

Lab 8

Bayesian Bootstrap

Why do we need to do Bootstrap

Recall from lab 7 that we want to calculate the ATE:

$$\Psi := ATE = E_Z [E_{Y|Z,X} [Y_i | X_i = 1, Z_i] - E_{Y|Z,X} [Y_i | X_i = 0, Z_i]]$$

Note that here X is the treatment variables, where Z is the confounders. We know from the lecture and previous labs that under a given model, we can express $E_{Y|Z,X} [Y_i | X_i, Z_i]$ in a regression function, whether that is parametric or not. For simplicity we will consider this parametric model:

$$E_{Y|Z,X} [Y_i | X_i, Z_i] = \beta_0 + \beta_1 X_i + \beta_2 X_i Z_i$$

we will see that

$$E_{Y|Z,X} [Y_i | X_i = 1, Z_i] = \beta_0 + \beta_1 + \beta_2 Z_i$$

and

$$E_{Y|Z,X} [Y_i | X_i = 0, Z_i] = \beta_0$$

Thus

$$\Psi = ATE = \beta_1 + \beta_2 E_Z[Z]$$

Now if we place priors on $\beta_0, \beta_1, \beta_2$ we can get posterior draws (say, size M) for these parameters : $\{\beta_0^{(m)}, \beta_1^{(m)}, \beta_2^{(m)}\}_{m=1}^M$. If we know the distribution of the confounder Z , than we can conduct inference of ATE by generating a series of posterior draws of $\Psi^{(m)} = \beta_1^{(m)} + \beta_2^{(m)} E_Z[Z]$. The problem however is that in regression models we tend to treat the confounders as fixed and known and usually do not specify a distribution in modeling stage. This requires us to use a nonparametric method (nonparametric in that we do not compute $E[Z]$ based on parametric assumptions of the distribution of Z).

- **Remark:** the process of ‘integrating over Z ’ is called **standardization** in causal inference. Bayesian bootstrapping is one way of doing standardization when we conduct Bayesian analysis for ATE estimation.
- **Remark 2:** Essentially, you can think about Bootstrapping as a way to ‘calculate’ things like expectation (in our case, $E[Z]$), where the only piece of information you have about Z is the observed data itself (i.e. a bunch of individual observations, Z_1, \dots, Z_n).

How to do Bayesian Bootstrap

Say now we have a vector of confounder variable Z : Z_1, \dots, Z_n , and we want to estimate $E[Z]$ through Bootstrapping. There are generally two steps in the Bootstrapping procedure:

- Generate a bunch of ‘pseudo-datasets’ $\mathbf{Z}'_1, \dots, \mathbf{Z}'_m$ (say, of size M) based on Z_1, \dots, Z_n .

- For each of these pseudo datasets, we calculate the average of the pseudo-dataset:

$$\bar{Z}'_1, \dots, \bar{Z}'_m$$

(We will learn how to generate these pseudo-datasets in a minute.)

We can use the set of pseudo-dataset averages for inference of $E[Z]$, (say, we can calculate sample quantiles as a credible/confidence intervals of $E[Z]$, or calculate the average of the averages as a point estimate for $E[Z]$).

We then see how to understand this under the Bayesian framework.

- Generating pseudo-datasets: draw weights from a uniform Dirichlet distribution with the same dimension as the number of data points. If the data is Z_1, \dots, Z_n , we sample a vector of weights p from a Dirichlet distribution of $Dir(1, 1, \dots, 1)$ where there are n number ones.
- What is a uniform Dirichlet distribution? For a uniform Dirichlet distribution of dimension K , the samples drawn from this distribution will be evenly distributed on a standard simplex of dimension $K - 1$:

$$\sum_{i=1}^K x_i = 1 \text{ and } x_i \geq 0 \text{ for all } i \in \{1, \dots, K\}$$

You can see a vector (x_1, \dots, x_K) like this will correspond to a discrete distribution of K different outcomes. This means that all possible distributions are likely to be drawn from this uniform Dirichlet distribution. - Now we have a vector of weights (p_1, \dots, p_n) , we then draw a pseudo dataset of size n' (notice that n' can be different than n), consisting of n' i.i.d samples from the discrete distribution associated with (p_1, \dots, p_n) . i.e.

$$P(Z'_i = k) = p_k, k = 1, \dots, K$$

where Z'_i is the i -th element in the pseudo-dataset. - Finally, we calculate the mean from this pseudodataset. This is the first pseudo dataset so we denote it as $\bar{Z}'^{(1)}$. We repeat it until we have M pseudo datasets, and we have

$$\bar{Z}'^{(1)}, \dots, \bar{Z}'^{(m)}$$

. The mean of this will serve as an estimator for $E[Z]$.

Okay this is super complicated – do we have an easy way out?

- Luckily if the population mean is what we care about, we do not need to sample the pseudo dataset – all we need are the weights. (Why?)
- for each $b = 1, \dots, B$, we just need to sample weights from the uniform dirichlet distribution:

$$(p_1^{(m)}, p_n^{(m)}) \sim Dir(1, \dots, 1)$$

- Then weight our data by the weights

$$Z'^{(m)} = \sum_{i=1}^n p_i^{(m)} Z_i$$

The rest is the same as the first procedure.

Estimating ATE: putting it back together

Now we put this back into our picture of estimating ATE . Suppose we have M posterior samples, $\{\beta_0^{(m)}, \beta_1^{(m)}, \beta_2^{(m)}\}_{m=1}^M$, we now replace $E_Z[Z]$ by each of the $\bar{Z}'^{(1)}, \dots, \bar{Z}'^{(m)}$ for $m = 1, \dots, M$. This gives us a set of ‘estimated’ posterior draws of ATE :

$$\Psi^{(m)} = \beta_1^{(m)} + \beta_2^{(m)} \bar{Z}'^{(m)}$$

This allow us to do inference for ATE: posterior mean, credible intervals, etc...

Cracking the code

Now we take a look at the example code of Bayesian Bootstrapping, so that you can adapt it for your own model!

- `mu_a1`, `mu_a0`: estimates for $E[Y|X = 1, Z]$ and $E[Y|X = 0, Z]$
- `mu_a1`, `mu_a0` are matrices: the number of columns represents the number of posterior draws, why the number of rows represents the number of observations in the dataset (row of the dataset)
- we repeat this procedure for M times, since we have M draws
- for each iteration, we calculate $ATE^{(m)}$ using the formula we have above
- the function returns `psi_post`, the vector of posterior draws of ATE

```
bayes_boot = function(mu_a1, mu_a0) {  
  n = nrow(mu_a1)  
  M = ncol(mu_a1)  
  psi_post = numeric(M)  
  for (m in 1:M) {  
    bb_weights = rdirichlet(1, rep(1, n))  
    psi_post[m] = sum(bb_weights * (mu_a1[, m] - mu_a0[, m]))  
  }  
  return(psi_post)  
}
```