

**Problem 2.1** (2 points). Which of the following are linear transformations? Justify.

$$(a) \quad T : \begin{cases} \mathbb{R}^2 & \rightarrow \mathbb{R}^2 \\ (x, y) & \mapsto (-2x + y, x + 3y) \end{cases}$$

*It is a linear transformation. And we prove it by definition:*

**Proof.**

$$(a) \quad \forall v = (v_1, v_2), w = (w_1, w_2) \in \mathbb{R}^2, \text{ we have } T(v+w) = T((v_1+w_1, v_2+w_2)) = (-2(v_1+w_1) + (v_2+w_2), (v_1+w_2) + 3(v_2+w_2)) = (-2v_1 + v_2 + (-2w_1 + w_2), v_1 + 3v_2 + w_2 + 3w_2) = (-2v_1 + v_2, v_1 + 3v_2) + (-2w_1 + w_2, w_1 + 3w_2) = T(v) + T(w)$$

$$(b) \quad \forall v = (v_1, v_2) \in \mathbb{R}^2, \alpha \in \mathbb{R}, L(v) = L(\alpha(v_1, v_2)) = L((\alpha v_1, \alpha v_2)) = (-2\alpha v_1 + \alpha v_2, \alpha v_1 + 3\alpha v_2) = \alpha(-2v_1 + v_2, v_1 + 3v_2) = \alpha L(v).$$

□

$$(b) \quad T : \begin{cases} \mathbb{R}^2 & \rightarrow \mathbb{R} \\ (x, y) & \mapsto x + y + 1 \end{cases}$$

*It is **not** a linear transformation. The counterexample would be easy to find. For example, we choose  $v = (1, 2), w = (3, 4)$ , then  $T(v+w) = T((4, 6)) = 4 + 6 + 1 = 11$  whereas  $T(v) + T(w) = (1 + 2 + 1) + (3 + 4 + 1) = 12$ , which shows that  $T(v+w) \neq T(v) + T(w)$ .*

$$(c) \quad T : \begin{cases} \mathbb{R}^{n \times m} & \rightarrow \mathbb{R}^n \\ A & \mapsto Ax \end{cases} \quad \text{where } x \in \mathbb{R}^m \text{ is a fixed vector.}$$

*It is a linear transformation. And we prove it by definition:*

**Proof.**

$$(a) \quad \forall A, B \in \mathbb{R}^{m \times n}, \text{ we have } T(A+B) = (A+B)x = Ax + Bx = T(A) + T(B)$$

$$(b) \quad \forall \alpha \in \mathbb{R}, A \in \mathbb{R}^{m \times n}, \text{ we have } T(\alpha A) = (\alpha A)x = \alpha Ax = \alpha T(A).$$

□

$$(d) \quad T : \begin{cases} \mathbb{R}^{n \times n} & \rightarrow \mathbb{R}^{n \times n} \\ A & \mapsto \begin{cases} A^{-1} & \text{if } A \text{ is invertible} \\ 0 & \text{otherwise} \end{cases} \end{cases}$$

*It is **not** a linear transformation. The counterexample could be if we choose  $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, B = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}$  where  $A^{-1}$  and  $B^{-1}$  both exists but  $(A+B)^{-1}$  doesn't exist and thus doesn't equal to  $A^{-1} + B^{-1}$ .*

**Problem 2.2** (3 points). Let  $L: \mathbb{R}^m \rightarrow \mathbb{R}^n$  be a linear map.

(a) Show that  $\text{Ker}(L)$  is a subspace of  $\mathbb{R}^m$ .

**Proof.**

(a) Since  $L(0) = 0$ ,  $0 \in \text{Ker}(L)$ .

(b)  $\forall v, w \in \text{Ker}(L)$ , we have  $L(v) = 0$  and  $L(w) = 0$ , then we have  $L(v+w) = L(v) + L(w) = 0$ , which means  $v+w \in \text{Ker}(L)$ .

(c)  $\forall v \in \text{Ker}(L), \alpha \in \mathbb{R}$ , we have  $L(v) = 0$  and  $L(\alpha v) = \alpha L(v) = 0$  which implies  $\alpha v \in \text{Ker}(L)$ .

□

(b) Show that  $\text{Im}(L)$  is a subspace of  $\mathbb{R}^n$ .

**Proof.**

(a) Since  $L(0) = 0$ , thus  $0 \in \mathbb{R}^n$  has a pre-image  $0 \in \mathbb{R}^m$ , and this implies  $0 \in \text{Im}(L)$ .

(b)  $\forall v, w \in \text{Im}(L) = \mathbb{R}^n$ , we have  $L(v_0) = v$  and  $L(w_0) = w$  where  $v_0, w_0 \in \mathbb{R}^m$ , then we have  $L(v_0 + w_0) = L(v_0) + L(w_0) = v + w$ , which means  $v + w$  has a pre-image and thus  $v + w \in \text{Im}(L)$ .

(c)  $\forall v \in \text{Im}(L), \alpha \in \mathbb{R}$ , we have  $L(v_0) = v, v_0 \in \mathbb{R}^m$  and  $L(\alpha v_0) = \alpha L(v_0) = \alpha v$ , which implies  $\alpha v$  has a pre-image  $\alpha v_0$  and  $\alpha v \in \text{Im}(L)$ .

□

(c) For each subspace below, find a linear map  $L$  such that it is its kernel or its image. You do not have to prove that  $L$  is linear.

(i)  $E_1 = \{(x, y) \in \mathbb{R}^2 \mid 3x - y = 0\}$ .

i. We can construct a linear map  $L: \begin{matrix} \mathbb{R}^2 & \rightarrow & \mathbb{R} \\ (x, y) & \mapsto & 3x - y \end{matrix}$  where  $E_1$  is its kernel.

ii. We can construct a linear map  $L: \begin{matrix} \mathbb{R}^2 & \rightarrow & \mathbb{R}^2 \\ (x, y) & \mapsto & (x + 2y, 3x + 6y) \end{matrix}$  where  $E_1$  is its image.

(ii)  $E_2 = \{(x, y, z) \in \mathbb{R}^3 \mid x = 0 \text{ and } y - z = 0\}$ .

i. We can construct a linear map  $L: \begin{matrix} \mathbb{R}^3 & \rightarrow & \mathbb{R} \\ (x, y, z) & \mapsto & x + y - z \end{matrix}$  where  $E_2$  is its kernel.

ii. We can construct a linear map  $L: \begin{matrix} \mathbb{R} & \rightarrow & \mathbb{R}^3 \\ x & \mapsto & (0, x, x) \end{matrix}$  where  $E_1$  is its image.

(iii)  $E_3 = \{(4a + b - 3c, 5a - 2b) \mid (a, b, c) \in \mathbb{R}^3\}$ .

We first rearrange the  $E_3$  into  $\text{Span}\left\{\begin{bmatrix} 4 \\ 5 \end{bmatrix}, \begin{bmatrix} 1 \\ -2 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \end{bmatrix}\right\} = \text{Span}\left\{\begin{bmatrix} 1 \\ -2 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \end{bmatrix}\right\}$

i. We can construct a linear map  $L: \begin{matrix} \mathbb{R}^2 & \rightarrow & \mathbb{R}^2 \\ (x, y) & \mapsto & 0 \end{matrix}$  where  $E_3$  is its kernel.

ii. We can construct a linear map  $L: \begin{matrix} \mathbb{R}^3 & \rightarrow & \mathbb{R}^2 \\ (x, y, z) & \mapsto & (4x + y - 3z, 5x - 2y) \end{matrix}$  where  $E_3$  is its image.

**Problem 2.3** (3 points). *Let*

$$A = \begin{pmatrix} 1 & 2 & -1 \\ 2 & 5 & -3 \\ 3 & 1 & 2 \end{pmatrix}$$

- (a) *Let  $(a, b, c) \in \mathbb{R}^3$ . Using Gaussian elimination, find all the  $(x, y, z) \in \mathbb{R}^3$  such that  $A(x, y, z) = (a, b, c)$ . You will have to separate cases according to the values of  $(a, b, c)$  (e.g., if you find the equation  $a = 0$ , then there are no solutions when  $a \neq 0$ ).*

*We perform gaussian elimination on augmented matrix  $[A|(a, b, c)]$  and could get*

$$\begin{bmatrix} 1 & 0 & 1 & 5a - 2b \\ 0 & 1 & -1 & b - 2a \\ 0 & 0 & 0 & 5b + c - 13a \end{bmatrix}$$

*(a) When  $5b + c - 13a \neq 0$ , we have no solution.*

*(b) When  $5b + c - 13a = 0$ , we have infinite solutions  $(x, y, z) = \left\{ \begin{bmatrix} 5a - 2b \\ b - 2a \\ 0 \end{bmatrix} + s \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} \mid s \in \mathbb{R} \right\}$*

- (b) *Using the first question, give  $\text{Im}(A)$  as a set of vectors satisfying a linear equation.*

*Since the pivot elements appear at the first two columns, we can pick these two pivot columns as our basis for the image of  $A$ , and we have  $\text{Im}(A) = \text{Span}\left(\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ 5 \\ 1 \end{bmatrix}\right) =$*

$$\left\{ \begin{bmatrix} x + 2y \\ 2x + 5y \\ 3x + y \end{bmatrix}, \forall x, y \in \mathbb{R} \right\}.$$

- (c) *Using the first question, give a basis of  $\text{Ker}(A)$ .*

*The  $\text{Ker}(A) = \text{Span}\left(\begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}\right)$ , which is given by the format of solution in part (a) where  $\dim(\text{Ker}(A)) = 1$ .*

**Problem 2.4** (2 points). Let  $B$  and  $P$  be the following matrices in  $\mathbb{R}^{3 \times 3}$ :

$$P = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad B = \begin{pmatrix} B_{1,1} & B_{1,2} & B_{1,3} \\ B_{2,1} & B_{2,2} & B_{2,3} \\ B_{3,1} & B_{3,2} & B_{3,3} \end{pmatrix}$$

with arbitrary entries for  $B$ .

- (a) Compute the matrix product  $BP$ . Why is  $P$  called a permutation matrix?

$BP = \begin{pmatrix} B_{1,2} & B_{1,1} & B_{1,3} \\ B_{2,2} & B_{2,1} & B_{2,3} \\ B_{3,2} & B_{3,1} & B_{3,3} \end{pmatrix}$ , since the first and second column of  $B$  is swapped to form a new permutation of the columns of  $B$ ,  $P$  is called a permutation matrix.

- (b) Compute  $PB$ . What can you notice?

$BP = \begin{pmatrix} B_{2,1} & B_{2,2} & B_{2,3} \\ B_{1,1} & B_{1,2} & B_{1,3} \\ B_{3,1} & B_{3,2} & B_{3,3} \end{pmatrix}$ , since the first and second row of  $B$  is swapped to form a new permutation of the rows of  $B$ .

The observation is that, if the permutation matrix appears at the left matrix, we are permuting the rows, otherwise we are permuting the columns.

**Problem 2.5** (★). (a) Show that the set  $V = \{L \mid L: \mathbb{R}^m \rightarrow \mathbb{R}^n \text{ linear}\}$  of all linear maps from  $\mathbb{R}^m$  to  $\mathbb{R}^n$  is a vector space.

**Proof.** By definition of linear maps, we first prove additivity:

$$(a) \quad \forall S, T \in V, v, w \in \mathbb{R}^m, \text{ we have } (S+T)(v+w) = S(v+w) + T(v+w) = S(v) + S(w) + T(v) + T(w) = (S+T)v + (S+T)w$$

$$(b) \quad \forall S, T \in V, v \in \mathbb{R}^m, \alpha \in \mathbb{R}, \text{ we have } (S+T)(\alpha v) = S(\alpha v) + T(\alpha v) = \alpha S(v) + \alpha T(v) = (\alpha(S+T))(v)$$

, thus  $S+T$  is linear map from  $\mathbb{R}^m$  to  $\mathbb{R}^n$  and  $S+T \in V$ .

We next prove scalar multiplication:

$$(a) \quad \forall S \in V, \alpha \in \mathbb{R}, v, w \in \mathbb{R}^m, \text{ we have } (\alpha S)(v+w) = \alpha S(v+w) = \alpha(S(v) + S(w)) = (\alpha S)(v) + (\alpha S)(w)$$

$$(b) \quad \forall S \in V, \alpha \in \mathbb{R}, v \in \mathbb{R}^m, \beta \in \mathbb{R}, \text{ we have } (\alpha S)(\beta v) = \alpha S(\beta v) = \alpha\beta S(v) = \beta\alpha S(v) = \beta(\alpha S)(v)$$

, thus  $\alpha S$  is linear map from  $\mathbb{R}^m$  to  $\mathbb{R}^n$  and  $\alpha S \in V$ .

Finally we know that zero map always exists, so  $V$  is a vector space.  $\square$

(b) Give an example of a linear map from  $V$  to  $\mathbb{R}^n$ .

$$\begin{array}{ccc} V & \rightarrow & \mathbb{R}^n \\ \text{One example should be } \mathcal{T}: S & \mapsto & \begin{bmatrix} \sum_{j=1}^m \tilde{S}_{1j} \\ \sum_{j=1}^m \tilde{S}_{2j} \\ \vdots \\ \sum_{j=1}^m \tilde{S}_{nj} \end{bmatrix} \end{array} \quad \text{where } \tilde{S}_{ij} \text{ is the } ij\text{-entry of the representation matrix of the linear map } S.$$

(c) What is the dimension of  $V$ ? Hint: what would be the equivalent for linear maps of the proof we did in class for matrices?

The dimension of  $V$  is  $n \times m$ , because the input is a matrix (representation matrix of a linear map).