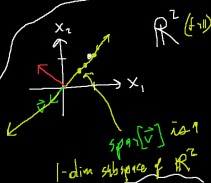


$$\vec{b} = (X^T X)^{-1} X^T \vec{y}, \text{ the OLS linear model, } \hat{\vec{y}} = X \vec{b}, g(\vec{x}_0) = \hat{y}_0 = \vec{x}_0 \vec{b}$$

What if we have no features? i.e. the null model case. Is there an OLS solution?

$$X = [\vec{1}_n] = \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}$$

$$\vec{b} = b_0 = \underbrace{(X^T X)^{-1}}_{\underbrace{\begin{bmatrix} 1 & \dots & 1 \\ \vdots & & \vdots \\ 1 & \dots & 1 \end{bmatrix}}_n \underbrace{X^T \vec{y}}_{\sum y_i}} = \frac{\sum y_i}{n} = \bar{y} = g_0$$

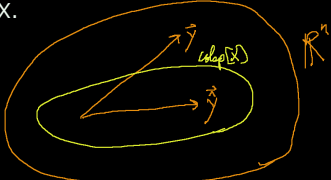


$$p+1 = \text{rank}[X] = \dim[\text{colsp}[X]]$$

$$\text{colsp}[X] := \text{span}[\vec{1}, \vec{x}_1, \dots, \vec{x}_p] := \left\{ w_0 \vec{1}_n + w_1 \vec{x}_1 + \dots + w_p \vec{x}_p : w_0, w_1, \dots, w_p \in \mathbb{R} \right\}$$

$p+1 < n$ dimensional subspace of the entire n -dimensional "full space" (the number of dimensions of y which is n , the number of rows of X).

$$\vec{y} \in \text{colsp}[X]? \quad \text{YES}$$



$$\vec{y} = X \vec{b} = X (X^T X)^{-1} X^T \vec{y} = H \vec{y}$$

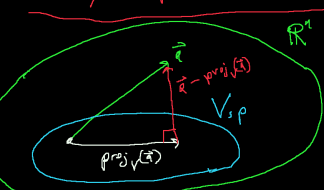
$$H \in \mathbb{R}^{n \times n}$$

H for "hat" matrix, the linear operator turning y -vec into \hat{y} -vec.

$$X \vec{b} \in \text{colsp}[X]$$

$$\Downarrow$$

$$H \vec{y} \in \text{colsp}[X] \Rightarrow \text{rank}[H] = p+1 \Rightarrow H \text{ is not invertible}$$



V is a K -dim subspace of the n -dim full space.

We want to "project" a y -vec onto V such that the difference between y -vec and its projection is perpendicular. This is called an "orthogonal projection". We want a formula for this projection as a function of the space V .

$$V_{sp} = \text{span} \{ \vec{v}_1, \dots, \vec{v}_K \}, K < n$$

$$\text{proj}_V(\vec{x}) \in \text{span} \{ \vec{v}_1, \dots, \vec{v}_K \} \Rightarrow \exists \vec{w}$$

$$\text{proj}_V(\vec{x}) = w_1 \vec{v}_1 + \dots + w_K \vec{v}_K = V \vec{w}$$

$$\text{s.t. } V = [\vec{v}_1 | \dots | \vec{v}_K], \vec{w} \in \mathbb{R}^K$$

due to the orthogonal constraint, $\vec{x} - \text{proj}_V(\vec{x}) \perp \vec{v}_j \quad \forall j$

$$\Rightarrow (\vec{x} - V \vec{w})^T \vec{v}_j = 0 \quad \forall j \Leftrightarrow \vec{v}_j^T (\vec{x} - V \vec{w}) = 0 \quad \forall j$$

$$\Rightarrow \begin{cases} \vec{v}_1^T (\vec{x} - V \vec{w}) = 0 \\ \vec{v}_2^T (\vec{x} - V \vec{w}) = 0 \\ \vdots \\ \vec{v}_K^T (\vec{x} - V \vec{w}) = 0 \end{cases} \Rightarrow \begin{bmatrix} \vec{v}_1^T \\ \vec{v}_2^T \\ \vdots \\ \vec{v}_K^T \end{bmatrix} (\vec{x} - V \vec{w}) = \vec{0}_K \Rightarrow V^T (\vec{x} - V \vec{w}) = \vec{0}_K$$

$$\Rightarrow V^T \vec{x} - V^T V \vec{w} = \vec{0}_K \Rightarrow (V^T V)^{-1} V^T V \vec{w} = V^T \vec{x} \Rightarrow \vec{w} = (V^T V)^{-1} V^T \vec{x}$$

$$\text{proj}_V(\vec{x}) = V \vec{w} = \underbrace{V (V^T V)^{-1} V^T}_{H} \vec{x} = H \vec{x}$$

We call the $n \times n$ matrix H the orthogonal projection matrix onto the subspace $V_{sp} = \text{colsp}[V]$.

orthogonal projection onto $\text{colsp}[V]$

$$H = X (X^T X)^{-1} X^T \text{ is the orthogonal projection matrix onto } \text{colsp}[X].$$

Properties that define orthogonal projection matrices, H

(1) H is symmetric, $H^T = H$

$$H^T = (V (V^T V)^{-1} V^T)^T = V^T ((V^T V)^{-1})^T V^T = V^T (V^T V)^{-1} V^T = V^T (V^T V)^{-1} V^T = H \quad \checkmark$$

Let A be square, invertible and symmetric

$$A^T A = I \Rightarrow (A^T A)^T = I^T = I \Rightarrow A^T (A^T)^T = I \Rightarrow (A^T)^T = (A^T)^{-1}$$

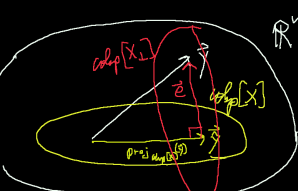
(2) H is idempotent, i.e. $HH = H$

$$HH = (V (V^T V)^{-1} V^T) (V (V^T V)^{-1} V^T) = V \cancel{(V^T V)^{-1}} (V^T V) \cancel{(V^T V)^{-1}} V^T = V (V^T V)^{-1} V^T = H \quad \checkmark$$

$$\text{proj}_V(\text{proj}_V \vec{x}) = \text{proj}_V(H \vec{x}) = H H \vec{x} = H \vec{x} = \text{proj}_V(\vec{x})$$

$$\hat{\vec{y}} = H \vec{y} = \text{proj}_{\text{colsp}[X]}(\vec{y})$$

$$\vec{y} = \hat{\vec{y}} + \vec{e}, \quad \vec{y} \cdot \vec{e} = 0$$



$$\vec{e} = \vec{y} - \hat{\vec{y}} = \vec{y} - H \vec{y} = (I - H) \vec{y}$$

$$\begin{aligned} \vec{y} \cdot \vec{e} &= (H \vec{y})^T (I - H) \vec{y} = \vec{y}^T H^T (I - H) \vec{y} \\ &= \vec{y}^T H (I - H) \vec{y} = \vec{y}^T H I \vec{y} - \vec{y}^T H H \vec{y} \\ &= \vec{y}^T H \vec{y} - \vec{y}^T H \vec{y} = 0 \end{aligned}$$

Let's verify $I-H$ is a projection matrix by demonstrating that it is (1) symmetric and (2) idempotent.

$$(I - H)^T = I^T - H^T = I - H \quad \checkmark$$

$$(I - H)(I - H) = I I - I H - H I + H H = I - H - H + H = I - H \quad \checkmark$$

$$\begin{aligned} (I - H) \vec{e} &= \vec{e} \\ H \vec{e} &= \vec{0}_n \\ (I - H) \hat{\vec{y}} &= \vec{0}_n \\ H \hat{\vec{y}} &= \hat{\vec{y}} \end{aligned}$$

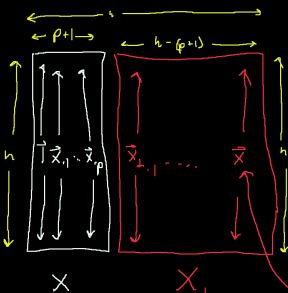
$$\text{colsp}[X] \oplus \text{colsp}[X_{\perp}] = \mathbb{R}^n$$

the "residual space" since it's the space the residuals e -vec live inside.

$$\text{rank}[X] = p+1, \quad \text{rank}[X_{\perp}] = n - (p+1)$$

$$\text{rank}[X] + \text{rank}[X_{\perp}] = n$$

degrees of freedom of the residuals



The column vectors in X_{\perp} are vectors that span the "rest of the space". They're not unique. And you can construct them computationally.

\vec{x}_{\perp} the last column in X_{\perp}