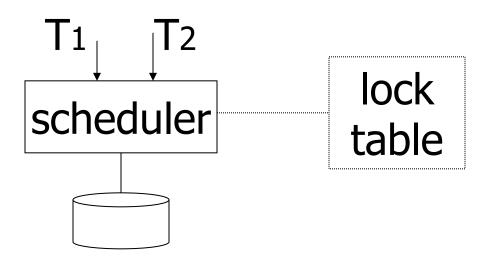


A locking protocol

Two new actions:

lock (exclusive): li (A)

unlock: ui (A)



Rule #1: Consistency of transactions

Ti: ... li(A) ... pi(A) ... ui(A) ...

- 1. A transaction can only read or write an element if it previously was granted a lock on that element and hasn't yet released the lock.
- 2. If a transaction locks an element, it must later unlock that element.

Rule #2 Legality of schedules

$$S = \dots Ii(A) \dots ui(A) \dots$$
no $Ij(A)$

Locks must have their intended meaning: no two transactions may have locked the same element without one having first released the lock.

Exercise:

What schedules are legal? What transactions are consistent? $S1 = I_1(A)I_1(B)r_1(A)w_1(B)I_2(B)u_1(A)u_1(B)$ $r_2(B)w_2(B)u_2(B)l_3(B)r_3(B)u_3(B)$ $S2 = I_1(A)r_1(A)w_1(B)u_1(A)u_1(B)$ $I_2(B)r_2(B)w_2(B)I_3(B)r_3(B)u_3(B)$ $S3 = I_1(A)r_1(A)u_1(A)I_1(B)w_1(B)u_1(B)$ $I_2(B)r_2(B)w_2(B)u_2(B)I_3(B)r_3(B)u_3(B)$

Exercise:

What schedules are legal? What transactions are consistent? $S1 = I_1(A)I_1(B)r_1(A)w_1(B)I_2(B)u_1(A)u_1(B)$ $r_2(B)w_2(B)u_2(B)l_3(B)r_3(B)u_3(B)$ (S1: not legal) $S2 = I_1(A)r_1(A)w_1(B)u_1(A)u_1(B)$ (T1: not consistent) $I_2(B)r_2(B)w_2(B)I_3(B)r_3(B)u_3(B)$ (S2: not legal) $S3 = I_1(A)r_1(A)u_1(A)I_1(B)w_1(B)u_1(B)$ $I_2(B)r_2(B)w_2(B)u_2(B)I_3(B)r_3(B)u_3(B)$ (S3: legal schedule, T1,T2,T3: consistent transactions)

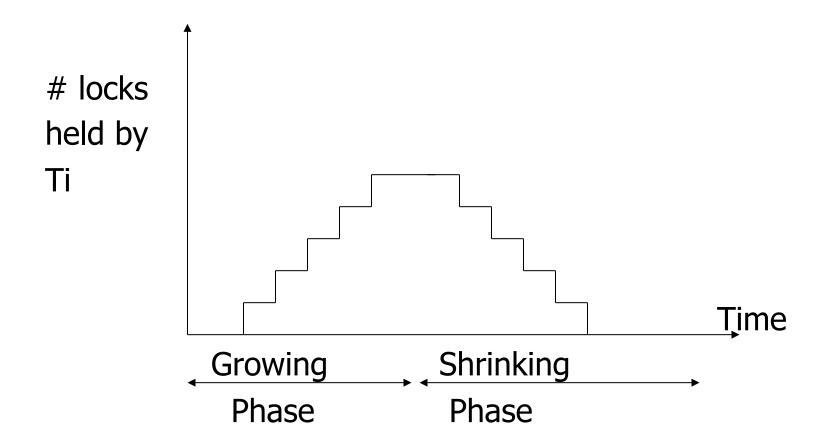
Schedule F (legal schedule of consistent transactions)

(still not equivalent to a serial schedule)

	_A	D
T2	25	25
	125	
l ₂ (A);Read(A)		
A←Ax2;Write(A);u ₂ (A)	250	
l ₂ (B);Read(B)		
B←Bx2;Write(B);u ₂ (B)		50
		150
	250	150
	I ₂ (A);Read(A) A←Ax2;Write(A);u ₂ (A) I ₂ (B);Read(B)	T2 125 12(A);Read(A) A — Ax2;Write(A);u ₂ (A) 12(B);Read(B) B — Bx2;Write(B);u ₂ (B)

Rule #3 Two phase locking (2PL)

for transactions



Schedule G

T1	T2
lı(A);Read(A)	
A←A+100;Write(A)	
l1(B); u1(A)	l ₂ (A);Read(A) A←Ax2;Write(A);[2(B)

Schedule G

<u>T1</u>	T2
l1(A);Read(A)	
A←A+100;Write(A)	
l1(B); u1(A)	له مديداً
	I ₂ (A);Read(A) delayed
	A←Ax2;Write(A);[2(B))
Read(B);B ← B+100	
Write(B); u ₁ (B)	

Schedule G

<u>T1</u>	T2
lı(A);Read(A)	
A←A+100;Write(A)	
I1(B); u1(A)	
	l ₂ (A);Read(A) delayed
	A←Ax2;Write(A);(□(B))
Read(B);B ← B+100	
Write(B); u1(B)	
	l ₂ (B); u ₂ (A);Read(B)
	$B \leftarrow Bx2;Write(B);u_2(B);$

Schedule G "good" (equivalent to a serial)

		A	B
T1	T2	25	25
I ₁ (A);Read(A); A←A+100			
Write(A); $I_1(B)$; $U_1(A)$		125	
	I ₂ (A);Read(A)		
	A←Ax2;Write(A);u ₂ (A)	250	
	I ₂ (B); delayed		
Read(B);			
B←B+100;Write(B);u ₁ (B)			125
	l ₂ (B);Read(B)		
	B←Bx2;Write(B);u ₂ (B)	250	250

Theorem Rules #1,2,3 \Rightarrow conflict (consistency, legality, 2PL) serializable schedule

Theorem Rules #1,2,3 \Rightarrow conflict (consistency, legality, 2PL) serializable schedule

Intuitively, each two-phase-locked transaction may be thought to execute in its entirety at the instant it issues its first unlock request. In a conflict-equivalent serial schedule transactions appear in the same order as their first unlocks.

Theorem Rules #1,2,3 \Rightarrow conflict serializable schedule

Proof:

BASIS: If n = 1, there is nothing to do; S is already a serial schedule.

INDUCTION: Suppose S involves n transactions T_1, T_2, \ldots, T_n , and let T_i be the transaction with the first unlock action in the entire schedule S, say u_i (x).

We claim it is possible to move all the read and write actions of T_i forward to the beginning of the schedule without passing any conflicting reads or writes.

```
Theorem Rules #1,2,3 \Rightarrow conflict (2PL) serializable schedule
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To help in proof:

Definition Shrink(Ti) = SH(Ti) =

first unlock action of Ti

Lemma

$$Ti \rightarrow Tj \text{ in } S \Rightarrow SH(Ti) <_S SH(Tj)$$

Proof of lemma:

 $Ti \rightarrow Tj$ means that

$$S = ... p_i(A) ... q_j(A) ...; p,q conflict$$

By rules 1,2:

$$S = \dots p_i(A) \dots u_i(A) \dots |_{j}(A) \dots q_j(A) \dots$$

By rule 3: SH(Ti) SH(Tj)

So, $SH(Ti) <_S SH(Tj)$

Theorem Rules #1,2,3
$$\Rightarrow$$
 conflict (2PL) serializable schedule

Proof:

(1) Assume P(S) has cycle

$$T_1 \rightarrow T_2 \rightarrow \dots T_n \rightarrow T_1$$

- (2) By lemma: $SH(T_1) < SH(T_2) < ... < SH(T_1)$
- (3) Impossible, so P(S) acyclic
- $(4) \Rightarrow S$ is conflict serializable

Schedule H (T₂ reversed)



Deadlock !!!

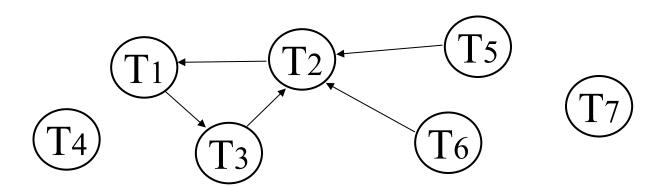
- Assume deadlocked transactions are rolled back
 - They have no effect
 - They do not appear in schedule

Deadlocks

- Detection
 - Wait-for graph
- Prevention
 - Resource ordering
 - Timeout
 - Wait-die
 - Wound-wait

Deadlock Detection

- Build Wait-For graph (Ti -> Tj edge if Ti waits for Tj)
- Use lock table structures
- Build incrementally or periodically
- When cycle found, rollback victim



Resource Ordering (prevention)

- Order all elements A₁, A₂, ..., A_n
- A transaction T can lock A_i after A_j only if i > j

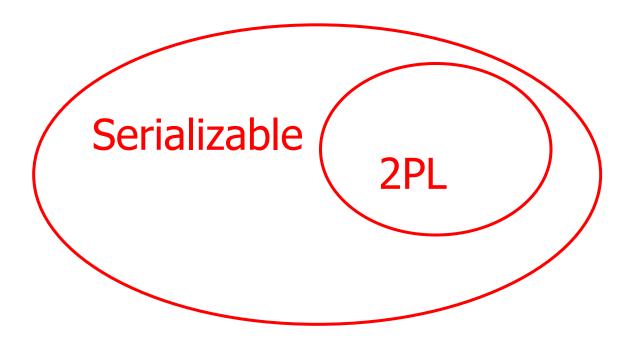
Problem: Ordered lock requests not realistic in most cases

<u>Timeout</u>

- If transaction waits more than L sec., roll it back!
- Simple scheme
- Hard to select L

2PL subset of Serializable

(schedules that can be implemented by 2PL locks are subset of serializable schedules)



S1: w1(x) w3(x) w2(y) w1(y)

- S1 cannot be achieved via 2PL:
 The lock by T1 for y must occur after w2(y),
 so the unlock by T1 for x must occur after
 this point (and before w3(x)). Thus, w3(x)
 cannot occur under 2PL where shown in S1
 because T1 holds the x lock at that point.
- However, S1 is serializable (conflict-serializable) (equivalent to T2, T1, T3).

If you need a bit more practice: Are our schedules S_C and S_D 2PL schedules?

$$S_c$$
: w1(A) w2(A) w1(B) w2(B)

 S_D : w1(A) w2(A) w2(B) w1(B)

- Beyond this simple 2PL protocol, it is all a matter of improving performance and allowing more concurrency....
 - Shared locks
 - Multiple granularity
 - Inserts, deletes and phantoms
 - Other types of C.C. mechanisms

Shared locks

So far:

$$S = ...I_1(A) r_1(A) u_1(A) ... I_2(A) r_2(A) u_2(A) ...$$

Do not conflict

Shared locks

So far:

$$S = ...I_1(A) r_1(A) u_1(A) ... I_2(A) r_2(A) u_2(A) ...$$

Do not conflict

Instead:

$$S = ... Is_1(A) r_1(A) Is_2(A) r_2(A) us_1(A) us_2(A)$$

Lock actions

I-t_i(A): lock A in t mode (t is S or X)

u-t_i(A): unlock t mode (t is S or X)

Shorthand:

ui(A): unlock whatever modes

Ti has locked A

Rule #1 Consistency of transactions

$$T_i = ... I-S_1(A) ... r_1(A) ... u_1(A) ...$$

 $T_i = ... I-X_1(A) ... w_1(A) ... u_1(A) ...$

- A transaction may not write without holding an exclusive lock, and may not read without holding some lock.
- All locks must be followed by an unlock of the same element.

Two-phase locking of transactions:

Locking must precede unlocking.

Legality of schedules:

An element may either be locked exclusively by one transaction or by several in shared mode, but not both. What about transactions that read and write same object?

Option 1: Request exclusive lock $T_i = ...I-X_1(A) ... r_1(A) ... w_1(A) ... u(A) ...$

 What about transactions that read and write same object?

Option 2: Upgrade

(E.g., need to read, but don't know if will write...)

$$T_i = ... I - S_1(A) ... r_1(A) ... I - X_1(A) ... w_1(A) ... u(A) ...$$

Think of
- Get 2nd lock on A, or

- Drop S, get X lock

Rule #2 Legal scheduler

$$S = \dots I - S_i(A) \dots \dots u_i(A) \dots$$

$$no \ I - X_j(A)$$

$$S = \dots I - X_i(A) \dots \dots u_i(A) \dots$$

$$no \ I - X_j(A)$$

$$no \ I - X_j(A)$$

$$no \ I - S_j(A)$$

A way to summarize Rule #2

Compatibility matrix

Comp

	S	X
S	true	false
X	false	false

Rule # 3 2PL transactions

No change except for upgrades:

- (I) If upgrade gets more locks
 (e.g., S → {S, X}) then no change!
 (It is like a new lock, allowed only in the growing phase)
- (II) If upgrade releases read (shared) lock (e.g., $S \rightarrow X$)
 - can be allowed in growing phase

(This is not a real release or unlock)

Theorem Rules 1,2,3 \Rightarrow Conf.serializable for S/X locks schedules

Proof: similar to X locks case

Detail:

I-t_i(A), I-r_j(A) do not conflict if comp(t,r) I-t_i(A), u-r_j(A) do not conflict if comp(t,r)

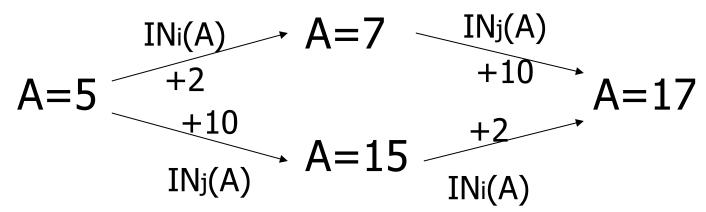
Lock types beyond S/X

Examples:

- (1) increment lock
- (2) update lock

Example (1): increment lock

- Atomic increment action: IN_i(A)
 {Read(A); A ← A+k; Write(A)}
- INi(A), INj(A) do not conflict!



Comp

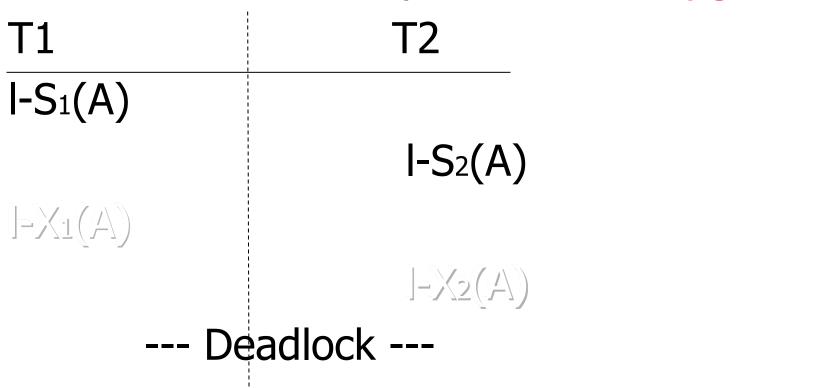
	S	X	I
S			
X			
Ι			

Comp

	S	X	I
S	Т	F	F
X	F	F	F
Ι	F	F	Т

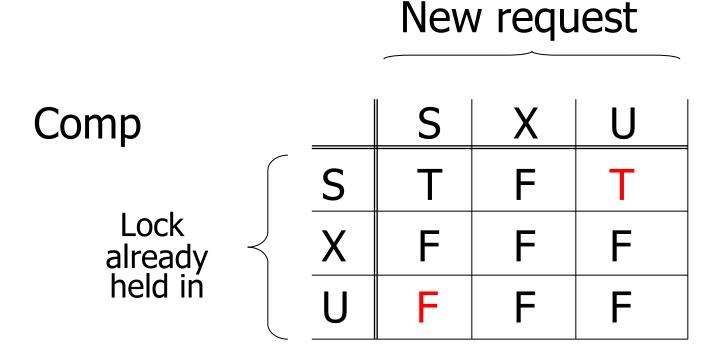
<u>Update locks</u>

A common deadlock problem with upgrades:



Solution

If Ti wants to read A and knows it may later want to write A, it requests update lock (not shared)



-> not symmetric table

Note: object A may be locked in different modes at the same time...

$$S_1=...I-S_1(A)...I-S_2(A)...I-U_3(A)...$$
 $I-S_4(A)...?$ $I-U_4(A)...?$

 To grant a lock in mode t, mode t must be compatible with all currently held locks on object

How does locking work in practice?

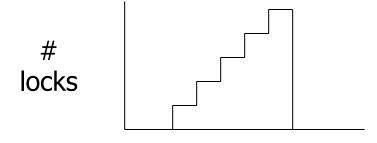
Every system is different

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(E.g., may not even provide CONFLICT-SERIALIZABLE schedules)
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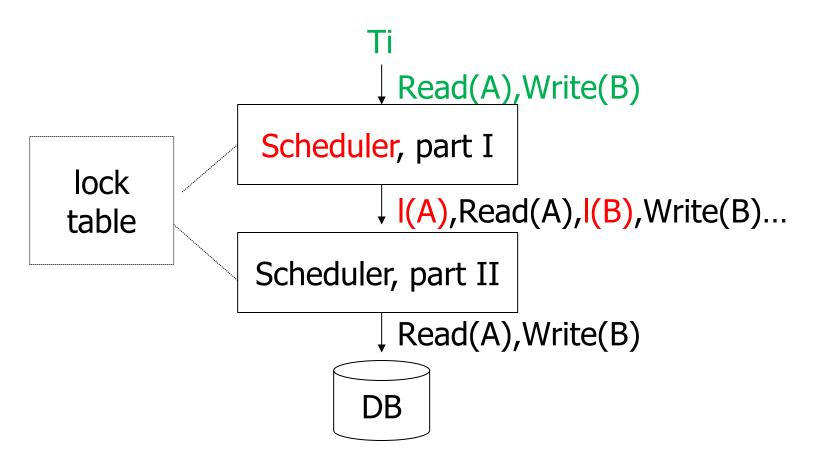
But here is one (simplified) way ...

Sample Locking System:

- (1) Don't trust transactions to request/release locks
- (2) Hold all locks until transaction commits

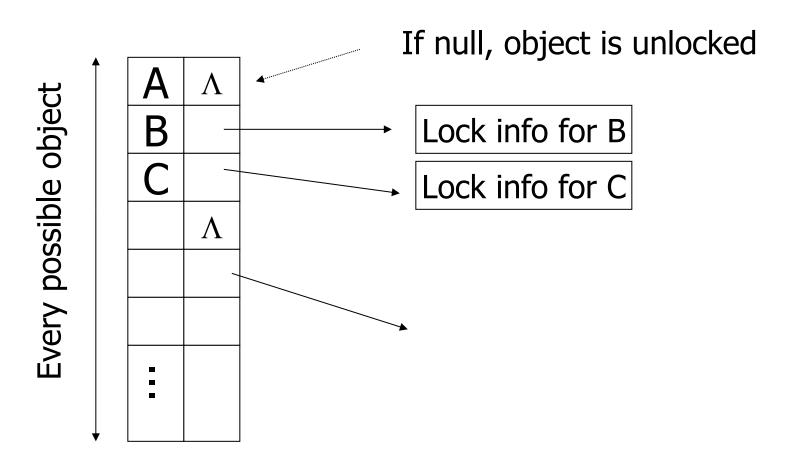


time

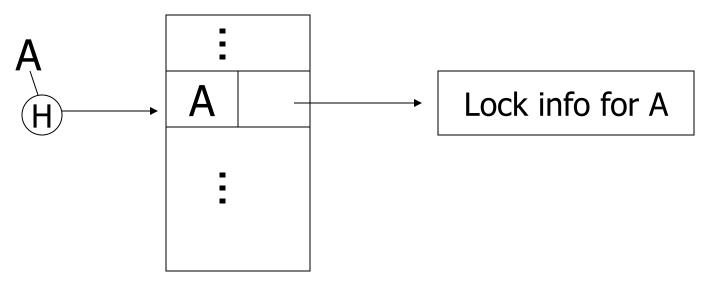


Scheduler requests locks (not transactions)

Lock table Conceptually

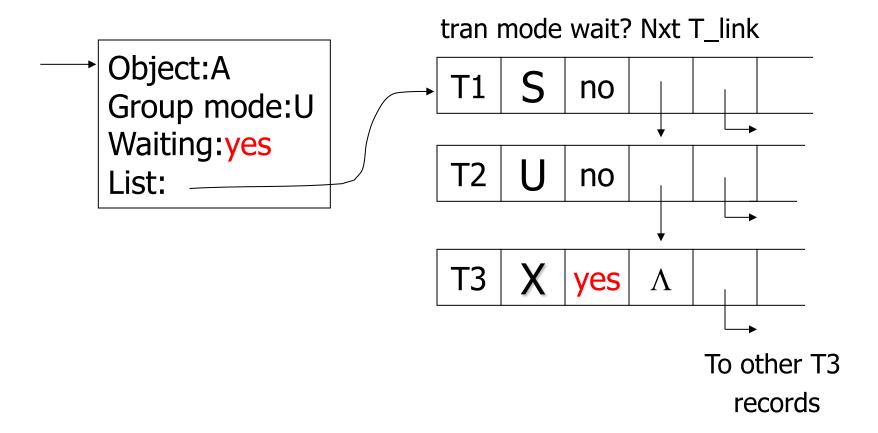


But use hash table:



If object not found in hash table, it is unlocked

Lock info for A - example



What are the objects we lock?

Tuple A Disk Relation A block Tuple B Α Tuple C Relation B Disk block B DB DB DB

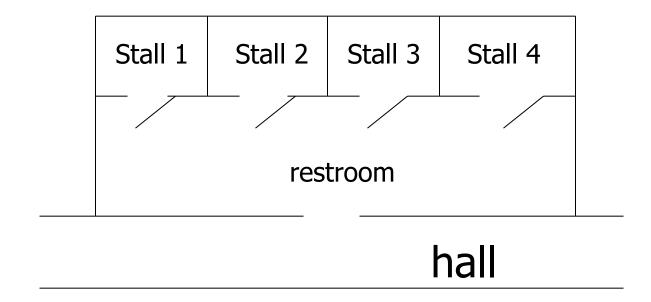
 Locking works in any case, but should we choose <u>small</u> or <u>large objects?</u> Locking works in any case, but should we choose <u>small</u> or <u>large objects?</u>

- If we lock <u>large</u> objects (e.g., Relations)
 - Need few locks
 - Low concurrency
- If we lock small objects (e.g., tuples, fields)
 - Need more locks
 - More concurrency

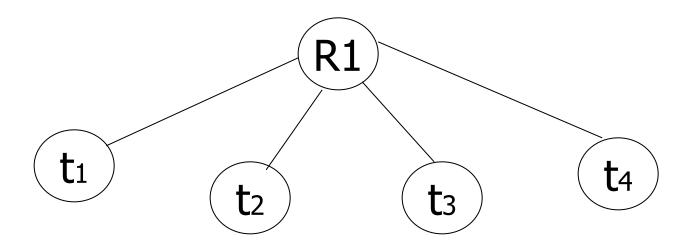
We can have it both ways!!

Ask any janitor to give you the solution...

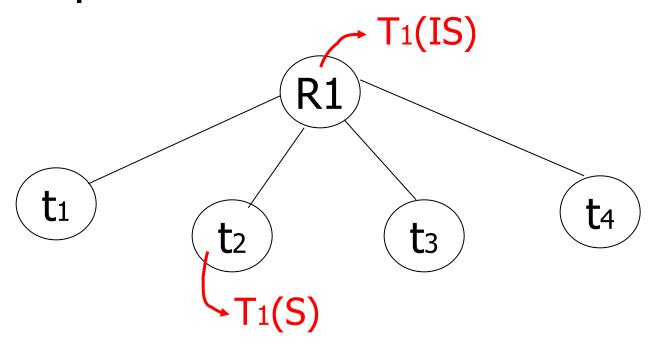
Should we close (lock) individual doors or restroom?



Example (R: relation, t: tuple)

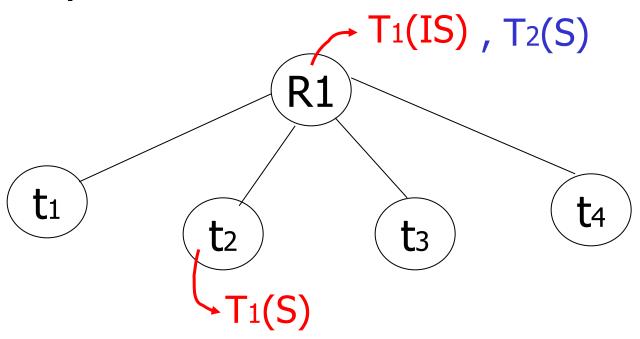


Example (Warning or Intention)

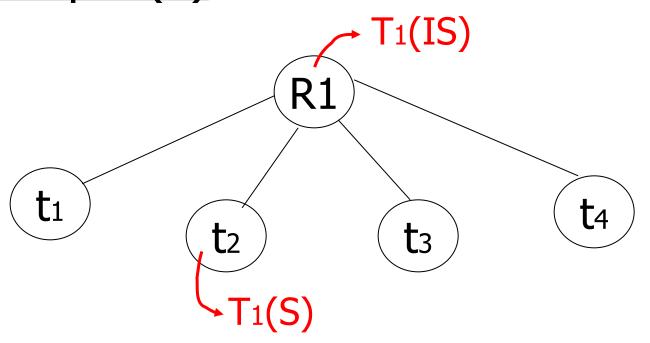


IS: Intention to obtain a shared lock on a subelement

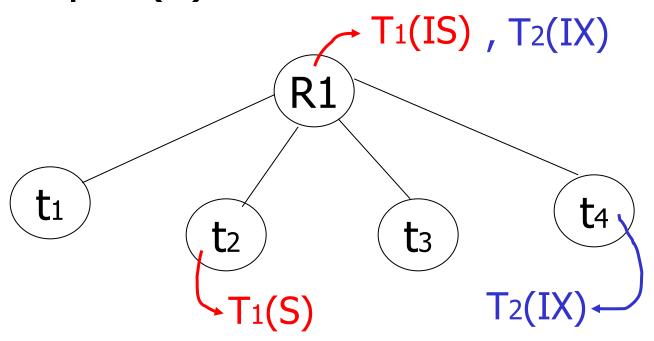
Example



Example (b)



Example (b)



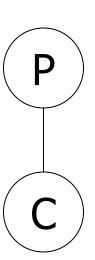
Multiple granularity (SIX: goup mode)

Comp		Requestor				
		IS	IX	S	SIX	X
	IS					
Holder	IX					
	S					
S	SIX					
	X					

Multiple granularity (SIX: goup mode)

Comp	Requestor					
		IS	IX	S	SIX	X
	IS	Т	Т	Т	Т	F
Holder	IX	T	H	F	F	F
	S	T	L	Τ	F	F
	SIX	H	Ш	L	F	F
	X	F	F	F	F	F

Parent locked in	Child can be locked in
IS IX	
S	
SIX	
X	



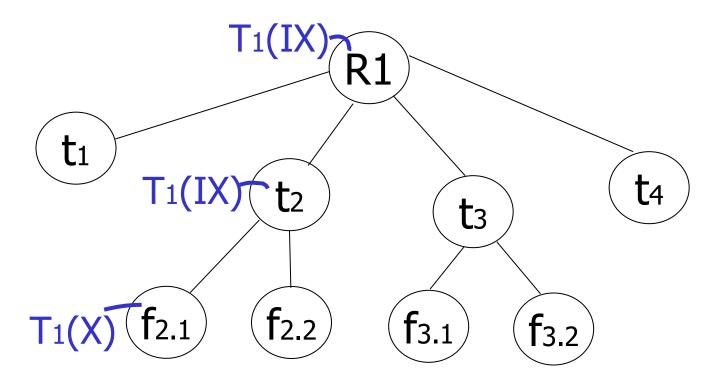
Parent locked in	Child can be locked by same transaction in
IS IX S SIX X	IS, S IS, S, IX, X, SIX none X, IX, [SIX] none

not necessary

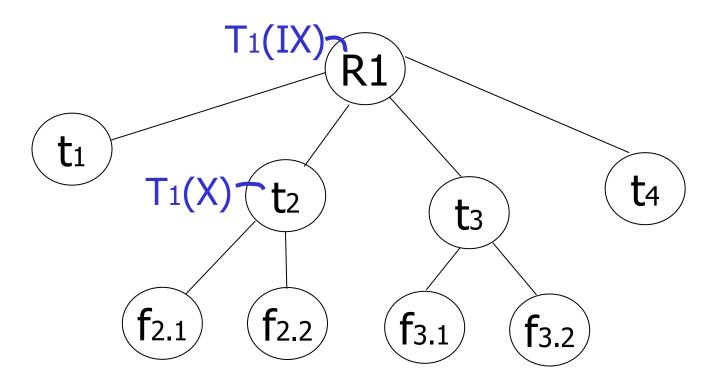
<u>Rules</u>

- (1) Follow multiple granularity compat. function
- (2) Lock root of tree first, any mode
- (3) Node Q can be locked by Ti in S or IS only if parent(Q) locked by Ti in IX or IS
- (4) Node Q can be locked by Ti in X,SIX,IX only if parent(Q) locked by Ti in IX,SIX
- (5) Ti is two-phase
- (6) Ti can unlock node Q only if none of Q's children are locked by Ti

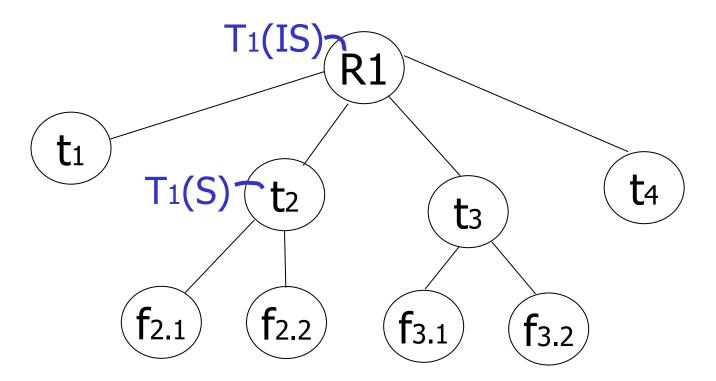
Can T2 access object f2.2 in X mode?
 What locks will T2 get?



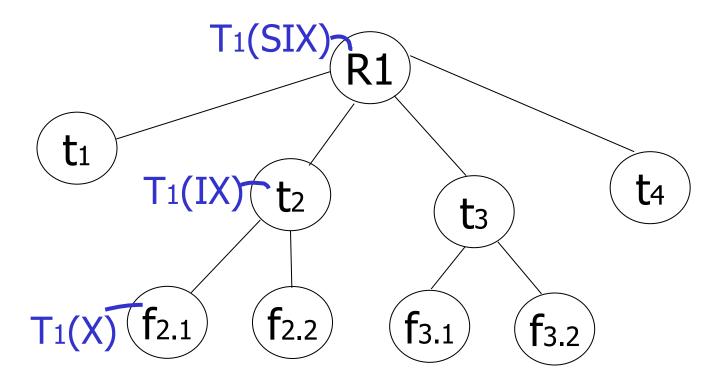
Can T2 access object f2.2 in X mode?
 What locks will T2 get?



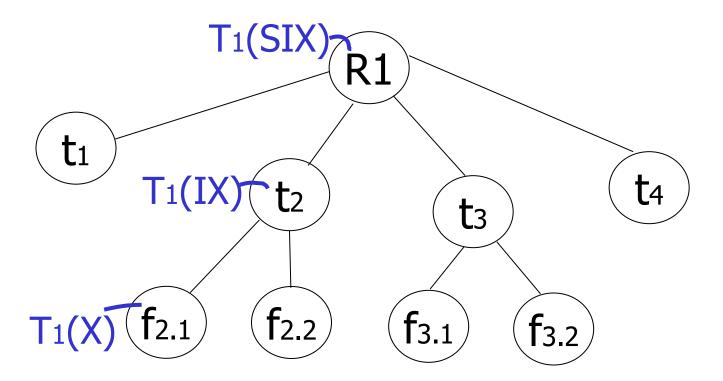
Can T₂ access object f_{3.1} in X mode?
 What locks will T₂ get?



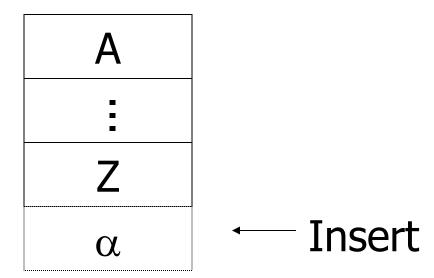
Can T2 access object f2.2 in S mode?
 What locks will T2 get?



Can T2 access object f2.2 in X mode?
 What locks will T2 get?



<u>Insert + delete operations</u>



Modifications to locking rules:

- (1) Get exclusive lock on A before deleting A
- (2) At insert A operation by Ti, Ti is given exclusive lock on A

Still have a problem: **Phantoms**

```
Example: relation R (E#,name,...)
constraint: E# is key
use tuple locking
```

R		E#	Name	
	o 1	55	Smith	
	02	75	Jones	

T₁: Insert <08,Obama,...> into R

T2: Insert <08,McCain,...> into R

T ₁	T ₂
S1(01)	S2(01)
S ₁ (0 ₂)	S ₂ (o ₂)
Check Constraint	Check Constraint
• •	• •
Insert o3[08,Obama,]	•
	Insert o4[08,McCain,]

Solution

- Use multiple granularity tree
- Before insert of node Q, lock parent(Q) in

X mode

t3

R1

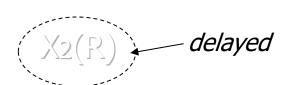
 t_2

Back to example

T1: Insert<08,Obama>

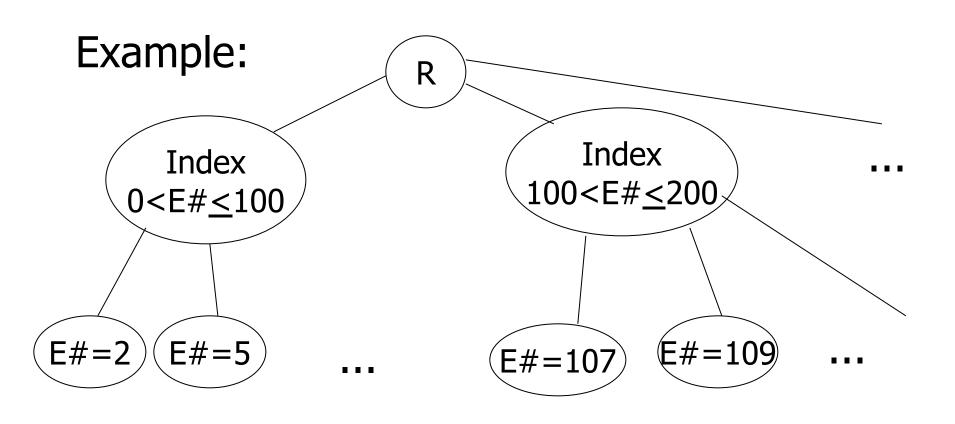
X1(R)

Check constraint Insert<08,Obama> U(R) T2: Insert<08,McCain>



X2(R)
Check constraint
Oops! e# = 08 already in R!

Instead of using R, can use index on R:



 This approach can be generalized to multiple indexes...

Next:

- Tree-based concurrency control
- Validation concurrency control

Example

• all objects accessed through root, following pointers A B

Example

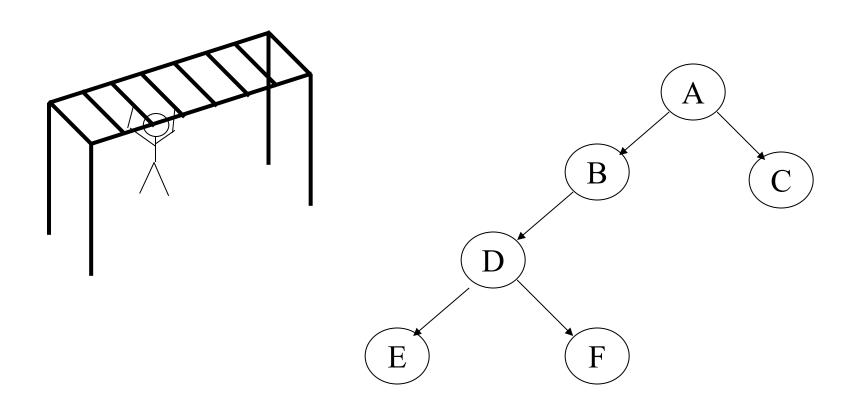
• all objects accessed through root, T₁ lock following pointers A B T₁ lock T₁ lock F E

Example

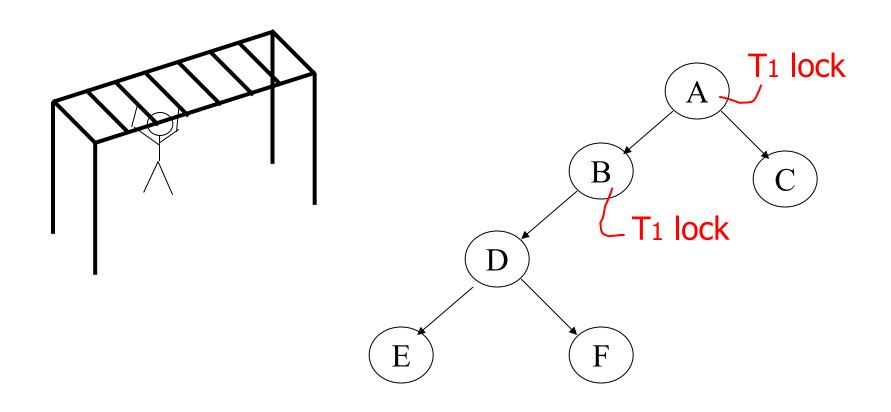
 all objects accessed through root, T₁ lock following pointers A B T₁ lock T₁ lock F E

> can we release A lock if we no longer need A??

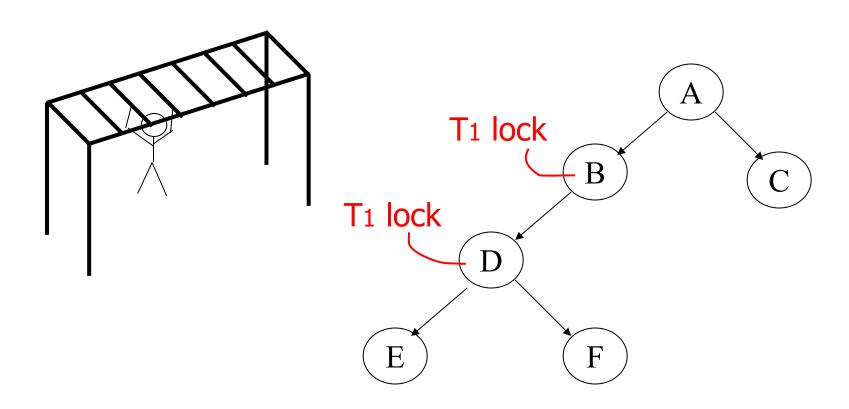
Idea: traverse like "Monkey Bars"



Idea: traverse like "Monkey Bars"

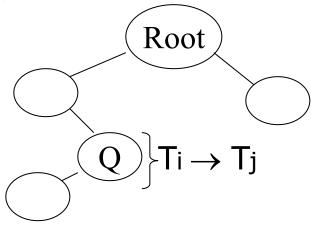


Idea: traverse like "Monkey Bars"



Why does this work?

- Assume all Ti start at root; exclusive lock
- $T_i \rightarrow T_j \Rightarrow T_i$ locks root before T_j

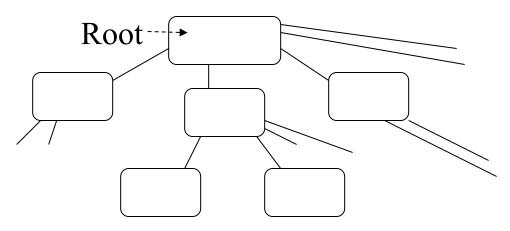


 Actually works if we don't always start at root

Rules: tree protocol (exclusive locks)

- (1) First lock by Ti may be on any item
- (2) After that, item Q can be locked by Ti only if parent(Q) locked by Ti
- (3) Items may be unlocked at any time
- (4) After Ti unlocks Q, it cannot relock Q

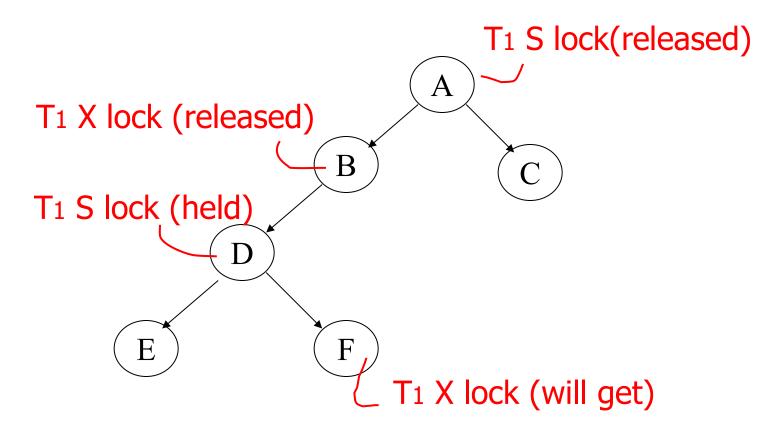
 Tree-like protocols are used typically for B-tree concurrency control



E.g., during insert, do not release parent lock, until you are certain child does not have to split

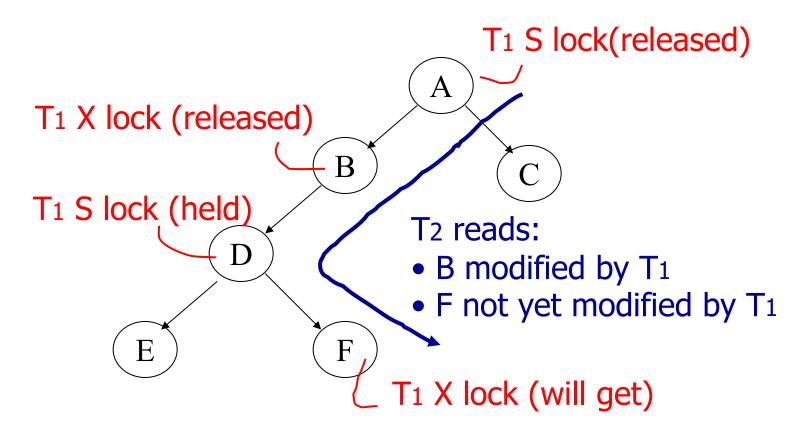
Tree Protocol with Shared Locks

Rules for shared & exclusive locks?



Tree Protocol with Shared Locks

Rules for shared & exclusive locks?



Tree Protocol with Shared Locks

- Need more restrictive protocol
- Will this work??
 - Once T₁ locks one object in X mode,
 all further locks down the tree must be in X mode

Validation

Transactions have 3 phases:

- (1) <u>Read</u>
 - all DB values read
 - writes to temporary storage
 - no locking
- (2) Validate
 - check if schedule so far is serializable
- (3) <u>Write</u>
 - if validate ok, write to DB

Key idea

- Make validation atomic
- If T₁, T₂, T₃, ... is validation order, then resulting schedule will be conflict equivalent to S_s = T₁ T₂ T₃...

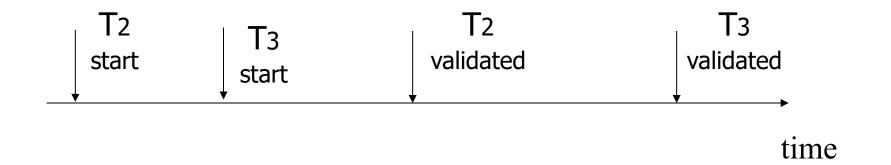
To implement validation, system keeps two sets:

- <u>FIN</u> = transactions that have finished phase 3 (and are all done)
- VAL = transactions that have successfully finished phase 2 (validation)

Example of what validation must prevent:

RS(T₂)={B}
$$RS(T_3)={A,B} \neq \phi$$

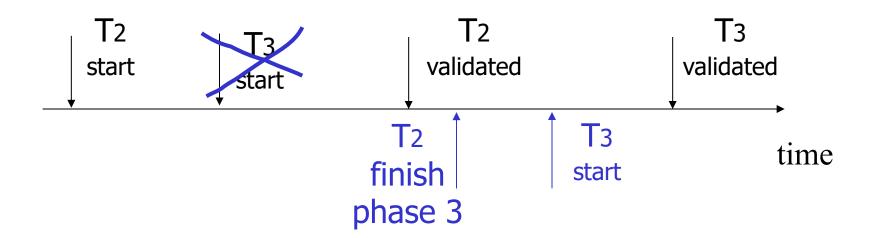
WS(T₂)={B,D} WS(T₃)={C}



allow Example of what validation must prevent:

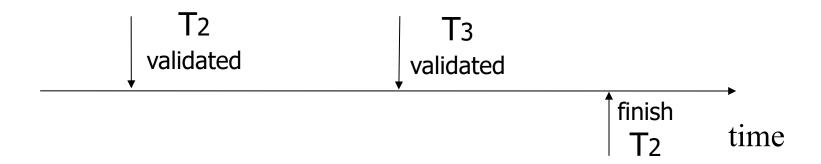
RS(T₂)={B}
$$RS(T_3)={A,B} \neq \phi$$

WS(T₂)={B,D} WS(T₃)={C}



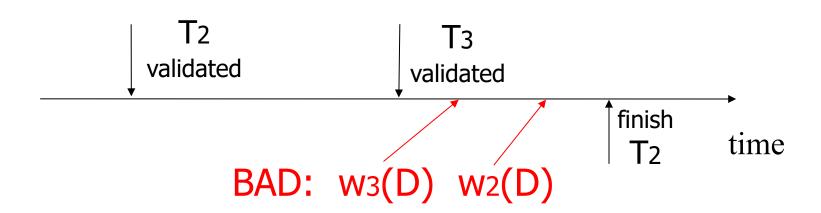
Another thing validation must prevent:

$$RS(T_2)=\{A\}$$
 $RS(T_3)=\{A,B\}$ $WS(T_2)=\{D,E\}$ $WS(T_3)=\{C,D\}$

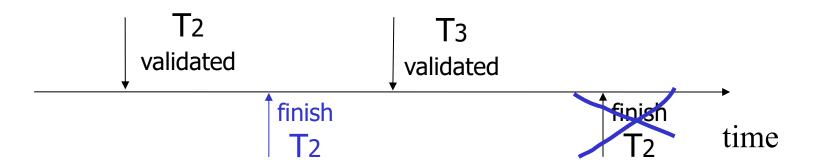


Another thing validation must prevent:

$$RS(T_2)=\{A\}$$
 $RS(T_3)=\{A,B\}$ $WS(T_2)=\{D,E\}$ $WS(T_3)=\{C,D\}$



allow Another thing validation must prevent:



Validation rules for Tj:

```
(1) When T<sub>j</sub> starts phase 1:
       ignore(T_j) \leftarrow FIN
(2) at T<sub>j</sub> Validation:
               if check (T<sub>j</sub>) then
                       [VAL \leftarrow VAL \cup \{T_i\};
                         do write phase;
                         FIN \leftarrow FIN \cup \{T_j\}
```

```
Check (T<sub>j</sub>):

For T<sub>i</sub> \in VAL - IGNORE (T<sub>j</sub>) DO

IF [ WS(T<sub>i</sub>) \cap RS(T<sub>j</sub>) \neq \emptyset OR

T<sub>i</sub> \notin FIN ] THEN RETURN false;

RETURN true;
```

Check (T_j): For T_i \in VAL - IGNORE (T_j) DO IF [WS(T_i) \cap RS(T_j) \neq \emptyset OR

Ti ∉ FIN] THEN RETURN false; RETURN true;

Is this check too restrictive?

Improving Check(T_i)

```
For T_i \in VAL - IGNORE (T_j) DO

IF [WS(T_i) \cap RS(T_j) \neq \emptyset] OR

(T_i \notin FIN AND WS(T_i) \cap WS(T_j) \neq \emptyset)]

THEN RETURN false;

RETURN true;
```

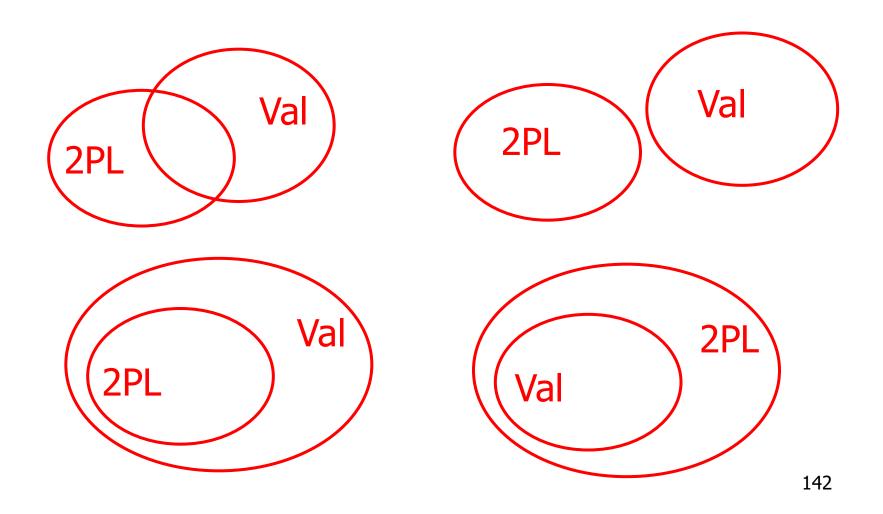
Exercise:

 $WS(T) = \{A,C\}$

 \triangle start \oplus validate \updownarrow finish

 $WS(V) = \{D, E\}$

Is Validation = 2PL?



S2: w2(y) w1(x) w2(x)

- Achievable with 2PL?
- Achievable with validation?

S2: w2(y) w1(x) w2(x)

- S2 can be achieved with 2PL:
 I2(y) w2(y) I1(x) w1(x) u1(x) I2(x) w2(x) u2(y) u2(x)
- S2 cannot be achieved by validation:
 The validation point of T2, val2 must occur before w2(y) since transactions do not write to the database until after validation. Because of the conflict on x, val1 < val2, so we must have something like</p>

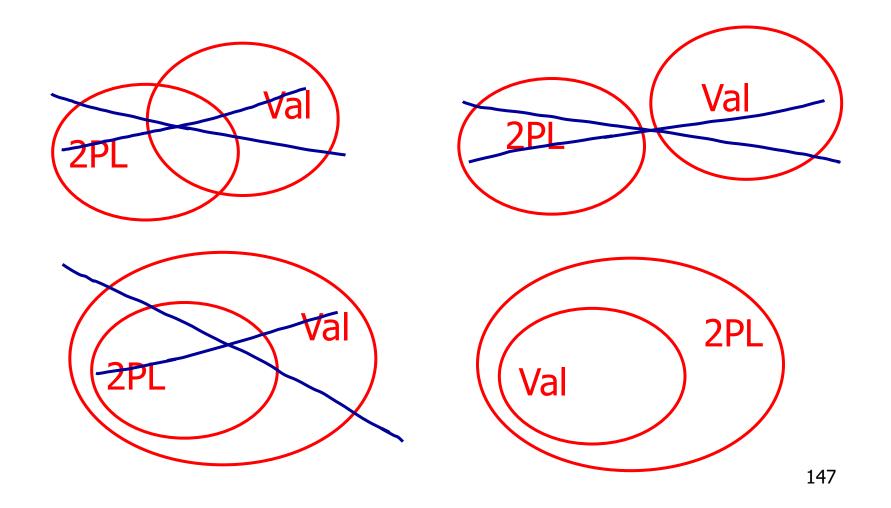
S2: val1 val2 w2(y) w1(x) w2(x) With the validation protocol, the writes of T2 should not start until T1 is all done with its writes, which is not the case.

Validation subset of 2PL?

- Possible proof (Check!):
 - Let S be validation schedule
 - For each T in S insert lock/unlocks, get S':
 - At T start: request read locks for all of RS(T)
 - At T validation: request write locks for WS(T); release read locks for read-only objects
 - At T end: release all write locks
 - Clearly transactions well-formed and 2PL
 - Must show S' is legal (next page)

- Say S' not legal (due to w-r conflict):
 S': ... | 1(x) | w2(x) | r1(x) | val1 | u1(x) | ...
 - At val1: T2 not in Ignore(T1); T2 in VAL
 - T1 does not validate: WS(T2) \cap RS(T1) ≠ Ø
 - contradiction!
- Say S' not legal (due to w-w conflict):
 S': ... val1 l1(x) w2(x) w1(x) u1(x) ...
 - Say T2 validates first (proof similar if T1 validates first)
 - At val1: T2 not in Ignore(T1); T2 in VAL
 - T1 does not validate:T2 ∉ FIN AND WS(T1) ∩ WS(T2) ≠ Ø)
 - contradiction!

Conclusion: Validation subset 2PL



Validation (also called optimistic concurrency control) is useful in some cases:

- Conflicts rare
- System resources plentiful
- Have real time constraints

<u>Summary</u>

Have studied C.C. mechanisms used in practice

- 2 PL
- Multiple granularity
- Tree (index) protocols
- Validation