

This homework is *never* due.

1. (Sp '19 Midterm 2 #7) Gradient Descent Algorithm

Consider $g : \mathbb{R}^n \rightarrow \mathbb{R}$, $g(\vec{x}) = \frac{1}{2} \vec{x}^\top Q \vec{x} - \vec{x}^\top \vec{b}$, where Q is a symmetric positive definite matrix, i.e., $Q \in \mathbb{S}_{++}^n$.

- (a) Write the update rule for the gradient descent algorithm

$$\vec{x}_{k+1} = \vec{x}_k - \eta \nabla g(\vec{x}_k), \quad (1)$$

where η is the step size of the algorithm, and bring it into the form

$$(\vec{x}_{k+1} - \vec{x}_\star) = P_\eta(\vec{x}_k - \vec{x}_\star), \quad (2)$$

where $P_\eta \in \mathbb{R}^{n \times n}$ is a matrix that depends on η . Find \vec{x}_\star and P_η in terms of Q , \vec{b} and η . *NOTE: \vec{x}_\star is a minimizer of g .*

- (b) Write a condition on the step size η and the matrix Q that ensures convergence of \vec{x}_k to \vec{x}_\star for every initialization of \vec{x}_0 .
- (c) Assume all eigenvalues of Q are distinct. Let η_m denote the largest stepsize that ensures convergence for all initializations \vec{x}_0 , based on the condition computed in part (b).

Does there exist an initialization $\vec{x}_0 \neq \vec{x}_\star$ for which the algorithm converges to the minimum value of g for certain values of the step size η that are larger than η_m ?

Justify your answer. *HINT: The question asks if such initializations exist; not whether it is practical to find them.*

2. (Sp '19 Midterm 2 #3) Convexity of Sets

Determine if each set C given below is convex. Prove that each set is convex or provide an example to show that it is not convex. You may use any techniques used in class or discussion to demonstrate or disprove convexity.

(a) $C = \{\vec{x} \in \mathbb{R}^2 \mid x_1 x_2 \geq 0\}$, where $\vec{x} = \begin{bmatrix} x_1 & x_2 \end{bmatrix}^\top$.

(b) $C = \{X \in \mathbb{S}^n \mid \lambda_{\min}(X) \geq 2\}$, where \mathbb{S}^n is the set of symmetric matrices in $\mathbb{R}^{n \times n}$ and $\lambda_{\min}(X)$ is the minimum eigenvalue of X .

(c) Let $\mathcal{H}(\vec{w})$ denote the hyperplane with normal direction $\vec{w} \in \mathbb{R}^n$, i.e.,

$$\mathcal{H}(\vec{w}) = \{\vec{x} \in \mathbb{R}^n \mid \vec{x}^\top \vec{w} = 0\}. \quad (3)$$

Let $P : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be given by

$$P(\vec{x}) = \operatorname{argmin}_{\vec{y} \in \mathcal{H}(\vec{w})} \|\vec{y} - \vec{x}\|_2. \quad (4)$$

Let

$$C = \{P(\vec{x}) \mid \vec{x} \in \mathcal{B}\} \quad (5)$$

where $\mathcal{B} = \{\vec{x} \in \mathbb{R}^n \mid \|\vec{x}\|_2 \leq 1\}$.

3. (Fa '22 Midterm #8) Matrix Square Root

Let $A, B \in \mathbb{S}_{++}^n$ be symmetric positive definite matrices.

As B is symmetric, it has an orthonormal eigendecomposition $B = V\Lambda V^\top$. Since B is positive definite, we can define its matrix square root as follows $B^{1/2} = V\Lambda^{1/2}V^\top$, where $\Lambda^{1/2}$ is a diagonal matrix whose entries are the square roots of the corresponding entries of Λ . We denote the inverse of $B^{1/2}$ as $B^{-1/2}$. Finally, define $C \doteq B^{-1/2}AB^{-1/2}$.

Prove that the maximum eigenvalue of C is λ^* , where

$$\lambda^* \doteq \max_{\vec{x} \neq \vec{0}} \frac{\vec{x}^\top A \vec{x}}{\vec{x}^\top B \vec{x}}. \quad (6)$$

4. (Sp '20 Midterm # 5) Subspace Projection

Consider a set of points $\vec{z}_1, \dots, \vec{z}_n \in \mathbb{R}^d$. The first principal component of the data, \vec{w}^* , is the direction of the line that minimizes the sum of the squared distances between the points and their projections on \vec{w}^* , i.e.,

$$\vec{w}^* = \operatorname{argmin}_{\|\vec{w}\|_2=1} \sum_{i=1}^n \|\vec{z}_i - \langle \vec{w}, \vec{z}_i \rangle \vec{w}\|^2.$$

In this problem, we generalize to finding the r -dimensional subspace (instead of a 1-dimensional line) that minimizes the sum of the squared distances between the points \vec{z}_i and their projections on the subspace. We assume that $1 \leq r \leq \min(n, d)$. We can represent an r -dimensional subspace by its orthonormal basis $(\vec{w}_1, \dots, \vec{w}_r)$, and we want to solve:

$$(\vec{w}_1^*, \dots, \vec{w}_r^*) = \operatorname{argmin}_{\substack{\|\vec{w}_i\|_2=1 \\ \langle \vec{w}_i, \vec{w}_j \rangle = 0 \ \forall i \neq j \\ 1 \leq i, j \leq r}} \sum_{i=1}^n \min_{\alpha_1, \dots, \alpha_r} \left\| \vec{z}_i - \sum_{k=1}^r \alpha_k \vec{w}_k \right\|^2. \quad (7)$$

Note that the inner minimization projects the point \vec{z}_i onto the subspace defined by $(\vec{w}_1, \dots, \vec{w}_r)$. The variables $\alpha_k \in \mathbb{R}$. This means that for an arbitrary point \vec{z} , this inner minimization

$$(\alpha_1^*, \dots, \alpha_r^*) = \operatorname{argmin}_{\alpha_1, \dots, \alpha_r} \left\| \vec{z} - \sum_{k=1}^r \alpha_k \vec{w}_k \right\|^2$$

has minimizers $\alpha_k^* = \langle \vec{w}_k, \vec{z} \rangle$.

(a) With the following definition of matrices Z and W :

$$Z = \begin{bmatrix} \uparrow & \dots & \uparrow \\ \vec{z}_1 & \dots & \vec{z}_n \\ \downarrow & \dots & \downarrow \end{bmatrix}, \quad W = \begin{bmatrix} \uparrow & \dots & \uparrow \\ \vec{w}_1 & \dots & \vec{w}_r \\ \downarrow & \dots & \downarrow \end{bmatrix},$$

show that we can rewrite the optimization problem in Equation (7) as:

$$(\vec{w}_1^*, \dots, \vec{w}_r^*) = \operatorname{argmin}_{\substack{\|\vec{w}_i\|_2=1 \\ \langle \vec{w}_i, \vec{w}_j \rangle = 0 \ \forall i \neq j \\ 1 \leq i, j \leq r}} \|Z - WW^\top Z\|_F^2. \quad (8)$$

Next, we will solve the optimization problem in Equation (8) using the SVD of Z .

(b) Let σ_i refer to the i^{th} largest singular value of Z , and $l = \min(n, d)$. First **show** that,

$$\min_{\substack{\|\vec{w}_i\|_2=1 \\ \langle \vec{w}_i, \vec{w}_j \rangle = 0 \ \forall i \neq j \\ 1 \leq i, j \leq r}} \|Z - WW^\top Z\|_F^2 \geq \sum_{i=r+1}^l \sigma_i^2.$$

(c) Again σ_i refers to the i^{th} largest singular value of Z , and $l = \min(n, d)$. **Show** that,

$$\min_{\substack{\|\vec{w}_i\|_2=1 \\ \langle \vec{w}_i, \vec{w}_j \rangle = 0 \ \forall i \neq j \\ 1 \leq i, j \leq r}} \|Z - WW^\top Z\|_F^2 \leq \sum_{i=r+1}^l \sigma_i^2.$$

Hint: Find a W that achieves this upper bound.