08 - Microprocessor-Based Systems

CEG 4330/6330 - Microprocessor-Based Embedded Systems

Max Gilson

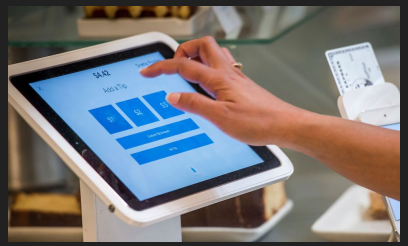
Microcontroller vs Microprocessor

- The Arduino Uno is a microcontroller
- Microcontrollers are usually an “all-in-one” solution
  - Usually contains memory, CPU, I/O, etc. all on one chip
  - Can have really small circuit board design
- Microprocessors are more powerful
  - Usually requires external RAM, storage, I/O, etc.
  - Results in larger circuit board, but more capabilities

Microcontroller vs Microprocessor (cont.)

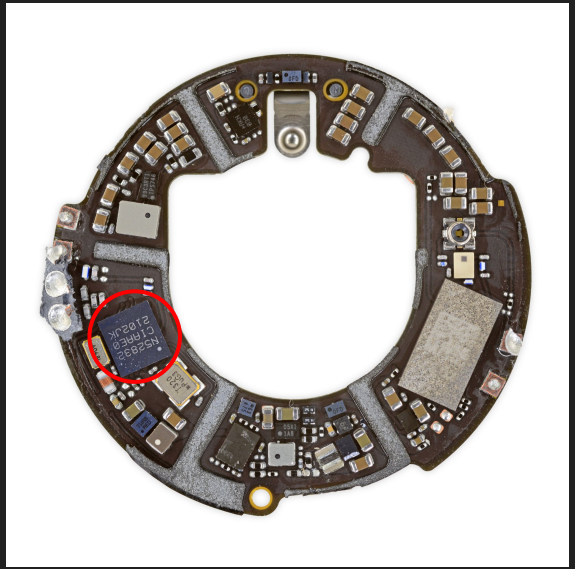
- Microcontroller
  - Used for “simple” applications:
  - control systems, washing machines, remote control, etc.

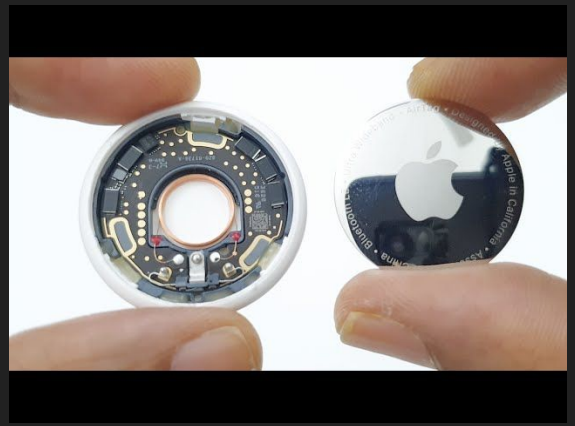
- Microprocessor
  - Used for “complex” applications:
  - computer vision, networking, smart watch, virtual reality headset, etc.



System On Chip

- A system on chip (SoC) is a specialized device that contains many functions and usually a microprocessor
- Example: N52832
  - Bluetooth SoC used in Apple's Airtag
  - Contains ARM processor and has many functions
  - The SoC is specialized for BLE capabilities, networking, and low power





Design Considerations

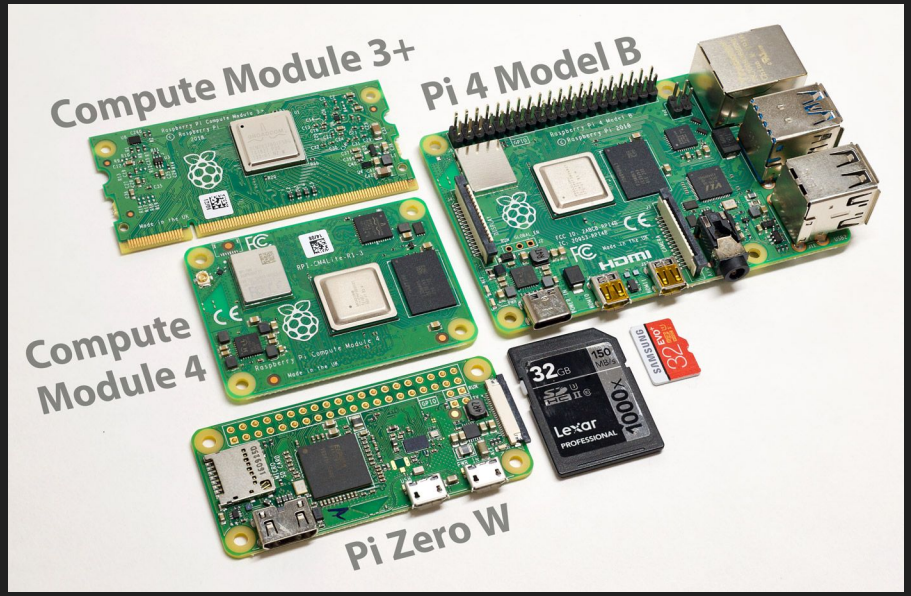
- When designing an embedded system many considerations have to be made when choosing a microprocessor:
  - Does it support my desired peripherals?
    - Bluetooth? Communication protocols? WiFi? Camera?
  - How much power consumption?
    - Is low power a requirement of your design?
  - How large is the device + external components?
    - How small does your circuit board need to be?
  - How much processing power or dedicated hardware?
    - High quality graphics might require integrated GPU

Many Choices

- Since there are so many considerations to make, there are many microprocessors available
- Many varieties of size, processing power, power consumption, I/O support, etc.

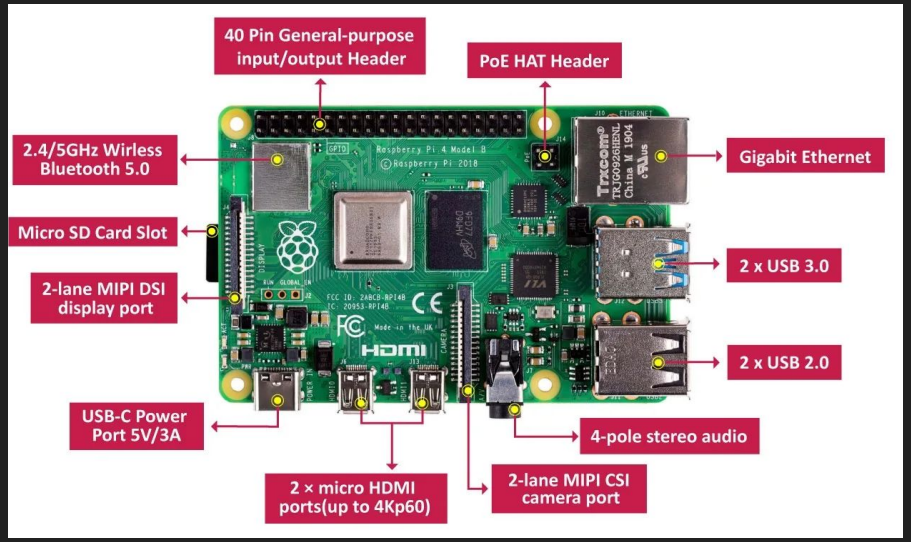
Raspberry Pi

- Single Board Computer (SBC)
- Open source software
- Closed source hardware
- “Off-the-shelf” solution for many applications
- There are many types of Raspberry Pi, and knock offs, with different functionality
- Lots of community support



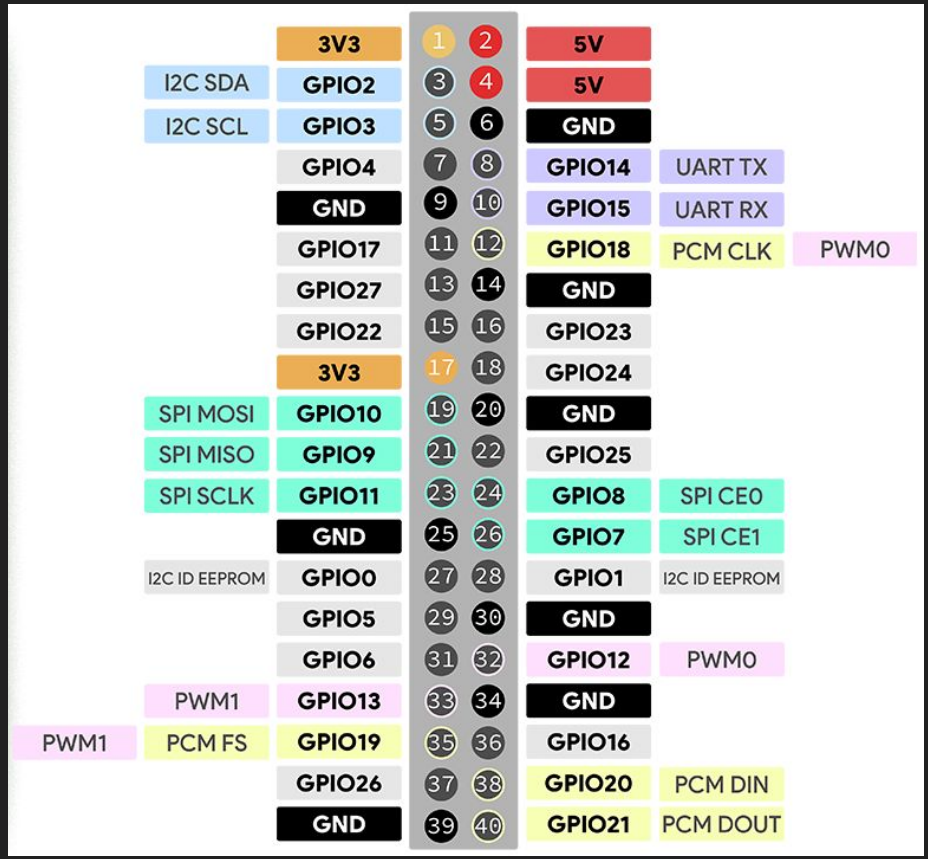
Raspberry Pi 4 Model B (RPI4B)

- Broadcom BCM2711, Quad core Cortex-A72 (ARM v8) 64-bit SoC @ 1.8GHz
- Ethernet
- USB3
- Dual 4K HDMI
- Camera port
- GPIO
  - Includes many functionalities
- Up to 8GB RAM



GPIO

- General Purpose I/O (GPIO)
- Pins can have multiple functions
- Some pins have dedicated hardware for communication, PWM, etc.



GPIO (cont.)

5.1.2 GPIO Alternate Functions

GPIO	Default Pull	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5
0	High	SDA0	SA5	PCLK	SPI3_CE0_N	TXD2	SDA6
1	High	SCL0	SA4	DE	SPI3_MISO	RXD2	SCL6
2	High	SDA1	SA3	LCD_VSYNC	SPI3_MOSI	CTS2	SDA3
3	High	SCL1	SA2	LCD_HSYNC	SPI3_SCLK	RTS2	SCL3
4	High	GPCLK0	SA1	DPI_D0	SPI4_CE0_N	TXD3	SDA3
5	High	GPCLK1	SA0	DPI_D1	SPI4_MISO	RXD3	SCL3
6	High	GPCLK2	SOE_N	DPI_D2	SPI4_MOSI	CTS3	SDA4
7	High	SPI0_CE1_N	SWE_N	DPI_D3	SPI4_SCLK	RTS3	SCL4
8	High	SPI0_CE0_N	SD0	DPI_D4	-	TXD4	SDA4
9	Low	SPI0_MISO	SD1	DPI_D5	-	RXD4	SCL4
10	Low	SPI0_MOSI	SD2	DPI_D6	-	CTS4	SDA5
11	Low	SPI0_SCLK	SD3	DPI_D7	-	RTS4	SCL5
12	Low	PWM0	SD4	DPI_D8	SPI5_CE0_N	TXD5	SDA5
13	Low	PWM1	SD5	DPI_D9	SPI5_MISO	RXD5	SCL5
14	Low	TXD0	SD6	DPI_D10	SPI5_MOSI	CTS5	TXD1
15	Low	RXD0	SD7	DPI_D11	SPI5_SCLK	RTS5	RXD1
16	Low	FL0	SD8	DPI_D12	CTS0	SPI1_CE2_N	CTS1
17	Low	FL1	SD9	DPI_D13	RTS0	SPI1_CE1_N	RTS1
18	Low	PCM_CLK	SD10	DPI_D14	SPI6_CE0_N	SPI1_CE0_N	PWM0
19	Low	PCM_FS	SD11	DPI_D15	SPI6_MISO	SPI1_MISO	PWM1
20	Low	PCM_DIN	SD12	DPI_D16	SPI6_MOSI	SPI1_MOSI	GPCLK0
21	Low	PCM_DOUT	SD13	DPI_D17	SPI6_SCLK	SPI1_SCLK	GPCLK1
22	Low	SD0_CLK	SD14	DPI_D18	SD1_CLK	ARM_TRST	SDA6
23	Low	SD0_CMD	SD15	DPI_D19	SD1_CMD	ARM_RTCK	SCL6
24	Low	SD0_DAT0	SD16	DPI_D20	SD1_DAT0	ARM_TDO	SPI3_CE1_N
25	Low	SD0_DAT1	SD17	DPI_D21	SD1_DAT1	ARM_TCK	SPI4_CE1_N
26	Low	SD0_DAT2	TE0	DPI_D22	SD1_DAT2	ARM_TDI	SPI5_CE1_N
27	Low	SD0_DAT3	TE1	DPI_D23	SD1_DAT3	ARM_TMS	SPI6_CE1_N

Table 5: Raspberry Pi 4 GPIO Alternate Functions

Operating System

- Microprocessors (including the RPI4B) require an operating system to run
- This operating system is usually some variety of Linux
- Linux is open source and usually free to use
- RPI4B uses Raspberry Pi OS (previously called Raspbian) as the officially supported operating system
  - Open source, Debian based, Linux operating system
  - Not as quick/easy as writing a simple program (like Arduino)
- Stored on SD card or EMMC

Accessing GPIO for Simple Functions

- First add permission to access GPIO:

```
sudo usermod -a -G gpio <username>
```

- Make sure Python and gpiozero is installed and run the following code to turn on an external LED (GPIO17) with a button press (GPIO2):

```
from gpiozero import LED, Button

led = LED(17)
button = Button(2)

while True:
    if button.is_pressed:
        led.on()
    else:
        led.off()
```

gpiozero Library

- https://gpiozero.readthedocs.io/en/stable/api_input.html
- The button class provides many different arguments
  - Pullup, pulldown, debounce, etc.
- There are many other sensors that are available
  - HC-SR04 distance sensor
  - TRCT5000 proximity sensor
  - SPI devices
- Outputs, inputs, and other helpful tools

Interfacing with Any I/O

- It is impossible to support interfacing with every I/O device
- The most popular are already implemented by the community or have an equivalent implemented
- Camera Solutions:
  - Raspberry Pi Camera Module
  - Arducam
- I2C IMU:
  - MPU9250
- Before buying a sensor, make sure you can find some available code for it for the RPI, otherwise, you'll have to write your own drivers!

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IMU Python Code

```
import FaBo9Axis_MPU9250
import time
import sys

mpu9250 = FaBo9Axis_MPU9250.MPU9250()

try:
    while True:
        accel = mpu9250.readAccel()
        print " ax = " , ( accel['x'] )
        print " ay = " , ( accel['y'] )
        print " az = " , ( accel['z'] )

        gyro = mpu9250.readGyro()
        print " gx = " , ( gyro['x'] )
        print " gy = " , ( gyro['y'] )
        print " gz = " , ( gyro['z'] )

        mag = mpu9250.readMagnet()
        print " mx = " , ( mag['x'] )
        print " my = " , ( mag['y'] )
        print " mz = " , ( mag['z'] )
        print

        time.sleep(0.1)

except KeyboardInterrupt:
    sys.exit()
```

Low Power Modes

- The RPI 4B uses 2.7W while idle, 6.4W @ 400% CPU load
  - Pi-zero under light load consumes about 0.335W
- The most efficient x86 computer will consume 10W to 25W at idle
- Most SBC’s allow for changing the clock speed, reducing power consumption for less processing power:
- RPI 4B clock speeds:
  - 1.8 Ghz (max overclocking)
  - 1.5 Ghz (nominal)
  - 0.6 Ghz (min underclocking)

Datasheet

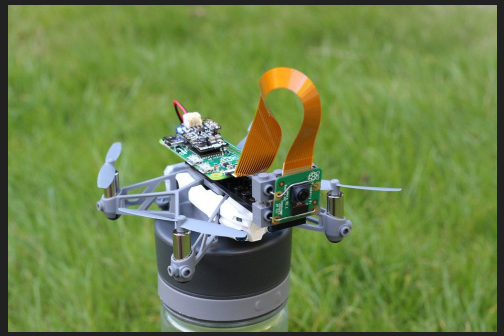
- Datasheet is very limited:
  - https://datasheets.raspberrypi.com/rpi4/raspberry-pi-4-datasheet.pdf
- Processor is closed source and documentation is protected under NDA
- Thankfully most of the tools and software is well documented and available so getting the RPI to work is no problem for most applications

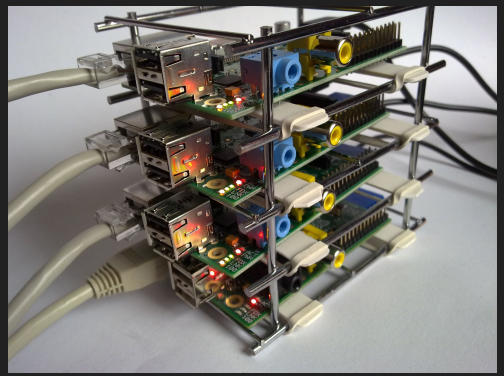
Raspberry Pi as a Desktop

- The Raspberry Pi is a fully capable computer
- Can be used as a general purpose computer
- Fully customizable

Many Applications

- Security Camera System
- Drone
- Web Server
- Smart Home / Home Automation
- Arcade Cabinet / Retro Console
- Open Source Phone





Alternatives to Raspberry Pi

- Many alternatives exist, providing specialized uses
- Small Form Factor:
  - NanoPi NEO Air
- AI and Image Processing:
  - Jetson Nano
- Open Source Hardware:
  - Banana Pi