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1 | conspd goal = residualize o drive_disj o normalize (goal, empty_substitution)
2 |
3 | drive_disj :: (Disjunction, Substitution) → Process_Tree
4 | drive_disj ((c1, ..., cn), subst) =  $\bigvee_{i=1}^n t_i \leftarrow \text{drive\_conj } (c_i, \text{subst})$ 
5 |
6 | drive_conj :: (Conjunction, Substitution) → Process_Tree
7 | drive_conj ((r1, ..., rn), subst) =
8 |   C@(r1, ..., rn) ← propagate_substitution subst onto r1, ..., rn
9 |   case whistle (C) of
10 |     | instance (C', subst')      ⇒ create_fold_node (C', subst')
11 |     | embedded_but_not_instance ⇒ create_stop_node (C, subst)
12 |     | otherwise ⇒
13 |       | case heuristically_select_a_call (r1, ..., rn) of
14 |         | | Just r ⇒
15 |           | | t ← drive_disj o normalize o unfold (r, subst)
16 |           | | if trivial o leafs (t)
17 |           | | then
18 |             | | subst' ← extract_substitution (t)
19 |             | | C' ← propagate_substitution (C \ r, subst')
20 |             | | drive_disj (C'[r ↦ extract_calls (t)], subst')
21 |             | | else
22 |             | | t  $\wedge$  drive_disj (C \ r, subst)
23 |             | | Nothing ⇒  $\bigwedge_{i=1}^n t_i \leftarrow \text{drive\_disj } (r_i, \text{subst})$ 

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