

Discrete Random Variables

random variable: each outcome in the sample space of a random experiment is a real number.

.. denoted by an upper-case variable if symbolic (usually X).

.. an actual outcome is then lower case ($x = 4.2 \text{ kg}$)

discrete random variable: finite or "countably-infinite" range of real numbers

ex: # of defective parts, transmitted bits, etc..

probability distribution: describes probabilities associated with possible values of X

.. can be an equation; for discrete, often a list of possible outcomes and associated probabilities

ex: three cell phone cameras tested for
flash recharge time; it is known
that they pass 80% of the time.

.. write a probability distribution for three
independent cameras passing/failing

First: determine the sample space of the
experiment

let's let p : pass f : fail

PPP fff pfp etc..
↑ ↑
all pass all fail

.. this is basically a factorial experiment w/

2^k outcomes, where $k=3$ cameras
↑
either pass or fail

$$2^3 = 8$$

.. let X represent the # of passing cameras

#1	#2	#3	X	P
P	P	P	3	$0.8 \cdot 0.8 \cdot 0.8 = 0.512$
P	P	f	2	$0.8 \cdot 0.8 \cdot 0.2 = 0.128$
P	f	P	2	0.128
P	f	f	1	0.032
f	P	P	2	0.128
f	P	f	1	0.032
f	f	P	1	0.032
f	f	f	0	0.008

~ next: associate these outcomes with values of X

.. now we need probabilities associated w/ each outcome

.. because they're independent, we use multiplication rule

$$P\{PPP\} = 0.8 \cdot 0.8 \cdot 0.8 = 0.512$$

known: they pass 80% of the time

or 51.2%

$$P\{PPf\} = 0.8 \cdot 0.8 (1 - 0.8)$$

↓
P

$$= 0.128$$

or 12.8%

this is - finally! -
useful info!!

decision-making
order of
two passes
irrelevant!

$$P\{PfP\} = 0.8 \cdot 0.2 \cdot 0.8 = 0.128$$

$$P\{p f f\} = P\{f p f\} = P\{f f p\} \\ = 0.2 \cdot 0.2 \cdot 0.8 = \underline{0.032}$$

$$P\{f f f\} = 0.2 \cdot 0.2 \cdot 0.2 \\ = \underline{0.008}$$

.. this is not yet a probability distribution!

.. by definition, that is a list of probabilities associated w/ values of X .

.. What are the possible values of X ?

$\{0 \ 1 \ 2 \ 3\}$ (passing cameras)

$$P(0) = P\{f f f\} = \underline{0.008}$$

$$P(1) = P\{p f f \ f p f \ f f p\} = 0.032 + 0.032 + 0.032 \\ \uparrow \text{ exactly one passing camera} \quad = \underline{0.096}$$

$$P(2) = 0.128 + 0.128 + 0.128 = \underline{0.384}$$

$$P(3) = P\{p p p\} = \underline{0.512}$$

this is a probability distribution

.. note: these probabilities add up to 1 or 100%

probability mass function  that describes probabilities

$$1.) f(x_i) = P(X = x_i)$$

$$2.) f_n(x_i) \geq 0$$

$$* 3.) \sum_{i=1}^n f(x_i) = 1 \text{ or } 100\%$$