

**Literature:** Weyl 1946 Classical groups, pages 177–229;

Muirhead 1982, Aspects of multivariate statistical theory, chapter 2, pages 50–72;

Katz, Sarnak, Chapter 5, pages 107–121;

## 1.1 $U(n)$ .

For a matrix  $A$ , denote

$$\delta A = A^{-1} dA,$$

whatever this means.

For  $A \in U(n)$ , represent

$$A = U \Lambda U^*, \quad (1.1)$$

where

$$\Lambda = \text{diag}(e^{i\varphi_1}, \dots, e^{i\varphi_n}), \quad 0 < \varphi_1 < \dots < \varphi_n < 2\pi, \quad (1.2)$$

and  $H^* \in U(n)$  is fixed by the condition that the in every column, the first (from up down over rows) non-zero column is positive. (Otherwise representation (1.1) is not unique,  $U \rightarrow UD$  with diagonal  $D$ ). Furthermore,  $U$  is parametrized by  $n^2 - n = l$  real parameters,  $\Lambda$  is parametrized by  $n$  parameters. The representation (1.1) is unique for  $A \in U(n)$  with all different eigenvalues, and hence we can consider it as a change of variables. Now, since  $UU^* = \mathbf{1}$ , and hence  $\delta U = -\delta U^*$  is skew-symmetric, we obtain by formal manipulations

$$\delta B := U^{-1} \delta A U = (\Lambda^{-1} \delta U \Lambda - \delta U) + \delta \Lambda. \quad (1.3)$$

From (1.3), considering separately diagonal and off-diagonal terms,

$$\begin{aligned} \delta b_{jj} &= i d\varphi_j, \\ \delta b_{jk} &= (e^{i(\varphi_k - \varphi_j)} - 1) \delta u_{jk}, \quad j \neq k. \end{aligned}$$

Now, after all matrix multiplications, we write  $\delta B$  in a row of  $n^2$  real elements:

$$\delta b_{11}, \dots, \delta b_{nn}, \delta b_{12}, \delta b_{21}, \dots, \delta b_{n-1,n}, \delta b_{n,n-1},$$

and take a (wedge) product of them (as of differentials; we obtain an  $n^2$  dimensional differential). Writing  $\delta B$  as a (scalar rather than matrix)  $n^2$  dimensional differential, and ignoring sign,

$$\delta B = \prod_{j=1}^n d\varphi_j \prod_{j \neq k} (e^{i\varphi_j} - e^{i\varphi_k}) \delta b_{j,k} = \prod_{j \neq k} (e^{i\varphi_j} - e^{i\varphi_k}) \prod_{j=1}^n d\varphi_j d\omega_U.$$

Now, when we integrate over  $U(n)$  ( or average over group) a function that depends only on eigenvalues, first of all we integrate only over matrices  $A$  with all distinct eigenvalues (other  $A$  form a sub-manifold of smaller dimension, and hence do not contribute in the integral)

$$\begin{aligned} \int_{U(n)} f(A) d\text{Haar} &= \int_{U(n)} f(A) A^{-1} dA = \int_{U(n)} f(A) \delta A = \int_{U(n)} f(A) \delta B = \\ &= \int_{U(n)} f(\varphi_1, \dots, \varphi_n) \prod_{j \neq k} (e^{i\varphi_j} - e^{i\varphi_k}) \prod_{j=1}^n d\varphi_j d\omega_U = \\ &= \left( \frac{1}{n!} \int_{[0, 2\pi]^n} f(\varphi_1, \dots, \varphi_n) \prod_{j \neq k} |e^{i\varphi_j} - e^{i\varphi_k}| \prod_{j=1}^n d\varphi_j \right) \cdot \text{Vol}(U) \end{aligned}$$

where we separated contribution in the integral coming from  $\varphi_j$ , and from  $U$ . The factor  $n!$  appeared since we changed integral from over  $0 < \varphi_1 < \dots < \varphi_n < 2\pi$  to over  $\varphi_j \in [0, 2\pi]$ . To have it normalized to 1, probably when we integrate over  $d\varphi$  over  $[0, 2\pi]$ , it is better to divide by  $2\pi$ . However, Katz Sarnak, chapter 5, divide by  $2\pi$  not only in the case  $U(n)$ , when integrate over  $[0, 2\pi]$ , but also in the cases  $O(2n)$ , when they integrate over  $[0, \pi]$ , but still divide by  $2\pi$ . Furthermore, normalizing, we need to divide by analogous expression with  $f = 1$ . In that way we get rid of  $Vol(U)$ .

$$\int_{U(n)} f(A) dHaar = \left( \frac{1}{n!} \int_{[0, 2\pi]^n} f(\varphi_1, \dots, \varphi_n) \prod_{j \neq k} |e^{i\varphi_j} - e^{i\varphi_k}| \prod_{j=1}^n \frac{d\varphi_j}{2\pi} \right). \quad (1.4)$$

## 1.2 $O^+(2n)$ .

We will take  $n = 2$ , so we consider  $O^+(4)$ . Here (1.1) and (1.3) still hold,

$$A = U\Lambda U^*, \quad \delta B := U^{-1} \delta A U = (\Lambda^{-1} \delta U \Lambda - \delta U) + \delta \Lambda,$$

but  $\Lambda$  changes: instead of (1.2), we have

$$\Lambda = \begin{bmatrix} \begin{bmatrix} \cos \varphi_1 & -\sin \varphi_1 \\ \sin \varphi_1 & \cos \varphi_1 \end{bmatrix} & 0 \\ 0 & \begin{bmatrix} \cos \varphi_2 & -\sin \varphi_2 \\ \sin \varphi_2 & \cos \varphi_2 \end{bmatrix} \end{bmatrix}, \quad 0 < \varphi_1 < \varphi_2 < \pi. \quad (1.5)$$

Again,  $U$  should be fixed somehow to ensure uniqueness. It is parametrized by

$$\frac{2n(2n-1)}{2} - n = 2n(n-1)$$

parameters.  $\Lambda$  is parametrized by  $n$  real parameters. What is  $\delta U$ ? It is a skew-symmetric matrix, parametrized by low-diagonal elements, whose are  $2n(2n-1)/2$ , where we need to subtract  $n$ , since we fixed somehow  $U$ . We have

$$\delta U = \begin{bmatrix} \begin{bmatrix} 0 & -\delta u_{21} \\ \delta u_{21} & 0 \end{bmatrix} & \begin{bmatrix} -\delta u_{31} & -\delta u_{41} \\ -\delta u_{32} & -\delta u_{42} \end{bmatrix} \\ \begin{bmatrix} \delta u_{31} & \delta u_{32} \\ \delta u_{41} & \delta u_{42} \end{bmatrix} & \begin{bmatrix} 0 & -\delta u_{43} \\ \delta u_{43} & 0 \end{bmatrix} \end{bmatrix}, \quad \text{where now the scalar meaning is } \delta U = \prod_{j>k} \delta u_{jk}.$$

What is  $\Lambda^{-1} \delta U \Lambda$ ? But first, what is

$$\delta \Lambda = \Lambda^{-1} d\Lambda = \begin{bmatrix} \begin{bmatrix} 0 & -d\varphi_1 \\ d\varphi_1 & 0 \end{bmatrix} & 0 \\ 0 & \begin{bmatrix} 0 & -d\varphi_2 \\ d\varphi_2 & 0 \end{bmatrix} \end{bmatrix}, \quad \text{with the scalar meaning } \delta \Lambda = d\varphi_1 d\varphi_2.$$

Second, diagonal block terms in  $\Lambda^{-1} \delta U \Lambda$  are conjugated by the same  $\varphi$ :

$$\begin{bmatrix} \cos \varphi_1 & \sin \varphi_1 \\ -\sin \varphi_1 & \cos \varphi_1 \end{bmatrix} \begin{bmatrix} 0 & -\delta u_{21} \\ \delta u_{21} & 0 \end{bmatrix} \begin{bmatrix} \cos \varphi_1 & -\sin \varphi_1 \\ \sin \varphi_1 & \cos \varphi_1 \end{bmatrix} = \begin{bmatrix} 0 & -\delta u_{21} \\ \delta u_{21} & 0 \end{bmatrix}, \quad \text{with meaning } \delta_{21}.$$

Third, off-diagonal block terms in  $\Delta^{-1} \delta U \Delta$  are conjugated by different  $\varphi$  :

$$\begin{bmatrix} \cos \varphi_2 & \sin \varphi_2 \\ -\sin \varphi_2 & \cos \varphi_2 \end{bmatrix} \begin{bmatrix} \delta u_{31} & \delta u_{32} \\ \delta u_{41} & \delta u_{42} \end{bmatrix} \begin{bmatrix} \cos \varphi_1 & -\sin \varphi_1 \\ \sin \varphi_1 & \cos \varphi_1 \end{bmatrix} - \begin{bmatrix} \delta u_{31} & \delta u_{32} \\ \delta u_{41} & \delta u_{42} \end{bmatrix} =: \begin{bmatrix} \delta v_1 & \delta v_2 \\ \delta v_3 & \delta v_4 \end{bmatrix}. \quad (1.6)$$

The scalar meaning of  $\begin{bmatrix} \delta v_1 & \delta v_2 \\ \delta v_3 & \delta v_4 \end{bmatrix}$  itself is just the (wedge) product of all the elements:  $\delta v_1 \delta v_2 \delta v_3 \delta v_4$ .

Formula (1.6) can be rewritten, elementwise, as (we denote for shortness  $c = \cos, s = \sin$ )

$$\begin{bmatrix} \begin{bmatrix} c_1 c_2 - 1 & s_1 c_2 \\ -s_1 c_2 & c_1 c_2 - 1 \end{bmatrix} & \begin{bmatrix} c_1 s_2 & s_1 s_2 \\ -s_1 s_2 & c_1 s_2 \end{bmatrix} \\ \begin{bmatrix} -c_1 s_2 & -s_1 s_2 \\ s_1 s_2 & -c_1 s_2 \end{bmatrix} & \begin{bmatrix} c_1 c_2 - 1 & s_1 c_2 \\ -s_1 c_2 & c_1 c_2 - 1 \end{bmatrix} \end{bmatrix} \cdot \begin{bmatrix} \delta u_{31} \\ \delta u_{32} \\ \delta u_{41} \\ \delta u_{42} \end{bmatrix}.$$

We need to take a covariant product of those differential forms, or, equivalently, take the determinant of the matrix, which equals

$$\det = 4(\cos \varphi_1 - \cos \varphi_2)^2.$$

Hence, the contribution from off-diagonal blocks are

$$4(\cos \varphi_j - \cos \varphi_k)^2 \prod \delta u_{...},$$

and the contribution from each diagonal block is

$$\delta u_{...}.$$

Finally,

$$\begin{aligned} \int_{O^+(2n)} f(A) dH_{aar} &= \int_{O^+(2n)} f(A) \delta A = \int_{O^+(2n)} f(A) \delta B = \\ &= \left( \frac{1}{n!} \int_{[0, \pi]^n} f(\varphi_1, \dots, \varphi_n) \prod_{j < k} 4(\cos \varphi_j - \cos \varphi_k)^2 \prod_j d\varphi_j \right) \cdot Vol(U). \end{aligned}$$

or, cheating with constant, using mathematical packages to check the correct constant for the first several  $n$ ,

$$\int_{O^+(2n)} f(A) dH_{aar} = \frac{2}{n!} \int_{[0, \pi]^n} f(\varphi_1, \dots, \varphi_n) \prod_{j < k} 4(\cos \varphi_j - \cos \varphi_k)^2 \prod_j \frac{d\varphi_j}{2\pi}.$$

### 1.3 $O^-(2n+2)$ .

In this case there are 1, -1 among eigenvalues. Let again  $n = 2$ . Denote by

$$T = \begin{bmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{bmatrix}$$

the block matrix. Then  $\Lambda$  can be parametrized in the form

$$\Lambda = \begin{pmatrix} T_1 & 0 & 0 \\ 0 & T_2 & 0 \\ 0 & 0 & \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \end{pmatrix}, \quad 0 < \varphi_1 < \varphi_2 < \pi.$$

What changes in our fundamental relation (1.3)?

$$\delta B = U^{-1} \delta A U = (\Lambda^{-1} \delta U \Lambda - \delta U) + \delta \Lambda.$$

We have

$$\delta U = \begin{bmatrix} \begin{bmatrix} 0 & -\delta u_{21} \\ \delta u_{21} & 0 \end{bmatrix} & \begin{bmatrix} -\delta u_{31} & -\delta u_{41} \\ -\delta u_{32} & -\delta u_{42} \end{bmatrix} & \begin{bmatrix} -\delta u_{51} & -\delta u_{61} \\ -\delta u_{52} & -\delta u_{62} \end{bmatrix} \\ \begin{bmatrix} \delta u_{31} & \delta u_{32} \\ \delta u_{41} & \delta u_{42} \end{bmatrix} & \begin{bmatrix} 0 & -\delta u_{43} \\ \delta u_{43} & 0 \end{bmatrix} & \begin{bmatrix} -\delta u_{53} & -\delta u_{63} \\ -\delta u_{54} & -\delta u_{64} \end{bmatrix} \\ \begin{bmatrix} \delta u_{51} & \delta u_{52} \\ \delta u_{61} & \delta u_{62} \end{bmatrix} & \begin{bmatrix} \delta u_{53} & \delta u_{54} \\ \delta u_{63} & \delta u_{64} \end{bmatrix} & \begin{bmatrix} 0 & -\delta u_{65} \\ \delta u_{65} & 0 \end{bmatrix} \end{bmatrix},$$

where now the scalar meaning is  $\delta U = \prod_{j>k} \delta u_{jk}$ . New pieces comparing to the previous case are now lying on the last block row (i.e., in last 2 rows).

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} \delta u_{51} & \delta u_{52} \\ \delta u_{61} & \delta u_{62} \end{bmatrix} \begin{bmatrix} c_1 & -s_1 \\ s_1 & c_1 \end{bmatrix} - \begin{bmatrix} \delta u_{51} & \delta u_{52} \\ \delta u_{61} & \delta u_{62} \end{bmatrix},$$

and the latter can be written line-by-line in the form of two decomposed relations, for  $\delta_{51}$ ,  $\delta_{52}$ , and distinctively for  $\delta_{61}$ ,  $\delta_{62}$ . We have

$$\begin{pmatrix} c_1 - 1 & s_1 \\ -s_1 & c_1 - 1 \end{pmatrix} \begin{pmatrix} \delta u_{51} \\ \delta u_{52} \end{pmatrix}, \quad \begin{pmatrix} c_1 + 1 & s_1 \\ -s_1 & c_1 + 1 \end{pmatrix} \begin{pmatrix} \delta u_{61} \\ \delta u_{62} \end{pmatrix}$$

and the determinant equals

$$(2 - 2 \cos \varphi_1)(2 + 2 \cos \varphi_1) = 4 \sin^2 \varphi_1.$$

Finally,

$$\begin{aligned} \int_{O^-(2n+2)} f(A) dH_{aar} &= \int_{O^-(2n+2)} f(A) \delta A = \int_{O^-(2n+2)} f(A) \delta B = \\ &= \left( \frac{1}{n!} \int_{[0, \pi]^n} f(1, -1, \varphi_1, \dots, \varphi_n) \prod_{j < k} 4(\cos \varphi_j - \cos \varphi_k)^2 \prod_j 4 \sin^2 \varphi_j \prod_j d\varphi_j \right) \cdot Vol(U). \end{aligned}$$

and, cheating with constant,

$$\begin{aligned} \int_{O^-(2n+2)} f(A) dH_{aar} &= \int_{O^-(2n+2)} f(A) \delta A = \int_{O^-(2n+2)} f(A) \delta B = \\ &= \left( \frac{1}{n!} \int_{[0, \pi]^n} f(1, -1, \varphi_1, \dots, \varphi_n) \prod_{j < k} 4(\cos \varphi_j - \cos \varphi_k)^2 \prod_j 4 \sin^2 \varphi_j \prod_j \frac{d\varphi_j}{2\pi} \right). \end{aligned}$$

#### 1.4 $O^+(2n+1)$ .

In this case there is an eigenvalue 1. We have (again  $n = 2$ )

$$\Lambda = \begin{pmatrix} T_1 & 0 & 0 \\ 0 & T_2 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad 0 < \varphi_1 < \varphi_2 < \pi.$$

Furthermore,  $\delta U$  is

$$\delta U = \begin{bmatrix} \begin{bmatrix} 0 & -\delta u_{21} \\ \delta u_{21} & 0 \end{bmatrix} & \begin{bmatrix} -\delta u_{31} & -\delta u_{41} \\ -\delta u_{32} & -\delta u_{42} \end{bmatrix} & \begin{bmatrix} -\delta u_{51} \\ -\delta u_{52} \\ -\delta u_{53} \end{bmatrix} \\ \begin{bmatrix} \delta u_{31} & \delta u_{32} \\ \delta u_{41} & \delta u_{42} \end{bmatrix} & \begin{bmatrix} 0 & -\delta u_{43} \\ \delta u_{43} & 0 \end{bmatrix} & \begin{bmatrix} -\delta u_{54} \\ -\delta u_{54} \\ 0 \end{bmatrix} \\ \begin{bmatrix} \delta u_{51} & \delta u_{52} \end{bmatrix} & \begin{bmatrix} \delta u_{53} & \delta u_{54} \end{bmatrix} & 0 \end{bmatrix}.$$

In  $\Lambda^{-1} \delta U \Lambda - \delta U$ , comparing to the case case  $O^+(2n)$ , the new pieces are on the last row. We have

$$(\delta u_{51}, \delta u_{52}) \begin{pmatrix} c_1 - 1 & s_1 \\ -s_1 & c_1 - 1 \end{pmatrix}, \quad \text{or} \quad \begin{pmatrix} c - 1 & s \\ -s & c - 1 \end{pmatrix} \begin{pmatrix} \delta u_{51} \\ \delta u_{52} \end{pmatrix},$$

from where the denominator is  $2(1 - \cos \varphi_1)$ . The result now is

$$\begin{aligned} \int_{O^+(2n+1)} f(A) d\text{Haar} &= \int_{O^+(2n+1)} f(A) \delta A = \int_{O^+(2n+1)} f(A) \delta B = \\ &= \left( \frac{1}{n!} \int_{[0, \pi]^n} f(1, \varphi_1, \dots, \varphi_n) \prod_{j < k} 4(\cos \varphi_j - \cos \varphi_k)^2 \prod_j 2(1 - \cos \varphi_j) \prod_j d\varphi_j \right) \cdot \text{Vol}(U), \end{aligned}$$

and cheating with a constant,

$$\begin{aligned} \int_{O^+(2n+1)} f(A) d\text{Haar} &= \int_{O^+(2n+1)} f(A) \delta A = \int_{O^+(2n+1)} f(A) \delta B = \\ &= \left( \frac{1}{n!} \int_{[0, \pi]^n} f(1, \varphi_1, \dots, \varphi_n) \prod_{j < k} 4(\cos \varphi_j - \cos \varphi_k)^2 \prod_j 2(1 - \cos \varphi_j) \prod_j \frac{d\varphi_j}{2\pi} \right). \end{aligned}$$

#### 1.5 $O^-(2n+1)$ .

In this case the representation  $\Lambda$  will have  $-1$  instead of  $1$  in the last row. The rest is the same as for  $O^+(2n+1)$ .

$$\begin{aligned} \int_{O^-(2n+1)} f(A) d\text{Haar} &= \\ &= \left( \frac{1}{n!} \int_{[0, \pi]^n} f(-1, \varphi_1, \dots, \varphi_n) \prod_{j < k} 4(\cos \varphi_j - \cos \varphi_k)^2 \prod_j 2(1 - \cos \varphi_j) \prod_j \frac{d\varphi_j}{2\pi} \right). \end{aligned}$$

All the wrapped formulas coincide with Katz, Sarnak, Chapter 5, pages 107-108, up to a constant, with the difference that he divides all  $d\varphi$  by  $2\pi$ , and discard  $Vol(U)$ . Indeed, the latter will cancel if we want our integral be normalized.

## 2 Meet Andreeiv.

Now a general statement,

$$\frac{1}{N!} \int_{X^N} \det(g_k(\theta_j))_{k,j=1}^N \cdot \det(h_k(\theta_j))_{k,j=1}^N \cdot \prod_{j=1}^N d\sigma(\theta_j) = \det \left[ \int_X g_k(\theta) h_j(\theta) d\sigma(\theta) \right]_{j,k=1}^N.$$

### 2.1 U(N).