

# Rytter-style Algorithm for Context-Free Path Querying

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## 1 THE REDUCTION

Suppose we have  $\Phi$  – an instance of 3-SAT problem contains  $m$  clauses over  $k$  variables.

First of all, we should to construct a graph. To do it we follow the next steps.

- (1) Let  $\gamma_i = \{v_1 \leftarrow b_1, v_2 \leftarrow b_2, \dots, v_k \leftarrow b_k\}$  where  $b_k \in \{0, 1\}$ . For each substitution  $\gamma_i$  a vertex  $V_{\gamma_i}$  should be created.
- (2) For each  $V_{\gamma_i}$  the following edges should be added:  $\{(V_{\gamma_i}, [v_j \leftarrow b_l]^+, V_{\gamma_i}) \mid v_j \leftarrow b_l \in \gamma_i\}$ .
- (3) For each clause  $(l_1 \vee l_2 \vee l_3)$  the following subgraph should be created. First, two new vertices are added:  $c_1$  and  $c_2$ . After that, the following edges for each  $l_p$  and for each  $\gamma_i$  should be added

$$\{(c_1, [v_j \leftarrow b_l]^-, c_2) \mid b_l = \begin{cases} 1 & \text{if } l_p = v_j \\ 0 & \text{if } l_p = \neg v_j \end{cases}\}.$$

- (4) Subgraph for all clauses should be connected sequentially. Suppose we have sequence of subgraphs with vertices

$$\{(c_1^1, c_2^1), (c_1^2, c_2^2), \dots, (c_1^m, c_2^m)\}.$$

To connect them we should merge vertices  $c_2^i$  and  $c_1^{i+1}$  for all  $i$  except  $i = m$ . After that we fix  $c_1^1$  as a start vertex of formula subgraph, and  $c_2^m$  as a final vertex of formula subgraph.

- (5) Finally, for all  $V_{\gamma_i}$  we should add the following edge

$$(V_{\gamma_i}, q, c_1^1)$$

The second part is a query. Suppose, we have  $p$  different substitutions. The grammar is following

$$\begin{aligned} S &\rightarrow q \\ S &\rightarrow [v_1 \leftarrow b_1]^+ S [v_1 \leftarrow b_1]^- \\ &\mid \dots \\ &\mid [v_k \leftarrow b_k]^+ S [v_k \leftarrow b_k]^- \end{aligned}$$

After that we should apply transformation which is described in the section 2. As a result we get h-Dyck reachability problem (yes, we can reduce it to 2-Dyck reachability).

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## 1.1 An Example of Reduction

Suppose we have the following instance of 3-SAT problem.

$$\Phi = (\neg x_1 \vee x_2 \vee \neg x_3) \wedge (\neg x_2 \vee x_1 \vee x_3) \wedge (x_1 \vee \neg x_3 \vee x_2)$$

Substitutions:

$$\begin{aligned} \gamma_1 &= \{x_1 \leftarrow 0, x_2 \leftarrow 0, x_3 \leftarrow 0\} \\ \gamma_2 &= \{x_1 \leftarrow 1, x_2 \leftarrow 0, x_3 \leftarrow 0\} \\ \gamma_3 &= \{x_1 \leftarrow 0, x_2 \leftarrow 1, x_3 \leftarrow 0\} \\ \gamma_4 &= \{x_1 \leftarrow 0, x_2 \leftarrow 0, x_3 \leftarrow 1\} \\ \gamma_5 &= \{x_1 \leftarrow 1, x_2 \leftarrow 1, x_3 \leftarrow 0\} \\ \gamma_6 &= \{x_1 \leftarrow 1, x_2 \leftarrow 0, x_3 \leftarrow 1\} \\ \gamma_7 &= \{x_1 \leftarrow 0, x_2 \leftarrow 1, x_3 \leftarrow 1\} \\ \gamma_8 &= \{x_1 \leftarrow 1, x_2 \leftarrow 1, x_3 \leftarrow 1\} \end{aligned}$$

Graph for  $\Phi$  is presented in figure 2.

The grammar:

$$\begin{aligned} S &\rightarrow [x_1 \leftarrow 0]^+ S [x_1 \leftarrow 0]^- \\ &\mid [x_2 \leftarrow 0]^+ S [x_2 \leftarrow 0]^- \\ &\mid [x_3 \leftarrow 0]^+ S [x_3 \leftarrow 0]^- \\ &\mid q \end{aligned}$$

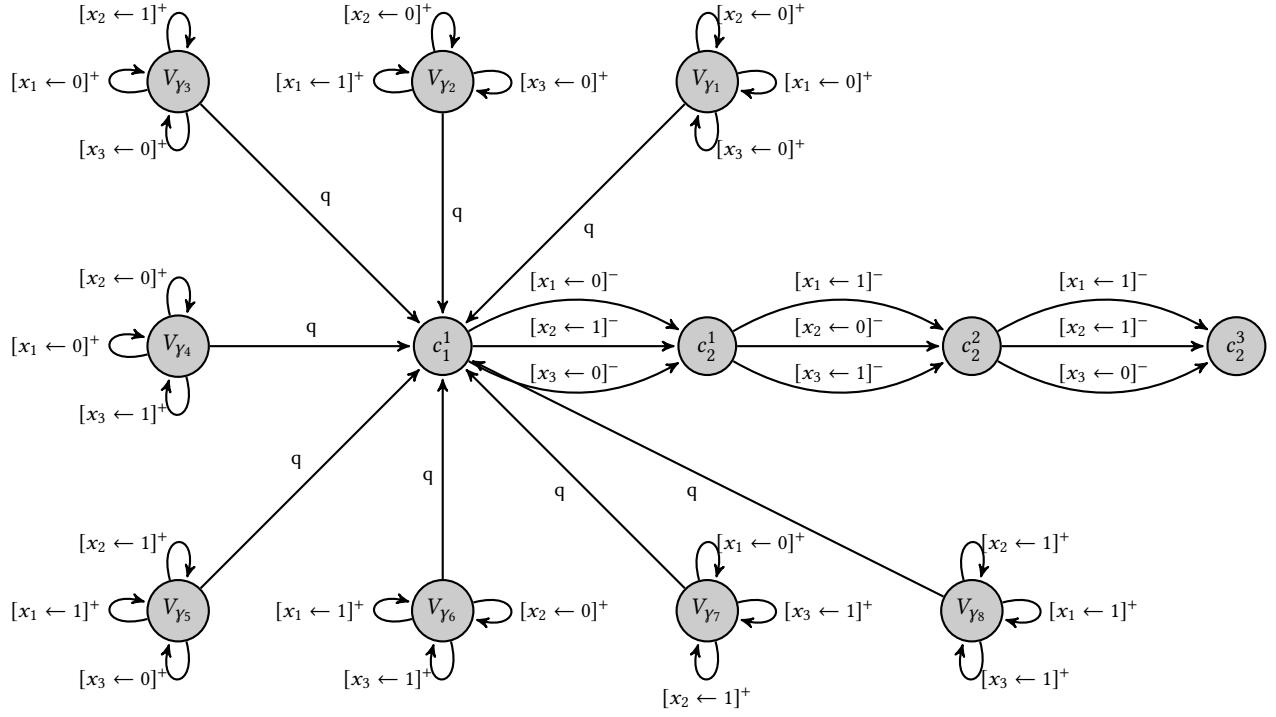
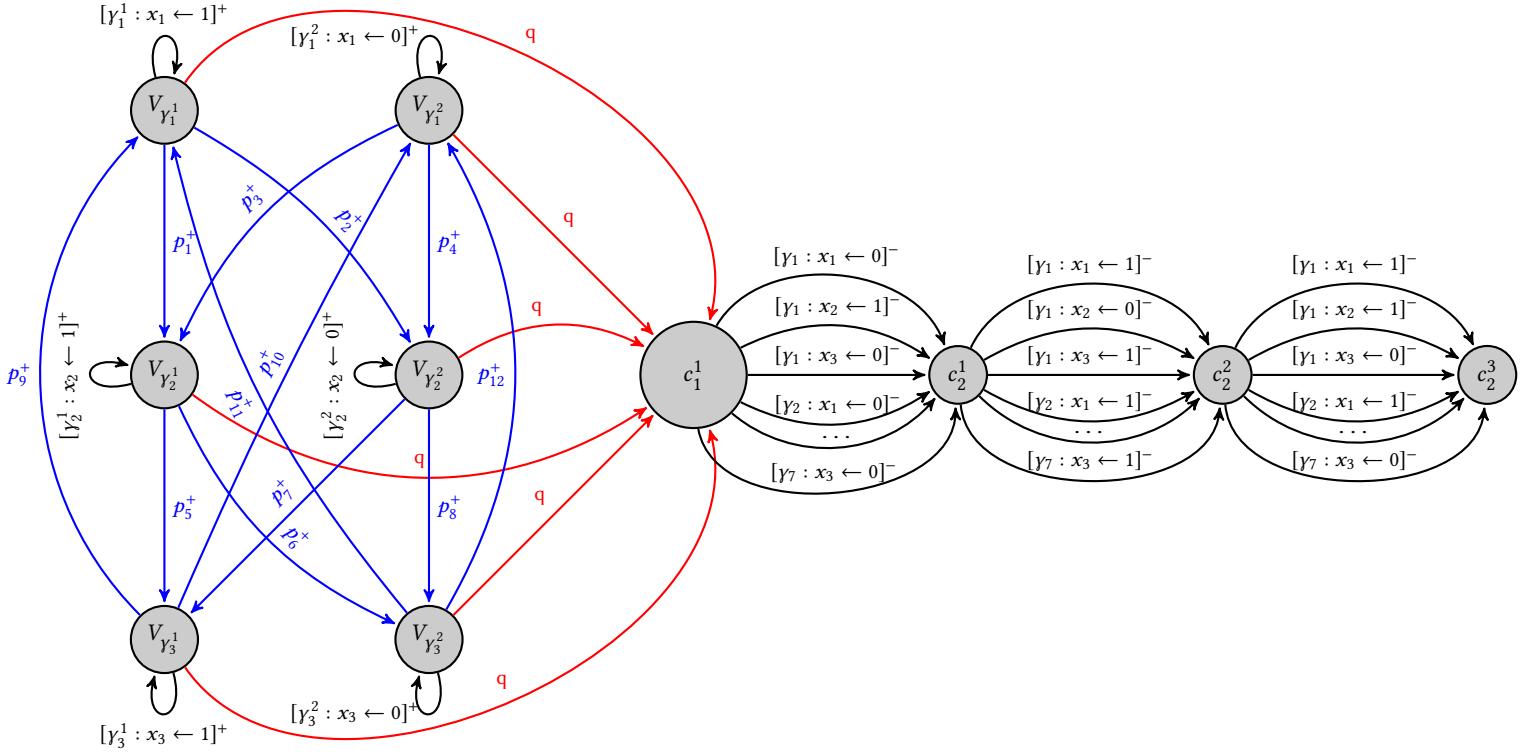
The intuition of such path finding is that substitution vertex ( $V_{\gamma_i}$ ) should provide appropriate values for respective variable in appropriate order to satisfy the given formula. It can be done by appropriate traversing of loops. After that, each edge from  $c_l^j$  to  $c_l^k$  “uses” provided values to satisfy respective closure, and it can be done if and only if the respective vertex provides value required. This fact is expressed by using balanced-bracket grammar. So, if there exists a path from  $V_{\gamma_i}$  to  $c_2^3$ , such that the corresponded word is derivable from  $S$ , then  $V_{\gamma_i}$  satisfy the given formula.

## 1.2 Improved reduction

First step is to split variables into three groups of the same size. Suppose this splitting preserves the order. So, we have a set of partial substitutions. For our example:

$$\begin{aligned} \gamma_1^1 &= \{x_1 \leftarrow 1\} \\ \gamma_1^2 &= \{x_1 \leftarrow 0\} \\ \gamma_2^1 &= \{x_2 \leftarrow 1\} \\ \gamma_2^2 &= \{x_2 \leftarrow 0\} \\ \gamma_3^1 &= \{x_3 \leftarrow 1\} \\ \gamma_3^2 &= \{x_3 \leftarrow 0\} \end{aligned}$$

By the same way we create vertices for partial substitutions.

Figure 1: Example of graph for  $\Phi$ Figure 2: Example of graph for  $\Phi$

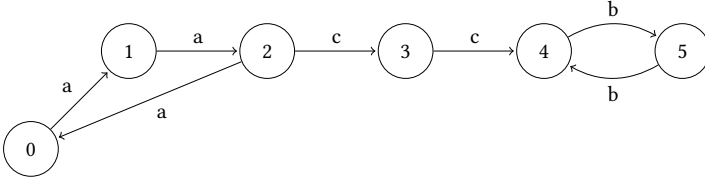
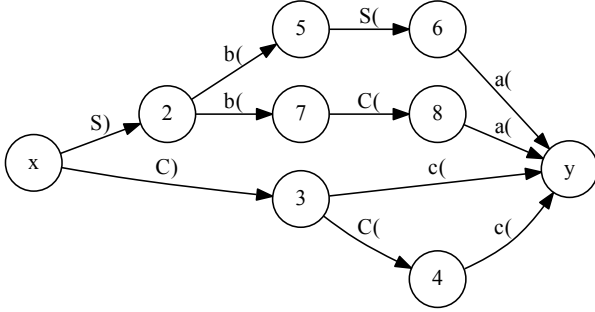


Figure 3: The input graph

Figure 4: The  $M_G$  graph

## 2 FROM ARBITRARY CFPQ TO DYCK QUERY

This reduction is inspired by the construction described in [1].

Consider a context-free grammar  $\mathcal{G} = (\Sigma, N, P, S)$  in BNF where  $\Sigma$  is a terminal alphabet,  $N$  is a nonterminal alphabet,  $P$  is a set of productions,  $S \in N$  is a start nonterminal. Also we denote a directed labeled graph by  $G = (V, E, L)$  where  $E \subseteq V \times L \times V$  and  $L \subseteq \Sigma$ .

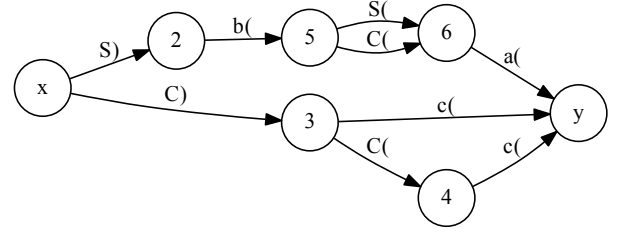
We should construct new input graph  $G'$  and new grammar  $\mathcal{G}'$  such that  $\mathcal{G}'$  specifies a Dyck language and there is a simple mapping from  $\text{CFPQ}(\mathcal{G}', G')$  to  $\text{CFPQ}(\mathcal{G}, G)$ . Step-by-step example with description is provided below.

Let the input grammar is

$$\begin{aligned} S &\rightarrow a S b \mid a C b \\ C &\rightarrow c \mid C c \end{aligned}$$

The input graph is presented in fig. 3.

- (1) Let  $\Sigma_0 = \{t_i \mid t \in \Sigma\}$ .
- (2) Let  $N_0 = \{N_i \mid N \in N\}$ .
- (3) Let  $M_G = (V_G, E_G, L_G)$  is a directed labeled graph, where  $L_G \subseteq (\Sigma_0 \cup N_0)$ . This graph is created the same manner as described in [1] but we do not require the grammar be in CNF. Let  $x \in V_G$  and  $y \in V_G$  is "start" and "final" vertices respectively. This graph may be treated as a finite automaton, so it can be minimized and we can compute an  $\varepsilon$ -closure if the input grammar contains  $\varepsilon$  productions. The graph  $M_G$  for our example is presented in fig. 4. The minimized graph is presented in fig. 5.
- (4) For each  $v \in V$  create  $M_G^v$ : unique instance of  $M_G$ .
- (5) New graph  $G'$  is a graph  $G$  where each label  $t$  is replaced with  $t_i^i$  and some additional edges are created:
  - Add an edge  $(v', S_i, v)$  for each  $v \in V$ .
  - And the respective  $M_G^v$  for each  $v \in V$ :
    - reattach all edges incoming to  $y^v$  ("final" vertex of  $M_G^v$ ) to  $v$ .

Figure 5: The minimized  $M_G$ 

- reattach all edges incoming to  $y^v$  ("final" vertex of  $M_G^v$ ) to  $v$ .

New input graph is ready. It is presented in fig. 6.

- (6) New grammar  $\mathcal{G}' = (\Sigma', N', P', S')$  where  $\Sigma' = \Sigma_0 \cup N_0$ ,  $N' = \{S'\}$ ,  $P' = \{S' \rightarrow b_i S' b_i; S' \rightarrow b_i b_i \mid b_i, b_i \in \Sigma'\} \cup \{S' \rightarrow S' S'\}$  is a set of productions,  $S' \in N'$  is a start nonterminal.

Now, if  $\text{CFPQ}(\mathcal{G}', G')$  contains a pair  $(u'_0, v')$  such that  $e = (u'_0, S_i, u'_1) \in E'$  is an extension edge (step 5, first subitem), then  $(u'_1, v') \in \text{CFPQ}(\mathcal{G}, G)$ .

In our example, we can find the following path:  $7 \xrightarrow{S_i} 1 \xrightarrow{S_i} 22 \xrightarrow{b_i} 25 \xrightarrow{C_i} 26 \xrightarrow{a_i} 1 \xrightarrow{a_i} 2 \xrightarrow{C_i} 33 \xrightarrow{C_i} 34 \xrightarrow{c_i} 2 \xrightarrow{C_i} 3 \xrightarrow{c_i} 43 \xrightarrow{c_i} 3 \xrightarrow{c_i} 4 \xrightarrow{b_i} 5$ . Edge  $7 \xrightarrow{S_i} 1$  is the extension, so  $(1, 5)$  should be in  $\text{CFPQ}(\mathcal{G}, G)$  and it is true.

## REFERENCES

- [1] Krishnendu Chatterjee, Bhavya Choudhary, and Andreas Pavlogiannis. 2017. Optimal Dyck Reachability for Data-dependence and Alias Analysis. *Proc. ACM Program. Lang.* 2, POPL, Article 30 (Dec. 2017), 30 pages. <https://doi.org/10.1145/3158118>

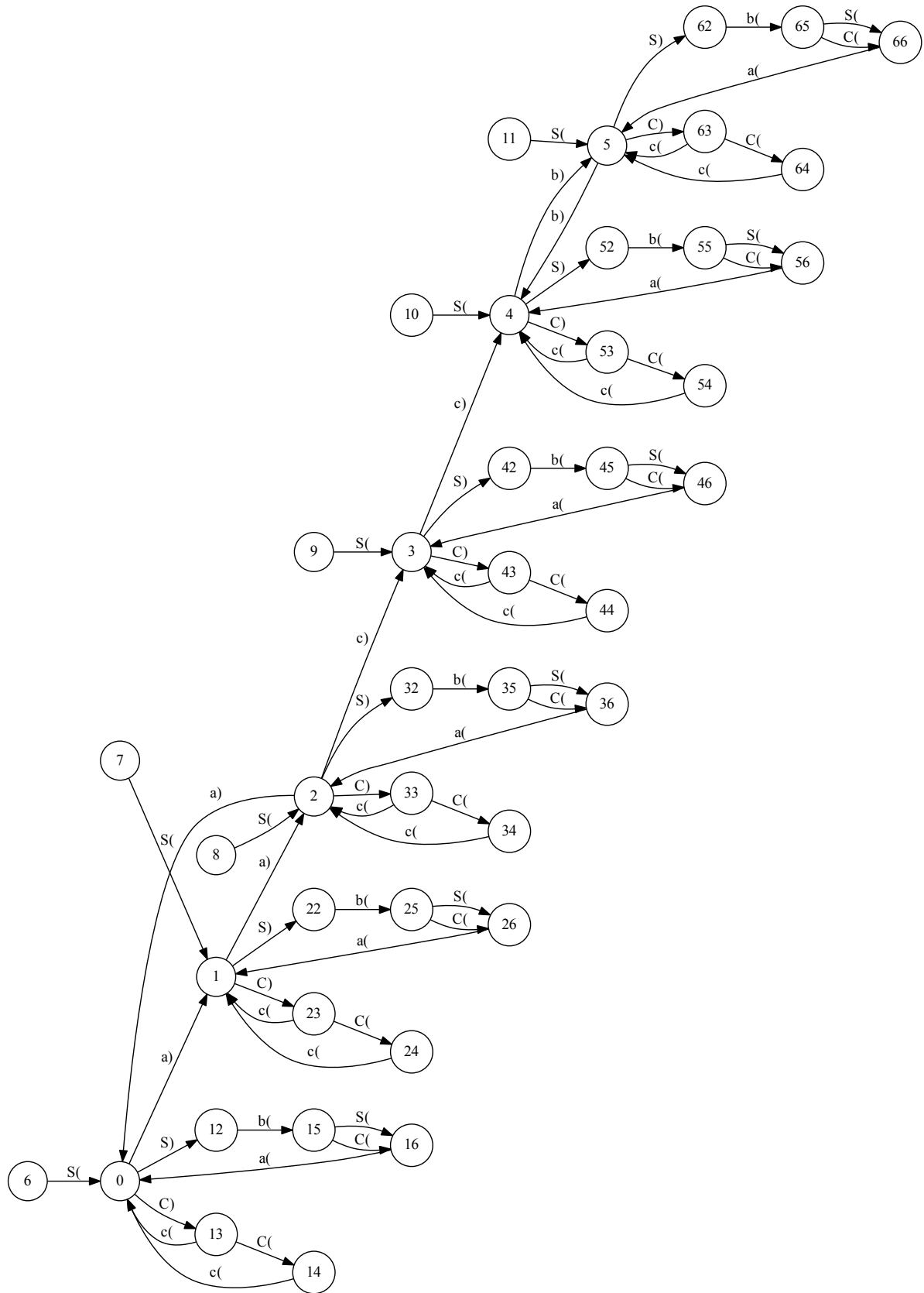


Figure 6: New input graph