

BODE ANALYSIS

FREQUENCY RESPONSE: $G(j\omega)$

BODE PLOTS: $|G(j\omega)|$ vs. ω ; $\angle G(j\omega)$ vs. ω
 (usually logarithmic) (usually logarithmic)
 (dB = 20 log₁₀ |G(jω)|)

$$G(j\omega) = \frac{K(j\omega + z_1)(j\omega + z_2) \cdots (j\omega + z_m)}{(j\omega + p_1)(j\omega + p_2) \cdots (j\omega + p_n)}$$

Bode gain:

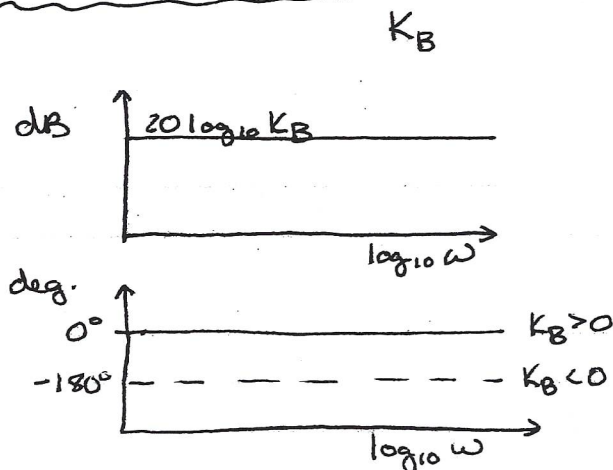
$$= \frac{\left[K \frac{\prod_{i=1}^m z_i}{\prod_{i=1}^n p_i} \right] (1 + j\omega/z_1)(1 + j\omega/z_2) \cdots (1 + j\omega/z_m)}{(1 + j\omega/p_1)(1 + j\omega/p_2) \cdots (1 + j\omega/p_n)}$$

EX. $G(j\omega) = \frac{K(j\omega + z_1)}{(j\omega + p_1)(j\omega + p_2)} = \frac{\frac{z_1}{p_1 p_2} K (1 + j\omega/z_1)}{(1 + j\omega/p_1)(1 + j\omega/p_2)}$ break (corner) frequencies

$$\log\left(\frac{ab}{cd}\right) = \log ab - \log cd = \log a + \log b - \log c - \log d$$

$$20 \log |G(j\omega)| = 20 \log \left| \left(K \frac{z_1}{p_1 p_2} \right) \right| + 20 \log |1 + j\omega/z_1| - 20 \log |1 + j\omega/p_1| - 20 \log |1 + j\omega/p_2|$$

CONSTANT GAIN



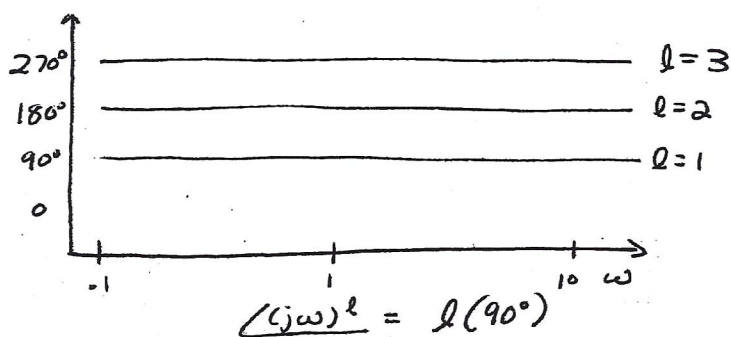
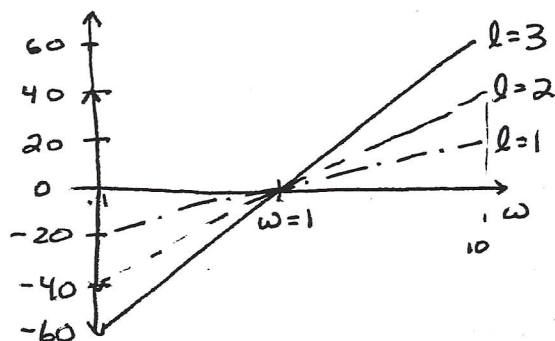
$$\begin{aligned} |K_B| &\angle 0^\circ \quad \text{if } K_B \geq 0 \\ |K_B| &\angle -180^\circ \quad \text{if } K_B < 0 \end{aligned}$$

NB: if $|K_B| > 1$ dB +
 if $|K_B| < 1$ dB -

POLES AND ZEROS @ THE ORIGIN

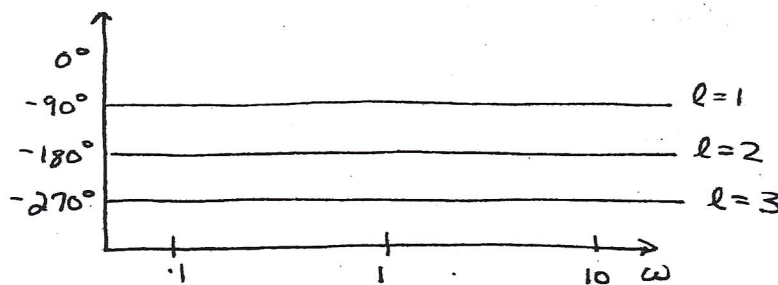
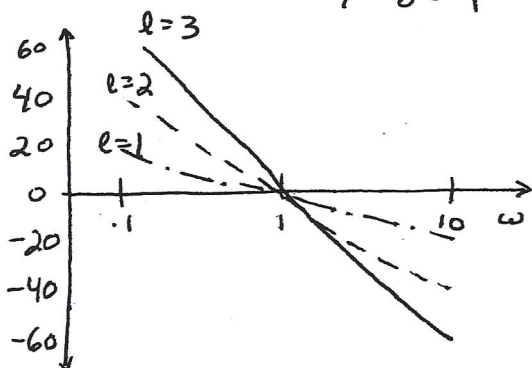
zeros @ origin: $(j\omega)^l \Rightarrow \text{dB} = 20 \log |(j\omega)^l| = 20l \log \omega$ $\nearrow 20 \log |\omega^l|$

BODE MAGNITUDE PLOT: straight line that intersect the ω -axis @ $\omega=1$ w/ slope of $20l$ dB/decade



pole @ origin $\frac{1}{(j\omega)^l} \Rightarrow \text{dB} = -20l \log \omega$

MAG. PLOT: straight line that intersects the ω -axis @ $\omega=1$ w/ slope of $-20l$ dB/decade

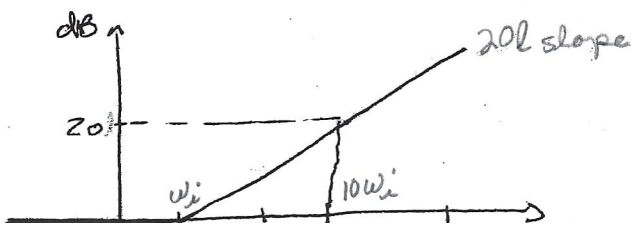


NONZERO REAL POLES AND ZEROS

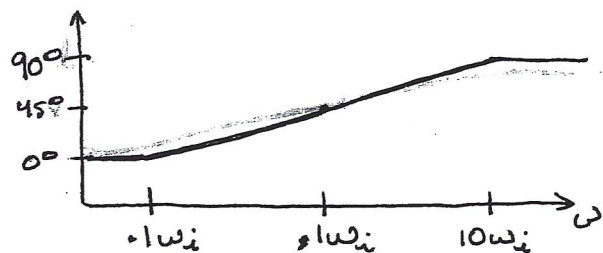
ZERO @ ω_i : $20 \log \left| 1 + \frac{j\omega}{\omega_i} \right| = 20 \log \sqrt{1 + \left(\frac{\omega}{\omega_i} \right)^2}$

$$\approx \begin{cases} 0 & \omega \leq \omega_i \\ 20 \log \omega - 20 \log \omega_i & \omega > \omega_i \end{cases}$$

$\hookrightarrow 20 \log_{10} \left| \frac{j\omega}{\omega_i} \right|$
 $\Rightarrow 20 \log_{10} \left(\frac{\omega}{\omega_i} \right)$ as $\frac{\omega}{\omega_i} \rightarrow \infty$



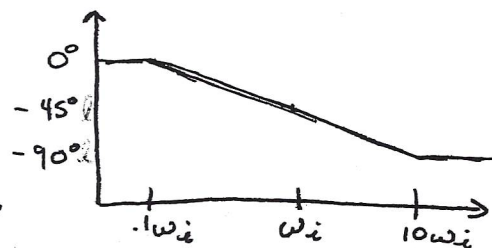
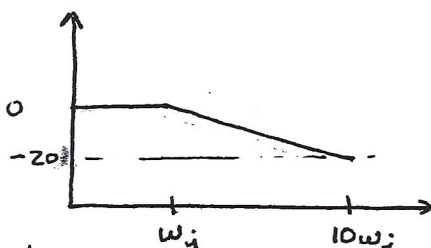
1 zeros @ ω_i : $20 \log | (1 + \frac{j\omega}{\omega_i})^2 | = 20 \log [1 + (\frac{\omega}{\omega_i})^2]^{1/2}$



$$\approx \begin{cases} 0 & \omega \leq \omega_i \\ 20 \log(\frac{\omega}{\omega_i}) & \omega > \omega_i \end{cases}$$

$$\angle 1 + \frac{j\omega}{\omega_i} = \tan^{-1} \frac{\omega}{\omega_i}$$

1 poles @ ω_i



mag: $20 \log_{10} | \frac{1}{(1 + \frac{j\omega}{\omega_i})} | = -20 \log_{10} | (1 + \frac{j\omega}{\omega_i}) |$

COMPLEX POLES AND ZEROS

complex poles: $\frac{1}{(1 + j 2 \zeta \omega/\omega_n - (\omega/\omega_n)^2)}$ \rightarrow factored out ω_n^2
 $0 \leq \zeta \leq 1$

shout
over heads

complex zeros: reflections about 0 dB & 0° lines for c.p.

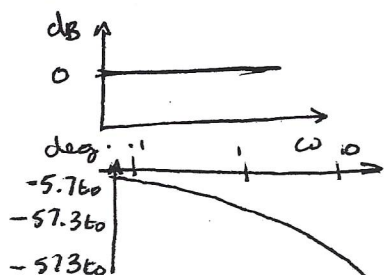
NONMINIMUM PHASE ZERO

$$(j\omega + z_1) \sim (j\omega - z_1) \sim (\frac{j\omega}{z_1} - 1)$$

magnitude unchanged: $|\frac{j\omega}{z_1} + 1| = |\frac{j\omega}{z_1} - 1| = \sqrt{1 + (\frac{\omega}{z_1})^2}$

phase changes: $\angle \frac{j\omega}{z_1} - 1 = \tan^{-1}(-\frac{\omega}{z_1})$ phase is like pole

IDEAL TIME DELAY



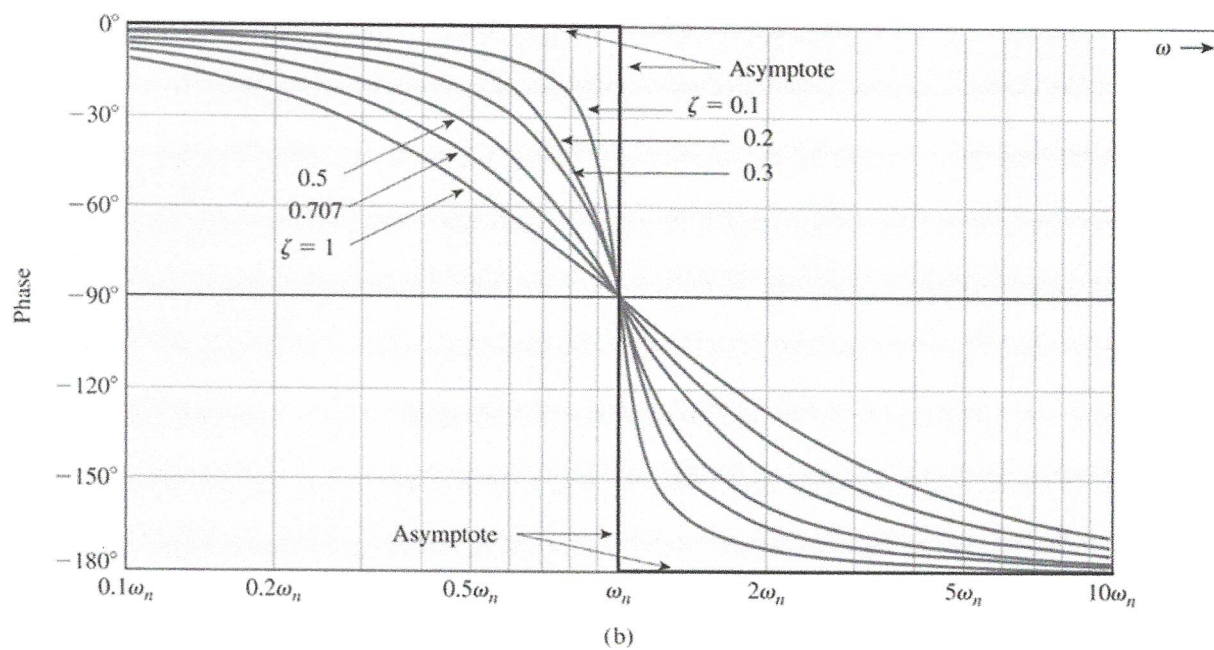
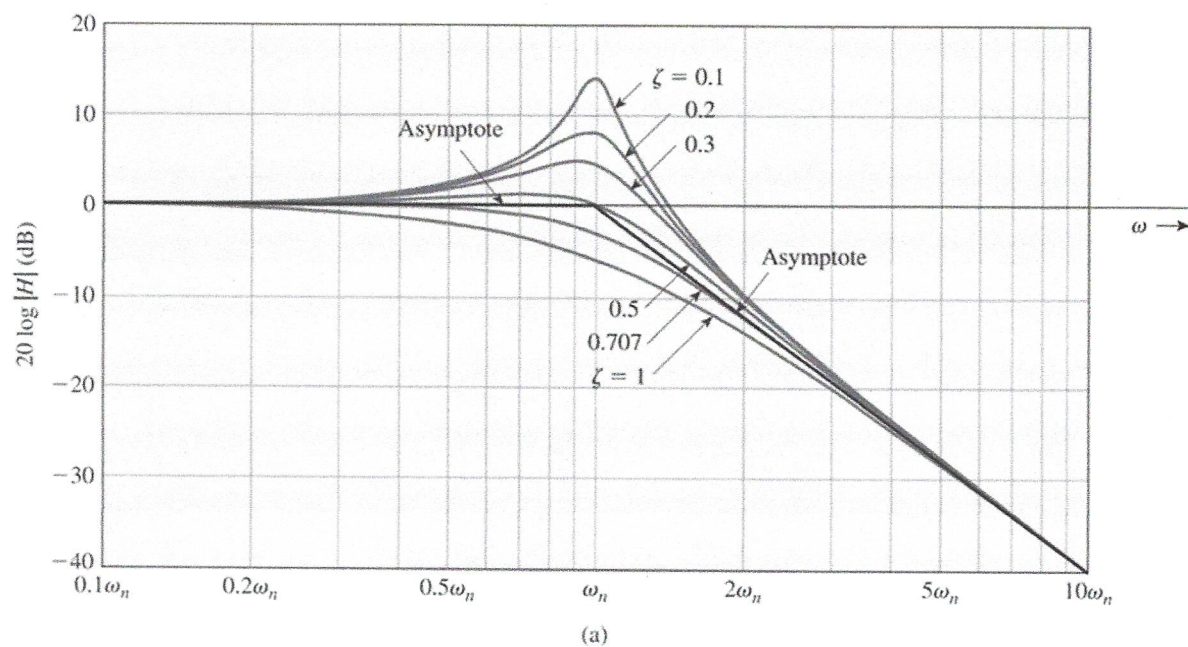
$$G(s) = e^{-t_o s} \Rightarrow G(j\omega) = 1 / e^{-j\omega t_o}$$

magnitude is unity
dB = 0

phase is linear w.r.t. ω

phase lag \uparrow as $\omega \rightarrow \infty$

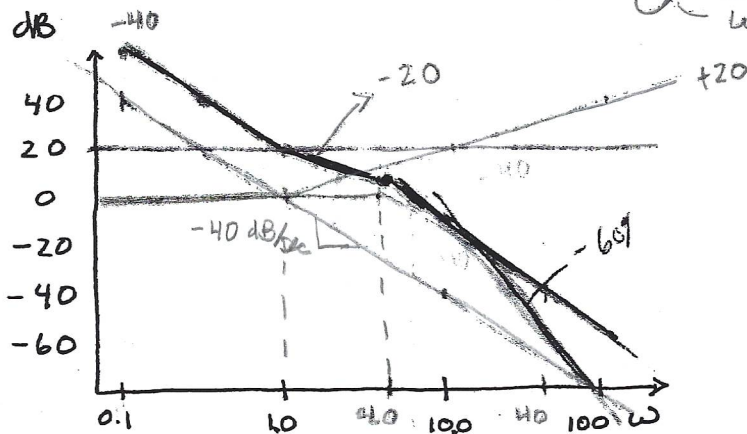
$$\text{Phase} = -57.3 \omega t_o$$



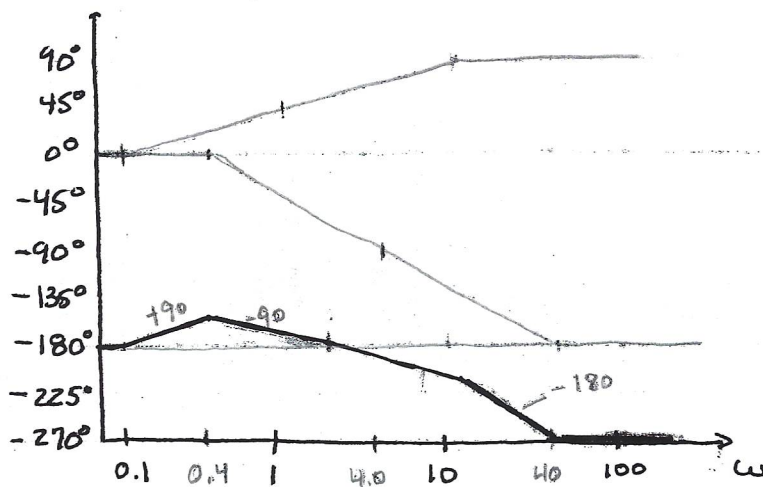
EX. $G_H(j\omega) = \frac{10(1+j\omega)}{(j\omega)^2 [1 + \frac{j\omega}{4} - (\frac{\omega}{4})^2]}$

$\omega_n = 4$ $\xi = 0.5$

$20 \log_{10}(10) = 20$



- straight line approximation
- for more accurate
 - plot drawn in excel
 - plot on computer



RELATIVE STABILITY

gain margin: # dB that $|G_H(j\omega)|$ is below 0 dB @ phase crossover freq. ($\omega \Rightarrow 180^\circ$)

phase margin: # deg. that $\arg G_H(j\omega)$ is above -180° @ gain crossover freq. ($|G_H(j\omega)| = 1$)

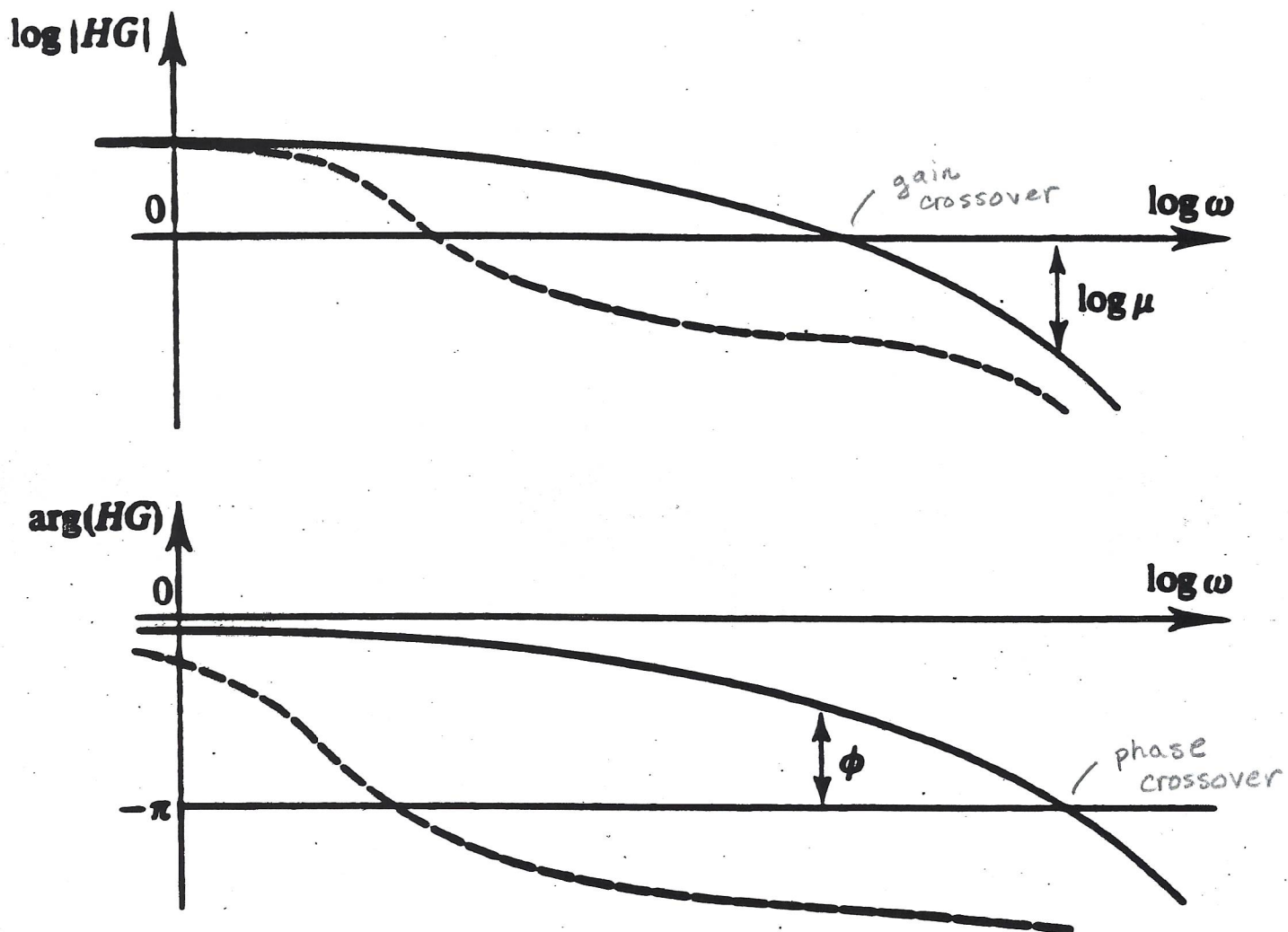


Figure 1.3 Bode plot form of Figure 1.2.