Lec 7: Empirical Bayes

Vanjun Han Oct. 24, 2023 A motivating example.

Given $y \sim N(0,1)$ with $0 \in \mathbb{R}^2$, aim to estimate 0 under quadratic loss: $\mathbb{E}_0 || \hat{\theta}(y) - 0||^2$.

Natural estimator: $\theta^{MLE}(y) = y$ Lots of nice properties: MLE, minimax, UMVUE (uniform smallest variance unbiased estimator), MRE (minimum risk equivariant estimator), ...

Shocking observation: a uniformly better estimator than ôMLE, if p33.

Note: JS estimator leads to the shrinkage idea, i.e. shrink y slightly to zero (slightly increases bias, significantly reduce variance)

$$\frac{\text{Risk of MLE}}{\text{Risk of JS}} = \mathbb{E} \|\hat{\theta}^{\text{MLE}} - \theta\|^2 = \mathbb{E} \|\hat{\mathbf{J}}\|^2 = \mathbf{p} , \quad \forall \theta.$$

$$\mathbb{E}_{\theta} \|\hat{\theta}^{\text{JS}} - \theta\|^2 = \mathbb{E}_{\theta} \left[\|\hat{\mathbf{J}}\|^2 - 2(\mathbf{p} - 2) \left(\frac{\mathbf{y}}{\|\mathbf{y}\|^2}, \frac{\mathbf{y}}{2} \right) + \frac{(\mathbf{p} - 2)^2}{\|\mathbf{y}\|^2} \right].$$

Lemma (Stein's identity).

Let
$$\mathfrak{Z} \sim N(\mathfrak{o}, I_{\mathfrak{p}})$$
 and $\mathfrak{f} : \mathbb{R}^{\mathfrak{p}} \to \mathbb{R}^{\mathfrak{p}}$. Then

$$\mathbb{E}[\langle \mathfrak{Z}, \mathfrak{f}(\mathfrak{Z}) \rangle] = \mathbb{E}[\nabla \cdot \mathfrak{f}(\mathfrak{Z})]$$
divergence: $\nabla \cdot \mathfrak{f}(\mathfrak{Z}) = \sum_{i=1}^{\mathfrak{p}} \frac{\partial f_{i}}{\partial \mathfrak{T}_{i}}(\mathfrak{Z})$.

Pf. Suffice to prove the case
$$p=1$$
. Here

$$E[f'(3)] = \int_{-\infty}^{+\infty} f'(3) \, \phi(3) \, d3$$

$$= f(3) \, \phi(3) \Big|_{-\infty}^{+\infty} - \int_{-\infty}^{+\infty} f(3) \, \phi'(3) \, d3 \Big|_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} f(3) \, \phi'(3) \, d3 \Big|_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} f(3) \, \phi'(3) \, d3 \Big|_{-\infty}^{+\infty} \left(\phi'(3) = -\frac{3}{2} \, \phi(3) \right)$$

$$= E[3f(3)]$$

$$\mathbb{E}_{\theta}\left\langle\frac{y}{\|y\|^{2}}, \beta\right\rangle = \mathbb{E}_{\theta}\left\langle\frac{\theta+\beta}{\|\theta+\beta\|^{2}}, \beta\right\rangle$$

$$= \mathbb{E}_{\theta}\left[\nabla \cdot \frac{\theta+\beta}{\|\theta+\beta\|^{2}}\right]$$

$$= \mathbb{E}_{\theta}\left[\sum_{i=1}^{p} \frac{\|\theta+\beta\|^{2}-2(\theta_{i}+\beta_{i})^{2}}{\|\theta+\beta\|^{2}}\right]$$

$$= \mathbb{E}_{\theta}\left[\frac{\frac{p-2}{\|\theta+\beta\|^{2}}}{\|\theta+\beta\|^{2}}\right] = \mathbb{E}_{\theta}\left[\frac{\frac{p-2}{\|y\|^{2}}}{\|y\|^{2}}\right].$$

By Stein's identity,

$$\int_{\sigma} \mathbb{E}_{\theta} \| \hat{\theta}^{TS} - \theta \|^{2} = P - 2(P-2) \mathbb{E}_{\theta} \left[\frac{P-2}{\|Y\|^{2}} \right] + (P-2)^{2} \mathbb{E}_{\theta} \left[\frac{1}{\|Y\|^{2}} \right]$$

$$= P - (P-2)^{2} \mathbb{E}_{\theta} \left[\frac{1}{\|Y\|^{2}} \right]$$

An expirical Bayes view of JS estimator.

Consider a Bayes setting where
$$0 \sim N(0, \tau^2 I_p)$$
.

Then

$$y \sim N(\circ, (1+\tau^2)I_p)$$
 (marginal distribution)
 $0 \mid y \sim N(\frac{\tau^2 y}{1+\tau^2}, \frac{\tau^2}{1+\tau^2})$ (posterior)

Bayes estimator:

$$\widehat{\Theta}^{\text{Bayes}}(y) = \mathbb{E}[\Theta|Y] = \frac{\tau^2}{|+\tau^2|}Y.$$

Problem: don't know how to set T.

Empirical Bayes: estimate (functions of) T based on marginal distribution of y!

$$\mathbb{E}\left[\frac{1}{\|y\|^{2}}\right] = \frac{1}{|+\tau^{2}|} \int_{\infty}^{\infty} \frac{1}{2^{\frac{p}{2}} \Gamma(\frac{p}{2})} t^{\frac{p}{2}-1} e^{-\frac{t}{2}} \frac{dt}{t}$$

$$= \frac{1}{|+\tau^{2}|} \int_{\infty}^{\infty} \frac{1}{2^{\frac{p}{2}} \Gamma(\frac{p}{2})} u^{\frac{p}{2}-2} e^{-u} du \quad (t=2u)$$

$$= \frac{1}{|+\tau^{2}|} \cdot \frac{\Gamma(\frac{p}{2}-1)}{2^{\frac{p}{2}} \Gamma(\frac{p}{2})} = \frac{1}{|+\tau^{2}|} \cdot \frac{1}{|-2|}$$

$$\Rightarrow \frac{p-2}{\|y\|^2}$$
 is an unbiased estimator of $\frac{1}{1+\tau^2}$.

So
$$\hat{\Theta}^{\text{Bayes}}(y) = \frac{\tau^2}{1+\tau^2}y$$

$$= \left(1 - \frac{1}{1+\tau^2}\right)y$$

$$\approx \left(1 - \frac{p-2}{1|y||^2}\right)y \quad \text{(fully data-driven:}}$$

$$JS!)$$

Robbins' empirical Bayes model Given $\begin{cases} y_1 \sim p_{\theta_1} \\ y_2 \sim p_{\theta_2} \end{cases}$, aim to estimate (functions of) $0 \in \mathbb{R}^k$. i.i.d. model (Robbins' 56) O, ..., Or ~ G (unknown prior) compound model (Roblins' 51) no distributional assumption on O (but usually pretend that $\theta_1, \dots, \theta_k \stackrel{iid.}{\sim} G$ with $G = \frac{1}{k} \stackrel{k}{\leq} \delta_{\theta_i}$) typical steps of EB; 1. for given G, obtain the Bayes estimator OG(Y) 2. use y yx to estimate G (two approaches: f-modeling and g-modeling - later) Robbins' estimator in Poisson models Assume $y \approx Poi(\theta_i)$, i=1,2,...,k. The Bayes estimator for 0: 6 = E (0 1 y) $= \frac{\mathbb{E}_{G}\left[0 \cdot e^{-\theta} \frac{\delta^{\gamma}}{\gamma!}\right]}{\mathbb{E}_{G}\left[e^{-\theta} \frac{\delta^{\gamma}}{\gamma!}\right]}$ $= (\gamma + 1) \cdot \frac{\mathbb{E}_{G}\left[e^{-\theta} \frac{\delta^{\gamma}}{(\gamma + 1)!}\right]}{\mathbb{E}_{G}\left[e^{-\theta} \frac{\delta^{\gamma}}{(\gamma + 1)!}\right]}$ $= (\gamma + 1) \cdot \frac{\int_{G}(\gamma + 1)}{\int_{G}(\gamma)} \quad (\int_{G}: \text{marginal distribution of } \gamma)$ An unbiased estimator for fa(y): $\mathbb{E}\left[\frac{1}{k}\sum_{i=1}^{k}1(y_{i}=y)\right]=\int_{G}(y).$

Robbins' estimator:
$$\hat{\theta}_i = (\gamma_i + 1) \frac{N_{\gamma_i + 1}}{N_{\gamma_i}}$$

Good-Turing estimator

Consider a special case
$$y_i \sim Poi(np_i)$$
, $i=1,\dots,k$ with $\sum_{i=1}^{k} p_i=1$.

(background: Poissonization of an i.i.d. sampling model.

Raw data: x1, ..., xn (P1, -, PK) (unknown)

The histogram: $y_i = \sum_{j=1}^{n} 1(x_j = i)$, $i=1,\dots,k$

 $(\gamma_1, \cdots, \gamma_k) \sim \text{Multi}(n; (p_1, \cdots, p_k)) \approx \text{Poi}(np_1) \times \cdots \times \text{Poi}(np_k))$

Target: estimate the portion of unseen species, i.e.

$$p^{(\bullet)} := \sum_{i=1}^{k} 1(\gamma_i = 0) p_{i,i}$$

Note: MLE would be meaningless as it always outputs pieo if yieo.

EB solution.

If pi, ..., pr ~ G, then

$$\mathbb{E}_{G}\left[\begin{array}{ccc} p_{i} \mid \gamma_{i} \end{array}\right] = \frac{\gamma_{i} + 1}{n} \quad \frac{f_{G}(\gamma_{i} + 1)}{f_{G}(\gamma_{i})} \approx \frac{\gamma_{i} + 1}{n} \quad \frac{N_{\gamma_{i} + 1}}{N_{\gamma_{i}}}$$

(Robbins' estimator)

$$\Rightarrow$$
 a good estimator for $\sum_{i=1}^{k} 1(y_i = 0) p_i$ is

$$\sum_{i=1}^{k} 1(\gamma_i = 0) \frac{\gamma_i + 1}{n} \cdot \frac{N\gamma_{i+1}}{N\gamma_{i}} = N_o \cdot \frac{1}{n} \cdot \frac{N_1}{N_0} = \frac{N_1}{n}$$

 N_1 : # of unique species in χ_1, \dots, χ_n

Intuition: - if x,..., x, are all distinct, then probably the population

is large and mostly unseen, i.e. $P^{(0)} \approx 1$

• if each x appears at least twice $\implies P^{(a)} \approx 0$.

Good-Turing estimator. $P_i = \frac{y_i + 1}{n} \cdot \frac{Ny_{i+1}}{Ny_{i}}$

Predicting # of new species (Thisted & Efron' 76, '87)

A related question: given a collection x, ... x of n observations:

- · how many new species do we expect to see in a new sample of size m?
 - · how many species do we expect to see, in a new sample of size m, which appear exactly t times in the original sample?

The Poisson model $y_i \stackrel{\text{ind}}{\sim} Poi(np_i)$, $i=1,\dots,k$, $\sum_{i=1}^{k} p_i = 1$

Aim to estimate

$$\sum_{i=1}^{k} 1(y_i = t) (1 - e^{-mp_i}), \quad k = 0, 1, \dots$$
species appearing prob. of observing exactly t times in i in the new sample.

Original sample

EB estimation of Pi.

$$\mathbb{E}_{G}[P^{\ell}|\gamma] = \frac{\mathbb{E}_{G}[P^{\ell} e^{-N^{\ell}} \frac{(Np)^{\gamma}}{\gamma!}]}{\mathbb{E}_{G}[e^{-N^{\ell}} \frac{(Np)^{\gamma}}{\gamma!}]} = \frac{(\gamma+1) \cdot (\gamma+\ell)}{N^{\ell}} \frac{f_{G}(\gamma+\ell)}{f_{G}(\gamma)}$$

$$\approx \frac{(\gamma+\ell)!}{\gamma! n^{\ell}} \cdot \frac{N_{\gamma+\ell}}{N_{\gamma}}.$$

Final EB estimator.

$$\frac{k}{\sum_{i=1}^{k} 1(\gamma_{i} = t) \left(1 - e^{-m\beta_{i}} \right)} = \sum_{i=1}^{k} 1(\gamma_{i} = t) \sum_{\ell=1}^{\infty} (-1)^{\ell+1} \frac{(m\rho_{i})^{\ell}}{\ell!}$$

$$\approx \sum_{i=1}^{k} 1(\gamma_{i} = t) \sum_{\ell=1}^{\infty} (-1)^{\ell+1} \left(\frac{\gamma_{i} + \ell}{\ell} \right) \left(\frac{m}{n} \right)^{\ell} \frac{N_{k+\ell}}{N_{k}}$$

$$= \sum_{\ell=1}^{\infty} (-1)^{\ell+1} {t+\ell \choose \ell} \left(\frac{m}{n} \right)^{\ell} N_{\ell+t}.$$

Example: if t=0 and m=n, then

of new species in the next n observations $\approx N_1 - N_2 + N_3 - \cdots$

Gaussian location model: Tweedie's formula

If $\gamma \sim N(0,1)$ with $0 \sim G$, then $\mathbb{E}_{G}[\theta|\gamma] = \frac{\mathbb{E}_{G}[\theta|(\gamma-\theta)]}{\mathbb{E}_{G}[(\gamma-\theta)]}$ $= \gamma - \frac{\mathbb{E}_{G}[(\gamma-\theta)|\phi(\gamma-\theta)]}{\mathbb{E}_{G}[(\gamma-\theta)]} = -\int_{G}^{G}(\gamma)$ $= \gamma + \frac{d}{d\gamma}|_{0}\int_{G}^{G}(\gamma)$ (Twee die's formula)

An estimator without knowledge of Gr. estimate the marginal distribution $\hat{f}(y)$ of y based on y_1, \dots, y_k , then use \hat{f} in place of f_G .

f-modeling us. g-modeling (ongoing topic)

- · All previous examples use f-modeling, where we aim to estimate the marginal distribution for based on Y1, ..., Yk
- · f-modeling is simple, yet could have a large variance
 · g-modeling: estimate G based on y,..., yk (parametric/nonparametric)

A popular choice: NPMLE G = argmax \(\frac{1}{6}\) \[\left[\text{Po} \(\text{Y}_i \) \]

(convex, but infinite dimensional)

Then use G in place of G.

· some evidence that g-modeling gives better estimation performances.