



Lecture 23

Expectation Maximization (EM)

ECEN5283
Computer Vision

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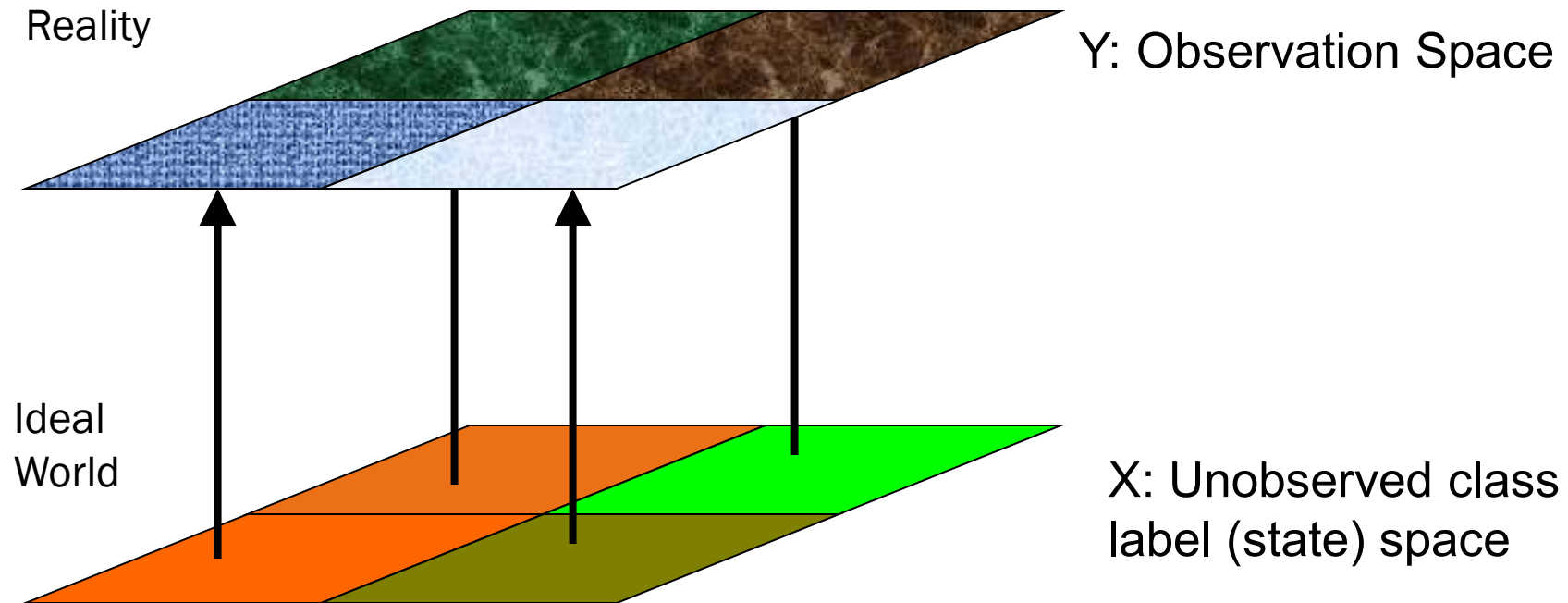
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Goals

To review the missing data problem and its two major issues

To introduce a soft-clustering algorithm, i.e., Expectation Maximization (EM) algorithm.

Missing Data Problem Restatement



Mapping $X \rightarrow Y$ loses the class label information.

Inference $Y \rightarrow X$ is needed.

Some Review of Probability Theory

Where do we start? $\alpha_i = p_X(x = i)$ $p_{Y|X}(y|x = i) = N(y|\mu_i, \Sigma_i)$
 (prior probability) (likelihood function)

Joint probability $p_{XY}(x, y) = p_{Y|X}(y|x)p_X(x)$

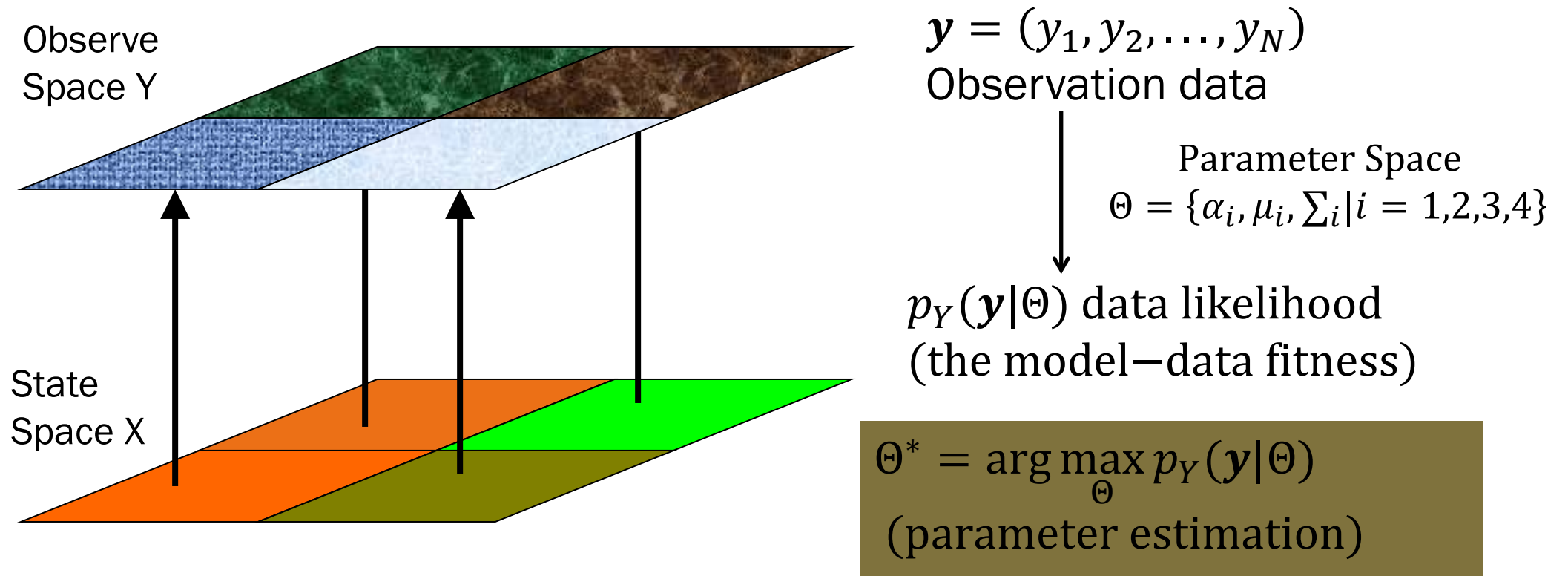
Bayes' Law of posteriori probability

$$p_{X|Y}(x|y) = \frac{p_{XY}(x, y)}{p_Y(y)} = \frac{p_{Y|X}(y|x)p_X(x)}{p_Y(y)}$$

Y: observation (e.g., symptoms)
X: label (e.g., diseases)

Marginalization probability $p_Y(y) = \sum_x p_{XY}(x, y) = \sum_x p_{Y|X}(y|x)p_X(x)$

Issue (1) Parameter Estimation



To find the parameter Θ that can best explain the current observation \mathbf{y} .

Formulation: Parameter Estimation

How does a tailor make a cloth?

- To make a cloth that fits best to the body

How to estimate the parameters Θ ?

- Estimating Θ that best fits the data set $\mathbf{y} = (y_1, y_2, \dots, y_N)$.

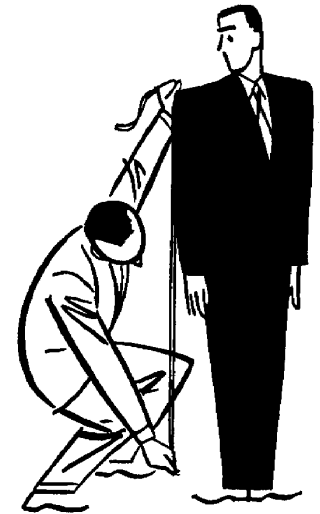
How to evaluate the fitness between Θ and \mathbf{y} ?

- The fitness between Θ (model) and \mathbf{y} (data) is reflected by the likelihood of \mathbf{y} given Θ . Therefore, parameter estimation is:

$$\Theta^* = \arg \max_{\Theta} p_Y(\mathbf{y}|\Theta) = \arg \max_{\Theta} \prod_{i=1}^N p_Y(y_i|\Theta) = \arg \max_{\Theta} \sum_{i=1}^N \log(p_Y(y_i|\Theta))$$

$$p_Y(\mathbf{y}|\Theta) = \prod_{i=1}^N p_Y(y_i|\Theta)$$

(independent assumption)



Issue (2) Data Classification

To classify data, we need to compute the probability of data sample y belonging to class x , i.e., the posterior probability $p(x|y)$, which is computed during parameter estimation.

$$\alpha_i = p_X(x = i)$$

(prior probability)

$$p_{Y|X}(y|x = i) = N(y|\mu_i, \Sigma_i)$$

(likelihood function)

$$p_{X|Y}(x|y) = \frac{p_{XY}(x, y)}{p_Y(y)} = \frac{p_{Y|X}(y|x)p_X(x)}{\sum_{i=1}^k p_{Y|X}(y|x = i)p_X(x = i)} \quad (\text{posterior probability})$$

(Bayes' law)

$$x^* = \arg_{x \in X} \max p_{X|Y}(x|y) \quad (\text{maximum a posteriori or MAP})$$

Data Classification Example

If we have **six samples** and **three classes**, the missing data indicates the class label for each pixel. Hopefully, the estimated missing data will be close to it.

$$\mathbf{I}^0 = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix}_{6 \times 3}$$

The true missing data

$$\mathbf{I} = \begin{pmatrix} 0.1 & 0.8 & 0.1 \\ 0.3 & 0.6 & 0.1 \\ 0.4 & 0.3 & 0.3 \\ 0.7 & 0.2 & 0.1 \\ 0.3 & 0.2 & 0.5 \\ 0.05 & 0.05 & 0.9 \end{pmatrix}_{6 \times 3}$$

The estimated missing data

$$x_l = \arg_{m \in \{1, \dots, g\}} \max \mathbf{I}(l, m)$$

EM Formulation: Likelihood Function

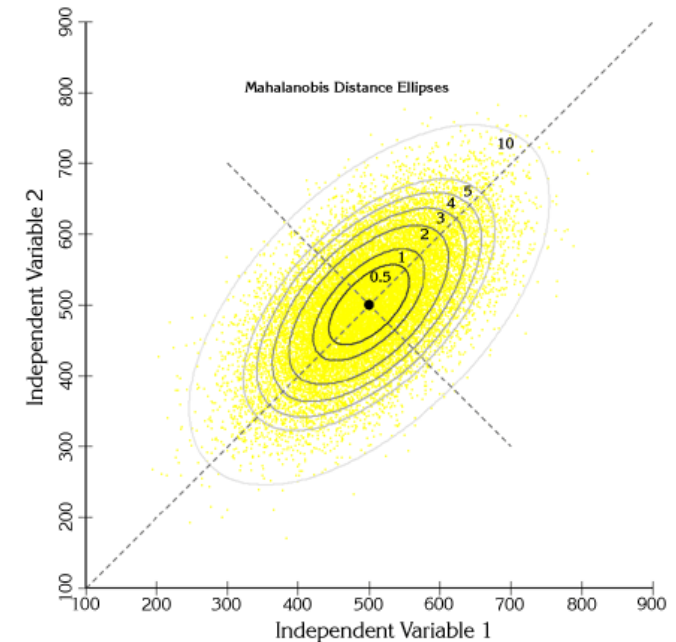
What is a likelihood function?

- The likelihood function indicates how likely a particular distribution is to produce an observed sample. It is like a ruler for the tailor.
- For cluster i , we can assume a d-dimensional Gaussian PDF as the likelihood function of data samples in that class that is defined by mean μ_i and covariance matrix Σ_i

$$p_{Y|X}(y|x=i) = N(y|\mu_i, \Sigma_i)$$

$$p_Y(y|\theta_i) = \frac{1}{(2\pi)^{d/2} \det(\Sigma_i)^{1/2}} \exp \left\{ -\frac{1}{2} (y - \mu_i)^T \Sigma_i^{-1} (y - \mu_i) \right\}$$

$\theta_i = \{\mu_i, \Sigma_i\}$



Mahalanobis Distance

EM Formulation: Two-Step Iteration

We use a two-step iteration to solve the missing data problem

- Initialize the parameters (it is like to initialize the centers in k-means)

$$\Theta = \{\alpha_i, \mu_i, \Sigma_i | i = 1, \dots, k\}$$

- Step 1: Estimate the missing data (x) in terms of the posterior probability of each data sample (y) (it is like to classify each data point in k-means.)

$$p_{X|Y}(x = i | y) \quad \{i = 1, \dots, k\}$$

(estimate the probability of each sample belonging to different classes)

- Step 2: From the estimated missing data, to obtain the maximum likelihood (ML) estimate of the parameters (it is like to update the centers in k-means)

$$\Theta^* = \arg \max_{\Theta} \log p_Y(y | \Theta)$$

(update the parameters to better fit the data and the model.)

EM Algorithm: E-step

Initialization: set $s = 0$ and

$$\Theta^0 = (\alpha_1^{(0)}, \alpha_2^{(0)}, \dots, \alpha_g^{(0)}, \theta_1^{(0)}, \theta_2^{(0)}, \dots, \theta_g^{(0)}).$$

Expectation (E-step):

$$\mathbf{I}(l, m) = \frac{\alpha_m^{(s)} p_Y(y_l | \theta_m^{(s)})}{\sum_{i=1}^k \alpha_i^{(s)} p_{Y|X}(y_l | \theta_i^{(s)})} = p_{X|Y}(x_l = m | y_l, \Theta^{(s)})$$

Posterior probability

$$p_{X|Y}(x = i | y) = \frac{p_{Y|X}(y | x) p_X(x)}{\sum_{i=1}^k p_{Y|X}(y | x = i) p_X(x = i)}$$
$$p_{Y|X}(y_l | \theta_m^{(s)}) = \frac{\exp\left\{-\frac{1}{2}(y_l - \mu_m)^T \Sigma_m^{-1}(y_l - \mu_m)\right\}}{(2\pi)^{d/2} \det(\Sigma_l)^{1/2}}$$

EM Algorithm: M-step

Maximization (M-step): $\Theta^* = \arg \max_{\Theta} \log p(\mathbf{y}|\Theta)$

$$\alpha_m^{(s+1)} = p_X(x) = \frac{1}{N} \sum_{l=1}^N p_{X|Y}(x_l = m | y_l, \Theta^{(s)})$$

$$\theta_m^{(s+1)} \left\{ \begin{array}{l} \mu_m^{(s+1)} = \frac{\sum_{l=1}^N y_l \cdot p_{X|Y}(x_l = m | y_l, \Theta^{(s)})}{\sum_{l=1}^N p_{X|Y}(x_l = m | y_l, \Theta^{(s)})} \\ \Sigma_m^{(s+1)} = \frac{\sum_{l=1}^N p_{X|Y}(x_l = m | y_l, \Theta^{(s)}) \{ (y_l - \mu_m^{(s)}) (y_l - \mu_m^{(s)})^T \}}{\sum_{l=1}^N p_{X|Y}(x_l = m | y_l, \Theta^{(s)})} \end{array} \right.$$