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Project 7 - GPS
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Table of Contents

Requirements.....	.1
Design.....	.1
Implementation.....	.1
Demo.....	.2
References.....	.3

Requirements

This project requires adding a GPS module to a raspberry pi on a flight capable drone. The GPS module should capture GPS data, send the data over wifi, and be displayed on a host device.

Design

Using the flight capable drone from previous assignment, the raspberry pi, power bank, and Gmouse GPS module are secured to the drone and connected over USB. On the pi, GPS packages are installed and while the drone and pi are powered, the GPS data is sent to the remote host using ssh to remote into the pi.

Implementation

In order to use the GPS module we first need to install some packages and verify devices.

// remotely connect to pi e.g.

\$ ssh user@IP

// make note of tty address to verify the gps module is connected and functioning

\$ ls /dev/tty*

> */dev/ttyACM0 is present after inserting the gps module*

// install relevant packages for gps data

\$ sudo apt install gpsd gpsd-clients

//restart the pi

\$ sudo reboot now

// connect to the pi again and view gps data remotely on the host

\$ cgps -s

Time:	2024-04-04T20:02:46.000Z (18)	GNSS	PRN	Elev	Azim	SNR	Use
Latitude:	41.65721650 N	GP	3	21.0	42.0	31.0	Y
Longitude:	73.91317220 W	GP	6	75.0	300.0	25.0	Y
Alt (HAE, MSL):	263.448, 375.292 ft	GP	11	41.0	252.0	23.0	Y
Speed:	0.00 mph	GP	14	16.0	162.0	32.0	Y
Track (true, var):	70.6, -13.1 deg	GP	19	72.0	53.0	29.0	Y
Climb:	0.00 ft/min	GP	4	8.0	79.0	16.0	N
Status:	3D FIX (70 secs)	GP	9	7.0	117.0	20.0	N
Long Err (XDOP, EPX):	1.21, +/- 59.6 ft	GP	12	25.0	315.0	9.0	N
Lat Err (YDOP, EPY):	1.01, +/- 49.6 ft	GP	17	50.0	93.0	27.0	N
Alt Err (VDOP, EPV):	1.95, +/- 863 ft	GP	20	15.0	203.0	14.0	N
2D Err (HDOP, CEP):	1.58, +/- 2017 ft	GP	22	n/a	0.0	26.0	N
3D Err (PDOP, SEP):	2.51, +/- 6232 ft	GP	24	7.0	265.0	0.0	N
Time Err (TDOP):	1.37 I	SB120	33	15.0	112.0	0.0	N
Geo Err (GDOP):	2.86	SB133	46	36.0	214.0	0.0	N
ECEF X, VX:	1322998.250 m -0.180 m/s	SB138	51	31.0	225.0	0.0	N
ECEF Y, VY:	-4584422.310 m -0.020 m/s	QZ	1	193	n/a	0.0	N
ECEF Z, VZ:	4218280.550 m 0.040 m/s	QZ	3	195	n/a	0.0	N
Speed Err (EPS):	+/- 2.1 mph						
Track Err (EPD):	n/a						
Time offset:	0.057856301 s						
Grid Square:	FN31bp07						

Demo

The flight capable drone had to be benched due to wind and rain, but the gps module works perfectly when pointed out a window.

https://drive.google.com/file/d/1bZFdHpuU_0rdDhxGUd_88utLs4X3bIN/view?usp=sharing

May 3rd, 2024:

I took the drone out and flew it successfully while capturing gps data on a remote machine over wifi:

https://drive.google.com/file/d/1_PYzoN338i3Q3Mi7xRHLReDeQW_Hef0u/view?usp=sharing

References

<https://raspberrypi.stackexchange.com/questions/68816/how-can-i-set-up-my-g-mouse-usb-gps-for-use-with-raspbian>