Intro to Neural Nets

Week 2: Mathematical Building Blocks & Working with Keras API

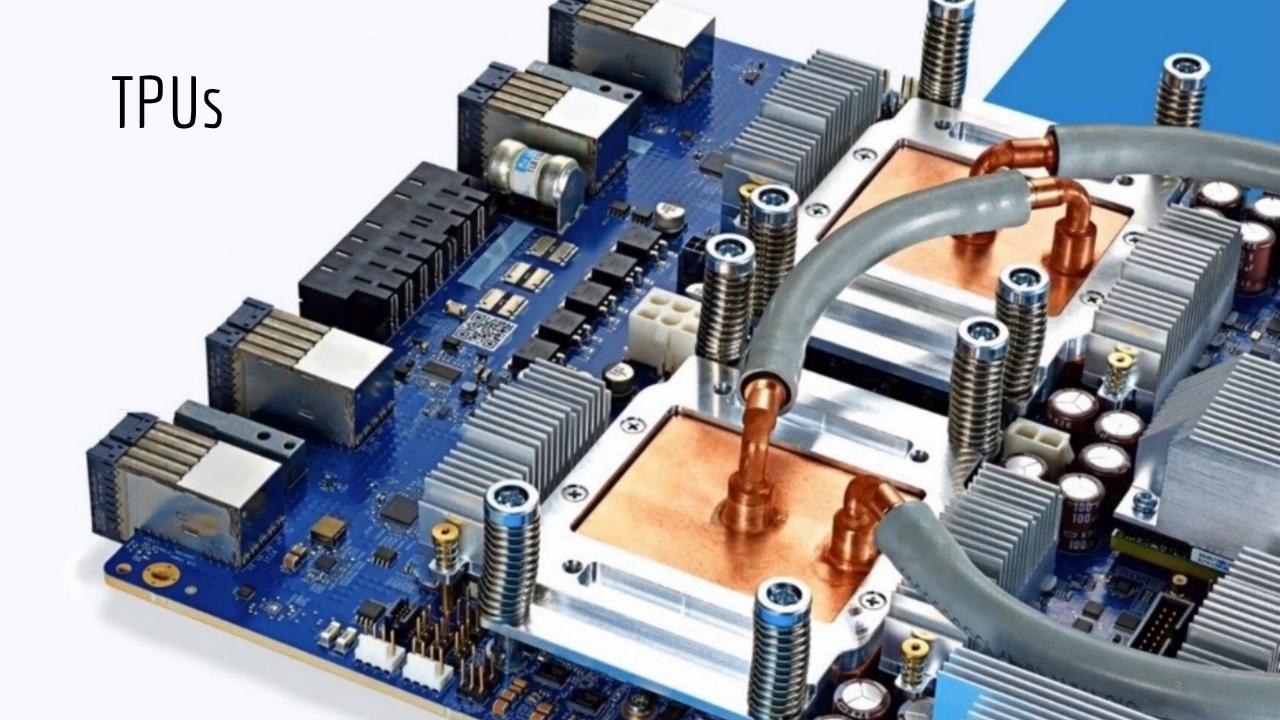
Today's Agenda

1. Building Blocks of NNs

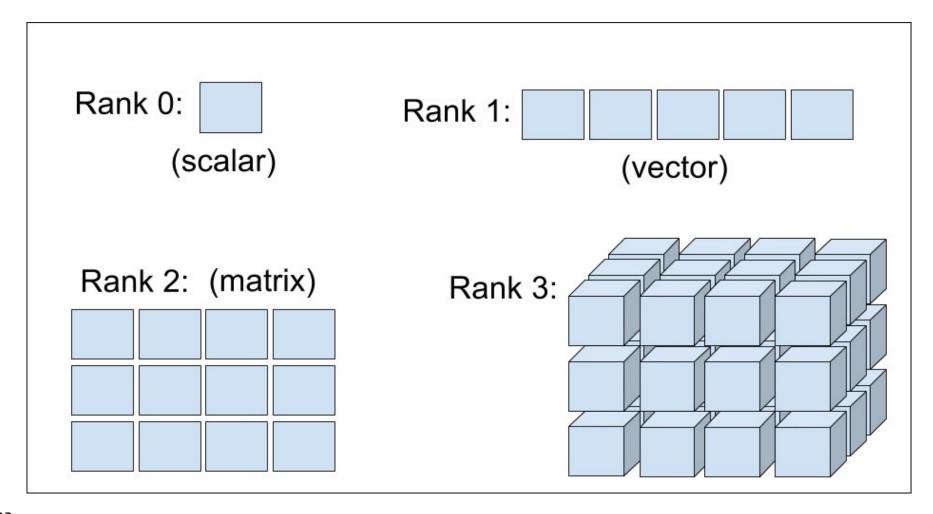
- Tensors (and relevant mathematical operations)
- Activation and Loss Functions
- Backpropagation: Derivatives, Gradients & the Chain Rule (with examples)

2. Building a Linear Classifier

- Overview of Keras and Tensorflow.
- Implementing a linear classifier in Keras (now that we know the components).



Tensors



Neuron / Network Components

X and Y are data

 These are input values and labels.

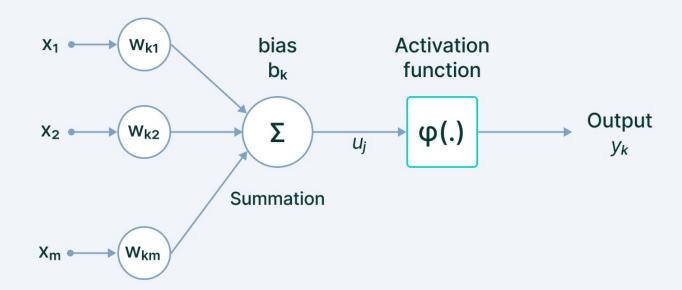
W and b are parameters

 These are values we 'learn' through the optimization process.

$\varphi(.)$ is a function we choose

• This is a hyper-parameter.

Neuron



Neuron / Network Components

x and w are vectors for a node

 These vectors comprise matrices that represent a layer of nodes in the network.

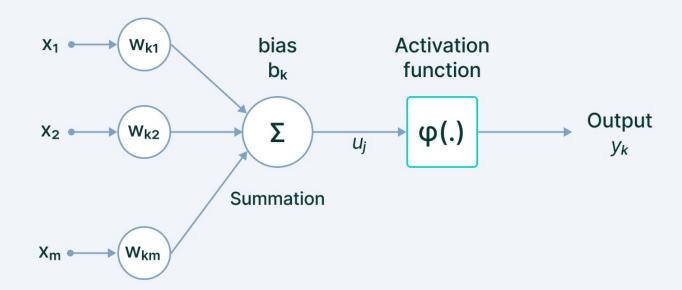
b and y are scalars for a node

 The set of all b's in a layer becomes a vector.

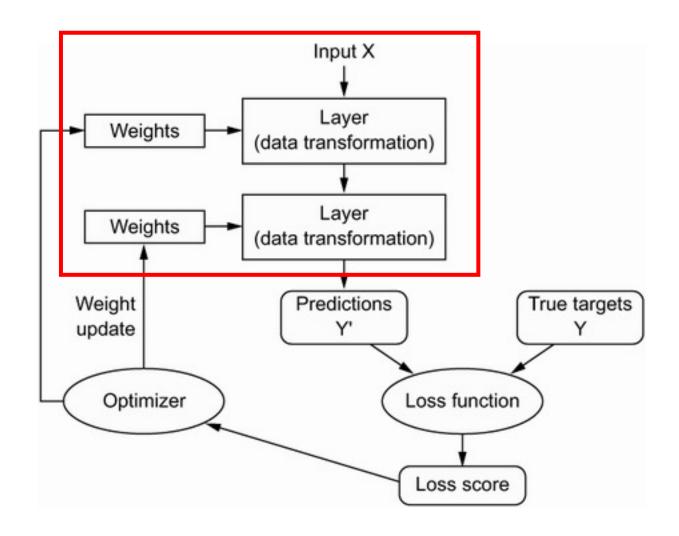
Nature of output, i.e., y

 Depends on position in the network, and what we are predicting

Neuron



Forward Pass



Multiplication

$$y_1 = \varphi \left(\mathbf{x}_1 \cdot \mathbf{w}_1 + b_1 \right)$$

Conformity of Shapes

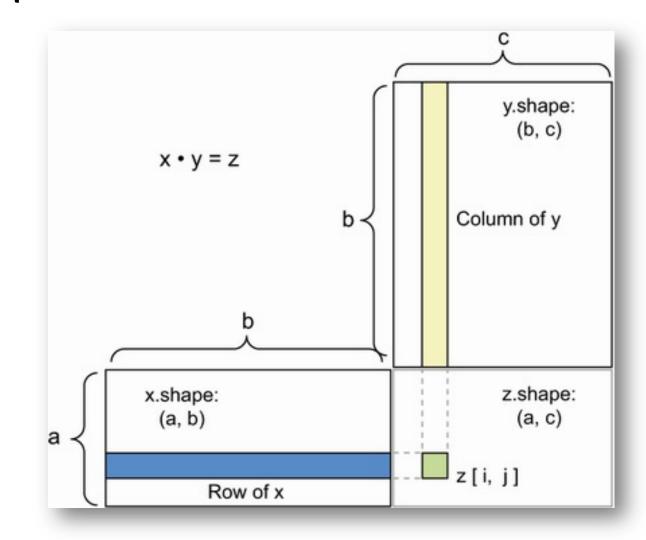
NCOL(X) == NROW(W)

Elements of Resulting Tensor are the Dot Product of X's Rows and Y's Columns

•
$$Z[2,2] = X[2,:] \cdot Y[:,2]$$

We Use This for Multiplication Step

x*w calculations.



Addition + Broadcast

$$y_1 = \varphi \left(x_1 \cdot w_1 + b_1 \right)$$

Shape of the Two Tensors Needs to Conform

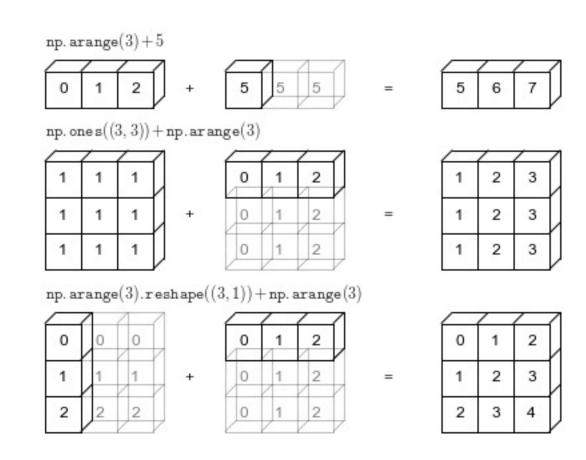
 A + B will only work if A is cleanly divisible by B (or vice versa)

Sum the Element-wise Products

Replicate B until it matches
 A's dimensions, then
 element-wise addition.

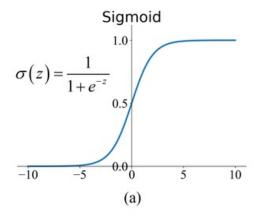
We Use This for the Addition Step

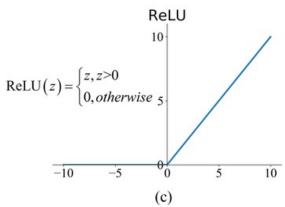
Add x*w and b (bias)

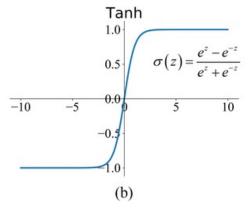


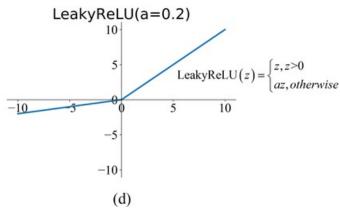
Activation Functions

 $y_1 = \varphi \left(x_1 \cdot w_1 + b_1 \right)$









We Know Enough for a Forward Pass

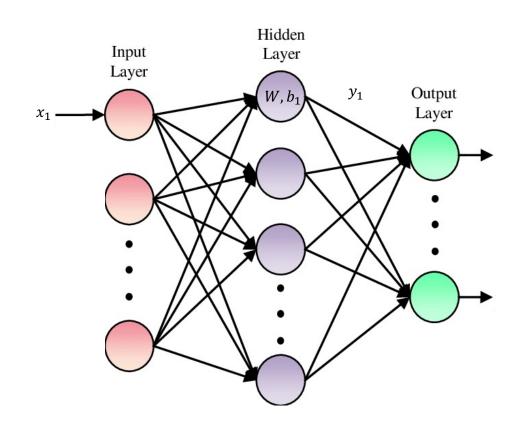
Calculate Output of Each Node Sequentially

$$y_1 = \varphi (x_1 \cdot w_{1,1} + x_2 \cdot w_{1,2} + \dots + b_1)$$

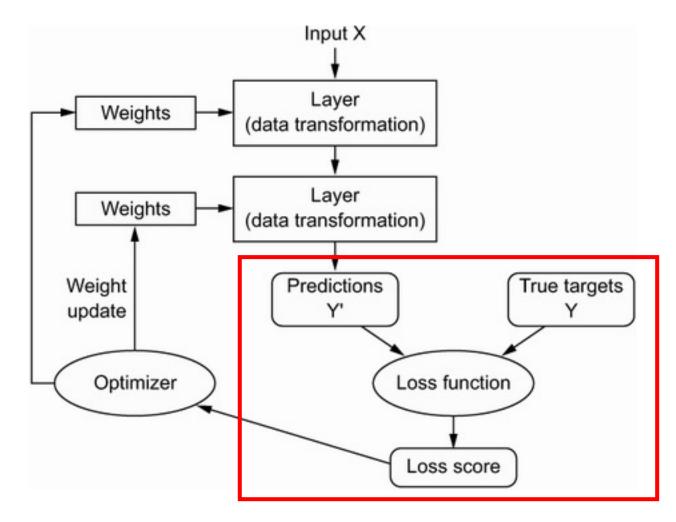
$$y_2 = \varphi \left(x_1 \cdot w_{2,1} + x_2 \cdot w_{2,2} + \dots + b_2 \right)$$

...

Eventually We Obtain Model's Predictions



Calculate Loss



Loss Functions

Cross-Entropy / Log-Loss

$$H_p(q) = -\frac{1}{N} \sum_{i=1}^{N} y_i \cdot log(p(y_i)) + (1 - y_i) \cdot log(1 - p(y_i))$$

- Typical for binary outcomes. Value grows exponentially larger as the predicted probability moves away from the true 0,1 label.
- Multi-category outcomes have an analogous loss function known as multi-class cross-entropy.

MAE / L1 Loss

$$MAE = \frac{\sum_{i=1}^{n} |y_i - \hat{y}_i|}{n}$$

 Typical for continuous outcomes.
 Errors are penalized homogenously, in magnitude and direction. This should look familiar!

MSE / Quadratic / L2 Loss

$$MSE = \frac{\sum_{i=1}^{n} (y_i - \hat{y}_i)^2}{n}$$

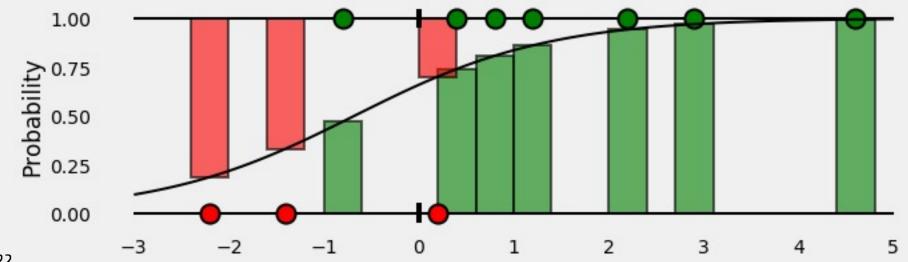
 Typical for continuous outcomes, larger errors penalized exponentially more. This should look familiar!

Binary Cross-Entropy Loss

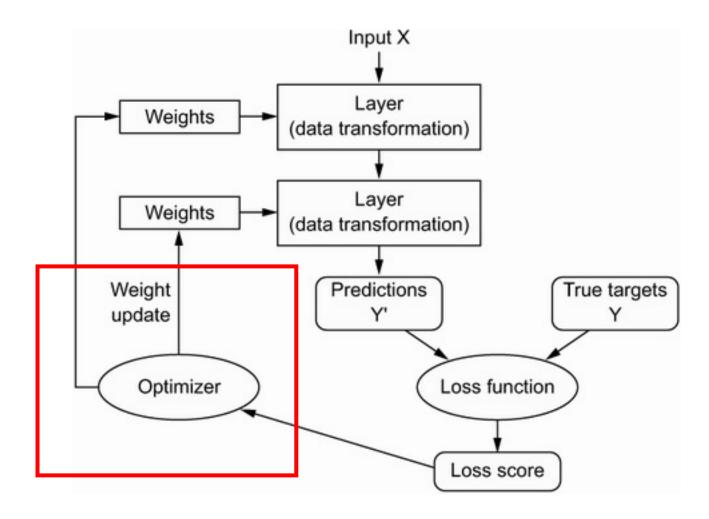
$$H_p(q) = -\frac{1}{N} \sum_{i=1}^{N} y_i \cdot log(p(y_i)) + (1 - y_i) \cdot log(1 - p(y_i))$$

Piecemeal Function:

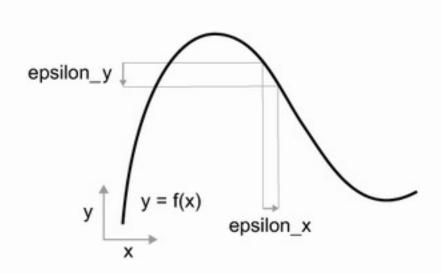
- If ground truth is 1, then loss is -1*log(p). As prediction approaches 1, loss approaches 0. As prediction approaches 0, loss grows exponentially.
- If ground truth is 0, then loss is -1*log(1-p). As prediction approaches 1, loss rises exponentially. As prediction approaches 0, loss approaches 0.

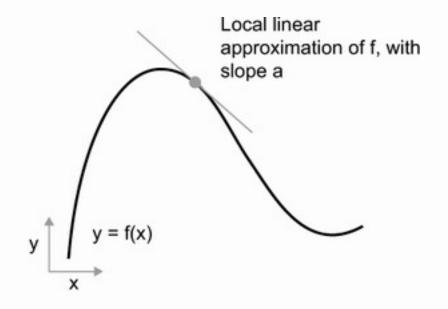


Backpropagation

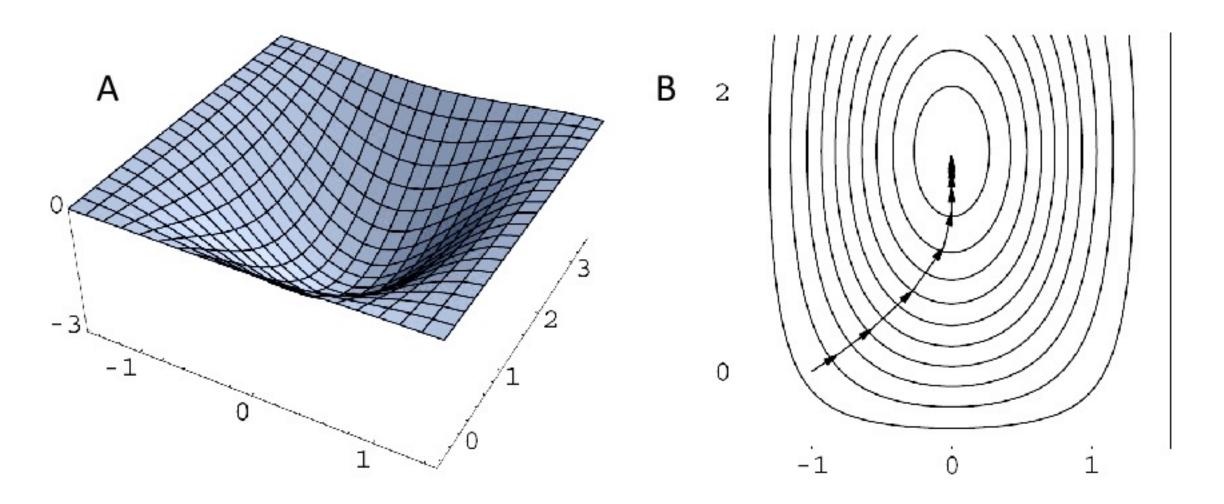


Derivative = "Rate" of Change

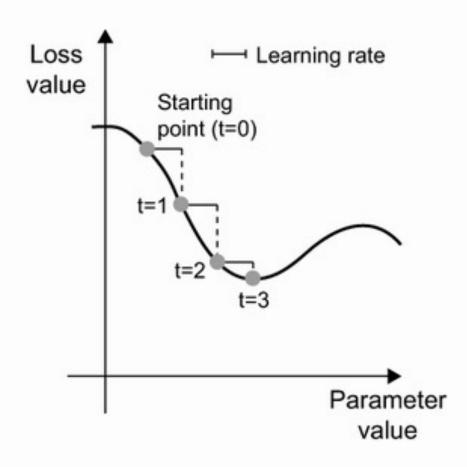




Gradient = Derivative in Multiple Dimensions



Gradient Descent



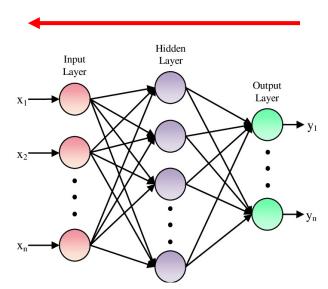
Derivatives of Loss w.r.t All Parameters

Recall that Each Node's Output Can be Expressed as a Function of the Prior Nodes' Outputs

$$y_1 = \varphi (x_1 \cdot w_{1,1} + x_2 \cdot w_{1,2} + \dots + b_1)$$

$$y_2 = \varphi \left(x_1 \cdot w_{2,1} + x_2 \cdot w_{2,2} + \dots + b_2 \right)$$

•••

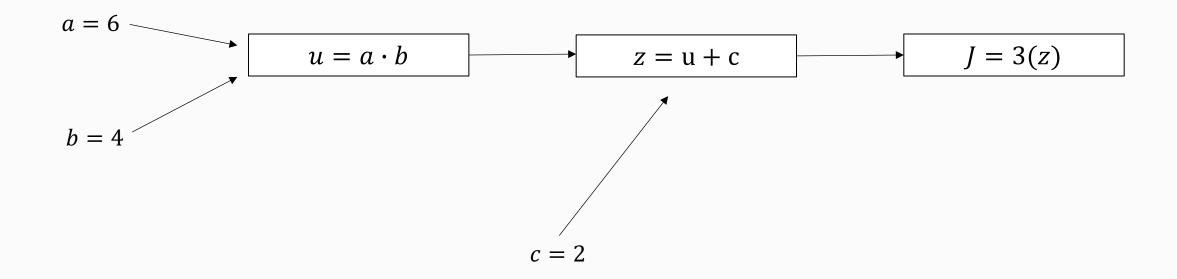


Start at the final nodes in the network and work backwards

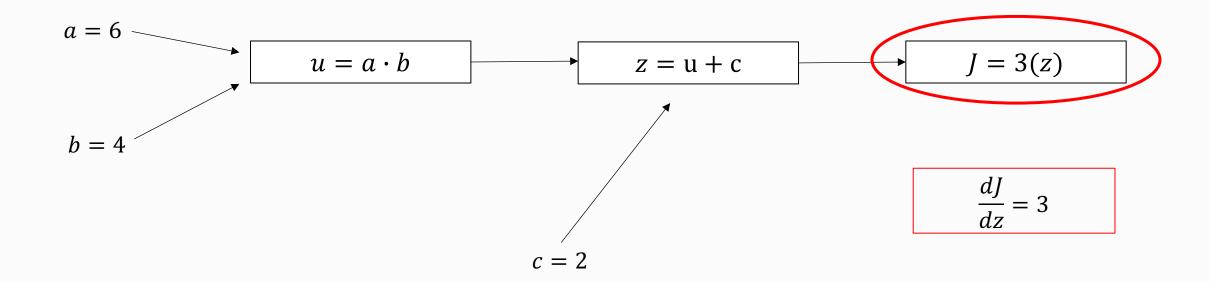
- We calculate partial derivatives w.r.t. their inputs / weights.
- Then, use those partial derivatives and work backward into earlier layers to get partial derivatives w.r.t. their inputs / weights, and so on.

Simplifying Gradients: Computation Graph

$$J = 3(a \cdot b + c)$$

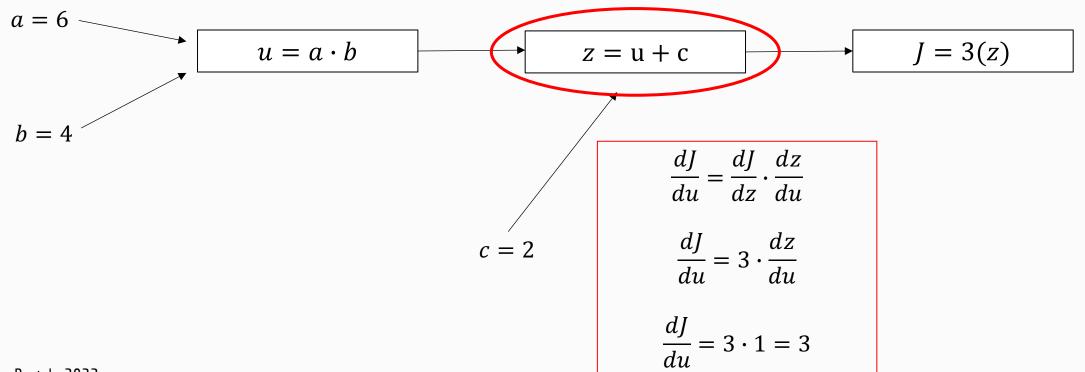


$$J = 3(a \cdot b + c)$$



$$\frac{dJ}{dz} = 3$$

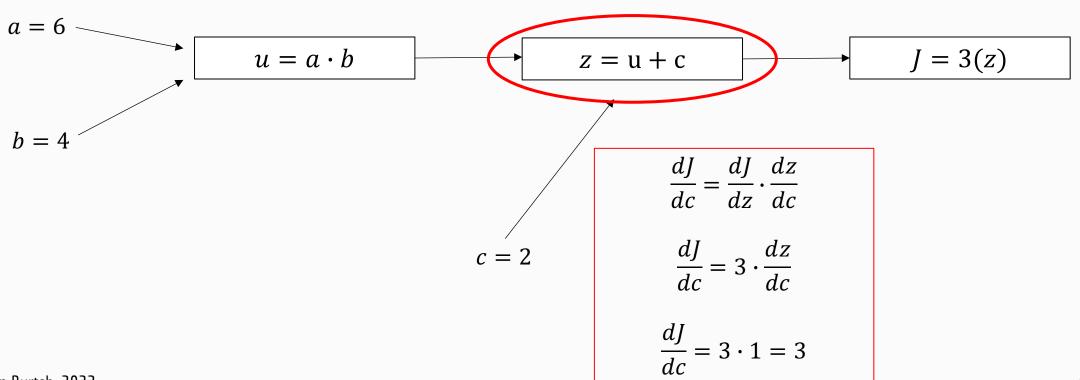
$$J = 3(a \cdot b + c)$$



$$\frac{dJ}{dz} = 3$$

$$\frac{dJ}{du} = 3$$

$$J = 3(a \cdot b + c)$$

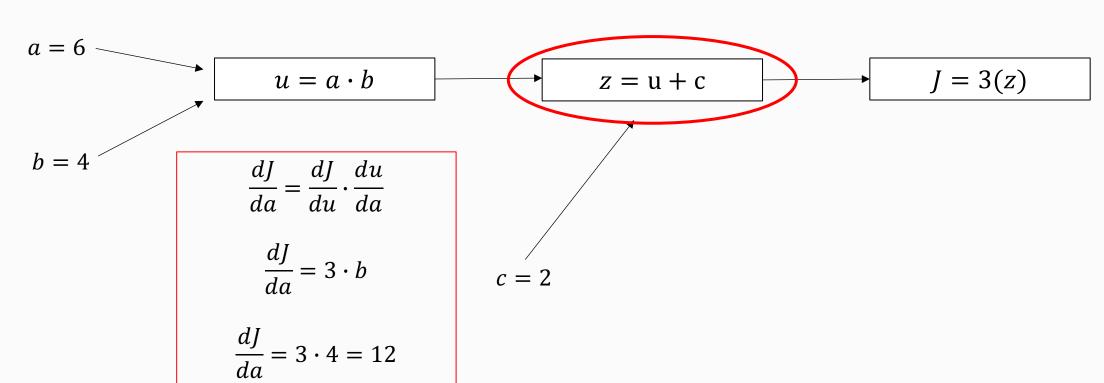


$$\frac{dJ}{dz} = 3$$

$$J = 3(a \cdot b + c)$$

$$\frac{dJ}{du} = 3$$

$$\frac{dJ}{dc} = 3$$



$$\frac{dJ}{dz} = 3$$

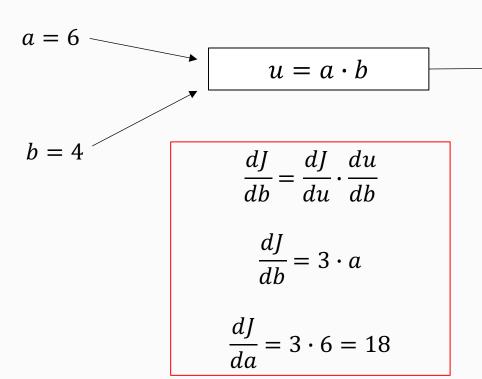
$$J = 3(a \cdot b + c)$$

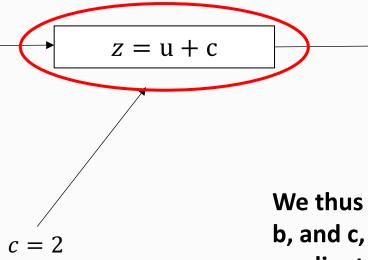
$$\frac{dJ}{da} = 12$$

$$\frac{dJ}{du} = 3$$

$$\frac{dJ}{du} = 3$$

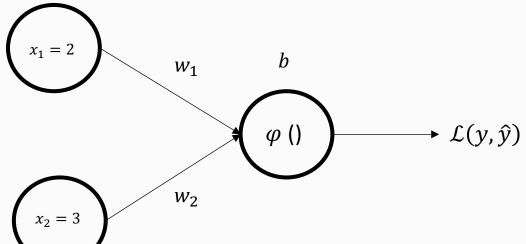
J=3(z)





We thus update our parameters, a, b, and c, subtracting each's gradients*epsilon from its current value. Epsilon is the learning rate.

Single Node with Sigmoid & Cross-Entropy Loss (i.e., Logistic Regression)



Remember that φ here is just a placeholder for the argument to the loss function. It happens to be a sigmoid transformation of 'something', i.e., $\varphi(wx+b)$, but it doesn't really matter. We just represent it with some variable name and calculate an expression for the derivative.

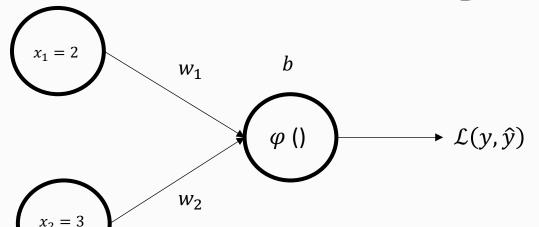
$$\frac{d\mathcal{L}}{d\varphi} = -\frac{y}{\varphi} + \frac{1-y}{1-\varphi}$$

$$\frac{d\mathcal{L}}{d\varphi} = \frac{\varphi(1-y) - y(1-\varphi)}{\varphi(1-\varphi)}$$

$$\frac{d\mathcal{L}}{d\varphi} = \frac{\varphi - \varphi y - y + \varphi y}{\varphi(1-\varphi)}$$

$$\frac{d\mathcal{L}}{d\varphi} = \frac{\varphi - y}{\varphi(1-\varphi)}$$

Single Node with Sigmoid & Cross-Entropy Loss (i.e., Logistic Regression)



Now we calculate derivative of the sigmoid with respect to its argument, z.

$$\begin{split} \varphi(z) &= (1 + e^{-z})^{-1} \\ \varphi'(z) &= -1 \cdot (1 + e^{-z})^{-2} \cdot (0 + e^{-z} \cdot -1) \\ \varphi'(z) &= (1 + e^{-z})^{-2} \cdot e^{-z} \\ \varphi'(z) &= \varphi(z) \cdot (1 - \varphi(z)) \end{split}$$

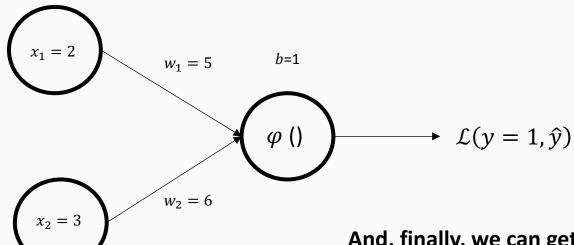
$$\frac{d\mathcal{L}}{dz} = \frac{d\mathcal{L}}{d\varphi} \cdot \frac{d\varphi}{dz}$$

$$\frac{d\mathcal{L}}{dz} = \frac{\varphi - y}{\varphi(1 - y)} \cdot \frac{d\varphi}{dz}$$

$$\frac{d\mathcal{L}}{dz} = \frac{\varphi - y}{\varphi(1 - y)} \cdot \varphi(1 - \varphi)$$

$$\frac{d\mathcal{L}}{dz} = \varphi - y$$

Single Node with Sigmoid & Cross-Entropy Loss (i.e., Logistic Regression)



And, finally, we can get gradient of loss with respect to weights and bias. For example, for the first weight...

Evaluate φ based on current values of parameters and the data.

Finally, update the weights...

$$\frac{d\mathcal{L}}{dw_1} = \frac{d\mathcal{L}}{dz} \cdot \frac{dz}{dw_1}$$

$$\frac{d\mathcal{L}}{dw_1} = (\varphi - y) \cdot x_1$$

$$w_{1,new} = w_{1,old} - (\frac{d\mathcal{L}}{dw_{1,old}} \cdot \varepsilon)$$

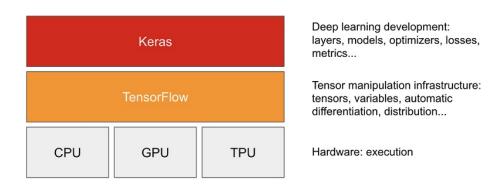
Keras and Tensorflow

1. Tensorflow

• A Python platform for working with tensors, implementing automatic differentiation, providing access to repositories of (well-known) pre-trained models.

2. Keras

- A higher-level API that wraps common usage patterns with Tensorflow functions, pre-defined loss functions, optimization algorithms, etc.
- Keras simplifies data scientists' interaction with Tensorflow.



Tensorflow GradientTape: AutoDiff

1. Gradient Tape

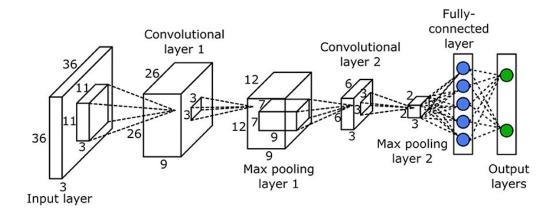
- A Tensorflow function that automates the calculation of derivatives.
- It constructs a computation graph in the background and implements codified rules for calculating derivatives of functions.
- You could technically use gradient tape to implement a gradient descent algorithm for many optimization problems.



The Layer

Layers are the Key Building Block of NNs in Keras

- There are a few subclasses of the Layers class: e.g., Dense is the one we have seen so far layers.Dense(), but we also have convolutional layers, max-pooling layers, recurrent layers, and so on. There are many pre-defined layers in Keras. See: https://keras.io/api/layers/.
- These are different architectural components that can be mixed and matched in different ways to create different network topologies.
- It is also possible to construct custom layers.



A mostly complete chart of

9 ש Neu

Backfed Input Cell

Input Cell

Deep Feed Forward (DFF)

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Perceptron (P)

Noisy Input Cell

Feed Forward (FF)

Radial Basis Network (RBF)

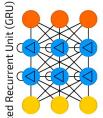
- Probablistic Hidden Cell Hidden Cell
 - Spiking Hidden Cell
- Output Cell

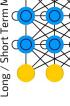
Recurrent

- Match Input Output Cell
- **Recurrent Cell**
- Memory Cell
- Different Memory Cell
- Kernel
- Convolution or Pool





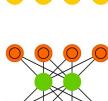


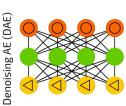


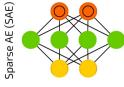




Variational AE (VAE)





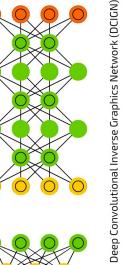








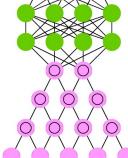


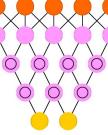


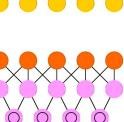
Deep Belief Network (DBN)

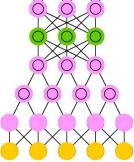
Deep Convolutional Network (DCN)

Deconvolutional Network (DN)



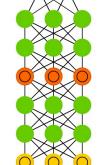


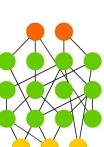




Generative Adversarial Network (GAN)

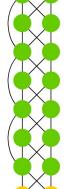
Liquid State Machine (LSM) Extreme Learning Machine (ELM)



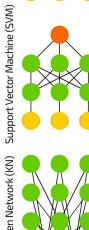


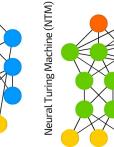


Deep Residual Network (DRN)



Kohonen Network (KN)





Recap

Building Blocks of NNs

- Tensors and Tensor Operations
- Activation Functions
- Loss Functions
- Backpropagation: Derivatives, Gradients & the Chain Rule

Procedure of Minibatch Stochastic Gradient Descent

- Grab a batch of observations (samples)
- Predict their labels using current weights / bias terms.
- Calculate loss value.
- Calculate gradient of loss w.r.t. all weight / bias terms.
- Update each weight by subtracting its gradient*learning rate
- Cycle over the whole training dataset (each cycle is an epoch) repeatedly, until loss is small.