

Rytter-style Algorithm for Context-Free Path Querying

Semyon Grigorev
Saint Petersburg State University
St. Petersburg, Russia
semen.grigorev@jetbrains.com

Ekaterina Shemetova
Saint Petersburg State University
St. Petersburg, Russia
katyacyfra@gmail.com

ACM Reference Format:

Semyon Grigorev and Ekaterina Shemetova. 2020. Rytter-style Algorithm for Context-Free Path Querying. In *Proceedings of ACM Conference (Conference'17)*. ACM, New York, NY, USA, 6 pages. <https://doi.org/10.1145/nnnnnnnn.nnnnnnnn>

1 THE REDUCTION

Suppose we have Φ — an instance of 3-SAT problem contains m clauses over k variables.

First of all, we should to construct a graph. To do it we follow the next steps.

- (1) Let $\gamma_i = \{v_1 \leftarrow b_1, v_2 \leftarrow b_2, \dots, v_k \leftarrow b_k\}$ where $b_k \in \{0, 1\}$. For each substitution γ_i a vertex V_{γ_i} should be created.
- (2) For each V_{γ_i} the following edges should be added: $\{(V_{\gamma_i}, [v_j \leftarrow b_l]^+, V_{\gamma_i}) \mid v_j \leftarrow b_l \in \gamma_i\}$.
- (3) For each clause $(l_1 \vee l_2 \vee l_3)$ the following subgraph should be created. First, two new vertices are added: c_1 and c_2 . After that, the following edges for each l_p and for each γ_i should be added

$$\{(c_1, [v_j \leftarrow b_l]^-, c_2) \mid b_l = \begin{cases} 1 & \text{if } l_p = v_j \\ 0 & \text{if } l_p = \neg v_j \end{cases}\}.$$

- (4) Subgraph for all clauses should be connected sequentially. Suppose we have sequence of subgraphs with vertices

$$\{(c_1^1, c_2^1), (c_1^2, c_2^2), \dots, (c_1^m, c_2^m)\}.$$

To connect them we should merge vertices c_2^i and c_1^{i+1} for all i except $i = m$. After that we fix c_1^1 as a start vertex of formula subgraph, and c_2^m as a final vertex of formula subgraph.

- (5) Finally, for all V_{γ_i} we should add the following edge

$$(V_{\gamma_i}, q, c_1^1)$$

The second part is a query. Suppose, we have p different substitutions. The grammar is following

$$\begin{aligned} S &\rightarrow q \\ S &\rightarrow [v_1 \leftarrow b_1]^+ S [v_1 \leftarrow b_1]^- \\ &\mid \dots \\ &\mid [v_k \leftarrow b_k]^+ S [v_k \leftarrow b_k]^- \end{aligned}$$

After that we should apply transformation which is described in the section 6. As a result we get h-Dyck reachability problem (yes, we can reduce it to 2-Dyck reachability).

Permission to make digital or hard copies of all or part of this work for personal or classroom use is granted without fee provided that copies are not made or distributed for profit or commercial advantage and that copies bear this notice and the full citation on the first page. Copyrights for components of this work owned by others than ACM must be honored. Abstracting with credit is permitted. To copy otherwise, or republish, to post on servers or to redistribute to lists, requires prior specific permission and/or a fee. Request permissions from permissions@acm.org.

Conference'17, July 2017, Washington, DC, USA

© 2020 Association for Computing Machinery.

ACM ISBN 978-x-xxxx-xxxx-x/YY/MM...\$15.00

<https://doi.org/10.1145/nnnnnnnn.nnnnnnnn>

1.1 An Example of Reduction

Suppose we have the following instance of 3-SAT problem.

$$\Phi = (\neg x_1 \vee x_2 \vee \neg x_3) \wedge (\neg x_2 \vee x_1 \vee x_3) \wedge (x_1 \vee \neg x_3 \vee x_2)$$

Substitutions:

$$\begin{aligned} \gamma_1 &= \{x_1 \leftarrow 0, x_2 \leftarrow 0, x_3 \leftarrow 0\} \\ \gamma_2 &= \{x_1 \leftarrow 1, x_2 \leftarrow 0, x_3 \leftarrow 0\} \\ \gamma_3 &= \{x_1 \leftarrow 0, x_2 \leftarrow 1, x_3 \leftarrow 0\} \\ \gamma_4 &= \{x_1 \leftarrow 0, x_2 \leftarrow 0, x_3 \leftarrow 1\} \\ \gamma_5 &= \{x_1 \leftarrow 1, x_2 \leftarrow 1, x_3 \leftarrow 0\} \\ \gamma_6 &= \{x_1 \leftarrow 1, x_2 \leftarrow 0, x_3 \leftarrow 1\} \\ \gamma_7 &= \{x_1 \leftarrow 0, x_2 \leftarrow 1, x_3 \leftarrow 1\} \\ \gamma_8 &= \{x_1 \leftarrow 1, x_2 \leftarrow 1, x_3 \leftarrow 1\} \end{aligned}$$

Graph for Φ is presented in figure 3.

The grammar:

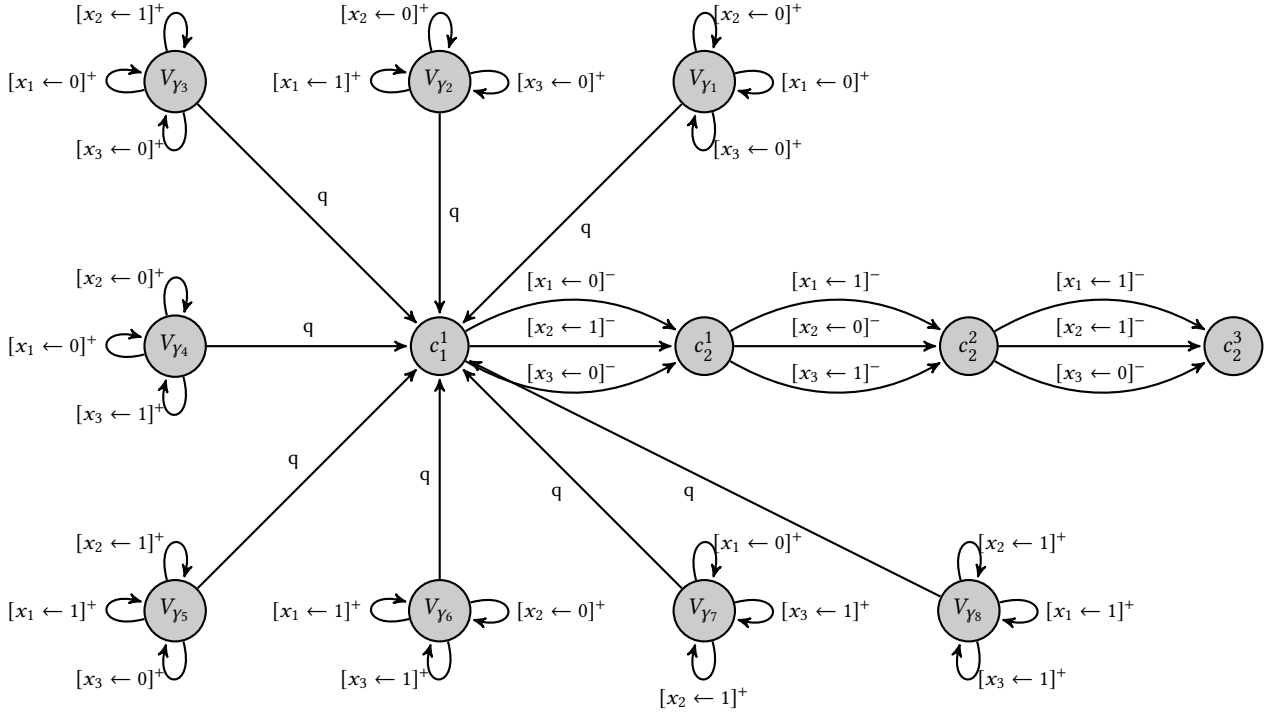
$$\begin{aligned} S &\rightarrow [x_1 \leftarrow 0]^+ S [x_1 \leftarrow 0]^- \\ &\mid [x_2 \leftarrow 0]^+ S [x_2 \leftarrow 0]^- \\ &\mid [x_3 \leftarrow 0]^+ S [x_3 \leftarrow 0]^- \\ &\mid [x_1 \leftarrow 1]^+ S [x_1 \leftarrow 1]^- \\ &\mid [x_2 \leftarrow 1]^+ S [x_2 \leftarrow 1]^- \\ &\mid [x_3 \leftarrow 1]^+ S [x_3 \leftarrow 1]^- \\ &\mid q \end{aligned}$$

The intuition of such path finding is that substitution vertex (V_{γ_i}) should provide appropriate values for respective variable in appropriate order to satisfy the given formula. It can be done by appropriate traversing of loops. After that, each edge from c_i^j to c_l^k “uses” provided values to satisfy respective closure, and it can be done if and only if the respective vertex provides value required. This fact is expressed by using balanced-bracket grammar. So, if there exists a path from V_{γ_i} to c_2^3 , such that the corresponded word is derivable from S , then V_{γ_i} satisfy the given formula.

2 REDUCTION TO $k/3$

First step is to split variables into three groups of the same size. Suppose this splitting preserves the order. So, we have a set of partial substitutions.

By the same way we create vertices for partial substitutions.

Figure 1: Example of graph for Φ

3 AN EXAMPLE OF REDUCTION $k/3$

For our example:

$$\begin{aligned} \gamma_1^1 &= \{x_1 \leftarrow 1\} \\ \gamma_1^2 &= \{x_1 \leftarrow 0\} \\ \gamma_2^1 &= \{x_2 \leftarrow 1\} \\ \gamma_2^2 &= \{x_2 \leftarrow 0\} \\ \gamma_3^1 &= \{x_3 \leftarrow 1\} \\ \gamma_3^2 &= \{x_3 \leftarrow 0\} \end{aligned}$$

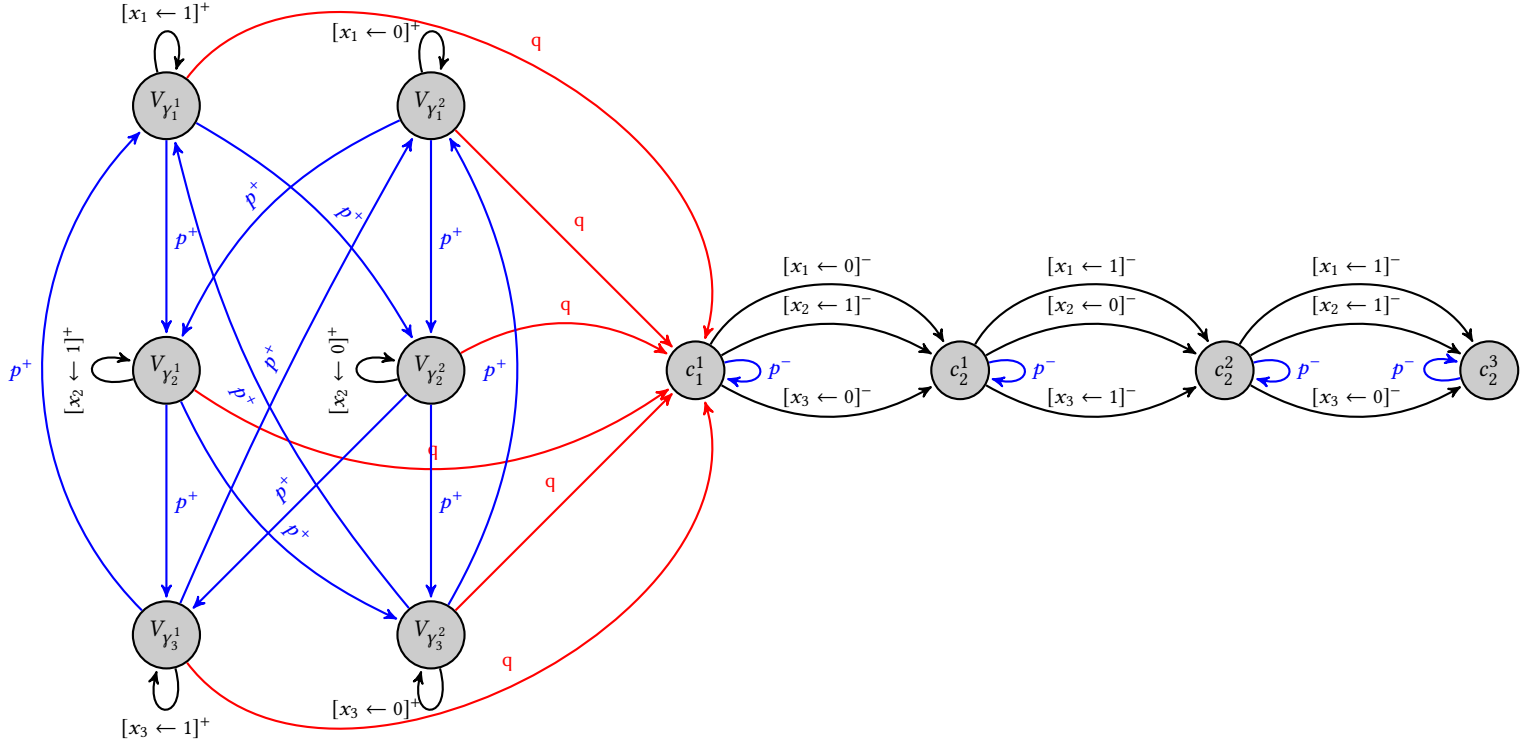
Grammar:

$$\begin{aligned} S &\rightarrow S_1 \mid S_2 \mid S_3 \mid S_4 \mid S_5 \mid S_6 \mid S_7 \mid S_8 \\ S_1 &\rightarrow q \mid p^+ S_1 p^- \mid [x_1 \leftarrow 0]^+ S_1 [x_1 \leftarrow 0]^- \\ &\quad \mid [x_2 \leftarrow 0]^+ S_1 [x_2 \leftarrow 0]^- \mid [x_3 \leftarrow 0]^+ S_1 [x_3 \leftarrow 0]^- \\ S_2 &\rightarrow q \\ &\quad \mid p^+ S_2 p^- \mid [x_1 \leftarrow 1]^+ S_2 [x_1 \leftarrow 1]^- \\ &\quad \mid [x_2 \leftarrow 0]^+ S_2 [x_2 \leftarrow 0]^- \mid [x_3 \leftarrow 0]^+ S_2 [x_3 \leftarrow 0]^- \\ S_3 &\rightarrow q \mid p^+ S_3 p^- \mid [x_1 \leftarrow 0]^+ S_3 [x_1 \leftarrow 0]^- \\ &\quad \mid [x_2 \leftarrow 1]^+ S_3 [x_2 \leftarrow 1]^- \mid [x_3 \leftarrow 0]^+ S_3 [x_3 \leftarrow 0]^- \\ S_4 &\rightarrow q \mid p^+ S_4 p^- \mid [x_1 \leftarrow 0]^+ S_4 [x_1 \leftarrow 0]^- \\ &\quad \mid [x_2 \leftarrow 0]^+ S_4 [x_2 \leftarrow 0]^- \mid [x_3 \leftarrow 1]^+ S_4 [x_3 \leftarrow 1]^- \\ S_5 &\rightarrow q \mid p^+ S_5 p^- \mid [x_1 \leftarrow 1]^+ S_5 [x_1 \leftarrow 1]^- \\ &\quad \mid [x_2 \leftarrow 1]^+ S_5 [x_2 \leftarrow 1]^- \mid [x_3 \leftarrow 0]^+ S_5 [x_3 \leftarrow 0]^- \\ S_6 &\rightarrow q \mid p^+ S_6 p^- \mid [x_1 \leftarrow 1]^+ S_6 [x_1 \leftarrow 1]^- \\ &\quad \mid [x_2 \leftarrow 0]^+ S_6 [x_2 \leftarrow 0]^- \mid [x_3 \leftarrow 1]^+ S_6 [x_3 \leftarrow 1]^- \\ S_7 &\rightarrow q \mid p^+ S_7 p^- \mid [x_1 \leftarrow 0]^+ S_7 [x_1 \leftarrow 0]^- \\ &\quad \mid [x_2 \leftarrow 1]^+ S_7 [x_2 \leftarrow 1]^- \mid [x_3 \leftarrow 1]^+ S_7 [x_3 \leftarrow 1]^- \\ S_8 &\rightarrow q \mid p^+ S_8 p^- \mid [x_1 \leftarrow 1]^+ S_8 [x_1 \leftarrow 1]^- \\ &\quad \mid [x_2 \leftarrow 1]^+ S_8 [x_2 \leftarrow 1]^- \mid [x_3 \leftarrow 1]^+ S_8 [x_3 \leftarrow 1]^- \end{aligned}$$

4 IMPROVED REDUCTION TO $k/3$

Firs step is to split variables into three group of the same size. Suppose this splitting preserves the order. So, we have a set of partial substitution.

By the same way we create vertices for partial substitutions.

Figure 2: Example of graph for Φ

5 AN EXAMPLE OF IMPROVED REDUCTION $k/3$

Grammar:

For our example:

$$\begin{aligned}
 \gamma_1^1 &= \{x_1 \leftarrow 1\} \\
 \gamma_1^2 &= \{x_1 \leftarrow 0\} \\
 \gamma_2^1 &= \{x_2 \leftarrow 1\} \\
 \gamma_2^2 &= \{x_2 \leftarrow 0\} \\
 \gamma_3^1 &= \{x_3 \leftarrow 1\} \\
 \gamma_3^2 &= \{x_3 \leftarrow 0\}
 \end{aligned}$$

$$\begin{aligned}
 S &\rightarrow S_{Y_1} \mid S_{Y_2} \mid S_{Y_3} \mid S_{Y_4} \mid S_{Y_5} \mid S_{Y_6} \mid S_{Y_7} \mid S_{Y_8} \\
 S_1 &\rightarrow q \mid [x_1 \leftarrow 1]^+ S_1 [x_1 \leftarrow 1]^- \\
 S_2 &\rightarrow q \mid [x_1 \leftarrow 0]^+ S_2 [x_1 \leftarrow 0]^- \\
 S_3 &\rightarrow q \mid [x_2 \leftarrow 1]^+ S_3 [x_2 \leftarrow 1]^- \\
 S_4 &\rightarrow q \mid [x_2 \leftarrow 0]^+ S_4 [x_2 \leftarrow 0]^- \\
 S_5 &\rightarrow q \mid [x_3 \leftarrow 1]^+ S_5 [x_3 \leftarrow 1]^- \\
 S_6 &\rightarrow q \mid [x_3 \leftarrow 0]^+ S_6 [x_3 \leftarrow 0]^- \\
 S_{Y_1} &\rightarrow S_2 \mid S_4 \mid S_6 \mid S_{Y_1} p S_2 \mid S_{Y_1} p S_4 \mid S_{Y_1} p S_6 \\
 S_{Y_2} &\rightarrow S_1 \mid S_4 \mid S_6 \mid S_{Y_2} p S_1 \mid S_{Y_2} p S_4 \mid S_{Y_2} p S_6 \\
 S_{Y_3} &\rightarrow S_2 \mid S_3 \mid S_6 \mid S_{Y_3} p S_2 \mid S_{Y_3} p S_3 \mid S_{Y_3} p S_6 \\
 S_{Y_4} &\rightarrow S_2 \mid S_4 \mid S_6 \mid S_{Y_4} p S_2 \mid S_{Y_4} p S_4 \mid S_{Y_4} p S_6 \\
 S_{Y_5} &\rightarrow S_1 \mid S_3 \mid S_6 \mid S_{Y_5} p S_1 \mid S_{Y_5} p S_3 \mid S_{Y_5} p S_6 \\
 S_{Y_6} &\rightarrow S_1 \mid S_4 \mid S_5 \mid S_{Y_6} p S_1 \mid S_{Y_6} p S_4 \mid S_{Y_6} p S_5 \\
 S_{Y_7} &\rightarrow S_2 \mid S_3 \mid S_5 \mid S_{Y_7} p S_2 \mid S_{Y_7} p S_3 \mid S_{Y_7} p S_5 \\
 S_{Y_8} &\rightarrow S_1 \mid S_3 \mid S_5 \mid S_{Y_8} p S_1 \mid S_{Y_8} p S_3 \mid S_{Y_8} p S_5
 \end{aligned}$$

Grammar in EBNF (better for tensor-based algorithm):

$$\begin{aligned}
S &\rightarrow S_{Y_1} \mid S_{Y_2} \mid S_{Y_3} \mid S_{Y_4} \mid S_{Y_5} \mid S_{Y_6} \mid S_{Y_7} \mid S_{Y_8} \\
S_1 &\rightarrow q \mid [x_1 \leftarrow 1]^+ S_1 [x_1 \leftarrow 1]^- \\
S_2 &\rightarrow q \mid [x_1 \leftarrow 0]^+ S_2 [x_1 \leftarrow 0]^- \\
S_3 &\rightarrow q \mid [x_2 \leftarrow 1]^+ S_3 [x_2 \leftarrow 1]^- \\
S_4 &\rightarrow q \mid [x_2 \leftarrow 0]^+ S_4 [x_2 \leftarrow 0]^- \\
S_5 &\rightarrow q \mid [x_3 \leftarrow 1]^+ S_5 [x_3 \leftarrow 1]^- \\
S_6 &\rightarrow q \mid [x_3 \leftarrow 0]^+ S_6 [x_3 \leftarrow 0]^- \\
S_{Y_1} &\rightarrow (S_2 \mid S_4 \mid S_6)(p(S_2 \mid S_4 \mid S_6))^* \\
S_{Y_2} &\rightarrow (S_1 \mid S_4 \mid S_6)(p(S_1 \mid S_4 \mid S_6))^* \\
S_{Y_3} &\rightarrow (S_2 \mid S_3 \mid S_6)(p(S_2 \mid S_3 \mid S_6))^* \\
S_{Y_4} &\rightarrow (S_2 \mid S_4 \mid S_6)(p(S_2 \mid S_4 \mid S_6))^* \\
S_{Y_5} &\rightarrow (S_1 \mid S_3 \mid S_6)(p(S_1 \mid S_3 \mid S_6))^* \\
S_{Y_6} &\rightarrow (S_1 \mid S_4 \mid S_5)(p(S_1 \mid S_4 \mid S_5))^* \\
S_{Y_7} &\rightarrow (S_2 \mid S_3 \mid S_5)(p(S_2 \mid S_3 \mid S_5))^* \\
S_{Y_8} &\rightarrow (S_1 \mid S_3 \mid S_5)(p(S_1 \mid S_3 \mid S_5))^*
\end{aligned}$$

6 FROM ARBITRARY CFPQ TO DYCK QUERY

This reduction is inspired by the construction described in [1].

Consider a context-free grammar $\mathcal{G} = (\Sigma, N, P, S)$ in BNF where Σ is a terminal alphabet, N is a nonterminal alphabet, P is a set of productions, $S \in N$ is a start nonterminal. Also we denote a directed labeled graph by $G = (V, E, L)$ where $E \subseteq V \times L \times V$ and $L \subseteq \Sigma$.

We should construct new input graph G' and new grammar \mathcal{G}' such that \mathcal{G}' specifies a Dyck language and there is a simple mapping from $\text{CFPQ}(\mathcal{G}', G')$ to $\text{CFPQ}(\mathcal{G}, G)$. Step-by-step example with description is provided below.

Let the input grammar is

$$\begin{aligned}
S &\rightarrow a S b \mid a C b \\
C &\rightarrow c \mid C c
\end{aligned}$$

The input graph is presented in fig. 4.

- (1) Let $\Sigma_0 = \{t_i \mid t_i \in \Sigma\}$.
- (2) Let $N_0 = \{N_i \mid N_i \in N\}$.
- (3) Let $M_{\mathcal{G}} = (V_{\mathcal{G}}, E_{\mathcal{G}}, L_{\mathcal{G}})$ is a directed labeled graph, where $L_{\mathcal{G}} \subseteq (\Sigma_0 \cup N_0)$. This graph is created the same manner as described in [1] but we do not require the grammar be in CNF. Let $x \in V_{\mathcal{G}}$ and $y \in V_{\mathcal{G}}$ is “start” and “final” vertices respectively. This graph may be treated as a finite automaton, so it can be minimized and we can compute an ε -closure if the input grammar contains ε productions. The graph $M_{\mathcal{G}}$ for our example is presented in fig. 5. The minimized graph is presented in fig. 6.
- (4) For each $v \in V$ create $M_{\mathcal{G}}^v$: unique instance of $M_{\mathcal{G}}$.
- (5) New graph G' is a graph G where each label t is replaced with t_i^i and some additional edges are created:
 - Add an edge (v', S_i, v) for each $v \in V$.
 - And the respective $M_{\mathcal{G}}^v$ for each $v \in V$:
 - reattach all edges outgoing from x^v (“start” vertex of $M_{\mathcal{G}}^v$) to v ;
 - reattach all edges incoming to y^v (“final” vertex of $M_{\mathcal{G}}^v$) to v .

New input graph is ready. It is presented in fig. 7.

- (6) New grammar $\mathcal{G}' = (\Sigma', N', P', S')$ where $\Sigma' = \Sigma_0 \cup N_0$, $N' = \{S'\}$, $P' = \{S' \rightarrow b_i S' b_i; S' \rightarrow b_i b_i \mid b_i, b_i \in \Sigma'\} \cup \{S' \rightarrow S' S'\}$ is a set of productions, $S' \in N'$ is a start nonterminal.

Now, if $\text{CFPQ}(\mathcal{G}', G')$ contains a pair (u'_0, v') such that $e = (u'_0, S_i, u'_1) \in E'$ is an extension edge (step 5, first subitem), then $(u'_1, v') \in \text{CFPQ}(\mathcal{G}, G)$.

In our example, we can find the following path: $7 \xrightarrow{S_i} 1 \xrightarrow{S_i} 22 \xrightarrow{b_i} 25 \xrightarrow{C_i} 26 \xrightarrow{a_i} 1 \xrightarrow{a_i} 2 \xrightarrow{C_i} 33 \xrightarrow{C_i} 34 \xrightarrow{c_i} 2 \xrightarrow{c_i} 3 \xrightarrow{C_i} 43 \xrightarrow{c_i} 3 \xrightarrow{c_i} 4 \xrightarrow{b_i} 5$. Edge $7 \xrightarrow{S_i} 1$ is the extension, so $(1, 5)$ should be in $\text{CFPQ}(\mathcal{G}, G)$ and it is true.

REFERENCES

- [1] Krishnendu Chatterjee, Bhavya Choudhary, and Andreas Pavlogiannis. 2017. Optimal Dyck Reachability for Data-dependence and Alias Analysis. *Proc. ACM Program. Lang.* 2, POPL, Article 30 (Dec. 2017), 30 pages. <https://doi.org/10.1145/3158118>

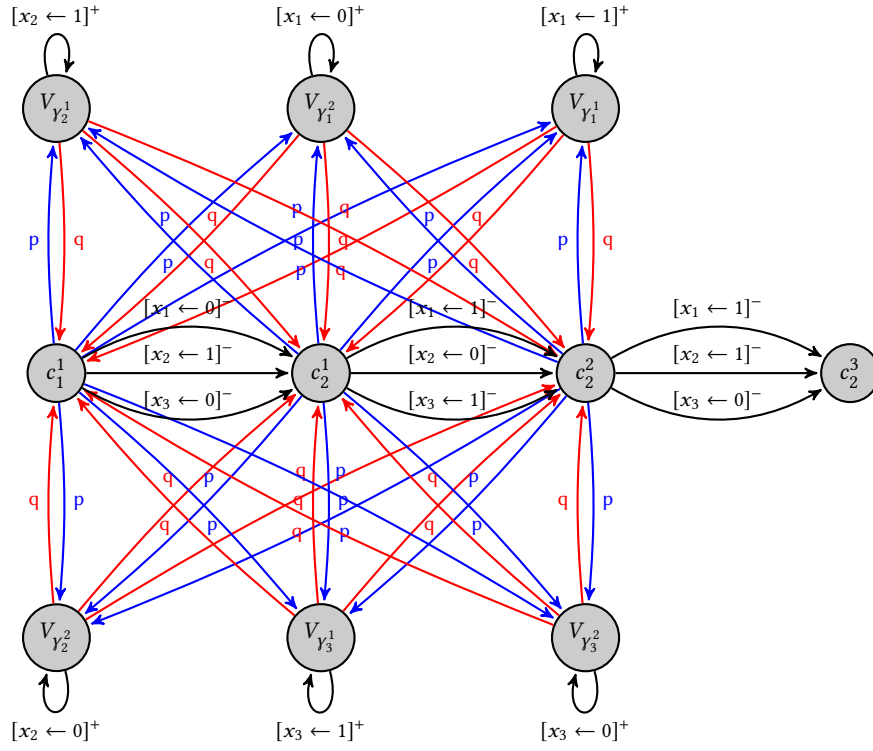
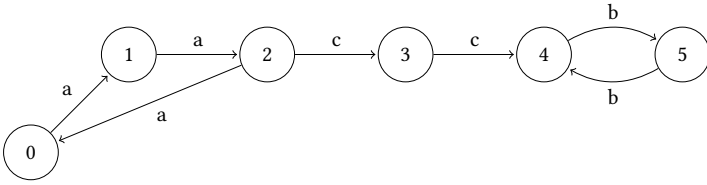
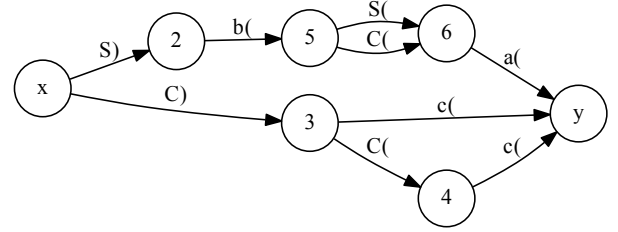
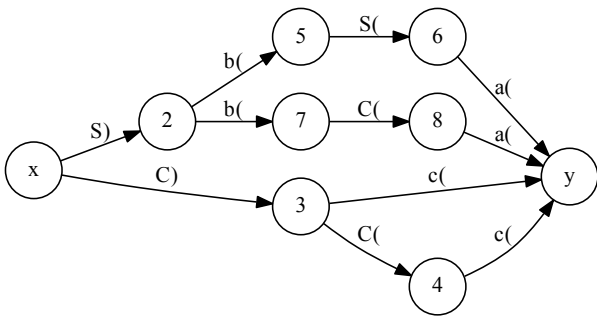
Figure 3: Example of graph for Φ 

Figure 4: The input graph

Figure 6: The minimized M_G Figure 5: The M_G graph

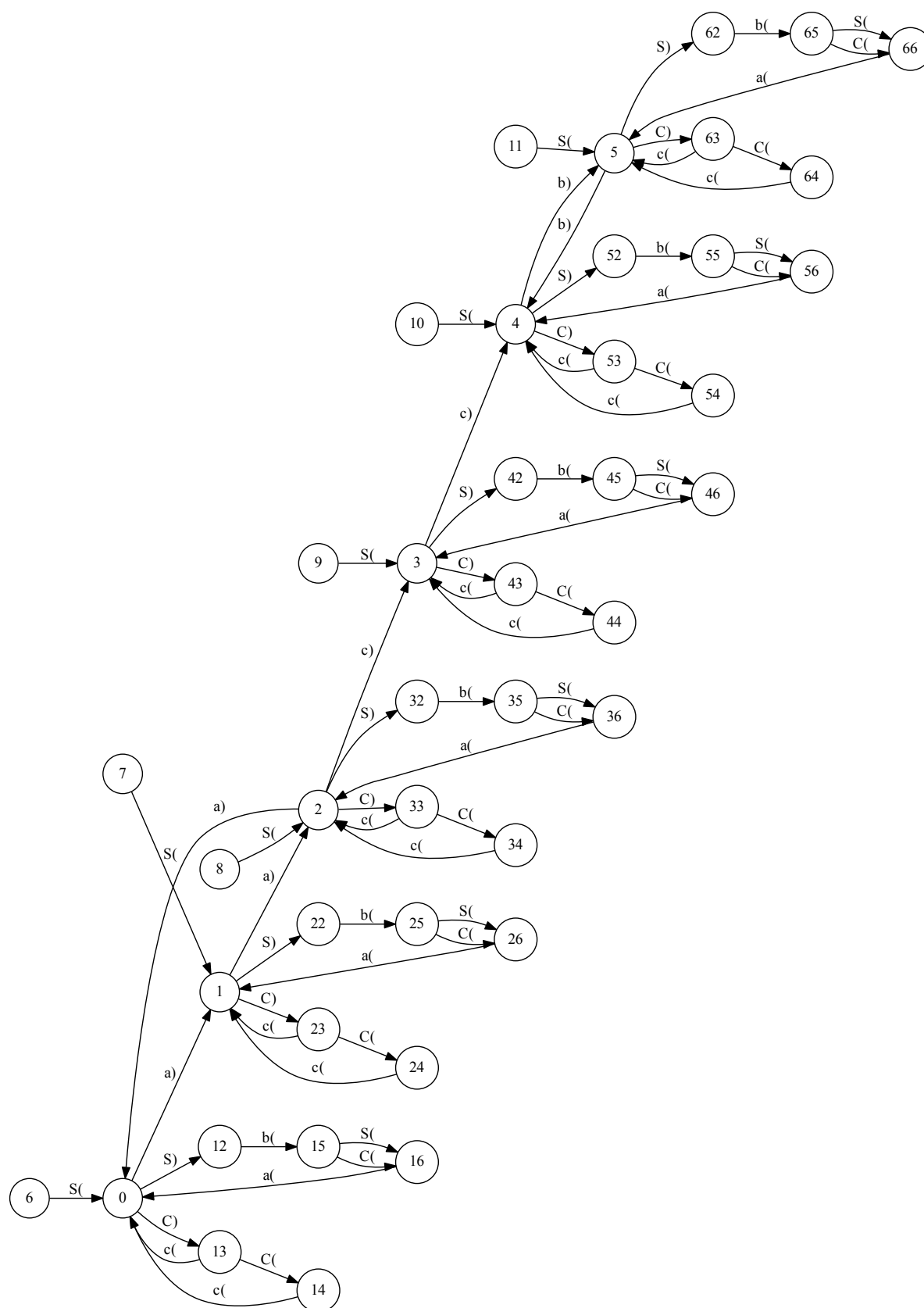


Figure 7: New input graph