

AP Calculus AB: Notes, Formulas, Examples

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Formatting may vary and be of differ in quality

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1 Limits and Continuity

The limit is when a given value approaches, or gets *really close* (infinitely) to another value. The standard limit notation is:

$$\lim_{x \rightarrow c} f(x)$$

represents when x can approach c from either left ($-$) or the right ($+$). By adding a sign superscript to the c , it means that x can only approach from that direction:

$$\lim_{x \rightarrow c^+} f(x)$$

Right hand limit, x approaches c from values greater than c

$$\lim_{x \rightarrow c^-} f(x)$$

Left hand limit, x approaches c from values lower than c

1.1 Limits to Infinity

If the degree (biggest exponent) of a polynomial is greater than or equal to 1, its limit as x approaches $\pm\infty$ will also be $\pm\infty$. This depends on the sign of the leading coefficient and the degree of polynomial

Example:

$$f(x) = 3x^3 - 7x^2 + 2$$

$$\lim_{x \rightarrow \infty} f(x) = \infty$$

$$\lim_{x \rightarrow -\infty} f(x) = -\infty$$

The degree of $f(x)$ is 3, and the leading coefficient is positive. The graph goes down to up from left to right.

With Fractions, just find whether the highest degree is the numerator or the denominator. Numerator means ∞ , denominator means 0

1.2 Asymptotes

Functions can have asymptotes, either vertical or horizontal. In the case of vertical asymptotes, the limit would be *unbounded* as it approaches that x value.

Example:

$$f(x) = \frac{2x - 4}{x - 3}$$

$$\lim_{x \rightarrow 3} f(x) = \text{undef}$$

$$\lim_{x \rightarrow 3^-} f(x) = -\infty$$

$$\lim_{x \rightarrow 3^+} f(x) = \infty$$

As with vertical asymptotes, as x approaches c (in this case $\pm\infty$), the limit would approach the horizontal asymptote. Although the y -value never actually touches the asymptote, the limit gets really close to the value, from both below and above

1.3 Limit Properties

The limits of combined functions can be found by finding the limit of each of the individual functions, then applying the operations.

- **Addition/Substraction**

When taking the limit of the sum or difference of multiple functions, it's the same thing as taking the sum or difference of each of the separate limits of each function

$$\lim_{x \rightarrow c} [f(x) + g(x)] \implies \lim_{x \rightarrow c} f(x) + \lim_{x \rightarrow c} g(x)$$

$$\lim_{x \rightarrow c} [f(x) - g(x)] \implies \lim_{x \rightarrow c} f(x) - \lim_{x \rightarrow c} g(x)$$

Note that when the limit of either function is *undefined* the combined limit would also be undefined

- **Multiplication**

Multiplication of the limits of functions is quite straightforward

$$\lim_{x \rightarrow c} [f(x) \cdot g(x)] \implies \lim_{x \rightarrow c} f(x) \cdot \lim_{x \rightarrow c} g(x)$$

The same exception applies when one of the limits is *undefined*. This just makes the entire combined limit undefined

- **Division**

Division is basically the same as the other basic operations except if the denominator is 0

$$\lim_{x \rightarrow c} \frac{f(x)}{g(x)} \implies \frac{\lim_{x \rightarrow c} f(x)}{\lim_{x \rightarrow c} g(x)}$$

- **Composite Functions**

When working with composite functions, it's the same thing as taking the limit of the inner function, then evaluating the outer function normally

$$\lim_{x \rightarrow c} f(g(x)) \implies f\left(\lim_{x \rightarrow c} g(x)\right)$$

- **Other Theorems**

Given that $\lim f(x)$ and $\lim g(x)$ are both finite for all numbers, and C is a "constant"

$$\lim kf(x) = k \lim f(x)$$

$$\lim_{x \rightarrow a} C = C$$

1.4 Solving Limits

The first thing to always try to do when solving limits is **direct substitution**. If this is not possible (undefined limit), then algebraic manipulation (factoring) is the next step

$$\begin{aligned} \lim_{x \rightarrow c} \frac{x^4 + 3x^3 - 10x^2}{x^2 - 2x} \\ &= \lim_{x \rightarrow c} \frac{x^2(x^2 + 3x - 10)}{x(x - 2)} \\ &= \lim_{x \rightarrow c} \frac{x^2(x + 5)(x - 2)}{x(x - 2)} \\ &= \lim_{x \rightarrow c} x^2(x + 5) \end{aligned}$$

When encountering radicals, conjugates can be used.

$$\begin{aligned}\lim_{x \rightarrow c} \frac{x+4}{\sqrt{3x+13}-1} \\&= \lim_{x \rightarrow c} \frac{x+4}{\sqrt{3x+13}-1} \cdot \frac{\sqrt{3x+13}+1}{\sqrt{3x+13}+1} \\&= \lim_{x \rightarrow c} \frac{(x+4)(\sqrt{3x+13}+1)}{3x+12} \\&= \lim_{x \rightarrow c} \frac{(x+4)(\sqrt{3x+13}+1)}{3(x+4)} \\&= \lim_{x \rightarrow c} \frac{\sqrt{3x+13}+1}{3}\end{aligned}$$

When dealing with trigonometric equations, trig identities can be used (assuming direct substitution doesn't work)

$$\begin{aligned}\lim_{x \rightarrow c} \frac{\cot^2(x)}{1 - \sin(x)} \\&= \lim_{x \rightarrow c} \frac{\cos^2(x)}{(\sin^2(x))(1 - \sin(x))} \\&= \lim_{x \rightarrow c} \frac{1 - \sin^2(x)}{(\sin^2(x))(1 - \sin(x))} \\&= \lim_{x \rightarrow c} \frac{(1 + \sin(x))(1 - \sin(x))}{(\sin^2(x))(1 - \sin(x))} \\&= \lim_{x \rightarrow c} \frac{1 + \sin(x)}{\sin^2(x)}, \text{ for } x \neq (2k+1)\frac{\pi}{2}\end{aligned}$$

However, functions can not always be factored, so in that case they will just be undefined

$$\begin{aligned}
 & \lim_{x \rightarrow 1} \frac{2x}{x^2 - 7x + 6} \\
 &= \lim_{x \rightarrow 1} \frac{2x}{(x-6)(x-1)} \\
 &= \frac{2}{0} \\
 &= \text{undef}
 \end{aligned}$$

1.5 Continuity

A function is continuous at a point if its right and left hand side limit at that point are the same. In other words, it can be drawn without lifting the pencil.

$$\lim_{x \rightarrow c^-} f(x) = \lim_{x \rightarrow c^+} f(x) = f(c)$$

For a function f to be continuous for all \mathbb{R} it has to return a real number result for all real number values of x . Basically $f : \mathbb{R} \rightarrow \mathbb{R}$

- $\sqrt{x+4}$ is continuous $\forall x : x \geq -4$
- $\sqrt[5]{x}$ is continuous $\forall x : x \in \mathbb{R}$
- $\ln x$ is continuous $\forall x : x > 0$
- $\frac{1}{x-3}$ is continuous $\forall x : x \neq 3$

Removable discontinuity is function, where a point is “removed”, and the graph of the new function is almost identical to the original function

Given:

$$\lim_{x \rightarrow c} f(x) = k \leq \infty$$

where:

$$F(x) = \begin{cases} f(x) & \text{if } x \neq c \\ k & \text{if } x = c \end{cases}$$

then $F(x)$ has a removable discontinuity at k

Jump discontinuity is when the graph jumps from one y value to another at the same x -value.

Infinite discontinuity Usually occurs when there is a vertical asymptote, and the discontinuity occurs over asymptote. Basically, both sides of the asymptote approach that x -value, but never actually touch, so the function is not continuous.

1.6 Squeeze Theorem

When it is to find the limit for a function, the squeeze theorem can be used. Basically, you find two other functions, one on top and on below, and use their limits to “squeeze” the limit of the given function.

Given:

$$g(x) \leq f(x) \leq h(x)$$

for all x in an open interval that includes c , and

$$\lim_{x \rightarrow c} f(x) = \lim_{x \rightarrow c} h(x) = L$$

then,

$$\lim_{x \rightarrow c} g(x) = L$$

Note that x and L can both be $\pm\infty$

Example:

Problem: $\lim_{x \rightarrow \infty} \frac{\sin x}{x}$

keep in mind that $-1 \leq \sin x \leq 1$

divide by x $\frac{-1}{x} \leq \frac{\sin x}{x} \leq \frac{1}{x}$

take limits of smaller functions $\lim_{x \rightarrow \infty} \frac{-1}{x} = 0 = \lim_{x \rightarrow \infty} \frac{1}{x}$

Squeeze Theorem: $\lim_{x \rightarrow \infty} \frac{\sin x}{x} = 0.$

The best way to solve the above problem is to recognize the easier part of the problem, in this case $\sin x$, then manipulate the inequality in such a way that the middle function becomes the original problem. Solve the limits of the other two functions to solve the original limit

1.7 Intermediate Value Theorem (IVT)

Given a function f where $f \in C[a, b]$ and $c \in [a, b]$. Then there must a value c such that $f(a) \leq f(c) \leq f(b)$. In other words, if a function is continuous from $a \rightarrow b$, then it must take on every value between $f(a)$ and $f(b)$ for all values of x such that $x \in [a, b]$

2 Differentiation: Definition and Fundamental

A derivative is the **instantaneous** rate of change of a function at a point. It's the average rate of change over an infinitely small interval. It has two main notations.

- **Lagrange's Notation:** The derivative of $f(x)$ is denoted as $f'(x)$, pronounced as "f prime of x". Higher order derivatives are denoted as $f''(x)$ or $f^2(x)$, etc. In general it's written as $f^n(x)$, or with the n in ticks.
- **Leibniz's Notation:** The derivative of $f(x)$ is denoted as $\frac{dy}{dx}$, pronounced as "dee y over dee x". Higher order derivatives are denoted as $\frac{d^2y}{dx^2}$, etc. In general it's written as $\frac{d^ny}{dx^n}$.

2.1 Continuity and Differentiability

Differentiability: A function is differentiable for every value in its domain

Continuity: The function has no breaks over its domain, can be drawn without lifting the pencil

Differentiability *implies* continuity, but not the other way around

2.2 Derivative as a Limit

The derivative of a function $f(x)$ at a point $x = a$ is quite truly just first principles, it is as follows:

$$\frac{d}{dx}f(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$
$$\frac{d}{dx}f(a) = \lim_{x \rightarrow a} \frac{f(x) - f(a)}{h}$$

2.3 Differentiation Rules

2.3.1 Derivative of a Constant

The derivative of a constant is always 0. This is because the slope of a constant function is always 0

$$f(x) = C$$

$$f'(x) = C' = 0$$

2.3.2 Constant in a function

The constant can be moved out in front of the derivative

$$(kf(x))' = kf'(x)$$

2.3.3 Sum Rule

The derivative of the sum of many functions is the same as the sum of the derivatives of the individual functions. The same applies for subtraction

$$\sum_{k=1}^n \left[f_n(x) \right] = \left[\sum_{k=1}^n \left[f_n(x) \right] \right]'$$

2.3.4 Power Rule

You put the exponent in front of the function as constant and then subtract 1 from the exponent. This also applies to negative or fractional exponents (radicals)

$$f(x) = x^n : n \in \mathbb{R}$$

$$f'(x) = nx^{n-1}$$

2.3.5 Product Rule

$$\left[f(x) \cdot g(x) \right]' = f'(x)g(x) + f(x)g'(x)$$

2.3.6 Quotient Rule

$$\left[\frac{f(x)}{g(x)} \right]' = \frac{f'(x)g(x) - f(x)g'(x)}{g^2(x)}$$

2.3.7 Chain Rule

The chain rule allows for the differentiation of a *composition* of two or more function. Take the derivative of the inner function, then multiply that by the derivative of the outer function.

$$\frac{d}{dx} \left[f(g(x)) \right] = f'(g(x)) \cdot g'(x)$$

2.4 Exponential Functions

Can be solved like the **chain rule**, with the base and exponent as the outer and inner functions, respectively. The formula is:

$$\frac{d}{dx}(a^x) = a^x \cdot \ln a$$

The only exception is e^x

$$\frac{d}{dx}(e^x) = e^x$$

2.5 Logarithmic Functions

The derivative of $\ln x$ is:

$$\frac{d}{dx}(\ln x) = \frac{1}{x}$$

This can be used to derive the derivative of other base log functions

$$\begin{aligned}\frac{d}{dx}(\log_a x) &= \frac{d}{dx}\left(\frac{\ln x}{\ln a}\right) \\ &= \frac{a}{\ln a} \cdot \frac{d}{dx}(\ln x) \\ &= \frac{1}{\ln a} \cdot \frac{1}{x} \\ &= \frac{1}{x \ln a}\end{aligned}$$

2.6 Trigonometric Functions

There isn't really an easy way to memorize these, just do enough problems and you'll get the hang of it.

Although, do note that all of the functions other than sin and cos can be derived using the quotient of chain Rules

$f(x)$	$f'(x)$
$\sin x$	$\cos x$
$\cos x$	$-\sin x$
$\tan x$	$\sec^2 x$
$\cot x$	$-\csc^2 x$
$\sec x$	$\sec x \cdot \tan x$
$\csc x$	$-\csc x \cdot \cot x$

2.7 Inverse Functions

The derivative of an inverse function is the reciprocal of the derivative of the original with its input being the inverse

$$\frac{d}{dx}f^{-1}(x) = \frac{1}{f'(f^{-1}(x))}$$

3 Differentiation: Composite, Implicit, and Inverse Functions

3.1 Implicit Differentiation

Implicit differentiation is taking the derivative of both sides of an equation with respect to two variables, usually x and y , by treating one of the variables as a function of the other. (Usually y is a function of x)

Example:

$$x^2 + y^2 = 1$$

$$\frac{d}{dx}(x^2 + y^2) = \frac{d}{dx}$$

$$\frac{d}{dx}(x^2) + \frac{d}{dx}(y^2) = 0$$

$$2x + 2y \cdot \frac{dy}{dx} = 0$$

$$x + y \cdot \frac{dy}{dx} = 0$$

$$\frac{dy}{dx} = -\frac{x}{y}$$

When taking the derivative of y^2 , multiply by $\frac{dy}{dx}$ because the equation is being taken as a function of x

3.2 Inverse Trigonometric Functions

These equations can be found using implicit differentiation along with trig identities.

A more in-depth explanation is provided for each under the table

$f(x)$	$f'(x)$
$\arcsin x$	$\frac{1}{\sqrt{1-x^2}}$
$\arccos x$	$-\frac{1}{\sqrt{1-x^2}}$
$\arctan x$	$\frac{1}{1+x^2}$
$\operatorname{arcsec} x$	$\frac{1}{ x \sqrt{x^2-1}}$
$\operatorname{arccsc} x$	$-\frac{1}{ x \sqrt{x^2-1}}$
$\operatorname{arccot} x$	$-\frac{1}{1+x^2}$

- $\arcsin x$

$$y = \arcsin x \implies x = \sin y$$

$$\frac{d}{dx}(\sin y) = \frac{d}{dx}x$$

$$\frac{dy}{dx}(\cos y) = 1$$

$$\frac{dy}{dx} = \frac{1}{\cos y}$$

$$\frac{dy}{dx} = \frac{1}{\sqrt{1 - \sin^2 y}}$$

$$\frac{dy}{dx} = \frac{1}{\sqrt{1 - x^2}}$$

- $\arccos x$

$$y = \arccos x \implies x = \cos y$$

$$\frac{d}{dx}(\cos y) = \frac{d}{dx}x$$

$$\frac{dy}{dx}(-\sin y) = 1$$

$$\frac{dy}{dx} = \frac{-1}{\sin y}$$

$$\frac{dy}{dx} = \frac{-1}{\sqrt{1 - \cos^2 y}}$$

- $\arctan x$

$$y = \arctan x \implies x = \tan y$$

$$\frac{d}{dx}(\tan y) = \frac{d}{dx}x$$

$$\frac{dy}{dx}(\sec^2 y) = 1$$

$$\frac{dy}{dx} = \frac{1}{\sec^2 y}$$

$$\frac{dy}{dx} = \frac{1}{1 + \tan^2 y}$$

$$\frac{dy}{dx} = \frac{1}{1 + x^2}$$

3.3 Higher Order Derivatives

To find higher order derivatives, take the derivative of the previous order derivative.

$$\frac{d^n}{dx^n} = \frac{d}{dx} \left(\frac{d^{n-1}}{dx^{n-1}} f(x) \right)$$

4 Contextual Applications of Differentiation

4.1 Straight Line Motion: Position, Velocity, and Acceleration

Position: where something is at a given time t

Velocity: how fast something is moving at a given time t . Determines the direction of the object

$$v(t) \begin{cases} < 0 \implies \text{Left} \\ = 0 \implies \text{Stopped} \\ > 0 \implies \text{Right} \end{cases}$$

Acceleration: Determines whether the velocity is increasing at a given time t . If it's sign is the same as that of the velocity, the object is speeding up. If the two signs are different, the object is slowing down. If the acceleration is 0, the object is moving at a constant speed.

Position, velocity, and acceleration are all related as follows

$$x'(t) = v(t)$$

$$v'(t) = a(t)$$

4.2 Related Rates

Related rates is using implicit differentiation and given variables to solve for unknown variables

Examples:

1. Given the equation $\frac{x}{y} = 9$ and, $\frac{dy}{dt} = -\frac{2}{3}$, find $\frac{dx}{dt}$ when $x = 3$

Solution:

First, differentiate $\frac{x}{y} = 9$ with respect to t

$$\frac{x}{y} = 9$$

$$\frac{y \cdot \frac{dx}{dt} - x \cdot \frac{dy}{dt}}{y^2} = 0$$

To solve for $\frac{dx}{dt}$, we first have to solve for y

$$\frac{x}{y} = 9$$

$$\frac{3}{y} = 9$$

$$3 = 9y$$

$$y = \frac{1}{3}$$

Finally, plug in all the variables to solve for $\frac{dx}{dt}$

$$\frac{y \cdot \frac{dx}{dt} - x \cdot \frac{dy}{dt}}{y^2} = 0$$

$$\frac{\frac{1}{3} \cdot \frac{dx}{dt} - 3 \cdot -\frac{2}{3}}{\frac{1}{3^2}} = 0$$

$$\frac{\frac{1}{3} \cdot \frac{dx}{dt} + 2}{\frac{1}{3}} = 0$$

$$\frac{1}{3} \cdot \frac{dx}{dt} + 2 = 0$$

$$\frac{dx}{dt} = -6$$

2. The surface area of a sphere is increasing at a rate of 14π square meters per hour. At a certain instant, the surface area is 36π square meters. **What is the rate of the volume of the sphere at that instant (in cubic meters per hours)?**

Solution:

The surface area (A) of a sphere with radius r is $4\pi r^2$. The volume (V) of a sphere with radius r is $\frac{4}{3}\pi r^3$. First, identify what was given:

- $\frac{dA}{dt} = 14\pi$
- $A = 36\pi = 4\pi r^2$
- $V = \frac{4}{3}\pi r^3$

Next, what is unknown:

- $r = ?$
- $\frac{dV}{dt} = ?$

Secondly, solve for r

$$A = 4\pi r^2$$

$$36\pi = 4\pi r^2$$

$$\frac{36\pi}{4\pi} = r^2$$

$$\sqrt{9} = r$$

$$r = 3$$

Then, solve for $\frac{dV}{dt}$

$$A = 4\pi r^2$$

$$\frac{dA}{dt} = 8\pi r \cdot \frac{dr}{dt}$$

$$14\pi = 8\pi \cdot 3 \cdot \frac{dr}{dt}$$

$$\frac{14\pi}{3 \cdot 8\pi} = \frac{dr}{dt}$$

$$\frac{7}{12} = \frac{dr}{dt}$$

Lastly, solve for $\frac{dV}{dt}$ using the above info

$$V = \frac{4}{3}\pi r^3$$

$$\frac{dV}{dt} = 4\pi r^2 \cdot \frac{dr}{dt}$$

$$\frac{dV}{dt} = 4\pi \cdot 3^2 \cdot \frac{7}{12}$$

$$\frac{dV}{dt} = 21\pi$$

4.3 Local Linearity and Approximation

Local linearity is the idea that if we zoom in really close to a point on a graph that is differentiable at all points in its domain, it would eventually be a straight line, a *tangent line*.

The general formula for the tangent line at a point $x = a$ is:

$$y = u'(a)(x - a) + u(a)$$

4.4 L'Hopitals Rule

L'Hopitals Rule states that:

IF

$$\lim_{x \rightarrow c} \frac{f(x)}{g(x)} = \frac{0}{0} \quad \text{OR} \quad \lim_{x \rightarrow c} \frac{f(x)}{g(x)} = \frac{\pm\infty}{\pm\infty}$$

THEN

$$\lim_{x \rightarrow c} \frac{f(x)}{g(x)} = \lim_{x \rightarrow c} \frac{f'(x)}{g'(x)}$$

5 Analytical Applications of Differentiation

5.1 Mean Value Theorem

The mean value theorem states that if a function is continuous on a closed interval $[a, b]$ and differentiable on the open interval (a, b) , then there is at least one point c in the open interval such that:

$$f'(c) = \frac{f(b) - f(a)}{b - a}$$

Extra Cool Stuff (Notation)

They written above is the correct way taught in the AP curriculum, but you can also shorten it as follows:

The mean value theorems states that $f \in C[a, b] \cap C^1(a, b) \rightarrow \exists c \in (a, b)$ such that:

$$f'(c) = \frac{f(b) - f(a)}{b - a}$$

Warning: *Although this may seem cool, I would not recommend it as it is confusing and VERY easy to mess up, stick with the normal notation*

5.2 Extreme Value Theorem

The extreme value theorem states that if a function is continuous over a closed interval $[a, b]$, then it has both a maximum and minimum value on that interval. There must also exist c and d in $[a, b]$ such that:

$$f(c) \leq f(x) \leq f(d) \quad \forall x \in [a, b]$$

6 Intergration and Accumulation of Change

The accumulation of change is the net change of a quantity. This is not the same thing as simply the quantity. The accumulation of change takes into consideration time, and it is the quantity over a specified time period. There may be some quantity before or after this time period, but we would not count that.

6.1 Riemann Sums

A Riemann sum is a way to approximate the area under a curve. It splits up the area into several rectangles, where the heights match the function. The sum of the area provides a decent approximation of the area under the curve.

6.1.1 Type of Riemann Sums

- **Left Riemann Sums** line up the left side of the rectangle with the curve of the function
- **Right Riemann Sums** line up the right side of the rectangle with the curve of the function
- **Midpoint Riemann Sums** line up the midpoint of the rectangle with the curve of the function
- **Trapezoidal Riemann Sums** line up the trapezoids with the curve of the function

With each type of sum, the more rectangles used, the more accurate the approximation. This can be achieved by making Δx , the base of the rectangle, smaller and smaller.

6.1.2 Riemann Sums in Summation Notation

Given any Riemann sum over an interval $[a, b]$ with n rectangles of *equal width*, the sum can be written as, Δx can be defined as $\frac{b-a}{n}$. The bottom right corner of each rectangle will be x_i , so $x_i = a + \Delta \cdot i$

Left	Right
$\sum_{i=0}^{n-1} \Delta x \cdot f(x_i)$	$\sum_{i=1}^n \Delta x \cdot f(x_i)$

6.2 Definite Integrals

As Δx gets smaller and smaller in the Riemann Sums, it is possible to get better approximations of the area under a curve. However, it is impossible to calculate the

exact area under a curve using a finite number of rectangles. In order to do so, an infinitely small Δx would be needed. Definite integrals can find the *exact* area of an interval under a curve.

The definite integral notation over $[a, b]$ of $f(x)$ is:

$$\int_a^b f(x)dx$$

The connection between definite integrals and Riemann Sums is as follows:

$$\int_a^b f(x)dx = \lim_{n \rightarrow \infty} \sum_{i=1}^n \Delta x \cdot f(x_i)$$

where $\Delta x = \frac{b-a}{n}$ and $x_i = a + \Delta x \cdot i$

6.2.1 Properties of Definite Integrals

The properties of definite integrals are relatively similar to those of derivatives, although, I would be careful when doing them to not mix them up. They are as follows:

1.

$$\int_a^a f(x)dx = 0$$

2.

$$\int_a^b f(x)dx = - \int_b^a f(x)dx$$

3.

$$\int_a^b k f(x)dx = k \int_a^b f(x)dx$$

4.

$$\int_a^b [f(x) \pm g(x)] = \int_a^b f(x)dx \pm \int_a^b g(x)dx$$

5.

$$\int_a^b f(x)dx = \int_a^c f(x)dx + \int_c^b f(x)dx$$

6.3 The Fundamental Theorem of Calculus

The fundamental theorem of calculus states:

Let f be a continuous function over $[a, b]$, and let:

$$F(x) = \int_a^x f(t)dt$$

F is the antiderivative of f , or in other words, the derivative of F is f . This can explain how to solve for the area under a curve using antidifferentiation.

$$\int_a^b f(x)dx = F(b) - F(a)$$

Note: The notation is the same as the one above and is commonly used

$$\int_a^b f(x)dx = F(x)|_a^b$$

6.4 Indefinite Integrals and Integration Techniques

Indefinite integrals, compared to their definite counterparts, have no bounds and the symbol \int is used to find the antiderivative of a function.

When differentiating, all constants are lost and so there are an infinite possibility of constants in the antiderivative. To account for this, a $+C$ is added.

$$F(x) + C = \int f(x)dx$$

The above is true where $F(x) = f'(x)$

6.4.1 Reverse Power Rule

$$\begin{aligned}\int x^n dx &= \frac{x^{n+1}}{n+1} + C \\ \int \sqrt[n]{x^n} dx &= \int x^{\frac{n}{n}} dx \\ &= \frac{x^{\frac{n}{n}+1}}{\frac{n}{n}+1} + C\end{aligned}$$

This would also apply to the antiderivative of a constant

$$\begin{aligned}\int A dx &= \int Ax^0 dx \\ &= \frac{Ax^1}{1} + C \\ &= Ax + C\end{aligned}$$

6.4.2 Reverse Power Rule Exception

$$\int \frac{1}{x} dx = \ln|x| + C$$

6.4.3 Exponential Functions

$$\int e^x dx = e^x + C$$

$$\int a^x dx = \frac{a^x}{\ln a}$$

6.4.4 Trigonometric Functions

$$\int \sin x dx = -\cos x + C$$

$$\int \cos x dx = \sin x + C$$

$$\int \sec^2 x dx = \tan x + C$$

$$\int \csc^2 x dx = -\cot x + C$$

$$\int \sec x \tan x dx = \sec x + C$$

$$\int \csc x \cot x dx = -\csc x + C$$

Those above are the basic cases, in class (if with Mrs. Cooper, which you probably are if you're getting these notes lmao) you should get the following trig derivatives, I've written them out to save paper and time

$$\frac{d}{dx}(\sec x) = \sec x \tan x$$

$$\frac{d}{dx}(\cot x) = -\csc^2 x$$

$$\frac{d}{dx}(\csc x) = -\csc x \cot x$$

$$\frac{d}{dx}(\arctan x) = \frac{1}{1+x^2}$$

$$\frac{d}{dx}(\arcsin x) = \frac{1}{\sqrt{1-x^2}}$$

$$\frac{d}{dx}(\arccos x) = \frac{-1}{\sqrt{1-x^2}}$$

$$\frac{d}{dx}(\operatorname{arccot} x) = \frac{-1}{1+x^2}$$

$$\frac{d}{dx}(\operatorname{arccsc} x) = \frac{-1}{|x|\sqrt{x^2-1}}$$

$$\frac{d}{dx}(\operatorname{arcsec} x) = \frac{1}{|x|\sqrt{x^2-1}}$$

6.5 Special Case Trigonometric Functions

These integrals look really messy, but they may show up on AP exams so it's useful to recognize these patterns to avoid unnecessary extra work

$$\begin{aligned}\int \frac{1}{\sqrt{a^2 - x^2}} dx &= \arcsin\left(\frac{x}{a}\right) + C \\ \int \frac{1}{\sqrt{a^2 - (bx)^2}} dx &= \frac{1}{a} \arctan\left(\frac{bx}{a}\right) + C \\ \int \frac{1}{a^2 + x^2} dx &= \frac{1}{a} \arctan\left(\frac{x}{a}\right) + C \\ \int \frac{1}{a^2 + (bx)^2} dx &= \frac{1}{ba} \arctan\left(\frac{bx}{a}\right)\end{aligned}$$

6.5.1 u-Substitution

Integration using u-substitution is a very versatile method and is often referred to as a reverse chain rule. It can be used when one part of a function is the derivative of another. Below are some Examples

Find the indefinite integral:

$$\int 2x \cos(x^2) dx$$

Notice that:

$$\frac{d}{dx} x^2 = 2x$$

We can apply u-substitution. Let $u = x^2$, then implicitly differentiate

$$u = x^2$$

$$\frac{d}{dx}u = \frac{d}{dx}x^2$$

$$\frac{du}{dx} = 2x$$

$$du = 2x dx$$

Return to the original function, make sure du is offset so that it equals dx . To do that, multiply by the reciprocal of du

$$\int 2x \cos(x^2) dx = \int 2x \cos(u) \cdot \frac{1}{2x} du$$

$$= \int \cos(u) du$$

$$= \sin(u) + C$$

$$= \sin(x^2) + C$$

6.5.2 Integration by Parts - NOT EVALUATED

Integration by parts can be used to find the antiderivative of the product of functions. It can also be referred to as the reverse power rule, as it can be derived from rearranging the product rule.

$$\int f(x)g'(x)dx = f(x)g(x) - \int f'(x)g(x)dx$$

For integration by parts to be most useful, $f(x)$ should be a function that is easy to take the derivative of, and $g(x)$ should be a function that is easy to take the antiderivative of.

7 Differential Equations

Differential equations involve functions and their derivatives. Unlike algebraic equations who evaluate to numbers or values, differential equations evaluate to a function or class (several) functions

7.1 Modelling Differential Equations

When interpreting words to turn into differential equations, there are a few key-words that should be looked for

- **Proportional** Means that the rate of change is equal to some constant k multiplied by what the rate of change is proportional

$$\frac{dy}{dx} = ak$$

- **Inversely Proportional** Means that the rate of change is equal to some constant k divided by what the rate of change is inversely proportional to

$$\frac{dy}{dx} = \frac{k}{a}$$

- **Shrinks, decays, melts, decreases, etc:** any word that suggests something is getting smaller, the rate of change is equal to some constant k multiplied by what the rate of change is proportional to, but negative

$$\frac{dQ}{dt} = -kQ$$

- **Fraction of ...:** usually means that the rate of change is equal to some constant k multiplied by one minus what the rate of change is proportional to

$$\frac{da}{dt} = ka(1 - a)$$