Package 'volesti'

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Type Package
License GPL (>= 2)
Title Volume approximation using VolEsti and CV algorithms.
Description Package provides C++ code and a Rcpp interface for volume approxiation. The main function takes as input a H-polytope or a V-polytope and apply VolEsti or CV algorithm.
Maintainer Fisikopoulos Vissarion <pre><vissarion.fysikopoulos@oracle.com< pre="">, Chalkis Aposto- los <tolis.chal@gmail.com< pre=""></tolis.chal@gmail.com<></vissarion.fysikopoulos@oracle.com<></pre>
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Imports Rcpp (>= 0.12.17)
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Author Fisikopoulos Vissarion [cph, cre, aut], Chalkis Apostolos [cph, ctb, aut] (Contribution and development, as part of Google Summer of Code 2018 program)
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CheBall

Compute the Chebychev ball of a H-polytope, P := Ax < =b

Description

Compute the Chebychev ball of a H-polytope, P:= Ax<=b

Usage

```
CheBall(A, b)
```

Arguments

A the matrix of the H-polytope

b the vector with the constants of the hyperplanes

Value

The Chebychev center of the Polytope discribed by the matrix A and the vector b

Examples

```
CheBall(A,b)
```

demoVolEsti

Run some experiments

Description

Run some experiments

Usage

```
demoVolEsti()
```

Value

Print the computed volumes and the total time

Examples

```
testRvolEsti()
```

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ineToMatrix

functiion to get a ine file and return matrix A in ine format for VolEsti()

Description

functiion to get a ine file and return matrix A in ine format for VolEsti()

Usage

```
ineToMatrix(P)
```

Arguments

Ρ

It is in format, read.cs('path/to/file.ine'). The ine file describies the H-polytope

Value

The numerical matrix in ine format of read.cs('path/to/file.ine')

Examples

```
ineToMatrix(read.cs('path/to/data/cube40.ine'))
```

modifyMat

takes a numerical matrix in ine format and return numerical matrix A and vector b: Ax<=b

Description

takes a numerical matrix in ine format and return numerical matrix A and vector b: Ax<=b

Usage

```
modifyMat(A)
```

Arguments

Α

the numerical matrix in ine format of the H-polytope

Value

```
numerical matrix A and vector b: Ax<=b
```

Examples

```
modifyMat(A)
```

VolEsti VolEsti

VolEsti	The main R function for volume approximation of a convex H-Polytope

Description

The main R function for volume approximation of a convex H-Polytope

Usage

VolEsti(Inputs)

Arguments

matrix", "vector", "Chebychev", "verbose", "coordinate", "rounding", "Walk_length", " A list that includes alla the parameters of the algorithm
The path to an ine or ext file that describes the H-polytope. If path is given then "matrix" and "vector" inputs are not needed
The matrix A of the polytope. If it is in ine format then the input "vector" is not needed
The vector b that containes the constants of the hyperplanes
Optional. Declare the number of the steps for the random walk, default is 10+d/10
Optional. Declare the goal for the approximation error. Default is 1 for volesti and 0.2 for CV.
Optional. A d+1 vector that containes the chebychev center in the first d coordinates and the radius of the chebychev ball in the last coordinate
Optional. A boolean parameter to use CV algorithm. Default value is false.
Optional. The size of the window for the ratios' approximation in CV algorithm. Default value is win_len=4*(dimension^2)+500
Optional. a constant for the upper boud of variance/mean^2 in schedule annealing
optional. The number of points we sample in each step of schedule annealing in CV algorithm. Default value is N=500*C+(dimension^2)/2
Optional. parameter of schedule annealing, larger ratio means larger steps in schedule annealing. Default value is ratio=1-1/dimension
Optional. the fraction of the total error to spend in the first gaussian. Default value is frac=0.1
Optional. Boolean parameter to use ball walk, only for CV algorithm .Default value is False
Optional. The radius for the ball walk
Optional. A boolean parameter for printing. Default is False
A boolean parameter, has to be true when a V-polytope is given as input

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coordinate Optional. A boolean parameter for the hit-and-run. True for Coordinate Direc-

tions HnR, false for Random Directions HnR. Default value is True

rounding Optional. A boolean parameter to activate the rounding option. Default value is

False

test Optional. A boolean parameter. Declare if the current excecution is a test or not.

Default value is False

Value

The approximation of the volume of an H-polytope

Examples

VolEsti(list("path"=/path/to/ine/file, "verbose"=TRUE))

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