Graph Parsing by Matrix Multiplication

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ABSTRACT

Graph data model is widely used in many areas, for example, bioinformatics, graph databases, RDF. One of the most common graph queries are navigational queries. Result of query evaluation are implicit relations between nodes of the graph, i.e. paths in the graph. Natural way to specify these relations is by specifying paths using formal grammars over edge labels. Answer to the context-free path queries in this approach is usually a set of triples (A, m, n) such that there is a path from node m to node n whose labeling is derived from non-terminal A of the given context-free grammar. This type of queries is evaluated using relational query semantics. There is a number of algorithms for query evaluation which use such semantics but they have computational problems with big data. One of the most common technique for efficient big data processing is GPGPU, but these algorithms do not allow to use this technique effectively. In this paper we propose graph parsing algorithm for query evaluation which use relational query semantics and context-free grammars, and is based on matrix operations which allows to speed up computations by means of GPGPU.

1. INTRODUCTION

Graph data model is widely used in many areas, for example, bioinformatics [2], graph databases [9], RDF [16]. In these areas, it is often required to process large graphs. Most common among graph queries are navigational queries. Result of query evaluation is implicit relations between nodes of the graph, i.e. paths in the graph. Natural way to specify these relations is by specifying paths using formal grammars (regular expressions, context-free grammars) over edge labels. Context-free grammars are actively used in graphs queries because of the limited expressive power of regular expressions.

Result of context-free path query evaluation is usually a set of triples (A, m, n) such that there is a path from node m to node n whose labeling is derived from non-terminal A of the given context-free grammar. This type of queries is evaluated using the *relational query semantics* [6]. There is a number of algorithms for query evaluation using this semantics [5, 6, 16].

Existing algorithms for query evaluation using this semantics have computational problems with big data. One of the most common technique for efficient big data processing is *GPGPU* (General-Purpose computing on Graphics Processing Units), but these algorithms do not allow to use this technique effectively. The algorithms for context-free recognizing had a similar problem until Valiant [13] proposed a parsing algorithm that computes a recognition table by computing a matrix transitive closure. Thus, the active use of matrix operations (such as matrix multiplication) in the process of computing a transitive closure makes it possible to effectively apply GPGPU computing techniques [3].

Therefore the question is whether it is possible to create an algorithm for query evaluation using the relational query semantics which allows to speed up computations with GPGPU by using the matrix operations.

The main contribution of this paper can be summarized as follows:

- We show how the query evaluation using the relational query semantics and context-free grammars can be reduced to the calculation of the matrix transitive closure.
- We provide formal proof of correctness of the proposed reduction.
- We introduce an algorithm for query evaluation which use relational query semantics and context-free grammars, and is based on matrix operations which allows to speed up computations by means of GPGPU.

2. PRELIMINARIES

In this section, we introduce the basic notions used throughout the paper.

Let Σ be a finite set of edge labels. Define an *edge-labeled directed graph* as a tuple $D = (V, E)$ with V is a set of nodes and $E \subseteq V \times \Sigma \times V$ is a directed edge-relation. For a path π in graph D we denote $l(\pi)$ — the unique word obtained by concatenating the labels of the edges along the path π. Also, we write $n\pi m$ to indicate that a path π starts at node $n \in V$ and ends at node $m \in V$.

According to Hellings [6], we deviate from the usual definition of a context-free grammar in *Chomsky Normal Form* [4] by not including a special start non-terminal, which will be specified in the queries to the graph. Since every context-free grammar can be transformed into an equivalent one in Chomsky Normal Form and checking that an empty string is in the language is trivial, then it is sufficient to only consider grammars of the following type. A *context-free grammar* is 3-tuple $G = (N, \Sigma, P)$ where N is a finite set of non-terminals, Σ is a finite set of terminals, and P is a finite set of productions of the following forms:

- $A \to BC$, for $A, B, C \in N$,
- $A \to x$, for $A \in N$ and $x \in \Sigma$.

Note that we omit rules of the form $A \to \varepsilon$, where ε denotes an empty string. This does not limit the applicability of further algorithms because checking that an empty string belongs to the context-free language in Chomsky normal form is trivial.

We use the conventional notation $A \xrightarrow{*} w$ to denote that the string $w \in \Sigma^*$ can be derived from a non-terminal A by some sequence of applying the production rules from P. The *language* of a grammar $G = (N, \Sigma, P)$ with respect to a start non-terminal $S \in N$ is defined by $L(G_S) = \{w \in \Sigma^* \mid S \xrightarrow{*} w\}$.

For a given graph $D = (V, E)$ and a context-free grammar $G = (N, \Sigma, P)$, we define *context-free relations* $R_A \subseteq V \times V$, for every $A \in N$, such that $R_A = \{(n, m) \mid \exists n\pi m \ (l(\pi) \in L(G_A))\}$.

We define a binary operation on arbitrary subsets N_1, N_2 of N with respect to a context-free grammar $G = (N, \Sigma, P)$ as $N_1 \cdot N_2 = \{A \mid \exists B \in N_1, \exists C \in N_2$ such that $(A \to BC) \in P\}$.

Using this binary operation as a multiplication on arbitrary subsets of N and union of sets as an addition, we can define *matrix multiplication*, $a \cdot b = c$, where a and b are matrices of suitable size that have subsets of N as elements, as $c_{i,k} = \bigcup_{j=1}^{n} a_{i,j} \cdot b_{j,k}$.

We define the *transitive closure* of a square matrix a as $a^+ = a^{(1)} \cup a^{(2)} \cup \cdots$ where $a^{(i)} = a^{(i-1)} \cup (a^{(i-1)} \cdot a^{(i-1)})$, $i \geq 2$ and $a^{(1)} = a$.

3. RELATED WORKS

Our work is inspired by Valiant [13], who proposed an algorithm for general context-free recognition in less than cubic time. This algorithm computes the same parsing table as the Cocke-Kasami-Younger algorithm [8, 15] but does this by offloading the most intensive computations into calls to a Boolean matrix multiplication procedure. This approach not only provides an asymptotically more efficient algorithm but it also allows to effectively apply GPGPU computing techniques. Valiant used the following definition of a transitive closure.

Definition 1. *The transitive closure of a square matrix a is a matrix $a^+ = a^{(1)} \cup a^{(2)} \cup \cdots$ where:*

- $a^{(i)} = \bigcup_{j=1}^{i-1} a^{(j)} \cdot a^{(i-j)}$, $i \geq 2$;
- $a^{(1)} = a$.

Valiant also showed that the matrix multiplication operation used in this approach is computationally no more difficult than Boolean matrix multiplication. Denote the number of elementary operations executed by the algorithm of multiplying $n \times n$ Boolean matrices as $BMM(n)$. Valiant showed that the matrix multiplication operation used in this approach is essentially the same as $|N|^2$ Boolean matrix multiplications, where $|N|$ is the number of non-terminals of the given context-free grammar in Chomsky normal form.

Hellings [6] presented an algorithm for query evaluation using the relational query semantics and context-free grammars. According to Hellings, for a given graph $D = (V, E)$ and a grammar $G = (N, \Sigma, P)$ the query evaluation using the relational query semantics reduces to a calculation of the relations R_A. Thus, in this paper, we focus on the calculation of these relations.

Yannakakis [14] analyzed the reducibility of various graph parsing problems to the calculation of transitive closure. He formulated a problem of generalization Valiant's technique to the query evaluation using the relational query semantics and context-free grammars. Also, he assumed that this technique can not be generalized for arbitrary graphs, though it does for acyclic graphs.

Thus, the possibility of reducing query evaluation using relational query semantics and context-free grammars to the calculation of transitive closure is an open problem. In this paper, we do not generalize Valiant's approach. We use a different definition of transitive closure. The possibility of using Valiant's transitive closure in graph parsing is an open problem.

4. GRAPH PARSING BY THE CALCULATION OF TRANSITIVE CLOSURE

In this section, we show how query evaluation using relational query semantics and context-free grammars can be reduced to the calculation of matrix transitive closure, prove the correctness of this reduction, introduce an algorithm for computing the transitive closure and provide a step-by-step illustration of this algorithm on a small example.

4.1 Reducing graph parsing to transitive closure

In this section, we show how the context-free relations R_A can be calculated by computing the transitive closure.

Let $G = (N, \Sigma, P)$ be a grammar and $D = (V, E)$ be a graph. We number the nodes of the graph D from 0 to $(|V|-1)$ and we associate the nodes with their numbers. We initialize $|V| \times |V|$ matrix b with $\emptyset$. Further, for every i and j we set $b_{i,j} = \{A_k \mid ((i, x, j) \in E) \wedge ((A_k \to x) \in P)\}$. Finally, we compute the transitive closure $b^+ = b^{(1)} \cup b^{(2)} \cup \cdots$ where $b^{(i)} = b^{(i-1)} \cup (b^{(i-1)} \cdot b^{(i-1)})$, $i \geq 2$ and $b^{(1)} = b$. For the transitive closure b^+, the following statements holds.

Lemma 1. *Let $D = (V, E)$ be a graph, let $G = (N, \Sigma, P)$ be a grammar. Then for any i, j and for any non-terminal $A \in N$, $A \in b^{(k)}_{i,j}$ iff $(i, j) \in R_A$ and $i\pi j$, such that there is a derivation tree according to the string $l(\pi)$ and a context-free grammar $G_A = (N, \Sigma, P, A)$ of height $h \leq k$.*

Proof. (Proof by Induction)

Basis: Show that the statement of the lemma holds for $k = 1$. For any i, j and for any non-terminal $A \in N$, $A \in b^{(1)}_{i,j}$ iff there is $i\pi j$ that consists of a unique edge e from node i to node j and $(A \to x) \in P$ where $x = l(\pi)$. Therefore $(i, j) \in R_A$ and there is a derivation tree, shown in Figure 1, according to the string x and a context-free grammar $G_A = (N, \Sigma, P, A)$ of height $h = 1$. Thus, it has been shown that the statement of the lemma holds for $k = 1$.

Inductive step: Assume that the statement of the lemma holds for any $k \leq (p-1)$ and show that it also holds for $k = p$ where $p \geq 2$. Since $b^{(p)} = b^{(p-1)} \cup (b^{(p-1)} \cdot b^{(p-1)})$ then for any i, j and for any non-terminal $A \in N$, $A \in b^{(p)}_{i,j}$ iff $A \in b^{(p-1)}_{i,j}$ or $A \in (b^{(p-1)} \cdot b^{(p-1)})_{i,j}$.

Let $A \in b^{(p-1)}_{i,j}$. By the inductive hypothesis, $A \in b^{(p-1)}_{i,j}$ iff $(i, j) \in R_A$ and there exists $i\pi j$, such that there is a derivation tree according to the string $l(\pi)$ and a context-free grammar $G_A = (N, \Sigma, P, A)$ of height $h \leq (p-1)$. Since the height h of this tree is also less than or equal to p, then the statement of the lemma holds for $k = p$.

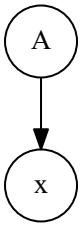

Figure 1: Derivation tree for string $x = l(\pi)$ of height $h = 1$.

Let $A \in (b^{(p-1)} \cdot b^{(p-1)})_{i,j}$. By the definition of the binary operation on arbitrary subsets, $A \in (b^{(p-1)} \cdot b^{(p-1)})_{i,j}$ iff there are r, $B \in b^{(p-1)}_{i,r}$ and $C \in b^{(p-1)}_{r,j}$, such that $(A \to BC) \in P$. Hence, by the inductive hypothesis, there are $i\pi_1 r$ and $r\pi_2 j$, such that $(i,r) \in R_B$ and $(r,j) \in R_C$, and there are derivation trees T_B and T_C according to the strings $w_1 = l(\pi_1)$, $w_2 = l(\pi_2)$ and the context-free grammars G_B, G_C of heights $h_1 \leq (p-1)$ and $h_2 \leq (p-1)$ respectively. Thus, the concatenation of paths π_1 and π_2 is $i\pi j$, where $(i,j) \in R_A$ and there is a derivation tree, shown in Figure 2, according to the string $w = l(\pi)$ and a context-free grammar G_A of height $h = 1 + max(h_1, h_2)$.

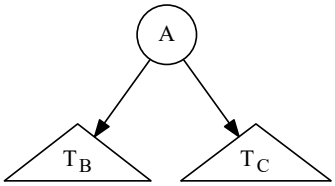

Figure 2: Derivation tree for string $w = l(\pi)$ of height $h = 1 + max(h_1, h_2)$, where T_B and T_C are derivation trees for strings w_1 and w_2 respectively.

Since the height $h = 1 + max(h_1, h_2) \leq p$, then the statement of the lemma holds for $k = p$ and this completes the proof of the lemma. □

THEOREM 1. *Let $D = (V, E)$ be a graph and let $G = (N, \Sigma, P)$ be a grammar. Then for any i, j and for any non-terminal $A \in N$, $A \in b^+_{i,j}$ iff $(i,j) \in R_A$.*

PROOF. Since the matrix $b^+ = b^{(1)} \cup b^{(2)} \cup \cdots$, then for any i, j and for any non-terminal $A \in N$, $A \in b^+_{i,j}$ iff there is $k \geq 1$, such that $A \in b^{(k)}_{i,j}$. By the lemma, $A \in b^{(k)}_{i,j}$ iff $(i,j) \in R_A$ and there is $i\pi j$, such that there is a derivation tree according to the string $l(\pi)$ and a context-free grammar $G_A = (N, \Sigma, P, A)$ of height $h \leq k$. This completes the proof of the theorem. □

We can, therefore, determine whether $(i,j) \in R_A$ by asking whether $A \in b^+_{i,j}$. Thus, we show how the context-free relations R_A can be calculated by computing the transitive closure b^+ of the matrix b.

4.2 The algorithm

In this section we introduce an algorithm for calculating the transitive closure b^+ which was discussed in Section 4.1.

The following algorithm takes on input a graph $D = (V, E)$ and a grammar $G = (N, \Sigma, P)$.

Algorithm 1 Context-free recognizer for graphs

```
1: function graphParse(D, G)
2:   n ← number of nodes in D
3:   E ← directed edge-relation from D
4:   P ← set of production rules in G
5:   T ← matrix n × n in which each element is ∅
6:   for all (i, x, j) ∈ E do                ▷ Matrix initialization
7:     T_{i,j} ← T_{i,j} ∪ {A | (A → x) ∈ P}
8:   while matrix T is changing do
9:     T ← T ∪ (T · T)                      ▷ Transitive closure calculation
10:  return T
```

Note that matrix initialization in lines **6-7** of the Algorithm 1 can handle arbitrary graph D. For example, if graph D contains multiple edges (i, x_1, j) and (i, x_2, j) then both the elements of set $\{A \mid (A \to x_1) \in P\}$ and the elements of set $\{A \mid (A \to x_2) \in P\}$ will be added to $T_{i,j}$.

We need to show that the Algorithm 1 terminates in a finite number of steps. Since each element of the matrix T contains no more than $|N|$ non-terminals, the total number of non-terminals in the matrix T does not exceed $|V|^2|N|$. Therefore, the following theorem holds.

THEOREM 2. *Let $D = (V, E)$ be a graph and let $G = (N, \Sigma, P)$ be a grammar. Algorithm 1 terminates in a finite number of steps.*

PROOF. It is sufficient to show, that the operation in line **9** of the Algorithm 1 changes the matrix T only finite number of times. Since this operation can only add non-terminals to some elements of the matrix T, but not remove them, it can change the matrix T no more than $|V|^2|N|$ times. □

According to Valiant, required matrix multiplication operation can be calculated in $O(|N|^2 BMM(|V|))$. Denote the number of elementary operations executed by matrix union operation of two $n \times n$ Boolean matrices as $BMU(n)$. Similarly, it can be shown that matrix union operation in line **9** of the Algorithm 1 can be calculated in $O(|N|^2 BMU(n))$. Since line **9** of the Algorithm 1 is executed no more than $|V|^2|N|$ times, then the following theorem holds.

THEOREM 3. *Let $D = (V, E)$ be a graph and let $G = (N, \Sigma, P)$ be a grammar. Algorithm 1 calculates the transitive closure b^+ in $O(|V|^2|N|^3(BMM(|V|) + BMU(|V|)))$.*

4.3 The example

In this section, we provide a step-by-step illustration of the proposed algorithm. For this, we consider the classical *same-generation query* [1].

The **example query** is based on the context-free grammar $G = (N, \Sigma, P)$ where:

- A set of non-terminals $N = \{S\}$.
- A set of terminals $\Sigma = \{subClassOf, subClassOf^{-1}, type, type^{-1}\}$.
- A set of production rules P is presented in Figure 3.

Since the proposed algorithm processes only grammars in Chomsky normal form, we first transform the grammar G into an equivalent grammar $G' = (N', \Sigma', P')$ in normal form, where:

$$
\begin{array}{ll}
0: & S \to subClassOf^{-1}\ S\ subClassOf \\
1: & S \to type^{-1}\ S\ type \\
2: & S \to subClassOf^{-1}\ subClassOf \\
3: & S \to type^{-1}\ type
\end{array}
$$

Figure 3: Production rules for the example query grammar.

- A set of non-terminals $N' = \{S, S_1, S_2, S_3, S_4, S_5, S_6\}$.
- A set of terminals $\Sigma' = \{subClassOf, subClassOf^{-1}, type, type^{-1}\}$.
- A set of production rules P' is presented in Figure 4.

$$
\begin{array}{ll}
0: & S \to S_1\ S_5 \\
1: & S \to S_3\ S_6 \\
2: & S \to S_1\ S_2 \\
3: & S \to S_3\ S_4 \\
4: & S_5 \to S\ S_2 \\
5: & S_6 \to S\ S_4 \\
6: & S_1 \to subClassOf^{-1} \\
7: & S_2 \to subClassOf \\
8: & S_3 \to type^{-1} \\
9: & S_4 \to type
\end{array}
$$

Figure 4: Production rules for the example query grammar in normal form.

We run the query on a graph presented in Figure 5.

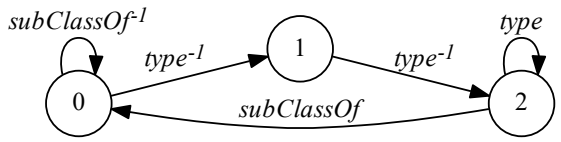

Figure 5: Input graph for the example query.

We provide a step-by-step illustration of the work with the given graph D and grammar G' of the Algorithm 1. After matrix initialization in lines **6-7** of the Algorithm 1 we have a matrix T_0 presented in Figure 6.

We denote T_i as a matrix T after i-th loop iteration in lines **8-9** of the Algorithm 1. The calculation of the matrix T_1 is shown in Figure 7.

When the algorithm at some iteration finds new paths in the graph D, then it adds corresponding nonterminals to the matrix T. For example, after the first loop iteration, non-terminal S is added to the matrix T. This non-terminal is added to the element with a row index $i = 1$ and a column index $j = 2$. This means that there is $i\pi j$ (a path π from node 1 to node 2), such that $S \xrightarrow{*} l(\pi)$. For example, such a path consists of two edges with labels $type^{-1}$ and $type$, and thus $S \xrightarrow{*} type^{-1}\ type$.

The calculation of transitive closure is completed after a loop iteration k such that $T_{k-1} = T_k$. For the example query, $k = 6$, since $T_6 = T_5$. The remaining iterations of computing the transitive closure are presented in Figure 8.

$$
T_0 = \begin{pmatrix} \{S_1\} & \{S_3\} & \emptyset \\ \emptyset & \emptyset & \{S_3\} \\ \{S_2\} & \emptyset & \{S_4\} \end{pmatrix}
$$

Figure 6: Initial matrix for the example query.

$$
T_0 \cdot T_0 = \begin{pmatrix} \emptyset & \emptyset & \emptyset \\ \emptyset & \emptyset & \{S\} \\ \emptyset & \emptyset & \emptyset \end{pmatrix}
$$

$$
T_1 = T_0 \cup (T_0 \cdot T_0) = \begin{pmatrix} \{S_1\} & \{S_3\} & \emptyset \\ \emptyset & \emptyset & \{S_3, S\} \\ \{S_2\} & \emptyset & \{S_4\} \end{pmatrix}
$$

Figure 7: The first iteration of computing the transitive closure for the example query.

Thus, the result of the Algorithm 1 for the example query is the matrix $T_5 = T_6$. Now, after constructing the transitive closure, we can construct context-free relations R_A. These relations for each non-terminal of the grammar G' are presented in Figure 9.

By the resulting context-free relation R_S, we can conclude that there are paths in graph D only from node 0 to node 0, from node 0 to node 2 or from node 1 to node 2, corresponding to the context-free grammar G_S. This conclusion is based on the fact that a grammar G'_S is equivalent to the grammar G_S and $L(G_S) = L(G'_S)$.

5. EVALUATION

To show practical applicability of the proposed algorithm, we implement this algorithm using different optimizations and apply these implementations to the navigation query problem for a dataset taken from a paper [16]. We also compare performance of our implementations with existing analogues from papers [5, 16]. This analogues use more complex algorithms, while our algorithm uses only simple matrix operations.

Since our algorithm works on graphs, then each RDF file from dataset was converted to edge-labeled directed graph as follows. For each triple (o, p, s) from RDF file, we added edges (o, p, s) and (s, p^{-1}, o) to the graph. We also constructed synthetic graphs g_1, g_2 and g_3 by simple repeating the existing graphs.

All tests were run on a PC with the following characteristics:

- OS: Microsoft Windows 10 Pro
- System Type: x64-based PC
- CPU: Intel(R) Core(TM) i7-4790 CPU @ 3.60GHz, 3601 Mhz, 4 Core(s), 4 Logical Processor(s)
- RAM: 16 GB
- GPU: NVIDIA GeForce GTX 1070
  - CUDA Cores: 1920
  - Core clock: 1556 MHz

$$T_2 = \begin{pmatrix} \{S_1\} & \{S_3\} & \emptyset \\ \{S_5\} & \emptyset & \{S_3, S, S_6\} \\ \{S_2\} & \emptyset & \{S_4\} \end{pmatrix}$$

$$T_3 = \begin{pmatrix} \{S_1\} & \{S_3\} & \{S\} \\ \{S_5\} & \emptyset & \{S_3, S, S_6\} \\ \{S_2\} & \emptyset & \{S_4\} \end{pmatrix}$$

$$T_4 = \begin{pmatrix} \{S_1, S_5\} & \{S_3\} & \{S, S_6\} \\ \{S_5\} & \emptyset & \{S_3, S, S_6\} \\ \{S_2\} & \emptyset & \{S_4\} \end{pmatrix}$$

$$T_5 = \begin{pmatrix} \{S_1, S_5, S\} & \{S_3\} & \{S, S_6\} \\ \{S_5\} & \emptyset & \{S_3, S, S_6\} \\ \{S_2\} & \emptyset & \{S_4\} \end{pmatrix}$$

Figure 8: Remaining states of the matrix T.

$$\begin{aligned} R_S &= \{(0,0),(0,2),(1,2)\}, \\ R_{S_1} &= \{(0,0)\}, \\ R_{S_2} &= \{(2,0)\}, \\ R_{S_3} &= \{(0,1),(1,2)\}, \\ R_{S_4} &= \{(2,2)\}, \\ R_{S_5} &= \{(0,0),(1,0)\}, \\ R_{S_6} &= \{(0,2),(1,2)\}. \end{aligned}$$

Figure 9: Resulting context-free relations for the example query.

– Memory data rate: 8008 MHz
– Memory interface: 256-bit
– Memory bandwidth: 256.26 GB/s
– Dedicated video memory: 8192 MB GDDR5

We denote the implementation of the algorithm from a paper [5] as *GLL*. The algorithm presented in this paper is implemented in F# programming language [12] and is available on GitHub[1]. We denote our implementations of the proposed algorithm as follows:

- dGPU (dense GPU) — an implementation with using row-major order for general matrix representation and using GPU to calculate matrix operations. For calculations of the matrix operations on GPU, we use wrapper for CUBLAS library from managedCuda[2] library.
- sCPU (sparse CPU) — an implementation with using CSR format for sparse matrix representation and using CPU to calculate matrix operations. For sparse matrix representation in CSR format, we use Math.Net Numerics[3] package.
- sGPU (sparse GPU) — an implementation with using CSR format for sparse matrix representation and using GPU to calculate matrix operations. For calculations of the matrix operations on GPU, where matrices represented in CSR format, we use wrapper for CUSPARSE library from managedCuda library.

We evaluate two classical *same-generation query* [1] which, for example, is applicable in bioinformatics.

Query 1 is based on the grammar G^1_S for retrieving concepts on the same layer, where:

- A grammar $G^1 = (N^1, \Sigma^1, P^1)$.
- A set of non-terminals $N^1 = \{S\}$.
- A set of terminals $\Sigma^1 = \{subClassOf, subClassOf^{-1}, type, type^{-1}\}$.
- A set of production rules P^1 is presented in Figure 10.

$$\begin{aligned} 0: &\quad S \to subClassOf^{-1}\ S\ subClassOf \\ 1: &\quad S \to type^{-1}\ S\ type \\ 2: &\quad S \to subClassOf^{-1}\ subClassOf \\ 3: &\quad S \to type^{-1}\ type \end{aligned}$$

Figure 10: Production rules for the query 1 grammar.

A grammar G^1 is transformed into an equivalent grammar in normal form, which is necessary for our algorithm. This transformation is the same as in Section 4.3. Let R_S be context-free relation for a start non-terminal in the transformed grammar.

The result of query 1 evaluation is presented in Table 1, where #triples is a number of triples (o, p, s) in RDF file, and #results is a number of pairs (n, m) in the context-free relation R_S. We can determine whether $(i, j) \in R_S$ by asking whether $S \in b^+_{i,j}$, where b^+ is the transitive closure calculated by the proposed algorithm. Since a dense matrix representation significantly degrades performance with increasing of the graph size, then we omit *dGPU* performance on graphs g_1, g_2 and g_3. All implementations in Table 1 have the same #results and demonstrate up to 1000 times better performance as compared to the algorithm presented in [16] for Q_1. Our implementations demonstrate better performance than *GLL* with increasing of the graph size. We also can conclude that acceleration from the *GPU* increases with the size of the graph.

Query 2 is based on the grammar G^2_S for retrieving concepts on the adjacent layers, where:

- A grammar $G^2 = (N^2, \Sigma^2, P^2)$.
- A set of non-terminals $N^2 = \{S, B\}$.
- A set of terminals $\Sigma^2 = \{subClassOf, subClassOf^{-1}\}$.
- A set of production rules P^2 is presented in Figure 11.

A grammar G^2 is transformed into an equivalent grammar in normal form. Let R_S be context-free relation for a start non-terminal in the transformed grammar.

The result of the query 2 evaluation is presented in Table 2. Since a dense matrix representation significantly degrades performance with increasing of the graph size, then

[1]GitHub repository of YaccConstructor project: `https://github.com/YaccConstructor/YaccConstructor`.
[2]GitHub repository of managedCuda library: `https://kunzmi.github.io/managedCuda/`.
[3]Math.Net Numerics WebSite: `https://numerics.mathdotnet.com/`.

Table 1: Evaluation results for Query 1

Ontology	#triples	#results	GLL(ms)	dGPU(ms)	sCPU(ms)	sGPU(ms)
skos	252	810	10	37	14	64
generations	273	2164	19	43	18	100
travel	277	2499	24	46	20	113
univ-bench	293	2540	25	53	23	127
atom-primitive	425	15454	255	127	82	247
biomedical-measure-primitive	459	15156	261	179	96	215
foaf	631	4118	39	99	44	167
people-pets	640	9472	89	262	127	182
funding	1086	17634	212	928	414	351
wine	1839	66572	819	1342	758	621
pizza	1980	56195	697	719	369	573
g_1	8688	141072	1926	—	25777	3243
g_2	14712	532576	6246	—	53913	5501
g_3	15840	449560	7014	—	22001	5191

Table 2: Evaluation results for Query 2

Ontology	#triples	#results	GLL(ms)	dGPU(ms)	sCPU(ms)	sGPU(ms)
skos	252	1	1	15	0	15
generations	273	0	1	0	0	0
travel	277	63	1	17	15	31
univ-bench	293	81	11	31	15	46
atom-primitive	425	122	66	31	15	156
biomedical-measure-primitive	459	2871	45	176	74	171
foaf	631	10	2	31	15	15
people-pets	640	37	3	93	31	46
funding	1086	1158	23	764	312	125
wine	1839	133	8	421	276	178
pizza	1980	1262	29	593	357	218
g_1	8688	9264	167	—	40005	1040
g_2	14712	1064	46	—	20863	1493
g_3	15840	10096	393	—	30146	3091

$0: \quad S \to B\ subClassOf$
$1: \quad S \to subClassOf$
$2: \quad B \to subClassOf^{-1}\ B\ subClassOf$
$3: \quad B \to subClassOf^{-1}\ subClassOf$

Figure 11: Production rules for the query 2 grammar.

we omit *dGPU* performance on graphs g_1, g_2 and g_3. All implementations in Table 2 have the same #results. On this query *GLL* demonstrates better performance than our implementations but we also can conclude that acceleration from the *GPU* increases with the size of the graph.

As a result, we conclude that our algorithm can be applied to some real-world problems and it allows to speed up computations by means of GPGPU.

6. CONCLUSION AND FUTURE WORK

In this paper, we presented the algorithm for reducing graph query evaluation using relational query semantics to the calculation of matrix transitive closure. Also, we provide a formal proof of the correctness of the proposed reduction. In addition, we introduce an algorithm for computing this transitive closure, which allows to effectively apply GPGPU computing techniques. Finally, we show the practical applicability of the proposed algorithm by running different implementations of our algorithm on real-world data.

We identify a several open problems for further research. In this paper we have considered only one semantics of graph querying but there are other important semantics, such as *single-path* and *all-path* semantics [7], which require to present paths, not only check reachability. Graph parsing implemented with algorithm [5] can answer to queries in these semantics by parsing forest construction. It is possible to construct parsing forest for linear input parsing by matrix multiplication [11]. Whether it is possible to generalize this approach for graph input is an open question.

In our algorithm, we calculate the matrix transitive closure naively, but there are algorithms for transitive closure calculation, which are asymptotically more efficient. Therefore, the question is whether it is possible to apply these algorithms for matrix transitive closure calculation to the problem of graph parsing. One way to answer this question is to generalize the Valiant's technique to arbitrary graphs. Yannakakis [14] formulated this problem and assumed that Valiant's technique does not seem to generalize to arbitrary graphs.

Also, there are Boolean grammars [10], which have more expressive power than context-free grammars. Graph parsing with boolean grammars is undecidable problem [6] but

our algorithm can be trivially generalized to work on boolean grammars because parsing with boolean grammars can be expressed by matrix multiplication [11]. It is not clear, what will be a result of our algorithm applied to Boolean grammars. Our hypothesis is that it will produce the upper approximation of a solution.

Matrix multiplication in the main loop of the proposed algorithm may be performed on different GPGPU independently. It can help to utilize the power of multi-GPU systems and increase the performance of graph parsing.

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