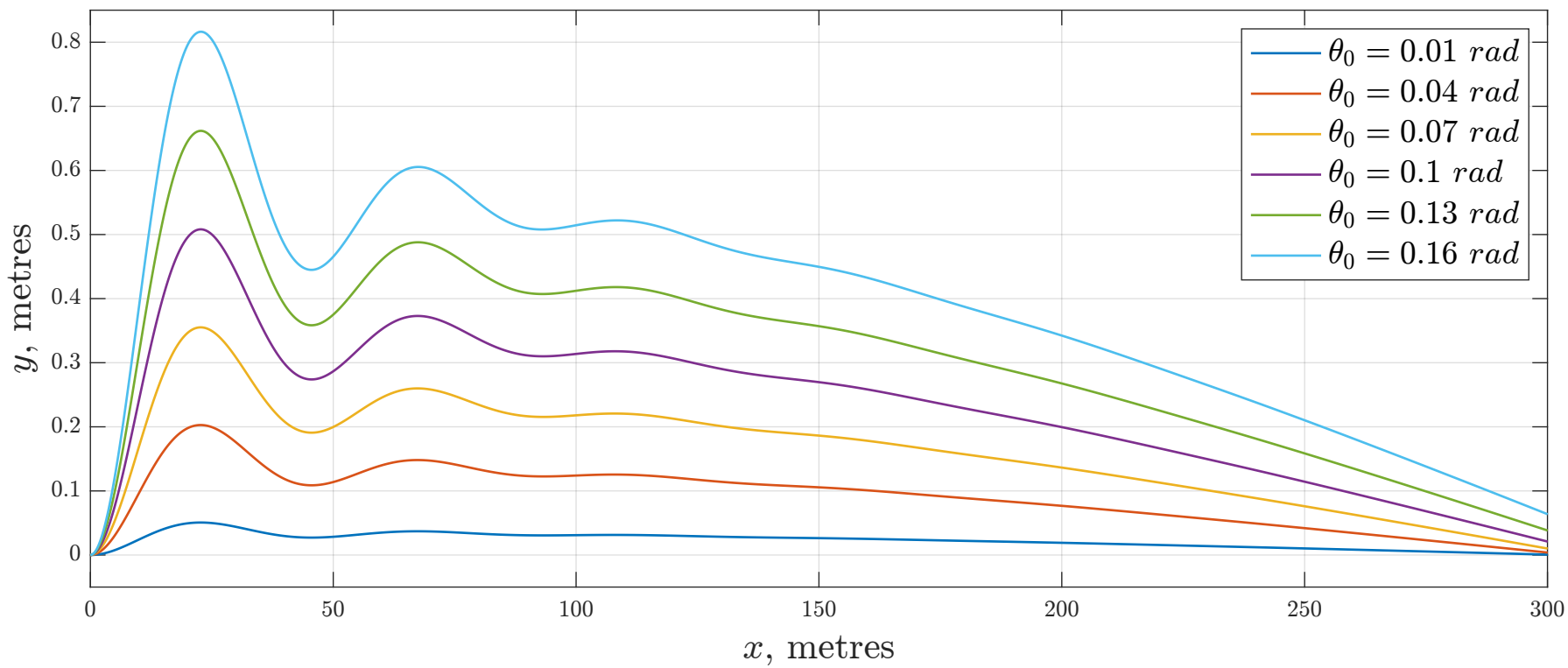


Trajectory  $y - x$



Trajectory  $y - x$

