Lecture 2:

Linear Methods of Machine Learning:

1) Principal Component Analysis (PCA)

- 1. Principal Component Analysis (PCA) most popular linear data analysis technique
- 2. PCA as the best linear approximation
- 3. PCA as the best solution to linear dimensionality reduction problem
- 4. PCA from Singular Value Decomposition technique
- 5. PCA as the best solution to Metric Multi Dimensionality Scaling
- 6. PCA as maximum variance preserving technique
- 7. PCA: how many components should be left
- 8. PCA: example (human faces)

Notations

$$X = \begin{pmatrix} x_1 \\ \dots \\ x_p \end{pmatrix} \in \mathbb{R}^p$$
- p-dimensional vector with components x_1, x_2, \dots, x_p

$$\{X_1, X_2, \ldots, X_n\}$$
 – dataset, $X_i = \begin{pmatrix} x_{i1} \\ \cdots \\ x_{ip} \end{pmatrix}$, $i = 1, 2, \ldots, n$ $X_i = \begin{pmatrix} x_{i1} \\ x_{i1} \\ x_{i2} \end{pmatrix}$

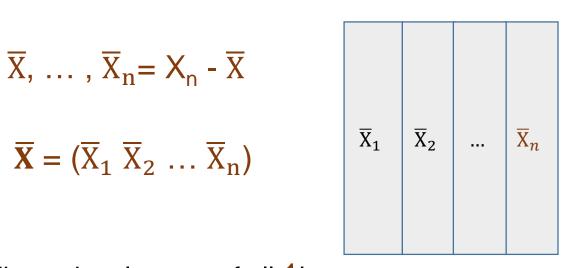
described by
$$\mathbf{p} \times \mathbf{n}$$
 data matrix $\mathbf{X} = (\mathbf{X}_1 \ \dots \ \mathbf{X}_n) = \begin{pmatrix} \mathbf{X}_{11} & \cdots & \mathbf{X}_{n1} \\ \cdots & \cdots & \cdots \\ \mathbf{X}_{1p} & \cdots & \mathbf{X}_{np} \end{pmatrix}$ $\mathbf{X}_1 \ \mathbf{X}_2 \ \dots \ \mathbf{X}_n$

Mean vector
$$\overline{X} = \frac{1}{n} \sum_{i=1}^{n} X_i$$

$$\overline{X}_1 = X_1 - \overline{X}, \ \overline{X}_2 = X_2 - \overline{X}, \dots, \ \overline{X}_n = X_n - \overline{X}$$

described by p×n centering data matrix

$$\overline{\mathbf{X}} = (\overline{\mathbf{X}}_1 \ \overline{\mathbf{X}}_2 \ \dots \ \overline{\mathbf{X}}_n)$$



 $\mathbf{H} = \mathbf{I}_{n} - \frac{1}{n} \mathbf{1} \times \mathbf{1}^{T} - \mathbf{n} \times \mathbf{n}$ centering matrix, $\mathbf{1} - \mathbf{n}$ -dimensional vector of all 1's:

$$\mathbf{H} \times \begin{pmatrix} a_1 \\ a_2 \\ \dots \\ a_n \end{pmatrix} = \begin{pmatrix} a_1 - \overline{a} \\ a_2 - \overline{a} \\ \dots \\ a_n - \overline{a} \end{pmatrix}, \qquad \overline{a} = \frac{1}{n} \sum_{i=1}^n a_i$$

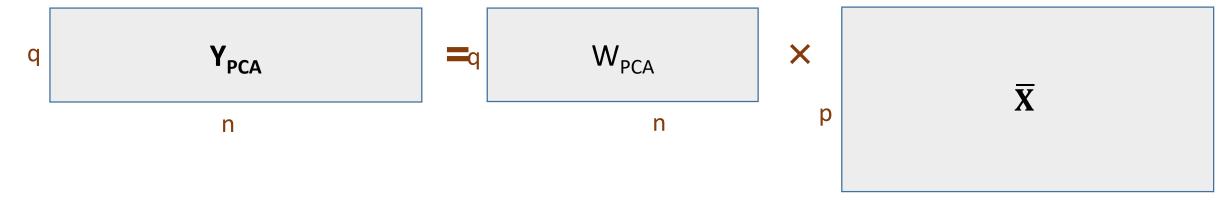
$$\overline{\mathbf{X}} = \mathbf{H} \times \mathbf{X}$$
 and $\{X_1, X_2, \dots, X_n\} \leftrightarrow (\overline{X}, \overline{X})$

Principal Component Analysis (PCA):

Linear data analysis technique that transform a vector consisting of possibly correlated variables (original features) into a vector consisting of low-dimensional uncorrelated features called principal components with certain desired properties

$$X \in R^p$$
 - original features \rightarrow $Y_{PCA} = W_{PCA} \times (X - \overline{X}) \in R^q$ - reduced features $W_{PCA} - q \times p$ - PCA-matrix

data
$$\{X_1, X_2, ..., X_n\} \rightarrow \text{reduced data matrix } \mathbf{Y}_{PCA} = (y_1 y_2 ... y_n)$$



Most popular and best-known, one of the oldest (K. Pearson, 1901) data analysis method widely used **as preprocessing step** in multivariate analysis, machine learning, pattern recognition, data mining, image processing, visualization, etc.

Underlies the many other linear and nonlinear data analysis methods

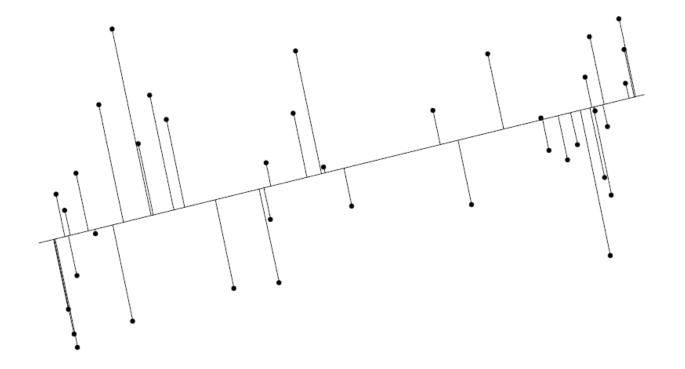
Various names:

- discrete Karhunen-Lòeve transform in stochastic analysis, image/video compression, and signal processing,
- Hotelling transform in multivariate quality control;
- proper orthogonal decomposition (POD) in mechanical engineering,
- singular value decomposition (SVD) or eigenvalue decomposition (EVD) in linear algebra, etc.

PCA can be justified in several ways

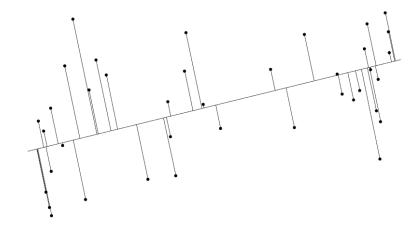
(from various points of view, a few various criteria leading to PCA)

1) The best linear approximation: to find low-dimensional linear affine subspace that best approximates given high-dimensional dataset

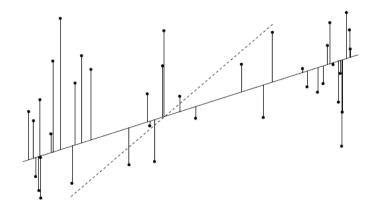


- L(q) desired q-dimensional linear affine subspace in R^p,
 for the time being, the dimension q is assumed to be chosen (given)
- $Pr_{L(q)}(X)$ orthogonal projection of p-dimensional vector X into L(q)

Best subspace minimizes the objective function $J(L(q)) = \frac{1}{n} \sum_{i=1}^{n} ||X_i - Pr_{L(q)}(X_i)||^2$



Not regression line



$$L(q) = L(q, X_0, E) = \{X_0 + \sum_{k=1}^q t_k \times e_k \in R^p : t = (t_1, t_2, \dots, t_q)^T \in R^q \} - t_1 + t_2 + t_3 + t_4 + t_4 + t_5 + t_6 + t_$$

q-dimensional linear affine plane

- passing through a point $X_0 \in \mathbb{R}^p$, and
- spanned by **orthonormal** vectors $\{e_1,\,e_2,\,\ldots\,,\,e_q\}\subset R^p$
- $E = (e_1 \dots e_q)$ orthogonal p×q matrix:

$$E^T \times E = I_q$$
 - unit $q \times q$ matrix

$$Pr_{L(q)}(X) = X_0 + \sum_{k=1}^{q} (X - X_0, e_k) \times e_k \in L(q, X_0, E)$$
 - orthogonal projection of vector X into L(q)

$$\mathsf{J}(\mathsf{L}(\mathsf{q},\,\mathsf{X}_0,\,\mathsf{E})) = \frac{1}{n} \sum_{i=1}^n \left\| \mathsf{X}_i - \mathsf{Pr}_{\mathsf{L}(\mathsf{q})}(\mathsf{X}_i) \right\|^2 = \frac{1}{n} \sum_{i=1}^n \left\| (\mathsf{X}_i - \mathsf{X}_0) - \sum_{k=1}^q (\mathsf{X}_i - \mathsf{X}_0,\,\mathsf{e}_k) \times \mathsf{e}_k \right\|^2$$

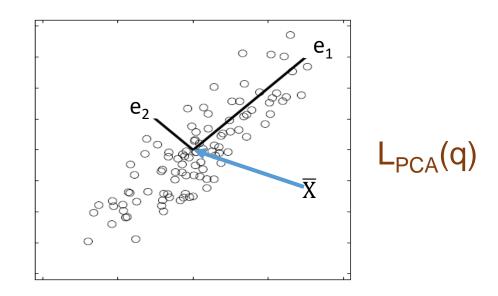
Let \overline{X} - mean vector and $L^*(q) = L(q, \overline{X}, E)$ - affine subspace passing through the mean vector.

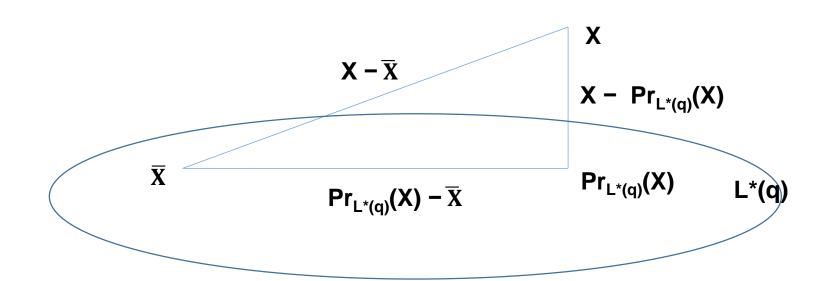
For any orthogonal $p \times q$ matrix E:

$$J(L(q, X_0, E)) = J(L(q, \overline{X}, E)) + ||X_0 - Pr_{L^*(q)}(X_0)||^2$$

Hence:

- X_0 must belong to the affine space $L(q, \overline{X}, E)$
- mean vector \overline{X} can be taken as X_0





$$X - \operatorname{Pr}_{\mathsf{L}^*(\mathsf{q})}(\mathsf{X}) = (\mathsf{X} - \overline{\mathsf{X}}) - (\operatorname{Pr}_{\mathsf{L}^*(\mathsf{q})}(\mathsf{X}) - \overline{\mathsf{X}}) \text{ and } \mathsf{X} - \operatorname{Pr}_{\mathsf{L}^*(\mathsf{q})}(\mathsf{X}) \perp \operatorname{Pr}_{\mathsf{L}(\mathsf{q})}(\mathsf{X}) - \overline{\mathsf{X}})$$

$$\left\| |\mathsf{X} - \operatorname{Pr}_{\mathsf{L}^*(\mathsf{q})}(\mathsf{X}) \right\|^2 = \|\mathsf{X} - \overline{\mathsf{X}}\|^2 - \left\| \overline{\mathsf{X}} - \operatorname{Pr}_{\mathsf{L}^*(\mathsf{q})}(\mathsf{X}) \right\|^2$$

$$\begin{split} & J(\mathsf{L}(\mathsf{q},\overline{\mathsf{X}},\,\mathsf{E})) = & \frac{1}{n} \sum_{i=1}^n \left\| \mathsf{X}_i - \mathsf{Pr}_{\mathsf{L}^*(\mathsf{q})}(\mathsf{X}_i) \right\|^2 = & \frac{1}{n} \sum_{i=1}^n \left\| (\mathsf{X}_i - \overline{\mathsf{X}}) - \sum_{k=1}^q (\mathsf{X}_i - \overline{\mathsf{X}},\, e_k) \times e_k \right\|^2 \\ & = & \frac{1}{n} \sum_{i=1}^n \left\| \mathsf{X}_i - \overline{\mathsf{X}} \right\|^2 - \frac{1}{n} \sum_{i=1}^n \left\| \sum_{k=1}^q (\mathsf{X}_i - \overline{\mathsf{X}},\, e_k) \times e_k \right\|^2 \end{split}$$

Orthogonal $p \times q$ matrix $E = (e_1 \dots e_q)$ must maximize quadratic form

$$\Phi(E) = \frac{1}{n} \sum_{i=1}^{n} \left\| \sum_{k=1}^{q} (X_i - \overline{X}, e_k) \times e_k \right\|^2$$

using an orthonormality of $\{e_1, e_2, \dots, e_q\}$:

$$\Phi(E) = \frac{1}{n} \sum_{i=1}^{n} \sum_{k=1}^{q} |(X_i - \overline{X}, e_k)|^2$$

using a representation $(u, v) = u^T \times v = v^T \times u$:

$$\frac{1}{n}\sum_{i=1}^{n}\sum_{k=1}^{q}\left(e_{k}^{T}\times(X_{i}^{-}\overline{X})\right)\times\left((X_{i}^{-}\overline{X})^{T}\times e_{k}\right)=\frac{1}{n}\sum_{i=1}^{n}\sum_{k=1}^{q}e_{k}^{T}\times\left[(X_{i}^{-}\overline{X})\times(X_{i}^{-}\overline{X})^{T}\right]\times e_{k}$$

changing the order of summation:

$$\begin{split} \Phi(\mathsf{E}) &= \tfrac{1}{n} \sum_{k=1}^q \mathrm{e}_k^\mathrm{T} \times \left(\sum_{i=1}^n (\mathrm{X}_i - \ \overline{\mathrm{X}}) \times (\mathrm{X}_i - \ \overline{\mathrm{X}})^\mathrm{T} \right) \times \mathrm{e}_k \\ &= \mathsf{Tr}(\mathsf{E}^\mathsf{T} \times \left(\tfrac{1}{n} \sum_{i=1}^n (\mathrm{X}_i - \ \overline{\mathrm{X}}) \times (\mathrm{X}_i - \ \overline{\mathrm{X}})^\mathrm{T} \right) \times \mathsf{E}) \end{split}$$

- X p-dimensional random vector
- $Cov(X) = M(X MX) \times (X MX)^T p \times p$ covariance matrix
- $\{X_1, X_2, ..., X_n\}$ i.i.d. (sample)
- \overline{X} sample mean (estimator of MX)
- $\Sigma = \frac{1}{n} \sum_{i=1}^{n} (X_i \overline{X}) \times (X_i \overline{X})^T$ sample covariance matrix estimator of Cov(X)

(1) Optimizing problem: maximize the quadratic form

$$\Phi(e_1, e_2, \dots, e_q) = \sum_{k=1}^q e_k^T \times \Sigma \times e_k$$

over vectors $e_1, e_2, \dots, e_q \in \mathbb{R}^p$ under 'orthonormality' constraints

$$(e_i, e_j) = \delta_{ij}, \quad 1 \le i \le j \le n$$
 $(\delta_{ij} - Kronecker symbol)$

(2) – **Eigenvector problem**: maximize the quadratic form

$$\Phi(\mathsf{E}) = \mathsf{Tr}(\mathsf{E}^\mathsf{T} \times \Sigma \times \mathsf{E})$$

over $p \times q$ matrix E under constraint $E^T \times E = I_q$

Denote St(p, q) – a set consisting of orthogonal $p \times q$ matrices – Stiefel manifold

(3) Optimizing problem: to maximize the quadratic form $\Phi(E) = Tr(E^T \times \Sigma \times E)$ over $E \in St(p, q)$

Solution to the Eigenvector problem: the columns $e_1, e_2, \dots, e_q \in R^p$ of the desired matrix E

are p-dimensional eigenvectors of p×p matrix Σ:

$$\Sigma e_k = \lambda_k \times e_k$$
, $k = 1, 2, ..., q$

• corresponding to q largest eigenvalues $\lambda_1 \ge \lambda_2 \ge ... \ge \lambda_q$ of the matrix Σ , respectively.

The best approximating affine subspace: $L_{PCA}(q) = L(q, \overline{X}, E_{PCA})$

$$\mathsf{Pr}_{\mathsf{PCA}}(\mathsf{X}) = \overline{\mathsf{X}} + \sum_{k=1}^q y_k \times e_k \in \mathsf{L}_{\mathsf{PCA}}(\mathsf{q}), \qquad \mathsf{Y}_{\mathsf{PCA}} = (\mathsf{y}_1, \, \mathsf{y}_2, \, \ldots, \, \mathsf{y}_\mathsf{q})^\mathsf{T} = (\mathsf{E}_{\mathsf{PCA}})^\mathsf{T} \times (\mathsf{X} - \overline{\mathsf{X}}) \in \mathsf{R}^\mathsf{q}$$

- orthogonal projection $Pr_{PCA}(X)$ of p-dimensional vector X into $L_{PCA}(q)$

$$W_{PCA} = (E_{PCA})^T$$
: defines

- best approximating affine subspace: $L_{PCA}(q) = L(q, \overline{X}, (W_{PCA})^T)$
- PCA-features $Y_{PCA} = W_{PCA} \times (X \overline{X})$

'Direct' solution to the optimizing problem

(1) maximize the quadratic form

$$\Phi_{n}(e_1, e_2, \dots, e_q) = \sum_{k=1}^{q} e_k^T \times \Sigma \times e_k$$

over vectors $\{e_1, e_2, \dots, e_q\}$ under 'orthonormality' constraints $(e_i, e_j) = \delta_{ij}, \ 1 \le i \le j \le n$

Step 1. Maximizing the first summand $(e_1)^T \times \Sigma \times e_1$ over e_1 subject to $(e_1)^T \times e_1 = 1$

Lagrange multipliers: maximize

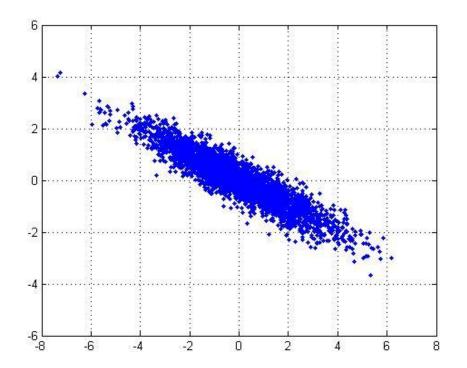
$$(e_1)^T \times \Sigma \times e_1 + \lambda \times (1 - (e_1)^T \times e_1)$$

Setting the gradient $\nabla = 2\Sigma \times e_1 - 2\lambda \times e_1$ w.r.t. e_1 to zero, we find that

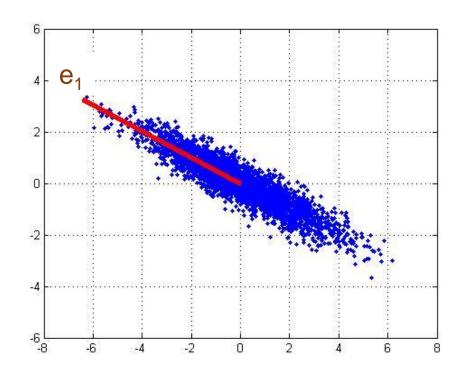
$$\Sigma \times e_1 = \lambda \times e_1 \rightarrow e_1 - eigenvector, \lambda - eigenvalue$$

$$(e_1)^T \times \Sigma \times e_1 = (e_1)^T \times \lambda \times e_1 = \lambda \times (e_1 \times (e_1)^T) = \lambda \in \{\lambda_1, \ \lambda_2, \ \dots \ , \ \lambda_q\}$$

$$\rightarrow$$
 max((e₁)^T× Σ ×e₁) = λ _{max} = λ ₁







1st PCA axis e₁

Step 2. Maximizing second summand $(e_2)^T \times \Sigma \times e_2$ over e_2 subject to $(e_2)^T \times e_2 = 1$ and $(e_2)^T \times e_1 = 0$ Lagrange multipliers: maximize

$$(e_2)^T \times \Sigma \times e_2 + \lambda \times (1 - (e_2)^T \times e_{12}) + b \times (e_2)^T \times e_1$$

the gradient w.r.t. $e_2 = 0$: $\rightarrow \Sigma \times e_2 - \lambda \times e_2 + b \times e_1 = 0$ (*

$$(\mathbf{e}_2)^\mathsf{T} \times \mathbf{e}_1 = 0 : \to (\mathbf{e}_2)^\mathsf{T} \times \Sigma \times \mathbf{e}_1 = (\mathbf{e}_2)^\mathsf{T} \times (\lambda \times \mathbf{e}_1) = \lambda_1 \times (\mathbf{e}_2)^\mathsf{T} \times \mathbf{e}_1 = 0$$

$$\to (\mathbf{e}_1)^\mathsf{T} \times \Sigma \times \mathbf{e}_2 = (\mathbf{e}_2)^\mathsf{T} \times \Sigma \times \mathbf{e}_1 = 0$$

a multiplication of equation (*) on the left by $(e_1)^T$ gives

$$(e_1)^T \times (\Sigma \times e_2 - \lambda \times e_2 + b \times e_1) = (e_1)^T \times \Sigma \times e_2 - \lambda \times ((e_1)^T \times e_2) + b \times ((e_1)^T \times e_1) = 0,$$

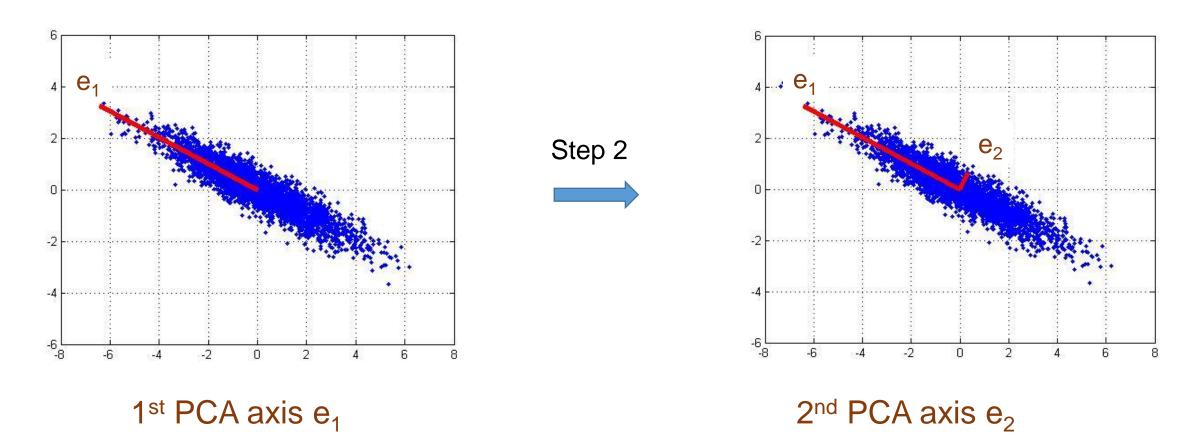
hence, b = 0 and (*) yields

$$\Sigma \times \mathbf{e}_2 = \lambda \times \mathbf{e}_2$$
 (\mathbf{e}_2 – eigenvector, λ - eigenvalue) and (\mathbf{e}_2)^T $\times \Sigma \times \mathbf{e}_2 = \lambda$

Let $u_1 = e_1, u_2, \ldots, u_p \in \mathbb{R}^p$ be all the eigenvectors of the $p \times p$ matrix Σ corresponding to the eigenvalues $\lambda_1 \geq \lambda_2 \geq \ldots \geq \lambda_p$ of the matrix Σ , respectively.

Thus, we must choose e_2 among the vectors $\{u_2, u_3, \dots, u_p\}$ and

$$\max_{2 \le k \le p} ((u_k)^T \times \Sigma \times u_k) = \max_{2 \le k \le p} \lambda_k = \lambda_2$$



... and in like manner vectors e_3 , e_4 , ..., e_q are sought

Solution to the Eigenvector problem:

• vectors $e_1, e_2, \dots, e_q \in \mathbb{R}^p$ which are the p-dimensional eigenvectors of $p \times p$ matrix Σ :

$$\Sigma e_k = \lambda_k \times e_k$$
, $k = 1, 2, ..., q$

• corresponding to q largest eigenvalues $\lambda_1 \geq \lambda_2 \geq ... \geq \lambda_q$ of the matrix Σ , respectively,

maximize the objective function $\Phi(e_1,\,e_2,\,\dots\,,\,e_q)=\sum_{k=1}^q e_k^T\times \Sigma\times e_k$ and

$$\max(\sum_{k=1}^{q} e_k^T \times \Sigma \times e_k) = \sum_{k=1}^{q} \lambda_k$$

2) The best solution of linear dimensionality reduction problem:

to find low-dimensional features which provide minimal recovering error

Dimensionality reduction

Reduced q-dimensional features $\{y_1, y_2, \dots, y_n\}$ are the results of applying of **Embedding mapping**

h:
$$X \in \mathbb{R}^p \rightarrow y = h(X) \in \mathbb{R}^q$$

to original p-dimensional features $\{X_1, X_2, \dots, X_n\}$

Low-dimensional reduced features must **preserve as much as possible available information** contained in high-dimensional original features: the possibility for **accurate recovery** of the original vectors from their low-dimensional features

Preserving information - the possibility for **recovery** of original vectors from reduced low-dimensional features **with small recovering error**

- an existence of a recovering mapping

g:
$$y = h(X) \in R^q \rightarrow g(y) \in R^p$$

from q-dimensional Reduced feature space to p-dimensional Original feature space

- a recovered value

$$y = h(X) \in R^q \rightarrow \widehat{X} = g(y) = g(h(X))$$

such that a recovering error $\Delta(X) = ||\widehat{X} - X||$ is small

Minimum average recovering error:
$$\Delta(W, V) = \left(\frac{1}{n}\sum_{i=1}^{n}\left|\widehat{X}_{i}-X_{i}\right|^{2}\right)^{1/2} \rightarrow \text{min over h, g}$$

Linear Dimensionality reduction

Linear embedding mapping h is defined by orthogonal q×p matrix W

$$W \times W^T = I_q$$
:

$$y_i = W \times (X_i - \overline{X}) \in R^q, i = 1, 2, ..., n$$

Linear recovering mapping is defined by P×Q matrix V and gives recovered values

$$\widehat{X}_i = \overline{X} + V \times y_i$$
, $i = 1, 2, ..., n$

Minimum average recovering error:
$$\Delta(W, V) = \left(\frac{1}{n}\sum_{i=1}^{n}\left|\widehat{X}_{i}-X_{i}\right|^{2}\right)^{1/2} \rightarrow \min \text{ over } W, V$$

Under chosen $q \times p$ matrix W, the best recovering mapping V = V(W) minimizes the recovering error

$$\|\widehat{X} - X\| = \|(X - \overline{X}) - V \times W \times (X - \overline{X})\|$$

 $V(W) = \arg\min_{V} \|\widehat{X} - X\| = W^+ - p \times q$ (left) pseudoinverse Moore-Penrose matrix to $q \times p$ matrix W

Due orthogonality of W

$$W^+ = (W^T \times W)^{-1} \times W^T = W^T$$

Recovered value: $\widehat{X}(W) = \overline{X} + W^T \times W \times (X - \overline{X})$

Squared averaged recovering error:

$$\Delta^{2}(W) = \frac{1}{n} \sum_{i=1}^{n} \left| \widehat{X}_{i}(W) - X_{i} \right|^{2} \rightarrow \min$$

Squared recovering error:

$$\Delta^{2}(W) = \frac{1}{n} \sum_{i=1}^{n} |\widehat{X}_{i}(W) - X_{i}|^{2} = \frac{1}{n} \sum_{i=1}^{n} |\overline{X} + W^{T} \times W \times (X_{i} - \overline{X}) - X_{i}|^{2}$$

Denote $P(W) = W^T \times W - p \times p$ matrix

$$\Delta^{2}(W) = \frac{1}{n} \sum_{i=1}^{n} |(X_{i} - \overline{X}) - P(W) \times (X_{i} - \overline{X})|^{2}$$

L(W^T) - q-dimensional linear space L(W^T)

spanned by q columns of p×q matrix W^T

P(W) - projection matrix into L(W^T)

$$\begin{split} & \Delta^{2}(\mathsf{W}) = \frac{1}{n} \sum_{i=1}^{n} |(\mathsf{X}_{i} - \overline{\mathsf{X}}) - \mathsf{P}(\mathsf{W}) \times (\mathsf{X}_{i} - \overline{\mathsf{X}})|^{2} \\ & = \frac{1}{n} \sum_{i=1}^{n} ||\mathsf{X}_{i} - \overline{\mathsf{X}}||^{2} - \frac{1}{n} \sum_{i=1}^{n} |\mathsf{P}(\mathsf{W}) \times (\mathsf{X}_{i} - \overline{\mathsf{X}})|^{2} \\ & = \frac{1}{n} \sum_{i=1}^{n} ||\mathsf{X}_{i} - \overline{\mathsf{X}}||^{2} - \frac{1}{n} \sum_{i=1}^{n} \{(\mathsf{X}_{i} - \overline{\mathsf{X}})^{\mathsf{T}} \times [\mathsf{P}^{\mathsf{T}}(\mathsf{W}) \times \mathsf{P}(\mathsf{W})] \times (\mathsf{X}_{i} - \overline{\mathsf{X}})\} \end{split}$$

 $P(W)\times(X_i-\overline{X})$

 $P^{T}(W) = P^{2}(W) = P(W)$

$$= \frac{1}{n} \sum_{i=1}^{n} ||X_i - \overline{X}||^2 - \frac{1}{n} \sum_{i=1}^{n} \{ (X_i - \overline{X})^T \times [W^T \times W] \times (X_i - \overline{X}) \}$$

$$= \frac{1}{n} \sum_{i=1}^{n} ||X_i - \overline{X}||^2 - \frac{1}{n} \sum_{i=1}^{n} \{ (X_i - \overline{X})^T \times [W^T \times W] \times (X_i - \overline{X}) \}$$

$$= \frac{1}{n} \sum_{i=1}^{n} ||X_i - \overline{X}||^2 - \frac{1}{n} \sum_{i=1}^{n} Tr \left((X_i - \overline{X})^T \times \left(W^T \times W \right) \times (X_i - \overline{X}) \right)$$

$Tr(A \times A^T) = Tr(A^T \times A)$

$$= \frac{1}{n} \sum_{i=1}^{n} \|X_i - \overline{X}\|^2 - \frac{1}{n} \sum_{i=1}^{n} Tr(W \times (X_i - \overline{X}) \times (X_i - \overline{X})^T \times W^T)$$

$$= \frac{1}{n} \sum_{i=1}^{n} \|X_i - \overline{X}\|^2 - \text{Tr}\left(W \times \frac{1}{n} \sum_{i=1}^{n} \left((X_i - \overline{X}) \times (X_i - \overline{X})^T \right) \times W^T \right)$$

$$= \frac{1}{n} \sum_{i=1}^{n} ||X_i - \overline{X}||^2 - \text{Tr}(W \times \Sigma \times W^T)$$

$$\Delta^{2}(W) = \frac{1}{n} \sum_{i=1}^{n} ||X_{i} - \overline{X}||^{2} - Tr(W \times \Sigma \times W^{T}) \rightarrow min$$

$$Tr(W \times \Sigma \times W^T) \rightarrow max$$

$$E = W^{T:}$$
: $Tr(E^T \times \Sigma \times E) \rightarrow max$, $E - orthogonal matrix$

$$E_{PCA} = arg max_F Tr(E^T \times \Sigma \times E)$$

PCA-matrix $W_{PCA} = E_{PCA}^{T}$ minimizes the recovering error $\Delta(W)$

PCA as Dimensionality reduction

Linear embedding mapping defined by q×p matrix W_{PCA}:

$$y_i = h(X_i) = W_{PCA} \times (X_i - \overline{X}), i = 1, 2, ..., n$$

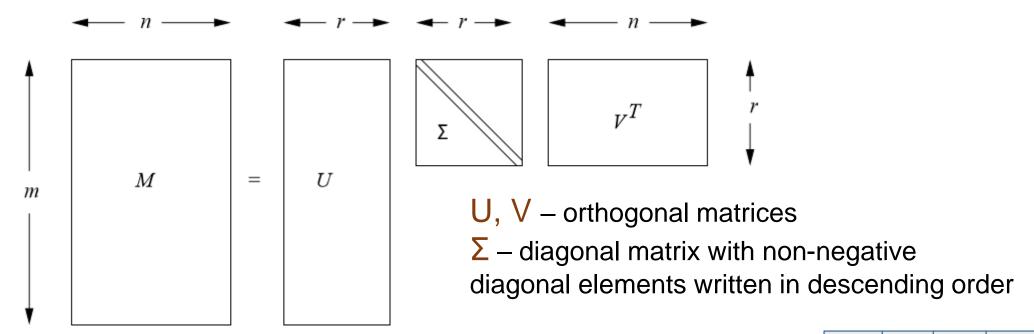
Linear recovering mapping defined by p×q matrix (W_{PCA})^T: gives recovered values

$$\widehat{X}_{PCA,i} = \overline{X} + W_{PCA}^T \times y_i$$
, $i = 1, 2, ..., n$

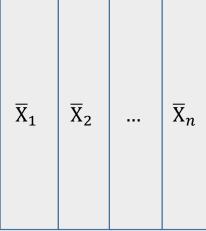
PCA averaged recovering error:

$$\Delta_{PCA}^{2} = \left(\frac{1}{n}\sum_{i=1}^{n}\left|\widehat{X}_{PCA,i} - X_{i}\right|^{2}\right)^{1/2} = \sum_{k=1}^{p}\lambda_{k} - \sum_{k=1}^{q}\lambda_{k} = \sum_{k=q+1}^{p}\lambda_{k}$$

3) PCA from Singular Value Decomposition (SVD)



$$\overline{\mathbf{X}} = (\overline{\mathbf{X}}_1 \ \overline{\mathbf{X}}_2 \ \dots \ \overline{\mathbf{X}}_n) - \mathbf{p} \times \mathbf{n}$$
 centering data matrix



Singular Value Decomposition: $\overline{X} = U_p \times \Lambda_p \times V_p^T$

• $U_p - p \times p$ orthogonal matrix with p orthonormal eigenvectors $e_1, e_2, \dots, e_p \in R^p$ of $p \times p$ matrix

$$\overline{\mathbf{X}} \times \overline{\mathbf{X}} = \sum_{i=1}^{n} \left((X_i - \overline{X}) \times (X_i - \overline{X})^T \right) = n \times \Sigma$$

corresponding to eigenvalues $\lambda_1 \geq \lambda_2 \geq \ldots \geq \lambda_p$ of the matrix Σ , respectively, as columns

- Λ_p p×p diagonal matrix with diagonal elements $\lambda_1, \lambda_2, \dots, \lambda_p$
- \mathbf{V}_{p} $n \times p$ orthogonal matrix: $\mathbf{V}_{p}^{T} \times \mathbf{V}_{p} = \mathbf{I}_{p}$

$$\overline{\boldsymbol{X}} = \boldsymbol{U}_p \times \boldsymbol{\Lambda}_p \times \boldsymbol{V}_p^T \quad \rightarrow \quad \boldsymbol{U}_p^T \times \overline{\boldsymbol{X}} = \boldsymbol{\Lambda}_p \times \boldsymbol{V}_p^T$$

Write in 'column form' for all columns

$$Z_{p,i} = \begin{pmatrix} z_{i1} \\ \cdots \\ z_{ip} \end{pmatrix} = \Lambda_p \times \mathbf{V}_i^{(p)} = \mathbf{U}_p^T \times (X_i - \overline{X}) \in \mathbb{R}^p, i = 1, 2, \dots, n$$

new 'transformed features'

New p-dimensional features $\{Z_{p,1}, Z_{p,2}, \ldots, Z_{p,n}\}$ are 'the same' centered features $\{\overline{X}_1, \overline{X}_2, \ldots, \overline{X}_n\}$ but written in other coordinate system in R^p defined by orthonormal vectors $e_1, e_2, \ldots, e_p \in R^p$

$$Z_{p,i} = \begin{pmatrix} z_{i1} \\ \cdots \\ z_{ip} \end{pmatrix} = \begin{pmatrix} \boldsymbol{Z}_{i1} \\ \boldsymbol{Z}_{i2} \end{pmatrix} \in R^p, \qquad \qquad \boldsymbol{Z}_{i1} = \begin{pmatrix} z_{i1} \\ \cdots \\ z_{iq} \end{pmatrix} \in R^q, \ \boldsymbol{Z}_{i2} = \begin{pmatrix} z_{i,q+1} \\ \cdots \\ z_{ip} \end{pmatrix} \in R^{p-q}$$

$$\Lambda_{p} = \begin{pmatrix} \lambda_{1} & \cdots & 0 \\ \cdots & \cdots & \cdots \\ 0 & \cdots & \lambda_{p} \end{pmatrix} = \begin{pmatrix} \Lambda_{q} & \mathbf{0} \\ \mathbf{0} & \Lambda_{p-q} \end{pmatrix}$$

$$\Lambda_{q} = \begin{pmatrix} \lambda_{1} & \cdots & 0 \\ \cdots & \cdots & \cdots \\ 0 & \cdots & \lambda_{q} \end{pmatrix} - q \times q \text{ diagonal matrix}$$

$$\Lambda_{p-q} = \begin{pmatrix} \lambda_{q+1} & \cdots & 0 \\ \cdots & \cdots & \cdots \\ 0 & \cdots & \lambda_p \end{pmatrix} - (p-q) \times (p-q) \text{ diagonal matrix}$$

$$\mathbf{Z}_{i1} = (\boldsymbol{\Lambda}_{q} \quad \mathbf{0}) \times \mathbf{V}_{i}^{(p)}$$
 $\mathbf{Z}_{i2} = (\mathbf{0} \quad \boldsymbol{\Lambda}_{p-q}) \times \mathbf{V}_{i}^{(p)}$

$$\lambda_1 \geq \lambda_2 \geq \ldots \geq \lambda_p$$

Let last (p-q) eigenvalues $\lambda_{q+1},\,\lambda_{q+2},\,\ldots\,,\,\lambda_p\approx 0$ - are small

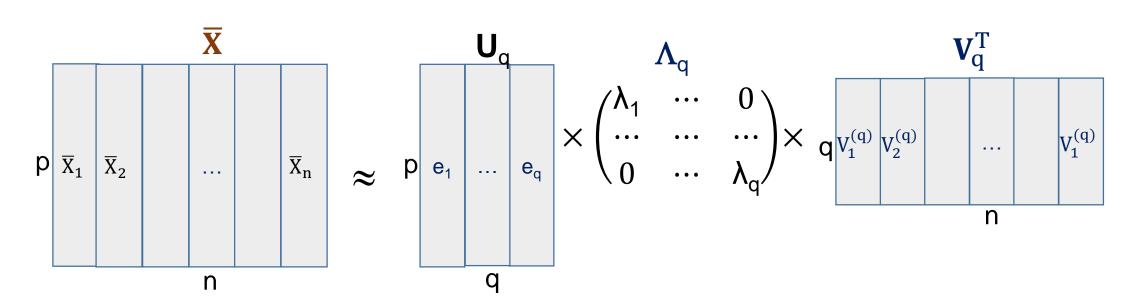
$$\Lambda_{p-q} = \begin{pmatrix} \lambda_{q+1} & \cdots & 0 \\ \cdots & \cdots & \cdots \\ 0 & \cdots & \lambda_p \end{pmatrix} \approx \mathbf{0}$$

$$\mathbf{Z}_{i2} = (\mathbf{0} \quad \Lambda_{p-q}) \times \mathbf{V}_{i}^{(p)} \approx \mathbf{0}$$

Transformed features:
$$Z_{p,i} = \begin{pmatrix} Z_{i1} \\ Z_{i2} \end{pmatrix} \approx \begin{pmatrix} Z_{i1} \\ 0 \end{pmatrix}$$
, $i = 1, 2, ..., n$

Thus, the features
$$\{Z_{i2} = \begin{pmatrix} Z_{i,q+1} \\ \cdots \\ Z_{ip} \end{pmatrix} \in \mathbb{R}^{p-q} \}$$
 are irrelevant and can be removed

$$\overline{\mathbf{X}} pprox \mathbf{U}_{q} imes \mathbf{\Lambda}_{q} imes \mathbf{V}_{q}^{T}$$



- \mathbf{U}_q $p \times q$ orthogonal matrix spanned by eigenvectors $\mathbf{e}_1, \, \mathbf{e}_2, \, \dots, \, \mathbf{e}_q \in R^p$ first q columns of \mathbf{U}_p ,
- Λ_q q×q diagonal matrix with diagonal elements $\lambda_1, \lambda_2, \dots, \lambda_q$

•
$$\mathbf{V}_q$$
 - $\mathbf{n} \times \mathbf{q}$ orthogonal matrix: $\mathbf{V}_q^T \times \mathbf{V}_q = \mathbf{I}_q$ which determines \mathbf{q} -dimensional reduced features:
$$Z_{q,i} = \mathbf{Z}_{i,1} = \begin{pmatrix} z_{i1} \\ \cdots \\ z_{iq} \end{pmatrix} = \mathbf{\Lambda}_q \times \mathbf{V}_i^{(q)} = \mathbf{U}_q^T \times (X_i - \overline{X}) \in \mathsf{R}^p, \ i = 1, \, 2, \, \dots \, , \, n$$

Orthonormal vectors e_1, e_2, \ldots, e_q - p-dimensional eigenvectors of $p \times p$ matrix Σ corresponding to q largest eigenvalues $\lambda_1 \geq \lambda_2 \geq \ldots \geq \lambda_q$ of the matrix Σ

Z_{q,i} – reduced **q**-dimensional 'decorrelated' PCA-features

$$\widehat{X}_i = \overline{X} + Z_{q,i} = \widehat{X}_{PCA,i}$$
 - 'PCA-reconstructed' original features

4) best solution to Metric Multi Dimensionality Scaling (Metric MDS):

to find low-dimensional features which preserve the Euclidean distances

Multi Dimensionality Scaling

- $\{X_1, X_2, ..., X_n\}$ p-dimensional original features
- $\{y_1, y_2, ..., y_n\}$ q-dimensional reduced features
- $\delta_p(X, X')$ and $\delta_q(y, y')$ chosen distance (or dissimilarity) functions in original feature space R^p and reduced feature space R^q , respectively

MDS: to find reduced features $\{y_1, y_2, \dots, y_n\}$ which preserve chosen distances - to minimize

$$\sum_{i,j=1}^{n} r_{ij} \left(\delta_p \big(X_i, X_j \big) - \delta_q \big(y_i, y_j \big) \right)^2 \,, \qquad \qquad \{ r_{ij} \} \,- \, \text{some chosen weights}$$

Example: images $X_1, X_2, ..., X_n$, $\delta_p(X, X')$ – chosen specific 'dissimilarity' function - 'distance'

Visualization: transform the images to 2 (or 3)-dimensional points $\{y_1, y_2, \dots, y_n\}$

Euclidean distances $\{D_q(y_i y_j) = |y_i - y_j|\}$ between the 'visualized' images should preserve as much as possible distances $\{\delta_q(X_i X_j)\}$ between the original images

Metric Multi Dimensionality Scaling (1)

- Euclidean distances
- linear feature transform (embedding) defined by orthogonal q×p matrix W

$$y_i = W \times (X_i - \overline{X}) \in R^q, i = 1, 2, ..., n$$

a preserving the Averaged Pairwise Euclidean Distances (APD):

$$\Delta_{APD}(W) = \sum_{i,j=1}^{n} (\|X_i - X_j\|^2 - \|y_i - y_j\|^2)^2 \rightarrow min$$

 \mathbf{D}_{X} - $\mathbf{N} \times \mathbf{N}$ Euclidean distance matrix with elements $\|\mathbf{X}_{i} - \mathbf{X}_{j}\|^{2}$, i, j = 1, 2, ..., n

 \mathbf{S}_{X} - n×n matrix with 'inner product' elements $\mathbf{S}_{ij} = (X_i - \overline{X}, X_j - \overline{X})$, i, j = 1, 2, ..., n

$$\|X_i - X_j\|^2 = S_{ii} + S_{jj} - 2S_{ij}$$
 \rightarrow $S_{ij} = -\frac{1}{2} \|X_i - X_j\|^2 - S_{ii} - S_{jj}$

 $\mathbf{H} = \mathbf{I}_{n} - \frac{1}{n} \mathbf{1} \times \mathbf{1}^{T} - \mathbf{n} \times \mathbf{n}$ centering matrix, $\mathbf{1} - \mathbf{n}$ -dimensional vector of all 1's:

$$\mathbf{H} \times \begin{pmatrix} a_1 \\ a_2 \\ \dots \\ a_n \end{pmatrix} = \begin{pmatrix} a_1 - \overline{a} \\ a_2 - \overline{a} \\ \dots \\ a_n - \overline{a} \end{pmatrix}, \qquad \overline{a} = \frac{1}{n} \sum_{i=1}^n a_i$$

$$H \times D_X \times H$$
:

- subtracts from each entry of D_X the means of the corresponding row and column
- ullet and adds back the mean of all entries of ${f D}_{f X}$

$$\mathbf{S}_{X} = -\frac{1}{2} \mathbf{H} \times \mathbf{D}_{X} \times \mathbf{H}$$

 $S_Y - n \times n$ matrix with elements (y_i, y_j) , i, j = 1, 2, ..., n

 \mathbf{D}_{Y} - n×n Euclidean distance matrix with elements $\|\mathbf{y}_{i} - \mathbf{y}_{j}\|^{2}$, i, j = 1, 2, ..., n

$$\mathbf{S}_{\mathsf{Y}} = -\frac{1}{2} \, \mathbf{H} \times \mathbf{D}_{\mathsf{y}} \times \mathbf{H}$$

$$\Delta_{APD} = \sum_{i,j=1}^{n} (\|X_i - X_j\|^2 - \|y_i - y_j\|^2)^2 = \|\mathbf{D}_X - \mathbf{D}_Y\|_F^2$$

 $\mathbf{A} = (\mathbf{a}_{ij}): ||\mathbf{A}||_{\mathrm{F}}^2 = \sum_{i,j} a_{ij}^2$ - Frobenius matrix norm

$$\mathbf{S}_{X} - \mathbf{S}_{Y} = -\frac{1}{2} \mathbf{H} \times (\mathbf{D}_{X} - \mathbf{D}_{Y}) \times \mathbf{H}$$

$$\mathbf{S}_{X} - \mathbf{S}_{Y} = -\frac{1}{2} \mathbf{H} \times (\mathbf{D}_{X} - \mathbf{D}_{Y}) \times \mathbf{H}$$

Metric Multi Dimensionality Scaling (2)

Minimizing the averaged pairwise distances

$$\Delta_{APD} = \sum_{i,j=1}^{n} (\|X_i - X_j\|^2 - \|y_i - y_j\|^2)^2 = \|\mathbf{D}_X - \mathbf{D}_Y\|_F^2$$

is reduced to Metric Multi Dimensionality Scaling Problem: to minimize

$$\Delta_{MDS} = ||\mathbf{S}_{X} - \mathbf{S}_{Y}||_{F}^{2} = \sum_{i,j=1}^{n} ((X_{i} - \overline{X}, X_{j} - \overline{X}) - (y_{i}, y_{j}))^{2}$$

Metric Multi Dimensionality Scaling: the best preserving the inner products of data (centering original features and reduced features) in Original and Reduced feature spaces - minimizing

$$\Delta(W) = ||\mathbf{S}_{X} - \mathbf{S}_{Y}||_{F}^{2} = \sum_{i,j=1}^{n} ((X_{i} - \overline{X}, X_{j} - \overline{X}) - (y_{i}, y_{j}))^{2}$$

 $\overline{\mathbf{X}}$: p×n matrix with columns $X_1 - \overline{X}$, $X_2 - \overline{X}$, ..., $X_n - \overline{X}$

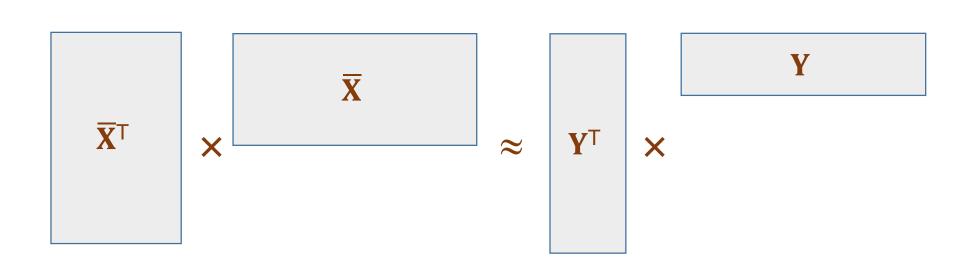
$$\rightarrow$$
 $\mathbf{S}_{\mathsf{X}} = \overline{\mathbf{X}}^{\mathsf{T}} \times \overline{\mathbf{X}}$

$$\mathbf{S}_{\mathsf{X}} = \overline{\mathbf{X}}^{\mathsf{T}} \times \overline{\mathbf{X}} \qquad \qquad \mathbf{X}$$

$$\mathbf{S}_{\mathbf{Y}} = \mathbf{Y}^{\mathsf{T}} \times \mathbf{Y}$$

$$= \mathbf{Y}^{\mathsf{T}} \times \mathbf{Y}$$

$$\|\mathbf{S}_{\mathbf{X}} - \mathbf{S}_{\mathbf{Y}}\|_{\mathrm{F}}^2 = \|\overline{\mathbf{X}}^{\mathsf{T}} \times \overline{\mathbf{X}} - \mathbf{Y}^{\mathsf{T}} \times \mathbf{Y}\|_{\mathrm{F}}^2 \rightarrow \text{min over } \mathbf{Y} = \mathbf{W} \times \overline{\mathbf{X}}$$



$$\overline{\mathbf{X}} = \mathbf{U}_{p} \times \mathbf{\Lambda}_{p} \times \mathbf{V}_{p}^{T} - SVD$$

$$\overline{\mathbf{X}}^{\mathsf{T}} \times \overline{\mathbf{X}} = (\mathbf{V}_{\mathsf{p}} \times \boldsymbol{\Lambda}_{\mathsf{p}} \times \mathbf{U}_{\mathsf{p}}^{\mathsf{T}}) \times (\mathbf{U}_{\mathsf{p}} \times \boldsymbol{\Lambda}_{\mathsf{p}} \times \mathbf{V}_{\mathsf{p}}^{\mathsf{T}}) = (\mathbf{V}_{\mathsf{p}} \times \boldsymbol{\Lambda}_{\mathsf{p}}) \times (\mathbf{U}_{\mathsf{p}}^{\mathsf{T}} \times \mathbf{U}_{\mathsf{p}}) \times (\boldsymbol{\Lambda}_{\mathsf{p}} \times \mathbf{V}_{\mathsf{p}}^{\mathsf{T}})$$

 \mathbf{U}_{p} - orthogonal matrix: $\mathbf{U}_{p}^{T} \times \mathbf{U} = \mathbf{I}_{p}$

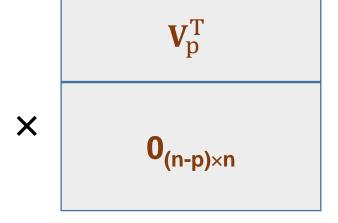
$$\overline{\mathbf{X}}^{\mathsf{T}} \times \overline{\mathbf{X}} = \mathbf{V}_{\mathsf{p}} \times \mathbf{\Lambda}_{\mathsf{p}}^2 \times \mathbf{V}_{\mathsf{p}}^{\mathsf{T}}$$

SVD for $\overline{\mathbf{X}}^{\mathsf{T}} \times \overline{\mathbf{X}}$: Rank $(\overline{\mathbf{X}}^{\mathsf{T}} \times \overline{\mathbf{X}}) \leq p$

$$\overline{\mathbf{X}}^{\mathsf{T}} \times \overline{\mathbf{X}} = (\mathbf{V}_{\mathsf{p}} \quad \mathbf{0}) \times \begin{pmatrix} \Lambda_{\mathsf{p}}^2 & 0 \\ 0 & 0 \end{pmatrix} \times \begin{pmatrix} \mathbf{V}_{\mathsf{p}}^{\mathsf{T}} \\ 0 \end{pmatrix}$$

$$\overline{\mathbf{X}}^{\mathsf{T}} \times \overline{\mathbf{X}}$$
 = \mathbf{V}_{p} $\mathbf{0}_{\mathsf{n} \times (\mathsf{n}-\mathsf{p})}$

$$\Lambda_p^2$$
 $\mathbf{0}_{\mathsf{p}\times(\mathsf{n-p})}$



$$\overline{\mathbf{X}}^{\mathsf{T}} \times \overline{\mathbf{X}} = (\mathbf{V}_{\mathsf{p}} \quad \mathbf{0}) \times \begin{pmatrix} \Lambda_{\mathsf{p}}^2 & 0 \\ 0 & 0 \end{pmatrix} \times \begin{pmatrix} \mathbf{V}_{\mathsf{p}}^{\mathsf{T}} \\ 0 \end{pmatrix}$$

The best $n \times q$ approximation:

$$\overline{\mathbf{X}}^{\mathsf{T}} \times \overline{\mathbf{X}} \approx (\mathbf{V}_{\mathsf{q}} \quad \mathbf{0}) \times \begin{pmatrix} \Lambda_{\mathsf{q}}^2 & 0 \\ 0 & 0 \end{pmatrix} \times \begin{pmatrix} \mathbf{V}_{\mathsf{q}}^{\mathsf{T}} \\ 0 \end{pmatrix} = \mathbf{V}_{\mathsf{q}} \times \Lambda_{\mathsf{q}}^2 \times \mathbf{V}_{\mathsf{q}}^{\mathsf{T}}$$

$$\overline{X}^{T} \times \overline{X} \qquad \approx \qquad V_{q} \qquad O_{n \times (n-q)} \qquad \times \qquad O_{(n-q) \times q} \qquad O_{(n-q) \times (n-q)} \qquad \times \qquad V_{q}^{T} \qquad \times \qquad O_{(n-q) \times n} \qquad \times$$

The best $n \times q$ approximation:

$$\overline{\boldsymbol{X}}^T \!\! \times \!\! \overline{\boldsymbol{X}} \approx \boldsymbol{V}_q \times \boldsymbol{\Lambda}_q^2 \times \boldsymbol{V}_q^T$$

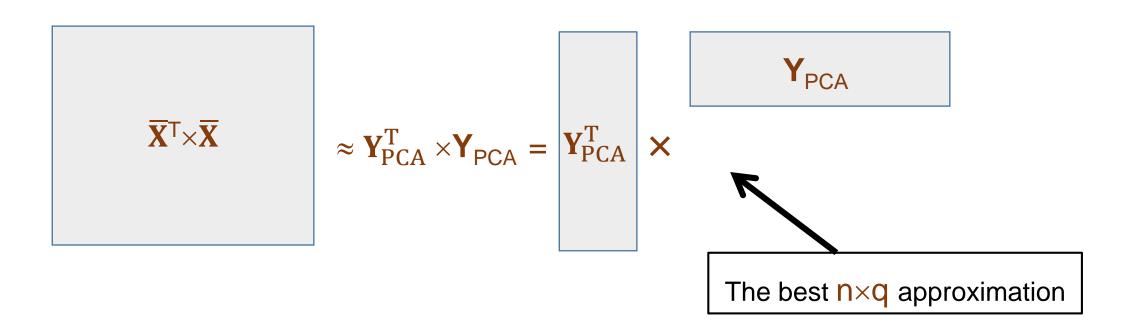
 \mathbf{V}_{q} - n×q orthogonal matrix: $\mathbf{V}_{q}^{T} \times \mathbf{V}_{q} = \mathbf{I}_{q}$

 Λ_q - $q \times q$ diagonal matrix

 \mathbf{V}_{q}^{T} - q×n matrix

$$\mathbf{Y}_{\text{PCA}} = \mathbf{\Lambda}_{\text{q}} \times \mathbf{V}_{\text{q}}^{\text{T}} = \mathbf{W}_{\text{PCA}} \times \overline{\mathbf{X}} \quad \rightarrow \quad \mathbf{V}_{\text{q}} \times \mathbf{\Lambda}_{\text{q}}^{2} \times \mathbf{V}_{\text{q}}^{\text{T}} = (\mathbf{\Lambda}_{\text{q}} \times \mathbf{V}_{\text{q}}^{\text{T}})^{\text{T}} \times (\mathbf{\Lambda}_{\text{q}} \times \mathbf{V}_{\text{q}}^{\text{T}}) = \mathbf{Y}_{\text{PCA}}^{\text{T}} \times \mathbf{Y}_{\text{PCA}}$$

$$\overline{\mathbf{X}}^{\mathsf{T}} \times \overline{\mathbf{X}}$$
 $\approx \mathbf{Y}_{\mathsf{PCA}}^{\mathsf{T}} \times \mathbf{Y}_{\mathsf{PCA}} = \mathbf{Y}_{\mathsf{PCA}}^{\mathsf{T}} \times \mathbf{X}$



$$\begin{aligned} \mathbf{Y}_{\text{MDS}} &= \text{arg min}_{\mathbf{Y}} \ \| \overline{\mathbf{X}}^{\text{T}} \times \overline{\mathbf{X}} - \mathbf{Y}^{\text{T}} \times \mathbf{Y} \|_{F}^{2} = W_{\text{PCA}} \times \overline{\mathbf{X}} \\ W_{\text{MDS}} &= W_{\text{PCA}} \times \overline{\mathbf{X}} \end{aligned} \rightarrow \begin{aligned} \mathbf{Y}_{\text{MDS}} &= W_{\text{MDS}} \times \overline{\mathbf{X}} = W_{\text{PCA}} \times \overline{\mathbf{X}} \end{aligned}$$

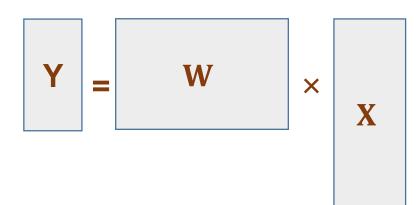
5) Maximum variance preserving:

to find low-dimensional features which:

- uncorrelated
- maximizing mutual information (Gaussian data)
- maximally preserving the dispersion (variance) in data

Probabilistic information model

- X p-dimensional Gaussian random vector with zero mean
- $\Sigma_X = Cov(X) = M(X \times X^T) p \times p$ covariance matrix



W - orthogonal q×p matrix

 $Y = W \times X - q$ -dimensional projected vector into space $Span(W^T)$ spanned by columns of W^T

Y – Gaussian,
$$MY = 0$$
, $\Sigma_Y = Cov(Y) = M(Y \times Y^T) = W \times \Sigma_X \times W^T - q \times q$ covariance matrix

$$I(X, Y) = H(Y) - H(Y|X)$$
 - mutual information between X and Y

- H(Y) entropy (measure of uncertainty) of Y,
- H(Y|X) conditional entropy of Y given X

$$I(X, Y) = I_W(X, Y)$$
: $I_W(X, Y) \rightarrow max$ over W

$$I(X, Y) = H(Y) - H(Y|X) = I_{W}(X, Y): \qquad I_{W}(X, Y) \rightarrow \text{max} \quad \text{over W}$$

W is deterministic \rightarrow H(Y|X) = 0 \rightarrow I(X, Y) = H(Y)

 $H(y) = -\int p(y) \times \log_2 p(y) dy$ – entropy of random variable Y with density p(y)

$$p(y) = ((2\pi)^q \times Det(\Sigma_Y))^{1/2} \times exp\Big\{-\frac{1}{2} exp(y^T \times \Sigma_Y^{-1} \times y)\Big\} - \text{density of } Y \sim N(0, \Sigma_Y)$$

$$H(y) = \frac{1}{2} \log_2 (e(2\pi)^q) + \frac{1}{2} \times \log_2 (Det(\Sigma_Y)) = \frac{1}{2} \log_2 (e(2\pi)^q) + \frac{1}{2} \times \log_2 (Det(W \times \Sigma_X \times W^T))$$

 $Det(W \times \Sigma_X \times W^T) \rightarrow max$ over W

$Det(W \times \Sigma_X \times W^T) \rightarrow max$ over W

The solution: $W^* = U \times E^T$

- U an arbitrary q×q orthogonal matrix, does not affect the entropy
- $p \times q$ orthogonal matrix $E = (e_1 e_2 \dots e_q)$ consists of q p-dimensional **orthogonal** eigenvectors of

 Σ corresponding to q largest eigenvalues $\lambda_1 \geq \lambda_2 \geq ... \geq \lambda_q$

$$q = 1$$
:

- e_1 a direction in which random variable $Y_e = (X, e)$ has maximal variance
- $Y_1 = (X, e_1) \text{ and } Var(Y_1) = \lambda_1$

The larger the variance has a random variable, the more information we get after obtaining its value

q>1: orthogonal directions e_1, \ldots, e_{k-1} are chosen $\to Y_1, \ldots, Y_{k-1}$

Remaining information in X – information in random vector $X_k = X - E(X \mid Y_1, \dots, Y_{k-1})$

We are looking for the best direction e which maximally preserves the remaining information:

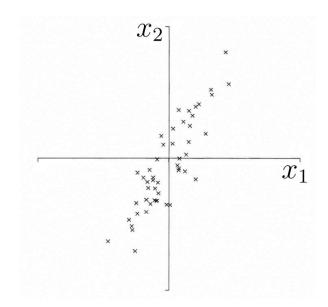
- $e \in Span(e_1, ..., e_{k-1})^{\perp}$: $e \perp e_1, ..., e_{k-1}$
- e_k the best remaining direction

Statistical analysis

- X p-dimensional random vector
- $Cov(X) = M(X MX) \times (X MX)^T p \times p$ covariance matrix
- $\{X_1, X_2, ..., X_n\}$ i.i.d. (sample)
- \overline{X} sample mean (estimator of MX)
- $\Sigma = \frac{1}{n} \sum_{i=1}^{n} (X_i \overline{X}) \times (X_i \overline{X})^T$ sample covariance matrix estimator of Cov(X)

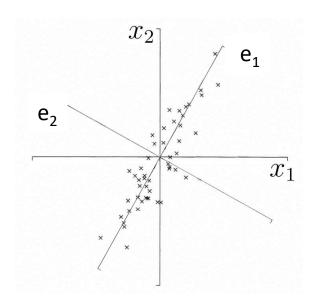
An applying the above technique to the sample covariance matrix results:

decorrelation and ordering by variance



$$X = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

consists of correlated components

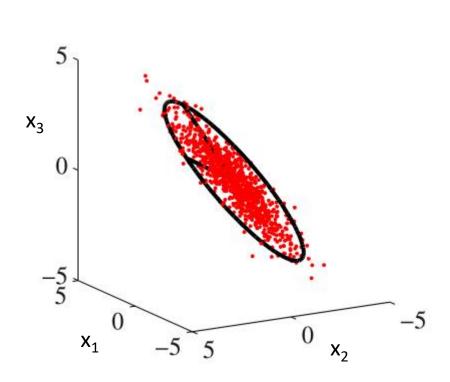


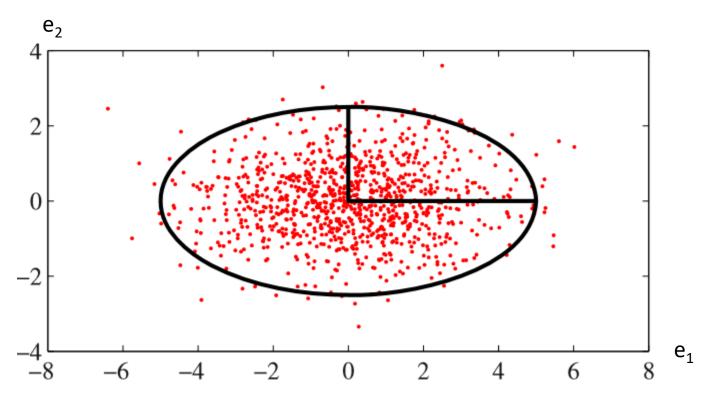
$$Y = \begin{pmatrix} y_1 = (X, e_1) \\ y_2 = (X, e_2) \end{pmatrix}$$

consists of uncorrelated components

$$Var(Y_1) = \lambda_1 > Var(Y_2) = \lambda_2$$

Maximum variance preserving with decorrelation





Variance in original vectors:

$$\frac{1}{n}\sum_{i=1}^{n}||X_i - \overline{X}||^2 = \sum_{k=1}^{p}\lambda_k$$

Variance in reduced vectors:

$$\frac{1}{n}\sum_{i=1}^{n}||Y_i||^2 = \sum_{k=1}^{q}\lambda_k$$

Machine Learning

• X - p-dimensional original feature vector, $\{X_1, X_2, \dots, X_n\}$ – training dataset

$$\mathsf{E}_{\mathsf{p}} = (\mathsf{e}_{\mathsf{1}} \ \ldots \ \mathsf{e}_{\mathsf{p}}) - \mathsf{q} \times \mathsf{p} \ \mathsf{matrix}, \ \mathsf{Y}_{\mathsf{p}} = \mathsf{E}_{\mathsf{p}}^{\mathsf{T}} \times (\mathsf{X} - \overline{\mathsf{X}}) = \begin{pmatrix} \mathsf{y}_{\mathsf{1}} \\ \ldots \\ \mathsf{y}_{\mathsf{p}} \end{pmatrix} \in \mathsf{R}^{\mathsf{p}} \text{- transformed feature vector}$$

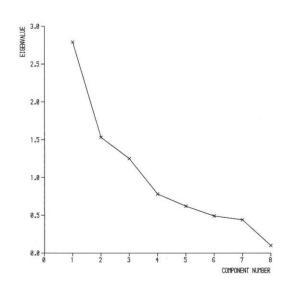
consists of 'the same' original features but written in other coordinate system with 'variance ordering'

Let dispersion in p-th transformed components $\frac{1}{n}\sum_{i=1}^{n}\left|y_{p,i}\right|^2=\lambda_p\approx 0$ is small:

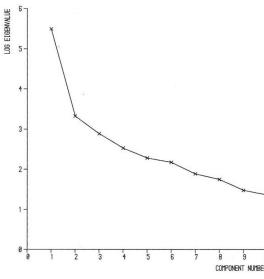
- all {y_{p,i}} have 'the same values' (zeros)
- all examples {X_i} are obtained under the same value of p-th transformed feature
- impossible to discover 'an influence' of the p-th transformed feature on any Variable of interest
- the p-th transformed feature is useless, 'non-informative' and can be removed

PCA transforms the original possibly correlated features to uncorrelated 'variance ordered' transformed features and removes the non-informative transformed features (with small variance)

How many transformed features should be left



Typical examples



Blood chemistry data

Gas chromatography data

Typical 'rules of thumb':

• to retain enough eigenvalues (q(P), say) to explain at least the fraction of P of dispersion in the data

$$q(P) = minimal q: \frac{\sum_{k=1}^{q} \lambda_k}{\sum_{k=1}^{p} \lambda_k} \ge P$$

$$P \sim 0.9; 0;95$$

• based on quantities $\left\{\frac{\lambda_q}{\sum_{k=q+1}^p \lambda_k}\right\}$, $\{\lambda_q - \lambda_{q+1}\}$, etc.

Training Face dataset



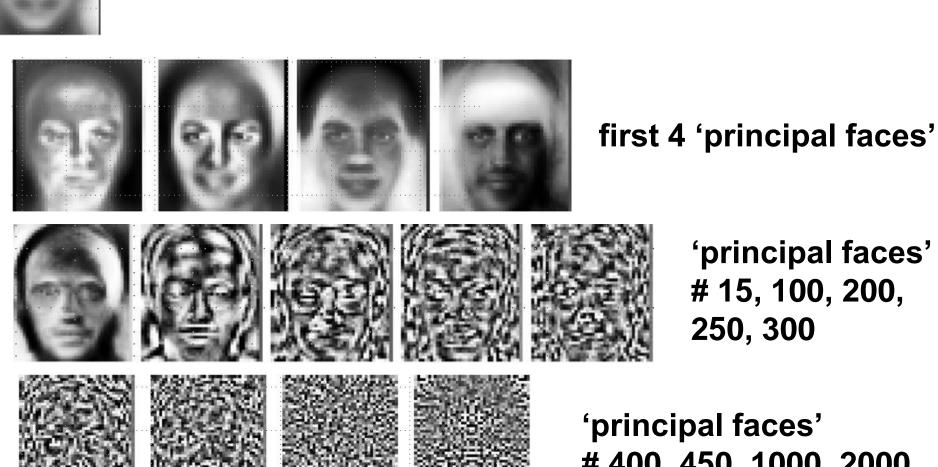
Each face has dimension p = 2061

PCA applying to the Training face dataset

'Mean' face



"Principal faces" (eigenfaces)



400, 450, 1000, 2000



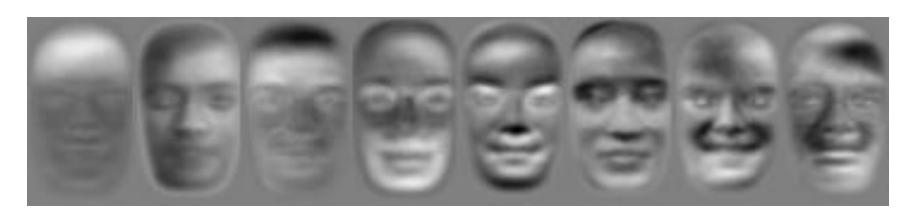


Keep only the first 8 principal components (eigenvectors)

Recovered face: X^* = mean face + $z_1 \times \mathbf{e}_1 + z_2 \times \mathbf{e}_2 + ... + z_8 \times \mathbf{e}_8$

- linear combination of 8 first principal faces $\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_8\}$
- projection onto 8-dimensional space in R^{2061} spanned by $\{\mathbf{e}_1, \mathbf{e}_2, \dots \mathbf{e}_8\}$ $(z_1, z_2, ..., z_8)$ - 8-dimensional reduced feature vector





$$y_1 \times \mathbf{e}_1 \quad y_2 \times \mathbf{e}_2$$

$$y_3 \times \mathbf{e}$$

$$y_4 \times \mathbf{e}_4$$

$$y_3 \times \mathbf{e}_3$$
 $y_4 \times \mathbf{e}_4$ $y_5 \times \mathbf{e}_6$ $y_6 \times \mathbf{e}_7$

$$y_6 \times \mathbf{e}_7$$

$$y_7 \times \mathbf{e}_7$$

$$y_8 \times \mathbf{e}_8$$