

# Computational Physics (PHYS6350)

Lecture 6: Numerical Integration: Part 1

- Basic methods for numerical integration (rectangle, trapezoid, Simpson)
- Adaptive quadratures
- Improper integrals

#### **February 2, 2023**

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**Course materials:** <a href="https://github.com/vlvovch/PHYS6350-ComputationalPhysics">https://github.com/vlvovch/PHYS6350-ComputationalPhysics</a>

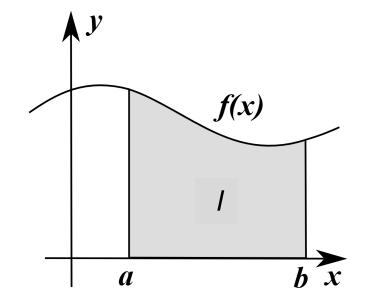
## **Numerical integration**

Generic problem: evaluate

$$I = \int_{a}^{b} f(x) dx$$

We need numerical integration when

- Cannot/difficult integrate analytically
- Only know the integrand f(x) at certain points



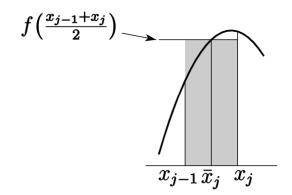
References: Chapter 5 of Computational Physics by Mark Newman

Chapter 4 of Numerical Recipes Third Edition by W.H. Press et al.

## Numerical integration: rectangular (midpoint) rule

Interpret the integral as area under the curve and approximate by a rectangle evaluated at midpoint

$$\int_{a}^{b} f(x) dx \approx (b - a) f\left(\frac{a + b}{2}\right)$$



Error (from Euler-McLaurin formula):

$$\int_{a}^{b} f(x)dx - (b-a)f\left(\frac{a+b}{2}\right) \approx \frac{(b-a)^{3}}{24}f''(a)$$

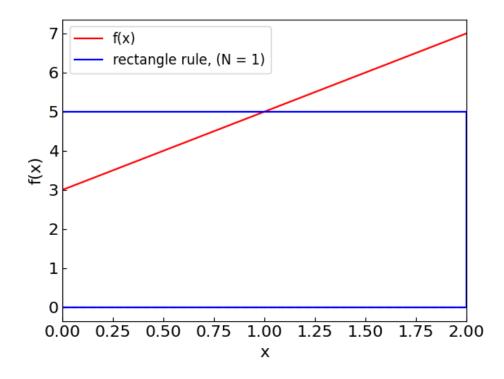
The rule is exact for the integration of linear functions

### Numerical integration: rectangular (midpoint) rule

Example:

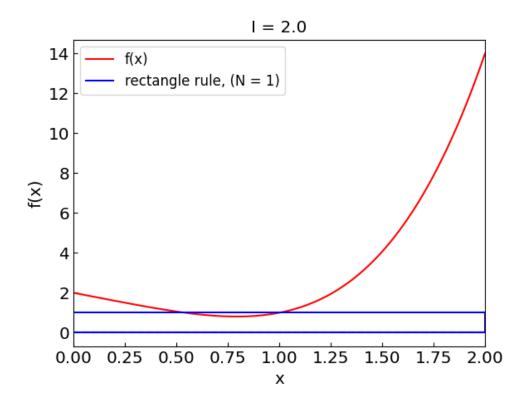
$$I = \int_0^2 2x + 3dx = 10$$

Although rectangle is a poor approximate of the line (which is a trapezoid here), the errors cancel out



## Numerical integration: rectangular (midpoint) rule

Another example: 
$$I = \int_0^2 x^4 - 2x + 2 = 6.4$$



Rectangle rule gives  $I_{rect} = 2$  which is way off

# Extended (composite) rectangular rule

Split the integration interval into N sub-intervals and apply the rectangle rule separately to each one

$$\int_0^2 x^4 - 2x + 2$$

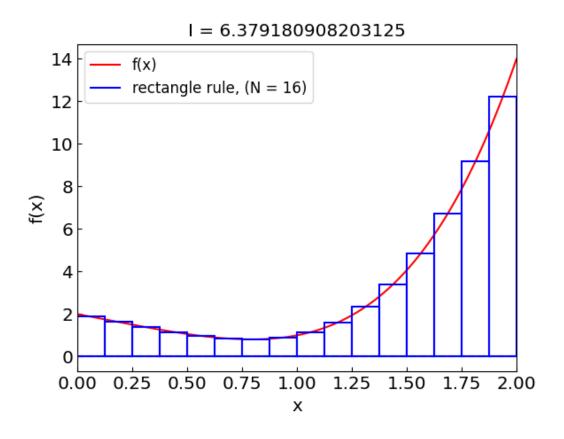
$$\int_{a}^{b} f(x) \approx h \sum_{k=1}^{N} f(x_{k}), \qquad k = 1, \dots, N$$

$$x_{k} = a + \frac{2k-1}{2}h.$$

$$h = (b-a)/N$$

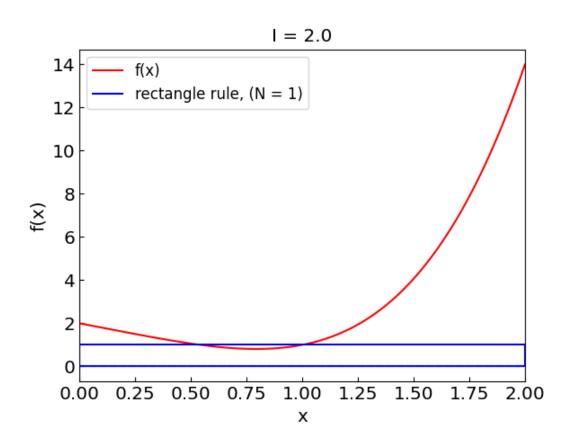
Error estimate:

$$I - I_{\text{rect}} = (b - a) \frac{h^2}{24} f''(a) + \mathcal{O}(h^4)$$



# Extended (composite) rectangular rule

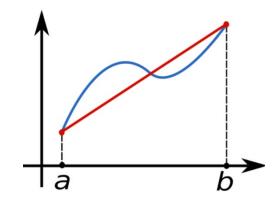
$$I = \int_0^2 x^4 - 2x + 2 = 6.4$$



### Numerical integration: trapezoidal rule

Approximate the integral by a trapezoid

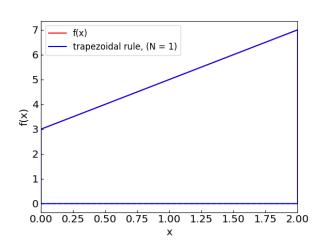
$$\int_{a}^{b} f(x) dx \approx (b - a) \frac{f(a) + f(b)}{2}$$



Error:

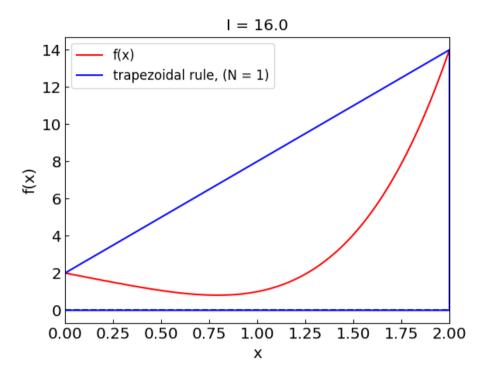
$$\int_{a}^{b} f(x)dx - (b-a)\frac{f(a) + f(b)}{2} \approx -\frac{(b-a)^{3}}{12}f''(a)$$

The rule is exact for the integration of linear functions



#### Numerical integration: trapezoidal rule

$$I = \int_0^2 x^4 - 2x + 2 = 6.4$$



Trapezoidal rule gives  $I_{\text{trap}}=16$ , way off in the opposite direction relative to rectangle rule

#### **Extended trapezoidal rule**

$$\int_{a}^{b} f(x) \approx h \sum_{k=0}^{N} \frac{f(x_{k}) + f(x_{k+1})}{2}, \qquad i = 0, \dots, N$$
$$x_{k} = a + kh.$$

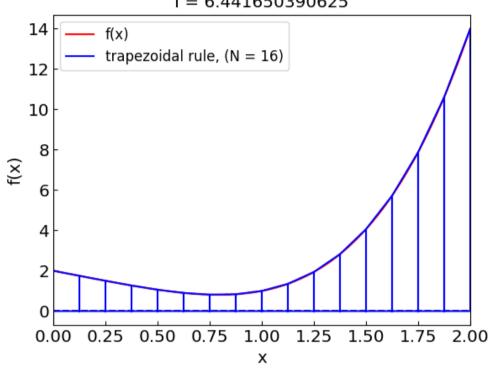
$$h = (b - a)/N$$

Error estimate:

$$I - I_{\text{trap}} = -(b - a)\frac{h^2}{12} f''(a) + \mathcal{O}(h^4)$$

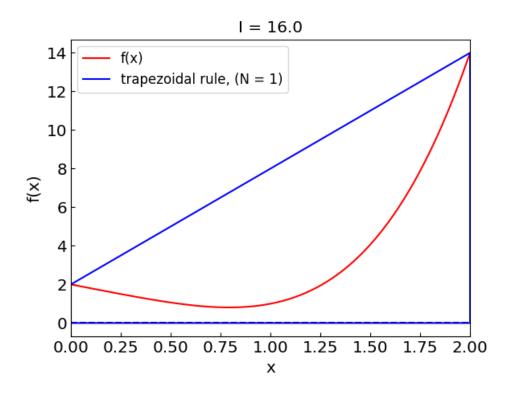
$$\int_0^2 x^4 - 2x + 2$$

= 6.441650390625



# Extended (composite) trapezoidal rule

$$I = \int_0^2 x^4 - 2x + 2 = 6.4$$

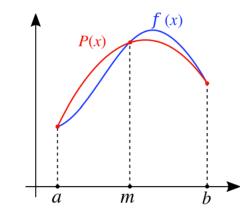


## Numerical integration: Simpson's rule

Recall the error estimates for rectangular and trapezoidal rules

$$I - I_{\text{rect}} = (b - a)\frac{h^2}{24} f''(a) + \mathcal{O}(h^4)$$

$$I - I_{\text{trap}} = -(b - a)\frac{h^2}{12} f''(a) + \mathcal{O}(h^4)$$



Combine them to eliminate  $O(h^2)$  error:

$$I_S = \frac{2I_{\text{rect}} + I_{\text{trap}}}{3}$$

i.e.

$$\int_{a}^{b} f(x) dx \approx \frac{(b-a)}{6} \left[ f(a) + 4f\left(\frac{a+b}{2}\right) + f(b) \right]$$

Equivalent way: replace the integrand by parabolic interpolation

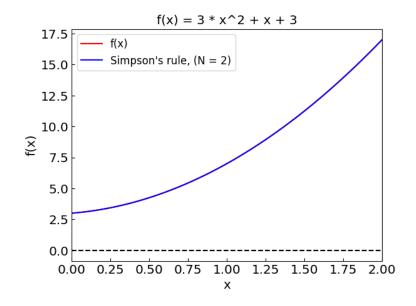
#### Numerical integration: Simpson's rule

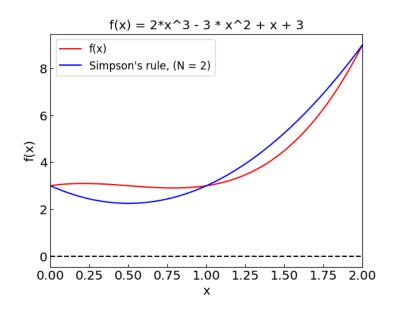
$$\int_{a}^{b} f(x) dx \approx \frac{(b-a)}{6} \left[ f(a) + 4f\left(\frac{a+b}{2}\right) + f(b) \right]$$

The error for the Simpson's rule is

$$I - I_S = C h^4 + \mathcal{O}(h^6)$$

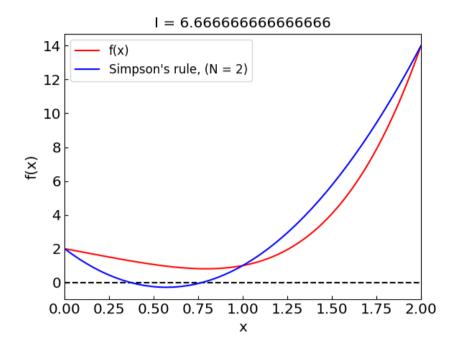
The method is exact for polynomials up to third order





#### Numerical integration: Simpson's rule

$$I = \int_0^2 x^4 - 2x + 2 = 6.4$$



Simpson's rule gives  $I_{trap} = 6.66$  using three points, which is already not too bad!

#### **Extended Simpson's rule**

$$\int_{a}^{b} f(x) \approx \frac{h}{3} \left[ f(x_0) + 4 \sum_{k=1}^{N/2} f(x_{2k-1}) + 2 \sum_{k=1}^{N/2-1} f(x_{2k}) + f(x_N) \right], \qquad i = 0, \dots, N$$

$$\int_{0}^{2} x^4 - 2x + 2 \int_{0}^{2} x$$

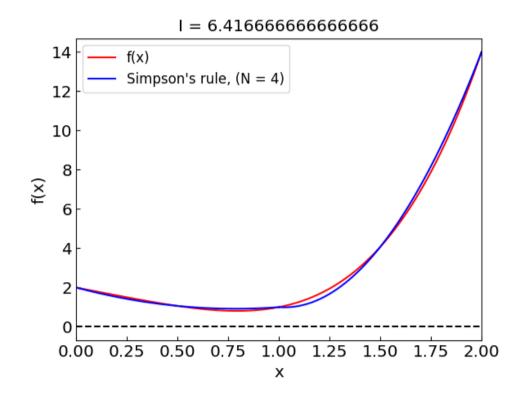
$$i = 0, \dots, N$$
 
$$\int_0^2 x^4 - 2x + 2x$$

$$h = (b - a)/N$$

N must be even!

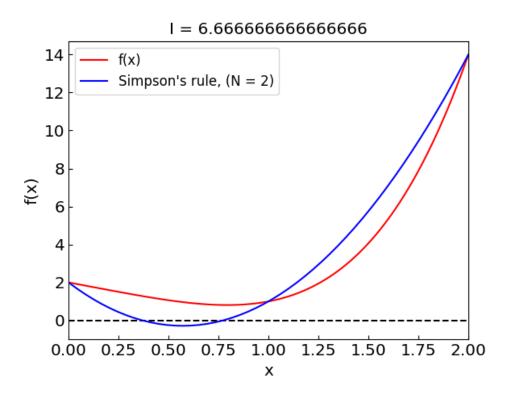
Error estimate:

$$I - I_S = C h^4 + \mathcal{O}(h^6)$$



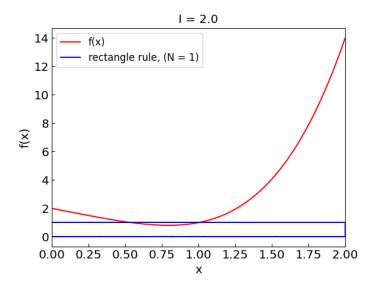
# **Extended Simpson's rule**

$$I = \int_0^2 x^4 - 2x + 2 = 6.4$$

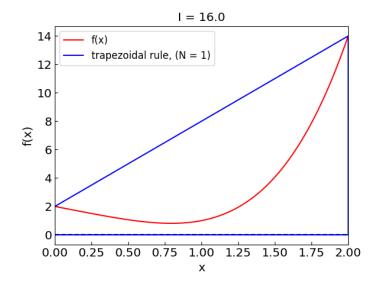


## **Comparing the methods**

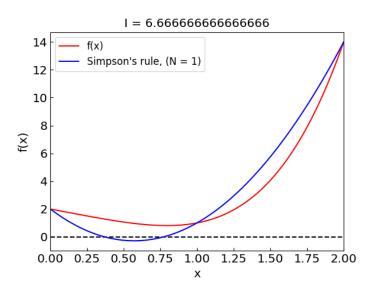
#### Rectangle



#### **Trapezoid**



#### **Simpson**



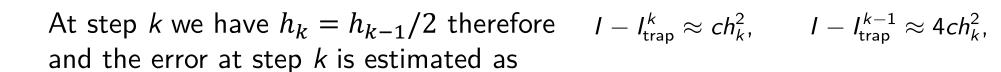
## **Adaptive quadratures**

We would like to control the error in our calculation

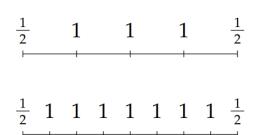
This can be achieved by doubling the number of subintervals and keeping track of the error estimate

Recall that in the rectangle/trapezoidal rule the error is proportional to  $h^2$ 

$$I - I_{\rm trap} \approx ch^2$$



$$\varepsilon_k \simeq (I_{\mathsf{trap}}^k - I_{\mathsf{trap}}^{k-1})/3$$



#### Adaptive trapezoidal rule

```
Trapezoidal rule for numerical integration with adaptive step
*f trapezoidal rule adaptive(f, a, b, nst = 1, tol = 1.e-8, max iterations = 16):
  Iprev = 0.
  n = nst
  Iprev = trapezoidal_rule(f, a, b, n)
  print("Iteration: {0:5}, I = {1:20.15f}".format(1, Iprev))
  for k in range(1, max iterations):
      n *= 2
      Inew = trapezoidal_rule(f, a, b, n)
      ek = (Inew - Iprev) / 3.
      print("Iteration: \{0:5\}, I = \{1:20.15f\}, error estimate = \{2:10.15f\}".format(k+1, Inew, ek))
      if (abs(ek) < tol):</pre>
          return Inew
                      Computing the integral of x^4 - 2x + 2 over the interval (0.0, 2.0) using adaptive trapezoidal rule
      Iprev = Inew
                      Iteration:
                                     1, I = 16.000000000000000
                       Iteration:
                                     2, I =
                                              print("Failed to achi
                       Iteration:
                                     3, I =
                                              7.06250000000000, error estimate = -0.6458333333333333
  return Inew
                      Iteration:
                                    4, I =
                                              6.566406250000000, error estimate = -0.165364583333333
                      Iteration:
                                    5, I =
                                              6.441650390625000, error estimate = -0.041585286458333
                      Iteration:
                                    6, I =
                                              6.410415649414062, error estimate = -0.010411580403646
                      Iteration:
                                    7, I =
                                              6.402604103088379, error estimate = -0.002603848775228
                                    8, I =
                      Iteration:
                                              6.400651037693024, error estimate = -0.000651021798452
                                   9, I =
                      Iteration:
                                              6.400162760168314, error estimate = -0.000162759174903
                      Iteration:
                                    10, I =
                                              6.400040690088645, error estimate = -0.000040690026556
                                    11, I =
                       Iteration:
                                              6.400010172525072, error estimate = -0.000010172521191
                                    12, I =
                      Iteration:
                                              6.400002543131352, error estimate = -0.000002543131240
                                    13, I =
                       Iteration:
                                              6.400000635782950, error estimate = -0.000000635782801
                                    14, I =
                                              6.400000158945742, error estimate = -0.000000158945736
                       Iteration:
                      Iteration:
                                    15, I =
                                              6.40000039736406, error estimate = -0.000000039736446
                                    16, I =
                      Iteration:
                                              6.40000009934106, error estimate = -0.000000009934100
```

#### **Adaptive Simpson rule**

For Simpson's rule  $\varepsilon_k \simeq (I_S^k - I_S^{k-1})/15$  (understand why 15 and not 3?)

```
# Simpson's rule for numerical integration with adaptive step
def simpson rule adaptive(f, a, b, nst = 2, tol = 1.e-8, max iterations = 16):
   Iprev = 0.
   n = nst
   Iprev = simpson rule(f, a, b, n)
   print("Iteration: {0:5}, I = {1:20.15f}".format(1, Iprev))
   for k in range(1, max iterations):
       n *= 2
       Inew = simpson rule(f, a, b, n)
       ek = (Inew - Iprev) / 15.
       print("Iteration: \{0:5\}, I = \{1:20.15f\}, error estimate = \{2:10.15f\}".format(k+1, Inew, ek))
       if (abs(ek) < tol):</pre>
           return Inew
       Iprev = Inew
                      Computing the integral of x^4 - 2x + 2 over the interval (0.0, 2.0) using adaptive Simpson's rule
   print("Failed to ac Iteration:
                                    1, I =
                                              6.66666666666666
   return Inew
                      Iteration:
                                    2, I =
                                              Iteration:
                                    3, I =
                                              6.4010416666666666, error estimate = -0.001041666666667
                      Iteration:
                                    4, I =
                                              6.400065104166666, error estimate = -0.000065104166667
                      Iteration:
                                    5, I =
                                              6.400004069010416, error estimate = -0.000004069010417
                      Iteration:
                                    6, I =
                                              6.400000254313150, error estimate = -0.000000254313151
                      Iteration:
                                    7, I =
                                              6.400000015894571, error estimate = -0.000000015894572
                      Iteration:
                                     8, I =
                                              6.40000000993410, error estimate = -0.000000000993411
```

## Adaptive quadratures: Romberg method

Recall that we obtained error estimate for trapezoidal method at step k

$$\varepsilon_k \simeq (I_{\mathsf{trap}}^k - I_{\mathsf{trap}}^{k-1})/3$$

On the other hand, by definition,  $\varepsilon_k = I - I_{\text{trap}}^k$ 

Therefore, we can improve our estimate of the integral as

$$I = R_{k,1} = I_{\mathsf{trap}}^k + \frac{I_{\mathsf{trap}}^k - I_{\mathsf{trap}}^{k-1}}{3} + \mathcal{O}(h^4)$$

Romberg method: continue this procedure iteratively

$$R_{k,m+1} = R_{k,m} + \frac{R_{k,m} - R_{k-1,m}}{4^m - 1}$$
.

until the desired accuracy is reached

#### Romberg method

```
def romberg(
   f,
   a,
   b,
   accuracy=1e-8,
   max order=10
):
   R = np.zeros((max order, max order))
   h = (b - a) / 2.
   R[0, 0] = h * (f(a) + f(b)) # The initial trapezoidal rule
   for n in range(1, max order):
      trapezoid = 0.0
      for j in range(2**(n-1)):
          trapezoid += f(a + (2*j+1)*h)
       R[n, 0] = 0.5 * R[n-1, 0] + h * trapezoid # The trapezoidal rule
      1 = 1
      # The Romberg iterations
      for m in range(1, n+1):
          1 *= 4
          R[n, m] = (1 * R[n, m-1] - R[n-1, m-1]) / (1-1)
       print("Iteration: \{0:5\}, I = \{1:20.15f\}, error estimate = \{2:10.15f\}".format(n, R[n, m], abs(R[n, m] - R[n-1, m-1])))
      if abs(R[n, m] - R[n-1, m-1]) < accuracy:
          return R[n, m]
       h /= 2.
   print("Romberg method did not converge to required accuracy")
   return R[-1, -1]
Computing the integral of x^4 - 2x + 2 over the interval (0.0, 2.0) using Romberg method
Iteration:
             3, I =
                     6.400000000000000, error estimate = 0.000000000000000
```

#### Improper integrals

Contain integrable singularities (typically at endpoints)

$$\int_0^1 \frac{1}{\sqrt{x}} dx = 2\sqrt{x} \Big|_0^1 = 2$$

• (Semi-)infinite integration range

$$\int_0^\infty e^{-x} dx = 1$$

$$\int_{-\infty}^{\infty} e^{-x^2} dx = \sqrt{\pi}$$

#### Improper integrals: Singularities at endpoints

• Even though if the singularities at integration endpoints are integrable trapezoidal, Simpson, etc. method will fail because they evaluate the integrand at endpoints

$$\int_0^1 \frac{1}{\sqrt{x}} dx = 2\sqrt{x} \Big|_0^1 = 2$$

```
def fsing1(x):
    return 1./np.sqrt(x)

trapezoidal_rule(fsing1,0.,1.,10)

/tmp/ipykernel_31240/847063500.py:2: RuntimeWarning: divide by zero encountered in double_scalars
    return 1./np.sqrt(x)
```

• **Solution:** use method that does use the endpoints (e.g. rectangle rule)

#### Improper integrals: Singularities at endpoints

$$\int_0^1 \frac{1}{\sqrt{x}} dx = 2\sqrt{x} \Big|_0^1 = 2$$

print('Using rectangle rule to evaluate \int 0^1 1/\sqrt{x} dx')

```
def fsing1(x):
    return 1./np.sqrt(x)
```

```
nst = 1
rectangle rule adaptive(fsing1,0.,1.,1,1.e-3,20)
Using rectangle rule to evaluate \int 0^1 1/\sqrt{x} dx
Iteration:
              1, I =
                       1.414213562373095
Iteration:
            2, I =
                       1.577350269189626, error estimate = 0.054378902272177
Iteration:
            3, I =
                       1.698844079579673, error estimate = 0.040497936796682
Iteration:
             4, I =
                       1.786461001734842, error estimate = 0.029205640718390
Iteration:
             5, I =
                       1.848856684639738, error estimate = 0.020798560968299
Iteration:
             6, I =
                       1.893088359706383, error estimate = 0.014743891688882
             7, I =
                       1.924392755699513, error estimate = 0.010434798664376
Iteration:
Iteration:
             8, I =
                       1.946535279970520, error estimate = 0.007380841423669
Iteration:
             9, I =
                        1.962194152677056, error estimate = 0.005219624235512
             10, I =
                        1.973267083679453, error estimate = 0.003690977000799
Iteration:
Iteration:
             11, I =
                        1.981096937261288, error estimate = 0.002609951193945
             12, I =
                        1.986633507070365, error estimate = 0.001845523269692
Iteration:
Iteration:
             13, I =
                       1.990548459938304, error estimate = 0.001304984289313
Iteration:
             14, I =
                        1.993316751362098, error estimate = 0.000922763807931
```

# Improper integrals: (Semi-)infinite intervals

**Solution:** map to a finite interval [e.g. (0,1)] by a change of variables

• Semi-infinite:

$$\int_{a}^{\infty} f(x)dx \qquad \qquad x = a + \frac{t}{1 - t} \qquad \qquad \int_{a}^{\infty} f(x)dx = \int_{0}^{1} f\left(a + \frac{t}{1 - t}\right) \frac{dt}{1 - t^{2}} = \int_{0}^{1} g(t)dt$$

• Infinite:

$$\int_{-\infty}^{\infty} f(x)dx \qquad \qquad x = \frac{t}{1 - t^2} \qquad \qquad \int_{-\infty}^{\infty} f(x)dx = \int_{-1}^{1} f\left(\frac{t}{1 - t^2}\right) \frac{1 + t^2}{(1 - t^2)^2} dt = \int_{-1}^{1} g(t)dt$$

Then apply a standard method (e.g. rectangle rule to avoid endpoint singularities) to g(t)

NB: Other options for variable change are possible

#### Improper integrals: Semi-infinite intervals

$$\int_0^\infty e^{-x} dx = 1$$

```
def fexp(x):
    return np.exp(-x)
def g(t, f, a = 0.):
    return f(a + t / (1. - t)) / (1. - t)**2
a = 0.
def frect(x):
    return g(x, fexp, a)
print('Using change of variable and the rectangle rule to evaluate \int 0^\infty \exp(-x) dx')
rectangle rule adaptive(frect, 0., 1., 1, 1.e-6, 20)
Using change of variable and the rectangle rule to evaluate \int 0^\infty \exp(-x) dx
Iteration:
              1, I = 1.471517764685769
              2, I = 1.035213267452946, error estimate = -0.145434832410941
Iteration:
             3, I =
                       0.984670579385046, error estimate = -0.016847562689300
Iteration:
Iteration:
             4, I =
                       1.001784913275257, error estimate = 0.005704777963404
             5, I =
Iteration:
                       1.000155714391028, error estimate = -0.000543066294743
             6, I =
Iteration:
                       1.000040642390661, error estimate = -0.000038357333456
Iteration:
             7, I = 1.000010172618432, error estimate = -0.000010156590743
Iteration:
              8, I =
                       1.000002543136036, error estimate = -0.000002543160799
              9, I =
                       1.000000635783161, error estimate = -0.000000635784292
Iteration:
```

#### Improper integrals: Infinite intervals

$$\int_{-\infty}^{\infty} e^{-x^2} dx = \sqrt{\pi} = 1.772454 \dots$$

```
def fexp2(x):
    return np.exp(-x**2)
def g2(t, f):
    return f(t / (1. - t**2)) * (1.+t**2) / (1. - t**2)**2
def frect2(x):
    return g2(x, fexp2)
print('Using change of variable and the rectangle rule to evaluate \int {- \int {- \sinh ty}^{-x^2} dx'}
rectangle rule adaptive(frect2,-1.,1.,1,1.e-6,20)
print('Expected value: \sqrt{\pi} =', np.sqrt(np.pi))
Using change of variable and the rectangle rule to evaluate \int {-\sinh ty}^{\sin ty} \exp(-x^2) dx
Iteration:
              1, I =
                        2.0000000000000000
Iteration:
              2, I = 2.849690615244243, error estimate = 0.283230205081414
Iteration:
              3, I = 1.557994553948652, error estimate = -0.430565353765197
              4, I = 1.808005109208286, error estimate = 0.083336851753211
Iteration:
Iteration:
              5, I = 1.770118560572371, error estimate = -0.012628849545305
              6, I = 1.772492101507391, error estimate = 0.000791180311673
Iteration:
Iteration:
              7, I = 1.772453880915058, error estimate = -0.000012740197444
Iteration:
              8, I =
                        1.772453850905505, error estimate = -0.000000010003185
Expected value: \sqrt{\pi} = 1.7724538509055159
```