

## Dancing and singing

## 1.Learning goals

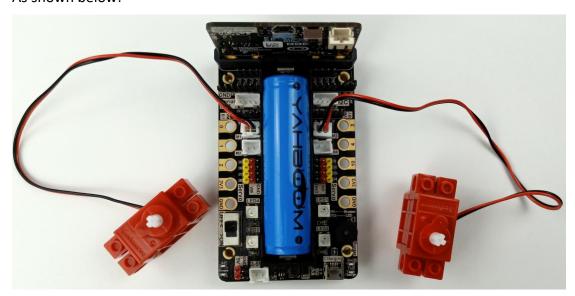
In this course, we mainly learn how to use the MakeCode graphical programming to realize the "singing" and "dancing" of the Freestyle, that is, the motor, buzzer and RGB lights work simultaneously.

## 2.Building block assembly steps

For the building block construction steps, please refer to the installation manual or building block installation picture of [Assembly course]-[Freestyle].

# 3. Wiring of motor and servo

The motor wiring on the left side of the freestyle is inserted into the M1 interface of the Super:bit expansion board, and the black wire is close to the battery side; The motor wiring on the right side of the freestyle is inserted into the M3 interface of the Super:bit expansion board, and the black wire is close to the battery side; As shown below:



# 4. Programming method

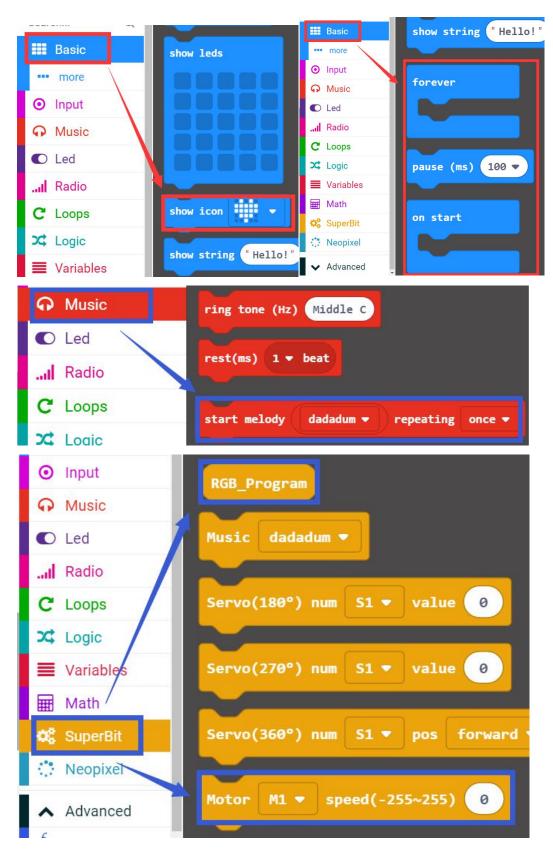
**Mode 1 online programming:** First, we need to connect the micro:bit to the computer by USB cable. The computer will pop up a USB flash drive and click on the URL in the USB flash drive: <a href="http://microbit.org/">http://microbit.org/</a> to enter the programming interface. Add the Yahboom package <a href="https://github.com/lzty634158/SuperBit\_">https://github.com/lzty634158/SuperBit\_</a> to program.

Mode 2 offline programming: We need to open the offline programming software. After the installation is complete, enter the programming interface, click \[ \text{New Project } \], add Yahboom package: \[ \text{https://github.com/lzty634158/SuperBit}, you can program. \]

## 5.Looking for blocks

The following is the location of the building blocks required for this programming.









#### 6.Combine block

The summary program is shown below.

```
on start

show icon

start melody ode ▼ repeating forever in background ▼
```



```
forever
      RGB_Program show color red ▼
      RGB_Program show
 Motor M1 ▼ speed(-255~255) 255
 Motor M3 ▼ speed(-255~255) 255
 pause (ms) 500 ▼
      RGB_Program show color green ▼
      RGB_Program
 Motor M1 ▼ speed(-255~255) -255
 Motor M3 ▼ speed(-255~255) -255
 pause (ms) 500 ▼
      RGB_Program show color blue ▼
      RGB_Program
                  show
 Motor M1 ▼ speed(-255~255) -255
 Motor M3 ▼ speed(-255~255) 255
 pause (ms) 1000 ▼
      RGB_Program show color violet ▼
      RGB_Program
```

```
Motor M1 ▼ speed(-255~255) 255
Motor M3 ▼ speed(-255~255) -255
pause (ms) 1000 ♥
     RGB_Program show color red ▼
     RGB_Program show
Motor M1 ▼ speed(-255~255) -255
Motor M3 ▼ speed(-255~255) 255
pause (ms) 200 ▼
     RGB_Program show color green ▼
     RGB_Program show
Motor M1 ▼ speed(-255~255) 255
Motor M3 ▼ speed(-255~255) -255
pause (ms) 200 ▼
     RGB Program show color blue ▼
     RGB_Program show
Motor M1 ▼ speed(-255~255) 255
Motor M3 ▼ speed(-255~255) 0
pause (ms) 500 ▼
```

```
RGB_Program show

RGB_Program show

Motor M1 ▼ speed(-255~255) 0

Motor M3 ▼ speed(-255~255) 255

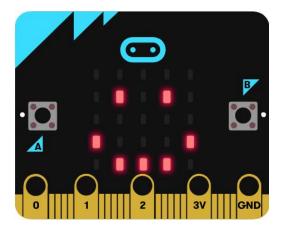
pause (ms) 500 ▼
```

## 7.Experimental phenomena

After the program is successfully downloaded, the micro: bit dot matrix will display the smile pattern, as shown below. Open the power switch, the Freestyle robot will play the music "Ode", and freestyle will move forward-> backward-> spin left -> spin



right switch different motion states, RGB lights will switch to different colors.



If you need to restart, press the reset button on the back of the micro:bit board.