MATH 2418: Linear Algebra

Assignment 9

Due: March 30, 2016 Term: Spring, 2016

Suggested problems(do not turn in): Section 4.8: 1, 3, 5, 7, 9, 13, 15. Section 4.9: 13, 15, 17, 19, 21, 23, 39.

- 1. [10 points] (2 points each) Use matrix multiplication to:
 - (a) Find the reflection of (a,b) about the y-axis.

Solution:

$$\begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} -a \\ b \end{bmatrix}$$

(b) Find the reflection of (a,b,c) about the xz-plane.

Solution:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} a \\ -b \\ c \end{bmatrix}$$

(c) Find the orthogonal projection of (a,b) onto the the y-axis.

Solution:

$$\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 0 \\ b \end{bmatrix}$$

(d) Find the orthogonal projection of (a,b,c) onto the yz-plane.

Solution:

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ b \\ c \end{bmatrix}$$

(e) Find the image of the nonzero vector $\mathbf{v} = (v_1, v_2)$ when it is rotated about the origin through a negative angle $-\alpha$.

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Solution:

$$\begin{bmatrix} cos(-\alpha) & -sin(-\alpha) \\ sin(-\alpha) & cos(-\alpha) \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} v_1cos(-\alpha) - v_2sin(-\alpha) \\ v_1sin(-\alpha) + v_2cos(-\alpha) \end{bmatrix} = \begin{bmatrix} v_1cos\alpha + v_2sin\alpha \\ -v_1sin\alpha + v_2cos\alpha \end{bmatrix}$$

2. [10 points] Consider the following matrices, where R is the reduced row-echelon form of A:

$$A = \begin{bmatrix} 2 & 0 & -4 & 1 & 3 \\ 1 & 3 & 1 & 3 & 7 \\ 0 & 2 & 2 & -2 & 0 \\ -1 & 1 & 3 & 4 & 4 \end{bmatrix} \Longrightarrow \begin{bmatrix} 1 & 0 & -2 & 0 & 1 \\ 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = R$$

Determine the following values without completing the solution to any system of equations.

(a) What is rank(A)?

Solution:

Count the leading ones in R to get rank(A) = 3.

(b) What is $rank(A^{T})$?

Solution:

The rank of the transpose, A^{T} , is the same as for A: $rank(A^{T}) = rank(A) = 3$.

(c) What is nullity(A)?

Solution:

The nullity of A is the number of columns of A minus rank(A) = 5 - 3 = 2, so nullity(A) = 2.

(d) What is $\operatorname{nullity}(A^{\mathrm{T}})$?

Solution:

The number of columns of A^{T} minus rank((^{T}A) is the number of rows of A minus the rank of A: nullity(A^{T}) = 4 - rank(A) = 4 - 3 = 1. Note that this is the same as the number of zero rows in R. Again, nullity(A^{T}) = 1.

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(e) What is the dimension of the row space of A?

Solution:

We have $\dim(\operatorname{row}(A)) = \operatorname{rank}(A) = 3$.

(f) What is the dimension of the row space of A^{T} ?

Solution:

Again, $\dim(\text{row}(A^{T})) = \text{rank}(A^{T}) = 3.$

(g) What is the dimension of the column space of A?

Solution:

We have $\dim(\operatorname{col}(A)) = \operatorname{rank}(A) = 3$.

(h) What is the dimension of the column space of A^{T} ?

Solution:

Again,
$$\dim(\operatorname{col}(A^{\mathsf{T}})) = \operatorname{rank}(A^{\mathsf{T}}) = 3.$$

(i) What is the dimension of the null space of A?

Solution:

We have
$$\dim(\text{null}(A)) = \text{nullity}(A) = 2$$
.

(j) What is the dimension of the null space of A^{T} ?

Solution:

This time we get $\dim(\operatorname{col}(\operatorname{null}(A^{\mathrm{T}}))) = \operatorname{nullity}(A^{\mathrm{T}}) = 1$.

3. [10 points] (5+5) In \mathbb{R}^3 the **orthogonal projections** onto the x-axis, y-axis and z-axis are

$$T_1(x, y, z) = (x, 0, 0),$$
 $T_2(x, y, z) = (0, y, 0),$ $T_3(x, y, z) = (0, 0, z),$

respectively.

(a) Find the standard matrices for T_1 , T_2 and T_3 .

Solution:

$$T_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}; T_2 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}; T_3 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

(b) Show that if $T: \mathbb{R}^3 \to \mathbb{R}^3$ is one of these orthogonal projections, then for every vector $\mathbf{v} \in \mathbb{R}^3$, $T(\mathbf{v})$ and $(\mathbf{v} - T(\mathbf{v}))$ are orthogonal.

Solution:

Consider, for example, T_1 . If $\mathbf{v} = (v_1, v_2, v_3), T_1(\mathbf{v}) = (v_1, 0, 0)$. Moreover,

$$T_1(\mathbf{v}) \cdot (\mathbf{v} - T_1(\mathbf{v})) = (v_1, 0, 0) \cdot (0, v_2, v_3) = 0.$$

4. [10 points] Find the rank (5 points) and nullity (5 points) of the standard matrix for T, where

$$T: \mathbb{R}^2 \to \mathbb{R}^3$$
, $T(x_1, x_2) = (x_1 + 3x_2, x_1 - x_2, x_1)$.

Solution:

$$T\left(x_{1},x_{2}\right) = \begin{bmatrix} x_{1}+3x_{2} \\ x_{1}-x_{2} \\ x_{1} \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 1 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix}; \text{ the standard matrix is } A = \begin{bmatrix} 1 & 3 \\ 1 & -1 \\ 1 & 0 \end{bmatrix}.$$
 Its reduced row echelon form is
$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}.$$

(a) rank (A) = 2 (b) nullity (A) = 0. Note that these conclusions could have been derived from a row echelon form.

- 5. [10 points] True or False.
 - (a) **T F**: In a square matrix A, nullity(A) = nullity (A^{T}) .

Solution:

True. Suppose A is an $n \times n$ square matrix with rank r. Then the nullity of A would be n-r, as would the nullity of A^{T} .

(b) **T F**: The nullity of an $m \times n$ matrix is at most m.

Solution:

False. The nullity of A is limited by the number of its columns, not the number of its rows. A suitable counterexample would be a 3×6 matrix A with rank 2, and thus nullity 4, which is greater than the number of rows, 3.

(c) **T F**: If A has more rows than columns, the nullity of A^{T} is less than the nullity of A.

Solution:

False. Suppose A is $m \times n$, so that m > n. If $\operatorname{rank}(A) = r$ then $\operatorname{nullity}(A) = n - r$ and $\operatorname{nullity}(A^{\mathrm{T}}) = m - r$. From m > n we get $\operatorname{nullity}(A) = n - r < m - r = \operatorname{nullity}(A^{\mathrm{T}})$.

(d) **T F**: If V is a subspace of \mathbb{R}^n and W is a subspace of V then V^{\perp} is a subspace of W^{\perp} .

Solution:

True. Any vector \mathbf{v} in V^{\perp} orthogonal to all vectors in V, and that includes all vectors in its subspace W, so \mathbf{v} is orthogonal to all vectors in W, and thus is in W^{\perp} . As this is true for any such vector \mathbf{v} , we must have that V^{\perp} is a subspace of W^{\perp} .

(e) **T F**: The kernel of the matrix transform $T_A : \mathbb{R}^n \to \mathbb{R}^m$ is the same as the null space of the corresponding $m \times n$ matrix A.

Solution:

True. $\operatorname{kernel}(T_A) = \{ \mathbf{x} \in \mathbb{R}^n \mid T_A(\mathbf{x}) = \mathbf{0} \} = \{ \mathbf{x} \in \mathbb{R}^n \mid A\mathbf{x} = \mathbf{0} \} = \operatorname{null}(A).$