

1. What is the big-Oh space complexity of Dijkstra's and Prim's? Justify your answer.

Dijkstra: $O(V)$ the set to store vertices distance; another array to store Boolean indicating the vertex is visited or not $O(V)$; therefore $O(2V) \sim O(V)$

Prim: $O(V)$ the set to store vertices distance; another array to store parent nodes $O(V)$; another array to store Boolean indicating the vertex is included in MST or not; $O(V)$ to create min-heap; therefore $O(4V) \sim O(V)$

2. What is the big-Oh time complexity for Dijkstra's and Prim's? Justify your answer.

it depends on the data structure used to implement

Dijkstra: $O(|E| * T_{decrease-key} + |V| * T_{extract-minimum})$

$O(|V|^2)$ for adjacency matrix representation since extract-minimum is linear search.

for adjacency list representation:

dense graph: $O(V^2 * \log|V|)$

sparse graph: $O(|E| + |V| \log|V|)$ with binary heap which is used as priority queue to extract the minimum distance vertex from the set that not visited and the time complexity of extract-min & decrease-key operation is $O(\log V)$ for each edge, but in practice if choose Fibonacci heap whose implementation induces large constant amortized overhead unless it's a large graph.

Prim:

PQ implementation	insert	delete-min	decrease-key	total
array	1	V	1	V^2
binary heap	$\log V$	$\log V$	$\log V$	$E \log V$
d-way heap	$\log_d V$	$d * \log_d V$	$\log_d V$	$E * \log_{\frac{E}{V}} V$
Fibonacci heap(amortized)	1	$\log V$	1	$E + V \log V$

Array implementation is suitable for dense graph, requires linear search to find min weight;

Binary heap is suitable for sparse graph;

d-way heap is suitable for problems requires fast performance.

Fibonacci heap is bad in practical situations.

3. Write up the *proof by induction* of the correctness of Dijkstra's algorithm. This should be done similar to the formal proof that we provided for the interval scheduling algorithm. Hint: review Lesson 11.6.

Assumption: for each vertex v , $\text{dist}[v]$ is the shortest distance from source to v on the path of visited nodes or infinity if no path exists.

Base case: source node is the first visited node with distance 0

Inductive part: assume the assumption holds for $n-1$ visited nodes, choose the edge $v \rightarrow u$ where $\text{dist}[u] = \text{dist}[v] + \text{weight}[v \rightarrow u]$ is the least among unvisited nodes, then $\text{dist}[u]$ would be the shortest distance from source to node u because if shorter path exists and w is the shortest unvisited node then $\text{dist}[w] < \text{dist}[u]$ which is contradict to the original assumption. Moreover, if shorter path to u among visited nodes exists and last node is w then $\text{dist}[u] = \text{dist}[w] + \text{weight}[w \rightarrow u]$ which is also a contradiction.

Then after visiting node u , for the unvisited node w , $\text{dist}[w]$ is the shortest distance from source to w using visited nodes.

Conclusion: after visiting all nodes, the shortest path from source to any nodes are all visited and $\text{dist}[v]$ is the shortest distance.