p - q $p \leftarrow q$ $p \rightarrow q$ $p \circ - \circ q$ $p \circ \leftarrow \circ q$ $p \circ \rightarrow \circ q$ Note: my own additions (besides notation) are in purple. Proceed with caution.

A topology on X is a set of open sets $T \subseteq \mathcal{P}(X)$ such that:

- $-X \in T$
- $-\emptyset \in T$
- T is closed under arbitrary unions
- T is closed under finite intersections

A closed set is a complement of an open set.

Neighborhoods of p contain an open set containing p.

p is a boundary point of a set S means every open set containing p intersects both S and S^C .

A connected set is one not formed by the union of two disjoint non-empty open sets.

A Hausdorff (T_2) space is one where every pair of distinct points lie in distinct open sets.

A Point-Spliced Linear Structure on a set S is an ordered pair $\langle S, \Lambda \rangle$ $\Lambda \subseteq \mathcal{P}(S)$ satisfying axioms LS₁, LS₂, LS₃, LS₄

lines are elements of Λ

LS₁:
$$\forall \lambda (|\lambda| \geq 2)$$

minimal lines are **lines** of size 2 ($p \multimap q$ denotes the minimal line connecting p, q, also acts as a binary relation which is true if such a minimal line exists)

 $\mathbf{segment}_{\lambda}(\mu) := \mu \subseteq \lambda \text{ and } \mu \in \Lambda.$

 \mathbf{point}_{λ} denotes an element of the line λ

(read: "segments on lambda, points on lambda")

 $r \ \mathbf{between}_{\lambda} \ p, q := p, q, r \in \lambda \ \mathrm{and} \ \left(\mathbf{segment}_{\lambda}(\mu) \ \mathrm{and} \ p, q \in \mu \ \Rightarrow \ r \in \mu \right).$ Denote p - r - q on $\lambda := r \ \mathbf{between}_{\lambda} \ p, q \ \ (\text{equivalent to} \ q - r - p \ \mathrm{on} \ \lambda).$

For nondistinct points, e.g. r-r-s, the relation is false.

LS₂: Every line λ admits a linear order > such that $\mu \in \Lambda \iff \mu$ is an interval of >

LS₂*: Equivalently, specify that for every line λ :

For any three distinct points p, q, r, there is exactly one choice of r for which p-r-q For all **points**_{λ} p, q the sets $PQ = \{r \in \lambda : p-r-q\}$ and $\overline{PQ} = PQ \cup \{p, q\}$ are **segments**_{λ} (provided $|PQ| \ge 2$)

This is enough to make the betweeness relation "behave nicely", as we have eliminated forks as candidates for lines by requiring the existence of at least one r and removed loops by the uniqueness of r, enforcing a linear order. So we can show a proof of equivalence:

For any $\operatorname{\mathbf{segment}}_{\lambda} S$ containing p,q, we have $\overline{PQ} \subseteq S$. Supposing otherwise would mean there exists a $r \in \lambda$: p - r - q and $r \notin S$, which contradicts S being a $\operatorname{\mathbf{segment}}_{\lambda} S$ containing p,q and the definition of p - r - q

Now, consider letting p-r-s and r-s-q on λ

 LS_2^* says exactly one of p-q-r, q-p-r, or p-r-q are true on λ . We have p-q-r admits a $\operatorname{\mathbf{segment}}_\lambda \overline{PR}$ containing q. But as r-s-q, \overline{PR} must contain both q and s. \overline{PR} is the smallest $\operatorname{\mathbf{segment}}_\lambda$ containing p and r, so any $\operatorname{\mathbf{segment}}_\lambda$ containing p and r also contains s, i.e. p-s-r, contrary to the assumption that p-r-s. A similar case holds for q-p-r, leaving p-r-q as the only acceptable choice to satisfy LS_2^* . Similarly, we also have p-s-q.

So LS_2^* justifies the notation p-r-s-q:=(p-r-s and r-s-q), as all derivable true

statements can be found by removing interior terms. Explicitly, this shows transitivity at both the interior and end points, so transitivity holds for all points, giving two symmetric linear orders. The trivial exceptions of lines with 2 or 3 points are easily handled. Both open and closed intervals (corresponding to PQ and \overline{PQ} , respectively) are **segments**_{λ}, hence $LS_2^* \Rightarrow LS_2$

The other direction LS₂ \Rightarrow LS₂* is easy: identify p > r > q with p - r - q

 LS_2^* is enough to push the p-q notation further, allowing us to make well-formed longer chains. It would be easy to repeat the tricks above to show p-x-r and $r-y-q \implies x-r-y$, which allows us to write p-x-r-y-q as shorthand for all those true statements from deleting interior terms. But since we showed the existence of a linear order, there is no need for the now obvious.

```
\begin{array}{l} \mathbf{endpoint}_{\lambda}(x) \coloneqq x \in \lambda \text{ and } \nexists \ p,q \in \lambda \ : \ p - x - q \\ \mathbf{Denote \ endpoints}_{\lambda} = \{p \ : \ \mathbf{endpoint}_{\lambda}(p)\} \\ \lambda \text{ is open } \ \coloneqq |\mathbf{endpoints}_{\lambda}| = 0 \\ \lambda \text{ is closed } \coloneqq |\mathbf{endpoints}_{\lambda}| = 2 \\ \lambda \text{ is clopen} \coloneqq |\mathbf{endpoints}_{\lambda}| = 1 \end{array}
```

Theorem 2.1: A line can have no more than 2 endpoints.

Alt Proof: Suppose the contrary. Consider LS_2^* and choose three endpoints. LS_2^* is immediately violated as there is no point between the other two.

LS₃: If $\lambda \cap \mu$ contains only a common **endpoint** r and for all **lines** γ we have $\gamma \subseteq (\lambda \cup \mu) - \{r\} \implies \gamma \subseteq \lambda \text{ or } \gamma \subseteq \mu$, then $\lambda \cup \mu \in \Lambda$

Theorem 2.2: Let lines λ and μ satisfy the conditions for point splicing with a common endpoint r. Let $p \in (\lambda/r), \ q \in (\mu/r)$. Then p-r-q on $\lambda \cup \mu$.

Alt proof: In contrapositive form, LS₃: $\gamma \nsubseteq \lambda$ and $\gamma \nsubseteq \mu \Longrightarrow \gamma \nsubseteq (\lambda \cup \mu) - \{r\}$. So $p \in \gamma$ and $q \in \gamma \Longrightarrow \gamma \nsubseteq (\lambda \cup \mu) - \{r\}$. If we take **segment**_{$\lambda \cup \mu$}(γ) (i.e. enforcing $\gamma \subseteq \lambda \cup \mu$), we must have $r \in \gamma$, i.e. p - r - q.

(had random thought about the usage of proof by contradiction, compare this to Maudlin's proof. Which feels more like showing how the pieces fit exactly together in the right way? Like things gradually falling into place? It is better if every usage of proof by contradiction can be relegated to the automatic/unwritten level.)

 LS_4 : Every set with a linear order > such that the {closed lines} = {closed intervals of >} is a line. LS_4^* :

```
quasi-lines are elements of a \lambda which satisfies LS<sub>1</sub>, LS<sub>2</sub>, and LS<sub>3</sub>. a set \sigma is closed-connected := |\sigma| \ge 2 and \exists a linear order > such that \{closed quasi-lines in \sigma\} = \{closed intervals of >\}
```

Theorem 2.3: Given a Quasi-Linear Structure $\langle S, \Lambda \rangle$, let Λ^+ denote the set of closed-connected subsets of S. Then $\langle S, \Lambda^+ \rangle$ is a Linear Structure.

A Proto-Linear Structure $\langle S, \Lambda \rangle$ satisfies LS₁, LS₂. Proto-lines are elements of Λ .

Proto-lines λ , μ are point-spliceable iff they have only a single endpoint p in common, and for all proto-lines γ , $\gamma \subseteq (\lambda \cup \mu) - \{p\} \implies \gamma \subseteq \lambda$ or $\gamma \subseteq \mu$

Given a proto-linear structure $\langle S, \Lambda_N \rangle$, Λ_{N+1} is the set Λ_N plus the unions of all pairs of point-spliceable proto-lines in $\langle S, \Lambda_N \rangle$

Each λ in Λ_{N+1} has a pair of associated linear orders.

Theorem 2.4: $\langle S, \Lambda_N \rangle$ is a proto-linear structure $\implies \langle S, \Lambda_{N+1} \rangle$ is a proto-linear structure

Given a proto-linear structure $\langle S, \Lambda_0 \rangle$, let Λ_{∞} denote $\bigcup_{i=0}^{\infty} \Lambda_i$

Theorem 2.5: If $\langle S, \Lambda_0 \rangle$ is a proto-linear structure, $\langle S, \Lambda_\infty \rangle$ is a quasi-linear structure

Given any proto-linear structure $\langle S, \Lambda_0 \rangle$, $\langle S, \Lambda_{\infty}^+ \rangle$ is the linear structure **generated** from Λ_0

Linear order properties: dense, complete, discrete corresponds to discrete space, continuum, rational space respectively, uniform space

 σ is a **neighborhood** of p means $p \in \sigma$ and $\mathbf{endpoint}_{\lambda}(p) \implies \exists \ (\mathbf{segment}_{\lambda} = \mu \subseteq \sigma) \ \mathbf{endpoint}_{\mu}(p)$

Theorem 2.6: $X \supseteq \sigma \implies X$ is a **neighborhood** of p

Theorem 2.7: $\{$ **neighborhoods** of $p\}$ are closed under finite intersection

Two points p and q are adjacent means $\{p,q\}$ is a minimal line.

Theorem 2.8: In a **discrete** linear structure, σ is a **neighborhood** of $p \iff \sigma$ contains p and all points **adjacent** to p.

 σ is an **open set** iff σ is a **neighborhood** of all of its members.

Theorem 2.9: The **open sets** on any linear Structure $\langle S, \Lambda \rangle$ are a topology on S.

Theorem 2.10: In a **discrete** linear structure, a set σ is **open** iff there is no **minimal line** intersecting σ and σ^C .

(so the smallest non-empty **open sets** partitions the **discrete** space)

A topology is **inherently directed** iff it cannot be generated by a Linear Structure, but can be by a Directed Linear structur.

A directed line $\underline{\lambda}$ is a set of points λ together with a linear order $>_{\underline{\lambda}}$ on the set. (so a line but with a preference for one of its associated linear orders)

Two directed lines $\underline{\lambda}$, $\underline{\mu}$ are codirectional iff for some pair of points p and q, $p>_{\lambda}q$ and $p>_{\mu}q$

Two directed lines $\underline{\lambda}$, μ are antidirectoinal iff for some pair of points p and q, $p>_{\lambda}q$ and $q>_{\mu}p$

Two directed lines $\underline{\lambda}$ and $\underline{\mu}$ agree iff λ and μ have at least two points in common and for every pair of points $\{p,q\}$ that they have in common, $p>_{\lambda}q\iff p>_{\mu}q$

Two **directed lines** $\underline{\lambda}$ and $\underline{\mu}$ are **opposite** iff λ and μ have at least two points in common and for every pair of points $\{p,q\}$ that they have in common, $p>_{\underline{\lambda}}q\iff q>_{\underline{\mu}}p$

Two directed lines $\underline{\lambda}$, μ are inverses iff $\lambda = \mu$ and $\underline{\lambda}$ is opposite to μ

segment_{λ} denotes a **directed line** μ for which $\mu \subseteq \lambda$ and μ **agrees** with $\underline{\lambda}$

inverse segment $_{\lambda}$ denotes the inverse of some segment $_{\lambda}$

```
\begin{split} & \textbf{initial endpoint}_{\underline{\lambda}}(p) \iff \nexists \ q \in \lambda \quad \  p >_{\underline{\lambda}} q \\ & \textbf{final endpoint}_{\lambda}(p) \iff \nexists \ q \in \lambda \quad \  q >_{\lambda} p \end{split}
```

A directed line $\underline{\mu}$ is an initial segment $\underline{\lambda}$ iff $\underline{\mu}$ is a segment $\underline{\lambda}$ and $\nexists q \in \lambda$ such that $p \in \mu \implies p >_{\underline{\lambda}} q$ A directed line $\underline{\mu}$ is a final segment $\underline{\lambda}$ iff $\underline{\mu}$ is a segment $\underline{\lambda}$ and $\nexists q \in \lambda$ such that $p \in \mu \implies q >_{\lambda} p$

A Point-Spliced Directed Linear Structure is an ordered pair $\langle S, \underline{\Lambda} \rangle$ satisfying axioms LS₁, LS₂, LS₃, LS₄

 DLS_1 : |directed line| > 2

- DLS₂: For every **directed line** $\underline{\lambda}$, $\underline{\mu}$ is a **segment** $\underline{\lambda} \iff \underline{\mu}$ is an interval of $>_{\underline{\lambda}}$. Otherwise, for a **directed line** $\underline{\mu}^*$, $\underline{\mu}^* \subseteq \lambda \iff \underline{\mu}^*$ is an **inverse segment** λ
- DLS₃: If $\lambda \cap \mu$ contains only a single point p for which **final endpoint**_{$\underline{\lambda}$}(p) and **initial endpoint**_{$\underline{\mu}$}(p) and for all **directed lines** γ we have $\gamma \subseteq (\lambda \cup \mu) \{p\} \implies \gamma \subseteq \lambda$ or $\gamma \subseteq \mu$, then $\lambda \cup \mu$ with the linear order that agrees with $>_{\lambda}$ and $>_{\mu}$ is a **directed line**.
- DLS₄: Every linearly ordered set of points $\underline{\sigma}$ such that all and only the **closed codirectional directed** lines whose points lie in σ are closed intervals of $>_{\underline{\sigma}}$ is a **directed line**.

 $\begin{array}{ll} \mathbf{outward} \ \mathbf{neighborhood}_p(\sigma) \iff p \in \sigma \ \mathrm{and} \ \forall \ \underline{\lambda} \\ \\ \left(\mathbf{initial} \ \mathbf{endpoint}_{\underline{\lambda}}(p) \ \Rightarrow \ \exists \ \underline{\mu} \ \left(\mathbf{segment}_{\underline{\lambda}}(\mu) \ \mathrm{and} \ \mathbf{initial} \ \mathbf{endpoint}_{\underline{\mu}}(p) \ \right) \right) \end{array}$

 $\mathbf{generalized} \ \mathbf{neighborhood}_p(\sigma) \iff \mathbf{outward} \ \mathbf{neighborhood}_p(\sigma) \ \mathrm{and} \ \mathbf{inward} \ \mathbf{neighborhood}_p(\sigma)$

q outward adjacent $p \iff \exists \underline{\lambda} (\lambda = \{p,q\} \text{ and } q >_{\underline{\lambda}} p)$

In a Directed Linear Structure, outward open $(\sigma) \iff \forall p \in \sigma \text{ outward neighborhood}_p(\sigma)$

Theorem 2.12: The collection of **outward open sets** on a Directed Linear Structure $\langle S, \underline{\Lambda} \rangle$ form a topology on S.

The **outward topology** is this topology.

- A topology on a point set is **geometrically interpretable** iff it is the **outward topology** of some Point-Spliced Directed Linear Structure. Otherwise, it is **geometrically uninterpretable**.
- Given a topology T on S and $p \in S$, $\sigma_p(T) = \{x \in S : \sigma \in T \Rightarrow x \in \sigma\}$ (intersection of all open sets containing p)

Lemma 2.1: In a finite-point topological space, every $\sigma_p(T)$ is an open set of T.

Given a topology T on S and $\rho \subset S$, $\rho^* = \{x \in S : \exists r \in \rho \ (x \in \sigma_r(T))\}$ (union of all $\sigma_r(T)$, $r \in \rho$) Lemma 2.1: In a finite-point topological space, every ρ^* is an open set.

Theorem 2.13: In any **discrete** Directed Linear Structure, **outward open**(σ) $\iff \nexists p \leadsto q \ (p \in \sigma \text{ and } q \in \sigma^{\mathsf{c}})$

A Directed Linear Structure $\langle S, \underline{\Lambda} \rangle$ is **complete** $\iff \forall \ p, q \in S \ \big(\ p \circ \longleftarrow \circ q \ \text{and} \ p \circ \longrightarrow \circ q \ \big).$

Lemma 2.3: If $q \in \sigma_p(T)$ and $q \neq p$, then $p \circ \longrightarrow \circ q$ is in the DLS constructed from $\langle S, T \rangle$.

Theorem 2.14 (the Finite-Point DLS/Topology Theorem): Let $\langle S, T_{\text{target}} \rangle$ be a topological space in which S is a finite set. There exists a Point-Spliced DLS (DLS_{constructed}) on S that generates T_{target} .