

PHYS2326 Lecture #5

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Department of Physics
The University of Texas at Dallas

Goals for this Lecture

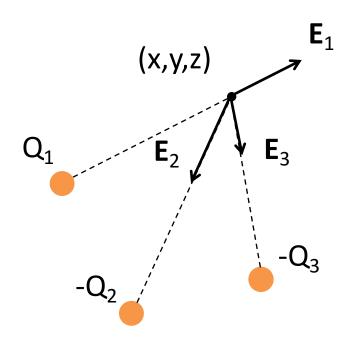
- Quick reminder
- Continue our tour on electric field calculation
 - Discrete charge distribution: electric dipole
 - Continuous (homogeneous) charge distribution
- Understand force and torque on electric dipole

Reminder: E-Field Calculations

Discrete distribution of charges

Continuous distribution of charges

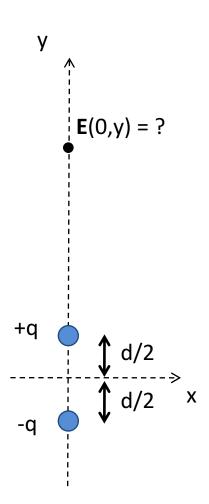
 Electric field produced by a discrete distribution of point charges (Superposition principle)



$$\vec{E}(x,y,z) = \vec{E}_1 + \vec{E}_2 + \vec{E}_3 + \dots$$

$$\vec{E}(x,y,z) = \sum_{i=1}^{N} \vec{E}_{i}$$

Electric Dipole



$$\vec{E}(y) = ?$$

$$\vec{E}(y) = \vec{E}_{-q}(y) + \vec{E}_{+q}(y)$$

$$\vec{E}(y) = \frac{1}{4\pi\epsilon_0} \frac{q}{r_{+q}^2} \hat{y} - \frac{1}{4\pi\epsilon_0} \frac{q}{r_{-q}^2} \hat{y}$$

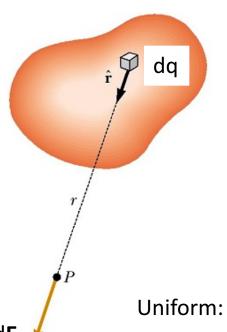
$$\vec{E}(y) = \frac{q}{4\pi\epsilon_0} \left[\frac{1}{\left(y - \frac{d}{2}\right)^2} - \frac{1}{\left(y + \frac{d}{2}\right)^2} \right] \hat{y}$$

$$\vec{E}(y) = \frac{q}{4\pi\epsilon_0 y^2} \left[\left(1 - \frac{d}{2y} \right)^{-2} - \left(1 + \frac{d}{2y} \right)^{-2} \right] \hat{y}$$

for $y \gg d$:

$$\vec{E}(y) = \frac{qd}{2\pi\epsilon_0 y^3}\hat{y}$$

Electric field produced by a uniform distribution of point charges

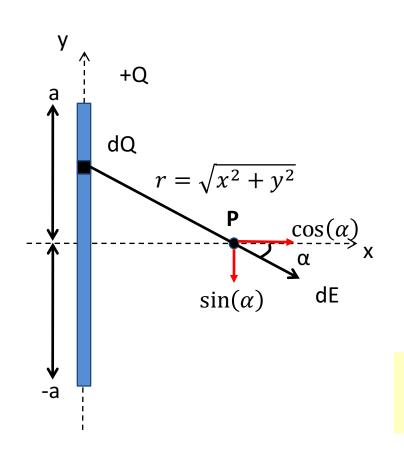


$$d\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{dq}{r^2} \hat{r}$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{r^2} \hat{r}$$

Uniform: The charge density is the same in any point of the object

Line of Charge



$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{r^2} \hat{r}$$

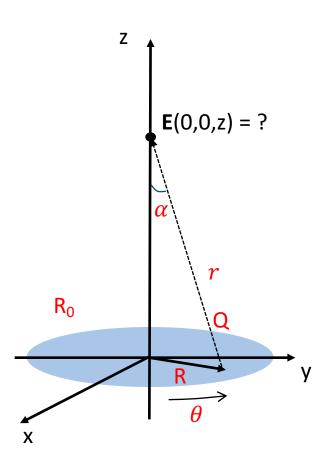
$$\vec{E} = \frac{\lambda}{4\pi\epsilon_0} \int_{-a}^{a} \frac{dy}{(x^2 + y^2)} \left[\frac{x}{\sqrt{x^2 + y^2}} \hat{x} + \frac{y}{\sqrt{x^2 + y^2}} \hat{y} \right]$$

$$\vec{E} = \frac{\lambda}{4\pi\epsilon_0} \int_{-a}^{a} \frac{dy}{(x^2 + y^2)^{3/2}} \left[x\hat{x} + y\hat{y} \right]$$

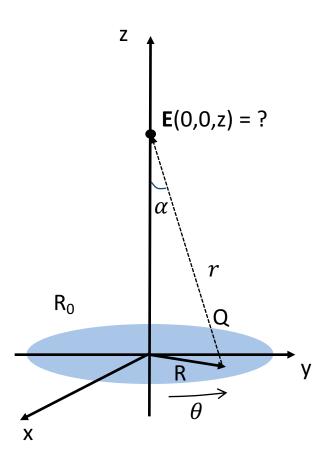
$$\vec{E} = \frac{\lambda}{4\pi\epsilon_0} \left[x \int_{-a}^{a} \frac{dy}{(x^2 + y^2)^{3/2}} \hat{x} + \int_{-a}^{a} \frac{ydy}{(x^2 + y^2)^{3/2}} \hat{y} \right]$$

$$\vec{E}(x, 0) = \frac{1}{4\pi\epsilon_0} \frac{Q}{x(a^2 + x^2)^{1/2}} \hat{x}$$

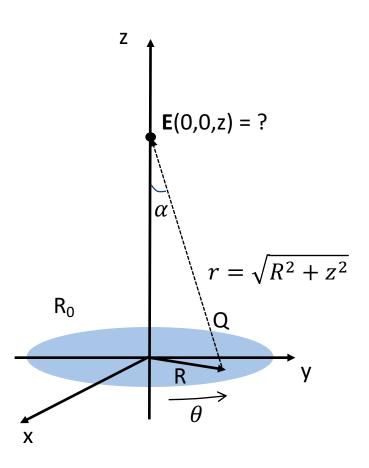
Uniformly Charged Disk



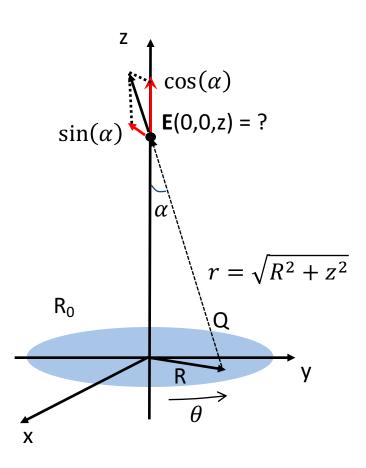
$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{r^2} \hat{r}$$



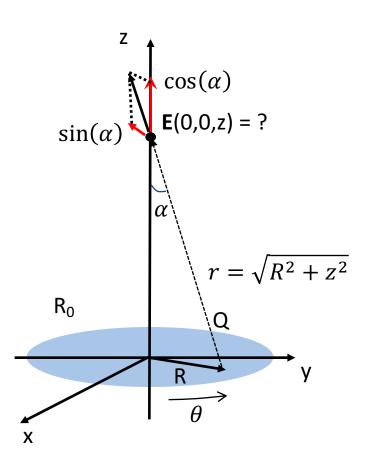
$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{r^2} \hat{r} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \hat{r}$$



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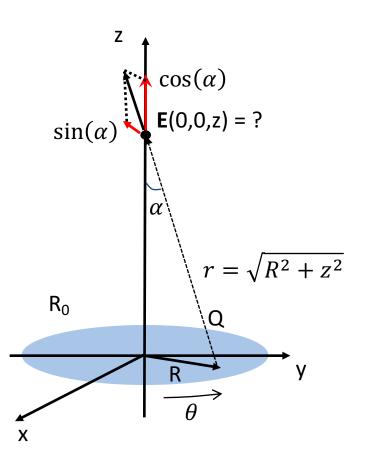


$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{r^2} \hat{r} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \hat{r} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \cos(\alpha) \hat{z}$$



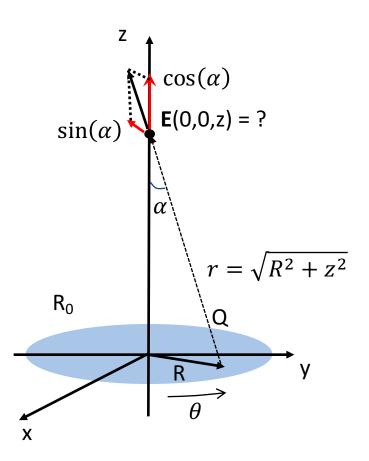
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$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \left[\frac{z}{(R^2 + z^2)^{1/2}} \right] \hat{z}$$



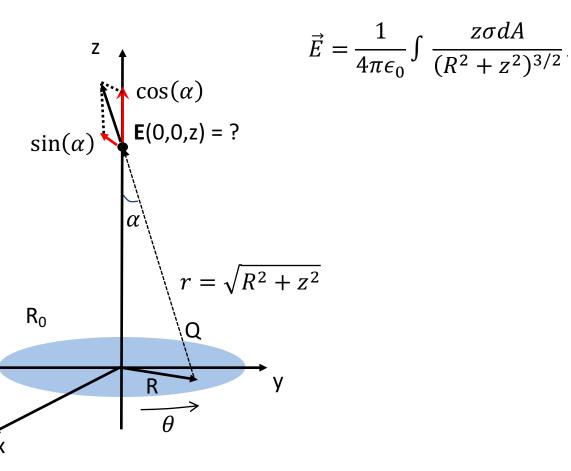
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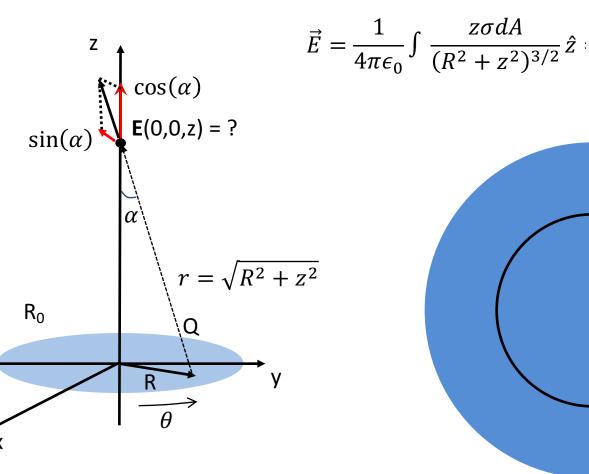
$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{z\sigma dA}{(R^2 + z^2)^{3/2}} \hat{z}$$

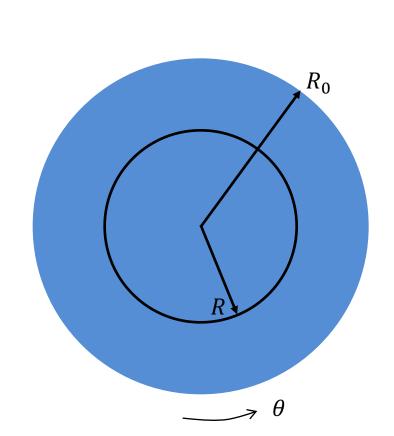
$$\sin(\alpha) \qquad F(0,0,z) = ?$$

$$R_0 \qquad Q$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{r^2} \hat{r} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \hat{r} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \cos(\alpha) \hat{z}$$

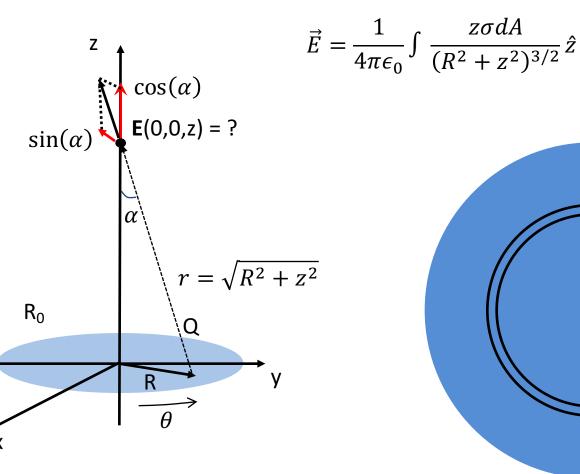
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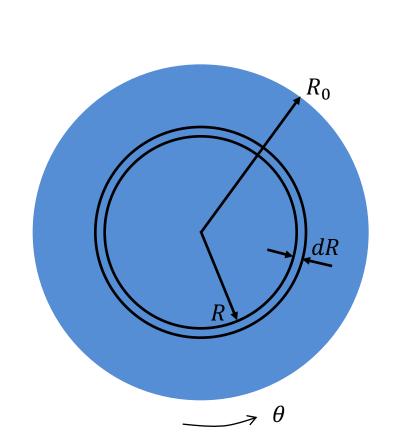




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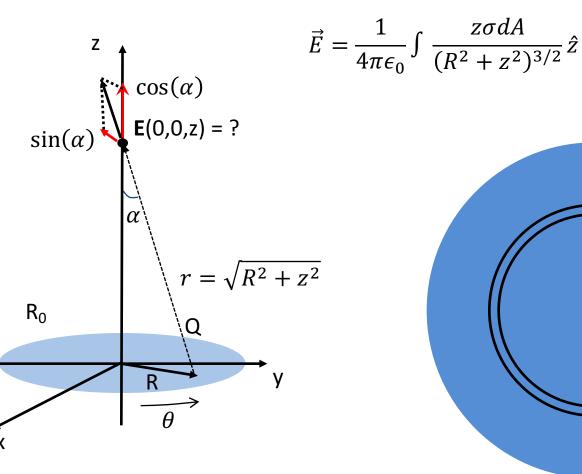
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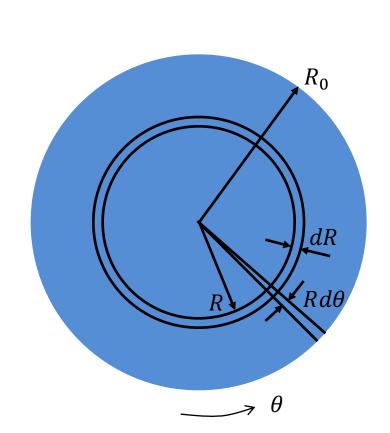




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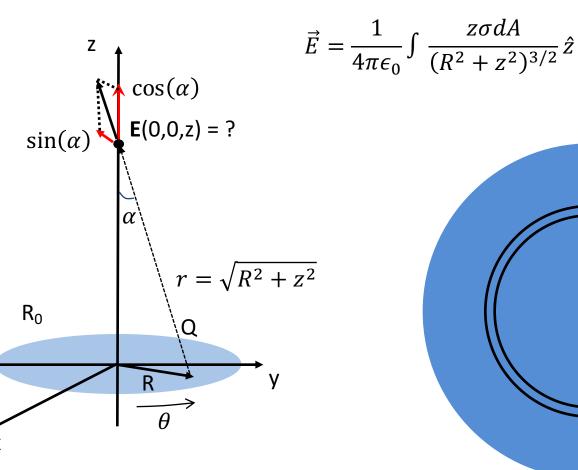
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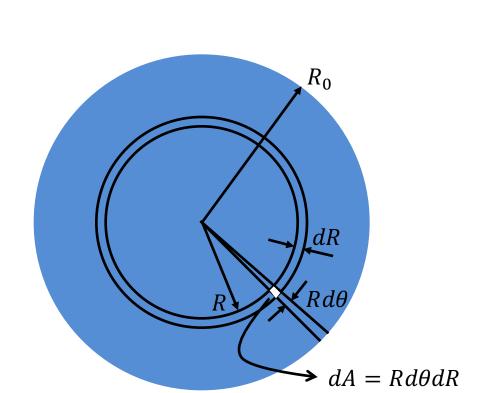




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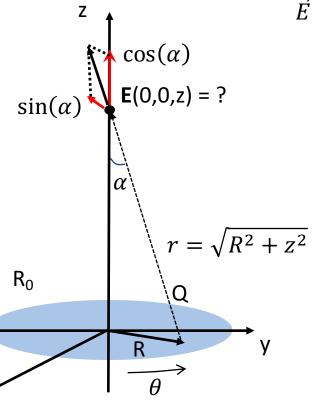


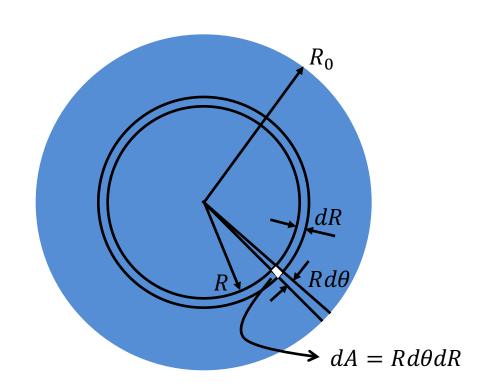


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$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{z\sigma dA}{(R^2 + z^2)^{3/2}} \hat{z} = \frac{1}{4\pi\epsilon_0} \int \int \frac{z\sigma R d\theta dR}{(R^2 + z^2)^{3/2}} \hat{z}$$





$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{r^2} \, \hat{r} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \, \hat{r} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \cos(\alpha) \, \hat{z}$$

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 R_0

 $Rd\theta$

 $dA = Rd\theta dR$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{r^2} \, \hat{r} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \, \hat{r} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \cos(\alpha) \, \hat{z}$$

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$$\vec{E} = \frac{z\sigma}{4\pi\epsilon_0} \int_0^{2\pi} d\theta \int_0^{R_0} \frac{R dR}{(R^2 + z^2)^{3/2}} \hat{z}$$

$$\vec{R} = \frac{z\sigma}{4\pi\epsilon_0} \int_0^{2\pi} d\theta \int_0^{R_0} \frac{R dR}{(R^2 + z^2)^{3/2}} \hat{z}$$

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$$\vec{E} = \frac{z\sigma}{4\pi\epsilon_0} (2\pi) \int_0^{R_0} \frac{R dR}{(R^2 + z^2)^{3/2}} \hat{z}$$

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$$R_0$$

$$\int \frac{ydy}{(y^2 + a^2)^{3/2}} = -\frac{1}{(y^2 + a^2)^{1/2}}$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{r^2} \hat{r} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \hat{r} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \cos(\alpha) \hat{z}$$

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$$\vec{E} = \frac{z\sigma}{4\pi\epsilon_0} (2\pi) \left[-\frac{1}{(R^2 + z^2)^{1/2}} \right]_0^{R_0} \hat{y}$$

$$\int \frac{ydy}{(y^2 + a^2)^{3/2}} = -\frac{1}{(y^2 + a^2)^{1/2}}$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{r^2} \, \hat{r} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \, \hat{r} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \cos(\alpha) \, \hat{z}$$

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$$\vec{E} = \frac{z\sigma}{4\pi\epsilon_0} (2\pi) \left[-\frac{1}{(R^2 + z^2)^{1/2}} \right]_0^{R_0} \hat{y}$$

$$\vec{E} = \frac{z\sigma}{2\epsilon_0} \left[-\frac{1}{(R^2 + z^2)^{1/2}} + \frac{1}{z} \right] \hat{y}$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{r^2} \, \hat{r} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \hat{r} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \cos(\alpha) \, \hat{z}$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \left[\frac{z}{(R^2 + z^2)^{1/2}} \right] \hat{z} = \frac{1}{4\pi\epsilon_0} \int \frac{zdq}{(R^2 + z^2)^{3/2}} \hat{z}$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{z\sigma dA}{(R^2 + z^2)^{3/2}} \hat{z} = \frac{1}{4\pi\epsilon_0} \int_0^{R_0} \int_0^{2\pi} \frac{z\sigma R d\theta dR}{(R^2 + z^2)^{3/2}} \hat{z}$$

$$\vec{E} = \frac{z\sigma}{4\pi\epsilon_0} \int_0^{2\pi} d\theta \int_0^{R_0} \frac{R dR}{(R^2 + z^2)^{3/2}} \hat{z}$$

$$\vec{E} = \frac{z\sigma}{4\pi\epsilon_0} (2\pi) \int_0^{R_0} \frac{R dR}{(R^2 + z^2)^{3/2}} \hat{z}$$

$$\vec{E} = \frac{z\sigma}{4\pi\epsilon_0} (2\pi) \left[-\frac{1}{(R^2 + z^2)^{1/2}} \right]_0^{R_0} \hat{y}$$

$$\vec{E} = \frac{z\sigma}{2\epsilon_0} \left[-\frac{1}{(R^2 + z^2)^{1/2}} + \frac{1}{z} \right] \hat{y}$$

$$\vec{E} = \frac{\sigma}{2\epsilon_0} \left[1 - \frac{z}{(R^2 + z^2)^{1/2}} \right] \hat{y}$$

 R_0

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{r^2} \hat{r} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \hat{r} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \cos(\alpha) \hat{z}$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{(R^2 + z^2)} \left[\frac{z}{(R^2 + z^2)^{1/2}} \right] \hat{z} = \frac{1}{4\pi\epsilon_0} \int \frac{zdq}{(R^2 + z^2)^{3/2}} \hat{z}$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{z\sigma dA}{(R^2 + z^2)^{3/2}} \hat{z} = \frac{1}{4\pi\epsilon_0} \int \int_0^{R_0} \frac{z\sigma Rd\theta dR}{(R^2 + z^2)^{3/2}} \hat{z}$$

$$\vec{E} = \frac{z\sigma}{4\pi\epsilon_0} \int_0^{2\pi} d\theta \int_0^{R_0} \frac{RdR}{(R^2 + z^2)^{3/2}} \hat{z}$$

$$\vec{E} = \frac{z\sigma}{4\pi\epsilon_0} (2\pi) \int_0^{R_0} \frac{RdR}{(R^2 + z^2)^{3/2}} \hat{z}$$

$$\vec{E} = \frac{z\sigma}{4\pi\epsilon_0} \left[-\frac{1}{(R^2 + z^2)^{1/2}} \right]_0^{R_0} \hat{y}$$

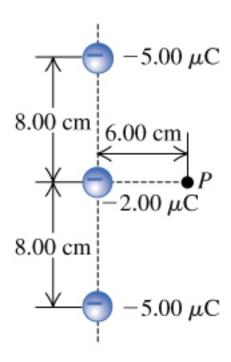
$$\vec{E} = \frac{z\sigma}{2\epsilon_0} \left[-\frac{1}{(R^2 + z^2)^{1/2}} \right] \hat{y}$$

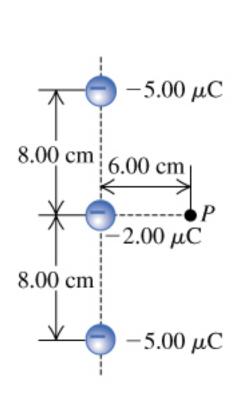
$$\vec{E} = \frac{\sigma}{2\epsilon_0} \left[1 - \frac{z}{(R^2 + z^2)^{1/2}} \right] \hat{y}$$

 R_0

Classical charge distributions:

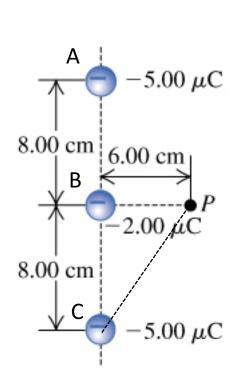
- Line of charge
- Ring of charge (see book)
- Uniformly charged disk
- Parallel plates (see book)





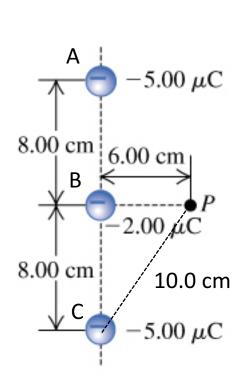
$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

$$|\vec{E}| = 1$$



$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

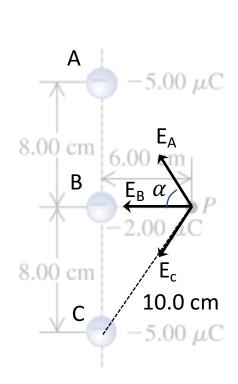
$$\left| \vec{E} \right| = 2$$



$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

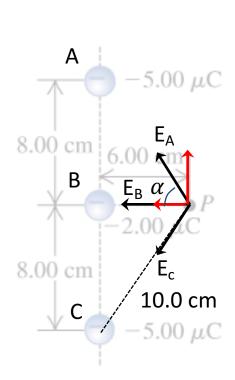
$$|\vec{E}| = ?$$

$$r = \sqrt{8.00^2 + 6.00^2} = 10.0 \ cm$$



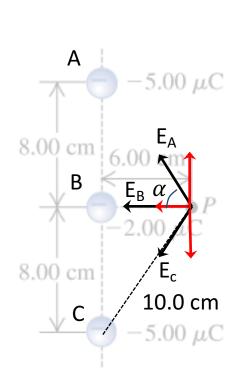
$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

$$|\vec{E}| = 2$$



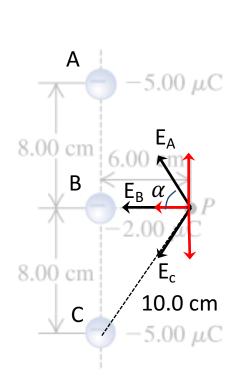
$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

$$|\vec{E}| = 2$$



$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

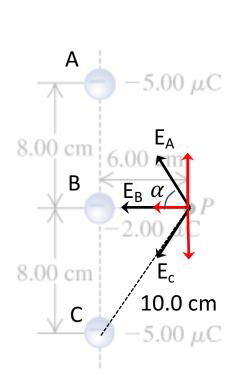
$$|\vec{E}| = 2$$



$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

$$|\vec{E}| = ?$$

$$\left| \vec{E} \right| = E_{A,x} + E_{B,x} + E_{C,x}$$

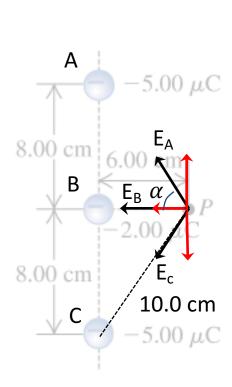


$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

$$|\vec{E}| = ?$$

$$|\vec{E}| = E_{A,x} + E_{B,x} + E_{C,x}$$

$$|\vec{E}| = 2E_{A,x} + E_{B,x}$$



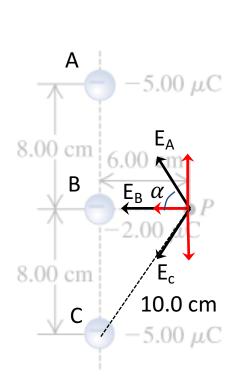
$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

$$|\vec{E}| = ?$$

$$|\vec{E}| = E_{A,x} + E_{B,x} + E_{C,x}$$

$$|\vec{E}| = 2E_{A,x} + E_{B,x}$$

$$|\vec{E}| = 2|\vec{E}_A|\cos(\alpha) + |\vec{E}_B|$$



$$|\vec{E}| = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

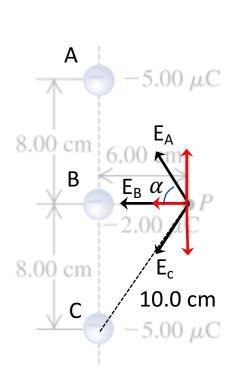
$$|\vec{E}| = ?$$

$$|\vec{E}| = E_{A,x} + E_{B,x} + E_{C,x}$$

$$|\vec{E}| = 2E_{A,x} + E_{B,x}$$

$$|\vec{E}| = 2|\vec{E}_A|\cos(\alpha) + |\vec{E}_B|$$

$$|\vec{E}| = 2\left[\left(\frac{1}{4\pi\epsilon_0} \frac{q_A}{r^2}\right)\cos(\alpha)\right] + \left(\frac{1}{4\pi\epsilon_0} \frac{q_B}{r^2}\right)$$



$$|\vec{E}| = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

$$|\vec{E}| = ?$$

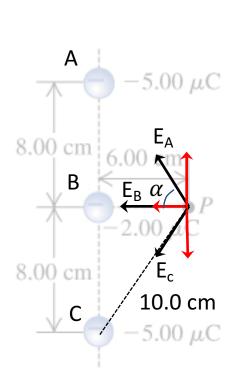
$$|\vec{E}| = E_{A,x} + E_{B,x} + E_{C,x}$$

$$|\vec{E}| = 2E_{A,x} + E_{B,x}$$

$$|\vec{E}| = 2|\vec{E}_A| \cos(\alpha) + |\vec{E}_B|$$

$$|\vec{E}| = 2 \left[\left(\frac{1}{4\pi\epsilon_0} \frac{q_A}{r^2} \right) \cos(\alpha) \right] + \left(\frac{1}{4\pi\epsilon_0} \frac{q_B}{r^2} \right)$$

$$|\vec{E}| = 2 \left[\left(\frac{1}{4\pi\epsilon_0} \frac{5 \times 10^{-6}}{(0.1)^2} \right) \left(\frac{0.06}{0.10} \right) \right] + \left(\frac{1}{4\pi\epsilon_0} \frac{2 \times 10^{-6}}{(0.06)^2} \right)$$



$$|\vec{E}| = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

$$|\vec{E}| = ?$$

$$|\vec{E}| = E_{A,x} + E_{B,x} + E_{C,x}$$

$$|\vec{E}| = 2E_{A,x} + E_{B,x}$$

$$|\vec{E}| = 2|\vec{E}_A|\cos(\alpha) + |\vec{E}_B|$$

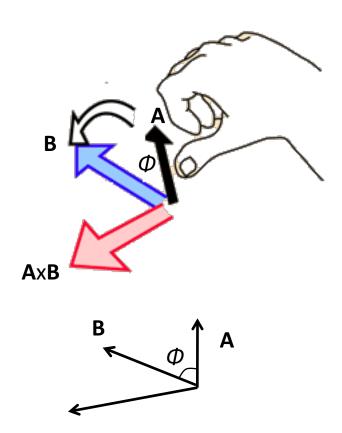
$$|\vec{E}| = 2\left[\left(\frac{1}{4\pi\epsilon_0} \frac{q_A}{r^2}\right)\cos(\alpha)\right] + \left(\frac{1}{4\pi\epsilon_0} \frac{q_B}{r^2}\right)$$

$$|\vec{E}| = 2\left[\left(\frac{1}{4\pi\epsilon_0} \frac{5\times10^{-6}}{(0.1)^2}\right)\left(\frac{0.06}{0.10}\right)\right] + \left(\frac{1}{4\pi\epsilon_0} \frac{2\times10^{-6}}{(0.06)^2}\right)$$

$$|\vec{E}| = 1.04\times10^7 \, N/C$$

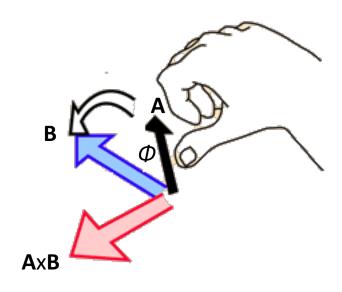
Electric Dipole: Force and Torque

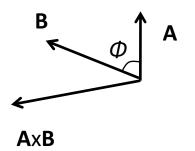
Reminder: vector ops



Ax**B**

Reminder: vector ops



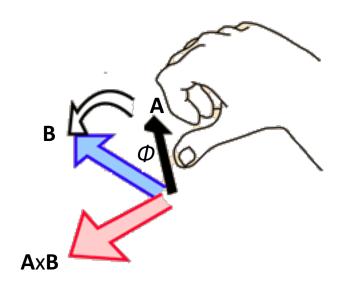


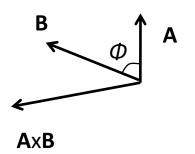
Cross product:

$$ec{A} imes ec{B} = egin{array}{cccc} \hat{x} & \hat{y} & \hat{z} \ A_x & A_y & A_z \ B_x & B_y & B_z \ \end{array}$$

$$|\vec{A} \times \vec{B}| = |\vec{A}| |\vec{B}| \sin(\phi)$$

Reminder: vector ops





Cross product:

$$ec{A} imes ec{B} = egin{bmatrix} \hat{x} & \hat{y} & \hat{z} \ A_x & A_y & A_z \ B_x & B_y & B_z \ \end{bmatrix}$$

$$|\vec{A} \times \vec{B}| = |\vec{A}| |\vec{B}| \sin(\phi)$$

Scalar (dot) product:

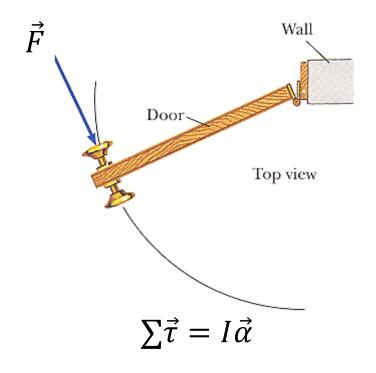
$$\vec{A} \cdot \vec{B} = |A| |B| \cos(\phi)$$



$$\sum \vec{F} = m\vec{a}$$

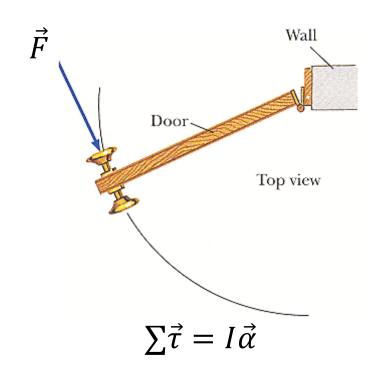


$$\sum \vec{F} = m\vec{a}$$





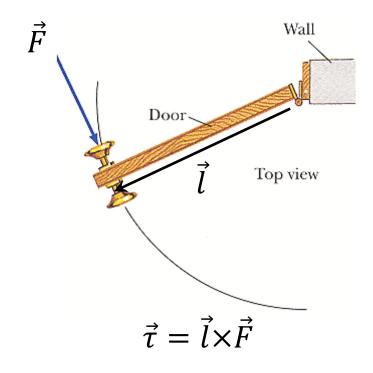
$$\sum \vec{F} = m\vec{a}$$



I: Moment of inertiaα: Angular acceleration



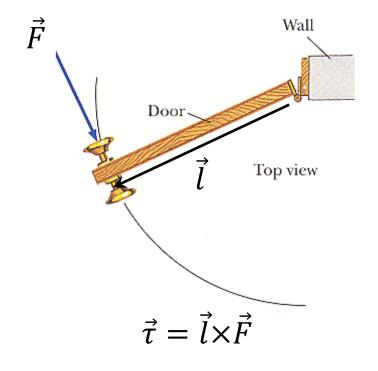
$$\sum \vec{F} = m\vec{a}$$



l: lever arm
Direction of torque?



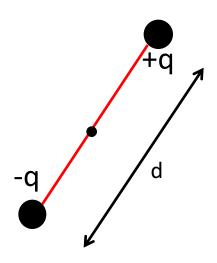
$$\sum \vec{F} = m\vec{a}$$

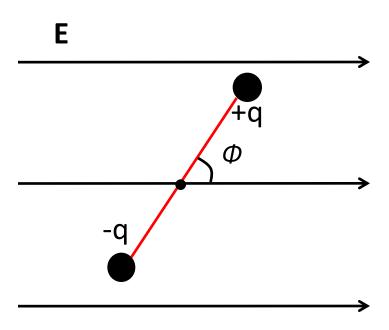


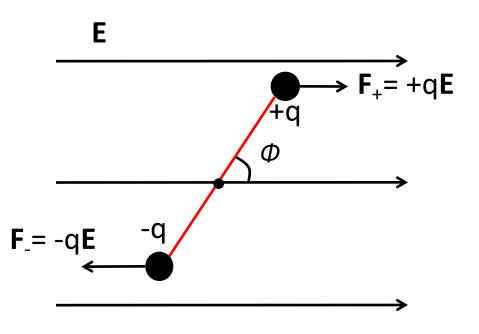
l: lever arm

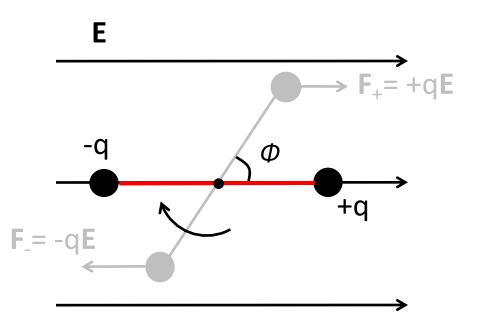
Direction of torque? Out of the page

Electric Dipole: Force and Torque

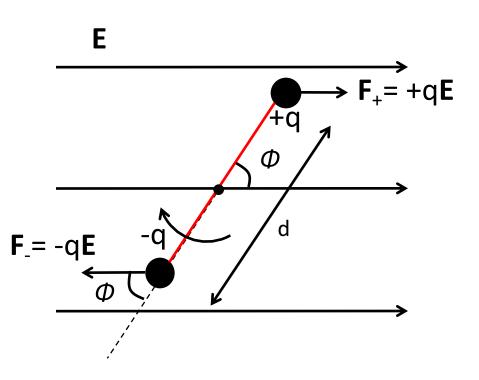




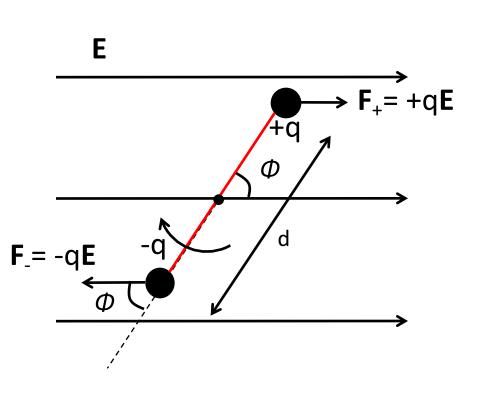




$$\sum \vec{\tau} = \sum_{i=1}^{N} \vec{l}_i \times \vec{F}_i$$
 (Torque)

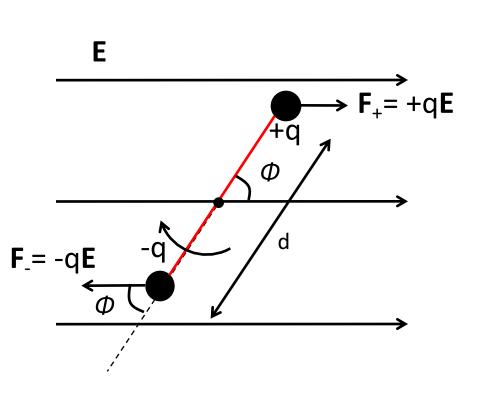


$$\sum_{i=1}^{N} \vec{l}_i \times \vec{F}_i \quad (Torque)$$



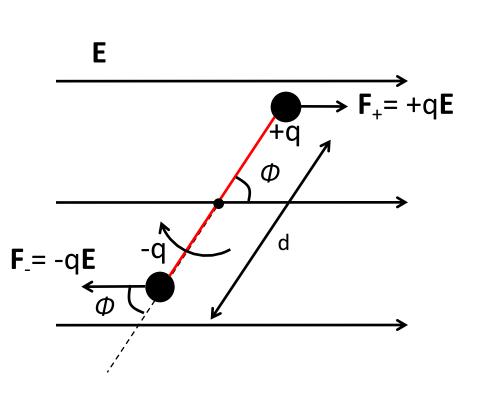
$$|\vec{\tau}| = \sum_{i=1}^{N} |l_i| |F_i| \sin(\phi)$$

$$\sum \vec{\tau} = \sum_{i=1}^{N} \vec{l}_i \times \vec{F}_i \quad (Torque)$$



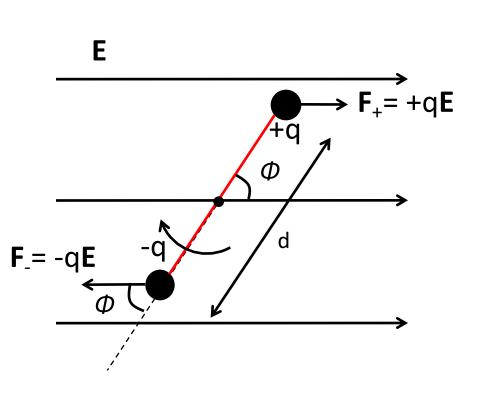
$$\begin{split} \mid \vec{\tau} \mid = \sum_{i=1}^{N} \mid l_{i} \mid \mid F_{i} \mid \sin(\phi) \\ \mid \vec{\tau} \mid = \left| \frac{d}{2} \right| \mid F_{+} \mid \sin(\phi) + \left| \frac{d}{2} \right| \mid F_{-} \mid \sin(\phi) \end{split}$$

$$\sum \vec{\tau} = \sum_{i=1}^{N} \vec{l}_i \times \vec{F}_i \quad (Torque)$$



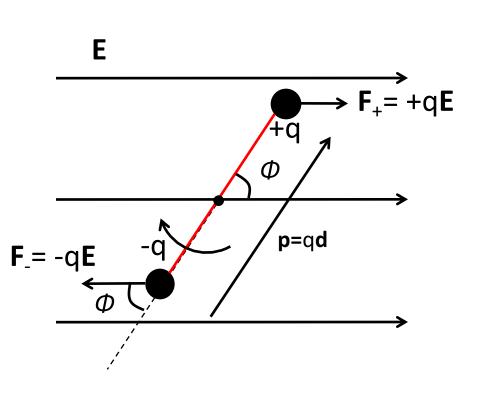
$$\begin{split} |\vec{\tau}| &= \sum_{i=1}^{N} |l_i| |F_i| \sin(\phi) \\ |\vec{\tau}| &= \left| \frac{d}{2} \right| |F_+| \sin(\phi) + \left| \frac{d}{2} \right| |F_-| \sin(\phi) \\ |\vec{\tau}| &= \left| \frac{d}{2} \right| |qE| \sin(\phi) + \left| \frac{d}{2} \right| |qE| \sin(\phi) \end{split}$$

$$\sum \vec{\tau} = \sum_{i=1}^{N} \vec{l}_i \times \vec{F}_i \quad (Torque)$$



$$\begin{split} |\vec{\tau}| &= \sum_{i=1}^{N} |l_i| |F_i| \sin(\phi) \\ |\vec{\tau}| &= \left| \frac{d}{2} \right| |F_+| \sin(\phi) + \left| \frac{d}{2} \right| |F_-| \sin(\phi) \\ |\vec{\tau}| &= \left| \frac{d}{2} \right| |qE| \sin(\phi) + \left| \frac{d}{2} \right| |qE| \sin(\phi) \\ |\vec{\tau}| &= |d| |q| |E| \sin(\phi) \end{split}$$

$$\sum \vec{\tau} = \sum_{i=1}^{N} \vec{l}_i \times \vec{F}_i \quad (Torque)$$



$$\begin{aligned} |\vec{\tau}| &= \sum_{i=1}^{N} |l_i| |F_i| \sin(\phi) \\ |\vec{\tau}| &= \left| \frac{d}{2} \right| |F_+| \sin(\phi) + \left| \frac{d}{2} \right| |F_-| \sin(\phi) \\ |\vec{\tau}| &= \left| \frac{d}{2} \right| |qE| \sin(\phi) + \left| \frac{d}{2} \right| |qE| \sin(\phi) \\ |\vec{\tau}| &= |d| |q| |E| \sin(\phi) \end{aligned}$$

Defining: $\vec{p} = q\vec{d}$ (dipole moment)

$$\sum \vec{\tau} = \sum_{i=1}^{N} \vec{l}_i \times \vec{F}_i \quad (Torque)$$

$$F_{-} = -qE$$

$$p = qd$$

$$p = qd$$

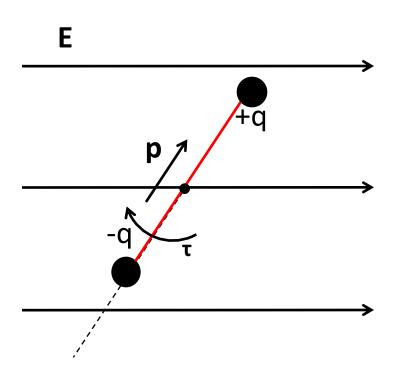
$$\begin{split} |\vec{\tau}| &= \sum_{i=1}^{N} |l_{i}| |F_{i}| \sin(\phi) \\ |\vec{\tau}| &= \left| \frac{d}{2} \right| |F_{+}| \sin(\phi) + \left| \frac{d}{2} \right| |F_{-}| \sin(\phi) \\ |\vec{\tau}| &= \left| \frac{d}{2} \right| |qE| \sin(\phi) + \left| \frac{d}{2} \right| |qE| \sin(\phi) \\ |\vec{\tau}| &= |d| |q| |E| \sin(\phi) \end{split}$$

Defining:
$$\vec{p} = q\vec{d}$$
 (dipole moment)

$$|\vec{\tau}| = |qd| |E| \sin(\phi)$$

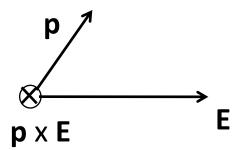
Torque on electric dipole

$$\vec{ au} = \vec{p} \times \vec{E}$$

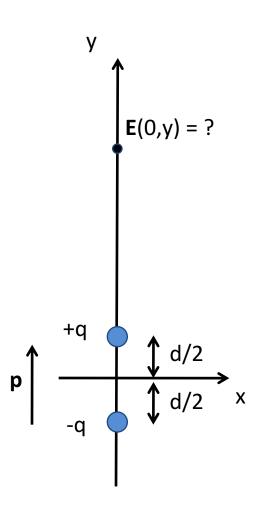


$$\vec{p} = q\vec{d}$$

$$\vec{\tau} = \vec{p} \times \vec{E}$$



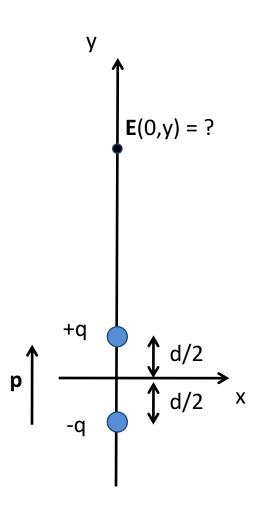
Electric Field: Torque



Earlier, we found:
$$\vec{E}(y) = \frac{qd}{2\pi\varepsilon_0 y^3} \hat{y}$$

And just now:
$$\vec{p} = q\vec{d}$$

Electric Field: Torque



Earlier, we found:
$$\vec{E}(y) = \frac{qd}{2\pi\varepsilon_0 y^3} \hat{y}$$

And just now:
$$\vec{p} = q\vec{d}$$

We can then write:

$$\vec{E}(y) = \frac{\vec{p}}{2\pi\varepsilon_0 y^3}$$