Lec 2: Properties of Exponential Family

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Let y be the observation space. A class of probability distributions (Po) 000 is called an exponential family iff

PO(Y) = exp (<0. T(y)> - A(0)) h(y), 4060, y 6 y.

Notations.  $T(y) = (T_1(y), \dots, T_d(y))$ : sufficient statistic

 $(x,y) = x(y,+\cdots+x)$  denotes the inner product

A(0): log-partition function
 h(y): base measure

Intoition of exp. family:

 $P_{\Theta}(y) = \exp((\Theta, T(y))) \times \text{function of } \Theta \times \text{function of } y$ 

"O and y interact OULT through (0, T(y)) in the exponent"

Examples.

1. Gaussian location family: y~ N(p. 1).

$$P_{\mu}(y) = \frac{1}{\sqrt{2\pi}} \exp(-\frac{(y-\mu)^2}{2})$$

$$= \frac{1}{\sqrt{2\pi}} \exp(\mu y - \frac{\mu^2}{2} - \frac{y^2}{2})$$

Correspondence to exp. family: 0= M

$$T(\gamma) = \gamma$$

$$A(\theta) = \frac{M^2}{2} = \frac{\theta^2}{2}$$

$$A(\gamma) = \frac{1}{\sqrt{2\pi}} \exp(-\frac{\gamma^2}{2})$$

2. Gaussian location and scale family: 
$$y \sim N(\mu, \sigma^2)$$

$$P_{M, \sigma^{2}}(y) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(y - y)^{2}}{2\sigma^{2}}\right)$$

$$= \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{y^{2}}{2\sigma^{2}} + \frac{My}{\sigma^{2}} - \frac{M^{2}}{2\sigma^{2}} - \log \sigma\right)$$

Correspondence to exp. family: 
$$\theta = \left(\frac{M}{\sigma^{2}}, -\frac{1}{2\sigma^{2}}\right)$$

$$T(\gamma) = (\gamma, \gamma^{2})$$

$$A(\theta) = \frac{M^{2}}{2\sigma^{2}} + \log \sigma = -\frac{\theta_{1}^{2}}{4\theta_{1}} - \frac{1}{2}\log(-2\theta_{2})$$

$$L(\gamma) = \frac{1}{\sqrt{2\pi}}$$

Reparandrization may be necessary for an exp. family

## 3. Bernoull: model: y~ Bern (p), p ∈ [0,1]

$$p(y) = \begin{cases} p & \text{if } y = 1 \\ 1 - p & \text{if } y = 6 \end{cases} = p^{1(y=1)} (1-p)^{1-2(y=1)}$$

$$= exp(1(y=1) \cdot |-\frac{p}{1-p} + |-\frac{p}{2}(1-p))$$

Correspondence to exp. family: 
$$\theta = \left[ \circ_{\mathcal{I}} \frac{P}{1-P} \in (-\infty, +\infty) \right]$$

$$T(y) = 1(y=1)$$

$$A(\theta) = -\left[ \circ_{\mathcal{I}} (1-P) = \left[ \circ_{\mathcal{I}} (1+e^{\theta}) \right] \right]$$

$$L(y) = 1$$

$$\begin{aligned}
\rho_{\lambda}(y) &= e^{-\lambda} \frac{\lambda^{\gamma}}{\gamma!} \\
&= exp(\gamma | ^{\circ} j \lambda - \lambda) \frac{1}{\gamma!}
\end{aligned}$$

$$\begin{aligned}
\theta &= l ^{\circ} j \lambda \in (-\infty, +\infty) \\
\lambda(0) &= \lambda = e^{\theta} \\
\lambda(y) &= \frac{1}{\gamma!}
\end{aligned}$$

5. Multinomial model: 
$$y \sim (p_1, \dots, p_k)$$
:  $p: \ge 0$ ,  $p_1 + \dots + p_k = 1$ .

$$p(y) = \begin{cases} p_1 & \text{if } y = 1 \\ p_2 & \text{if } y = 2 \end{cases} = p_1 \begin{cases} p_2 & p_2 \\ p_2 & \dots & p_k \end{cases}$$

$$p(y) = \begin{cases} p_1 & \text{if } y = 1 \\ p_2 & \dots & p_k \end{cases}$$

$$p(y) = \begin{cases} p_1 & \text{if } y = 1 \\ p_2 & \dots & p_k \end{cases}$$

$$= \left(\frac{e^{\theta_1}}{e^{\theta_1} + \dots + e^{\theta_k}}\right) \dots \left(\frac{e^{\theta_k}}{e^{\theta_1} + \dots + e^{\theta_k}}\right)^{1(\gamma = k)}$$

$$\left(\text{reparametrization}: P_j = \frac{e^{\theta_j}}{e^{\theta_1} + \dots + e^{\theta_k}}\right)$$

$$= \exp\left(\theta_1 \mathbf{1}(\gamma=1) + \dots + \theta_k \mathbf{1}(\gamma=k) - \log\left(e^{\theta_1} + \dots + e^{\theta_k}\right)\right)$$

Correspondence to exp. family: 
$$\theta = (\theta_1, \dots, \theta_k)$$
  
 $T(y) = (1(y=1), 1(y=2), \dots, 1(y=k))$   
 $A(\theta) = \log(e^{\theta_1} + \dots + e^{\theta_k})$   
 $h(y) = 1$ 

## Modeling idea behird exponential family.

- y ∈ y: response variable, either discrete or continuous
   p<sub>o</sub>(y): a "base probability distribution" trying to fit (Y1, ..., Yn)
  - · Poly), an "exponential tilting" of Poly);

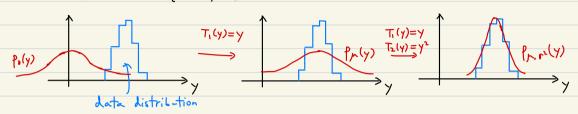
$$p_{\theta}(y) = \exp\left(\langle \theta, T(y) \rangle - A(\theta)\right) h(y)$$

$$\Rightarrow \frac{p_{\theta}(y)}{p_{\theta}(y)} = \exp\left(\langle \theta, T(y) \rangle - A(\theta) + A(\theta)\right)$$

$$= \exp((0,T(y))) \times \text{function of } 0$$

Exponential tilting maintains the support Y, but changes the shape of the distribution.

· T(y): the "quantity of interest" to be fit



•  $A(\theta)$ : normalization factor

Y discrete:  $A(\theta) = \log \sum_{y \in y} \exp(\langle \theta, T(y) \rangle) h(y)$ Y continuous:  $A(\theta) = \log \int_{y} \exp(\langle \theta, T(y) \rangle) h(y) dy$ 

response with covariate: (x1, y1), --, (xn, yn)

modeling via exp. family: y: ~ Po; (yi) with  $\theta_i = \beta^T x$ this is called "generalized linear model" (more in Lec 4)

(GLM)

Examples of GLM:

1. Gaussian family. E[Y|X] = BTX (linear regression)

2. Bernoulli family: log E[Y|X] = BTX (logistic regression)

3. Poisson family: log E[Y|X] = BTX (Poisson regression)

## Properties of exp. family 1. Mean. $M_{\theta} = \mathbb{E}_{P_{\theta}}[T(y)] = \sum_{y \in \mathcal{Y}} T(y) \cdot P_{\theta}(y)$ $= \sum_{y \in \mathcal{Y}} T(y) \cdot exp(\langle \theta \rangle)$

$$= \sum_{Y \in Y} T(y) \cdot exp((0, T(y)) - A(0)) h(y)$$

$$\nabla A(0) = \nabla_0 |_{\mathcal{I}_{Y \in Y}} \left(\sum_{Y \in Y} exp((0, T(y))) h(y)\right)$$

$$= \frac{\sum_{Y \in Y} T_0 exp((0, T(y))) h(y)}{\sum_{Y \in Y} exp((0, T(y))) h(y)}$$

=  $e^{-A(\theta)} \sum_{y \in y} T(y) \exp((0,T(y))) h(y)$ 

$$= \sum_{y \in y} T(y) \exp((\theta, T(y)) - A(\theta)) h(y)$$

$$\mathbb{E}_{\theta} [T(y)] = \nabla A(\theta)$$

2. Covariance.

$$\nabla^2 A(\Theta) = \nabla \left( \nabla A(\Theta) \right) = \nabla_{\Theta} \left( \frac{\sum_{y \in y} \nabla_{\Theta} \exp(\langle \Theta, T(y) \rangle) \lambda(y)}{\sum_{y \in y} \exp(\langle \Theta, T(y) \rangle) \lambda(y)} \right)$$

$$= \frac{\sum_{y \in y} \nabla_{\theta}^{2} \exp(\langle \theta, T(y) \rangle) k|y)}{\sum_{y \in y} \exp(\langle \theta, T(y) \rangle) k|y)}$$

$$-\left(\frac{\sum\limits_{\gamma \in \mathcal{I}} \nabla_{\theta} \exp(\langle \theta, T(\gamma) \rangle) k |_{\gamma}}{\sum\limits_{\gamma \in \mathcal{I}} \exp(\langle \theta, T(\gamma) \rangle) k |_{\gamma}}\right) \left(\frac{\sum\limits_{\gamma \in \mathcal{I}} \nabla_{\theta} \exp(\langle \theta, T(\gamma) \rangle) k |_{\gamma}}{\sum\limits_{\gamma \in \mathcal{I}} \exp(\langle \theta, T(\gamma) \rangle) k |_{\gamma}}\right)^{T}$$

$$\left(\nabla \frac{f}{J} = \frac{(\nabla f) J - f(\nabla J)}{J^{2}}\right)$$

$$= \sum_{\gamma \in \mathcal{Y}} T(\gamma) T(\gamma)^{\mathsf{T}} \underbrace{\exp(\langle \Theta, T(\gamma) \rangle - A(\Theta)) k(\gamma)}_{\mathsf{P}_{\Theta}(\gamma)} - \underbrace{\left(\mathbb{E}_{\bullet} T(\gamma)\right) \left(\mathbb{E}_{\bullet} T(\gamma)\right)}_{\mathsf{P}_{\Theta}(\gamma)}$$

$$Cov_{\theta}(T(y)) = \nabla^2 A(\theta)$$

Corollary:  $\nabla^2 A(\theta) \succeq 0$ , so  $A(\theta)$  convex in  $\theta$ .

Note: the above corollary implies that the correspondence 0 to no = Fo[T(y)] is one-to-one Therefore, exp. families have two parametrizations: parametrize by 0: natural parametrization parametrize by Mo: mean parametrisation

3. Repeated sampling.

$$y_1, y_2, \dots, y_n \sim p_{\theta}(y)$$

$$\Rightarrow p_{\theta}(y_1, \dots, y_n) = p_{\theta}(y_1) p_{\theta}(y_2) \dots p_{\theta}(y_n)$$

$$= \exp\left(\left\langle \theta, \sum_{i=1}^{n} T(y_i) \right\rangle - n A(\theta)\right) h(y_i) h(y_k) \dots h(y_n)$$

(Y1, -, Yn) belongs to a new exponential family:

$$\begin{cases} \Gamma_{(u)}(\lambda^{1},...,\lambda^{u}) = \frac{1}{\mu} \Gamma_{(\lambda^{i})} \\ \Gamma_{(u)}(\lambda^{1},...,\lambda^{u}) = \frac{1}{\mu} \sum_{i=1}^{u} \Gamma_{(\lambda^{i})} \\ \Gamma_{(u)}(\lambda^{1},...,\lambda^{u}) = \frac{1}{\mu} \sum_{i=1}^{u} \Gamma_{(\lambda^{i})} \end{cases}$$

Note: As - = T(Yi) is the sufficient statistic, for estimation/inference of to, one may discard (Y,, ", Y-) and only keep In I T(y:)

4. Conditioning.

If  $\{p_{\theta}(y)\}_{\theta \in \Theta}$  is an exp. family, then for  $Y_{\theta} \subseteq Y$ , the conditional probability distributions  $\{p_{\theta}(y \mid Y_{\theta})\}_{\theta \in \Theta}$  is also an exp. family. (See HWI)

5. Conjugate prior.

A natural prior associated with exp. family:  $\theta \sim \pi_{3,T}(\theta) = \exp((\theta, 3) - \tau A(\theta)) b(3,\tau)$ 

The posterior distribution of  $\theta$  given y.  $\pi_{\sigma,\tau}(\theta|y) = \frac{\pi_{\sigma,\tau}(\theta) P_{\theta}(y)}{\theta}$ 

 $\pi_{3,\tau}(\Theta|y) = \frac{\pi_{3,\tau}(\Theta) P_{\theta}(y)}{P(y)}$   $\max_{y \in T} \{\theta \mid y\} = \int_{\Theta} \pi_{3,\tau}(\Theta) P_{\theta}(y) d\Theta$ 

$$= \frac{1}{p(y)} \exp(\langle \theta, 3 + T(y) \rangle - (\tau + i) A(\theta)) h(y) b(3, \tau)$$

$$= \pi_{\beta+T(y),\tau+l}(\theta)$$

Under the conjugate prior, the posterior takes the same form as the prior, with  $(3, T) \mapsto (3+T(y), T+1)$