

PHYS2326

Lecture #23

Prof. Fabiano Rodrigues

Department of Physics
The University of Texas at Dallas

Reminders

- Exam #3 on Thursday
- Bring:
 - ID
 - Pen, pencil and scientific calculator
 - Formulas available on eLearning
- Arrive early

Goals for today's lecture

- Introduce Ampere's Law
- Applications of Ampere's Law

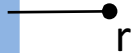
Chapter 28

Reminder: Electric Fields

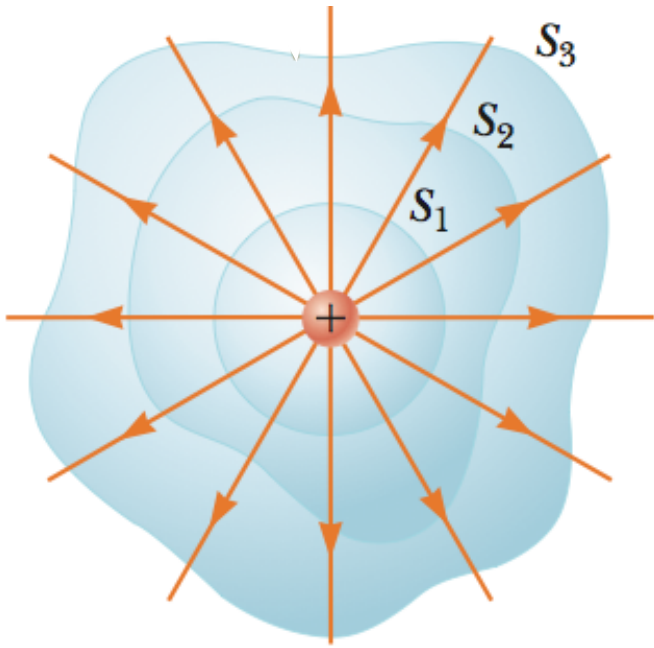
λ Reminder: Electric Fields

Electric field at point r ?

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{r^2} \hat{r}$$



Reminder: Gauss's Law



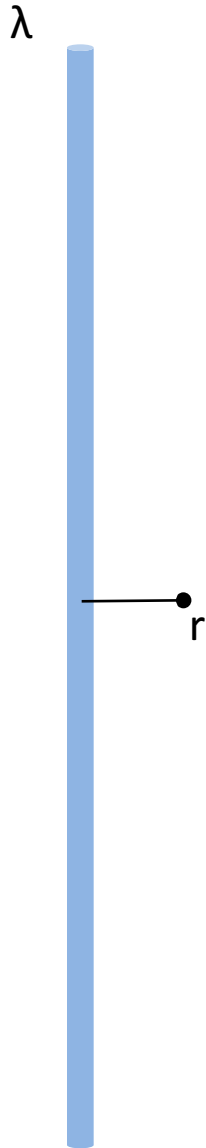
$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{enclosed}}{\epsilon_0}$$

Applications of Gauss's Law

- Gauss's Law is particularly useful (analytically treatable) when the **direction** of the electric field is known from the symmetry of the charge distribution.
- Our task is to choose a Gaussian surface that simplifies the equation for Gauss's Law, so that electric field can be determined from:

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{enclosed}}{\epsilon_0}$$

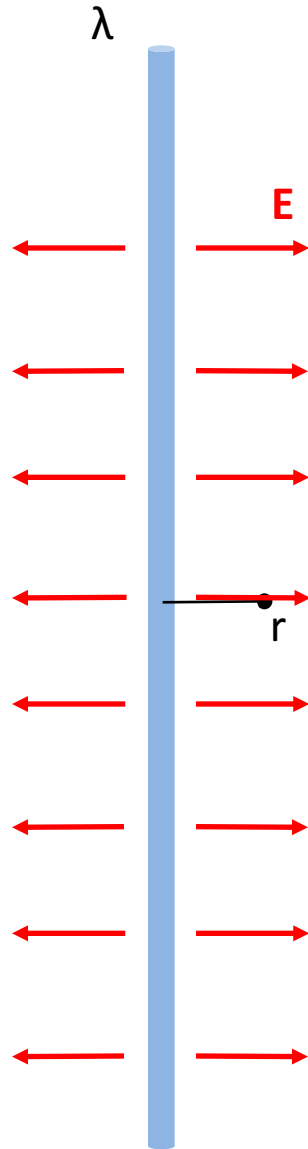
Example: Using Gauss's Law, find the magnitude of the electric field at a distance "r" from an infinite length line of positive charge with constant linear charge density " λ ".



$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{enclosed}}{\epsilon_0}$$

$$E(r) = ?$$

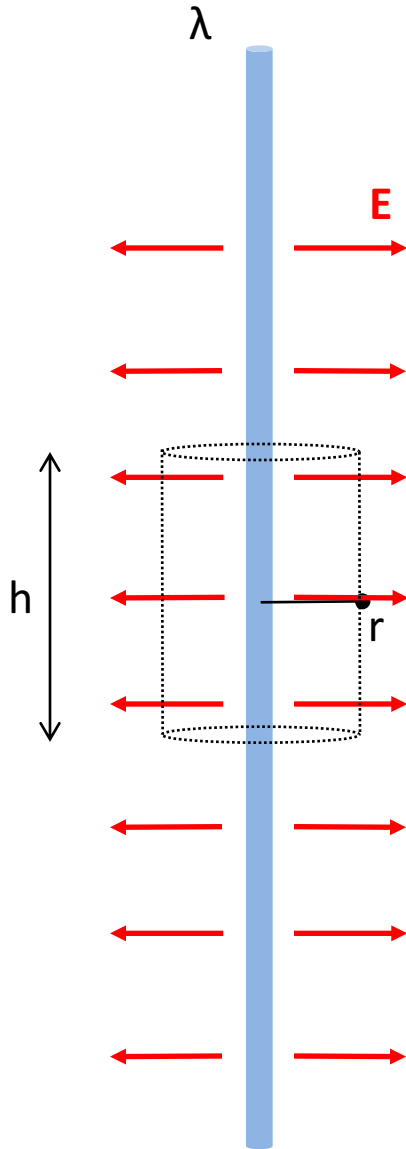
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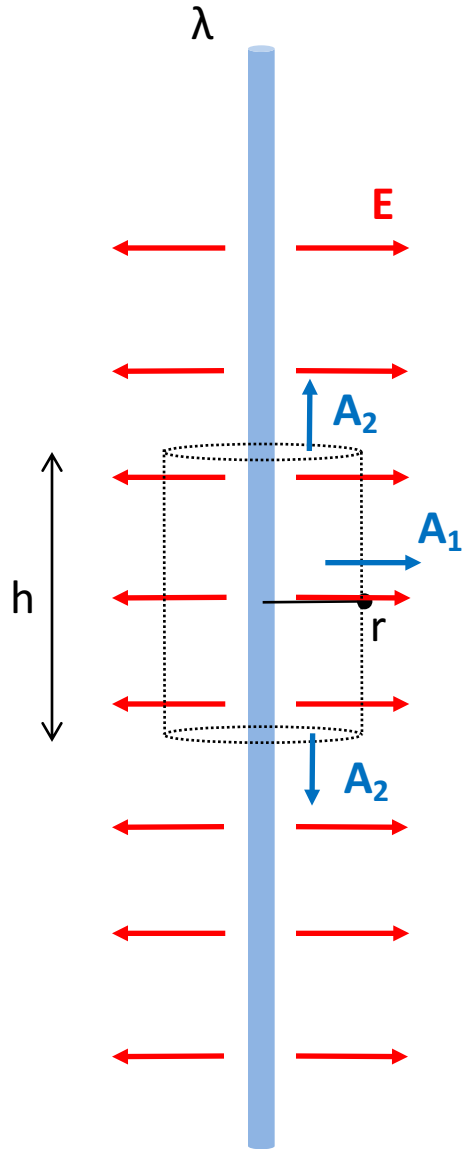
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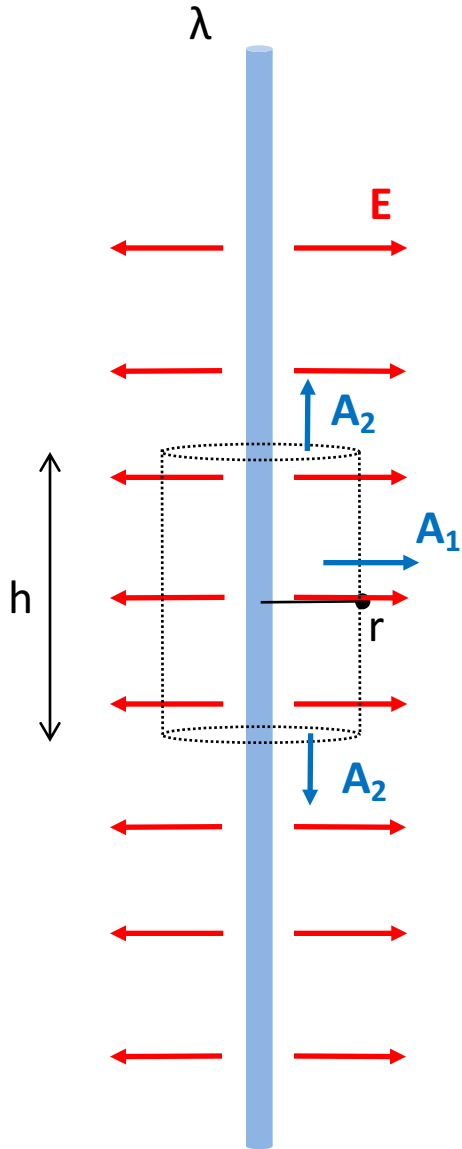
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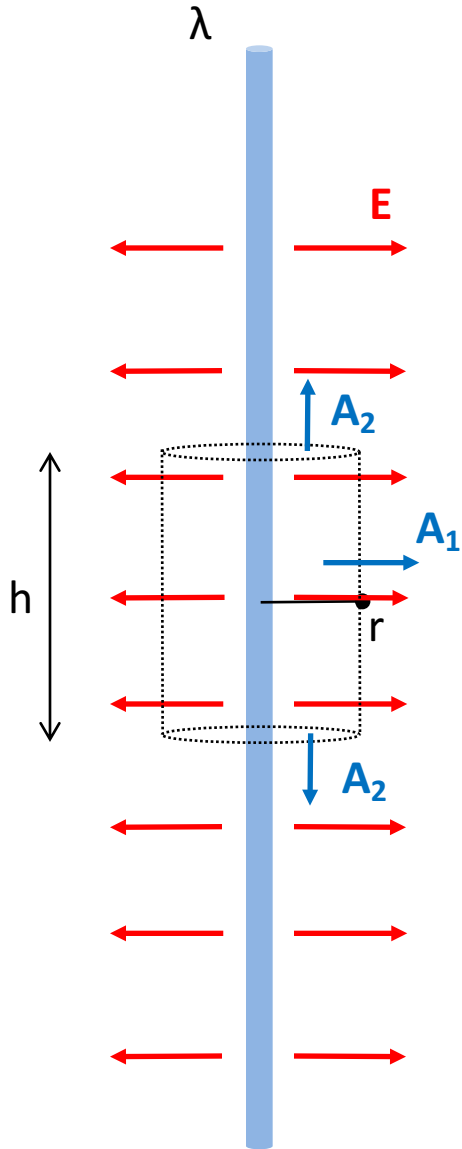


$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{enclosed}}{\epsilon_0}$$

$$E(r) = ?$$

$$E(r)A_1 = \frac{\lambda h}{\epsilon_0}$$

Example: Using Gauss's Law, find the magnitude of the electric field at a distance "r" from an infinite length line of positive charge with constant linear charge density " λ ".



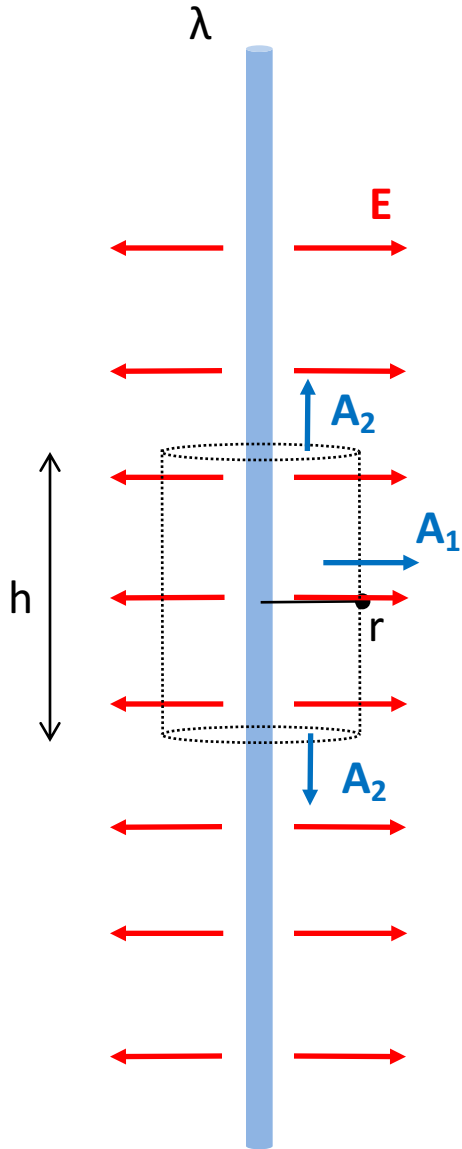
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$$E(r) = ?$$

$$E(r)A_1 = \frac{\lambda h}{\epsilon_0}$$

$$E(r)(2\pi r)h = \frac{\lambda h}{\epsilon_0}$$

Example: Using Gauss's Law, find the magnitude of the electric field at a distance “r” from a infinite length line of positive charge with constant linear charge density “λ”.



$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{enclosed}}{\epsilon_0}$$

$$E(r) = ?$$

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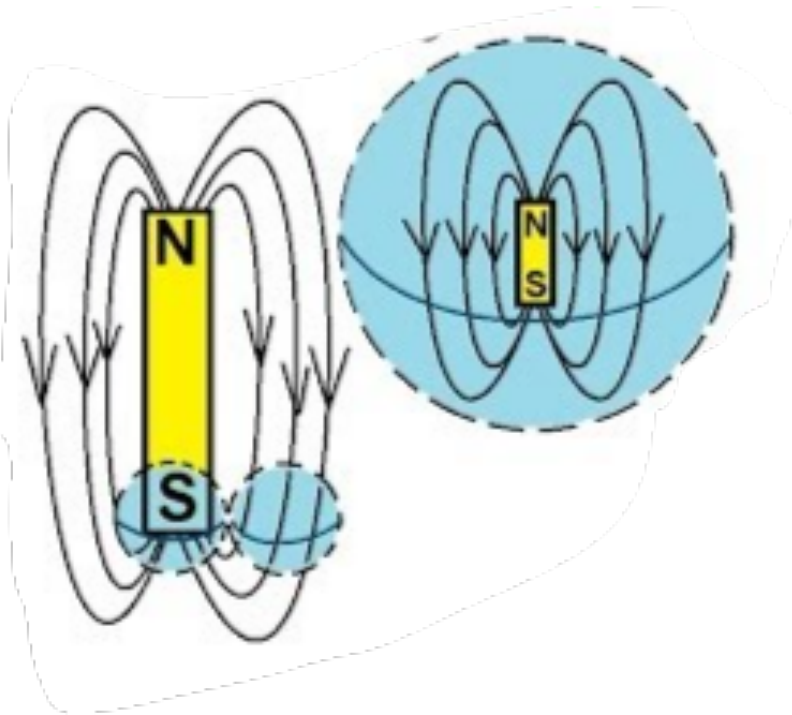
$$E(r) = \frac{\lambda}{2\pi r \epsilon_0}$$

Field of infinite line of charge

Gauss's Law (for Magnetism)

$$\oint \vec{B} \cdot d\vec{A} = 0$$

Gauss's Law (for Magnetism)



$$\oint \vec{B} \cdot d\vec{A} = 0$$

Maxwell's Equations



Gauss's Law

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q}{\epsilon}$$

Gauss's Law for Magnetism

$$\oint \vec{B} \cdot d\vec{A} = 0$$

Ampere's Law

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl} + \mu_0 \epsilon_0 \frac{\partial \Phi_E}{\partial t}$$

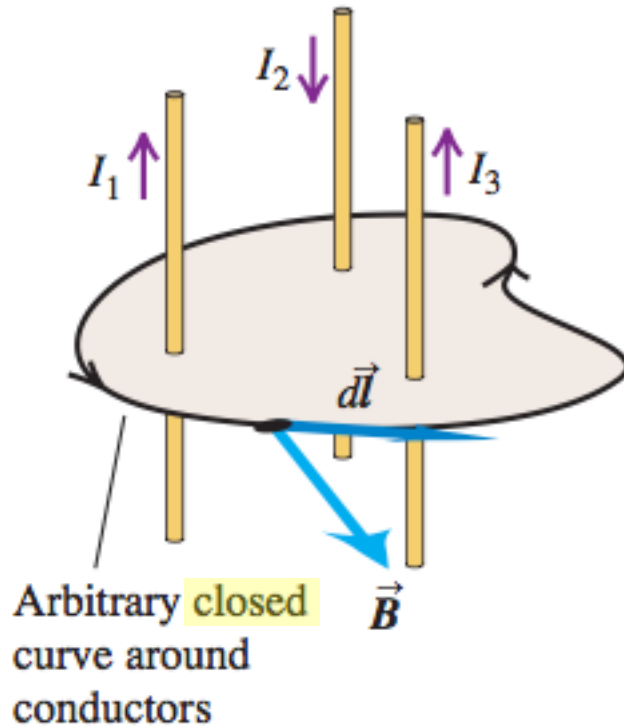
Faraday's Law

$$\oint \vec{E} \cdot d\vec{l} = -\frac{\partial \Phi_B}{\partial t}$$

Ampere's Law

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enclosed}}$$

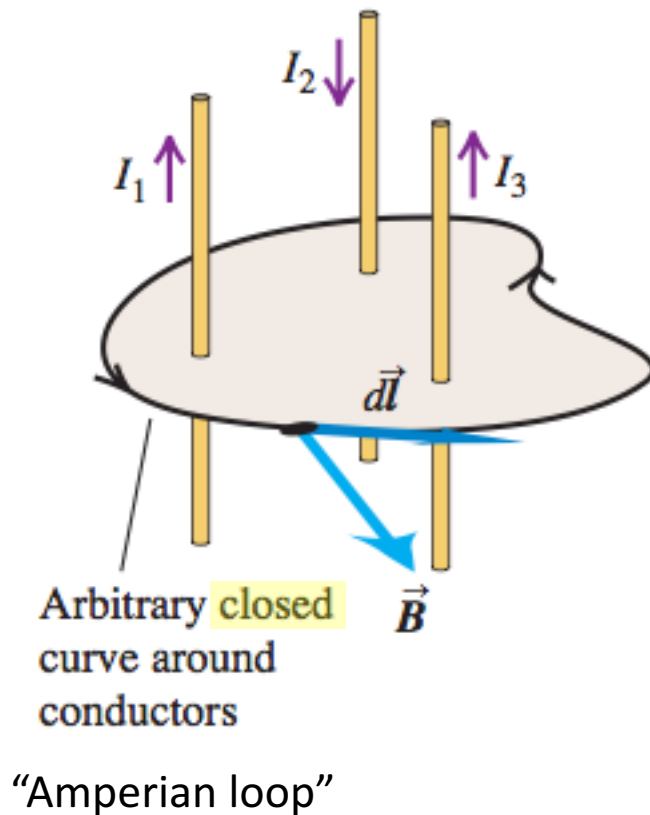
Ampere's Law



“Amperian loop”

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enclosed}}$$

Ampere's Law



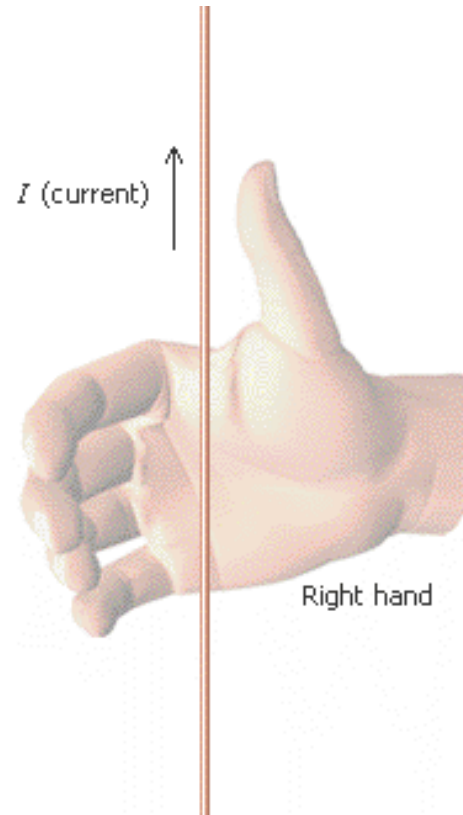
$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enclosed}}$$

Example:

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 (+I_1 - I_2 + I_3)$$

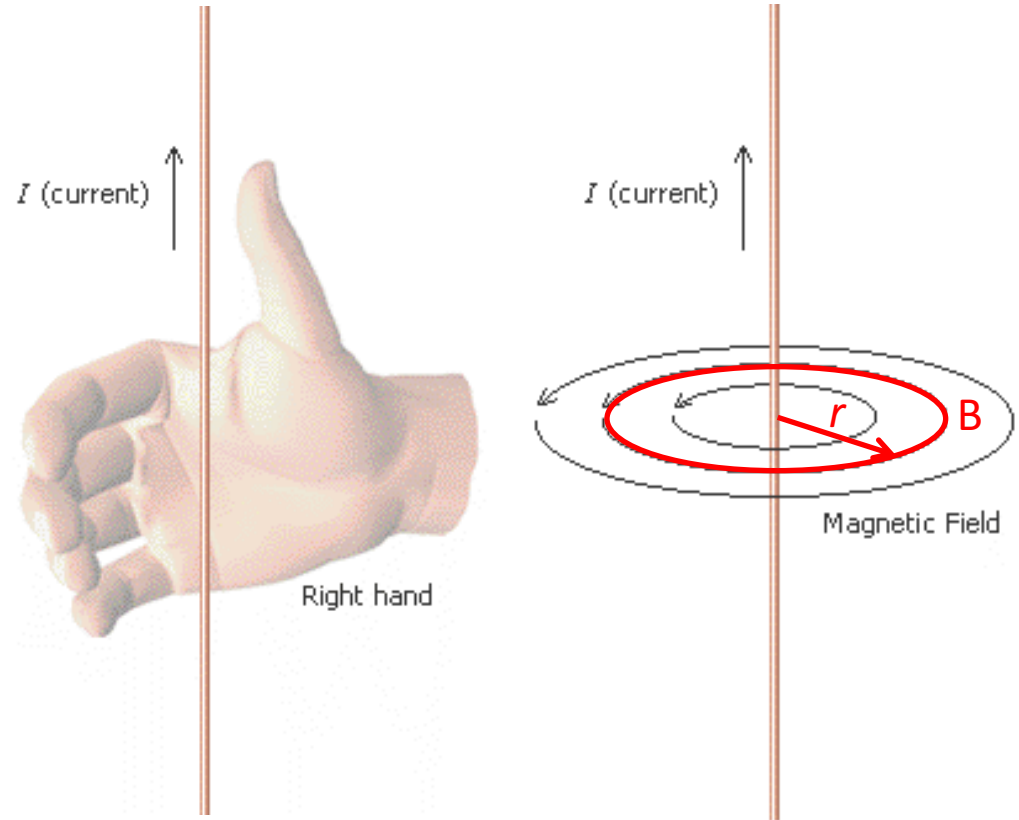
Application of Ampere's Law #1: Long Conductor

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$



Application of Ampere's Law #1: Long Conductor

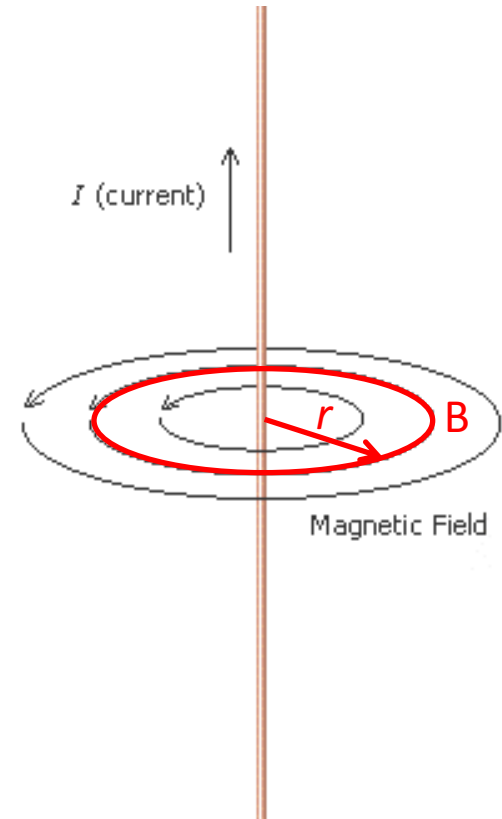
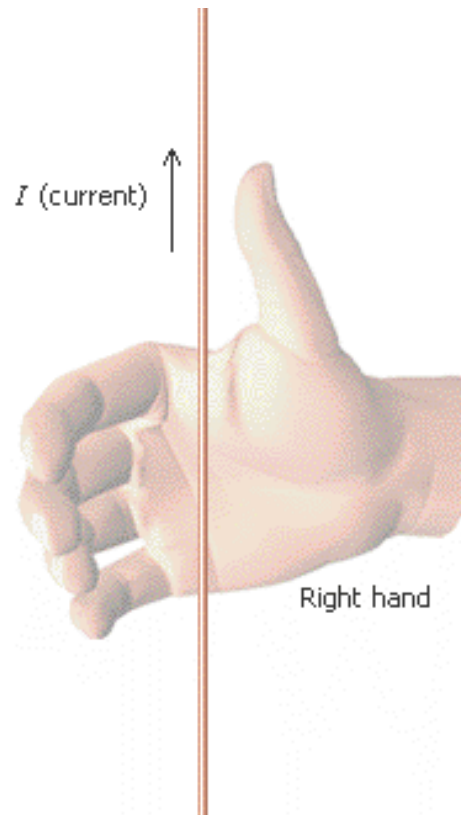
$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$



Application of Ampere's Law #1: Long Conductor

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

$$B \int_0^{2\pi} r d\theta = \mu_0(+I)$$

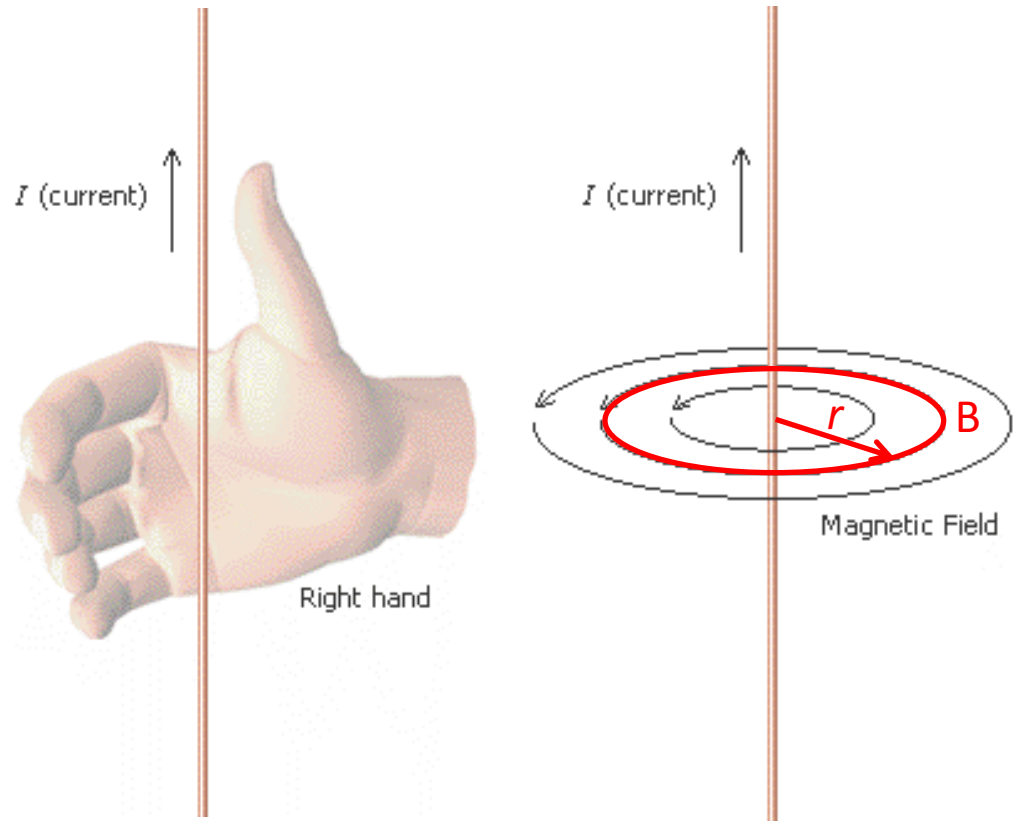


Application of Ampere's Law #1: Long Conductor

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

$$B \int_0^{2\pi} r d\theta = \mu_0(+I)$$

$$B2\pi r = \mu_0 I$$



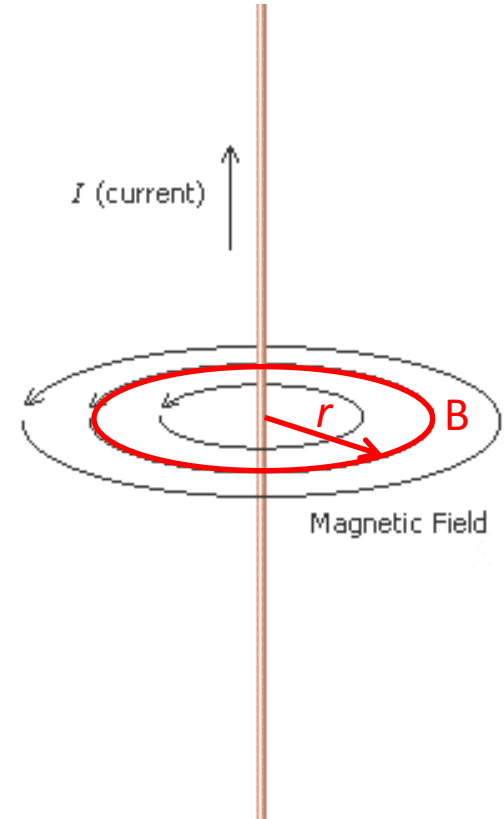
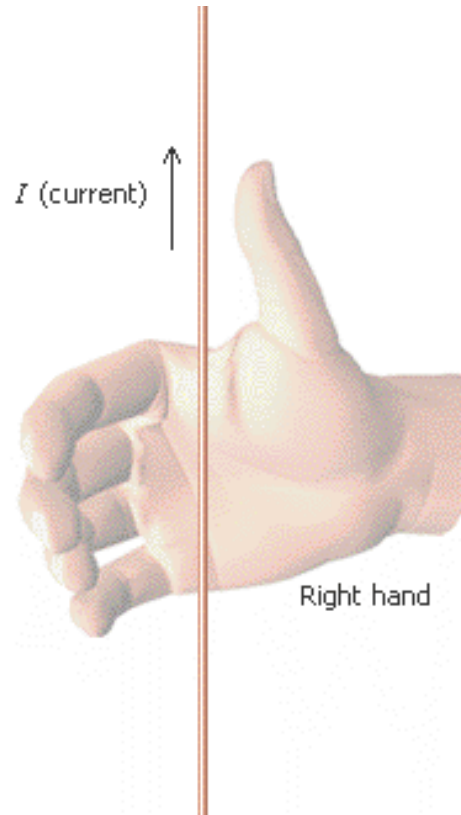
Application of Ampere's Law #1: Long Conductor

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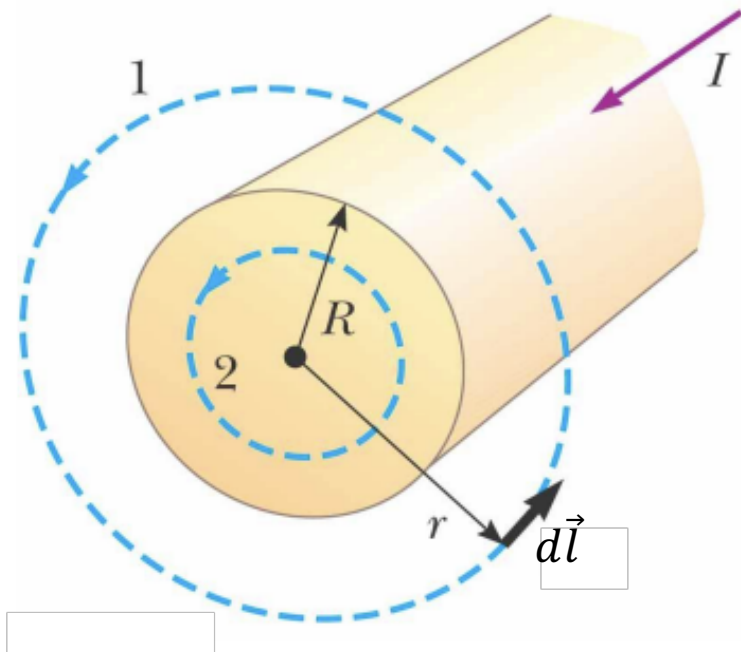
$$B2\pi r = \mu_0 I$$

$$B = \frac{\mu_0 I}{2\pi r}$$



Application of Ampere's Law #2: Cylindrical Conductor

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$



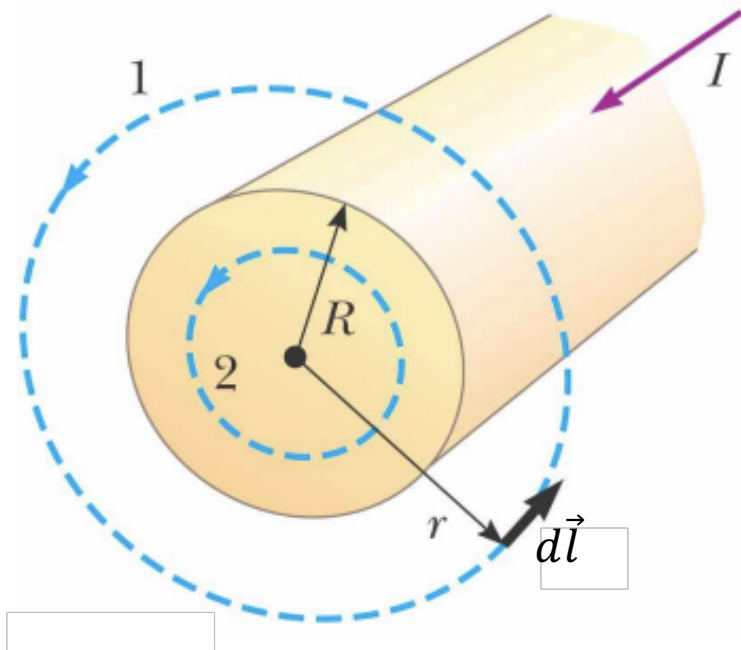
Application of Ampere's Law #2: Cylindrical Conductor

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

Two regions:

Region 1: $r > R$

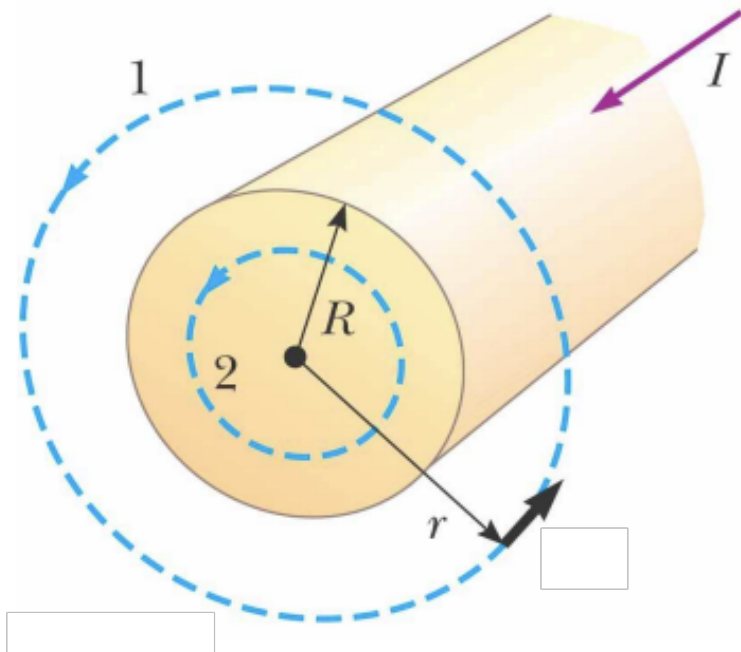
Region 2: $r < R$



Application of Ampere's Law #2: Cylindrical Conductor

Region 1: $r > R$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

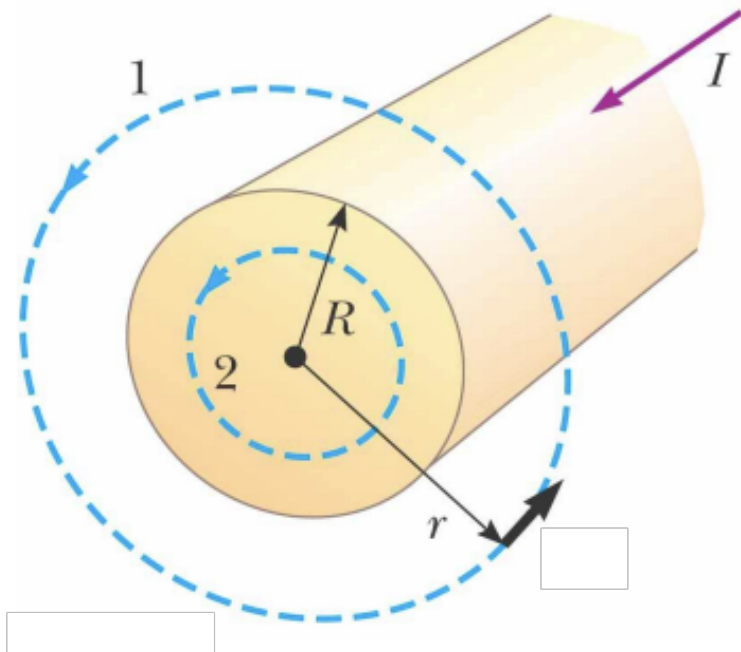


Application of Ampere's Law #2: Cylindrical Conductor

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$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

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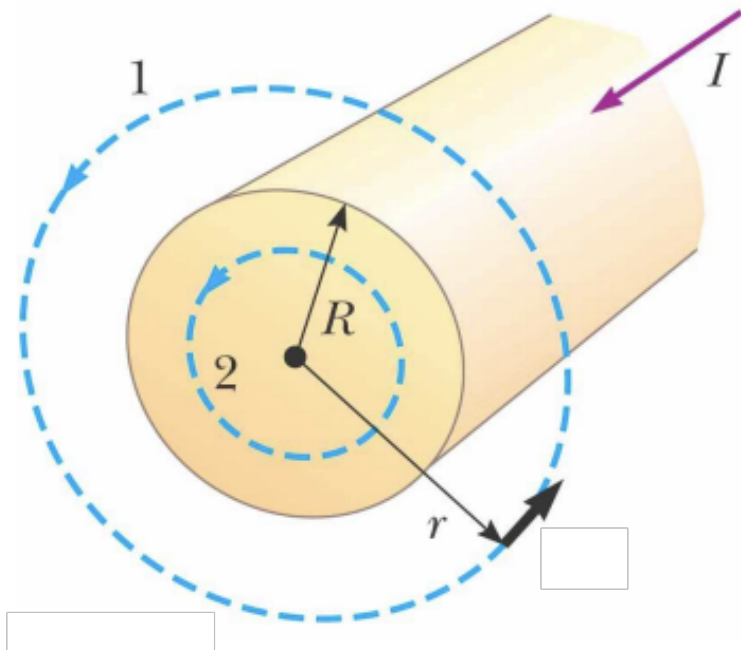
Application of Ampere's Law #2: Cylindrical Conductor

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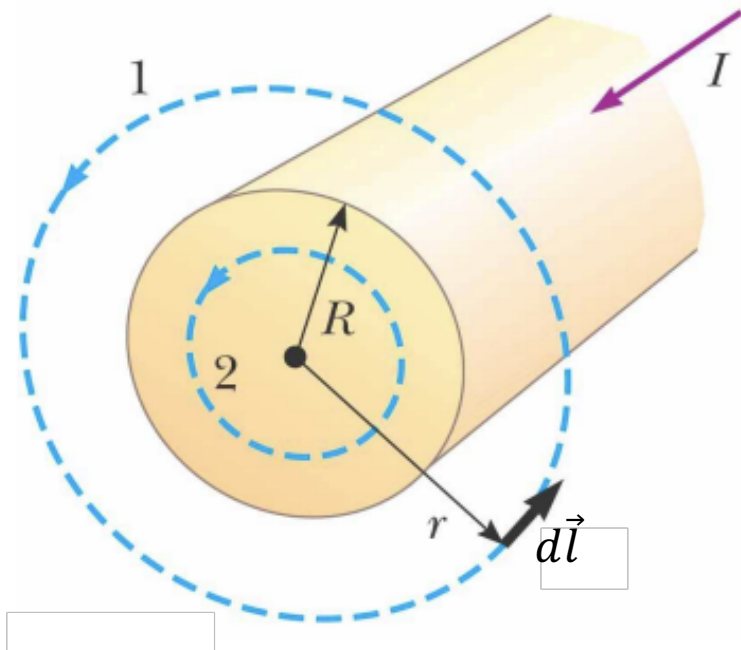
$$B = \frac{\mu_0 I}{2\pi r}$$



Application of Ampere's Law #2: Cylindrical Conductor

Region 2: $r < R$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

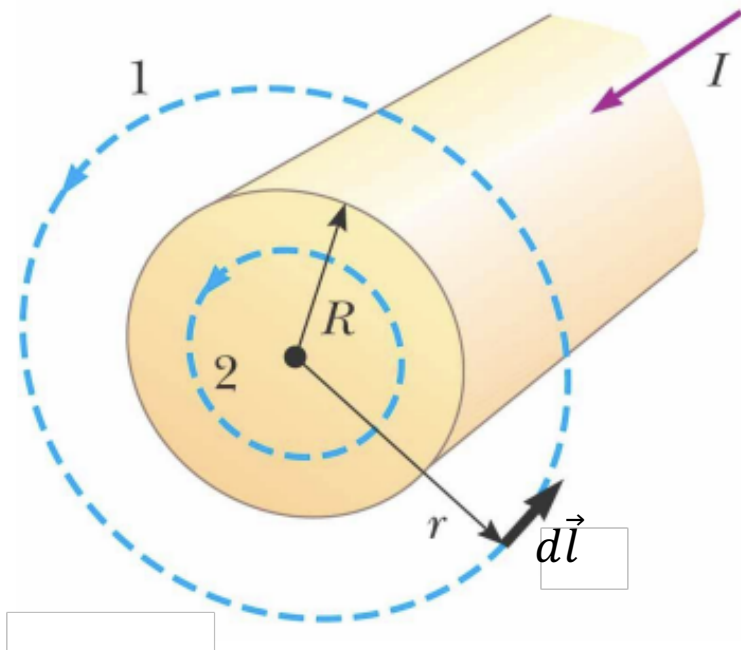


Application of Ampere's Law #2: Cylindrical Conductor

Region 2: $r < R$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

$$B2\pi r = \mu_0(JA)$$



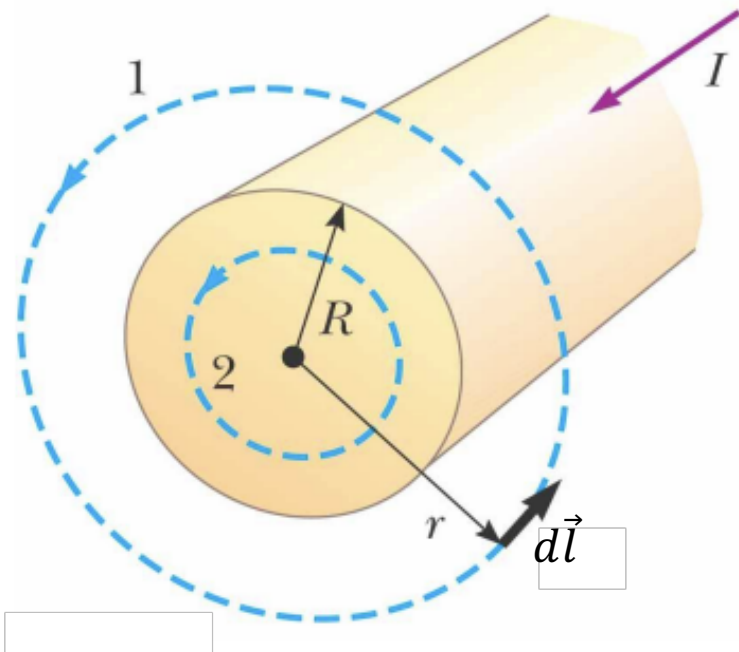
Application of Ampere's Law #2: Cylindrical Conductor

Region 2: $r < R$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

$$B2\pi r = \mu_0(JA)$$

$$B2\pi r = \mu_0 \left(\frac{I}{\pi R^2} \right) A$$



Application of Ampere's Law #2: Cylindrical Conductor

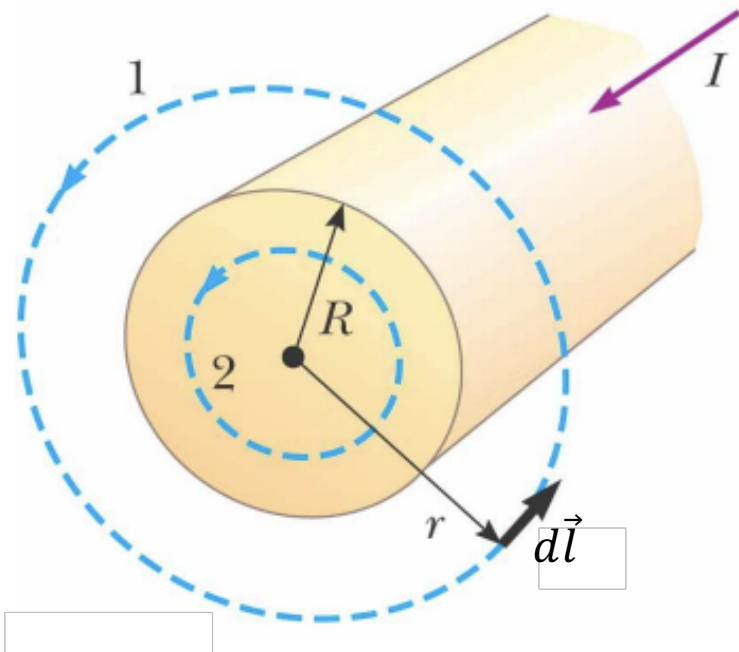
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$$B2\pi r = \mu_0 \left(\frac{I}{\pi R^2} \right) \pi r^2$$



Application of Ampere's Law #2: Cylindrical Conductor

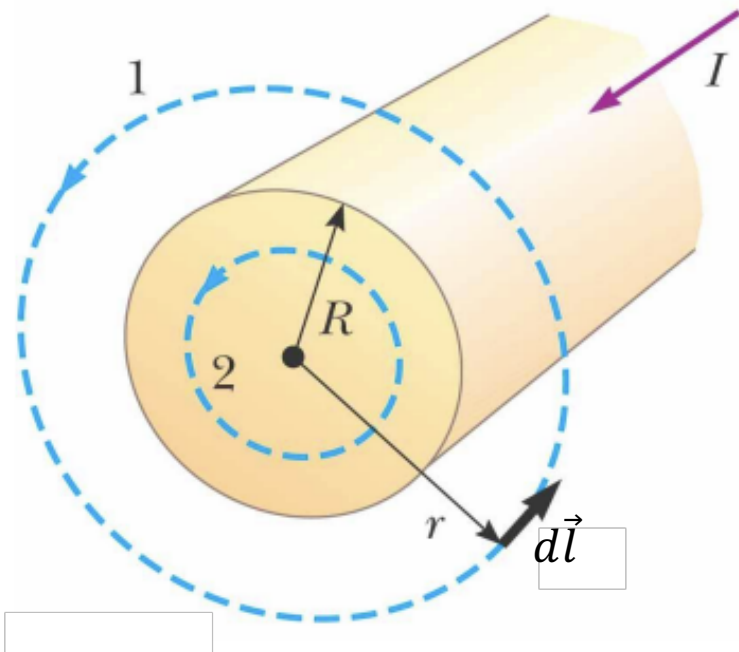
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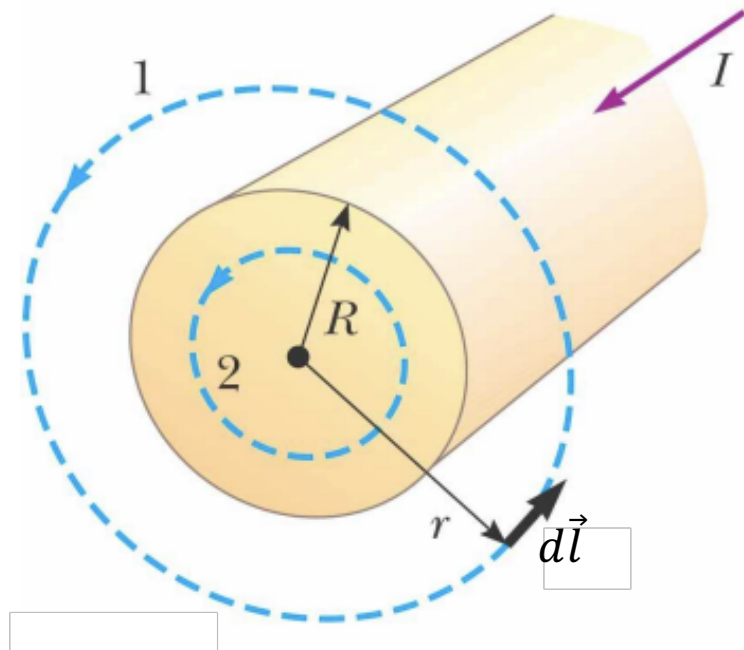
$$B2\pi r = \mu_0(JA)$$

$$B2\pi r = \mu_0 \left(\frac{I}{\pi R^2} \right) A$$

$$B2\pi r = \mu_0 \left(\frac{I}{\pi R^2} \right) \pi r^2 = \mu_0 I \left(\frac{r^2}{R^2} \right)$$



Application of Ampere's Law #2: Cylindrical Conductor



Region 2: $r < R$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

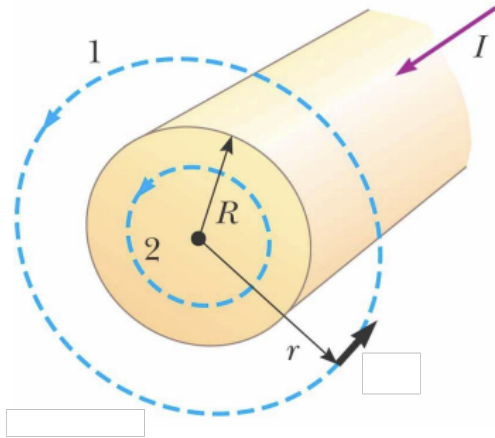
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$$B = \frac{\mu_0 I r}{2\pi R^2}$$

Application of Ampere's Law #2: Cylindrical Conductor



$$r < R:$$

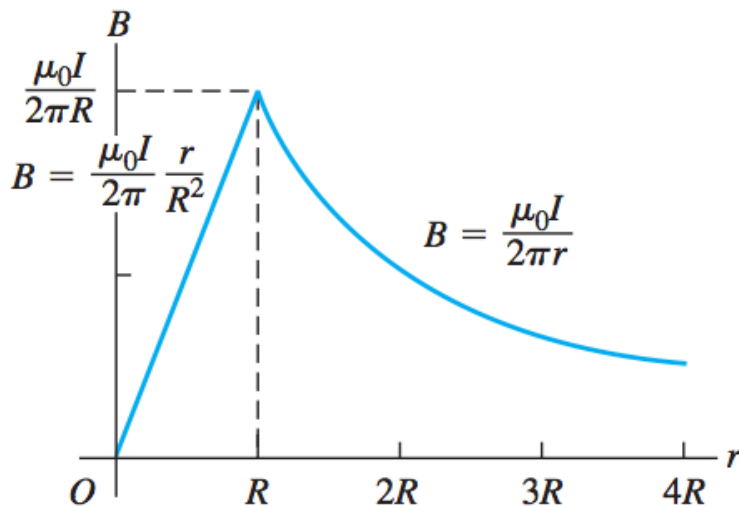
$$B = \frac{\mu_0 I}{2\pi r}$$

$$r < R:$$

$$B = \frac{\mu_0 I r}{2\pi R^2}$$

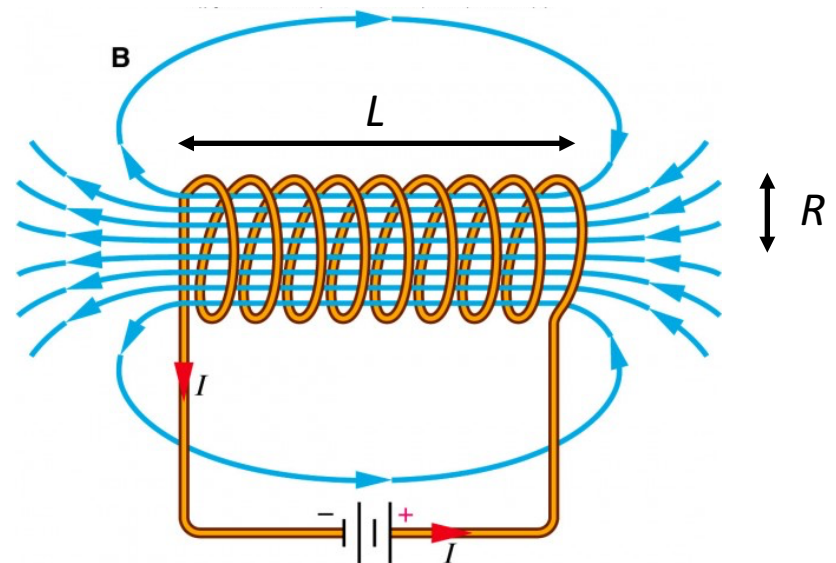
$$r = R:$$

$$B = \frac{\mu_0 I}{2\pi R}$$



Application of Ampere's Law #3: Ideal Solenoid

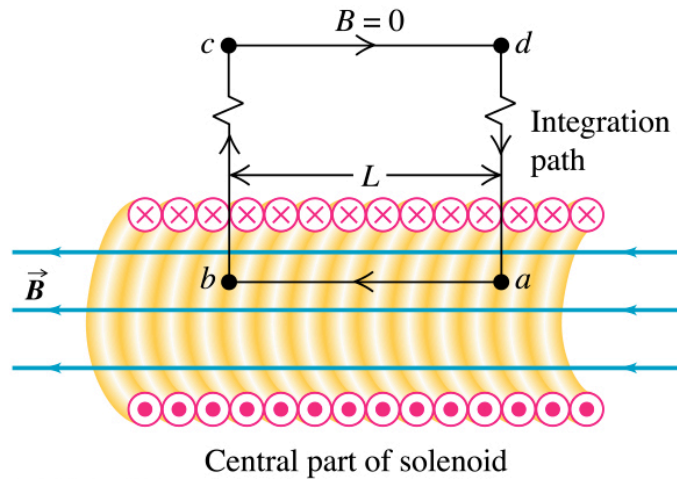
- A **solenoid** is a coil wound into a close-packed helix.
- **Ideal**: Solenoid has a large number of turns per unit length, and its length L is much greater than its radius R so that magnetic field inside can be considered uniform, and the magnetic field outside negligible.



Application of Ampere's Law #3: Ideal Solenoid

*Solenoid with
"n" turns per unit length*

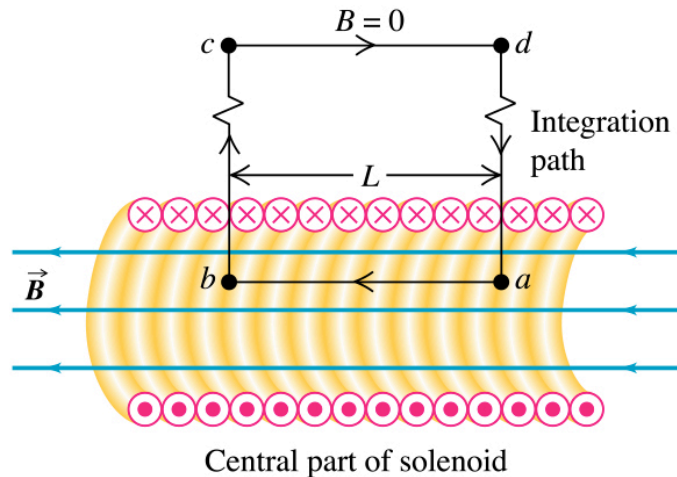
$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$



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Application of Ampere's Law #3: Ideal Solenoid

*Solenoid with
"n" turns per unit length*



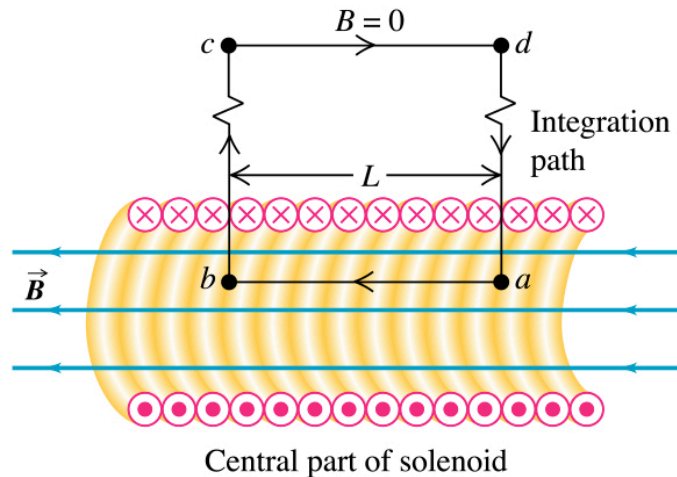
$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

$$\int_a^b \vec{B} \cdot d\vec{l} + \int_b^c \vec{B} \cdot d\vec{l} + \int_c^d \vec{B} \cdot d\vec{l} + \int_d^a \vec{B} \cdot d\vec{l} = \mu_0 NI$$

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Application of Ampere's Law #3: Ideal Solenoid

*Solenoid with
"n" turns per unit length*



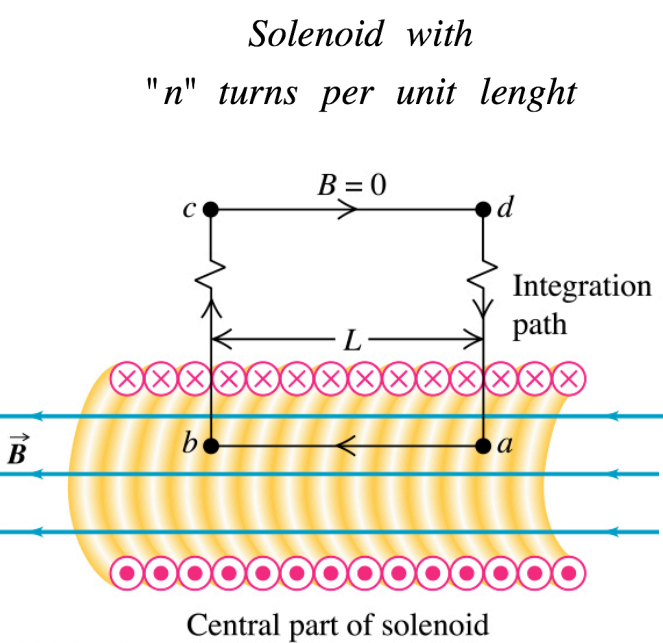
$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

$0: \vec{B} \perp d\vec{l}$ $0: \vec{B} = 0$ $0: \vec{B} \perp d\vec{l}$

$$\int_a^b \vec{B} \cdot d\vec{l} + \int_b^c \vec{B} \cdot d\vec{l} + \int_c^d \vec{B} \cdot d\vec{l} + \int_d^a \vec{B} \cdot d\vec{l} = \mu_0 NI$$

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Application of Ampere's Law #3: Ideal Solenoid



$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

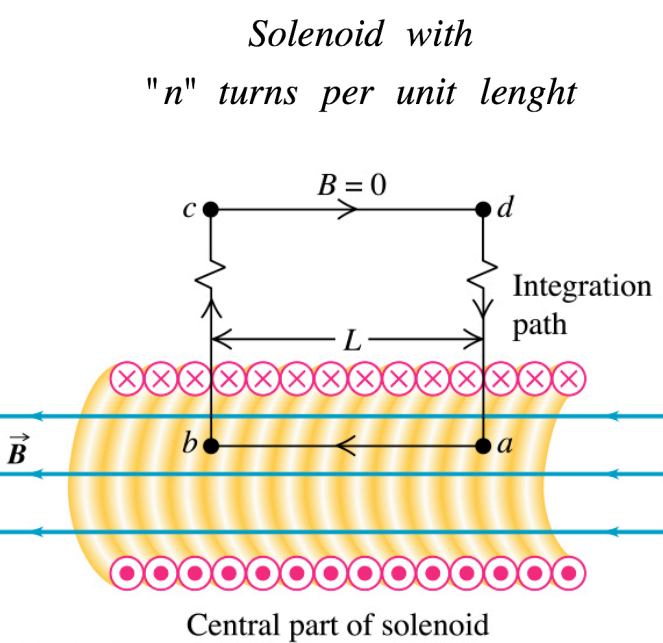
Annotations for the integration path segments:

- For segment cd : $0: \vec{B} \perp d\vec{l}$
- For segment bc : $0: \vec{B} = 0$
- For segment da : $0: \vec{B} \perp d\vec{l}$

$$\int_a^b \vec{B} \cdot d\vec{l} + \int_b^c \vec{B} \cdot d\vec{l} + \int_c^d \vec{B} \cdot d\vec{l} + \int_d^a \vec{B} \cdot d\vec{l} = \mu_0 NI$$
$$\int_a^b \vec{B} \cdot d\vec{l} = \mu_0 NI$$

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Application of Ampere's Law #3: Ideal Solenoid



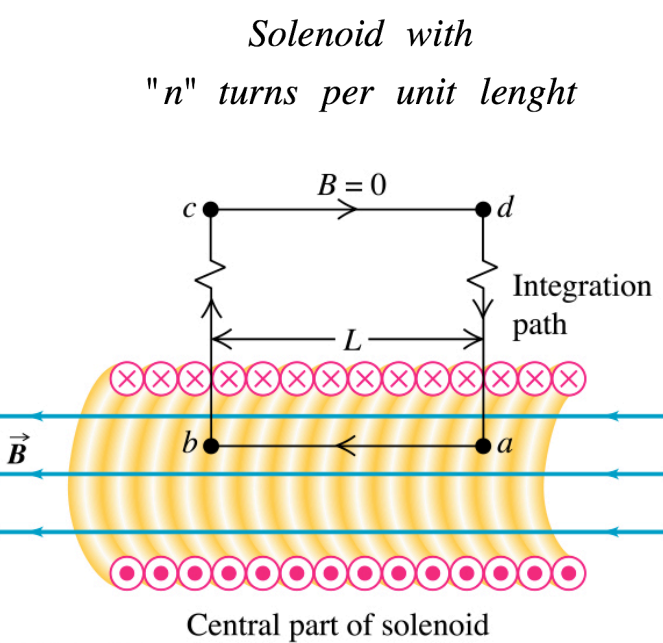
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$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

0: $\vec{B} \perp d\vec{l}$ 0: $\vec{B} = 0$ 0: $\vec{B} \perp d\vec{l}$

$$\int_a^b \vec{B} \cdot d\vec{l} + \int_b^c \vec{B} \cdot d\vec{l} + \int_c^d \vec{B} \cdot d\vec{l} + \int_d^a \vec{B} \cdot d\vec{l} = \mu_0 NI$$
$$\int_a^b \vec{B} \cdot d\vec{l} = \mu_0 NI$$
$$BL = \mu_0 NI$$

Application of Ampere's Law #3: Ideal Solenoid



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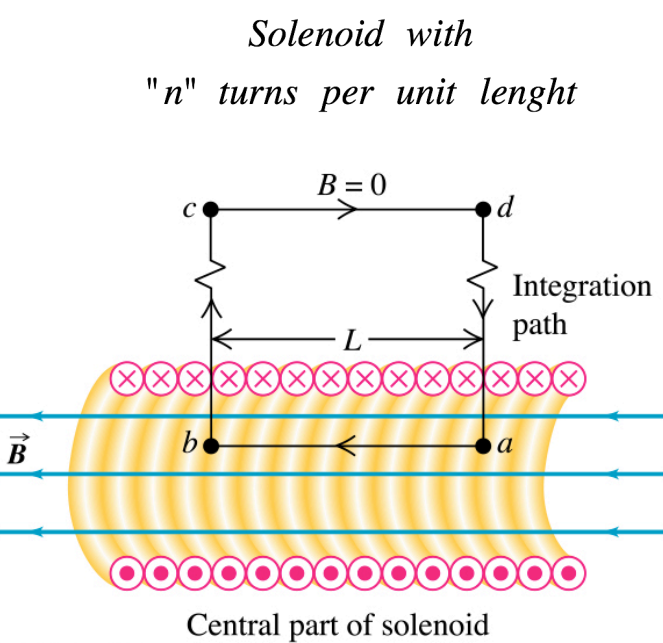
$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

Annotations for the integration path segments:

- Top segment cd : $0: \vec{B} \perp d\vec{l}$
- Right segment da : $0: \vec{B} = 0$
- Left segment bc : $0: \vec{B} \perp d\vec{l}$

$$\int_a^b \vec{B} \cdot d\vec{l} + \int_b^c \vec{B} \cdot d\vec{l} + \int_c^d \vec{B} \cdot d\vec{l} + \int_d^a \vec{B} \cdot d\vec{l} = \mu_0 NI$$
$$\int_a^b \vec{B} \cdot d\vec{l} = \mu_0 NI$$
$$BL = \mu_0 NI$$
$$B = \frac{\mu_0 NI}{L}$$

Application of Ampere's Law #3: Ideal Solenoid



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$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

Annotations for the integration path segments:

- Top segment cd : $0: \vec{B} \perp d\vec{l}$
- Right segment da : $0: \vec{B} = 0$
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$$\int_a^b \vec{B} \cdot d\vec{l} + \int_b^c \vec{B} \cdot d\vec{l} + \int_c^d \vec{B} \cdot d\vec{l} + \int_d^a \vec{B} \cdot d\vec{l} = \mu_0 NI$$

$$\int_a^b \vec{B} \cdot d\vec{l} = \mu_0 NI$$

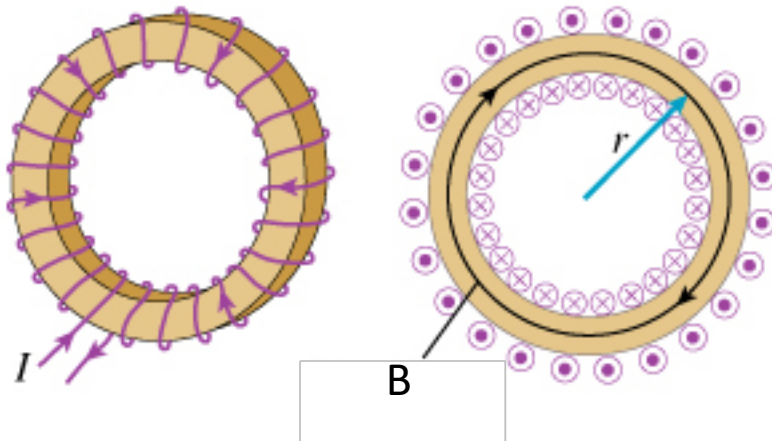
$$BL = \mu_0 NI$$

$$B = \frac{\mu_0 NI}{L}$$

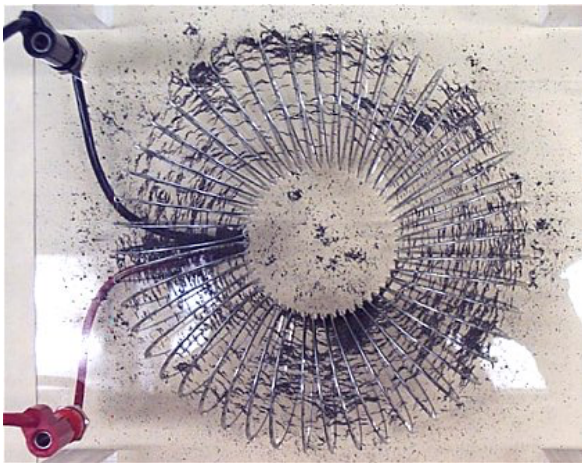
$$B = \mu_0 nI$$

Where $n = \frac{N}{L}$ (turns per unit length)

Application of Ampere's Law #4: Toroid

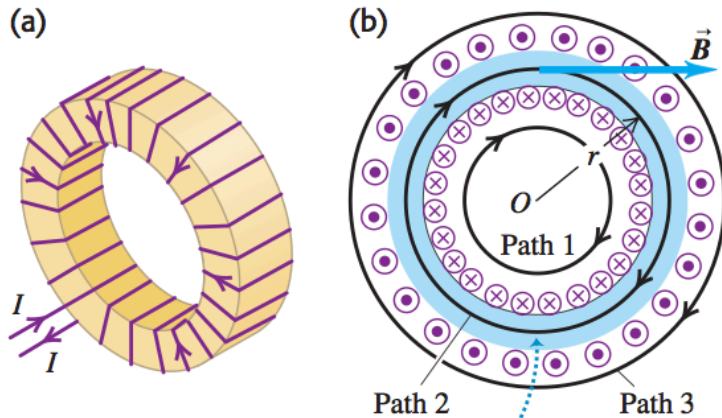


Toroid with N turns



- A **toroid** is a ring-shaped type of solenoid.
- Like the regular toroid the magnetic field is confined, almost entirely, to the space enclosed by the windings.

Application of Ampere's Law #4: Toroid

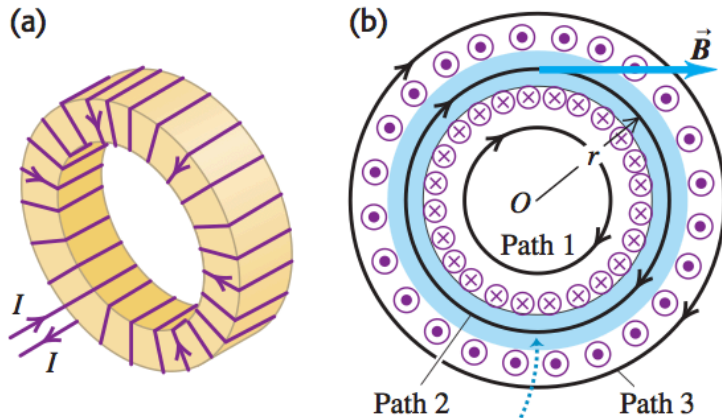


The magnetic field is confined almost entirely to the space enclosed by the windings (in blue).

Toroid with N turns

Three regions (Amperian loops) possible

Application of Ampere's Law #4: Toroid



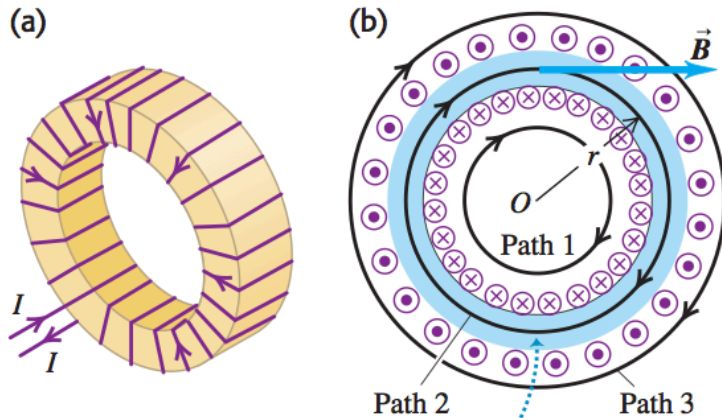
The magnetic field is confined almost entirely to the space enclosed by the windings (in blue).

Toroid with N turns

Region/Path 1:

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

Application of Ampere's Law #4: Toroid



The magnetic field is confined almost entirely to the space enclosed by the windings (in blue).

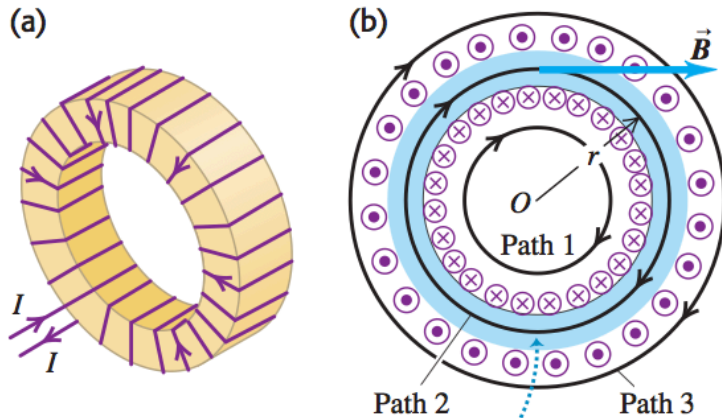
Toroid with N turns

Region/Path 1:

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

$$B2\pi r = \mu_0(0)$$

Application of Ampere's Law #4: Toroid



The magnetic field is confined almost entirely to the space enclosed by the windings (in blue).

Toroid with N turns

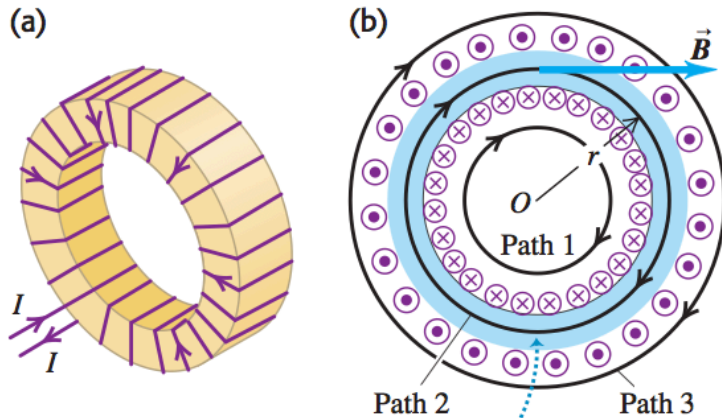
Region/Path 1:

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

$$B2\pi r = \mu_0(0)$$

$$B = 0$$

Application of Ampere's Law #4: Toroid



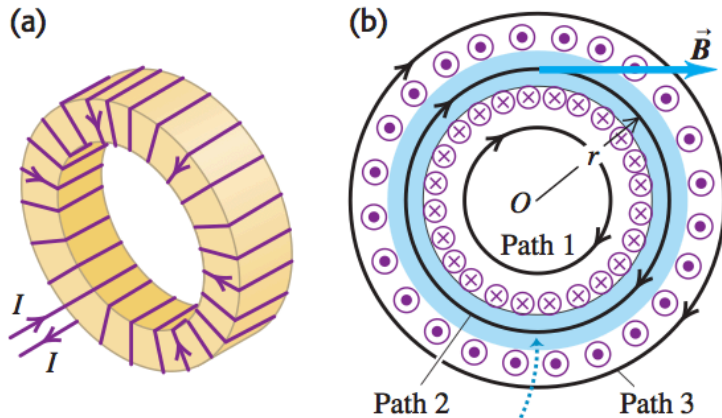
The magnetic field is confined almost entirely to the space enclosed by the windings (in blue).

Toroid with N turns

Region/Path 2:

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

Application of Ampere's Law #4: Toroid



The magnetic field is confined almost entirely to the space enclosed by the windings (in blue).

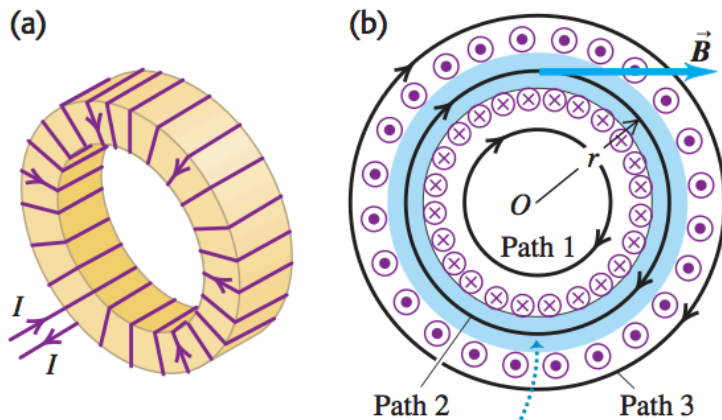
Toroid with N turns

Region/Path 2:

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

$$B2\pi r = \mu_0 NI$$

Application of Ampere's Law #4: Toroid



The magnetic field is confined almost entirely to the space enclosed by the windings (in blue).

Toroid with N turns

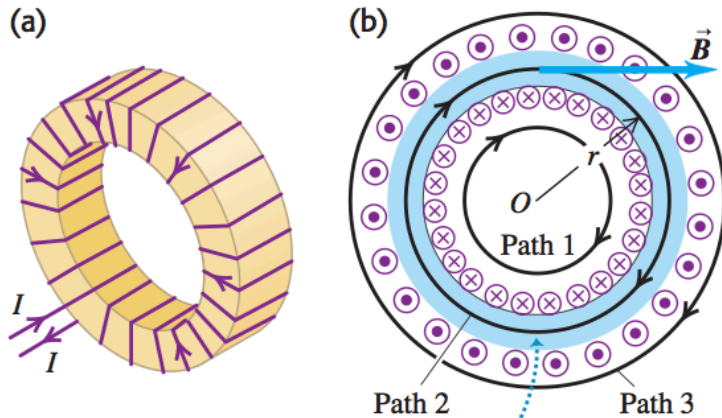
Region/Path 2:

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

$$B2\pi r = \mu_0 NI$$

$$B = \frac{\mu_0 NI}{2\pi r}$$

Application of Ampere's Law #4: Toroid



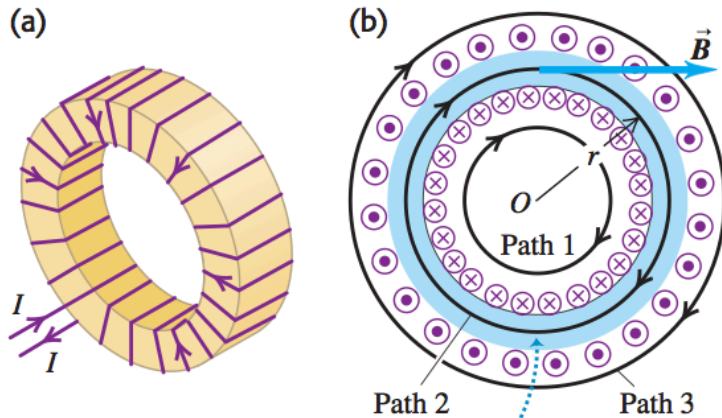
The magnetic field is confined almost entirely to the space enclosed by the windings (in blue).

Toroid with N turns

Region/Path 3:

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

Application of Ampere's Law #4: Toroid



The magnetic field is confined almost entirely to the space enclosed by the windings (in blue).

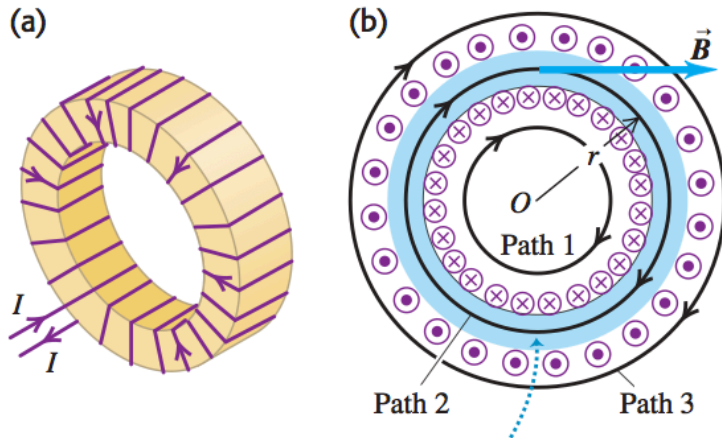
Toroid with N turns

Region/Path 3:

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

$$B2\pi r = \mu_0(+NI - NI) = 0$$

Application of Ampere's Law #4: Toroid



The magnetic field is confined almost entirely to the space enclosed by the windings (in blue).

Toroid with N turns

Region/Path 3:

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

$$B2\pi r = \mu_0(+NI - NI) = 0$$

$$B = 0$$