

### Carousel APP control

**! Note: Due to the building block structure, the carousel only supports clockwise rotation. That is, the speed needs to be set to -255 during programming, and cannot be set to a positive number.**

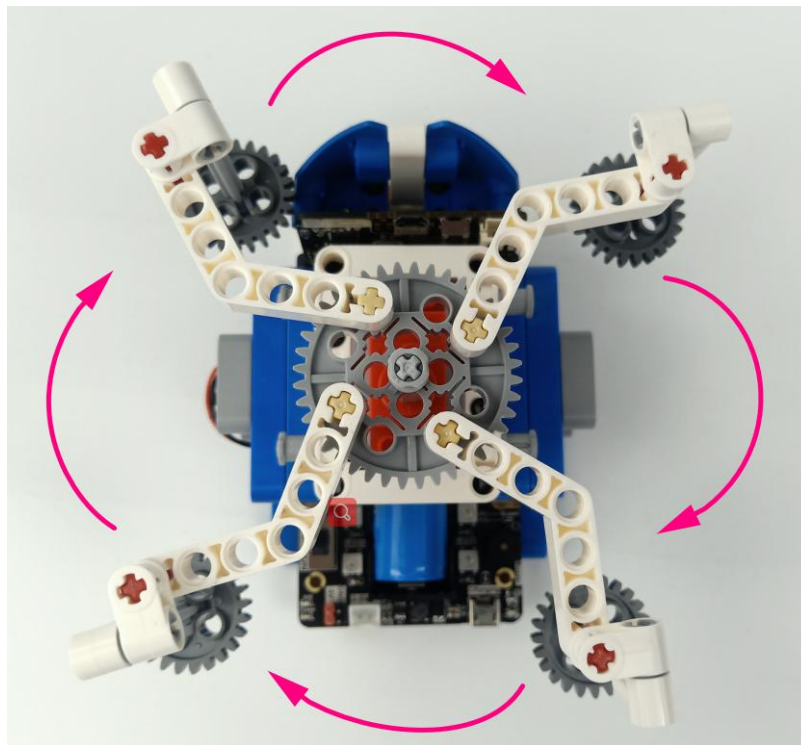
#### 1.Learning goals

In this course, we mainly learn how to use APP control Carousel .

#### 2.Building block assembly steps

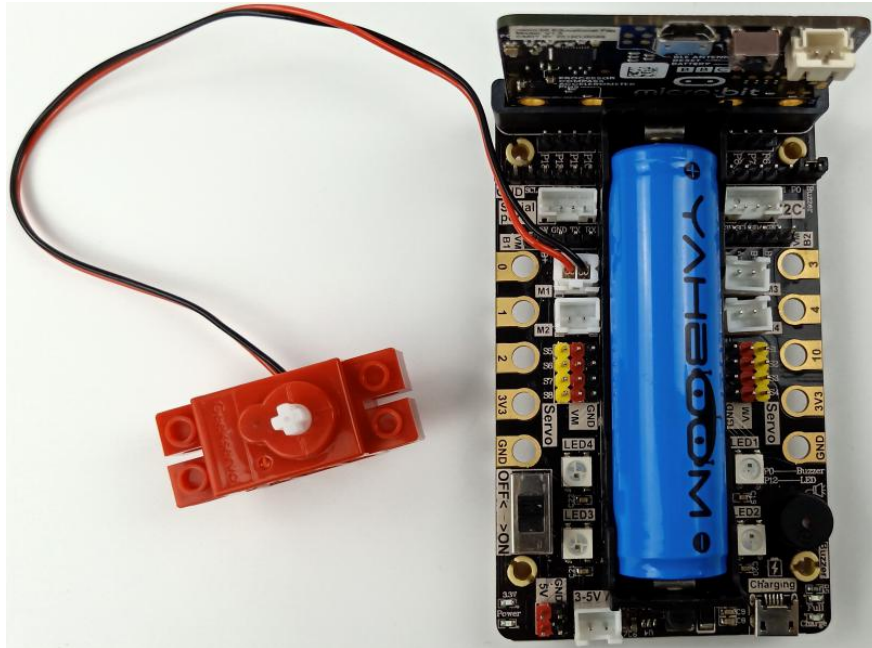
For the building block construction steps, please refer to the installation manual or building block installation picture of [Assembly course]-[Biped robot].

**Please make sure that the direction of the L-shaped hole, as shown below.**



#### 3.Wiring of motor

The motor wiring is inserted into the M1 interface of the Super:bit expansion board, and the black wire is close to the battery side;  
As shown below.



#### 4.Programming method

**Mode 1 online programming:** First, we need to connect the micro:bit to the computer by USB cable. The computer will pop up a USB flash drive and click on the URL in the USB flash drive: <http://microbit.org/> to enter the programming interface. Add the Yahboom package <https://github.com/lzty634158/SuperBit> to program.

**Mode 2 offline programming:** We need to open the offline programming software. After the installation is complete, enter the programming interface, click 【New Project】 , add Yahboom package: <https://github.com/lzty634158/SuperBit>, you can program.

#### 4.About code

The summary program of this course can be viewed by opening the hex we provided on the MakeCode programming interface.

#### 5.Download APP

Android users scan the following QR code by browser or search "Mbit" in Play Store to download APP;

iOS users scan the following QR code by camera or search "Mbit" in App Store to download APP.



IOS

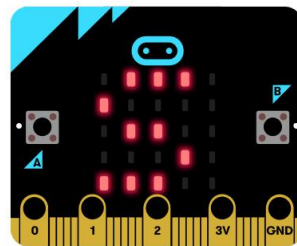


Android

Note: If there are any prompts on the phone during installation, please select "Allow".

## 6. APP remote control

1) After the program is downloaded successfully, turn on the power switch of the car, the micro: bit dot matrix will display the "S" pattern, as shown below, this is the state of Bluetooth not connected.



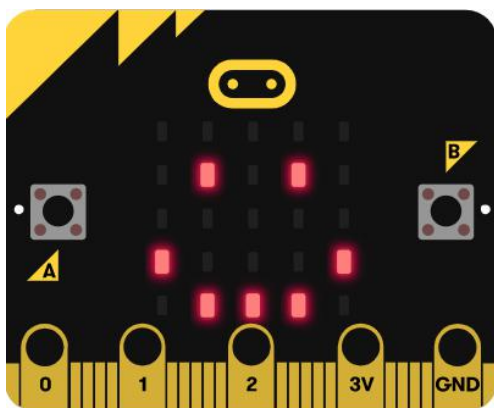
2) Open the Bluetooth of your mobile phone, and open the Bluetooth APP. You can see the interface as shown below. At the same time, you can see the Bluetooth signal in the upper left corner.



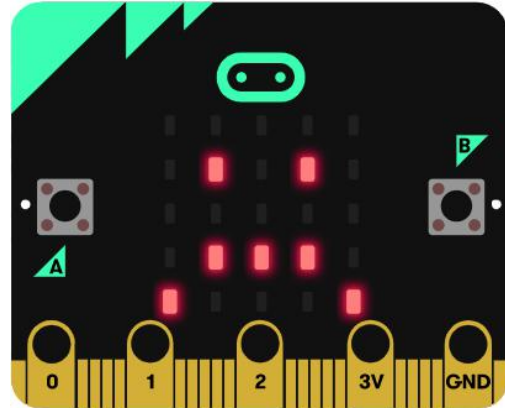
3) Mobile phone close to robot Bluetooth automatic connection. If Bluetooth can't connect automatically, you need to click **【CONNECT】** to connect the Bluetooth between the phone and the robot.



After Bluetooth connection successfully, micro:bit dot matrix will display a smile pattern. If Bluetooth disconnect, it will display a cry pattern.



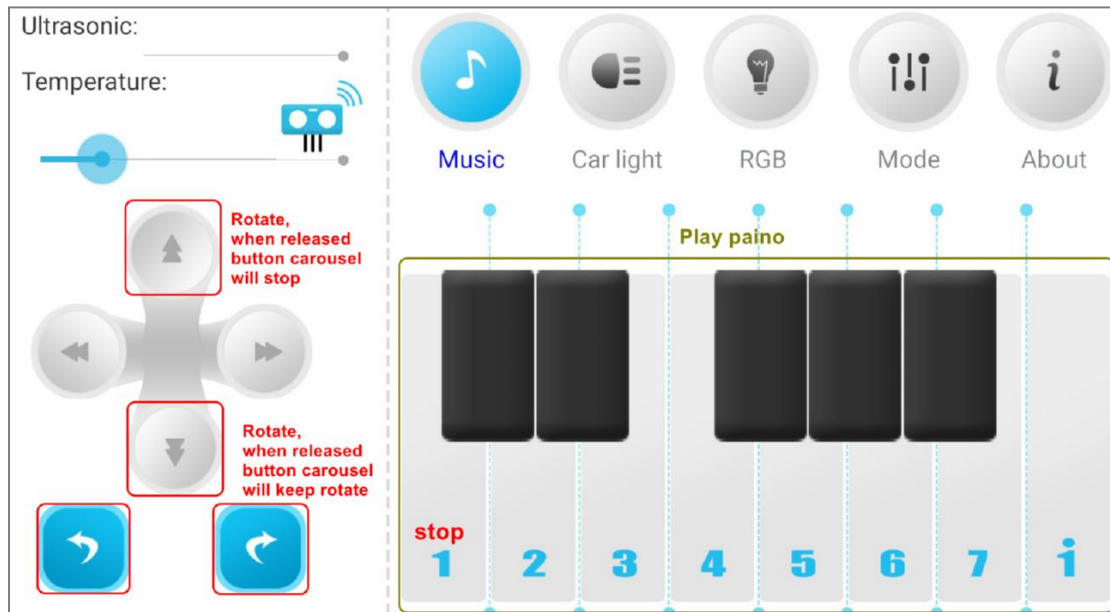
【Bluetooth be connected】



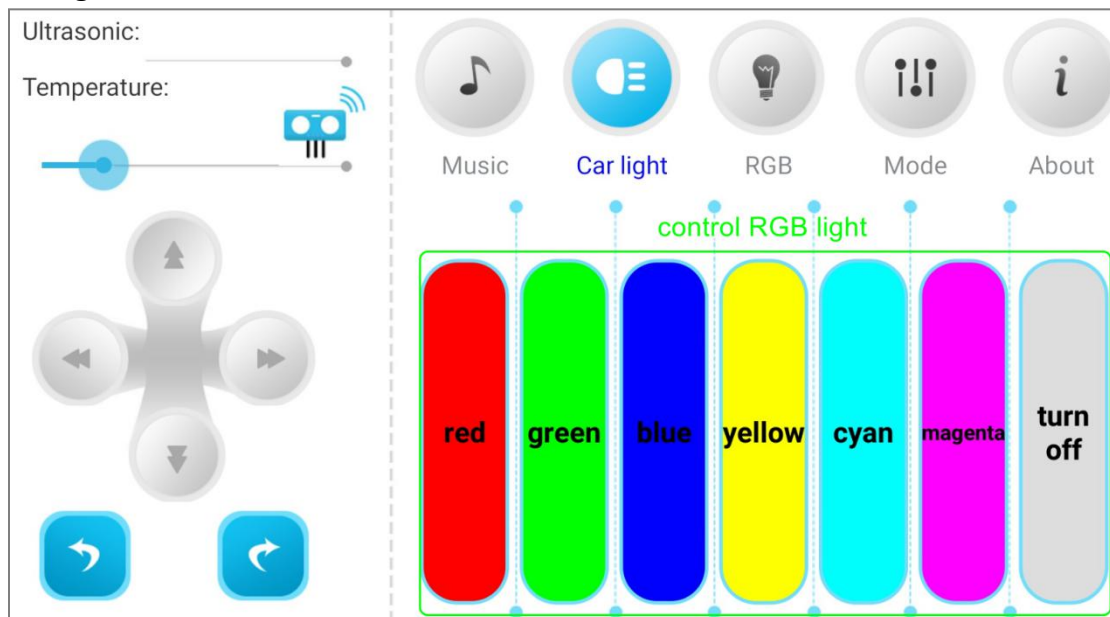
【Bluetooth disconnect】

Main control interface:

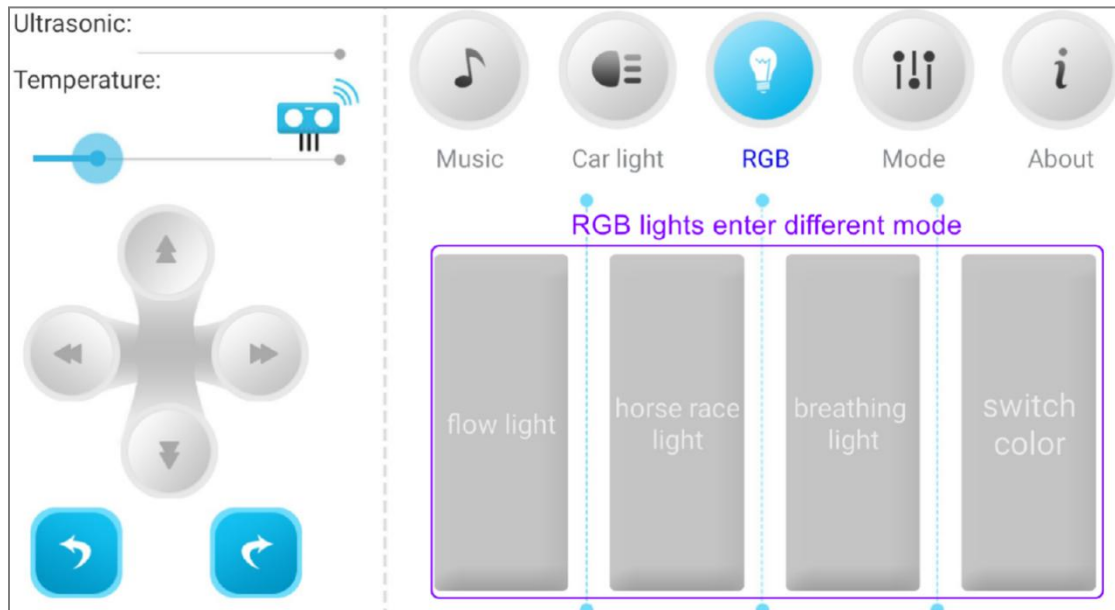
- Forward button controls the carousel to rotate, when release button it will stop;
- Back button controls the carousel to rotate, when release button it will keep rotate;
- Press the piano 1 keys to stop carousel.
- Press the piano keys to make buzzer play different tones.



### Car light interface



### RGB interface



**!Note: Mode option is unavailable.**