FUNDAMENTALS OF MACHINE LEARNING

AA 2023-2024

Prova Finale (FACSIMILE)

18 Dicembre, 2023

Istruzioni: Niente libri, niente appunti, niente dispositivi elettronici, e niente carta per appunti. Usare matita o penna di qualsiasi colore. Usare lo spazio fornito per le risposte. Instructions: No books, no notes, no electronic devices, and no scratch paper. Use pen or pencil. Use the space provided for your answers.

This exam has 5 questions, for a total of 100 points and 10 bonus points.

1.

Nome:
Matricola:
Multiple Choice: Select the correct answer from the list of choices.
(a) [5 points] True or False: A K-nearest neighbor classifier is only able to learn linear discriminant functions. ○ True √ False
(b) [5 points] True or False: Projecting a dataset onto its first principal component maximizes the variance of the projected data. $\sqrt{\text{True}}$ False \rightarrow F
(c) [5 points] True or False: The K-means algorithm is guaranteed to find the best cluster centers for any dataset. True $\sqrt{\text{False}} \sim 70000000000000000000000000000000000$
(d) [5 points] True or False: A Parzen kernel density estimator uses only the nearest sample in the dataset to estimate the probability of an input sample x. True False
(e) [5 points] How many parameters will a Multilayer Perceptron (MLP) for binary classification with a single hidden layer of width 10 and an input dimensionality of 8 have? (8) 80 \$\sqrt{99}\$ (88 \$\infty\$ None of the above \$\infty\$ 81 \$\infty\$ None of the above \$\infty\$ (15) \$\in
to estimate the probability of an input sample \mathbf{x} . \bigcirc True $\sqrt{\mathbf{False}}$ runt is given by violating the following purpose \mathbf{x} . The following purpose \mathbf{x} is a function of the sample \mathbf{x} . The following purpose \mathbf{x} is a function of the sample \mathbf{x} . The following purpose \mathbf{x} is a function of the sample \mathbf{x} . The following purpose \mathbf{x} is a function of the sample \mathbf{x} . The following purpose \mathbf{x} is a function of the sample \mathbf{x} . The function of the sample \mathbf{x} is a function of the sample \mathbf{x} is a function of the sample \mathbf{x} is a function of the sample \mathbf{x} . The function of the sample \mathbf{x} is a function of the sample \mathbf{x} is a function of the sample \mathbf{x} . The function of the sample \mathbf{x} is a function of the sample \mathbf{x} is a function of the sample \mathbf{x} . The function of the sample \mathbf{x} is a functi
(g) [5 points] Which of the following loss functions is called the negative log likelihood?
$igcup_{c} \mathcal{L}(\mathbf{y},\hat{\mathbf{y}}) = -\sum_{c=1}^C (\ln y_c - \ln \hat{y}_c)^2$ $igcup_{c} \mathcal{L}(\mathbf{y},\hat{\mathbf{y}}) = -\sum_{c=1}^C (y_c - \ln \hat{y}_c)^2$ $igcup_{c} \mathcal{L}(\mathbf{y},\hat{\mathbf{y}}) = -\sum_{c=1}^C y_c \ln \hat{y}_c$ -> Anche detal (noss-entropy)
$\mathcal{L}(\mathbf{y}, \hat{\mathbf{y}}) = \mathcal{L}_{c=1}^{c=1} g_c \ln g_c$ $\mathcal{L}(\mathbf{y}, \hat{\mathbf{y}}) = -\sum_{c=1}^{C} \ln \hat{y}_c$
(h) [5 points] How many iterations of gradient descent must we perform for an epoch of minibatch Stochastic Gradient Descent with a dataset of 1024 samples and a batch size of 16?
\bigcirc 1024 \bigcirc 1 \bigcirc 32 $\sqrt{64}$ 102h = 64
Total Question 1: 40
) SE EM BATCH SOD ALLON EPA
CW' UNICA ITERAZIONE!

	Inswer : Select ALL correct choices: there may be more than one correct choice, but there is ast one correct choice.	3					
(a) [5 points	s] What are the advantages of projecting data onto $K < D$ principal components?						
v	We eliminate noise in the original representation.						
\subset	Classes are guaranteed to be linearly separable.						
\subset) It is a nonlinear embedding that makes learning easy with simpler models.						
ν	/ Models trained on the reduced data are simpler> PERCUE DINIVISU IN CONFUSION FOR						
(b) [5 points	s] Which of the following are advantages of Ensemble Models (e.g. Committees)?						
V	They reduce the variance of the resulting model.						
\subset	They are much more efficient than the base model.	·					
ν	They can reduce the expected error of the final model.						
\subset	The resulting model is nonlinear even if the base model is linear.						
(c) [5 points	s] Which of the following are causes of the vanishing gradients when training neural networks?						
V	/ Saturated inputs to activation functions with near-zero derivatives when satu-	-					
	rated. Signological Signologic						
C							
V	Very deep models.						
	Bad random initialization of the network parameters.						
. ,	s] If we want to penalize classification errors less when training an SVM we should						
_	Increase the hyperparameter C .						
_	Use a radial basis kernel.						
•	/ Decrease the hyperparameter C .						
	None of the above.						
	s] Which of the following are requirements for applying backpropagation to compute gradients ep network?	3					
C	The network must not be too deep.						
	The network must be a directed acyclic graph.						
V	All activation functions must be differentiable.						
C	All activation functions must be continuous.						
· / -	s] Which of the following are true of the Nadaraya-Watson estimator?						
_	It only requires some of the training data at test time.						
	/ It is a nonparametric method.						
٧	/ It estimates a nonlinear function of the input.						
C	It estimates a linear function of the input.						
(g) [5 points	s] Which of the following models are nonparametric?						
C	The Multilayer Perceptron (MLP).						
C	Logistic regression.						
V	/ The K-Nearest Neighbor Classifier						
C	Decision Trees.						
	LTIL PARAMETRO SUMO LE SOCIE DI DEUSIONE! Total Question 2	: 35					

2.

3. [10 points] Show that a Committee Ensemble model using N bootstrapped linear regression models is a linear regression (i.e. that can be expressed as $\mathbf{w}^T \mathbf{x} + b$ for some \mathbf{w} and b).

Solution: A committee model with N bootstrapped linear regression models has this form:

$$f(\mathbf{x}; \theta) = \frac{1}{N} \sum_{n=1}^{N} \overrightarrow{\mathbf{w}_{n}^{T} \mathbf{x}} + \overrightarrow{b_{n}}$$

for $\theta = (\mathbf{w}_n, b_b)_{n=\emptyset}^N$. But then by linearity and commutativity of inner products we have:

$$f(\mathbf{x}; \theta) = \frac{1}{N} \sum_{n=1}^{N} \mathbf{w}_{n}^{T} \mathbf{x} + b_{n}$$

$$= \frac{1}{N} \sum_{n=1}^{N} \mathbf{w}_{n}^{T} \mathbf{x} + \frac{1}{N} \sum_{n=1}^{N} b_{n} \text{ (by linearity)}$$

$$= \frac{1}{N} \mathbf{x}^{T} \sum_{n=1}^{N} \mathbf{w}_{n} + \frac{1}{N} \sum_{n=1}^{N} b_{n} \text{ (by commutativity of inner product)}$$

$$= \frac{1}{N} \hat{\mathbf{w}}^{T} \mathbf{x} + \hat{b}$$

For the new model parameters $\hat{\theta}$:

$$\hat{\mathbf{w}} = \frac{1}{N} \sum_{n=1}^{N} \mathbf{w}_n \text{ and } \hat{b} = \frac{1}{N} \sum_{n=1}^{N} b_n$$

4. [15 points] Show that a Multilayer Perceptron with two hidden layers with activation function $\sigma(x) = x$ is only capable of learning linear functions.

Solution: An MLP with two hidden layers computes the function:

$$f(\mathbf{x}) = W_{\text{out}}\sigma(W_2\sigma(W_1\mathbf{x} + \mathbf{b}_1) + \mathbf{b}_2) + \mathbf{b}_{\text{out}}$$

$$= W_{\text{out}}(W_2(W_1\mathbf{x} + \mathbf{b}_1) + \mathbf{b}_2) + \mathbf{b}_{\text{out}} \text{ (since } \sigma \text{ is the identity function)}$$

$$= (W_{\text{out}}W_2W_1)\mathbf{x} + [W_{\text{out}}W_2\mathbf{b}_1 + W_{\text{out}}\mathbf{b}_2 + \mathbf{b}_{\text{out}}],$$

which is a linear (well, affine) function $f(\mathbf{x}) = W\mathbf{x} + \mathbf{b}$ for:

$$\begin{aligned} W &=& W_{\mathrm{out}}W_2W_1 \\ \mathbf{b} &=& W_{\mathrm{out}}W_2\mathbf{b}_1 + W_{\mathrm{out}}\mathbf{b}_2 + \mathbf{b}_{\mathrm{out}}. \end{aligned}$$

0

IN A H SUT

5. [10 points (bonus)] Design a Deep Convolutional Neural Network (with at least three convolutional layers and one or more pooling layers) to classify MNIST images (input size 28 × 28). Draw the network (or write pseudocode for its definition) and indicate how many parameters each layer has and the sizes of the intermediate feature maps.

Solution: I will write pseudocode in tabular form for the definition of each layer (with corresponding numbers of parameters and size of the activations:

Layer	Type	Activation Size	# Parameters
1	Input	$1 \times 28 \times 28$	0
2	Conv2D(32, 1, 3, 3)	$32 \times 26 \times 26$	320 (32 * 3 * 3 + 32)
3	ReLU	$32 \times 26 \times 26$	0
4	Conv2D(32, 32, 3, 3)	$32 \times 24 \times 24$	9248 -> (32*3*3*32+32)
5	ReLU	$32 \times 26^{23} \times 26^{23}$	0
6	MaxPool(2, 2)	$32 \times 13 \times 13$	0
7	Conv2D(16, 32, 3, 3)	$16 \times 11 \times 11$	4624
8	ReLU	$16 \times 11 \times 11$	0
9	Conv2D(16, 16, 3, 3)	$16 \times 9 \times 9$	2320
10	ReLU DILENSIONE	$16 \times 9 \times 9$	0
11	MaxPool(2, 2)	$16 \times 5 \times 5$	0
12	Flatten()	400	0
13	Linear(400, 128)	128	51328
14	ReLU	128	0
15	Linear(128, 64)	64	8256
16	ReLU	64	0
17	Linear(64, 10)	10	650

