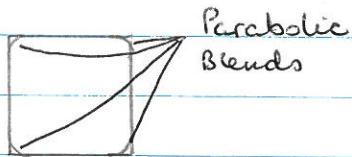


Trajectories

Mechatronics

Summer '09

4a)

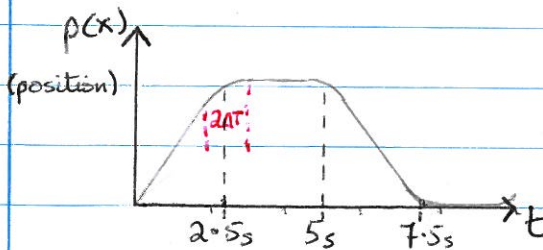


$$t_{\text{total}} = 10 \text{ secs}$$

$$t_{\text{side}} = 2.5 \text{ secs}$$

$$1 \text{ side} = 5 \text{ units} \rightarrow 2 \text{ units/sec}$$

(Ignoring parabolic blends)



Approx. $\frac{1}{2}$ way through parabola at $2.5s$, $5s$, $7.5s$.

We have assumed that initial velocity = max velocity.

$$\text{Time for entire parabolic blend} = 2\Delta T$$

$$|x, y \text{ acceleration}| = \frac{2}{2\Delta T} = \frac{1}{\Delta T} \text{ units/s}^2$$

$$|x, y \text{ deviation}| = \frac{a\Delta T^2}{2} = \frac{\Delta T}{2}$$

$$|\text{deviation}| = \sqrt{2} \frac{\Delta T}{2} \quad (\text{Overall taking xerr \& yerr into account, using pythagoras})$$

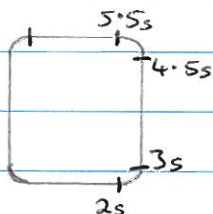
$$= \sqrt{2}(0.25)$$

$$\Delta T = 0.5s$$

$$\Rightarrow |x, y \text{ acceleration}| = 2 \text{ unit/s}^2$$

$$|x \text{ or } y \text{ acceleration}| = 2\sqrt{2} \text{ unit/s}^2$$

b)



Note: Using $s = s_0 + ut + \frac{1}{2}at^2$

$$\text{x-axis } v_x = 0, \quad 3s \leq t \leq 4.5s$$

$$P_x = 5$$

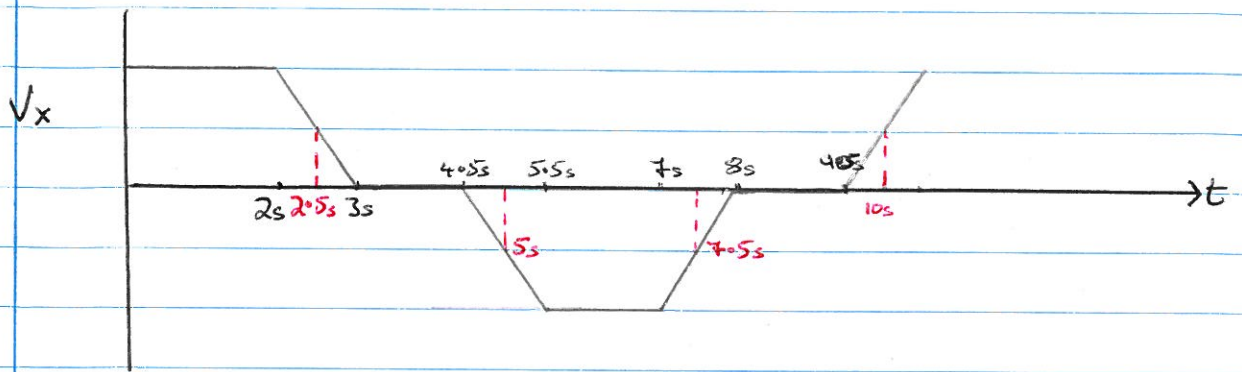
$$v_x = -2 \text{ units/s}, \quad 5.5 \leq t \leq 7s$$

$$\text{Looking for } 3.5s \leq t \leq 6.5s \quad P_x = 5 - 2(t - 5) = 15 - 2t$$

$$4.5s \leq t \leq 5.5s$$

$$P_x = 5 + 0t + \frac{1}{2}(-2)(t - 4.5)^2$$

Initial velocity IN x DIRECTION



3. $T_{\text{total}} = 10\text{s}$ $\Delta T = 0.5\text{s}$

$$w^1 = [-3, 0, 0, 0, 0, -1, 0.5]^T$$

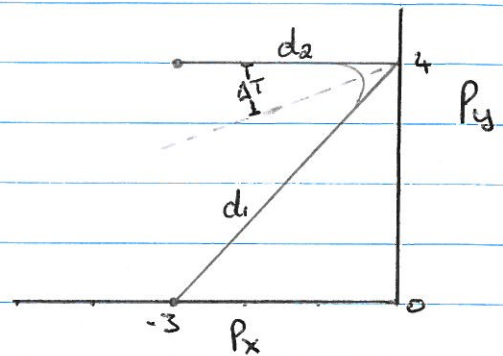
$$w^2 = [0, 4, 0, 0, 0, -1, 0.8]^T$$

$$w^3 = [-3, 4, 0, 0, 0, -1, 0.5]^T$$

$$d_1 = \sqrt{3^2 + 4^2} = 5 \text{ units}$$

$$d_2 = 3 \text{ units}$$

@ Constant velocity, $v = \frac{3}{10} = 0.3 \text{ units/sec}$.



a) X-Component

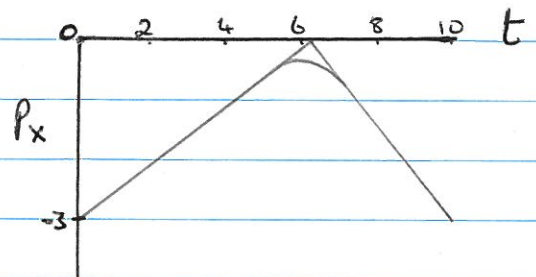
$$T_1 = 6.25\text{s}$$

$$T_2 = 3.75\text{s}$$

$$V_{x1} = \frac{3}{6.25} = 0.48 \text{ units/sec}$$

$$V_{x2} = \frac{-3}{3.75} = -0.8 \text{ units/sec}$$

$$a_x = \frac{V_{x2} - V_{x1}}{2\Delta T} = -1.28 \text{ units/sec}^2$$



$$w_x(t) = \begin{cases} -3 + 0.48t & 0 \leq t \leq 6.25 \\ -0.24 + 0.48(t - 6.25) - (0.64)(t - 6.25)^2 & 6.25 \leq t \leq 7.5 \\ -0.4 - 0.8(t - 7.5) & 7.5 \leq t \leq 10 \end{cases}$$

b) Y-Component

$$V_{y1} = \frac{4}{6.25} = 0.64 \text{ units/sec}$$

$$V_{y2} = 0$$

Over first 4s: $p_y = 0 + 0.64t$

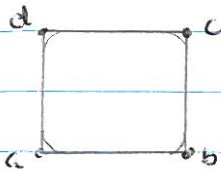
$$p_x = -3 + 0.48t$$

$$p_y^2 = 0.4096t^2$$

$$p_x^2 = 0.2304t^2 - 2.88t + 9$$

$$\Theta_2 = \pm \cos^{-1} \left(\frac{0.64t^2 - 2.88t - 41}{20} \right)$$

7.



$$T_{\text{total}} = 10s$$

$$\Rightarrow v = 2 \text{ units/s}$$

$$d_{\text{total}} = 20 \text{ units}$$

$$\Rightarrow \Delta T = ?$$

- a) Half way through parabola @ $2.5s, 5s, 7.5s, 10s$
 Length of time for $\frac{1}{2}$ parabola = ΔT

$$a_{x,y} = \frac{2}{2\Delta T} = \frac{1}{\Delta T}$$

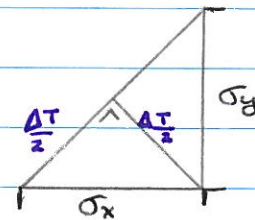
Deviation from corner

$$dx,y = \frac{a\Delta T^2}{2} = \frac{\Delta T}{2}$$

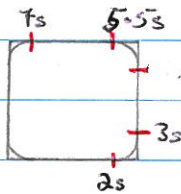
$$dx = dy = \sqrt{2} \frac{\Delta T}{2} = 0.25\sqrt{2}$$

$$\Rightarrow \Delta T = 0.5$$

$$a = 2 \text{ units/s}^2 \quad \text{duration of parabolic blend} = 1s$$



b)



$$x_1(t) = 5$$

$$3.5s \leq t \leq 4.5s$$

$$x_2(t) = 5 + 0(t-4.5) - \frac{1}{2}(2)(t-4.5)^2 \quad 4.5s \leq t \leq 5.5s$$

$$x_3(t) = 5 - 2(t-5)$$

$$5.5s \leq t \leq 6.5s$$

$$x(t) = \begin{cases} 5 & 3.5 \leq t \leq 4.5 \\ 5 - (t-4.5)^2 & 4.5 \leq t \leq 5.5 \\ 5 - 2(t-5) & 5.5 \leq t \leq 6.5 \end{cases}$$

7.

$$\omega^1 = [-3, 0, 0]^T$$

$$\omega^2 = [0, 8, 0]^T$$

$$\omega^3 = [-3, 8, 0]^T$$

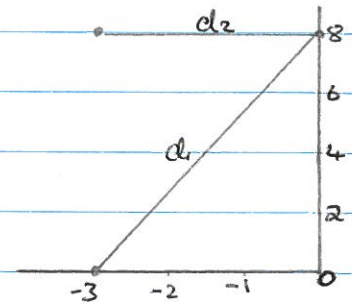
$$T_{12} = T_{23} = T_{31}$$

$$d_1 = \sqrt{73}$$

$$v_1 = \frac{\sqrt{73}}{5} \text{ units/s}$$

$$d_2 = 3$$

$$v_2 = -0.6 \text{ units/s}$$



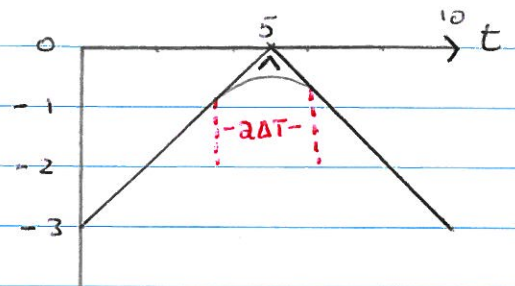
X-Component

$$v_{1x} = 0.6 \text{ units/s}$$

$$v_{2x} = -0.6 \text{ units/s}$$

$$a_x = -\frac{1.2}{2\Delta T} \text{ units/s}^2$$

$$|\sigma_x| = \left| \frac{a\Delta T^2}{2} \right| = \frac{1.2\Delta T}{4} = 0.3\Delta T$$



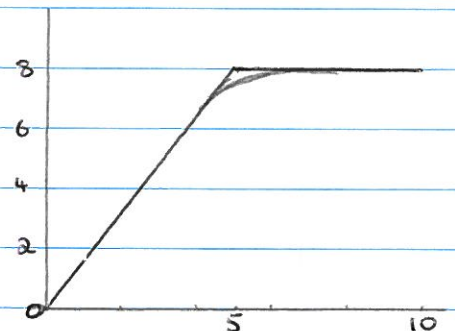
Y-Component

$$v_{1y} = 1.6 \text{ units/s}$$

$$v_{2y} = 0 \text{ units/s}$$

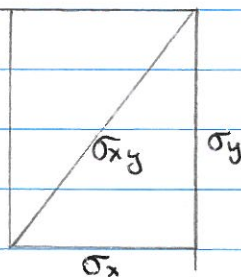
$$a_y = -\frac{1.6}{2\Delta T}$$

$$|\sigma_y| = \left| \frac{a\Delta T^2}{2} \right| = \frac{1.6\Delta T}{4} = 0.4\Delta T$$



$$\sigma_{xy} = 0.5\Delta T = 0.125$$

$$\Delta T = 0.25$$

 σ_{xy}

X-Trajectory

$$x(t) = \begin{cases} -3 + 0.6t & 0 \leq t \leq 4.75 \\ -0.15 + 0.6(t-4.75) - \frac{1}{2}(2.4)(t-4.75)^2 & 4.75 \leq t \leq 5.25 \\ -0.6(t-5) & 5.25 \leq t \leq 10 \end{cases}$$

EE4009

Mechatronics

Summer '06

 y -Trajectory

$$y(t) = \begin{cases} 1.6t & 0 \leq t \leq 4.75 \\ 7.6 + 1.6(t-4.75) - \frac{1}{2}(3.2)(t-4.75)^2 & 4.75 \leq t \leq 5.25 \\ 8 & 5.25 \leq t \leq 10 \end{cases}$$

Summer '05

$$\begin{aligned} \omega^1 &= [4, 3, 0, 0, 0, -1, 0.8]^T \\ \omega^2 &= [0, 0, 0, 0, 0, -1, 0.5]^T \\ \omega^3 &= [4, 0, 0, 0, 0, -1, 0.8]^T \end{aligned}$$

$$t_{\text{total}} = 18s$$

$$\Delta T = 1s \quad \bar{v}_1 = \bar{v}_2$$

$$d_1 = 5 \Rightarrow |\bar{v}| = 0.5 u/s$$

$$d_2 = 4$$

$$\bar{v}_{1x} = -0.4 u/s$$

$$\bar{v}_{1y} = -0.3 u/s$$

$$\bar{v}_{2x} = 0.5 u/s$$

$$\bar{v}_{2y} = 0 u/s$$

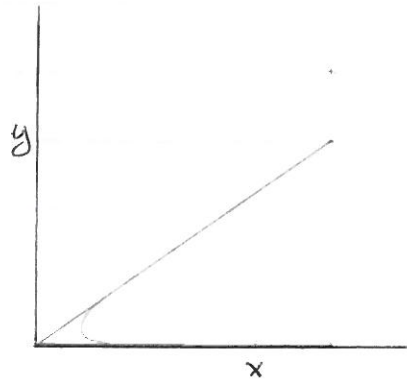
$$a_x = 0.45 u/s^2$$

$$a_y = 0.15 u/s^2$$

$$dev_x = 0.225 \text{ units}$$

$$dev_y = 0.075 \text{ units}$$

$$dev_{xy} = 0.237171$$



X-Trajectory

$$0 \leq t \leq 9s, \quad P_x = 4 - 0.4t$$

$$9 \leq t \leq 11s, \quad P_x = 0.4 - 0.4(t-9) + 0.225(t-9)^2$$

$$11s \leq t \leq 18s, \quad P_x = 0.5(t-10)$$

Y-Trajectory

$$0 \leq t \leq 9s, \quad P_y = 3 - 0.3t$$

$$9 \leq t \leq 11s, \quad P_y = 0.3 - 0.3(t-9) + 0.075(t-9)^2$$

$$11s \leq t \leq 18s, \quad P_y = 0$$

$$\Theta_2 = \pm \text{Arccos} \left(\frac{(4-0.4t)^2 + (3-0.3t)^2 - 50}{50} \right) \quad 0 \leq t \leq 9s$$

$$\Theta_2 = \pm \text{Arccos} \left(\frac{0.25t^2 - 5t - 25}{50} \right) \quad 9 \leq t \leq 11s$$

$$\Theta_2 = \pm \text{Arccos} \left(\frac{(0.5t-5)^2 - 50}{50} \right) = \pm \text{Arccos} \left(\frac{0.25t^2 - 5t - 25}{50} \right) \quad 11s \leq t \leq 18s$$

Summer '04

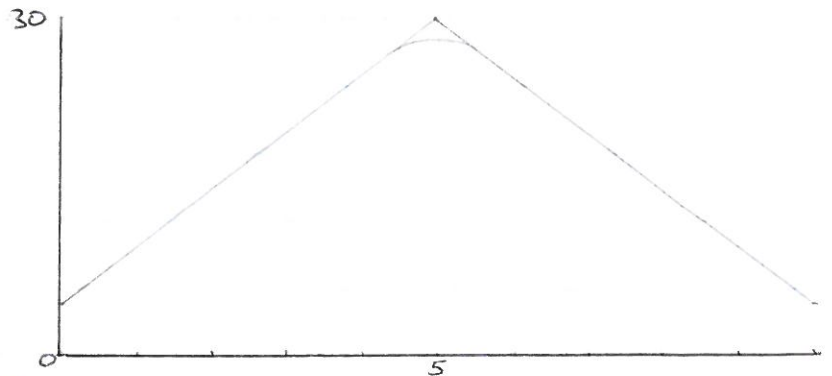
$$\begin{aligned} p_x(t) &= 5 + 5t & p_y(t) &= 25 - 5t & 0 \leq t \leq 5 \\ p_x(t) &= 55 - 5t & p_y(t) &= 0 & 5 \leq t \leq 10 \end{aligned}$$

$$a = -5 \text{ m/s}^2 = \frac{v_{2x} - v_{1x}}{2\Delta T}$$

$$\bar{v}_{2x} = -5 \text{ m/s} \quad \bar{v}_{1x} = 5 \text{ m/s}$$

$$\Rightarrow \Delta T = 1 \text{ s}$$

$$d_{ex} = 2.5 \text{ cm}$$



$$0 \leq t < 4, \quad p_x = 5 + 5t$$

$$4 \leq t < 6, \quad p_x = 25 + 5(t-4) - 2.5(t-4)^2$$

$$6 \leq t < 10, \quad p_x = 30 - 5(t-5)$$

$$\bar{v}_{1y} = 5 \text{ m/s} \quad \bar{v}_{2y} = 0$$

$$a = -5 \Rightarrow \Delta T = 0.5 \text{ s}$$

$$d_{ey} = 0.625$$

$$d_{exy} = 2.577 \text{ cm}$$