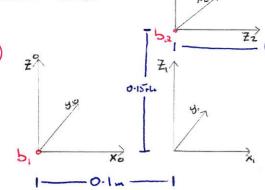
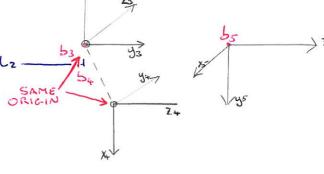
Mechatronics

23/10/09







$$\begin{bmatrix}
C_1 & -S_1 & 0 & 0 \cdot 1 C_1 \\
S_1 & C_1 & 0 & 0 \cdot 1 S_1 \\
0 & 0 & 1 & 0 & 0 & 0
\end{bmatrix}$$

$$\begin{bmatrix}
0 & 0 & 1 & 0 & 0 \\
0 & 0 & 0 & 1
\end{bmatrix}$$

$$\begin{bmatrix}
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0
\end{bmatrix}$$

$$\begin{bmatrix}
0 & 0 & 1 & 0 \\
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0
\end{bmatrix}$$