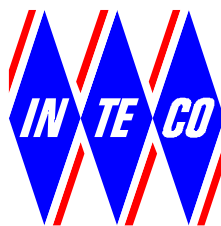
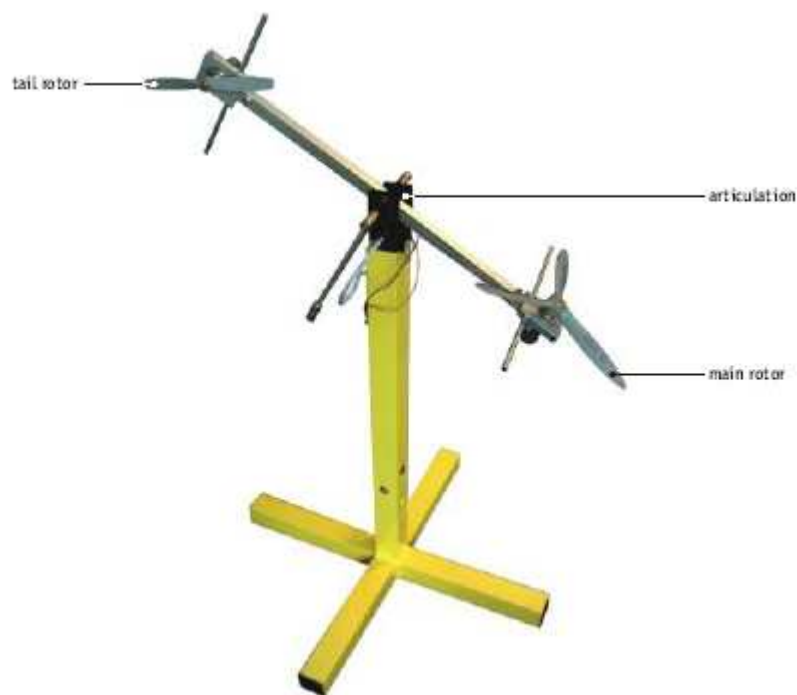


Two Rotor Aero-dynamical System

Installation manual

PCI version



www.inteco.com.pl



NOTES

SAFETY OF THE EQUIPMENT

The equipment, when used in accordance with the supplied instructions, within the parameter set for its mechanical and electrical performance, should not cause any danger to health or safety if normal engineering applications are observed.

If, in specific cases, circumstances exist in which a potential hazard may be brought about by careless or improper use, these will be pointed out and the necessary precautions emphasised.

Some National Directives require to indicate on our equipment certain warnings that require attention by the user. These have been indicated in the specified way by labels. The meaning of any labels that may be fixed to the equipment instrument are explained in this manual.



Risk of electric shock

PRODUCT IMPROVEMENTS

The Producer reserves a right to improve design and performance of the product without prior notice.

All major changes are incorporated into up-dated editions of manuals and this manual is believed to be correct at the time of printing. However, some product changes which do not affect the capability of the equipment, may not be included until it is necessary to incorporate other significant changes.



ELECTROMAGNETIC COMPABILITY

This equipment, when operated in accordance with the supplied documentation, does not cause electromagnetic disturbance outside its immediate electromagnetic environment.

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CONTENTS

1. INTRODUCTION.....	6
2. COMPONENTS OF THE SYSTEM.....	7
3. UNPACKING AND CHECKING THE ITEMS	8
4. ASSEMBLY OF THE MECHANICAL CONSTRUCTION	10
5. RT-DAC BOARD INSTALLATION	11
5.1 RT-DAC/PCI BOARD CONNECTORS.....	12
5.2 DRIVER INSTALLATION	13
6. CONNECTING THE POWER INTERFACE	14
7. SOFTWARE INSTALLATION	16
8. STARTING AND TESTING	20
9. OPERATION AND SECURITY NOTES.....	22



1. INTRODUCTION

This manual contains a description of the components of the Two Rotor Aerodynamical System, assembly instructions and test procedures. The procedures described in this manual will ensure correct:

- assembly of the system,
- RT-DAC interface board installation,
- cable connections between the mechanical part of the model, Power Interface and PC.



2. COMPONENTS OF THE SYSTEM

To use the system the following software and hardware components are required:

- Pentium or AMD based personal computer.
- Microsoft Windows 2000/XP/W7
- MATLAB R2008a/b, R2009a/b, or R2010a/b with appropriate versions of Simulink RTW and RTWT toolboxes (not included),
- If Windows 7 is used only R2009a/b and R2010a/b versions of Matlab are supported,
- RT-DAC/PCI Programmable Input/Output board to install in the PC,
- Inteco TRAS set-up consisting of the TRAS Mechanical Unit and TRAS Power Interface Unit,
- CD-ROM with TRAS software and e-manuals (in pdf format):
- this manual,

3. UNPACKING AND CHECKING THE ITEMS

Carefully unpack the items, and remove all packaging and securing material. You should have the following items (Fig.3.1):

- TRAS beam and leg, with DC motors, rotors, counterbalance, sensors and attached ribbon signal cables and power cables,
- TRAS support,
- couplings bolts (2) and special allen wrench,
- fixing clamp (1) and fixing bar (1),
- TRAS Power Interface,
- Emergency switch,
- Main power cable,
- RT-DAC/PCI board with rear bracket connector and ribbon cables (3)
- CD-ROM (Documentation: *User's Manual*, this manual, software),
- Packing List.

The exact specification you will find on the *Item List*. If any item is missing or damaged please, contact *Inteco*.



Carefully follow the installation steps described below. Only correct installation procedure ensures proper operation of the system

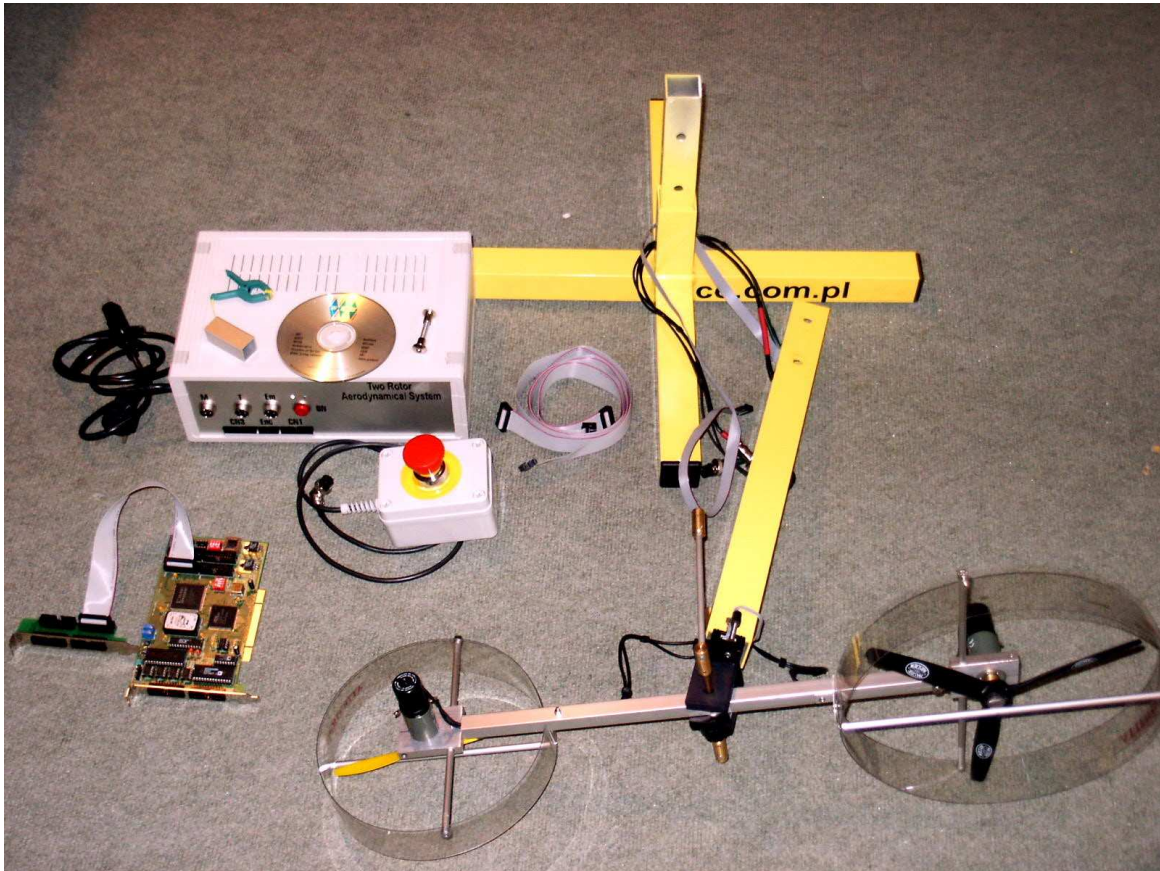


Fig 3.1 The TRAS set-up, not assembled

4. ASSEMBLY OF THE MECHANICAL CONSTRUCTION

Components of the mechanical construction are given in Fig.4.1

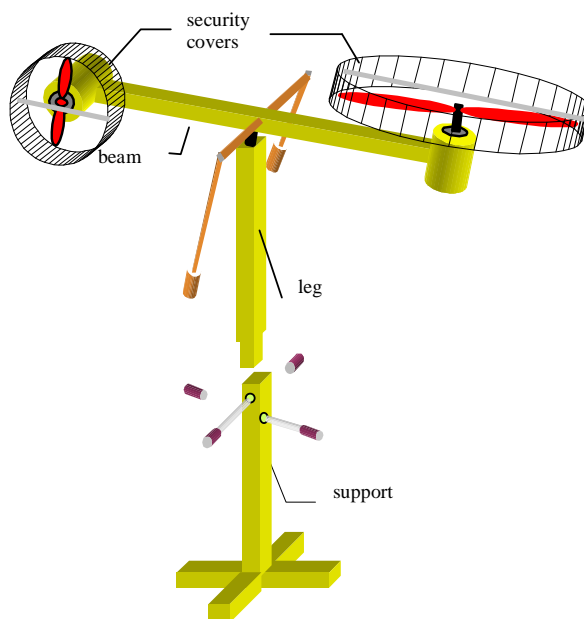


Fig.4.1 TRAS mechanical construction

Select the TRAS support and place it on the table. Join with the leg and TRAS beam. Insert coupling bolts into mounting sockets and loosely screw them with the allen key provided (Fig.4.2).

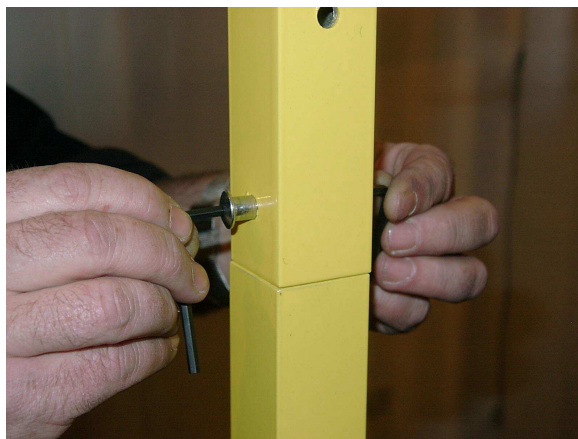


Fig 4.2 Coupling bolts

5. RT-DAC BOARD INSTALLATION



The RT-DAC/PCI board contains sensitive electric components, which can be easily damaged by static electricity, therefore the board should be kept in its original packing until it is installed. During installation the board should be handled carefully only by the edges to avoid static electricity discharge

To install the board:

- Check, if CN3 connector of the board is connected to the rear bracket connector by 20-way short ribbon cable (included). If not, the cable to CN3 connector of the rear bracket connector.
- Connect 20-way ribbon cable to CN1 connector of the board (see Fig.5.1),
- Turn off the computer and remove the cover.

One empty PCI slot is required at the rear of your PC.

- Find an empty expansion slot, remove the metal bracket,
- Insert the RT-DAC/PCI board into the expansion slot, then secure the board with the screws,
- Secure rear bracket connector with the screw,
- Replace the cover of the computer.

Next step is connecting the cables to the TRAS Power Interface (Fig.5.2).



Before removing the cover turn OFF the computer and disconnect the mains cable

5.1 RT-DAC/PCI BOARD CONNECTORS

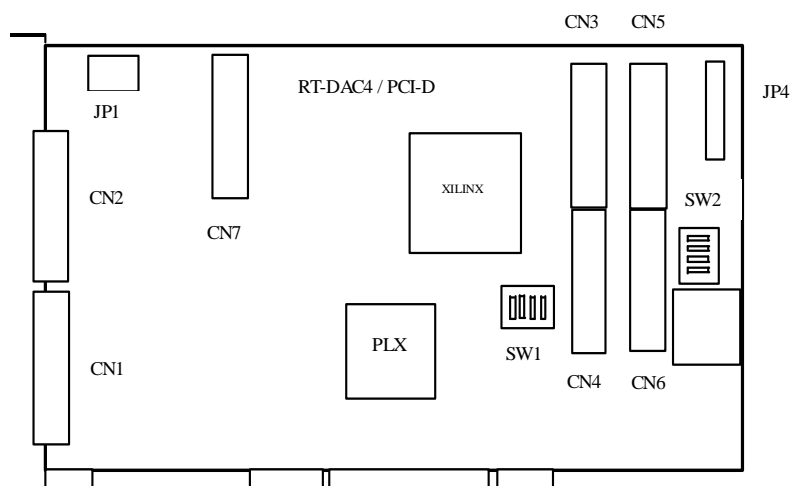


Fig. 5.1. RT-DAC/PCI board and location of connectors

Fig. 5.2 shows connection the ribbon cables to the RT-DAC/PCI interface board.

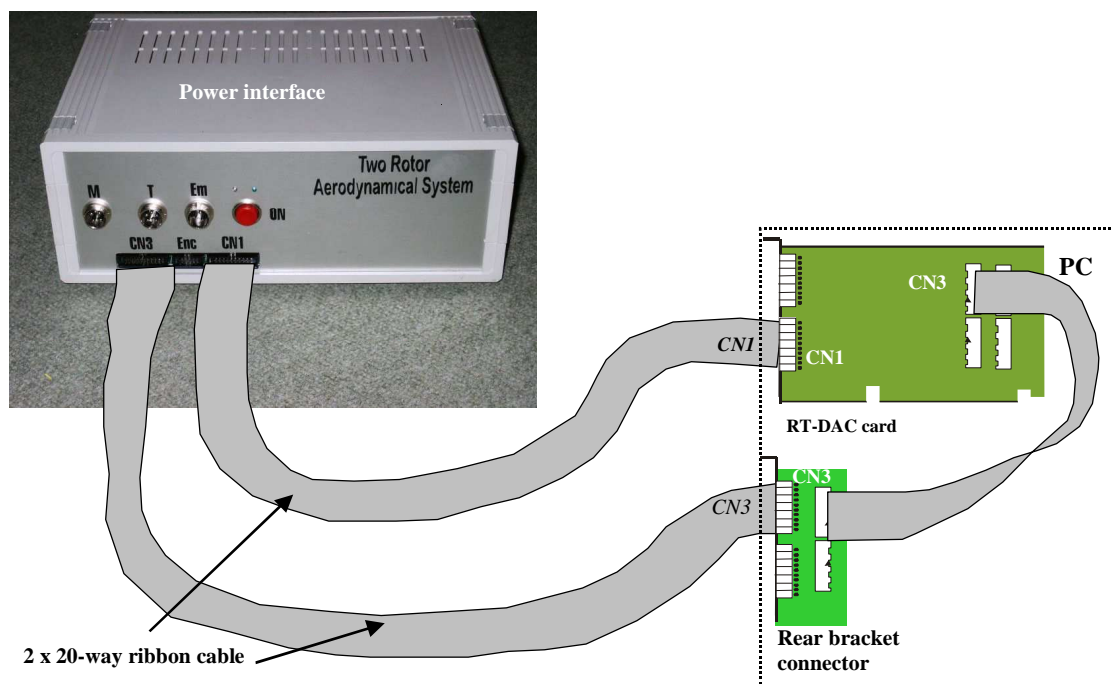


Fig.5.2. RT-DAC/PCI cables connection



5.2 DRIVER INSTALLATION

The driver for RTDAC/PCI board has to be installed because the board is of the PCI type. Administrator privileges are required for driver installation.

Windows 2000/XP installation

- Start Microsoft Windows 2000/XP
- System detects *new PCI device*
- Select Next, then Display a list....
- Select Other Devices, then Next
- Select Have a disk, then Browse
- Select path CD:\driver\Win9x2K\RTDAC_PCI9030.inf, then *Open*
- Select *OK* and *Next*, and *Next*
- Select *Finish*
- If Windows propose to restart the computer select *Yes*.

Windows 7 installation

- Start Microsoft Windows 7
- System detects *new PCI device*
- Select Next, then Display a list....
- Select Other Devices, then Next
- Select Have a disk, then Browse
- Select path CD:\driver\ WinW7x86\RTDAC_PCI9030.inf, then *Open*
- Select *OK* and *Next*, and *Next*
- Select *Finish*
- If Windows propose to restart the computer select *Yes*.

6. CONNECTING THE POWER INTERFACE

The general diagram of power interface connections is given in Fig. 6.1.



Before connecting the cables turn OFF the computer

There are two kinds of cables attached to the mechanical unit: 1 ribbon cables from the encoders and 1 round cables controlling the motor and 1 round cable from the tachogenerators. Notice, that the cables are terminated by different types of plugs.

In order to connect cables go through the following steps:

- Check the position of the Power Switch located on the back side of the Power Interface box – it must be in the „0” (OFF) position.
- Connect the cables:
 - ⇒ plug the 20-way ribbon cable from the RT-DAC/PCI board into the **CN1** socket,
 - ⇒ plug the 20-way ribbon cable from the rear bracket connector into the **CN3** socket,
 - ⇒ plug 10 - way ribbon cables from the encoders into the connectors marked as **E** (Fig 6.1).
- Connect two round cables: controlling DC motors, respectively: to the **M socket** and cable from tachogenerators to the **T socket**,
- Connect the emergency switch cable to the **Em socket**,
- Plug the mains power cable to the socket located on the back side of the Power Interface box.



Notice, that the connectors and the sockets are clearly marked using the convention presented in Fig. 6.1

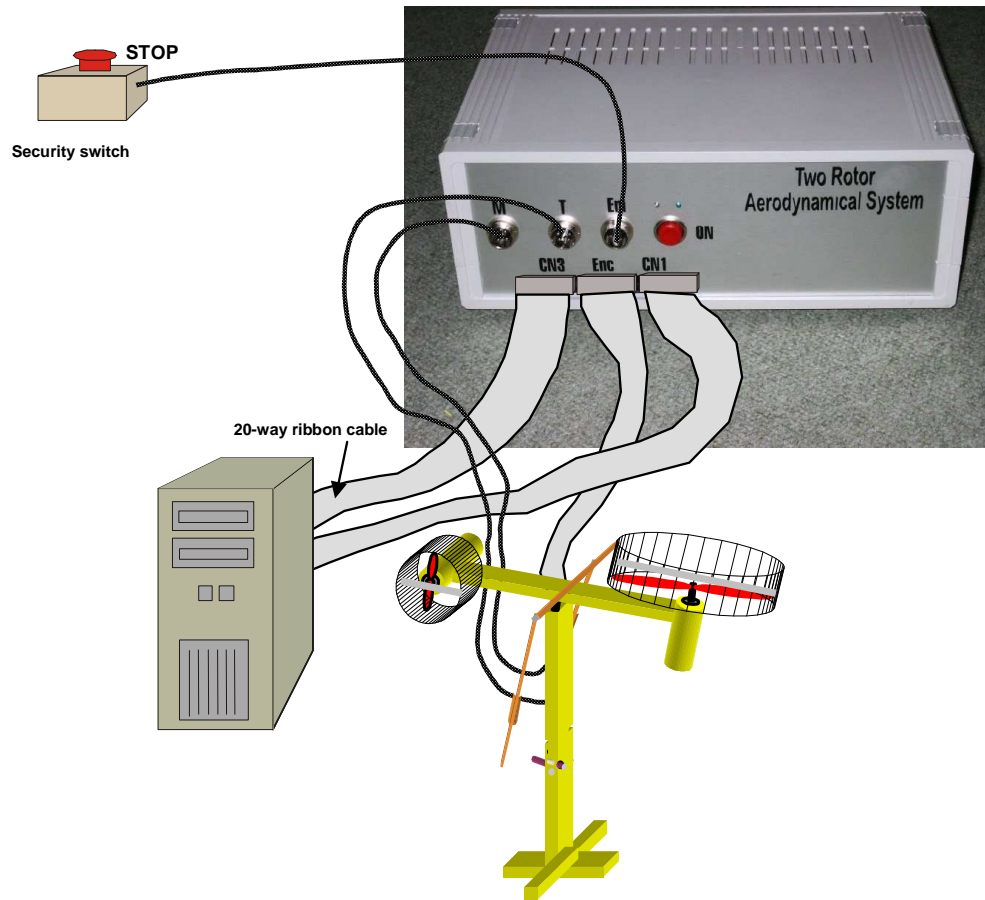


Fig. 6.1 Power Interface and connecting cables

7. SOFTWARE INSTALLATION



The installation program has to be started by a system administrator

To start the installation program insert the CD-ROM into the drive, and open it in the Windows explorer. Next find the `in_3dcrane.exe` file located in the Crane3DToolbox directory. Click it with right mouse button and select the “run as administrator” option.

If you run installation you will see the license information. Read the license agreement carefully. If you accept the license terms mark the checkbox and click the *Next* button.

The window that follows asks you for your name and the name of your company (Fig.7.2).



Fig.7.2

If you click the *Next* you will see an important dialogue window containing your current MATLAB settings (Fig. 7.3). You will be informed about the version of your Windows system.

You must select the appropriate version of the MATLAB software installed.



Fig. 7.3

Browse your system directories and select the appropriate directory. The program automatically detects the presence of the *matlab.exe* file and closes the dialogue window. The selected location will be displayed in the *Matlab location* window (Fig.7.4).

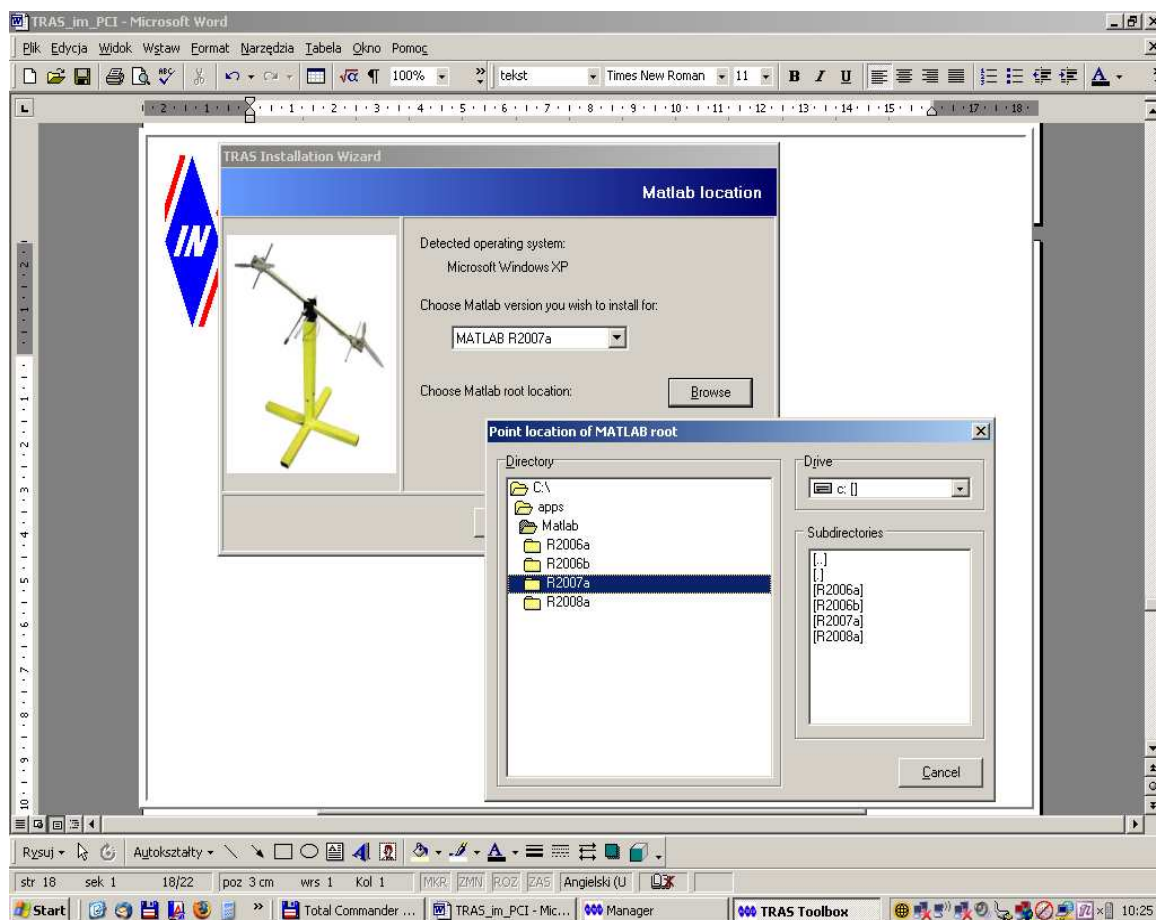


Fig. 7.4

If you have completed installation settings click the *Next* button to start the installation procedure. The end of installation process will be confirmed by the appropriate window (Fig.7.5).

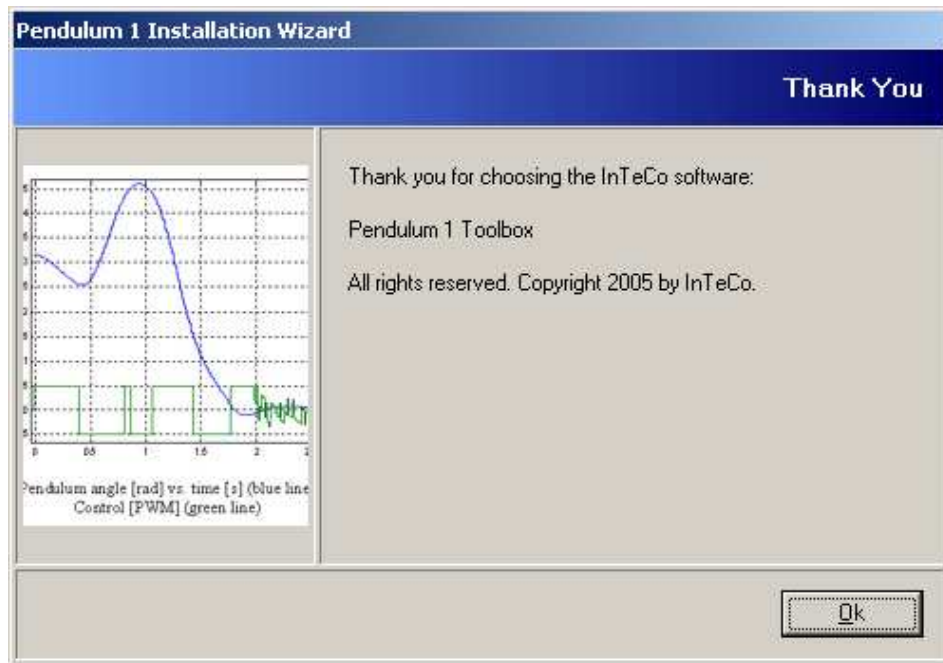


Fig.7.5

The computer has to be restarted after the installation process.

To uninstall the software run as administrator un_tras.exe file.

Uninstalling process will be performed automatically.

8. STARTING AND TESTING



For safety reasons it is not allowed to start the system if the plastic security shield is removed.

In order to test the system perform the following steps:

- Install the *TRAS* software. For this purpose refer to Section 7.
- According to your selection (1-degree or 2-degrees of freedom experiment) fix one of axis using the included clamp or fixing bar (Fig.8.1, Fig.8.2)

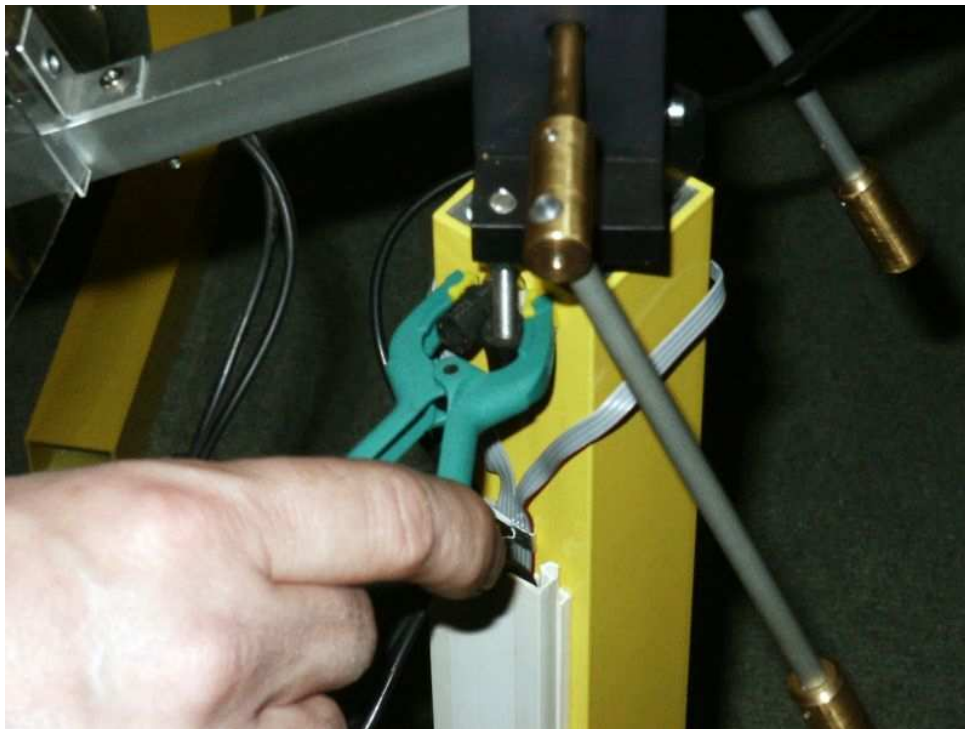


Fig. 8.1 Fixing one degree of freedom

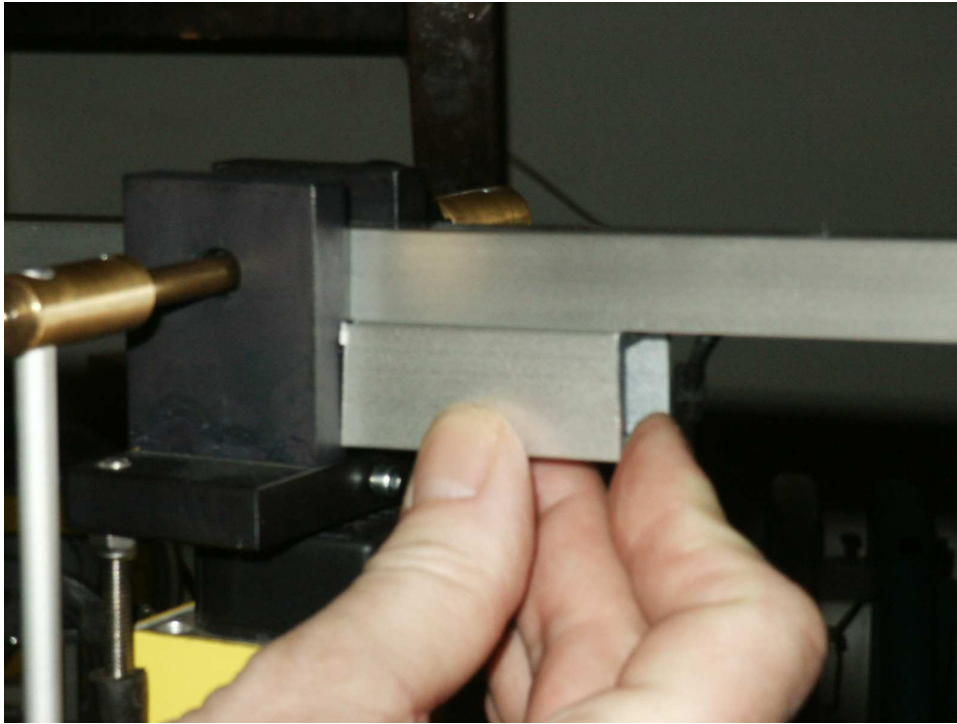


Fig.8.2 Fixing bar

- If the RT-DAC/PCI board has been properly installed and ribbon cables connected turn on your PC,
- Start MATLAB and type *TRAS* command,
- Switch on the mains (back side of the panel)
- Blue LED on the front panel will alight,
- Switch the power on (**ON**),
- Red LED on the front panel will alight,
- run *Manual Setup* application to perform the test, described in the section *Starting, testing and stopping procedures* in *TRAS User's Manual*, to check connections of the sensors to the Power Interface.
- In the case of any unexpected behaviour of the system use the **EMERGENCY SWITCH**. After using the emergency switch, you have to turn and press switch and next press the **ON** button in order to start the system again.
- Now, you can perform your own experiments
- If your experiments are finished, stop the MATLAB application. Switch off the mains.



9. OPERATION AND SECURITY NOTES

- It is not allowed to start the system if the plastic security shields are removed,
- Allow good air circulation around the Power Interface box for correct cooling of radiators, do not cover the fan.