

Note: my own additions (besides notation) are in **purple**. Proceed with caution.

A topology on X is a set of open sets $T \subseteq \mathcal{P}(X)$ such that:

- $X \in T$
- $\emptyset \in T$
- T is closed under arbitrary unions
- T is closed under finite intersections

A closed set is a complement of an open set.

Neighborhoods of p contain an open set containing p .

p is a boundary point of a set S means every open set containing p intersects both S and S^C .

A connected set is one not formed by the union of two disjoint non-empty open sets.

A Hausdorff (T_2) space is one where every pair of distinct points lie in distinct open sets.

A **Point-Spliced Linear Structure** on a set S is an ordered pair $\langle S, \Lambda \rangle$ $\Lambda \subseteq \mathcal{P}(S)$ satisfying axioms LS_1, LS_2, LS_3, LS_4

lines are elements of Λ

$LS_1: \forall \lambda (|\lambda| \geq 2)$

minimal lines are **lines** of size 2.

segment $_{\lambda}(\mu) := \mu \subseteq \lambda$ and $\mu \in \Lambda$.

point $_{\lambda}$ denotes an element of the **line** λ

(read: “segments on lambda, points on lambda”)

r **between** $_{\lambda} p, q := p, q, r \in \lambda$ and $(\text{segment}_{\lambda}(\mu) \text{ and } p, q \in \mu \Rightarrow r \in \mu)$.

Denote $p-r-q$ on $\lambda := r$ **between** $_{\lambda} p, q$ (equivalent to $q-r-p$ on λ).

For nondistinct points, e.g. $r-r-s$, the relation is false.

LS_2 : Every **line** λ admits a linear order $>$ such that $\mu \in \mathcal{P}(\lambda) \in \Lambda \iff \mu$ is an interval of $>$

LS_2^* : Equivalently, specify that for every **line** λ :

For any three distinct points p, q, r , there is exactly one choice of r for which $p-r-q$

For all **points** $_{\lambda} p, q$ the sets $PQ = \{r \in \lambda : p-r-q\}$ and $\overline{PQ} = PQ \cup \{p, q\}$ are **segments** $_{\lambda}$ (provided $|PQ| \geq 2$)

This is enough to make the betweenness relation “behave nicely”, as we have eliminated loops and forks as candidates for lines by requiring the existence of at least one r and enforced the linear order by the uniqueness of r , so we can show a proof of equivalence:

For any **segment** $_{\lambda} S$ containing p, q , we have $\overline{PQ} \subseteq S$. Supposing otherwise would mean there exists a $r \in \lambda : p-r-q$ and $r \notin S$, which contradicts S being a **segment** $_{\lambda} S$ containing p, q and the definition of $p-r-q$

Now, consider letting $p-r-s$ and $r-s-q$ on λ

LS_2^* says exactly one of $p-q-r$, $q-p-r$, or $p-r-q$ are true on λ . We have $p-q-r$ admits a **segment** $_{\lambda} \overline{PR}$ containing q . But as $r-s-q$, \overline{PR} must contain both q and s . \overline{PR} is the smallest **segment** $_{\lambda}$ containing p and r , so any **segment** $_{\lambda}$ containing p and r also contains s , i.e. $p-s-r$, contrary to the assumption that $p-r-s$. A similar case holds for $q-p-r$, leaving $p-r-q$ as the only acceptable choice to satisfy LS_2^* . Similarly, we also have $p-s-q$.

So LS_2^* justifies the notation $p-r-s-q := (p-r-s \text{ and } r-s-q)$, as all derivable true statements can be found by removing interior terms. Explicitly, this shows transitivity at both the interior and end points, so transitivity holds for all points, giving two symmetric linear orders. The

trivial exceptions of lines with 2 or 3 points are easily handled. Both open and closed intervals (corresponding to PQ and \overline{PQ} , respectively) are **segments** $_{\lambda}$, hence $\text{LS}_2^* \Rightarrow \text{LS}_2$

The other direction $\text{LS}_2 \Rightarrow \text{LS}_2^*$ is easy: identify $p > r > q$ with $p-r-q$

endpoint $_{\lambda}(x) := x \in \lambda$ and $\nexists p, q \in \lambda : p-x-q$

Denote **endpoints** $_{\lambda} = \{p : \text{endpoint}_{\lambda}(p)\}$

λ is **open** $:= |\text{endpoints}_{\lambda}| = 0$

λ is **closed** $:= |\text{endpoints}_{\lambda}| = 2$

λ is **clopen** $:= |\text{endpoints}_{\lambda}| = 1$

Theorem 2.1: A **line** can have no more than 2 **endpoints**.

Alt Proof: Suppose the contrary. Consider LS_2^* and choose three endpoints. LS_2^* is immediately violated as there is no point between the other two.

LS_3 : If $\lambda \cap \mu$ contains only a common **endpoint** p and for all **lines** γ we have

$$\gamma \subseteq (\lambda \cup \mu) - \{p\} \implies \gamma \subseteq \lambda \text{ or } \gamma \subseteq \mu, \text{ then } \lambda \cup \mu \in \Lambda$$

Theorem 2.2: Let **lines** λ and μ satisfy the conditions for point splicing with a common endpoint r . Let $p \in (\lambda/r)$, $q \in (\mu/r)$. Then $p-r-q$ on $\lambda \cup \mu$.

LS_4 : Every set with a linear order $>$ such that the **{closed lines}** $= \{\text{closed intervals of } >\}$ is a line.

LS_4^* :

quasi-lines are elements of a λ which satisfies LS_1 , LS_2 , and LS_3 .

a set σ is **closed-connected** $:= |\sigma| \geq 2$ and \exists a linear order $>$ such that

$$\{\text{closed quasi-lines in } \sigma\} = \{\text{closed intervals of } >\}$$

Theorem 2.3: Given a Quasi-Linear Structure $\langle S, \Lambda \rangle$, let Λ^+ denote the set of closed-connected subsets of S . Then $\langle S, \Lambda^+ \rangle$ is a Linear Structure.

A Proto-Linear Structure $\langle S, \Lambda \rangle$ satisfies LS_1 , LS_2 . Proto-lines are elements of Λ .

Proto-lines λ, μ are point-spliceable iff they have only a single endpoint p in common, and for all proto-lines γ , $\gamma \subseteq (\lambda \cup \mu) - \{p\} \implies \gamma \subseteq \lambda \text{ or } \gamma \subseteq \mu$

Given a proto-linear structure $\langle S, \Lambda_N \rangle$, Λ_{N+1} is the set Λ_N plus the unions of all pairs of point-spliceable proto-lines in $\langle S, \Lambda_N \rangle$

Each λ in Λ_{N+1} has a pair of **associated linear orders**.

Theorem 2.4: $\langle S, \Lambda_N \rangle$ is a proto-linear structure $\implies \langle S, \Lambda_{N+1} \rangle$ is a proto-linear structure

Given a proto-linear structure $\langle S, \Lambda_0 \rangle$, let Λ_{∞} denote $\bigcup_{i=0}^{\infty} \Lambda_i$

Theorem 2.5: If $\langle S, \Lambda_0 \rangle$ is a proto-linear structure, $\langle S, \Lambda_{\infty} \rangle$ is a quasi-linear structure

Given any proto-linear structure $\langle S, \Lambda_0 \rangle$, $\langle S, \Lambda_{\infty}^+ \rangle$ is the linear structure **generated** from Λ_0

Linear order properties: **dense, complete, discrete**

corresponds to **discrete space, continuum, rational space** respectively, **uniform space**

σ is a **neighborhood** of p means $p \in \sigma$ and $\text{endpoint}_\lambda(p) \implies \exists (\text{segment}_\lambda = \mu \subseteq \sigma) \text{ endpoint}_\mu(p)$

Theorem 2.6: $X \supseteq \sigma \implies X$ is a **neighborhood** of p

Theorem 2.7: $\{\text{neighborhoods of } p\}$ are closed under finite intersection

Two points p and q are **adjacent** means $\{p, q\}$ is a **minimal line**.

Theorem 2.8: In a **discrete** linear structure, σ is a **neighborhood** of $p \iff \sigma$ contains p and all points **adjacent** to p .

σ is an **open set** iff σ is a **neighborhood** of all of its members.

Theorem 2.9: The **open sets** on any linear Structure $\langle S, \Lambda \rangle$ are a topology on S .

Theorem 2.10: In a **discrete** linear structure, a set σ is **open** iff there is no **minimal line** intersecting σ and σ^C .

(so the smallest non-empty **open sets** partitions the **discrete** space)

A topology is **inherently directed** iff it cannot be generated by a Linear Structure, but can be by a Directed Linear structure.

A **directed line** $\underline{\lambda}$ is a set of points λ together with a linear order $>_{\underline{\lambda}}$ on the set. (so a **line** but with a preference for one of its **associated linear orders**)

Two **directed lines** $\underline{\lambda}, \underline{\mu}$ are **codirectional** iff for some pair of points p and q , $p >_{\underline{\lambda}} q$ and $p >_{\underline{\mu}} q$

Two **directed lines** $\underline{\lambda}, \underline{\mu}$ are **antidirectoinal** iff for some pair of points p and q , $p >_{\underline{\lambda}} q$ and $q >_{\underline{\mu}} p$

Two **directed lines** $\underline{\lambda}$ and $\underline{\mu}$ **agree** iff λ and μ have at least two points in common and for every pair of points $\{p, q\}$ that they have in common, $p >_{\underline{\lambda}} q \iff p >_{\underline{\mu}} q$

Two **directed lines** $\underline{\lambda}$ and $\underline{\mu}$ are **opposite** iff λ and μ have at least two points in common and for every pair of points $\{p, q\}$ that they have in common, $p >_{\underline{\lambda}} q \iff q >_{\underline{\mu}} p$

Two **directed lines** $\underline{\lambda}, \underline{\mu}$ are **inverses** iff $\lambda = \mu$ and $\underline{\lambda}$ is **opposite** to $\underline{\mu}$

$\text{segment}_{\underline{\lambda}}$ denotes a **directed line** $\underline{\mu}$ for which $\mu \subseteq \lambda$ and $\underline{\mu}$ **agrees** with $\underline{\lambda}$

inverse segment $_{\underline{\lambda}}$ denotes the **inverse** of some $\text{segment}_{\underline{\lambda}}$

initial endpoint $_{\underline{\lambda}}(p) \iff \nexists q \in \lambda \quad p >_{\underline{\lambda}} q$

final endpoint $_{\underline{\lambda}}(p) \iff \nexists q \in \lambda \quad q >_{\underline{\lambda}} p$

A **directed line** $\underline{\mu}$ is an **initial segment** $_{\underline{\lambda}}$ iff $\underline{\mu}$ is a $\text{segment}_{\underline{\lambda}}$ and $\nexists q \in \lambda$ such that $p \in \mu \implies p >_{\underline{\lambda}} q$

A **directed line** $\underline{\mu}$ is a **final segment** $_{\underline{\lambda}}$ iff $\underline{\mu}$ is a $\text{segment}_{\underline{\lambda}}$ and $\nexists q \in \lambda$ such that $p \in \mu \implies q >_{\underline{\lambda}} p$

A **Point-Spliced Directed Linear Structure** is an ordered pair $\langle S, \underline{\Lambda} \rangle$ satisfying axioms LS₁, LS₂, LS₃, LS₄

DLS₁: $|\text{directed line}| > 2$

DLS₂: For every **directed line** $\underline{\lambda}$, $\underline{\mu}$ is a **segment** $_{\underline{\lambda}}$ $\iff \underline{\mu}$ is an interval of $>_{\underline{\lambda}}$.
 Otherwise, for a **directed line** $\underline{\mu}^*$, $\underline{\mu}^* \subseteq \underline{\lambda} \iff \underline{\mu}^*$ is an **inverse segment** $_{\underline{\lambda}}$

DLS₃: If $\lambda \cap \mu$ contains only a single point p for which **final endpoint** $_{\underline{\lambda}}(p)$ and **initial endpoint** $_{\underline{\mu}}(p)$ and for all **directed lines** γ we have $\gamma \subseteq (\lambda \cup \mu) - \{p\} \implies \gamma \subseteq \lambda$ or $\gamma \subseteq \mu$, then $\lambda \cup \mu$ with the linear order that agrees with $>_{\underline{\lambda}}$ and $>_{\underline{\mu}}$ is a **directed line**.

DLS₄: Every linearly ordered set of points $\underline{\sigma}$ such that all and only the **closed codirectional directed lines** whose points lie in σ are closed intervals of $>_{\underline{\sigma}}$ is a **directed line**.

outward neighborhood $_p(\sigma) \iff p \in \sigma$ and $\forall \underline{\lambda}$

$\left(\text{initial endpoint}_{\underline{\lambda}}(p) \implies \exists \underline{\mu} \left(\text{segment}_{\underline{\lambda}}(\underline{\mu}) \text{ and } \text{initial endpoint}_{\underline{\mu}}(p) \right) \right)$

generalized neighborhood $_p(\sigma) \iff \text{outward neighborhood}_p(\sigma) \text{ and } \text{inward neighborhood}_p(\sigma)$

q **outward adjacent** $p \iff \exists \underline{\lambda} \left(\lambda = \{p, q\} \text{ and } q >_{\underline{\lambda}} p \right)$

Theorem 2.11: In a **discrete** Directed Linear Structure, **outward neighborhood** $_p(\sigma) \iff p \in \sigma$
 and $p \circ \rightarrow \circ x \implies x \in \sigma$

In a Directed Linear Structure, **outward open** $(\sigma) \iff \forall p \in \sigma \text{ outward neighborhood}_p(\sigma)$

Theorem 2.12: The collection of **outward open sets** on a Directed Linear Structure $\langle S, \underline{\Lambda} \rangle$ form a topology on S .

The **outward topology** is this topology.

A topology on a point set is **geometrically interpretable** iff it is the **outward topology** of some Point-Spliced Directed Linear Structure. Otherwise, it is **geometrically uninterpretable**.

Given a topology T on S and $p \in S$, $\sigma_p(T) = \{x \in S : \sigma \in T \implies x \in \sigma\}$ (intersection of all open sets containing p)

Lemma 2.1: In a finite-point topological space, every $\sigma_p(T)$ is an open set of T .

Given a topology T on S and $\rho \subset S$, $\rho^* = \{x \in S : \exists r \in \rho (x \in \sigma_r(T))\}$ (union of all $\sigma_r(T)$, $r \in \rho$)

Lemma 2.1: In a finite-point topological space, every ρ^* is an open set.

Theorem 2.13: In any **discrete** Directed Linear Structure,

outward open $(\sigma) \iff \nexists p \circ \rightarrow \circ q \left(p \in \sigma \text{ and } q \in \sigma^c \right)$

A Directed Linear Structure $\langle S, \underline{\Lambda} \rangle$ is **complete** $\iff \forall p, q \in S (p \circ \leftarrow \circ q \text{ and } p \circ \rightarrow \circ q)$.

Lemma 2.3: If $q \in \sigma_p(T)$ and $q \neq p$, then $p \circ \rightarrow \circ q$ is in the DLS constructed from $\langle S, T \rangle$.

Theorem 2.14 (the Finite-Point DLS/Topology Theorem): Let $\langle S, T_{\text{target}} \rangle$ be a topological space in which S is a finite set. There exists a Point-Spliced DLS (DLS_{constructed}) on S that generates T_{target} .