

Recent Advances of Language Transformer Machine

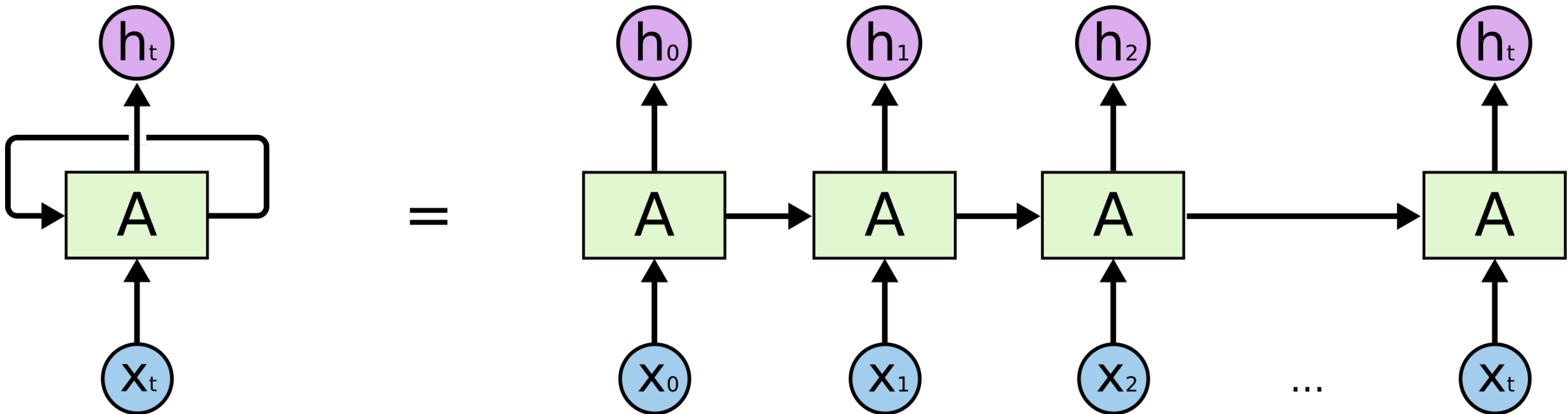
Presenters: Lecheng Zheng, Dawei Zhou

Outline

- Recurrent Neural Networks (RNN)
- Long-Short Term Memory (LSTM)
- Transformer
 - Encoder
 - Multi-head Attention
 - Decoder

Recurrent Neural Networks

- The Recurrent Neural Network A processes some input x_i and outputs h_i . A loop allows information to be passed from one state to the next.
- It aims to learn the dependencies of words.

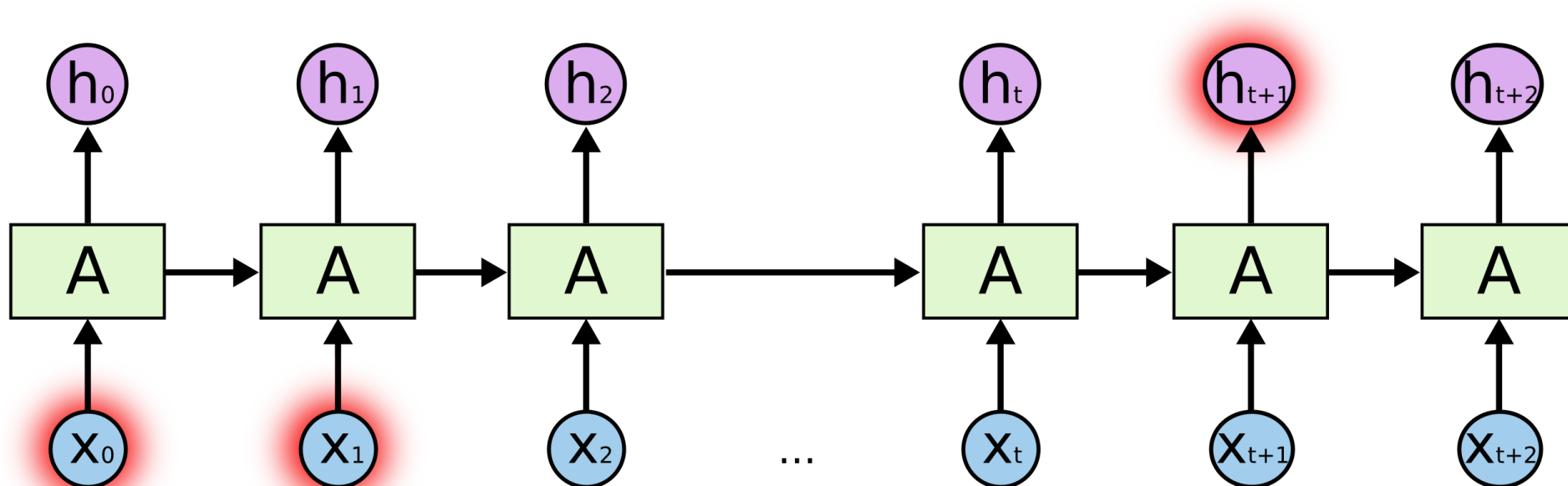


The problem of long-term dependencies

- If we are trying to predict the next word of the sentence “**the clouds in the __**”, we don’t need further context. It’s pretty obvious that the next word is going to be **sky**.
- However, you are trying to predict the last word of the text: “**Tom grew up in France... Tom can speak fluent __?**”.
 - Recent information suggests that the next word is probably a language.
 - If we want to narrow down which language, we need context of **France**, that is further back in the text.

The problem of long-term dependencies

- In theory, RNNs could learn this long-term dependencies.
- In practice, they don't seem to learn them, as the model often forgets the content of distant positions in the sequence.

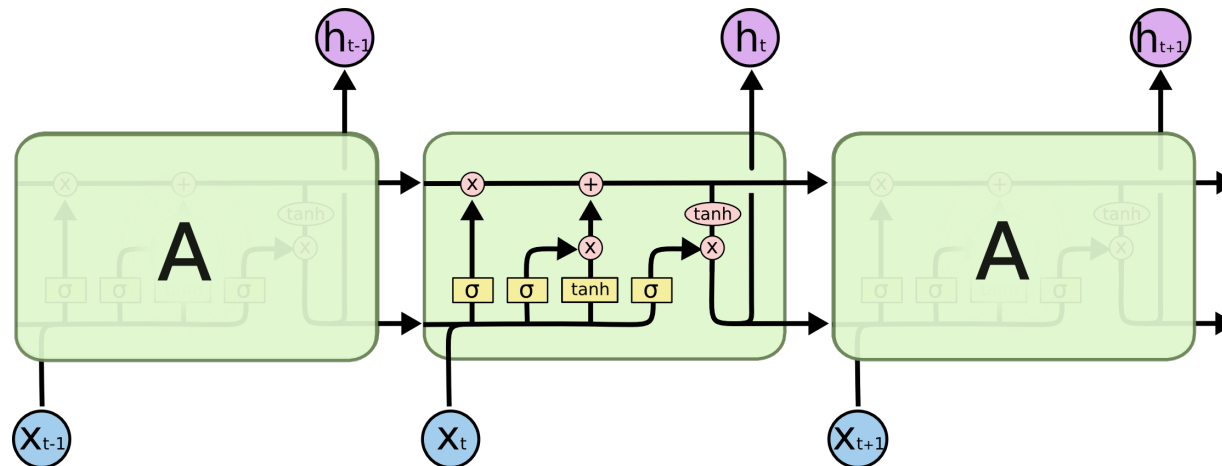


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Long-Short Term Memory (LSTM)

- Each cell takes as inputs x_t , the previous cell state c_{t-1} and the output of the previous cell h_{t-1} .
- It generates a new cell state c_t , and an output h_t .
- The forget gate is responsible for removing irrelevant information and remember important information.



The problem with LSTMs

- The same problem that happens to RNNs generally, happen with LSTMs, i.e. when **sentences are too long (maybe a paragraph)** LSTMs still don't do too well.
- The reason is that the probability of keeping the context from a word that is far away from the current word being processed decreases exponentially with the distance from it.
- That means that when sentences are too long, the model often forgets the content of distant positions in the sequence.

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What is a transformer?

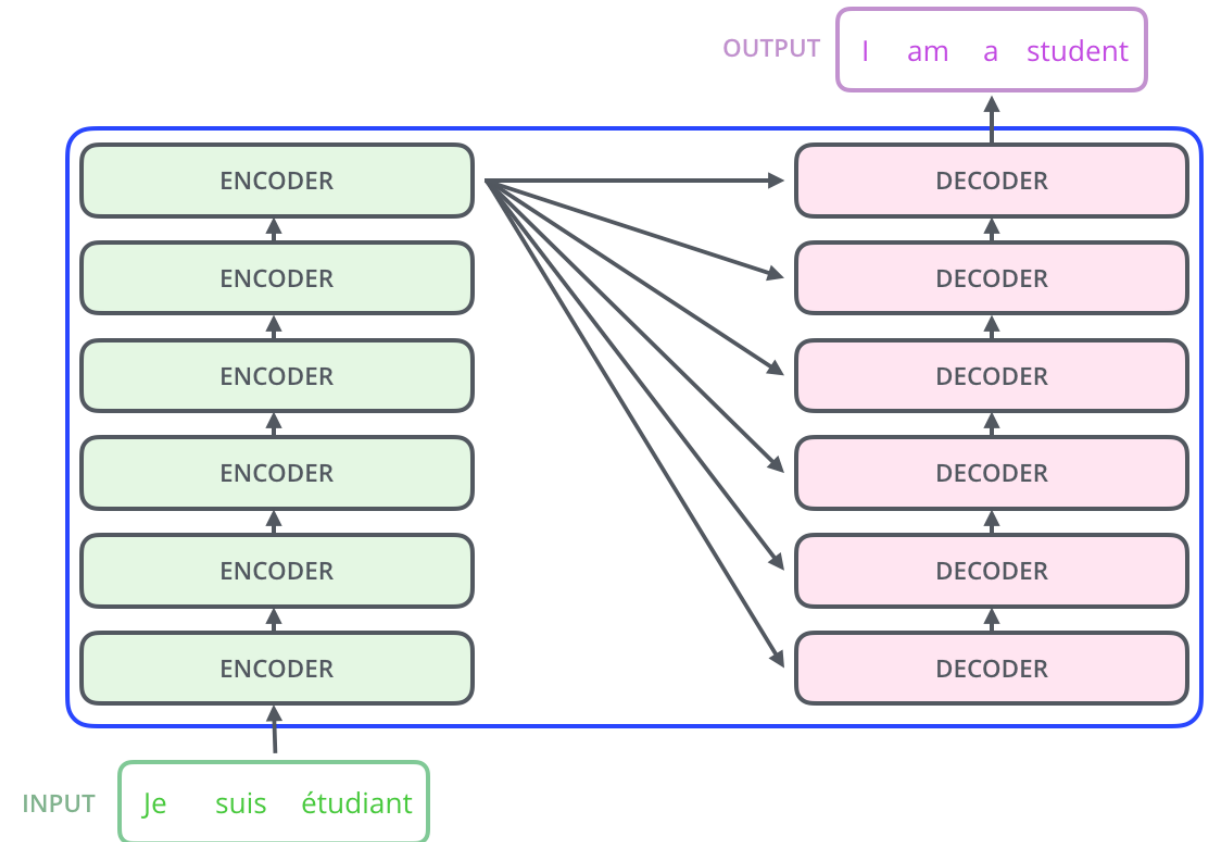
- Transformer is a type of neural network architecture, which is developed to solve the problem of **neural machine translation**.
 - Speech recognition
 - Text-to-speech transformation
 - Language translation

Why transformer?

- **Efficiency is the key!**
- Feed forward layer of transformer could be computed in parallel.
- Transformers try to solve the problem by using Convolutional Neural Networks together with attention models.
- Attention boosts the speed of how fast the model can translate from one sequence to another.

Structure of Transformer

- The transformer consists of **encoders** and **decoders**.
- The transformer shown in the figure on the right hand side stacks six encoders and six decoders.

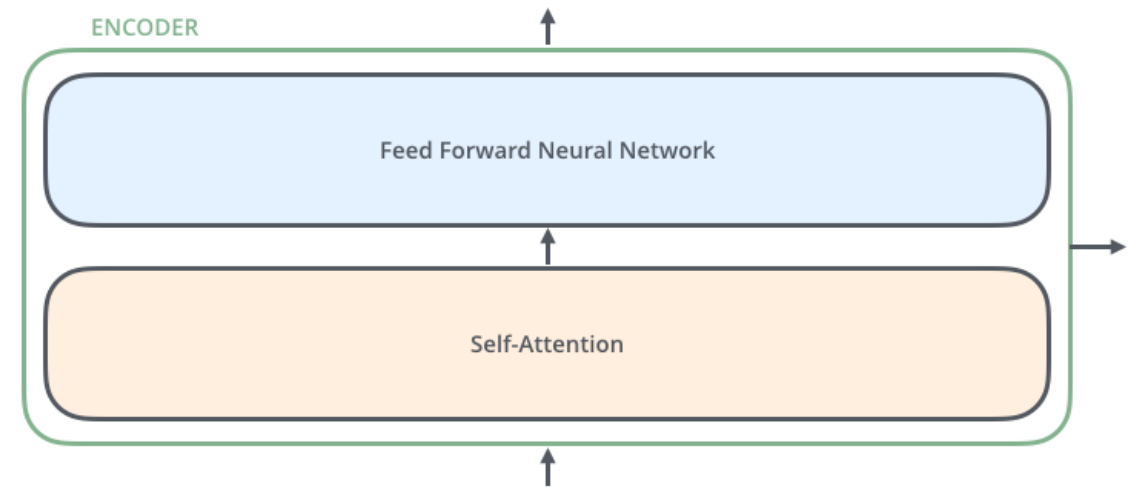


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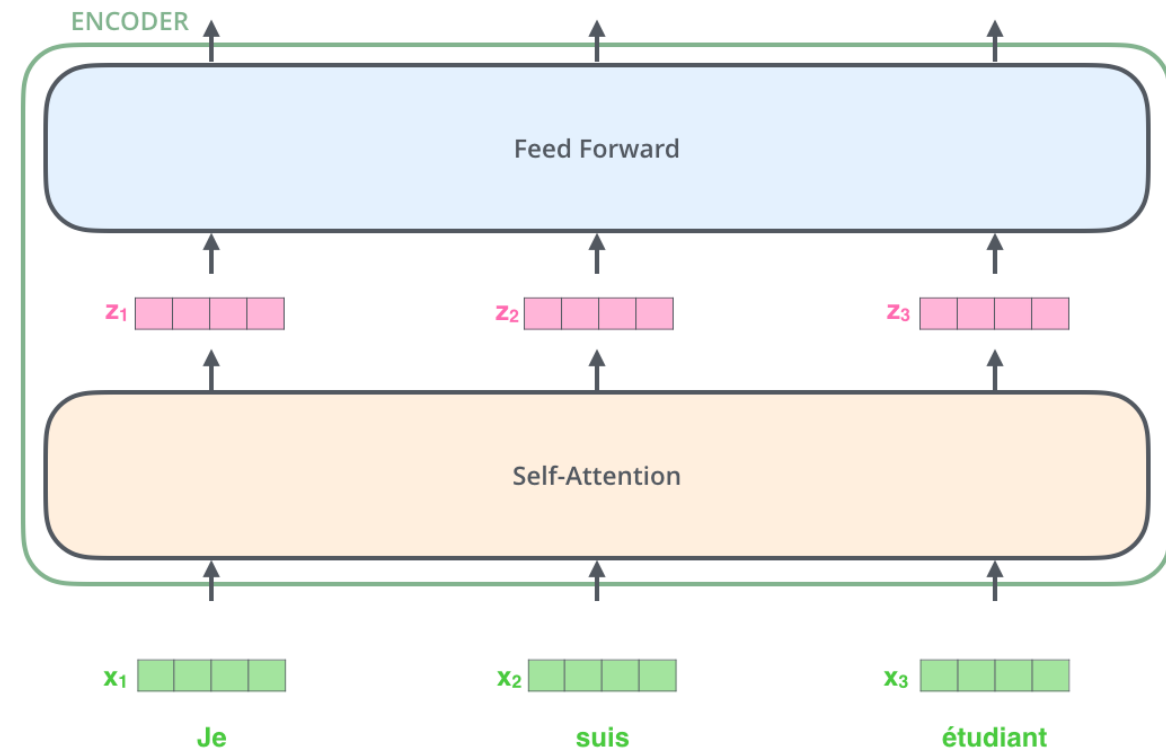
Encoder of a transformer

- Each encoder consists of two layers: Self-Attention Layer and Feed Forward Neural Network.
- The goals of self-attention layer
 - To learn the dependencies between the words in the sentence.
 - To use that information to capture the internal structure of the sentence.



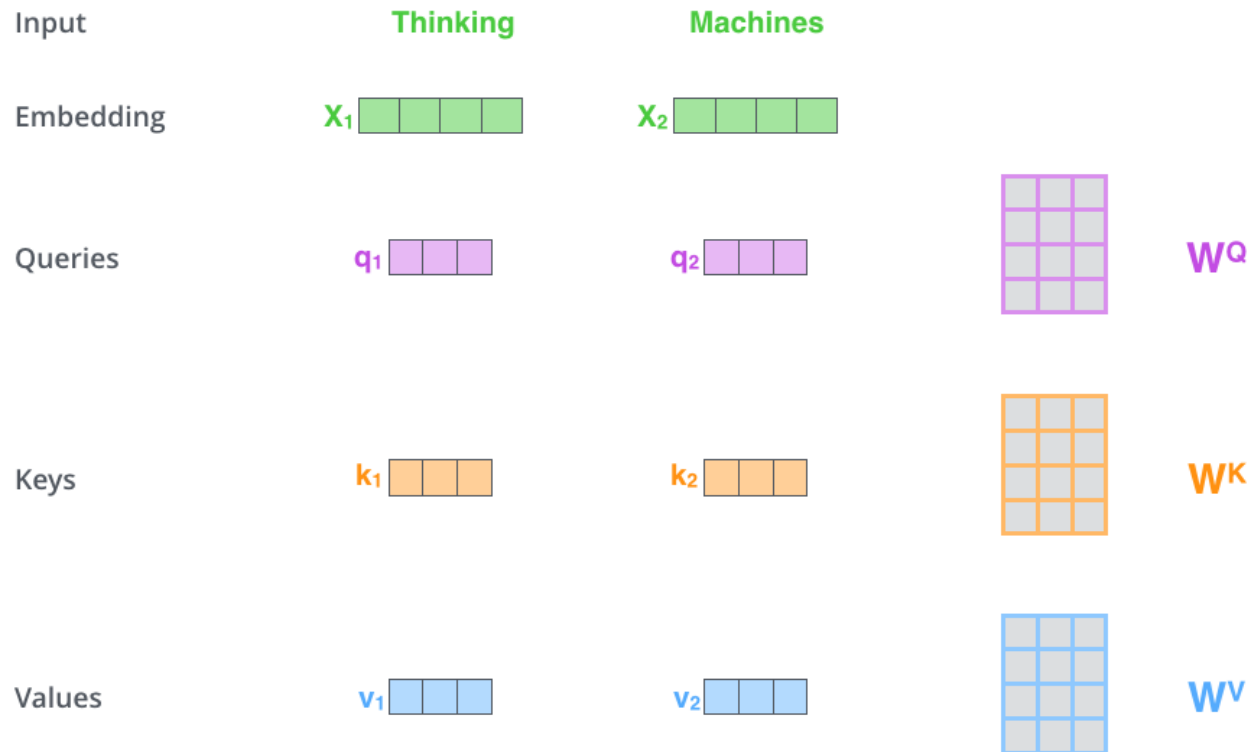
Encoder

- The input of the encoder is the word embeddings.
- There are dependencies between words in the self-attention layer.
- The feed-forward layer does not have those dependencies, and thus the various paths can be executed in parallel.



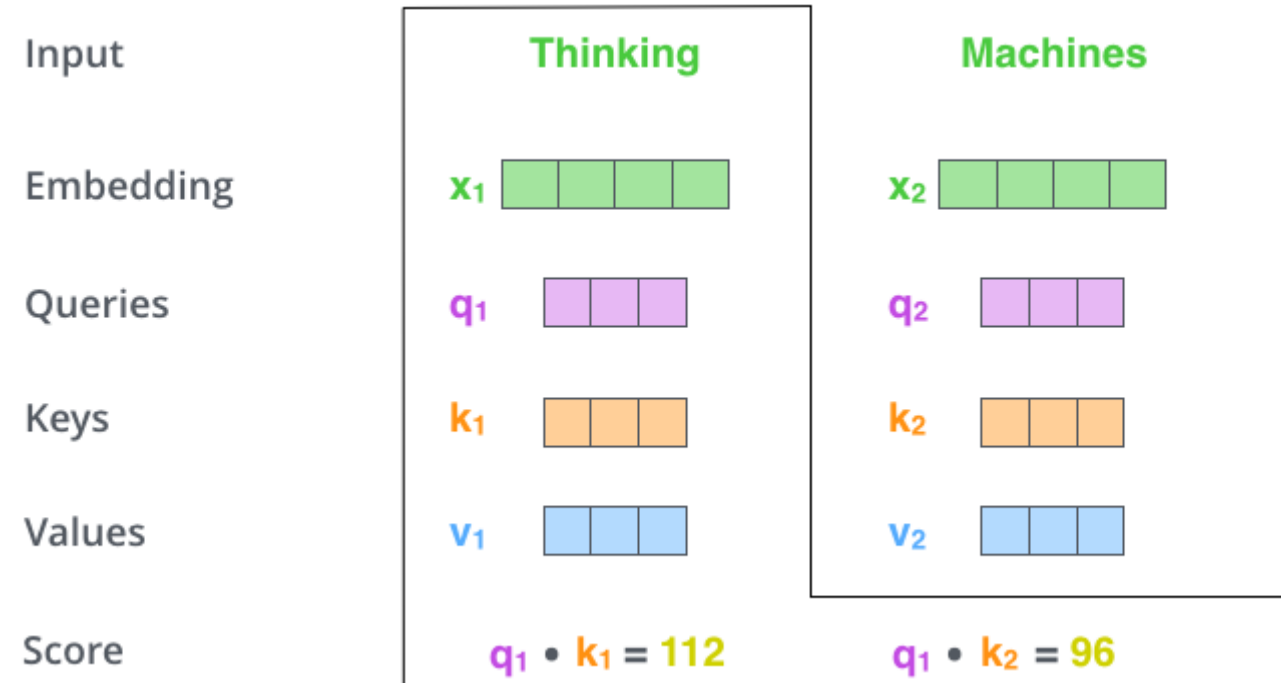
Self-Attention Layer of Encoder

- **The first step:** for each word, we create a Query vector, a Key vector, and a Value vector.
- Multiplying X_1 by the weight matrix W^Q produces q_1 (similar for v_1 and k_1).



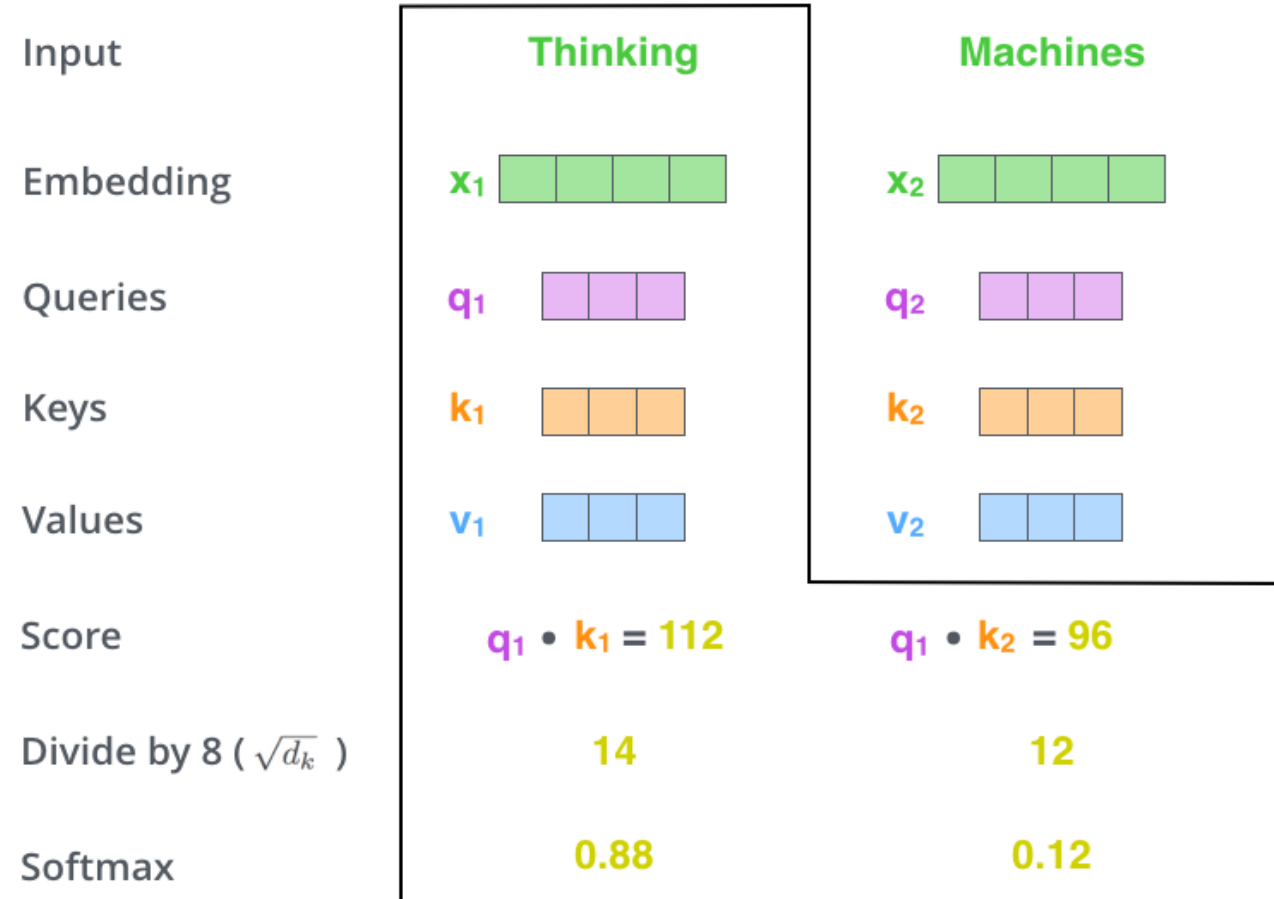
Self-Attention Layer of Encoder

- **The second step:** we need to score each word of the input sentence against this word.
- The score determines how much focus to place on other words as we encode a word at a certain position.



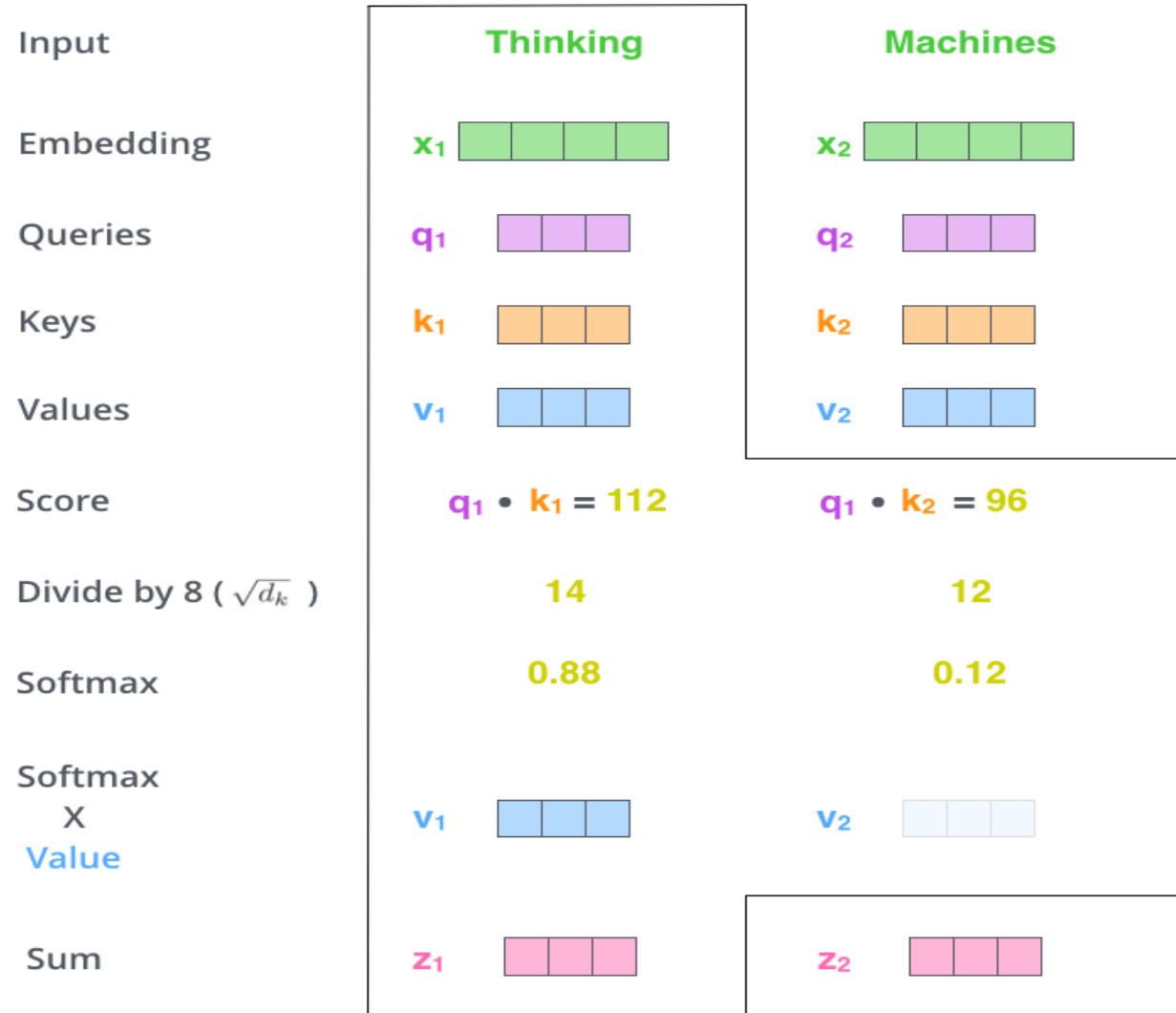
Self-Attention Layer of Encoder

- **The third step** is to divide the scores by the square root of the dimension of the key vectors. This leads to having more stable gradients.
- **The fourth step** is to pass the result through a Softmax operation.



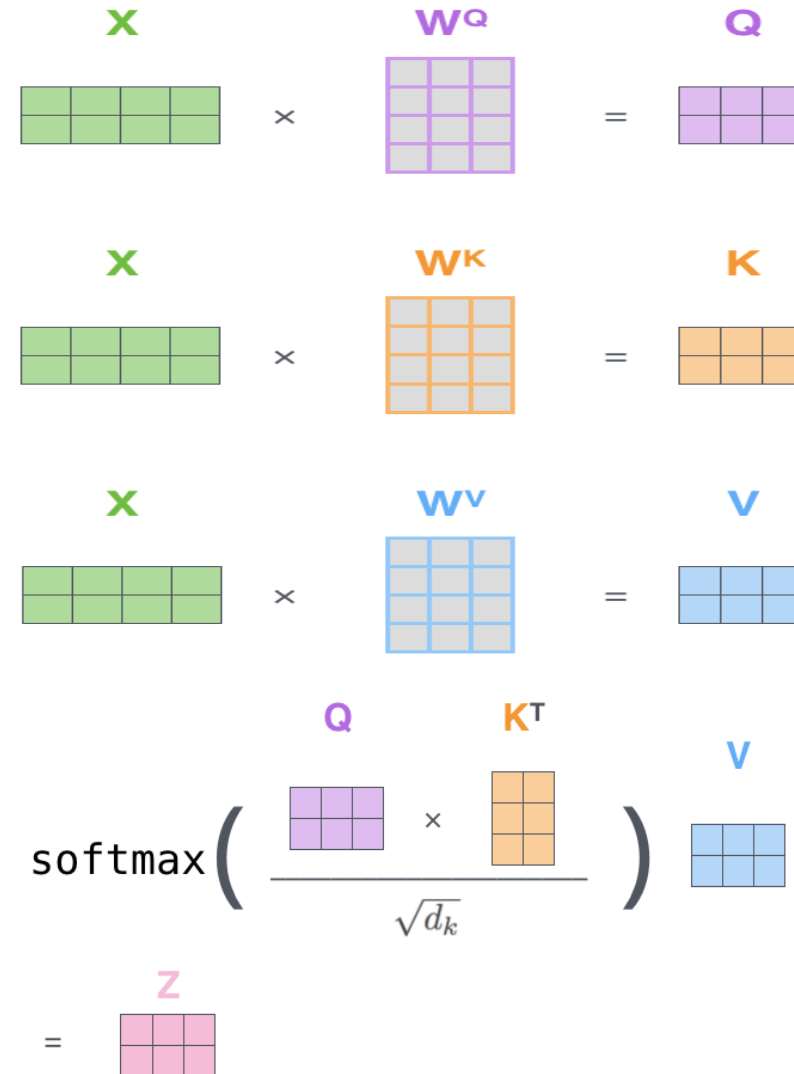
Self-Attention Layer of Encoder

- The fifth step is to multiply each value vector v_i by the Softmax score.
- The intuition here is to keep intact values of the word(s) we want to focus on, and dropout irrelevant words.
- The sixth step is to sum up the weighted value vectors.



Recap: Self-Attention in Encoder

- The first step is to calculate the Query, Key, and Value matrices.
- Steps two through six, we calculate the outputs of the self-attention layer.



A Family of Attention Score Functions

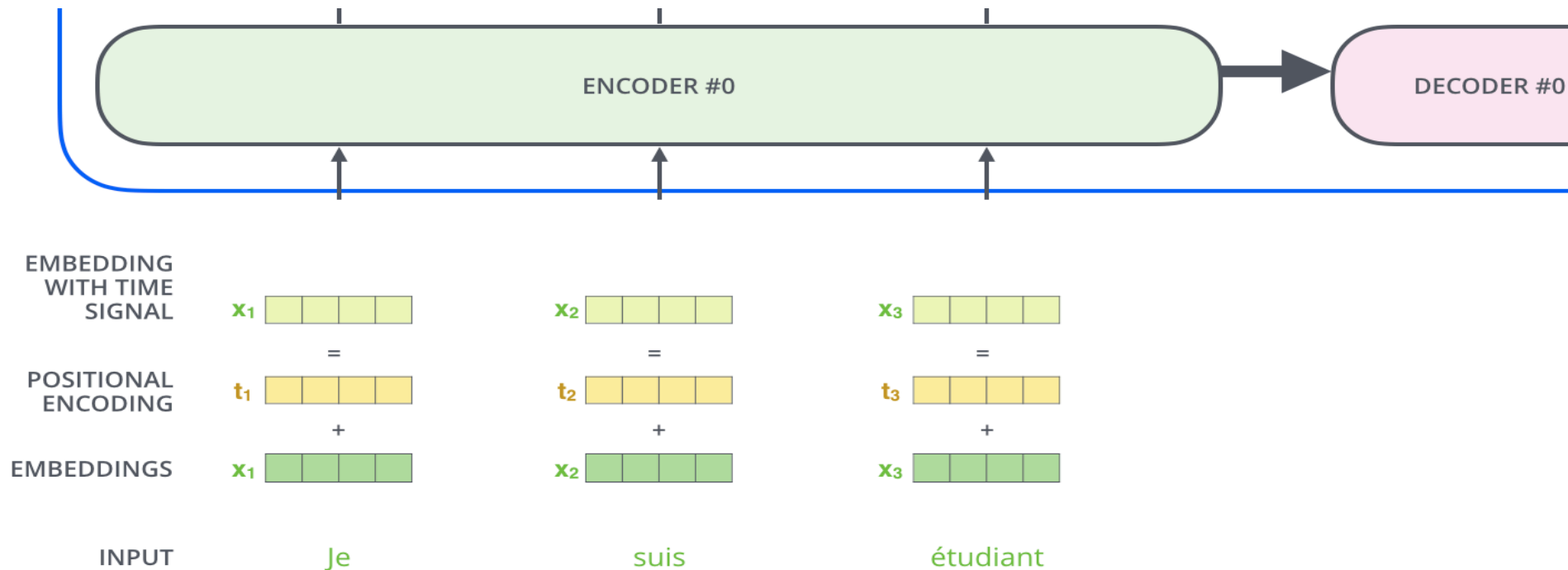
Summary

Below is a summary table of several popular attention mechanisms and corresponding alignment score functions:

Name	Alignment score function	Citation
Content-base attention	$\text{score}(\mathbf{s}_t, \mathbf{h}_i) = \text{cosine}[\mathbf{s}_t, \mathbf{h}_i]$	Graves2014
Additive(*)	$\text{score}(\mathbf{s}_t, \mathbf{h}_i) = \mathbf{v}_a^\top \tanh(\mathbf{W}_a[\mathbf{s}_t; \mathbf{h}_i])$	Bahdanau2015
Location-Base	$\alpha_{t,i} = \text{softmax}(\mathbf{W}_a \mathbf{s}_t)$ Note: This simplifies the softmax alignment to only depend on the target position.	Luong2015
General	$\text{score}(\mathbf{s}_t, \mathbf{h}_i) = \mathbf{s}_t^\top \mathbf{W}_a \mathbf{h}_i$ where \mathbf{W}_a is a trainable weight matrix in the attention layer.	Luong2015
Dot-Product	$\text{score}(\mathbf{s}_t, \mathbf{h}_i) = \mathbf{s}_t^\top \mathbf{h}_i$	Luong2015
Scaled Dot-Product(^)	$\text{score}(\mathbf{s}_t, \mathbf{h}_i) = \frac{\mathbf{s}_t^\top \mathbf{h}_i}{\sqrt{n}}$ Note: very similar to the dot-product attention except for a scaling factor; where n is the dimension of the source hidden state.	Vaswani2017

Positional Encoding

- To account for the order of the words in the input or output sequence, the transformer adds a vector to each input embedding to determine the position of each word.



The intuition Behind Positional Encoding

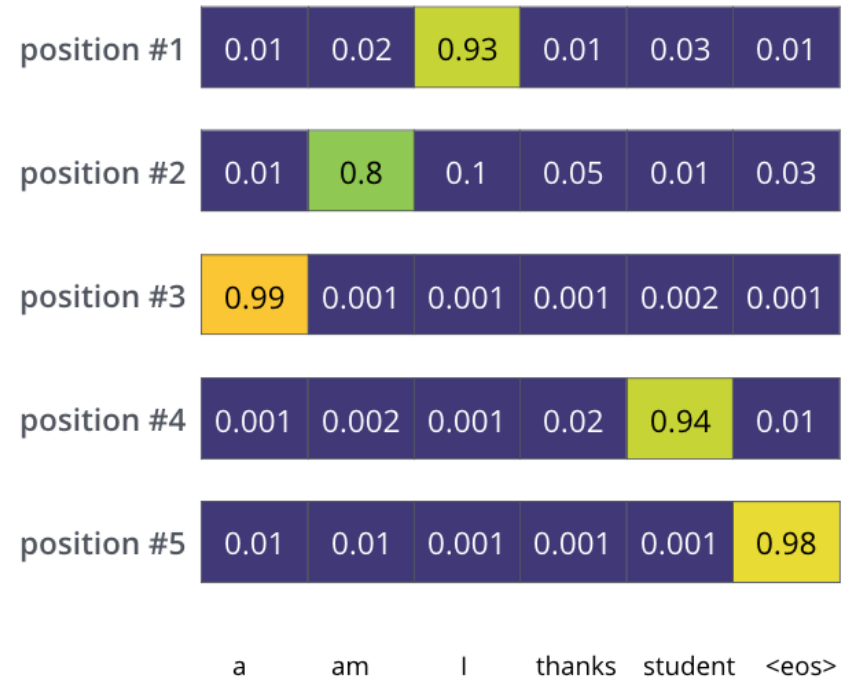
- Adding these values to the embeddings provides meaningful distances between the embedding vectors once they're projected into Q/K/V vectors and during dot-product attention.

Positional Encoding

- In the positional encodings $U \in R^{L \times d}$, L is length of sequence and d is vocabulary size, and the i -th row U_i corresponds to the i -th word in the input/output sequence.
- Example of French to English translation:
 - input: “je suis étudiant”.
 - output: “I am a student”.

Trained Model Outputs

Output Vocabulary: a am I thanks student <eos>



Outline

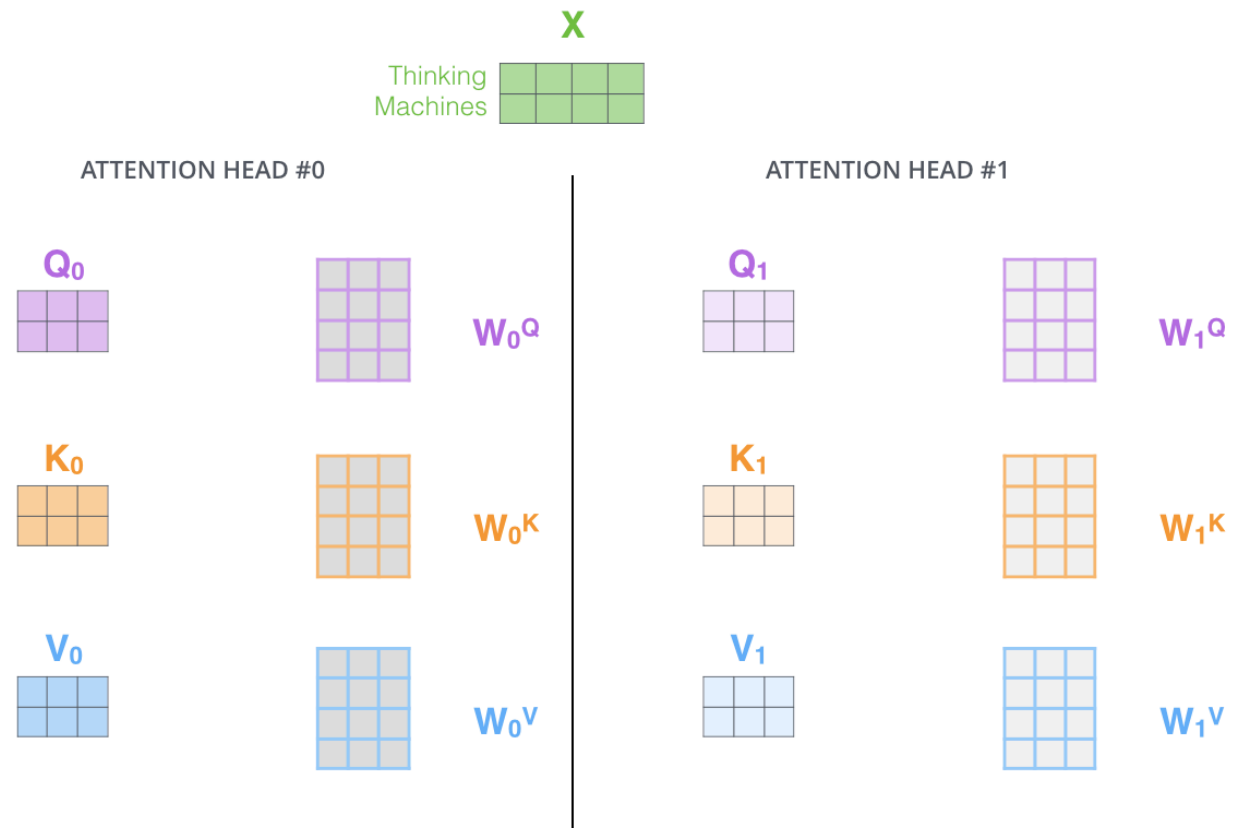
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Benefits of Multi-head Attention

- It expands the model's ability to focus on different positions.
 - In a single attention layer, output vector z contains a little bit of every other encoding, but it could be still dominated by the actual word itself.
 - If we're translating a sentence like "The animal didn't cross the street because it was too tired", we would want to know which word "it" refers to.
- It gives the attention layer multiple "representation subspaces".
 - With multi-headed attention we have multiple sets of Query/Key/Value weight matrices, and different representation subspace.

Multi-head Self Attention

- If we do the same self-attention calculation we outlined before, just eight different times with different weight matrices, we end up with eight different Z matrices or eight different representation subspace.



Multi-head Self Attention

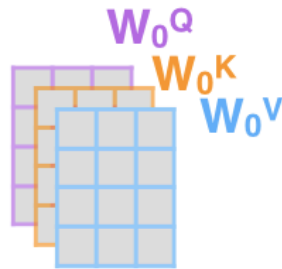
1) This is our input sentence*

Thinking
Machines

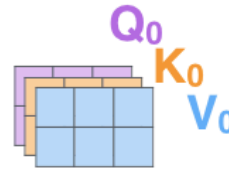
2) We embed each word*



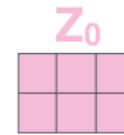
3) Split into 8 heads.
We multiply X or R with weight matrices



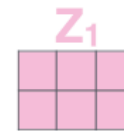
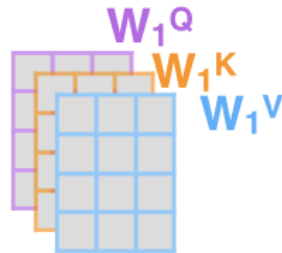
4) Calculate attention using the resulting $Q/K/V$ matrices



5) Concatenate the resulting Z matrices, then multiply with weight matrix W^O to produce the output of the layer



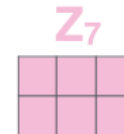
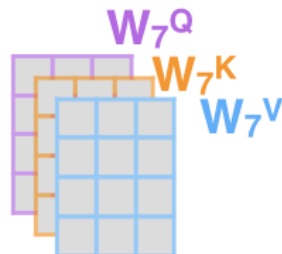
* In all encoders other than #0, we don't need embedding. We start directly with the output of the encoder right below this one



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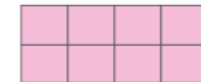
...



W^O



Z

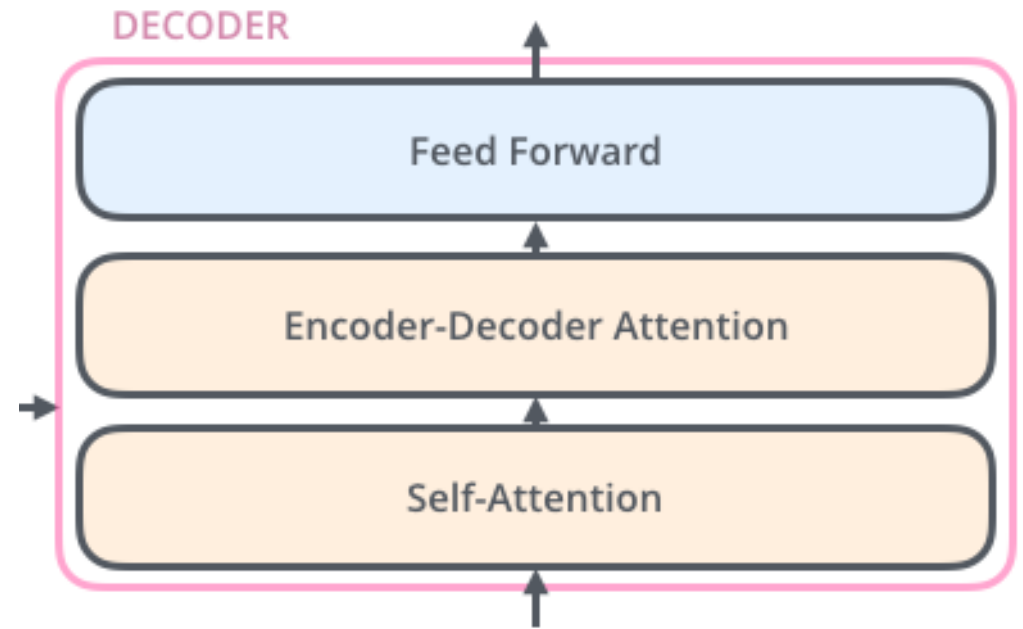


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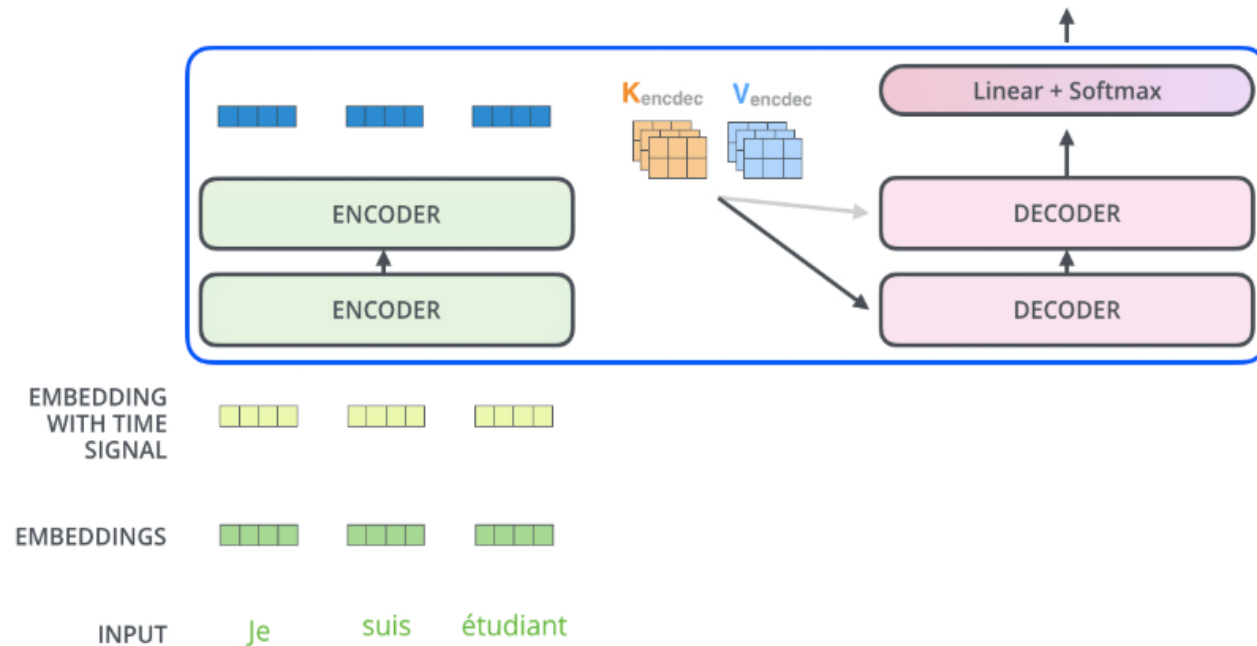
Decoder of a transformer

- The decoder has both those layers, but between them is another attention layer (Encoder-Decoder Attention Layer) that helps the decoder focus on relevant parts of the input sentence.
- The self-attention layer and feed forward network of a decoder work similarly to that of encoder.



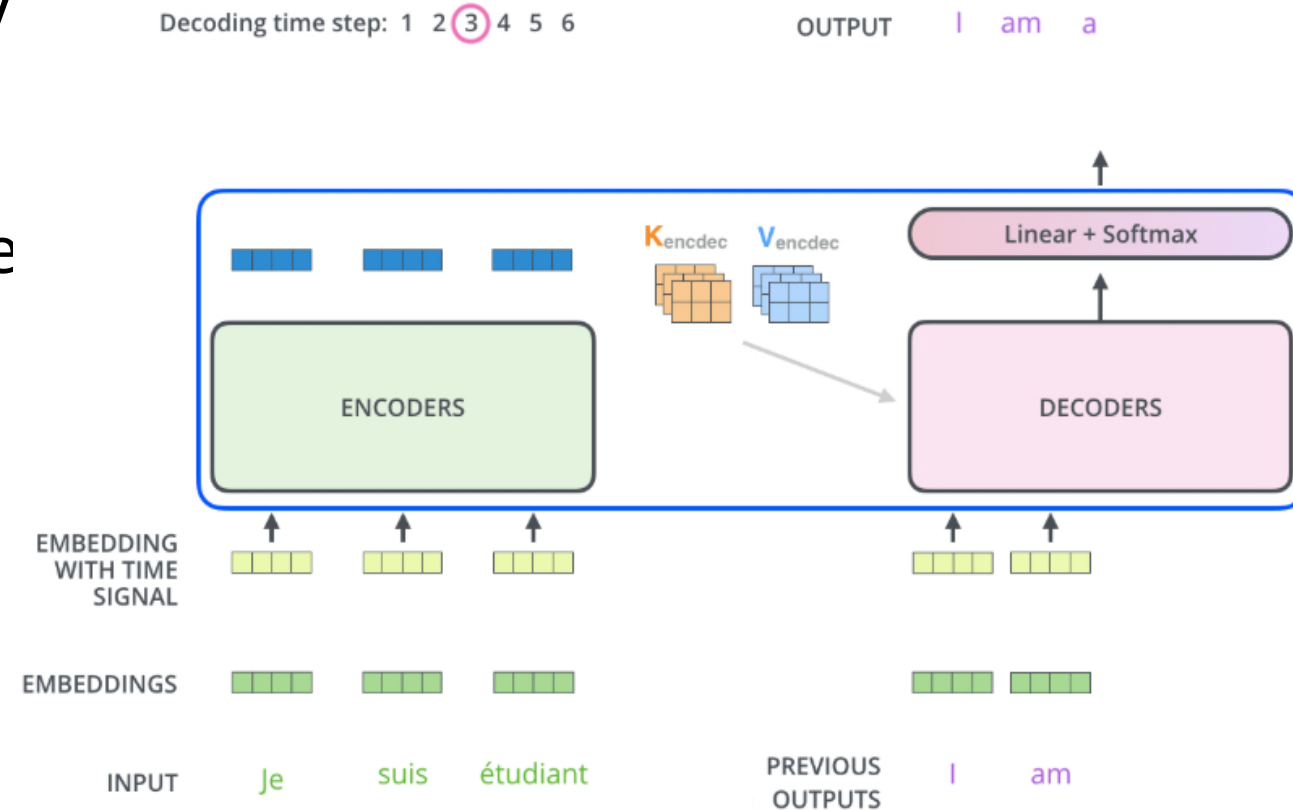
Encoder-Decoder Attention Layer of Decoder

- The output of the top encoder is transformed into a set of attention vectors K and V .
- Just like we did with the encoder inputs, we embed and add positional encoding to those decoder inputs to indicate the position of each word.



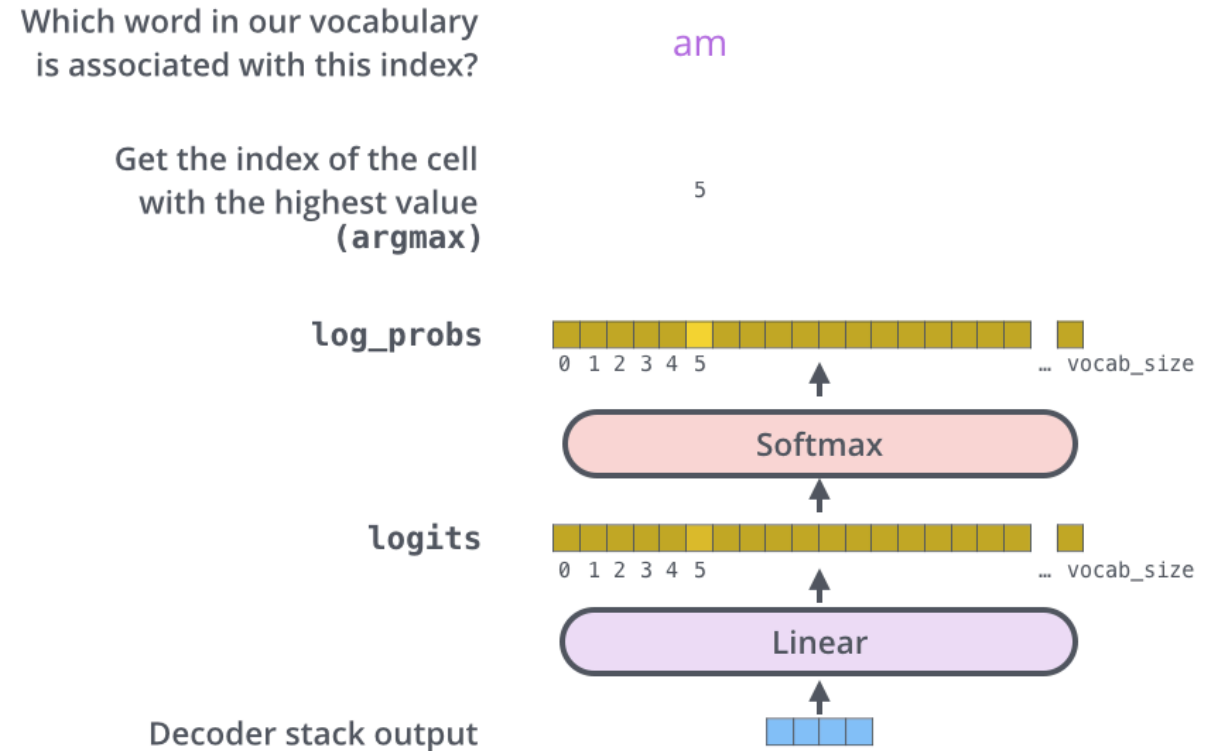
Encoder-Decoder Attention Layer of Decoder

- These output vectors are used by each decoder in its encoder-decoder attention layer to help the decoder focus on appropriate places in the input sequence.



Linear and Softmax Layer of Decoder

- The Linear layer projects the output of decoders to a logits vector.
- The Softmax layer then turns those scores into probabilities.



Useful Tutorial

- [How Transformers Work](#)
- <http://jalammar.github.io/illustrated-transformer/>
- [**Attention? Attention!**](#)
- <http://nlp.seas.harvard.edu/2018/04/03/attention.html>

Transformer XL: Attentive Language Models Beyond a Fixed-Length Context

Vanilla model

- The central problem is how to effectively encode an arbitrarily long context into a fixed size representation.
- Vanilla model splits the entire corpus into shorter segments of manageable sizes, and ignore all contextual information from previous segments.

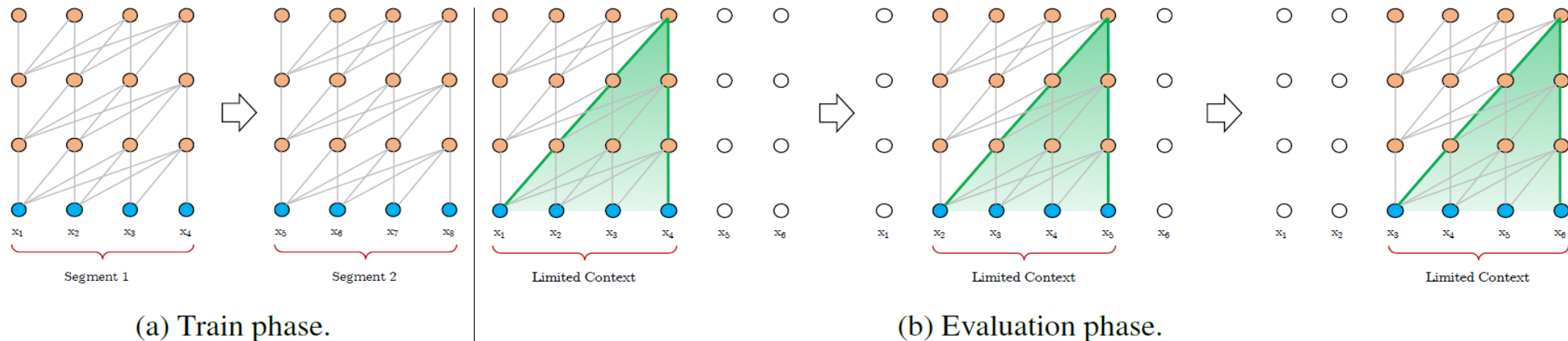


Figure 1: Illustration of the vanilla model with a segment length 4.

Major limitations of vanilla model

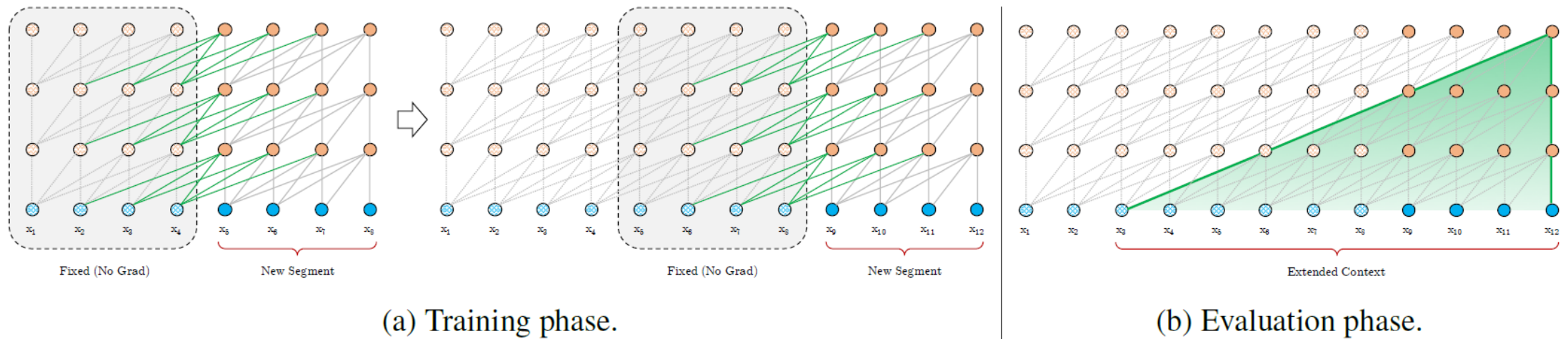
- The largest possible dependency length is upper bounded by the segment length.
- The model lacks necessary contextual information needed to well predict the first few symbols.
- Simply chunking a sequence into fixed-length segments lead to inefficient optimization and inferior performance.

Transformer-XL: Segment-Level Recurrence with State Reuse

- To address these limitations, they take the advantage of the recurrence mechanism and apply it to the Transformer architecture.
- The goal of this mechanism is to enable long-term dependencies with the information from previous segments.
- Transformer-XL processes the first segment of tokens but keeps the output of the hidden layers. When the next segment is processed, each hidden layer receives two inputs.

Transformer-XL: Segment-Level Recurrence with State Reuse

- Two inputs:
 - The output of the previous hidden layer of that segment.
 - The output of the previous hidden layer from the previous segment.
- Advantages: Incorporate longer dependencies and speed up the evaluation.



Transformer-XL: Segment-Level Recurrence with State Reuse

- Let the two consecutive segments of length L be $s_\tau = [x_{\tau,1}, \dots, x_{\tau,L}]$ and $s_{\tau+1} = [x_{\tau+1,1}, \dots, x_{\tau+1,L}]$, respectively.
- Denote the n -th layer hidden state sequence produced for the τ -th segment s_τ as $h_\tau^n \in R^{L \times d}$, where d is the hidden dimension.
- The n -th layer hidden state for segment $s_{\tau+1}$ is produced as follows,

$$\tilde{\mathbf{h}}_{\tau+1}^{n-1} = [\text{SG}(\mathbf{h}_\tau^{n-1}) \circ \mathbf{h}_{\tau+1}^{n-1}], \quad (\text{extended context})$$

$$\mathbf{q}_{\tau+1}^n, \mathbf{k}_{\tau+1}^n, \mathbf{v}_{\tau+1}^n = \mathbf{h}_{\tau+1}^{n-1} \mathbf{W}_q^\top, \tilde{\mathbf{h}}_{\tau+1}^{n-1} \mathbf{W}_k^\top, \tilde{\mathbf{h}}_{\tau+1}^{n-1} \mathbf{W}_v^\top, \quad (\text{query, key, value vectors})$$

$$\mathbf{h}_{\tau+1}^n = \text{Transformer-Layer}(\mathbf{q}_{\tau+1}^n, \mathbf{k}_{\tau+1}^n, \mathbf{v}_{\tau+1}^n). \quad (\text{self-attention} + \text{feed-forward})$$

, where $\text{SG}(\cdot)$ stands for stop-gradient.

Transformer-XL: Relative Positional Encodings

- Challenge to reuse the hidden states - keep the positional information coherent.
- In Transformer, the information of sequence order is provided by a set of positional encodings $U \in R^{L_{max} \times d}$, where the i -th row U_i corresponds to the i -th absolute position within a segment and L_{max} is the maximum possible length to be modeled.

$$\mathbf{h}_{\tau+1} = f(\mathbf{h}_{\tau}, \mathbf{E}_{\mathbf{s}_{\tau+1}} + \mathbf{U}_{1:L}) \quad \text{and} \quad \mathbf{h}_{\tau} = f(\mathbf{h}_{\tau-1}, \mathbf{E}_{\mathbf{s}_{\tau}} + \mathbf{U}_{1:L}),$$

- Notice that , both $E_{s_{\tau+1}}$ and $E_{s_{\tau}}$ are associated with the same positional encoding $U_{1:L}$.

Transformer-XL: Relative Positional Encodings

- To avoid this failure mode, they encode **relative positional information** in the hidden states.
 - Technically, it expands the simple multiplication of the Attention Head's $Score(q_i \cdot k_j)$ to include the four parts mentioned previously.

$$\mathbf{A}_{i,j}^{\text{abs}} = q_i^\top k_j = \underbrace{\mathbf{E}_{x_i}^\top \mathbf{W}_q^\top \mathbf{W}_k \mathbf{E}_{x_j}}_{(a)} + \underbrace{\mathbf{E}_{x_i}^\top \mathbf{W}_q^\top \mathbf{W}_k \mathbf{U}_j}_{(b)} + \underbrace{\mathbf{U}_i^\top \mathbf{W}_q^\top \mathbf{W}_k \mathbf{E}_{x_j}}_{(c)} + \underbrace{\mathbf{U}_i^\top \mathbf{W}_q^\top \mathbf{W}_k \mathbf{U}_j}_{(d)}.$$
$$\mathbf{A}_{i,j}^{\text{rel}} = \underbrace{\mathbf{E}_{x_i}^\top \mathbf{W}_q^\top \mathbf{W}_{k,E} \mathbf{E}_{x_j}}_{(a)} + \underbrace{\mathbf{E}_{x_i}^\top \mathbf{W}_q^\top \mathbf{W}_{k,R} \mathbf{R}_{i-j}}_{(b)} + \underbrace{\mathbf{u}^\top \mathbf{W}_{k,E} \mathbf{E}_{x_j}}_{(c)} + \underbrace{\mathbf{v}^\top \mathbf{W}_{k,R} \mathbf{R}_{i-j}}_{(d)}.$$

- Relative positional encoding $R \in R^{L_{max} \times d}$ substitutes the positional encoding $U \in R^{L_{max} \times d}$, since we only need to know the relative distance of two words rather than the real order when calculating the self-attention.

Transformer-XL: Overall

- Equipping the recurrence mechanism with this relative positional embedding,

$$\begin{aligned} \text{For } n = 1, \dots, N : \quad & \tilde{\mathbf{h}}_{\tau}^{n-1} = [\text{SG}(\mathbf{m}_{\tau}^{n-1}) \circ \mathbf{h}_{\tau}^{n-1}] \\ & \mathbf{q}_{\tau}^n, \mathbf{k}_{\tau}^n, \mathbf{v}_{\tau}^n = \mathbf{h}_{\tau}^{n-1} \mathbf{W}_q^n{}^{\top}, \tilde{\mathbf{h}}_{\tau}^{n-1} \mathbf{W}_{k,E}^n{}^{\top}, \tilde{\mathbf{h}}_{\tau}^{n-1} \mathbf{W}_v^n{}^{\top} \\ & \mathbf{A}_{\tau,i,j}^n = \mathbf{q}_{\tau,i}^n{}^{\top} \mathbf{k}_{\tau,j}^n + \mathbf{q}_{\tau,i}^n{}^{\top} \mathbf{W}_{k,R}^n \mathbf{R}_{i-j} + u^{\top} \mathbf{k}_{\tau,j} + v^{\top} \mathbf{W}_{k,R}^n \mathbf{R}_{i-j} \\ & \mathbf{a}_{\tau}^n = \text{Masked-Softmax}(\mathbf{A}_{\tau}^n) \mathbf{v}_{\tau}^n \\ & \mathbf{o}_{\tau}^n = \text{LayerNorm}(\text{Linear}(\mathbf{a}_{\tau}^n) + \mathbf{h}_{\tau}^{n-1}) \\ & \mathbf{h}_{\tau}^n = \text{Positionwise-Feed-Forward}(\mathbf{o}_{\tau}^n) \end{aligned}$$