

Rytter-style Algorithm for Context-Free Path Querying

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ACM Reference Format:

Semyon Grigorev and Ekaterina Shemetova. 2020. Rytter-style Algorithm for Context-Free Path Querying. In *Proceedings of ACM Conference (Conference'17)*. ACM, New York, NY, USA, 5 pages. <https://doi.org/10.1145/nnnnnnnn.nnnnnnnn>

1 THE REDUCTION

Suppose we have Φ — an instance of 3-SAT problem contains m clauses over k variables.

First of all, we should to construct a graph. To do it we follow the next steps.

- (1) Let $\gamma_i = \{v_1 \leftarrow b_1, v_2 \leftarrow b_2, \dots, v_k \leftarrow b_k\}$ where $b_k \in \{0, 1\}$. For each substitution γ_i a vertex V_{γ_i} should be created.
- (2) For each V_{γ_i} the following edges should be added: $\{(V_{\gamma_i}, [v_j \leftarrow b_l]^+, V_{\gamma_i}) \mid v_j \leftarrow b_l \in \gamma_i\}$.
- (3) For each clause $(l_1 \vee l_2 \vee l_3)$ the following subgraph should be created. First, two new vertices are added: c_1 and c_2 . After that, the following edges for each l_p and for each γ_i should be added

$$\{(c_1, [v_j \leftarrow b_l]^-, c_2) \mid b_l = \begin{cases} 1 & \text{if } l_p = v_j \\ 0 & \text{if } l_p = \neg v_j \end{cases}\}.$$

- (4) Subgraph for all clauses should be connected sequentially. Suppose we have sequence of subgraphs with vertices

$$\{(c_1^1, c_2^1), (c_1^2, c_2^2), \dots, (c_1^m, c_2^m)\}.$$

To connect them we should merge vertices c_2^i and c_1^{i+1} for all i except $i = m$. After that we fix c_1^1 as a start vertex of formula subgraph, and c_2^m as a final vertex of formula subgraph.

- (5) Finally, for all V_{γ_i} we should add the following edge

$$(V_{\gamma_i}, q, c_1^1)$$

The second part is a query. Suppose, we have p different substitutions. The grammar is following

$$\begin{aligned} S &\rightarrow q \\ S &\rightarrow [v_1 \leftarrow b_1]^+ S [v_1 \leftarrow b_1]^- \\ &\mid \dots \\ &\mid [v_k \leftarrow b_k]^+ S [v_k \leftarrow b_k]^- \end{aligned}$$

After that we should apply transformation which is described in the section 4. As a result we get h-Dyck reachability problem (yes, we can reduce it to 2-Dyck reachability).

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Conference'17, July 2017, Washington, DC, USA

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ACM ISBN 978-x-xxxx-xxxx-x/YY/MM...\$15.00

<https://doi.org/10.1145/nnnnnnnn.nnnnnnnn>

1.1 An Example of Reduction

Suppose we have the following instance of 3-SAT problem.

$$\Phi = (\neg x_1 \vee x_2 \vee \neg x_3) \wedge (\neg x_2 \vee x_1 \vee x_3) \wedge (x_1 \vee \neg x_3 \vee x_2)$$

Substitutions:

$$\begin{aligned} \gamma_1 &= \{x_1 \leftarrow 0, x_2 \leftarrow 0, x_3 \leftarrow 0\} \\ \gamma_2 &= \{x_1 \leftarrow 1, x_2 \leftarrow 0, x_3 \leftarrow 0\} \\ \gamma_3 &= \{x_1 \leftarrow 0, x_2 \leftarrow 1, x_3 \leftarrow 0\} \\ \gamma_4 &= \{x_1 \leftarrow 0, x_2 \leftarrow 0, x_3 \leftarrow 1\} \\ \gamma_5 &= \{x_1 \leftarrow 1, x_2 \leftarrow 1, x_3 \leftarrow 0\} \\ \gamma_6 &= \{x_1 \leftarrow 1, x_2 \leftarrow 0, x_3 \leftarrow 1\} \\ \gamma_7 &= \{x_1 \leftarrow 0, x_2 \leftarrow 1, x_3 \leftarrow 1\} \\ \gamma_8 &= \{x_1 \leftarrow 1, x_2 \leftarrow 1, x_3 \leftarrow 1\} \end{aligned}$$

Graph for Φ is presented in figure 2.

The grammar:

$$\begin{aligned} S &\rightarrow [x_1 \leftarrow 0]^+ S [x_1 \leftarrow 0]^- \\ &\mid [x_2 \leftarrow 0]^+ S [x_2 \leftarrow 0]^- \\ &\mid [x_3 \leftarrow 0]^+ S [x_3 \leftarrow 0]^- \\ &\mid [x_1 \leftarrow 1]^+ S [x_1 \leftarrow 1]^- \\ &\mid [x_2 \leftarrow 1]^+ S [x_2 \leftarrow 1]^- \\ &\mid [x_3 \leftarrow 1]^+ S [x_3 \leftarrow 1]^- \\ &\mid q \end{aligned}$$

The intuition of such path finding is that substitution vertex (V_{γ_i}) should provide appropriate values for respective variable in appropriate order to satisfy the given formula. It can be done by appropriate traversing of loops. After that, each edge from c_i^j to c_l^k “uses” provided values to satisfy respective closure, and it can be done if and only if the respective vertex provides value required. This fact is expressed by using balanced-bracket grammar. So, if there exists a path from V_{γ_i} to c_2^3 , such that the corresponded word is derivable from S , then V_{γ_i} satisfy the given formula.

2 IMPROVED REDUCTION

First step is to split variables into three group of the same size. Suppose this splitting preserves the order. So, we have a set of partial substitution.

By the same way we create vertices for partial substitutions.

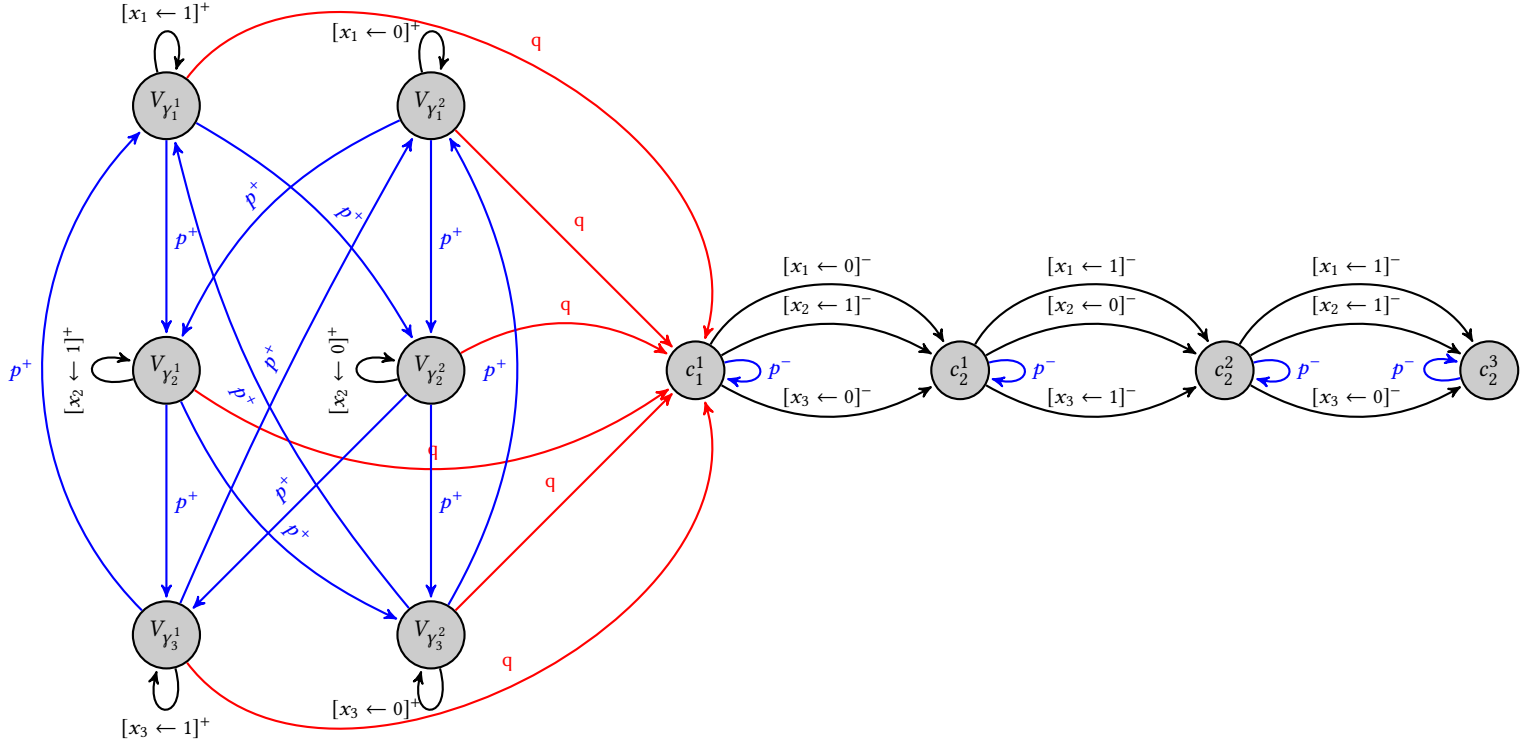
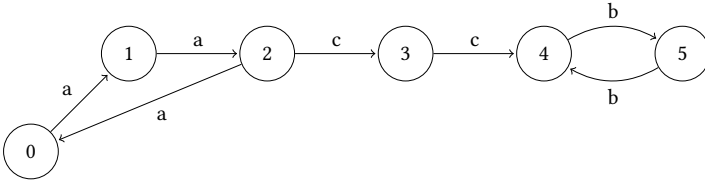
Figure 2: Example of graph for Φ 

Figure 3: The input graph

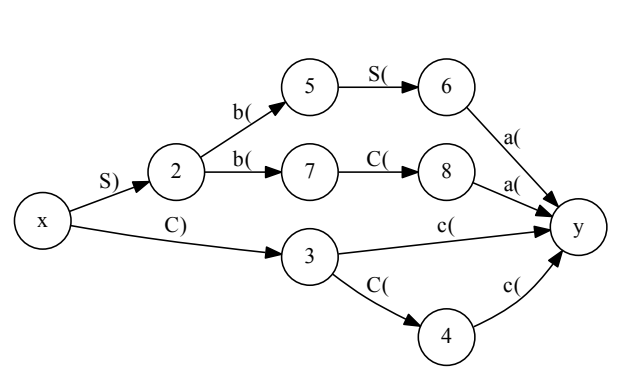
We should construct new input graph G' and new grammar \mathcal{G}' such that \mathcal{G}' specifies a Dyck language and there is a simple mapping from $\text{CFPQ}(\mathcal{G}', G')$ to $\text{CFPQ}(\mathcal{G}, G)$. Step-by-step example with description is provided below.

Let the input grammar is

$$\begin{aligned} S &\rightarrow a S b \mid a C b \\ C &\rightarrow c \mid C c \end{aligned}$$

The input graph is presented in fig. 3.

- (1) Let $\Sigma_0 = \{t_i \mid t_i \in \Sigma\}$.
- (2) Let $N_0 = \{N_i \mid N_i \in N\}$.
- (3) Let $M_{\mathcal{G}} = (V_{\mathcal{G}}, E_{\mathcal{G}}, L_{\mathcal{G}})$ is a directed labeled graph, where $L_{\mathcal{G}} \subseteq (\Sigma_0 \cup N_0)$. This graph is created the same manner as described in [1] but we do not require the grammar be in CNF. Let $x \in V_{\mathcal{G}}$ and $y \in V_{\mathcal{G}}$ is "start" and "final" vertices respectively. This graph may be treated as a finite automaton, so it can be minimized and

Figure 4: The $M_{\mathcal{G}}$ graph

we can compute an ε -closure if the input grammar contains ε productions. The graph $M_{\mathcal{G}}$ for our example is presented in fig. 4. The minimized graph is presented in fig. 5.

- (4) For each $v \in V$ create $M_{\mathcal{G}}^v$: unique instance of $M_{\mathcal{G}}$.
- (5) New graph G' is a graph G where each label t is replaced with t_i^i and some additional edges are created:
 - Add an edge (v', S_i, v) for each $v \in V$.
 - And the respective $M_{\mathcal{G}}^v$ for each $v \in V$:

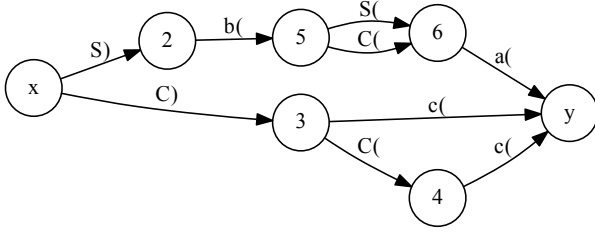


Figure 5: The minimized $M_{\mathcal{G}}$

- reattach all edges outgoing from x^v (“start” vertex of $M_{\mathcal{G}}^v$) to v ;
- reattach all edges incoming to y^v (“final” vertex of $M_{\mathcal{G}}^v$) to v .

New input graph is ready. It is presented in fig. 6.

- (6) New grammar $\mathcal{G}' = (\Sigma', N', P', S')$ where $\Sigma' = \Sigma_0 \cup N_0$, $N' = \{S'\}$, $P' = \{S' \rightarrow b_1 S' b_2; S' \rightarrow b_1 b_2 \mid b_1, b_2 \in \Sigma'\} \cup \{S' \rightarrow S' S'\}$ is a set of productions, $S' \in N'$ is a start nonterminal.

Now, if $\text{CFPQ}(\mathcal{G}', G')$ contains a pair (u'_0, v') such that $e = (u'_0, S_1, u'_1) \in E'$ is an extension edge (step 5, first subitem), then $(u'_1, v') \in \text{CFPQ}(\mathcal{G}, G)$.

In our example, we can find the following path: $7 \xrightarrow{S_1} 1 \xrightarrow{S_1} 22 \xrightarrow{b_1} 25 \xrightarrow{C_1} 26 \xrightarrow{a_1} 1 \xrightarrow{a_1} 2 \xrightarrow{C_1} 33 \xrightarrow{C_1} 34 \xrightarrow{c_1} 2 \xrightarrow{c_1} 3 \xrightarrow{C_1} 43 \xrightarrow{c_1} 3 \xrightarrow{c_1} 4 \xrightarrow{b_1} 5$. Edge $7 \xrightarrow{S_1} 1$ is the extension, so $(1, 5)$ should be in $\text{CFPQ}(\mathcal{G}, G)$ and it is true.

REFERENCES

- [1] Krishnendu Chatterjee, Bhavya Choudhary, and Andreas Pavlogiannis. 2017. Optimal Dyck Reachability for Data-dependence and Alias Analysis. *Proc. ACM Program. Lang.* 2, POPL, Article 30 (Dec. 2017), 30 pages. <https://doi.org/10.1145/3158118>

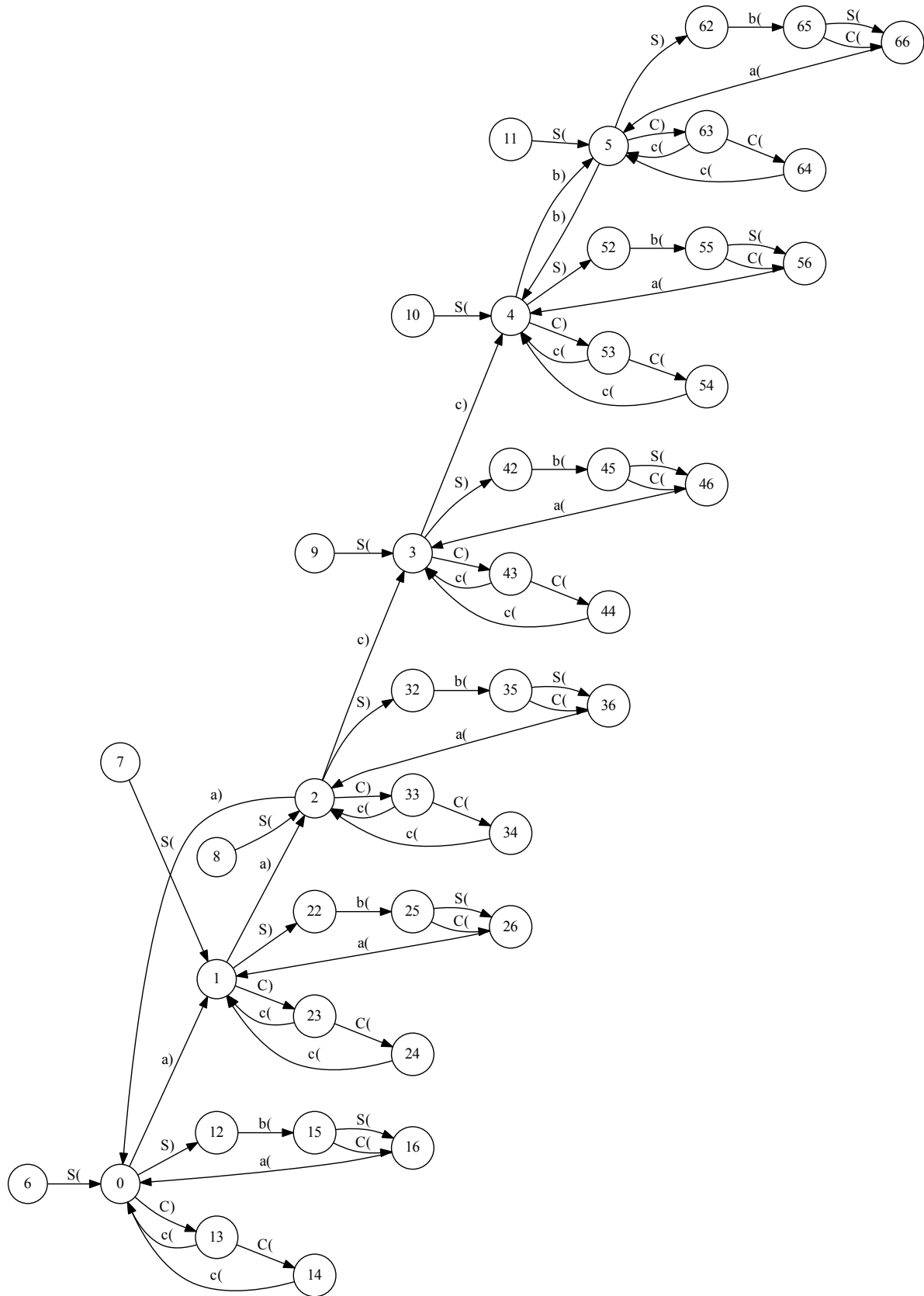


Figure 6: New input graph