



### Relational Interpreters for Search Problems

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## Recognition vs. Search

$$X$$
 — alphabet

$$L \subseteq X^*$$

if  $\omega \in L$ , denote the witness of this fact  $p_{\omega}$ 

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if  $\omega \in L$ , denote the witness of this fact  $p_{\omega}$ 

Recognition: 
$$V(\omega, p_{\omega}) = \begin{cases} 1, & \omega \in L \\ 0, & \omega \notin L \end{cases}$$

Search:  $S(\omega) = p_{\omega}$ 

## Propositional Formulas: Recognition

```
let rec eval st = function
  Conj (1, r) \rightarrow eval st 1 && eval st r
  Disj (1, r) \rightarrow \text{eval st } 1 \mid | \text{eval st } r
  Neg e \rightarrow not (eval st e)
  Var \quad x \quad \rightarrow \quad List.assoc \ x \ st
```

# Propositional Formulas: Recognition

```
let rec eval st = function
  Conj (1, r) \rightarrow eval st 1 && eval st r
  Disj (1, r) \rightarrow \text{eval st } 1 \mid | \text{eval st } r
  Neg e \rightarrow not (eval st e)
  Var \quad x \quad \rightarrow \ List.assoc \ x \ st
# eval [('x,true);('y,false)] (Conj (Var 'x) (Neg (Var 'y)));;
-: bool = true
```

## Propositional Formulas: Search

```
let rec solve st b = function
  Var n \rightarrow (match assoc_opt n st with)
                 None \rightarrow [extend st n b]
                 Some b' when b \Longrightarrow b' \rightarrow [st]
                 \rightarrow [])
  Conj (1, r) when b \rightarrow
    concat @@
    map (\lambda \text{ st } \rightarrow \text{ solve st b r}) 00
    solve st b l
  Conj (1, r) \rightarrow solve st b 1 @ solve st b r
  Neg e \rightarrow solve st (not b) e
 Disj (1, r) \rightarrow solve st b (Neg (Conj (Neg 1, Neg r)))
```

### Search is Hard<sup>1</sup>

Is it possible to generate a search procedure from a recognizer?

<sup>&</sup>lt;sup>1</sup>compared to recognition

### Relational Interpreter

$$V^R(\omega,p_\omega,q)$$
  $V^R(\omega,p_\omega,1), \quad ext{if} \ \omega\in L, p_\omega - ext{a} \ ext{witness}$   $V^R(\omega,p_\omega,0), \quad ext{otherwise}$ 

# Relational Interpretation for Recognition and Search

$$V^R(\omega, p_\omega, ?) \rightsquigarrow V(\omega, p_\omega)$$

$$V^R(\omega, ?, 1) \rightsquigarrow S(\omega)$$

Only one program to implement!

### Propositional Formulas: Relational Interpreter

```
let rec eval<sup>o</sup> st fm u = ocanren (
fresh x, y, z, v, w in
 fm = conj x y \& eval^o st x v \& eval^o st y w \& and^o v w u |
 fm = disj x y \& eval^o st x v \& eval^o st y w \& or^o v w u
 fm = neg x \& eval^o st x v \& not^o v u
 fm = var z \& assoc^o z st u
```

# Relational Programming is Hard<sup>2</sup>

```
let rec hanoi° a b c moves a' b' c' = ocanren (
moves = [] & a = a' & b = b' & c = c' |
fresh f, t, moves', pin_f, pin_t, pin_f_res, pin_t_res, a'', b'', c'' in
  moves == (f. t) :: moves' &
  (f = A & t = B & pin_f = a & pin_f_res = a'' & pin_t = b & pin_t_res = b'' & c'' = c
   f == A & t == C & pin_f == a & pin_f_res == a'' & pin_t == c & pin_t_res == c'' & b'' == b
   f = B \& t = A \& pin f = b \& pin f res = b'' \& pin t = a \& pin t res = a'' \& c'' = c
   f == B & t == C & pin_f == b & pin_f_res == b'' & pin_t == c & pin_t_res == c'' & a'' == a
   f == C & t == A & pin_f == c & pin_f_res == c'' & pin_t == a & pin_t_res == a'' & b'' == b
   f == C & t == B & pin_f == c & pin_f_res == c'' & pin_t == b & pin_t_res == b'' & a'' == a) &
   fresh top f. rest f in
    pin_f == top_f :: rest_f &
     (pin_t == [] |
      fresh top t. rest t in
        pin_t == top_t :: rest_t & lt o top_f top_t true
    pin f res == rest f &
    pin t res == top f :: pin t &
    hanoi<sup>o</sup> a'' b'' c'' moves' a' b' c'
```

<sup>&</sup>lt;sup>2</sup>compared to functional programming

# Relational Programming is Hard<sup>2</sup>

```
let rec hanoi° a b c moves a' b' c' = ocanren (
moves = [] & a = a' & b = b' & c = c' |
fresh f, t, moves', pin_f, pin_t, pin_f_res, pin_t_res, a'', b'', c'' in
  moves == (f. t) :: moves' &
  (f = A & t = B & pin_f = a & pin_f_res = a'' & pin_t = b & pin_t_res = b'' & c'' = c
   f == A & t == C & pin_f == a & pin_f_res == a'' & pin_t == c & pin_t_res == c'' & b'' == b
   f == B & t == A & pin_f == b & pin_f_res == b'' & pin_t == a & pin_t_res == a'' & c'' == c
   f == B & t == C & pin_f == b & pin_f_res == b'' & pin_t == c & pin_t_res == c'' & a'' == a
   f == C & t == A & pin_f == c & pin_f_res == c'' & pin_t == a & pin_t_res == a'' & b'' == b
   f == C & t == B & pin_f == c & pin_f_res == c'' & pin_t == b & pin_t_res == b'' & a'' == a) &
   fresh top f. rest f in
    pin_f == top_f :: rest_f &
     (pin_t == [] |
      fresh top t. rest t in
        pin_t == top_t :: rest_t & lt o top_f top_t true
    pin f res == rest f &
    pin_t_res == top_f :: pin_t &
    hanoi<sup>o</sup> a'' b'' c'' moves' a' b' c'
```

#### It took 3 people 6 hours to implement

<sup>&</sup>lt;sup>2</sup>compared to functional programming

## Ways to Create Relational Interpreters

- Manual implementation
- Interpretation of functional programs with a relational interpreter
- Relational conversion

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### Relational Interpretation of Functional Programs

- Implement good relational interpreter of a Turing-complete language
- Implement functional recognizer
- Run functional recognizer with a relational interpreter

### Interpretation Overhead

Running relational interpreter comes with a price Are there ways to get rid of it?

# Specialization

Interpreter:

eval prog input == output

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Consider that a part of the input is known: input == (static, dynamic)

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Consider that a part of the input is known: input == (static, dynamic)

### Specializer:

spec prog static  $\Rightarrow$  prog<sub>spec</sub> eval prog (static, dynamic) == eval  $prog_{spec}$  dynamic

### Jones-Optimality

- Specializers can fail to remove all interpretation overhead
- Jones-optimal specializer: the specialized interpreter is as efficient as the program it was specialized for
- There exists a Jones-optimal specializer for a logical language [Leuschel, 2004]
- Not for miniKanren
- Jones-optimality is hard to achieve

## Ways to Create Relational Interpreters

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- Interpretation of functional programs with a relational interpreter
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## Relational Conversion for Relational Interpreter

- Implement a functional recognizer (verifier):  $V(\omega, p_{\omega})$
- Transform it into a relation:  $V^R(\omega, p_\omega, q)$
- Specialize
  - Redundancy introduced with the relational conversion
  - Direction (q == 1)
  - Known data ( $\omega$ )
- The result is a search routine

# Relational Conversion (Unnesting) [Byrd 2009]

- Introduce a new variable for each subexpression
- For every n-ary function create an (n+1)-ary relation, where the last argument is unified with the result
- Transform if -expressions and pattern matchings into disjunctions with unifications for patterns
- Introduce into scope free variables (with fresh)
- Pop unifications to the top

Introduce a new variable for each subexpression

```
let rec append a b =
  match a with
  \mid x :: xs \rightarrow
    x :: append xs b
```

```
let rec append a b =
  match a with
  | x :: xs \rightarrow
    let q = append xs b in
    x :: q
```

Introduce a new argument for result

let rec append<sup>o</sup> a b  $c = \dots$ 

Transform if -expressions and pattern matchings into disjunctions with unifications for patterns

```
let rec append a b =
  match a with
   \mathtt{x} :: \mathtt{xs} 	o
    let q = append xs b in
    x :: q
```

```
let rec append<sup>o</sup> a b c =
 ocanren (
    (a = [] \& b = c) |
    ( a == x :: xs &
       appendo xs b q &
       c = x :: q)
```

Introduce free variables into scope (with fresh)

```
let rec append<sup>o</sup> a b c =
 ocanren (
    (a = [] \& b = c) |
    ( (a == x :: xs) &
       (append^o xs b q) &
       (c = x :: q)))
```

```
let rec append^{o} a b c =
 ocanren (
    (a = [] \& b = c) |
   (fresh x, xs, q in)
       a == x :: xs \&
       append^{o} xs b q &
       c = x :: q)
```

### Pop unifications to the top

```
let rec append<sup>o</sup> a b c =
 ocanren (
    (a = [] \& b = c) |
    (fresh x, xs, q in
       a == x :: xs &
       append^{o} xs b q &
       c = x :: q)
```

```
let rec append<sup>o</sup> a b c =
  ocanren (
    (a = [] \& b = c) |
    (fresh x, xs, q in
       a == x :: xs \&
       c = x :: q \&
       append^{o} xs b q))
```

### Forward Execution is Efficient. Backward Execution is not

Forward execution is efficient, since it mimics the execution of a function

Relational conversion for  $f_1 \times_1 \&\& f_2 \times_2$ :

```
\lambda res 
ightarrow ocanren (
  fresh p in
      f_1 x_1 p \&
      ( p == false & res == false |
        p = true \& f_2 x_2 res)
```

Computes  $f_2$   $x_2$  res only if  $f_1$   $x_1$  p fails

It is not the best strategy, if res is known

### Relational Conversion Aimed at Backward Execution

This coversion of  $f_1 \times_1 \&\& f_2 \times_2$  is better for the backward execution, but not for forward

```
\lambda res 
ightarrow ocanren (
  res = false \& f_1 x_1 false
  f_1 \times_1 true \& f_2 \times_2 res
```

There is no single strategy suitable for all cases

# There is no Single Good Strategy

Is there a way to automatically generate relations efficient in the specified directions?

### Specialization: Not Only for Direction

When solving a search problem, we know its search space

$$V^R(\omega,?,1) \leadsto S(\omega)$$

# Partial Deduction: Specialization for Logic Language

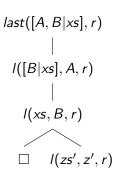
- Given:
  - Logic program
  - Goal
- Result: specialized program
- How:
  - Construct a partial SLD-tree
  - Generate a program from the tree
- Hopefully, all excessive computations are done statically and do not come to the specialized program

### Partial Deduction: Example

```
last([x|xs], r) \leftarrow l(xs, x, r).
1([], x, x).
l([z|zs], x, r) \leftarrow l(zs, z, r).
\leftarrow last([A,B|xs], r).
```

### Partial Deduction: Example

$$\begin{aligned} & \mathsf{last}([x|xs], \ r) \leftarrow \mathsf{l}(xs, \ x, \ r). \\ & \mathsf{l}([], \ x, \ x). \\ & \mathsf{l}([z|zs], \ x, \ r) \leftarrow \mathsf{l}(zs, \ z, \ r). \\ & \leftarrow \mathsf{last}([A,B|xs], \ r). \end{aligned}$$



## Partial Deduction: Example

$$last([x|xs], r) \leftarrow l(xs, x, r).$$

$$l([], x, x).$$

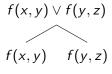
$$l([z|zs], x, r) \leftarrow l(zs, z, r).$$

$$l([x, B|xs], r).$$

$$l(xs, B, r)$$

last([A,B], B).  
last([A,B,z'|zs'], r) 
$$\leftarrow$$
 l(zs', z', r).  
l([], x, x).  
l([z|zs], x, r)  $\leftarrow$  l(zs, z, r).

# Partial Deduction: Conjunctions





# Partial Deduction: Conjunctions

$$f(x,y) \lor f(y,z)$$
 $f(x,y) \land f(y,z)$ 
 $f(x,y) \land f(y,z)$ 
 $f(x,y) \land f(y,z)$ 
 $f(x,y) \land f(y,z)$ 

## Conjunctive Partial Deduction

- Fully automatic program transformation
- For pure logic language
- Features:
  - Specialization
  - Deforestation
  - Tupling

### Deforestation

Deforestation — program transformation which eliminates intermediate data structures

```
let double_append° x y z xyz =
 ocanren (
    fresh t in
     append° x y t &
                                   let rec double_append° x y z xyz =
     appendo t z xyz )
                                     ocanren (
                                       x = [] & append^{\circ} y z xyz |
                                       (fresh h, t, t' in
let rec append x y xy =
                                          x == h :: t &
 ocanren (
   x = [] & xy = y |
                                          xyz = h :: t' &
                                          double_appendo t y z t')
    fresh h, t, ty in
     x == h :: t &
     xy == h :: t' &
     appendo t y t')
```

## Tupling

Tupling — program transformation which eliminates multiple traversals of the same data structure

```
let max_lengtho xs m l = ocanren (maxo xs m & lengtho xs l)
let rec length xs 1 = ocanren (
  xs = [] & 1 = 0 |
  (fresh h, t, m in
    xs = h :: t \& l = succ m \& length^o t m)
let \max^{\circ} xs m = \max_{1}^{\circ} xs 0 m
let rec \max_{1}^{o} xs n m = ocanren (
  xs = [] & m = n |
  (fresh h, t in
    xs == h :: t &
    ( le^{\circ} h n true & max_1^{\circ} t n m |
      gt° h n true & max<sub>1</sub>° t h m)))
```

## Tupling

Tupling — program transformation which eliminates multiple traversals of the same data structure

```
let max_length° xs m l = ocanren (max_length° xs m 0 1)
let rec max_length<sup>o</sup> xs m n l = ocanren (
  xs = [] \& m = n \& 1 = 0 |
  (fresh h, t, l<sub>1</sub> in
     xs == h :: t &
     1 = succ 1_1 \&
     ( le° h n & max_length<sub>1</sub>° t m n l |
       gt° h n & max_length1° t m h 1)))
```

## CPD: Intuition

- Local control: compute a partial SLD-tree per a relation of interest
  - Having a conjunction of atoms, which atom should be selected?
  - When to stop building a tree?
- Global control: determine which relations are of interest
  - Do not process the same conjunction twice
  - If a conjunction *embeds* something processed before, *generalize* it
  - How to define embedding?
  - How to generalize?

## CPD: Implementation

- Local control
  - Deterministic unfold (only one nondeterministic unfold per tree)
  - Selectable conjunct: leftmost call which does not have any predecessor embedded into it
  - Variant check
  - Stop when there are no selectable conjuncts
- Global control
  - Variant check
  - Generalization: split conjunction in maximally connected subconjunctions + most specific generalization
  - Homeomorphic embedding extended for conjunctions
- Residualization
  - A definition per a local tree
  - Redundant Argument Filtering

#### **Evaluation**

#### Compare

- Unnesting
- Unnesting strategy aimed at backward execution
- Unnesting + CPD
- Interpretation of functional verifier with relational interpreter

#### Tasks

- Path search
- Search for a unifier of two terms

### Path Search

*Directed graph* is a tuple (*N*, *E*, *start*, *end*), where:

- N set of nodes
- E set of edges
- Functions start, end :  $E \rightarrow N$  return a start (end) node of an edge

### Path Search

Directed graph is a tuple (N, E, start, end), where:

- N set of nodes
- E set of edges
- Functions start, end :  $E \to N$  return a start (end) node of an edge

Path is a sequence  $\langle n_0, e_0, n_1, e_1, \dots, n_k, e_k, n_{k+1} \rangle$ , such that

$$\forall i \in \{0 \dots k\} : n_i = start(e_i) \text{ and } n_{i+1} = end(e_i)$$

### Path Search

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$$\forall i \in \{0 \dots k\} : n_i = start(e_i) \text{ and } n_{i+1} = end(e_i)$$

Path search problem is to find the set of paths in a given graph

### Path Search: Relational Conversion

```
let rec is_path ns g =
 match ns with
```

## Path Search: Relational Conversion

```
let rec is_path ns g =
  match ns with
| x_1 :: x_2 :: xs \rightarrow elem(x_1, x_2) g \&\& is_path(x_2 :: xs) g
| [_]
                       \rightarrow true
let rec is_path ons g res = ocanren (
   fresh el in (ns = [el] \& res = true)
   (fresh x_1, x_2, x_3, res_elem, res_is_path in
     ns = x_1 :: (x_2 :: x_3) \&
     elem<sup>o</sup> (x<sub>1</sub>, x<sub>2</sub>) g res_elem &
     is_path<sup>o</sup> (x<sub>2</sub> :: xs) g res_is_path &
     ( res_elem == false & res == false |
       res_elem == true & res == res_is_path )))
This relation is inefficient for "is_path" q <graph> true"
```

## Path Search: Specialized Relation

```
let rec is_path ons g res = ocanren (
  fresh el in (ns == [el] & res == true) |
  (fresh x<sub>1</sub>, x<sub>2</sub>, xs, res_elem, res_is_path in
    res_elem == true &
    res_is_path == true &
    ns = x_1 :: (x_2 :: x_3) \&
    elem<sup>o</sup> (x<sub>1</sub>, x<sub>2</sub>) g res_elem &
    is_path<sup>o</sup> (x<sub>2</sub> :: xs) g res_is_path)))
```

Better performance for "is\_path" q <graph> true"

## Path Search: Specialized Relation

```
let rec is_patho ns g res = ocanren (
  fresh el in (ns == [el] & res == true) |
  (fresh x<sub>1</sub>, x<sub>2</sub>, xs, res_elem, res_is_path in
    res_elem == true &
    res_is_path == true &
    ns = x_1 :: (x_2 :: x_3) \&
    elem<sup>o</sup> (x<sub>1</sub>, x<sub>2</sub>) g res_elem &
    is_path<sup>o</sup> (x<sub>2</sub> :: xs) g res_is_path)))
```

Better performance for "is\_path" q <graph> true"

This can be achieved automatically with CPD

## Evaluation: Path Search

Path length	5	7	9	11	13	15
Only conversion	0.01	1.39	82.13	>300	_	_
Backward oriented conversion	0.01	0.37	2.68	2.91	4.88	10.63
Conversion and CPD	0.01	0.06	0.34	2.66	3.65	6.22
Scheme interpreter	0.80	8.22	88.14	191.44	>300	_

Table: Searching for paths in the graph (seconds)

#### Term:

- Variable (*X*, *Y*,...)
- Some constructor applied to terms (nil, cons(H, T), ...)

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Substitution can be applied to a term by simultaneously substituting variables for their images

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Unifier is a substitution  $\sigma$  which equalizes terms:  $t\sigma = s\sigma$ 

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- Variable (*X*, *Y*,...)
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Substitution can be applied to a term by simultaneously substituting variables for their images

Unifier is a substitution  $\sigma$  which equalizes terms:  $t\sigma = s\sigma$ 

Problem: given two terms with free variables, find their unifier

## Unification: Functional Verifier

```
let rec check_uni subst t1 t2 =
 match t1, t2 with
    Constr (n1, a1), Constr (n2, a2) \rightarrow
      eq_nat n1 n2 && forall2 subst a1 a2
    Var_v , Constr(n, a) \rightarrow
    begin match get_term v subst with
      None \rightarrow false
      Some t \rightarrow check uni subst t t2
    end
    Constr (n, a) , Var_ v
    begin match get_term v subst with
      None \rightarrow false
      Some t \rightarrow check uni subst t1 t
    end
    Var_ v1 , Var_ v2
    match get_term v1 subst with
      Some t1' \rightarrow check_uni subst t1' t2
                → match get_term v2 subst with
                   \mid Some \rightarrow false
                    None \rightarrow eq_nat v1 v2
```

### Unification: Relational Conversion

Does not fit the slide.

### **Evaluation:** Unification

Terms	f(X, a) f(a, X)	f(a % b % nil, c % d % nil, L) f(X % XS, YS, X % ZS)	$\begin{array}{c c} f(X, X, g(Z, t)) \\ \hline f(g(p, L), Y, Y) \end{array}$
Only conversion	0.01	>300	>300
Backward oriented conversion	0.01	0.11	2.26
Conversion and CPD	0.01	0.07	0.90
Scheme interpreter	0.04	5.15	>300

Table: Searching for a unifier of two terms (seconds)

## Conclusion & Future Work

Functional recognizer + unnesting + specialization = search

#### Future work

- Generate functional program from relational to reduce interpretation overhead
- Some other specialization technique, less ad-hoc than CPD