

Multiple-Source Context-Free Path Querying in Terms of Linear Algebra

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ABSTRACT

A long time ago in a galaxy far far away... Abstract is very abstract.

1 INTRODUCTION

Language-constrained path querying [2] is a way to find paths in edge-labeled graphs with constraints are formulated in terms of language which restrict words formed by paths: the word formed by path's labels concatenation should be in the specified language. This way is very natural for navigational queries in graph databases, and one of the most popular languages which are used for such constraints is a regular language. But in some cases, regular languages are not expressive enough, as a result, context-free languages gain popularity. Constraints in the form of context-free languages, or context-free path querying (CFPQ), can be used for RDF analysis [16], biological data analysis [14], static code analysis [13, 17], and in other areas.

Big amount of research done on CFPQ, a number of CFPQ algorithms were proposed, but the application of context-free constraints for real-world data analysis faced with some problems. The first problem is a bad performance of proposed algorithms on real-world data, as was shown by Jochem Kuijpers et al. [8]. The second problem is that there are no graph databases with full-stack support of CFPQ, the main effort was made in algorithms and their theoretical properties research. This fact hinders research of problems reducible to CFPQ, thus it hinders the development of new solutions for some problems. For example, recently graph segmentation in data provenance analysis was reduced to CFPQ [10], but authors faced the problem during

the evaluation of the proposed approach: no one graph database support CFPQ.

In [1] Rustam Azimov proposed a matrix-based algorithm for CFPQ. This algorithm is one of promising way to solve the first problem and provide performant solution for real-world data analysis, as was shown by Nikita Mishim et al. in [11] and Arseniy Terekhov et al. in [15]. But this algorithm always computes information (reachability facts or single path which satisfies constraints) for all pairs of vertices in the graph, namely it solves *all-pairs* context-free path querying problem. Handling of all possible pairs is unreasonable in some real-world scenarios when one can provide a relatively small set of start vertices or even single start vertex.

While all-pairs context-free path querying is a classical problem that investigates in a number of works, there is no, in our knowledge, solutions for single-source and multiple-source CFPQ. In this work we propose a matrix-based *multiple-source* (and *single-source* as a partial case) CFPQ algorithm.

To solve the second problem, we provide full-stack support of CFPQ for the RedisGraph¹ [3] graph database. We implement a Cypher query language extension² that allows one to express context-free constraints, and extend the RedisGraph to support this extension. In our knowledge, it is the first full-stack implementation of CFPQ.

To summarize, we make the following contribution in this paper.

- (1) We modify Azimov's matrix-based CFPQ algorithm and provide a multiple-source matrix-based CFPQ algorithm. As a partial case, it is possible to use our algorithm in a single-source scenario. Our modification still based on linear algebra, hence it is simple to implementation and allows one to use high-performance libraries for implementation and utilize modern parallel hardware for queries evaluation.
- (2) We evaluate the proposed algorithm. Our evaluation shows that !!!
- (3) We provide full-stack support of CFPQ by extending the RedisGraph graph database. To do it, we extend Cypher

¹RedisGraph graph database Web-page: <https://redislabs.com/redis-enterprise/redis-graph/>. Access date: 19.07.2020.

²Proposal which describes path patterns specification syntax for Cypher query language: <https://github.com/thobe/openCypher/blob/rpq/cip/1.accepted/CIP2017-02-06-Path-Patterns.adoc>. The proposed syntax allows one to specify context-free constraints. Access date: 19.07.2020.

with syntax allows one to express context-free constraints, implement the proposed algorithm in a RedisGraph backend, and support new syntax in the RedisGraph query execution engine. Finally, evaluate the proposed solution.

2 PRELIMINARIES

In this section we introduce common definitions in graph theory and formal language theory which will be used in this paper. Also, we provide brief description of Azimov's algorithm which is used as a base of our solution.

2.1 Basic definitions of Graph Theory

In this work we use labeled directed graph as a data model and define it as follows.

Definition 2.1. *Labeled directed graph* is a tuple of six elements $\mathcal{D} = (V, E, \Sigma_V, \Sigma_E, \lambda_V, \lambda_E)$, where

- Σ_V and Σ_E is a set of labels of vertices and edges respectively, such that $\Sigma_V \cap \Sigma_E = \emptyset$.
- V is a set of vertices. For simplicity, we assume that the vertices are natural numbers from 1 to $|V|$.
- $E \subseteq V \times V$ is a set of edges.
- $\lambda_V : V \rightarrow 2^{\Sigma_V}$ is a function that maps a vertex to a set of its labels, which can be empty.
- $\lambda_E : E \rightarrow 2^{\Sigma_E} \setminus \{\emptyset\}$ is a function that maps a edge to a not empty set of its labels, so each edge must have at least one label.

An example of the labeled directed graph D_1 is presented in figure 1. Here the set of labels $\Sigma_V = \{x, y\}$ and $\Sigma_E = \{a, b, c, d\}$.

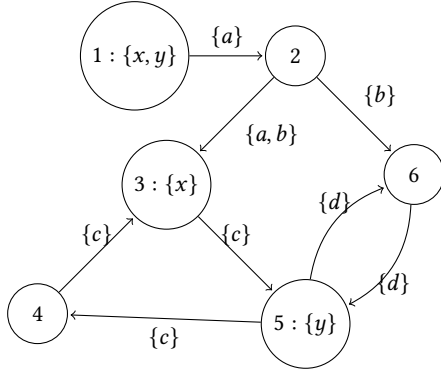


Figure 1: The example of input graph \mathcal{D}

Let's denote \mathcal{D} as a labeled directed graph $(V, E, \Sigma_V, \Sigma_E, \lambda_V, \lambda_E)$ for the following definitions. Also we identify a Boolean $|V| \times |V|$ matrix A and binary relation $R \in V \times V$ in the following way:

$$A \equiv R \iff R = \{(i, j) \mid A[i, j] = 1\}$$

Definition 2.2. Path π in the graph \mathcal{D} is a tuple of arbitrary $2n+1$ length $(v_1, e_1, v_2, e_2, \dots, e_n, v_{n+1})$, where $\forall i \mid 1 \leq n+1 \mid v_i \in V, \forall j \mid 1 \leq j \leq n \mid e_j = (v_j, v_{j+1}) \in E$.

We denote the set of all possible paths in the graph \mathcal{D} as $\pi(\mathcal{D})$.

Definition 2.3. An *adjacency matrix* M of the graph \mathcal{D} is a square $|V| \times |V|$ matrix, such that

$$M[i, j] = \begin{cases} \lambda_E((i, j)), & (i, j) \in E \\ \emptyset, & \text{else} \end{cases}$$

For example adjacency matrix M of the graph D_1 is

$$M = \begin{pmatrix} \emptyset & \{a\} & \emptyset & \emptyset & \emptyset & \emptyset \\ \emptyset & \emptyset & \{a, b\} & \emptyset & \emptyset & \{b\} \\ \emptyset & \emptyset & \emptyset & \emptyset & \{d\} & \emptyset \\ \emptyset & \emptyset & \{c\} & \emptyset & \emptyset & \emptyset \\ \emptyset & \emptyset & \emptyset & \{c\} & \emptyset & \{d\} \\ \emptyset & \emptyset & \emptyset & \emptyset & \{d\} & \emptyset \end{pmatrix}.$$

Definition 2.4. Let M be an adjacency matrix of the graph \mathcal{D} . Then the *adjacency matrix of label $l \in \Sigma_E$* of graph \mathcal{D} is a $|V| \times |V|$ matrix \mathcal{E}^l , such that

$$\mathcal{E}^l[i, j] = \begin{cases} 1, & l \in M[i, j] \\ 0, & \text{else} \end{cases}$$

Definition 2.5. *Boolean decomposition of adjacency matrix M* of the graph \mathcal{D} is a set of Boolean matrices

$$\mathcal{E} = \{\mathcal{E}^l \mid l \in \Sigma\},$$

where \mathcal{E}^l is the adjacency matrix of label l .

For example, adjacency matrix M of the example graph D_1 can be represented as a set of four Boolean matrices $\mathcal{E}^a, \mathcal{E}^b, \mathcal{E}^c$ and \mathcal{E}^d such that

$$\mathcal{E}^a = \begin{pmatrix} \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 1 & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & 1 & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix}, \mathcal{E}^b = \begin{pmatrix} \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix},$$

$$\mathcal{E}^c = \begin{pmatrix} \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & 1 & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & 1 & \cdot \\ \cdot & \cdot & 1 & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix}, \mathcal{E}^d = \begin{pmatrix} \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & 1 \\ \cdot & \cdot & \cdot & \cdot & 1 & \cdot \end{pmatrix}.$$

Definition 2.6. An *vertex label matrix* H of the graph \mathcal{D} is a square $|V| \times |V|$ matrix, such that

$$H[i, j] = \begin{cases} \lambda_V(i), & i = j \\ \emptyset, & \text{else} \end{cases}$$

For example, the vertex label matrix H of the example graph D_1 is the following:

$$H = \begin{pmatrix} \{x, y\} & \emptyset & \emptyset & \emptyset & \emptyset & \emptyset \\ \emptyset & \emptyset & \emptyset & \emptyset & \emptyset & \emptyset \\ \emptyset & \emptyset & \{x\} & \emptyset & \emptyset & \emptyset \\ \emptyset & \emptyset & \emptyset & \emptyset & \emptyset & \emptyset \\ \emptyset & \emptyset & \emptyset & \emptyset & \{y\} & \emptyset \\ \emptyset & \emptyset & \emptyset & \emptyset & \emptyset & \emptyset \end{pmatrix}.$$

Definition 2.7. Let H be a vertex label matrix of graph \mathcal{D} . Then the *vertex matrix of label l* is a square $|V| \times |V|$ matrix \mathcal{V}^l , such that

$$\mathcal{V}^l[i, j] = \begin{cases} 1, & l \in H[i, j] \\ 0, & \text{else} \end{cases}$$

Definition 2.8. Boolean decomposition of vertex label matrix H of the graph \mathcal{D} is the set of Boolean matrices

$$\mathcal{V} = \{\mathcal{V}^l \mid l \in \Sigma\},$$

where \mathcal{V}^l is a vertex matrix of label l .

For example, vertex label matrix H of the example graph D_1 can be decomposed into a set of the following boolean matrices:

$$\mathcal{V}^x = \begin{pmatrix} 1 & . & . & . & . & . \\ . & . & . & . & . & . \\ . & . & 1 & . & . & . \\ . & . & . & . & . & . \\ . & . & . & . & . & . \\ . & . & . & . & . & . \end{pmatrix}, \mathcal{V}^y = \begin{pmatrix} . & . & . & . & . & . \\ . & . & . & . & . & . \\ . & . & . & . & . & . \\ . & . & . & . & . & . \\ . & . & . & . & 1 & . \\ . & . & . & . & . & . \end{pmatrix},$$

2.2 Basic Definitions of Formal Languages

We formulate constraints in terms of context-free languages, for this reason there are following definitions.

Definition 2.9. Let Σ be a alphabet, $A, B \in \Sigma^*$. Then concatenation of A and B is the following:

$$A \cdot B = \{ab \mid a \in A, b \in B\} \subset \Sigma^*$$

In other words concatenation of two sets contains all concatenations of elements from the first set with all elements from the second one.

Definition 2.10. Context-free grammar is a tuple $G = (N, \Sigma, P, S)$, where

- N is a finite set of nonterminals
- Σ is a finite set of terminals
- P is a finite set of productions of the following forms:
 $A \rightarrow \alpha, A \in N, \alpha \in (N \cup \Sigma)^*$
- S is a starting nonterminal

Definition 2.11. Context-free language is a language generated by a context-free grammar G :

$$L(G) = \{w \in \Sigma^* \mid S \xrightarrow[G]{*} w\}$$

Where $S \xrightarrow[G]{*} w$ denotes that a string w can be generated from a starting non-terminal S using some sequence of production rules from P .

Definition 2.12. Context-free grammar $G = (N, \Sigma, P, S)$ is said to be in *Chomsky normal form* if all productions in P are in one of the following forms:

- $A \rightarrow BC, A \in N, B, C \in N \setminus S$
- $A \rightarrow a, A \in N, a \in \Sigma$
- $S \rightarrow \varepsilon, \varepsilon$ is an identity element of Σ^* that corresponds to empty string

Definition 2.13. Context-free grammar $G = (N, \Sigma, P, S)$ is said to be in *weak Chomsky normal form* if all productions in P are in one of the following forms:

- $A \rightarrow BC, A, B, C \in N$
- $A \rightarrow a, A \in N, a \in \Sigma$
- $A \rightarrow \varepsilon, A \in N$

In other words, weak Chomsky normal form differs from Chomsky normal form in the following:

- ε can be derived from any non-terminal
- S can be at a right part of productions

Since matrix-based CFPQ algorithms processes grammars only in weak Chomsky normal form, it should be noted that every context-free grammar can be transformed into an equivalent one in this form. Let's consider the example of the context-free

grammar $G_1 = (N, \Sigma, P, S)$, $N = \{S\}$, $\Sigma = \{c, d, y\}$ given by the two production rules:

$$\begin{aligned} S &\rightarrow cSd \\ S &\rightarrow cyd \end{aligned}$$

This grammar generates the context-free language

$$L(G_1) = \{c^n y d^n, n \in \mathbb{N}\}$$

and after transformation to weak Chomsky normal form the resulting grammar:

$$\begin{aligned} S &\rightarrow CE & E &\rightarrow YD & S &\rightarrow CS_1 & S_1 &\rightarrow SD \\ C &\rightarrow c & D &\rightarrow d & Y &\rightarrow y \end{aligned}$$

Modified context-free grammar with these productions generate the same language as the original grammar.

We use a context-free grammar in the weak Chomsky normal form without a starting non-terminal, which will be specified in the path queries for the graph. Also we omit the rules of the form $A \rightarrow \varepsilon$ for the reason that they correspond to trivial paths, which are more convenient to consider separately.

2.3 Context-Free Path Querying

Definition 2.14. Let $\mathcal{D} = (V, E, \Sigma_V, \Sigma_E, \lambda_V, \lambda_E)$ be a labeled graph, $G = (N, \Sigma_V \cup \Sigma_E, P, S)$ be a context free grammar. Then a *context free relation* with grammar G on the labeled graph \mathcal{D} is the following relation $R_{G, \mathcal{D}} \subseteq V \times V$:

$$R_{G, \mathcal{D}} = \{(v, to) \in V \times V \mid \exists \pi = (v_1, e_1, v_2, e_2, \dots, e_n, v_n) \in \pi(D) : \\ v_1 = v, v_n = to, l(\pi) \cap L(G) \neq \emptyset\},$$

where $l(\pi) \subset (\Sigma_V \cup \Sigma_E)^*$ is the set of possible labels along the path π :

$$l(\pi) = \lambda_V(v_1)^* \cdot \lambda_E(e_1) \cdot \lambda_V(v_2)^* \cdot \lambda_E(e_2) \cdot \dots \cdot \lambda_E(e_n) \cdot \lambda_V(v_n)^*$$

For example, in the labeled graph presented in figure 1 we have the path π from the vertex 3 to vertex 6. The labels along this path can form the sequence cyd . It can be observed that this sequence satisfies context-free constraints of the above grammar G_1 :

$$S \Rightarrow CE \Rightarrow cE \Rightarrow cyD \Rightarrow cyd \Rightarrow cyd$$

Hence $l(\pi) \cap L(G_1) \neq \emptyset$ and the pair $(3, 6) \in R_{G_1, \mathcal{D}}$.

Finally, in these notations we are ready to define context-free path querying problem.

Definition 2.15. Context-free path querying problem is the problem of finding context-free relations $R_{G, \mathcal{D}}$ for a graph \mathcal{D} and a context-free grammar G .

In other words, the result of context-free path query evaluation is a set of vertex pairs such that there is a path between them and its labels form a word from the language.

For above example of graph D_1 and context-free free grammar G_1 the resulting set $R_{G_1, D_1} = \{(3, 5), (5, 5), (5, 6)\}$ and the resulting matrix

$$\mathcal{M} = \begin{pmatrix} . & . & . & . & . & . \\ . & . & . & . & . & . \\ . & . & . & . & 1 & . \\ . & . & . & . & . & . \\ . & . & . & . & 1 & 1 \\ . & . & . & . & . & . \end{pmatrix}.$$

2.4 Matrix-Based Algorithm

Our algorithm is based on the Azimov's algorithm which solves CFPQ problem in special case when we need to find paths for all vertex pairs.

Let $G = (N, \Sigma, P)$ be the input grammar, the input edge-labeled graph $\mathcal{D} = (V, E, \Sigma_V, \Sigma_E, \lambda_V, \lambda_E)$ and language L over alphabet Σ . For the context-free path query evaluation, we need to provide context-free relations $R_A \subseteq V \times V$ for every $A \in N$. The matrix-based algorithm for CFPQ can be expressed in terms of operations over Boolean matrices (see listing 1) which is an advantage for implementation.

Algorithm 1 Context-free path querying algorithm

```

1: function EVALCFPQ( $\mathcal{D} = (V, E), G = (N, \Sigma, P)$ )
2:    $n \leftarrow |V|$ 
3:    $T \leftarrow \{T^{A_i} \mid A_i \in N, T^{A_i} \text{ is a matrix } n \times n, T_{k,i}^{A_i} \leftarrow \text{false}\}$ 
4:   for all  $(i, x, j) \in E, A_k \mid A_k \rightarrow x \in P$  do  $T_{i,j}^{A_k} \leftarrow \text{true}$ 
5:   for all  $A_k \mid A_k \rightarrow \varepsilon \in P$  do
6:     for all  $i \in \{0, \dots, n-1\}$  do  $T_{i,i}^{A_k} \leftarrow \text{true}$ 
7:   while any matrix in  $T$  is changing do
8:     for  $A_i \rightarrow A_j A_k \in P$  do  $T^{A_i} \leftarrow T^{A_i} + (T^{A_j} \times T^{A_k})$ 
9:   return  $T$ 

```

This CFPQ algorithm allows efficiently apply GPGPU techniques, but it solves all-pairs problem and takes unreasonable amount of memory in scenarios in which we want to find paths from a relatively small set of vertices, since it calculates a lot of redundant information.

3 MATRIX-BASED MULTIPLE-SOURCE CFPQ ALGORITHM

In this section we introduce two versions of multiple-source matrix-based CFPQ algorithm. This algorithm is a modification of Azimov's matrix-based algorithm for CFPQ and its idea is that we cut off those vertices from which we are not interested in paths.

Let $\mathcal{G} = (N, \Sigma, P)$ be the input context-free grammar, $\mathcal{D} = (V, E, \Sigma_V, \Sigma_E, \lambda_V, \lambda_E)$ be the input graph and Src be the input set of vertices. For the multiple-source context-free path query evaluation for every $A \in Src$ we need to find all context-free relations R_A , i.e. all node pairs (n, m) such that $\exists \pi m (l(\pi) \in L(\mathcal{G}_A))$. In order to solve the single-source and multiple-source CFPQ problem Azimov's algorithm was modified: operations of Boolean matrix multiplication $T_A = T_A + T_B \cdot T_C$ for each $A \rightarrow BC \in R$ represented in line 8 of Algorithm 1 was supplemented with one more matrix multiplication $T_A = T_A + (T_{Src^A} \cdot T_B) \cdot T_C$ for each $A \rightarrow BC \in R$ which saves only vertices we are interested in, where T_{Src^A} — matrix of vertices to calculate the paths from. It is represented in lines 11-13 of the Algorithm 2. Also, after every iteration of while loop this is necessary to update the set of vertices paths from which we need to calculate. To do this, the function **getDst**, represented in lines 17-21, is called at line 14. Thus, the modified algorithm does not calculate the paths from all vertices in case of query to calculate the paths small set of vertices.

We proposed the variant of the algorithm that can calculate the paths from a certain set of vertices, however there are such scenarios when queries are partially or completely repeated. In such cases it would be useful to add data caching to improve the performance. The problem is that every time we want to find all paths from the certain set of vertices, the Algorithm 2

Algorithm 2 Multiple-source context-free path querying algorithm

```

1: function MULTISRCFPQ( $\mathcal{D} = (V, E, \Sigma_V, \Sigma_E, \lambda_V, \lambda_E), \mathcal{G} = (N, \Sigma, P, S), Src$ )
2:    $T \leftarrow \{T^A \mid A \in N, T^A \leftarrow \emptyset\}$   $\triangleright$  Matrix in which every element is 0
3:    $T_{Src} \leftarrow \{T_{Src}^A \mid A \in N \setminus S, T_{Src}^A \leftarrow \emptyset\}$   $\triangleright$  Matrix for input vertices in which every element is 0
4:   for all  $v \in Src$  do  $\triangleright$  Input matrix initialization
5:      $T_{v,v}^{Src} \leftarrow \text{true}$ 
6:   for all  $A \rightarrow x \in P$  do  $\triangleright$  Simple rules initialization
7:     for all  $(v, x, to) \in E$  do
8:        $T_{v,to}^A \leftarrow \text{true}$ 
9:   while  $T$  or  $T_{Src}$  is changing do  $\triangleright$  Algorithm's body
10:    for all  $A \rightarrow BC \in P$  do
11:       $M \leftarrow T_{Src^A} * T^B$ 
12:       $T^A \leftarrow T^A + M * T^C$ 
13:       $T_{Src^B} \leftarrow T_{Src^B} + T_{Src^A}$ 
14:       $T_{Src^C} \leftarrow T_{Src^C} + \text{GETDST}(M)$ 
15:    return  $T$ 
16:
17: function GETDST( $M$ )
18:    $A \leftarrow \emptyset$ 
19:   for all  $(v, to) \in V^2 \mid M_{v,to} = \text{true}$  do
20:      $A_{to,to} \leftarrow \text{true}$ 
21:   return  $A$ 

```

calculates everything from scratch. Since recalculating might take the significant amount of time, we modified multiple-source CFPQ algorithm to specify it for such scenarios. This version stores all the vertices the paths from which have already been calculated in cash *index*, which is used to filter such vertices in line 3 of Algorithm 3. Thus, modified algorithm calculates paths from the particular vertex only once.

Algorithm 3 Optimized multiple-source context-free path querying algorithm

```

1: function MULTISRCFPQSMART( $index = (\mathcal{D}, \mathcal{G}, T, T_{Src}), Src$ )
2:    $T_{NewSrc} \leftarrow \{T_{NewSrc}^A \mid A \in N \setminus S, T_{NewSrc}^A \leftarrow \emptyset\}$ 
3:   for all  $v \in Src \mid index.T_{Src,v} = \text{false}$  do
4:      $T_{NewSrc}_{v,v}^{Src} \leftarrow \text{true}$ 
5:   while  $index.T$  or  $T_{NewSrc}$  is changing do
6:     for all  $A \rightarrow BC \in P$  do
7:        $M \leftarrow T_{NewSrc^A} * index.T^B$ 
8:        $index.T^A \leftarrow index.T^A + M * index.T^C$ 
9:        $T_{NewSrc^B} \leftarrow T_{NewSrc^B} + T_{NewSrc^A} \setminus index.T_{Src^B}$ 
10:       $T_{NewSrc^C} \leftarrow T_{NewSrc^C} + \text{GETDST}(M) \setminus index.T_{Src^C}$ 

```

3.1 Implementation Details

All of the above versions have been implemented³ using GraphBLAS framework that allows you to represent graphs as matrices and work with them in terms of linear algebra. For convenience,

³GitHub repository with implemented algorithms: https://github.com/JetBrains-Research/CFPQ_PyAlgo, last accessed 28.08.2020

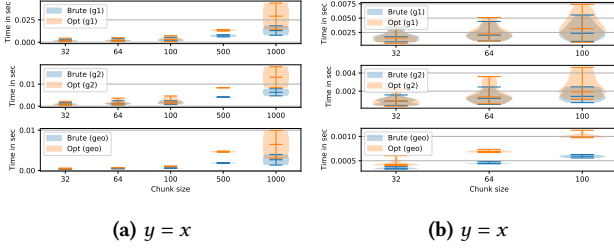


Figure 2: Single path extraction

all the code is written in Python using pygraphblas⁴, which is Python wrapper around GraphBLAS API and based on SuiteSparse:GraphBLAS⁵ [4] – the full implementation of GraphBLAS standard. This library is specialized for working with sparse matrices, which most often appear in real graphs. Also, it should be noted that, despite the fact that the function `getDst` does not seem to be expressed in terms of linear algebra, the implementation used the function `reduce_vector` from pygraphblas that reduces matrix to a vector, with which further work takes place.

3.2 Algorithm Evaluation

We evaluate both described version of multiple-source algorithm on real-world graphs. For evaluation, we use a PC with Ubuntu 20.04 installed. It has Intel core i7-4790 CPU, 3.60GHz, and DDR3 32Gb RAM. As far as we evaluate only algorithm execution time, we store each graph fully in RAM as its adjacency matrix in sparse format. Note, that graph loading time is not included in the result time of evaluation.

For evaluation we use graphs and queries from CFPQ Data dataset⁶. Detailed information on graphs which we select for evaluation is provided in table 1. We use classical same-generation queries G_1 (eq. 1) and G_2 (eq. 2) which are used in other works for CFPQ evaluation. Also we use Geo (eq. 3) query which was provided by J. Kuijpers et. al [8] for *geospecies* RDF. Note that in queries we use \bar{x} notation to denote inverse of x relation and respective edge.

$$S \rightarrow \overline{\text{subClassOf}} S \text{ subClassOf} | \overline{\text{type}} S \text{ type} | \overline{\text{subClassOf}} \text{ subClassOf} | \overline{\text{type}} \text{ type} \quad (1)$$

$$S \rightarrow \overline{\text{subClassOf}} S \text{ subClassOf} | \text{subClassOf} \quad (2)$$

$$S \rightarrow \overline{\text{broaderTransitive}} S \overline{\text{broaderTransitive}} | \overline{\text{broaderTransitive}} \text{ broaderTransitive} \quad (3)$$

Our main goal is to compare behavior of two proposed versions of the algorithm. To do it we measure query execution time for both versions for different sizes of star vertex set. Namely, for each graph we split all vertices into disjoint subsets of fixed size. After that, for each subset we evaluate queries using the given subset as a set of start vertices.

Results of evaluation is presented in figures !!!!.

We can see, that As a result, we select !!! to integrate into RedisGraph!!!

⁴GitHub repository of PyGraphBLAS library: <https://github.com/michelp/pygraphblas>

⁵GitHub repository of SuiteSparse:GraphBLAS library: <https://github.com/DrTimothyAldenDavis/SuiteSparse>

⁶CFPQ Data is a dataset for CFPQ evaluation which contains both synthetic and real-world data and queries https://github.com/JetBrains-Research/CFPQ_Data, last accessed 28.08.2020.

Table 1: Graphs for CFPQ evaluation

Graph	#V	#E	#subCalssOf	#type	#broaderTrans
gohierarchy	45007	980218	490109	0	0
go	582929	1758432	94514	226481	0
skos	144	323	1	70	0
funding	778	1480	90	304	0
eclass_514en	239111	523727	90962	72517	0
atom-primitive	291	685	122	138	0
generations	129	351	0	78	0
wine	733	2450	126	485	0
travel	131	397	30	90	0
geospecies	450609	2311461	0	89062	20867
univ-bench	179	413	36	84	0
taxonomyhierarchy	2112625	65752578	32876289	0	0
biomedical-mesure-primitive	341	711	122	130	0
pathways	6238	18598	3117	3118	0
enzyme	48815	117851	8163	14989	8156
people_pets	337	834	33	161	0
taxonomy	5728398	19543397	2112637	2508635	0
pizza	671	2604	259	365	0
foaf	256	815	10	174	0
core	1323	3636	178	706	0

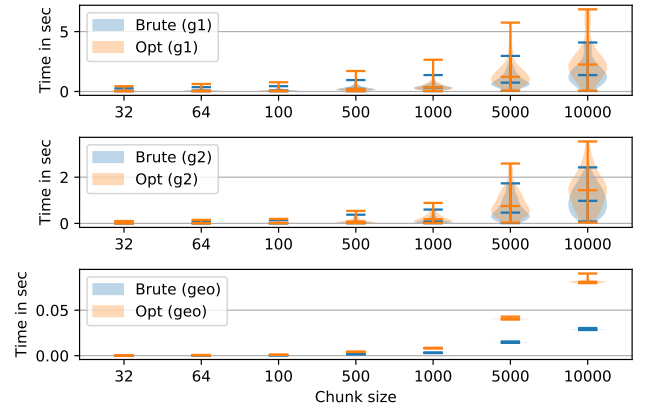


Figure 3: Example of a parametric plot ($\sin(x)$, $\cos(x)$, x)

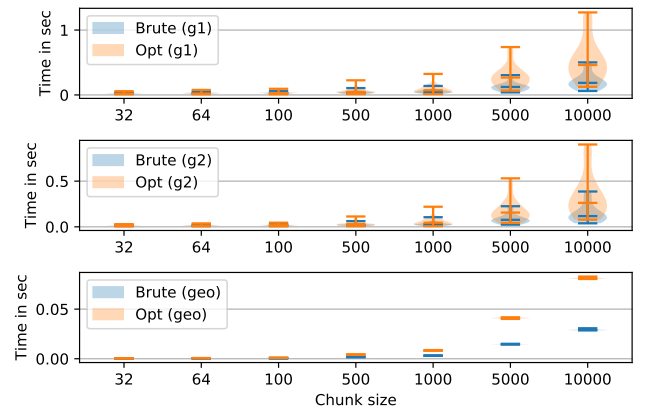


Figure 4: Example of a parametric plot ($\sin(x)$, $\cos(x)$, x)

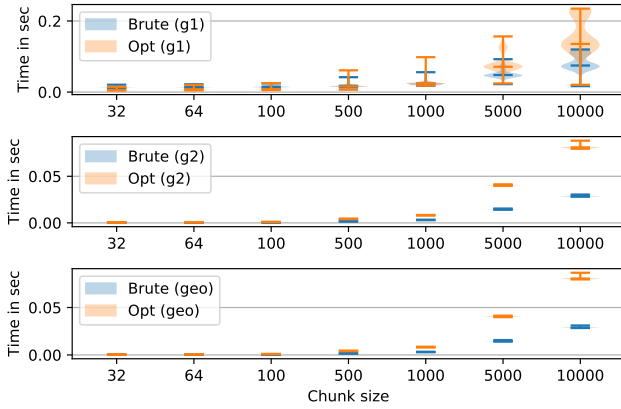


Figure 5: Example of a parametric plot ($\sin(x)$, $\cos(x)$, x)

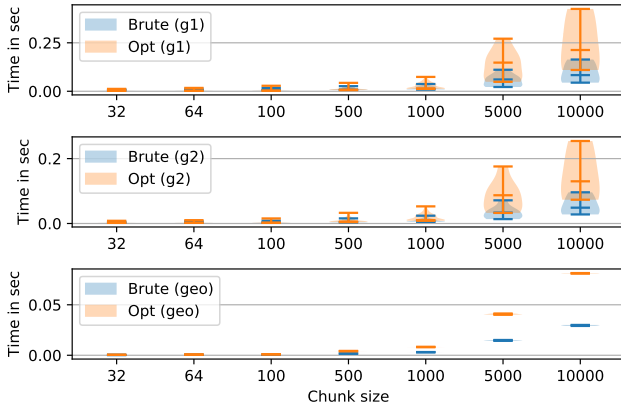


Figure 6: Example of a parametric plot ($\sin(x)$, $\cos(x)$, x)

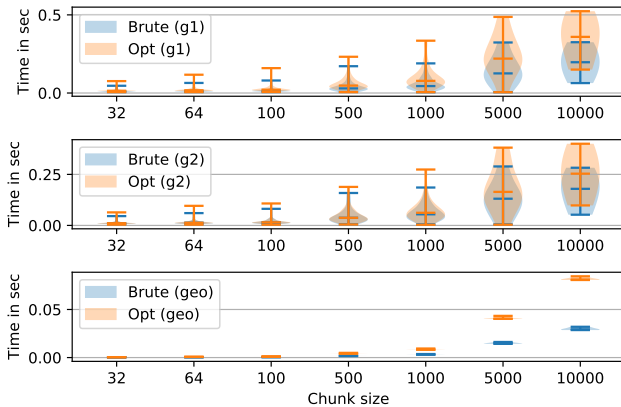


Figure 7: Example of a parametric plot ($\sin(x)$, $\cos(x)$, x)

4 CFPQ FULL-STACK SUPPORT

In order to provide full-stack support of CFPQ it is necessary to choose an appropriate graph database. It was shown by Arseniy Terekhov et al. in [15] that matrix-based algorithm can be naturally integrated into RedisGraph graph database because both, the algorithm and the database, operates over matrix representation of graphs. Moreover, RedisGraph supports Cypher as a

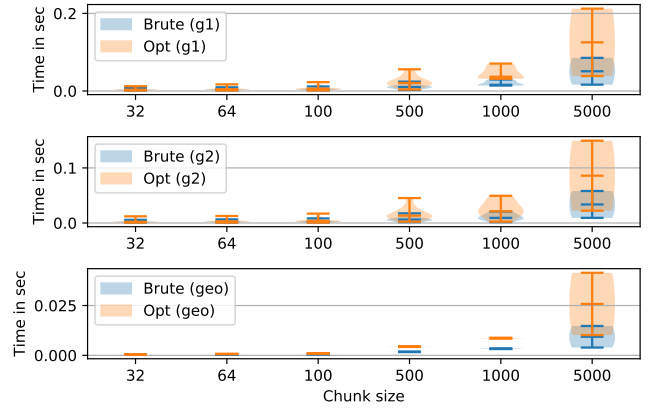


Figure 8: Example of a parametric plot ($\sin(x)$, $\cos(x)$, x)

query language and there is a proposal which describes Cypher extension which allows one to specify context-free constraints. Thus we choose RedisGraph as a base for our solution.

4.1 Cypher Extending

The first what we should do is to extend Cypher to be able to express context-free constraints. There is a description of the respective Cypher syntax extension⁷, proposed by Tobias Lindaaer, but this syntax does not implement yet in Cypher parsers.

This extension introduces path patterns, which are a more powerful alternative to relationship patterns. Path patterns allow you to express regular constraints over basic patterns such as relationship and node patterns. Just like relationship patterns they can be specified in the MATCH clause between the node patterns.

Listing 4 Example of using a simple path pattern

```
1: MATCH (v)-[:a(:x):b] | [:c(:y):d] /->(to)
2: RETURN v, to
```

The listing 4 provides an example of query in extended syntax with a simple path pattern. In this example there are relationship patterns $:a$, $:b$, $:c :d$ and node patterns $(:x)$, $(:y)$. The square brackets are used for grouping parts of the pattern. The $|$ symbol denotes alternative between corresponding paths and the blank denotes sequence of paths. So the result of executing the query on the labeled graph D will be the following set of vertex pairs:

$$\{(v, to) : \exists \pi = (v, r_1, u, r_2, to) \in \pi(D) : \left. \begin{array}{l} a \in \lambda_E(r_1), x \in \lambda_V(u), b \in \lambda_E(r_2) \\ c \in \lambda_E(r_1), y \in \lambda_V(u), d \in \lambda_E(r_2) \end{array} \right\}$$

Main feature which allows one to specify context-free constraints is a *named path patterns*: one can specify a name for path pattern and after that use it in other patterns, or in the same pattern. Using this feature, structure of query is pretty similar to context-free grammar in the Extended Backus–Naur Form.

The listing 5 shows an example of using named path patterns. They can be defined in the PATH PATTERN clause and referenced within any other path pattern. In order to explain the semantics of the query let's consider context-free grammar $G = (N, \Sigma, P, S)$

⁷Formal syntax specification: <https://github.com/thobe/openCypher/blob/rpq/cip/1.accepted/CIP2017-02-06-Path-Patterns.adoc#11-syntax>. Access date: 19.07.2020.

Listing 5 Example of using a named path pattern

```

1: PATH PATTERN S = ()-[:a ~S :b] | [:a :b] /->()
2: MATCH (v)-[:a ~S /->(to)
3: RETURN v, to

```

with $N = \{S\}$, $\Sigma = \{a, b\}$ and $P = \{S \rightarrow ab, S \rightarrow aSb\}$. Then $L(G) = \{a^n b^n : n \in \mathbb{N}\}$ specifies restrictions on the path labels and query result on the graph D will be the context free relation $R_{G,D}$.

Thus this Cypher extension allows one express more complex queries including context-free path queries. RedisGraph database supports subset of Cypher language and uses `libcypher-parser`⁸ library to parse queries. We extend this library by introducing new syntax proposed⁷. We implement⁹ full extension, not only part which is necessary for simple CFPQ.

4.2 RedisGraph Intro (TODO: move to introduction)

Named path patterns described in subsection 4.1 allows one to specify context-free constraints on the paths. In order to support the execution of these types of queries we need to extend back-end of the RedisGraph database and integrate a suitable CFPQ algorithm into it.

There are quite a few algorithms that solve CFPQ problem ??, but their running time makes them unsuitable for practical use ?. Recent studies ?? have shown that one can achieve high performance through the use of matrix-based algorithms. These studies were conducted to analyze the performance of the Rustam Azimov algorithm described in ?? and have shown that it is acceptable for practical application.

Using the Rustam Azimov algorithm one can only find paths between all pairs of vertexes at once and in some cases it is quite wasteful. Queries to graph databases can be specified so that when they are executed, it is required to find paths from a given set of initial vertices. This set can be quite small due to the different filtering specified in the query. For example in the listing 7 path pattern `-[:a ~S /->` follows pattern `(v)-[:r]->(u)`.

The WHERE clause specifies some arbitrary predicate `p(v, r, u)` which also fixes a set of initial vertexes for a paths that must satisfy path pattern `S`. Depending on this predicate, this set of vertexes can have different sizes and for proper practical use the running time of the CFPQ algorithm should be sensitive to this.

Listing 6 ...

```

1: PATH PATTERN S = ()-[:A [~S | ()] :B /->()
2: MATCH (v)-[:r]->(u)-[:a ~S /->(to)
3: WHERE p(v, r, u)
4: RETURN to

```

The Multi-Source algorithm described in ?? is sensitive to the initial set of vertices and is therefore well suited for graph database query scenarios. In addition, it is based on matrix operations and works with graphs as sparse matrices, so it is suitable for integration in RedisGraph.

⁸The `libcypher-parser` is an open-source parser library for Cypher query language. GitHub repository of the project: <https://github.com/cleishm/libcypher-parser>. Access date: 19.07.2020.

⁹The modified `libcypher-parser` library with support of syntax for path patterns: <https://github.com/YaccConstructor/libcypher-parser>. Access date: 19.07.2020.

4.3 RedisGraph extension

This section describes the implementation of support for executing queries with the extended syntax in the RedisGraph. Throughout this section, we consider executing the example query from listing 7 for the graph D_1 from Figure 1. \mathcal{E} and \mathcal{V} denotes boolean decompositions of adjacency and vertex label matrices of D_1 respectively.

Listing 7 Query with path patterns example

```

1: PATH PATTERN S = ()-[:c ~S :d] | [:c (:y) :d] /->()
2: MATCH (v:x)-[:a | :c]->()-[:b ~S /->(to)
3: RETURN v, to

```

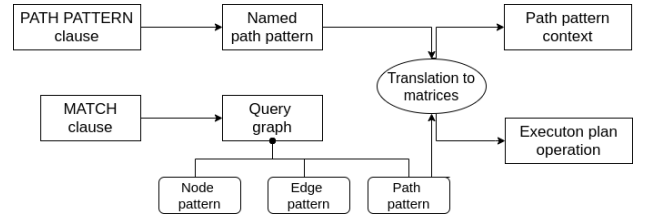


Figure 9: Extension diagram for building a query execution plan

4.3.1 Execution plan building. In the RedisGraph the main part of processing a query is building its execution plan. Execution plan consists of operations that perform basic processing such as filtering, pattern matching, aggregation and result construction. The diagram of its construction is shown in Figure 9. It can be divided into two parts — processing named and unnamed path patterns, which are described below.

Let's consider the part that associated with unnamed path patterns. Unnamed path patterns relates to the pattern matching operations and is very similar to relationship patterns from the original Cypher. All pattern matching operations are derived from the MATCH clause that consists of relationship patterns and node patterns. In the example query there is a relationship pattern $r = -[:a | :c]->$, path pattern $p = -[:b ~S /->$ and node pattern $n = (:x)$. In the first stage of processing, these patterns turn into an intermediate representation — the *query graph*. The nodes and edges of the query graph corresponds to node and relationship patterns. We extended query graph to be able to contain path patterns. Thus the query graph edges can be either relationship or path patterns, which are stored in a more convenient intermediate representation other than AST. The query graph for patterns p, r and n is shown in Figure 10.

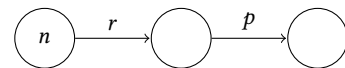


Figure 10: The example of input graph \mathcal{G}

At the second stage, the query graph is translated into algebraic expressions over matrices. The abstract syntax of an algebraic expression is provided in Figure 11. Thus the algebraic expression is an expression with addition, multiplication and transposition operations whose operands are matrices. To support references to named paths patterns in algebraic expressions

we added a matrix operand $Ref(ref)$ that stores a reference. In order to translate the query graph RedisGraph first linearizes it and then splits it into small paths. To support path patterns we extended the split processing so that each path pattern corresponds to exactly one path after query graph splitting. For example the query graph in Figure 10 is very simple and is divided into three patterns n, r and p . After that, each path is translated into a single algebraic expression. We developed the semantics of path patterns in terms of algebraic expressions and implemented translation. For example, node pattern n translates to $AlgExp(n) = \mathcal{V}^x$, relationship pattern r to $AlgExp(r) = \mathcal{E}^a + \mathcal{E}^c$ and path pattern p to $AlgExp(p) = \mathcal{E}^b * Ref(S)$.

Figure 11: Algebraic expression abstract syntax

$$\begin{aligned}
 AlgExpr = & (AlgExpr + AlgExpr) \mid \\
 & (AlgExpr * AlgExpr) \mid \\
 & Transpose(AlgExpr) \mid \\
 & Matrix \mid \\
 & Ref(ref)
 \end{aligned}$$

After obtaining algebraic expressions they are used to construct execution plan operations. Each operation is derived from a single algebraic expression that is involved in the further execution of the corresponding operation. For example for the $AlgExp(r)$ and $AlgExp(n)$ will be created $CondTraverse(AlgExp(r))$ and $LabelScan(AlgExp(n))$ operations respectively which already existed in RedisGraph. For expressions that correspond to path patterns we created a new $CFPQTraverse$ operation. Thus algebraic expression of pattern p will be stored in the new $CFPQTraverse(AlgExp(p))$ operation. During the query execution this operation performs path pattern matching and solves context-free path reachability problem if necessary. This completes the part of the query execution plan building which concerns unnamed path patterns.

Another processing that occurs during the execution plan construction and was supported by us is related to named path patterns. They are processed independently of the unnamed path patterns found in MATCH clause and don't produce execution plan operations.

All named path patterns are collected from PATH PATTERN clauses. In the example query there is a path pattern $S = () / [:c \sim S :d] / [:c (:y) :d] / \rightarrow ()$. Then this named path patterns translated into algebraic expressions and stored in the corresponding global context of the query — *path pattern context*. This storage provides mapping between the path pattern name and its algebraic expression and its relation and source matrices. Initially these matrices are empty and populated later in the execution stage. For the example query this storage will be as follows:

$$\begin{aligned}
 \{S \rightarrow \{ & expr \rightarrow \mathcal{E}^c * Ref(S) * \mathcal{E}^d + \mathcal{E}^c * \mathcal{V}^y * \mathcal{E}^d, \\
 & m_{rel} \rightarrow \emptyset, \\
 & m_{src} \rightarrow \emptyset \} \}
 \end{aligned}$$

Thus after execution plan building we receive $CFPQTraverse$ operations that correspond to unnamed path patterns in MATCH clause and *path pattern context* that stores all named path patterns from PATH PATTERN clauses. Therefore we can proceed to the stage of execution plan evaluation.

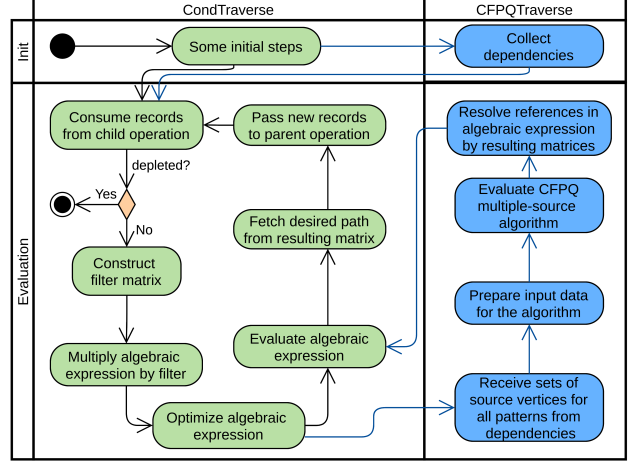


Figure 12: CFPQTraverse and CondTraverse evaluation

4.3.2 Execution plan evaluating. The remaining part of query processing is evaluation its execution plan. This section describes how the CFPQTraverse operation is performed. For explanation, we use example graph D_1 from Figure 1 and execution plan operations $LabelScan(n)$, $CondTraverse(r)$ and $CfpqTraverse(p)$ that were obtained in the previous section for example query from listing 7.

Let's first consider the structure of the execution plan operations. Operations have parent-child relationships, so they are formed into a tree. For example, the part of execution plan that derived from example query is shown in Figure 13. Each operation can consume a record from a child operation, process it and produce another one for the parent. Records contain information necessary for the parent operation, as well as everything to restore the response, such as identifiers of accumulated vertices and edges.

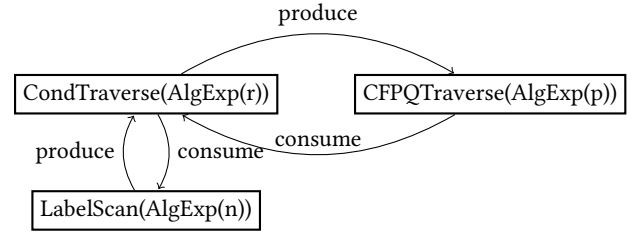


Figure 13: Example of part of the execution plan

The CFPQTraverse operation is based on CondTraverse operation that already exists in the RedisGraph and performs a patterns matching. The activity diagram of this operations is shown in Figure 12 and described below. Actions that corresponds to CondTraverse operation are highlighted in green, actions of the CFPQTraverse operation that extend CondTraverse are highlighted in blue.

The CondTraverse works as follows. At first it consumes several records from the child operation and accumulates them in the buffer. Here each record corresponds to the path that built by the child operation. For simplicity we can presume that each record is the destination vertex of the path. For example for the graph D_1 the $CondTraverse$ from Figure 13 make $LabelScan$ operation to produce vertices with the label X and then store

the resulting set of vertices $\{1, 3\}$ in the buffer. The task of the CondTraverse is to continue the path from this vertices in such way that the resulting path satisfies pattern corresponding to this operation. To do this CondTraverse uses the algebraic expression obtained in the previous step. The resulting matrix of this expression represents all pairs of vertices between which there is a path satisfying the pattern. In order to find paths that start from given sources vertices CondTraverse uses a filter matrix. This matrix is constructed from the destination vertices retrieved from the record buffer and resembles matrix from boolean decomposition of label vertex matrix. For example filter matrix of set $\{1, 3\}$ is $r_f = \{(1, 1), (3, 3)\}$. Then algebraic expression $AlgExp(r)$ is multiplied to the left by r_f and we get algebraic expression $r_f * AlgExp(r) = r_f * (\mathcal{E}^a + \mathcal{E}^c)$. Then this expression is optimized, including all distributivity rules applying. For example, for expression $r_f * (\mathcal{E}^a + \mathcal{E}^c)$ after all optimizations we get expression $r_f * \mathcal{E}^a + r_f * \mathcal{E}^c$. Only after that this expression is evaluated and we get the matrix $\{(1, 2), (3, 5)\}$. This matrix exactly corresponds to all paths of length one where the source vertex is labelled by x and the edge is labeled by a or c . Then this paths are passed to the parent operation, in our case to *CFPQTraverse*, by producing new records.

The CFPQTraverse operation is arranged in the same way as CondTraverse but performs some additional work. Since each CFPQTraverse corresponds to path pattern, its algebraic expression may contain references to named path patterns. Therefore all named path patterns that the algebraic expression depends on must be processed. For this they are stored in the *set of operation dependencies* during its initialization. In this case, dependencies are extracted recursively, so that references inside named path patterns are also extracted. For example, path pattern p depends only on named path pattern S , so the dependency set of *CFPQTraverse*(p) operation is $\{S\}$.

The CFPQTraverse execution stage starts the same way as CondTraverse one. First filter matrix is constructed from record buffer. For example, *CFPQTraverse*(p) consumes several records from CondTraverse(r), extracts from them the set of destination vertices $\{2, 5\}$ and builds filter matrix $p_f = \{(2, 2), (5, 5)\}$. Then this matrix is embedded in the algebraic expression of operation in the same way as in CondTraverse and we get new algebraic expression $p_f * AlgExp(p) = p_f * \mathcal{E}^b * Ref(S)$. After that for each reference in the algebraic expression we need to determinate the set of source vertices. This can be done during algebraic expression evaluation which we extended for this purpose.

Algorithm 8 Extension of multiplication evaluation

```

1: function EVALMUL( $e_l : AlgExp, e_r : AlgExp, context$ )
2:    $M_l = \text{EVAL}(e_l, context)$ 
3:   if  $r$  is  $Ref(ref)$  then
4:      $context[ref].src \leftarrow context[ref].src + \text{GETDST}(M_l)$ 
5:   ...            $\triangleright$  Remaining original part of the EvalMul

```

Specifically, we extended the multiplication operation as shown in the listing 8. At first the left operand e_l of multiplication is evaluated by **EVAL** function to matrix M_l in line 2. Then if the right operand of the multiplication is a reference, we need to populate source matrix of corresponding named path pattern. In this case matrix M_l specifies some set of destination vertices $\{j \mid M_l[i, j] = 1\}$ from which the path should continue. So we add this set to source matrix of named path pattern. For example, lets consider evaluation of $p_f * AlgExp(p) = p_f * \mathcal{E}^b * Ref(S)$.

First, $p_f * \mathcal{E}^b$ is evaluated into matrix $M_l = \{(2, 3), (2, 6)\}$. It corresponds to edges starting from vertex 2 and labeled by b . Then destination vertices $\{3, 6\}$ of M_l are extracted and added to source matrix of named path pattern S . So after this evaluation the path pattern context becomes the following:

$$\begin{aligned}
\{S \rightarrow \{expr \rightarrow \mathcal{E}^c * Ref(S) * \mathcal{E}^d + \mathcal{E}^c * \mathcal{V}^y * \mathcal{E}^d, \\
m_{rel} \rightarrow \emptyset, \\
m_{src} \rightarrow \{(3, 3), (6, 6)\}\}
\end{aligned}$$

After that we have everything to run multiple-source CFPQ algorithm provided in listing 9 to resolve all operation dependencies. This algorithm is slightly different from *MultiSrcCFPQ* algorithm described in listing 2 and is a generalization of it. It receives the set of operation dependencies *deps* and path pattern context *context*. The algorithm's task is to populate relation and source matrices of all named path pattern from *deps*. To do this on each iteration for all pattern from *deps* this matrices are updated. Namely, first of all the algebraic expression is constructed from source matrix and algebraic expression of current pattern and then optimized in line 5. This is followed by substitution references in line 6, after which all references in the expression are replaced by relation matrices from *context*. At the end of iteration the resulting expression is evaluated and stored in relation matrix in line 7. These iterations continue as long as the context changes, i.e. at least one of the pattern matrices m_{rel} or m_{src} changes during iteration.

Algorithm 9 Multiple-source context-free path querying algorithm in terms of algebraic expressions

```

1: function MULTISRCCFPQALGEXP( $deps, context$ )
2:   while  $context$  is changing do
3:     for all  $p \in deps$  do
4:        $src \leftarrow context[p].m_{src}$ 
5:        $expr \leftarrow \text{OPTIMIZE}(src * context[p].expr)$ 
6:        $\text{FETCHREFERENCES}(expr, ctx)$ 
7:        $context[p].m_{rel} \leftarrow \text{EVAL}(expr)$ 

```

After running this algorithm on the dependency set of *CFPQTraverse* operation and path pattern context we receive relation matrices of all named path pattern, on which operation depends. For example, after running it on dependency set $\{S\}$, relation and source matrices of pattern S will be as follows:

$$\begin{aligned}
m_{rel} &= \{(3, 5), (3, 6), (4, 5), (4, 6), (5, 5), (5, 6)\} \\
m_{src} &= \{(3, 3), (4, 4), (5, 5)\}
\end{aligned}$$

After that all references in the algebraic expression $p_f * AlgExp(p)$ are replaced with the relation matrices and we get algebraic expression $p_f * \mathcal{E}^b * context[S].m_{rel}$. Then this expression is evaluated to matrix $\{(3, 5), (3, 6)\}$ that corresponds to paths from 3rd vertex that satisfy the constraints specified by pattern S . Finally as well as CondTraverse, CFPQTraverse extracts desired paths from this resulting matrix and passes them to parent operation.

Therefore if we put together the results of all operations of execution plan the query from listing 7 on graph D_1 return the set of vertices $\{(1, 5), (1, 6)\}$.

4.4 Evaluation

Small basic evaluation on real-world graph (geo?). In order to show, that performance is reasonable.

5 CONCLUSION

In this paper we propose a number of multiple-source modifications of Azimov's CFPQ algorithm. Evaluation of the proposed modifications on the real-world examples shows that !!!! Finally, we provide the full-stack support of CFPQ. For our solution we implement corresponding Cypher extension as a part of libcypher-parser, integrate the proposed algorithm into RedisGraph, and extend RedisGraph execution plan builder to support extended Cypher queries. We demonstrate, that our solution allows one evaluate not only context-free queries, but also regular one.

In the future, it is necessary to provide formal translation of Cypher to linear algebra, or find a maximal subset of Cypher which can be translated to linear algebra. There is a number of work on a subset of SPARQL to linear algebra translation, such as [5–7, 9]. But most of them practical-oriented and do not provide full theoretical basis to translate querying language to linear algebra. Other of them are discuss only partial cases and should be extended to cover real-world query languages. Deep investigation of this topic helps one to realize limits and restrictions of linear algebra utilization for graph databases. Moreover, it helps to improve existing solutions.

We show that evaluation of regular queries is possible in practice by using CFPQ algorithm, as far as regular queries is a partial case of the context-free one. But it seems, that the proposed solution is not optimal. For real-world solutions it is important to provide an optimal unified algorithm for both RPQ and CFPQ. One of possible way to solve this problem is to use tensor-based algorithm [12].

Another important task is to compare non-linear-algebra-based approaches to multiple-source CFPQ with the proposed solution. In [8] Jochem Kuijpers et al. show that all-pairs CFPQ algorithms implemented in Neo4j demonstrate unreasonable performance on real-world data. At the same time, Arseniy Terekhov et.al. shows that matrix-based all-pairs CFPQ algorithm implemented in appropriate linear algebra based graph database (RedisGraph) demonstrates good performance. But in the case of multiple-source scenario, when a number of start vertices is relatively small, non-linear-algebra-based solutions can be better, because such solutions naturally handle small required subgraph. Thus detailed investigation and comparison of other approaches to evaluate multiple-source CFPQ is required in the future.

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