

Oscillating fan Micro:bit handle control

1.Learning goals

In this course, we mainly learn how to use handle control Oscillating fan.

2.Building block assembly steps

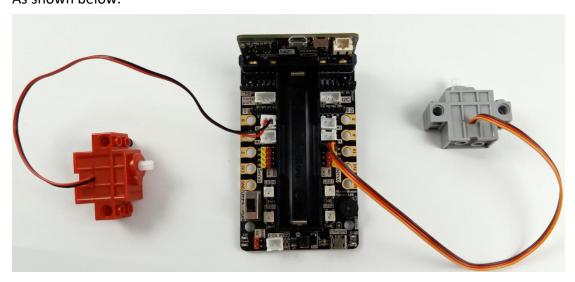
For the building block construction steps, please refer to the installation manual or building block installation picture of [Assembly course]-[Oscillating fan].

3. Wiring of motor and servo

The motor wiring is inserted into the M1 interface of the Super:bit expansion board, and the black wire is close to the battery side;

Building block servo insert into the Super:bit expansion board S1 interface, and the orange wiring connect the yellow pin of S1.

As shown below.



4. Programming method

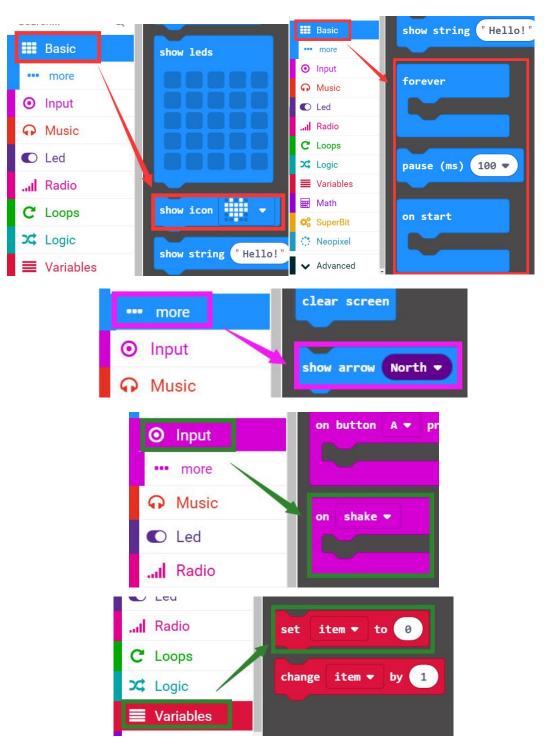
Mode 1 online programming: First, we need to connect the micro:bit to the computer by USB cable. The computer will pop up a USB flash drive and click on the URL in the USB flash drive: http://microbit.org/ to enter the programming interface. Add the Yahboom package https://github.com/lzty634158/GHBit to program.

Mode 2 offline programming: We need to open the offline programming software. After the installation is complete, enter the programming interface, click [New Project], add Yahboom package: https://github.com/lzty634158/SuperBit and https://github.com/lzty634158/GHBit, you can program.

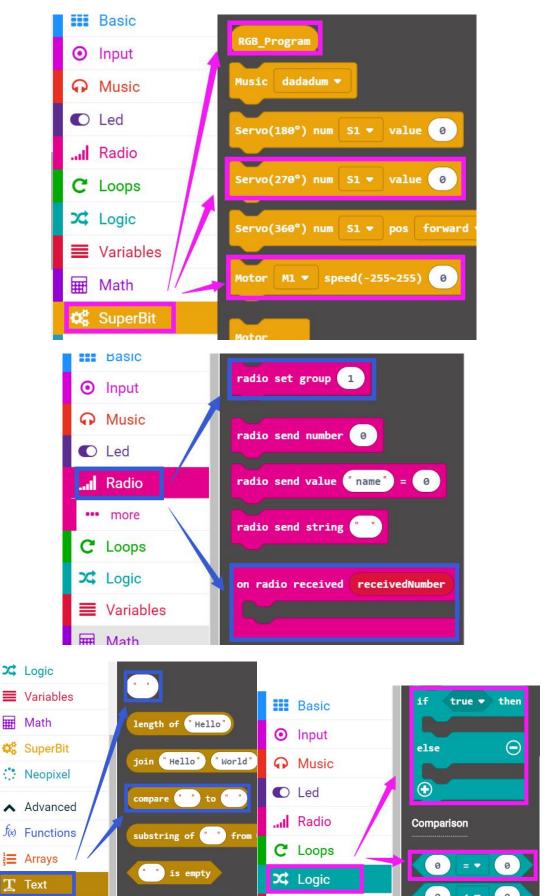
5.Looking for blocks

The following is the location of the building blocks required for this programming.

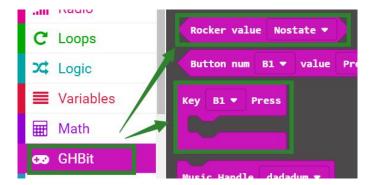






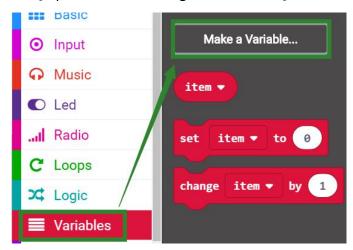






How to create a new variable

1) Find the [Variable] option in the building block column-[Make a Variable]

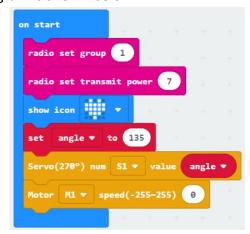


2) Enter the name of variable to complete the new variable.



6.Combine block

The Oscillating fan program is shown below.

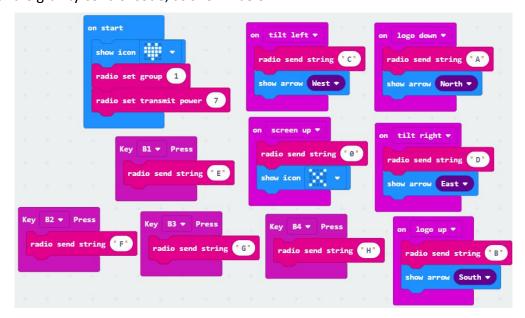




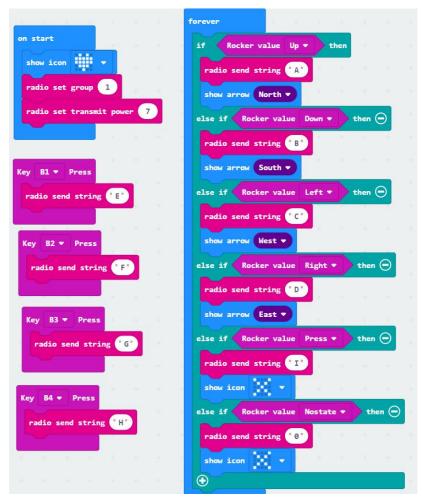
```
on radio received receivedString .
 set item ▼ to receivedString ▼
        compare item ▼ to ('E') = ▼ 0
                                            then
       RGB_Program show color red ▼
       RGB_Program show
   Servo(270°) num 51 ♥ value 0
          compare item ▼ to ('F') = ▼ 0
 else if
                                             then 😑
       RGB_Program show color green ▼
       RGB_Program show
   Servo(270°) num S1 ▼ value 135
                                               then 😑
          compare item ▼ to "G" = ▼ 0
 else if
       RGB_Program show color blue ▼
       RGB_Program show
          compare item ▼ to "H" = ▼ 0
                                               then 😑
 else if
       RGB_Program show color yellow *
       RGB_Program show
   Servo(270°) num | S1 ▼ | value | 270
          compare item ▼ to "A" = ▼ 0
 else if
                                               then 🕣
   Motor M1 ▼ speed(-255~255) 255
          compare item ▼ to "B"
                                   = - 8
 else if
                                               then 😑
  Motor M1 ▼ speed(-255~255) -255
 else if
          compare item ▼ to 'I' = ▼ 0
                                               then 😑
       RGB_Program clear
       RGB_Program show
 else
   Motor M1 ▼ speed(-255~255) 0
```



Handle gravity control code, as shown below.



Handle rocker control code, as shown below.



7. Experimental phenomena

We need to download the Oscillating fan code into the micro:bit board of the Oscillating fan. Open the power switch of the Oscillating fan, we can see a heart



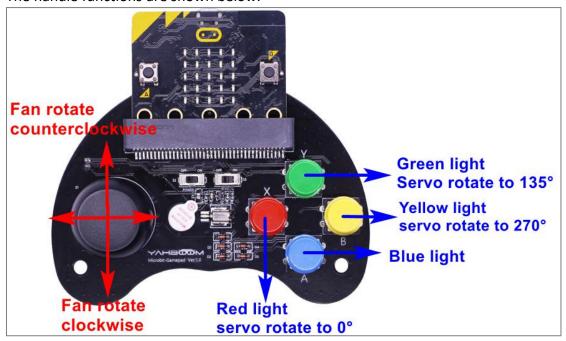
pattern displayed on the micro:bit dot matrix;

We need to download the Handle code into the micro:bit board of the handle.

Open the power switch of the handle, we can see that the micro: bit dot matrix will initially display a heart pattern, and then display an "X" pattern, indicating that the handle is in the default(no data is sent).

They will automatically pairing, then, we can start remote control the Oscillating fan by handle.

The handle functions are shown below.



! Note:

In case of handle rocker control, press the rocker to control the RGB light closed. In case of handle gravity control, this function is not available.