

lecture 07

$$\hat{y} = g(x) = \underbrace{\bar{y}_{red}}_{b_0} + \underbrace{(\bar{y}_{green} - \bar{y}_{red})}_{b_1} x, \quad 1e + n_0 =$$

$$\sum x_i, \quad p_g = \bar{x} = \frac{n_g}{n}, \quad n_r = n - n_g$$

$$\bar{y} = \frac{1}{n} (\sum y_i) = \frac{1}{n} (\underbrace{\sum y_i}_{\text{green}} + \underbrace{\sum y_i}_{\text{red}}) = \frac{\sum y_i}{n} \cdot \frac{n_g}{n_g} + \frac{\sum y_i}{n} \cdot \frac{n_r}{n_r}$$

$$= p_g \frac{\sum y_i}{n_g} + (1 - p_g) \frac{\sum y_i}{n_r} = p_g \bar{y}_g + (1 - p_g) \bar{y}_r$$

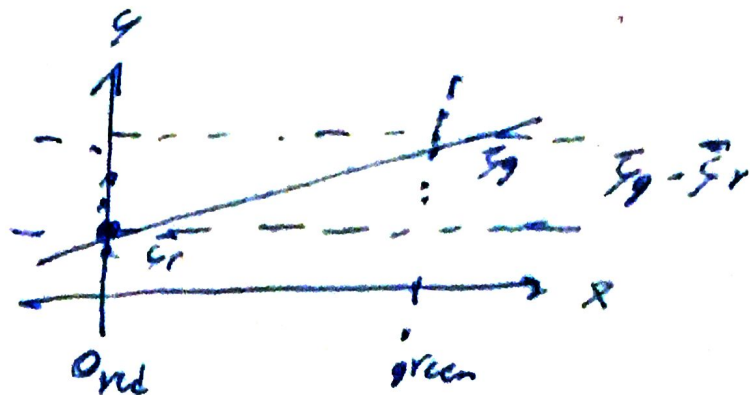
$$b_1 = \frac{\underbrace{\sum x_i y_i}_{n_g} - \underbrace{n \bar{x} \bar{y}}_{p_g}}{\underbrace{\sum x_i^2}_{n_g} - \underbrace{n \bar{x}^2}_{p_g}} = \frac{n_g \bar{y}_g - n p_g \bar{y}}{n_g - n p_g^2} \cdot \frac{1}{n} =$$

$$\frac{p_g \bar{y}_g - p_g \bar{y}}{p_g - p_g^2} = \frac{\bar{y}_g - \bar{y}}{1 - p_g}$$

$$= \frac{\bar{y}_g - (p_g \bar{y}_g + (1 - p_g) \bar{y}_r)}{1 - p_g} = \frac{(1 - p_g) \bar{y}_g - (1 - p_g) \bar{y}_r}{1 - p_g}$$

$$= \bar{y}_g - \bar{y}_r$$

$$b_0 = \bar{y} - b_1 \bar{x} = p_g \bar{y}_g + (1 - p_g) \bar{y}_r - (\bar{y}_g - \bar{y}_r) p_g = \bar{y}_r$$



What if $x \in \{\text{red, green, blue}\}$? This is then $p=2$ and we need an OLS solution for $p \geq 1$. But intuitively,

$$f(x) = \begin{cases} \bar{y}_{\text{red}} & \text{if } x = \text{red} \\ \bar{y}_{\text{green}} & \text{if } x = \text{green} \\ \bar{y}_{\text{blue}} & \text{if } x = \text{blue} \end{cases} = \underbrace{\bar{y}_{\text{red}}}_{b_0} + \underbrace{(\bar{y}_{\text{green}} - \bar{y}_{\text{red}})}_{b_1} x_1 + \underbrace{(\bar{y}_{\text{blue}} - \bar{y}_{\text{red}})}_{b_2} x_2$$

How well does g predict? We need a "model performance metric". In the SVM this was accuracy or misclassification error. Here it will can also be what we use internally, in the algorithm

$$SSE := \sum_{i=1}^n e_i^2 = \sum (y_i - g(x_i))^2$$

Is SSE interpretable? No, let's take the mean at least, call that mean squared error (MSE):

$$MSE = \frac{1}{n-2} SSE$$

But this is still 1 - the squared unit of the phenomenon so it's still uninterpretable. We can take the squared root of MSE called root mean squared error (RMSE)

$$s_e = \text{RMSE} = \sqrt{\frac{1}{n-1} \sum e_i^2} = \sqrt{\text{MSE}}$$

RMSE is in the same unit as y (it's akin to the standard deviation of the residuals & also from the CLT)

$$[y(x) \pm 1.96 \cdot \text{RMSE}]$$

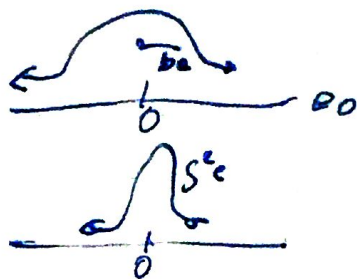
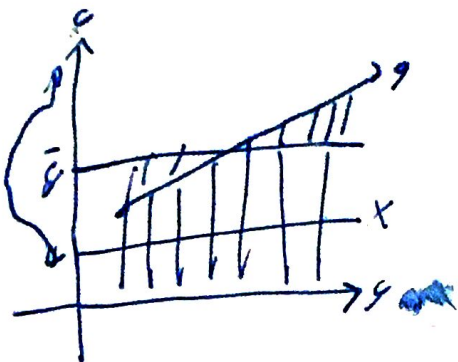
is approx a 95% confidence interval for the true y at that x . RMSE is a very important metric in regression models.

Another important error / performance metric is "R-squared", which is the "proportion of variance explained". We will now explain this definition

Consider the null model $y_0 = \bar{y}$. What is the SSE of this model? Let's call it SSE_0

$$\text{SSE}_0 = \sum_{i=1}^n e_{0,i}^2 = \sum_{i=1}^n (y_i - \bar{y})^2 = \text{SST} = (n-1) s_y^2$$

Sum of squares total

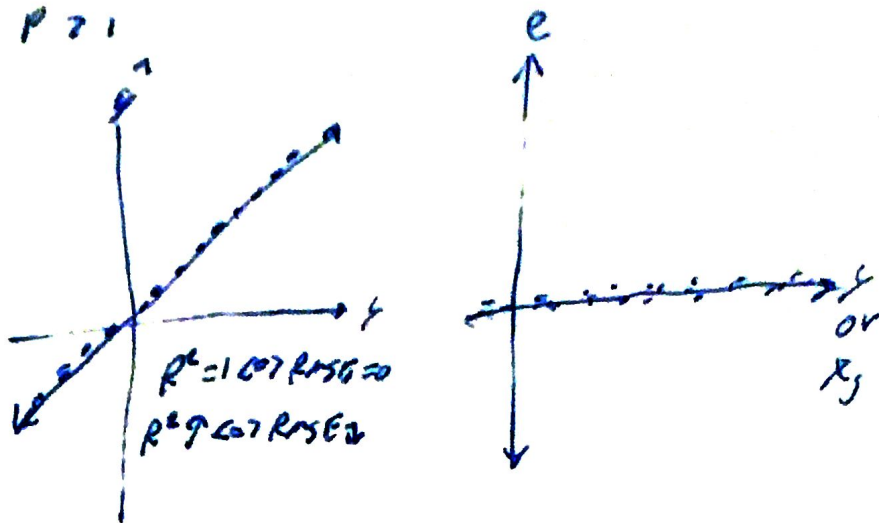


$$\frac{\text{SSE}}{\text{SST}} = \frac{(n-1) s_e^2}{(n-1) s_y^2} = \frac{s_e^2}{s_y^2}$$

$$R^2 = \frac{\text{SST} - \text{SSE}}{\text{SST}} = \frac{(n-1) s_y^2 - (n-1) s_e^2}{(n-1) s_y^2} = \frac{s_y^2 - s_e^2}{s_y^2} = \frac{\Delta s^2}{s_y^2}$$

R^2 -squared can never be more than 100%. But R^2 -squared can be negative. This occurs when $S^2 < \bar{y}^2$ meaning the model is probably worse than $y = \bar{y}$

Here's some other useful plots especially when $p \geq 1$



If $R^2 = 99\%$, does this mean the model is for a while good? No because if the initial variance was so very large, even a 99% reduction wouldn't result in a small residual variance i.e. $RMSE$ still could be high after 99% variance reduction.

We now would like to generalize the least squares estimation algorithm to cases where $p \geq 1$. Let's begin with $p = 2$.

$$H = \{w_0 + w_1 x_1 + w_2 x_2 : \underbrace{w_0, w_1, w_2}_{\in \mathbb{R}^3} \in \mathbb{R}\}$$

$$SSE = \sum_{i=1}^n e_i^2 = \sum_{i=1}^n (y_i - \hat{y}_i)^2 = \sum_{i=1}^n (y_i - w_0 - w_1 x_{1,i} - w_2 x_{2,i})^2$$

As arguments $\{ \vec{a}, b, \vec{a} \}$ arguments $\{ \vec{a}, b, \vec{a} \}$
 $w_1 \in R$ $w_2 \in R$ $w_3 \in R$

The problem can be solved more simply with matrix algebra and a vector notation.

$$D = \{ X, \vec{y} \}, \text{ let } X = \begin{bmatrix} \vec{x}_1 & \vec{x}_2 & \vec{x}_3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & x_{11} & x_{12} \\ 1 & x_{21} & x_{22} \\ 1 & x_{31} & x_{32} \\ \vdots & \vdots & \vdots \\ 1 & x_{n1} & x_{n2} \end{bmatrix} \quad \text{eq } \vec{y} = X\vec{\beta}, \vec{\beta} = \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix}$$

$$\vec{\hat{y}} = X\vec{\hat{\beta}} = \begin{bmatrix} w_0 + w_1 x_{11} + w_2 x_{12} \\ w_0 + w_1 x_{21} + w_2 x_{22} \\ \vdots \\ w_0 + w_1 x_{n1} + w_2 x_{n2} \end{bmatrix}$$

$$\text{define } \vec{e} := \vec{y} - \vec{\hat{y}}$$

$$SSE = \sum_{i=1}^n e_i^2 = \vec{e}^T \vec{e} = (\vec{y} - \vec{\hat{y}})^T (\vec{y} - \vec{\hat{y}}) = (\vec{y}^T \vec{y} -$$

$$(\vec{y} - \vec{\hat{y}})^T$$

$$= \vec{y}^T \vec{y} - \vec{y}^T \vec{\hat{y}} + \vec{\hat{y}}^T \vec{y} - \vec{\hat{y}}^T \vec{\hat{y}} = \vec{y}^T \vec{y} - 2 \vec{y}^T \vec{\hat{y}} +$$

$$\vec{\hat{y}}^T \vec{\hat{y}}$$

$$= \vec{y}^T \vec{y} - 2(\lambda \vec{w})^T \vec{y} + (\lambda \vec{w})^T \lambda \vec{w} =$$

$$= \vec{y}^T \vec{y} - 2\vec{w}^T X^T \vec{y} + \vec{w}^T X^T X \vec{w}$$