

, SPPF should contains two trees. SPPF presented in figure 2 will be constructed.

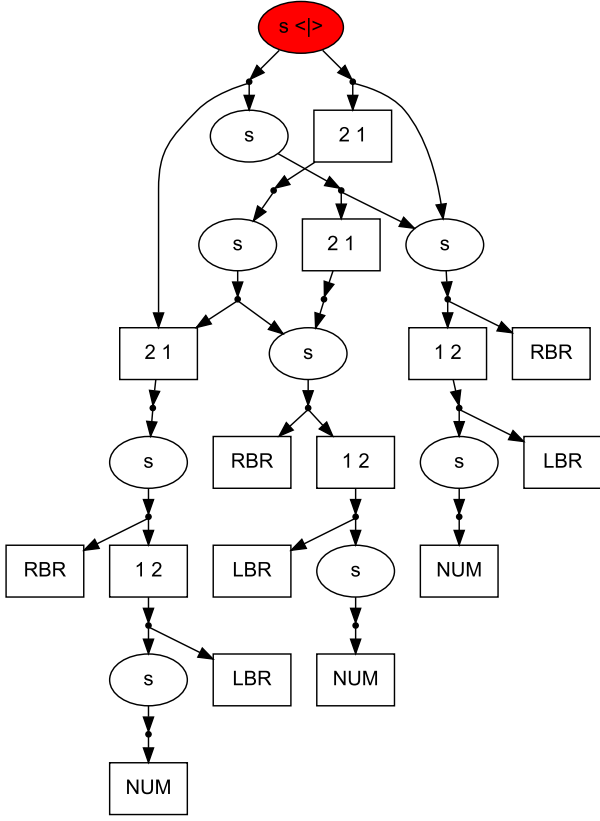


Figure 2: SPPF

Binarised SPPF is a graph where !!! and each node has one of four types and one node marked as 'root' — node for start nonterminal.

- terminal node
- nonterminal node
- intermediate node
-

Further we will remove redundant nodes from SPPF to simplify it and decrease size of structure.

GLL can use SPPF [13] for results representation achieve cubic space complexity with binarised version.

3. PRELIMINARIES

Let we introduce some definitions.

- Context-free grammar $G = (N, \Sigma, P, S)$ where N is a set of nonterminal symbols, Σ is a set of nonterminal symbols, $S \in N$ is a start nonterminal, and P is a productions set.
- Directed graph $M = (V, E, L)$ where V — vertices set, $L \subseteq \Sigma$ — edge labels set, $E \subseteq V \times L \times V$. We assume that there are no parallel edges with equal labels: for every $e_1 = (v_1, l_1, v_2) \in E, e_2 = (u_1, l_2, u_2) \in E$ if $v_1 = u_1$ and $v_2 = u_2$ then $l_1 \neq l_2$.

- Helper function for edge's tag calculation $tag : E \rightarrow L; tag(e = (v_1, l, v_2), e \in E) = l$.
- Concatenation operation $\oplus : L^+ \times L^+ \rightarrow L^+$.
- Path p in graph M .
 $p = (v_0, l_0, v_1), (v_1, l_1, v_2), \dots, (v_{n-1}, l_{n-1}, v_n) = e_0, e_1, \dots, e_{n-1}$ where $v_i \in V, e_i \in E, l_i \in L, |p| = n \geq 1$.
- Set of paths $P = \{p : p \text{ path in } M\}$
- Helper function for string produced by path calculation $\Omega : P \rightarrow L^+$.
 $\Omega(p = e_0, e_1, \dots, e_{n-1}, p \in P) = tag(e_0) \oplus \dots \oplus tag(e_{n-1})$.

As a result we can define that context-free language constrained path querying means that each path $p = e_0, \dots, e_{n-1}$ from result set satisfied with next constraint: $\Omega(p) \in L(G)$.

As a motivation of context-free constraints importance let we introduce the next example. Let we have graph $M = (\{0; 1; 2; 3\}, E, \{A; B\})$ presented in figure 3 where labels represent $parent(A)$ and $child(B)$ relations. Suppose for each $n \leq 1$ we want to find all n -th generation descendants with a common ancestor. In the other words, we want to find all paths p , such that $\Omega(p) \in \{AB; AAB; AAAB; \dots\}$ or $\Omega(p) = A^n B^n$ where $n \geq 1$. This constraint can not be specified with regular language as far as $L = \{A^n B^n; n \geq 1\}$ is not regular but context free. Required language can be specified by grammar G_1 presented in picture 4 where $N = \{s; middle\}$, $\Sigma = \{A; B\}$, and $S = s$.

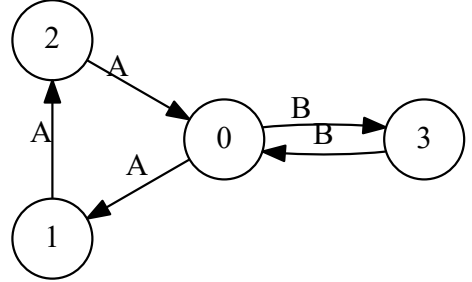


Figure 3: Input graph M

- 0: $s = L s R$
- 1: $s = middle$
- 2: $middle = L R$

Figure 4: Grammar G_1 for language $L = \{L^n R^n; n \geq 1\}$

4. GLL-BASED GRAPH PARSING

We propose a context-free language constrained path problem solution which allow to find all paths satisfied specified arbitrary context-free grammar and to construct implicit representation of result. Finite representation of result set with structure related to specified grammar may be

useful not only for results understanding and processing but also for query debugging especially for complex queries.

Our solution is based on generalized LL (GLL) [12, 1] parsing algorithm which allow to process ambiguous context-free grammars. Complexity is $O(n^3)$ in worst case and linear for unambiguous grammars, that better then complexity of CYK and Earley which used as base in other solutions (for example [5], [16]). This fact allow to demonstarte better performance on linear subgraphs and unambiguous grammars. Also it is not necessary to transform input grammar to CNF which required for CYK.

In order to use GLL for graph parsing we need only use graph verticea as position in input. As far as we work with context-free languages it is not important how this descriptor was created, and so descriptors management and other basic mechanisms of original algorithm can be reused “as is”. We can merge it if thea are equal.

We implement some optimizations: [1]

We also use binarised SPPF for result representation which allow to simplify query debugging and result exploration. In our case more then one root may be specified. For example, look at picture!!!! We

4.1 Complexity

Worst case: $O(|V|^3 * |E|)$ For unambiguous grammar: $O(|V| * |E|)$

Descriptor is a tryple (L, s, j) where $|L| = f(G)$ — some grammar-depended constant, $|j| = |V|$, and $|s| = |GSS.Nodes|$. GSS node N is a pair (lbl, j) where $|lbl| = f(G)$ and $|j| = |V|$. Thus we can create at most V^2 descriptors. For each descriptor we should examine all outgoing edges. Let $l = \max_{v \in V} (deg^+(v))$ where $deg^+(v)$ is outdegree of vertex v . Thus we need $O(|V|^2 * l)$ operation for outgoing edges processing. For all results of previous step we should find internal structures. It is possible in linear (w.r.t position count, $|V|$ in our case) time [7]. So, worst-case complexity of proposed algorithm is $O(V^3 * l)$. Averege-case complexity

should !!! $O(|V|^3 * \frac{\sum_{v \in V} deg^+(v)}{|V|})$. For unambiguous grammar complexity should be linear in terms of vertices count for the same reason as in classical GLL.

As discussed in [7] achiving of theoretical complexity required special datastructures which can be irrational for practice implementation and it is necessary to finde balance between performance, software complexity, and hardware resources. So in practice we can get slightly worse performance than theoretical estimation.

4.2 Example

In details, main function input is graph M , set of start vertices $V_s \subseteq V$, set of final vertices $V_f \subseteq V$, grammar G_1 . Output is Shared Packed Parse Forest (SPPF) [10] — finite data structure which contains all derivation trees for all paths in M , $\Omega(p) \in L(G_1)$ and allows to reconstruct any of paths implicitly. As far as we can specify sets of start and final vertices, our solution can find all paths in graph, all paths from specified vertex, all paths between specified vertices. Also SPPF represents a structure of paths in terms of derivation which allow to get more useful information about result.

Let we introduce the next example. Grammar G_1 is a query and we want to find all paths in graph M (presented in picture 3) matched this query. Result SPPF for this input

is presented in picture 5. Note that presented version does not contain obsolete nodes.

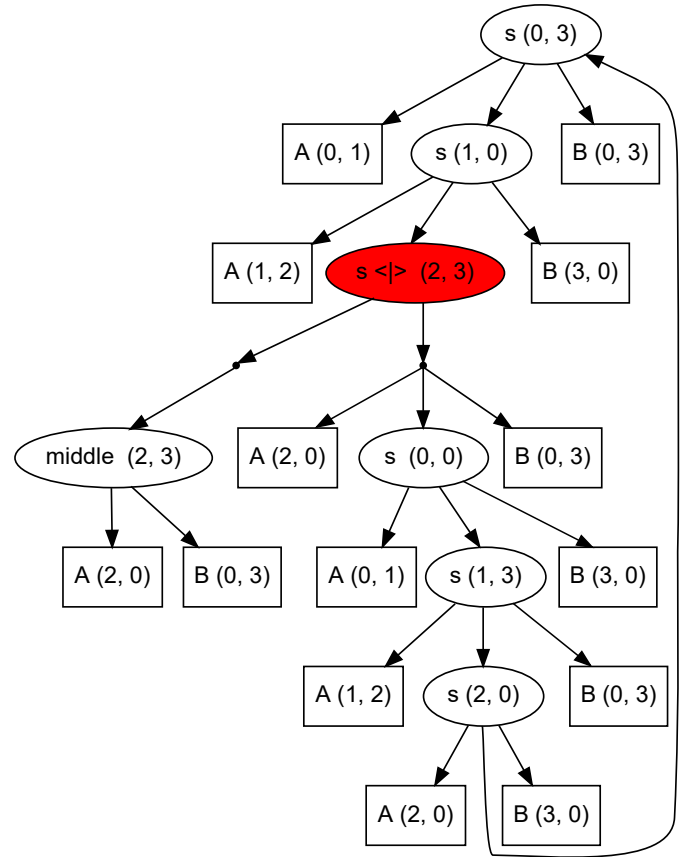


Figure 5: Result SPPF for input graph M (pic. 3) and query G_1 (pic. 4)

We use next markers for nodes.

- Node with rectangle shape labeled with (v_0, T, v_1) is terminal node. Each terminal node corresponds with edge in the input graph: for each node with label (v_0, T, v_1) there is $e \in E : e = (v_0, T, v_1)$. Duplication of terminal nodes is only for figure simplification.
- Node with oval shape labeled with (v_0, nt, v_1) is non-terminal node. This node denote that there is at least one path p from vertex v_0 to vertex v_1 in input graph M such that $nt \Rightarrow_G^* \Omega(p)$. All paths matched this condition can be extracted from SPPF by left-to-right top-down graph traversal started from respective node.
- Filled node with oval shape labeled with $(<|> (v_0, nt, v_1))$ is nonterminal node denote that there are more then one path from v_0 to v_1 such that $nt \Rightarrow_G^* \Omega(p)$.
- Node with dot shape is used for representation of derivation variants. Subgraph with root in one such node is one variant of derivation. Parent of such nodes is always node with label $(\diamond (v_0, nt, v_1))$.
- v_0 and v_1 are left and right extensions of node respectively.

As an example of derivation structure usage we can find 'middle' of any path in example above simply by finding corresponded nonterminal *middle* in SPPF. So we can found that there is only one common ancestor for all results and it is vertex with $id = 0$.

Extensions stored in nodes allow to check whether path from u to v exists and extract it. Path extraction is SPPF traversal. Let for example we want to find path satisfying specified constraints from vertex 0. To do this we should find vertices with label $(0, s, _)$ in SPPF. There are two vertices: $(0, s, 0)$ and $(0, s, 3)$. In our example there is cycle in SPPF so there are **at least** two different paths: $p_0 = \{(0, A, 1); (1, A, 2); (2, A, 0); (0, B, 3); (3, B, 0); (0, B, 3)\}$ and $p_1 = \{(0, A, 1); (1, A, 2); (2, A, 0); (0, A, 1); (1, A, 2); (2, A, 0); (0, B, 3); (3, B, 0); (0, B, 3); (3, B, 0); (0, B, 3); (3, B, 0)\}$.

5. EVALUATION

We perform some experiments on syntatic graphs. Full graphs and graphs with structure presented in figure !!! All paths from all vertices and all paths from one specified vertex. For full graph also all paths between two specified vertices.

We use two grammars for balanced brackets in order to investigate performance relations with grammar ambiguity: ambiguous grammar G_0 1 and unambiguous grammar G_2 6.

```
0: s = L s R s
1: s = eps
```

Figure 6: Unambiguous grammar G_2 for balanced brackets

All tests were performed on a PC with following characteristics:

- OS Name: Microsoft Windows 10 Pro
- System Type: x64-based PC
- CPU: Intel(R) Core(TM) i7-4790 CPU @ 3.60GHz, 3601 Mhz, 4 Core(s), 4 Logical Processor(s)
- RAM: 32 GB

Results presented in figure 7. From all and from one vertex is because descriptors reusing.

To summarise we can say that performance for unambiguous grammars is better then for ambiguous.

6. CONCLUSION AND FUTURE WORK

We propose GLL-based algorithm for context-free path querying which construct finite structural representation of all paths satisfying given constraint. Provided data structure can be useful for result investigation and processing, and query debugging. Presented algorithm implemented in F# and available on GitHub:<https://github.com/YaccConstructor/YaccConstructor>.

In order to estimate practical !!! we should perform evaluation on real dataset and real queries.

Also we are working on performance improvement by implementation of recently proposed modifications in original GLL algorithm [14]. One of direction of our research is generalization of grammar factorization proposed in [14] which may be useful for regular query processing.

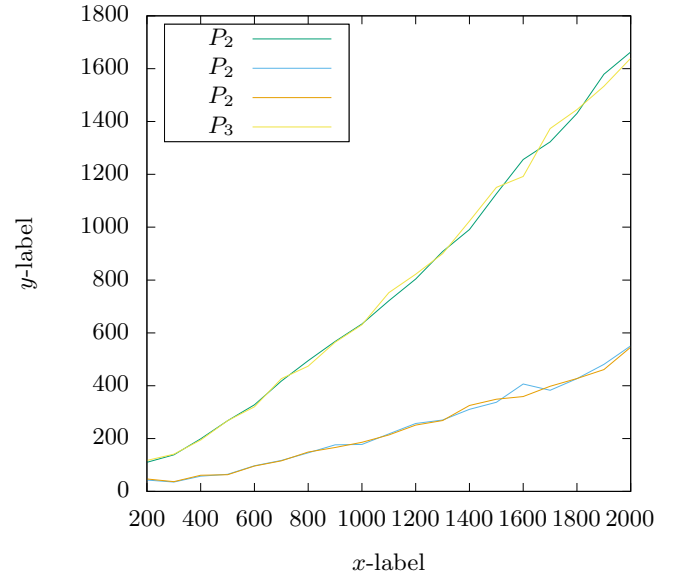


Figure 7: Performance on C graph for grammars G_0 and G_2

We are working on utilisation of GPGPU and multicore CPU power for graph parsing problem with Valiant [18] algorithm modification proposed by Alexander Okhotin [9]. One of possible benefit is ability to process more expressive queries because modification proposed by Alexander Okhotin extended to support boolean grammars.

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