

Calibration results

=====

Camera-system parameters:

cam0 (/camera/mono_right/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.21573671 0.063102 0.00009055 0.00075862] +- [0.00063335 0.00055142 0.00007493 0.00009735]

projection: [1194.26185001 1191.00869895 968.39056781 591.25965596] +- [1.45529669 1.44506189 1.37983352 1.39283283]

reprojection error: [-0.000003, -0.000002] +- [0.618678, 0.580406]

Target configuration

=====

Type: aprilgrid

Tags:

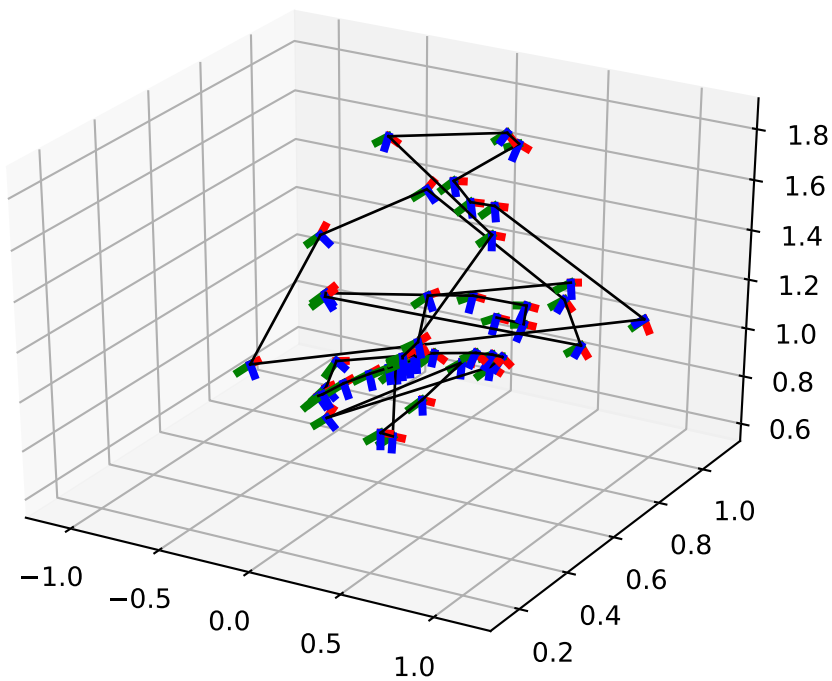
Rows: 6

Cols: 6

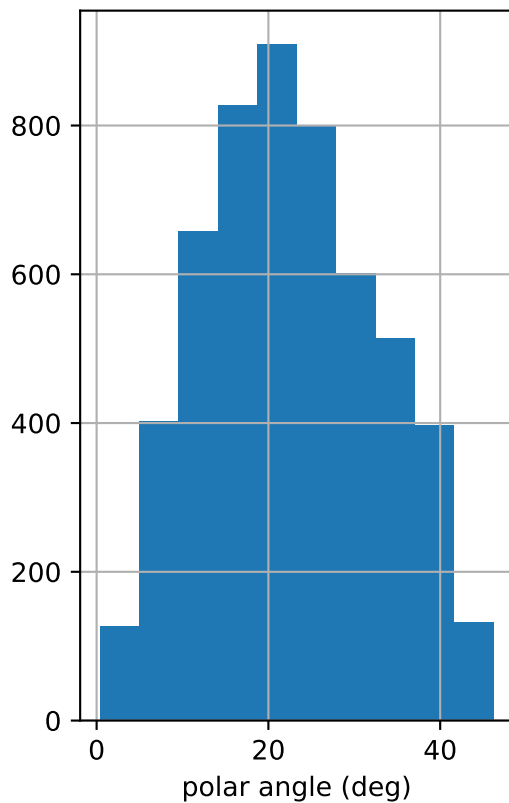
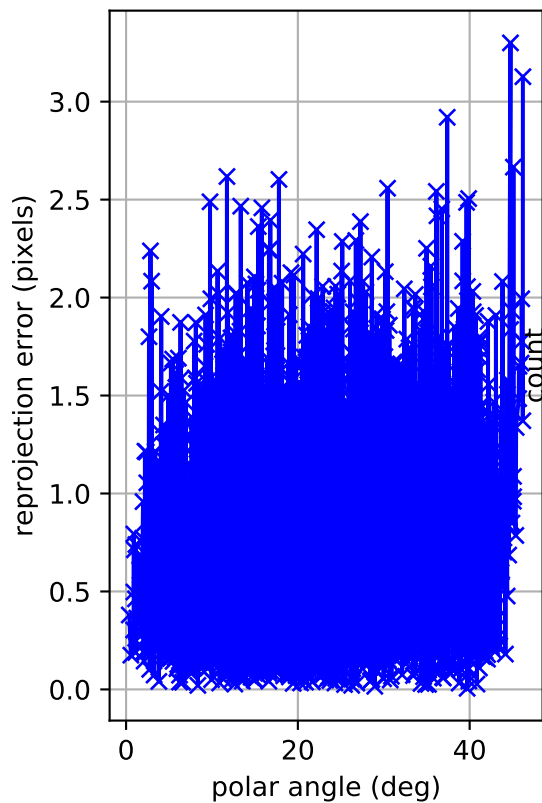
Size: 0.088 [m]

Spacing 0.02639999999999996 [m]

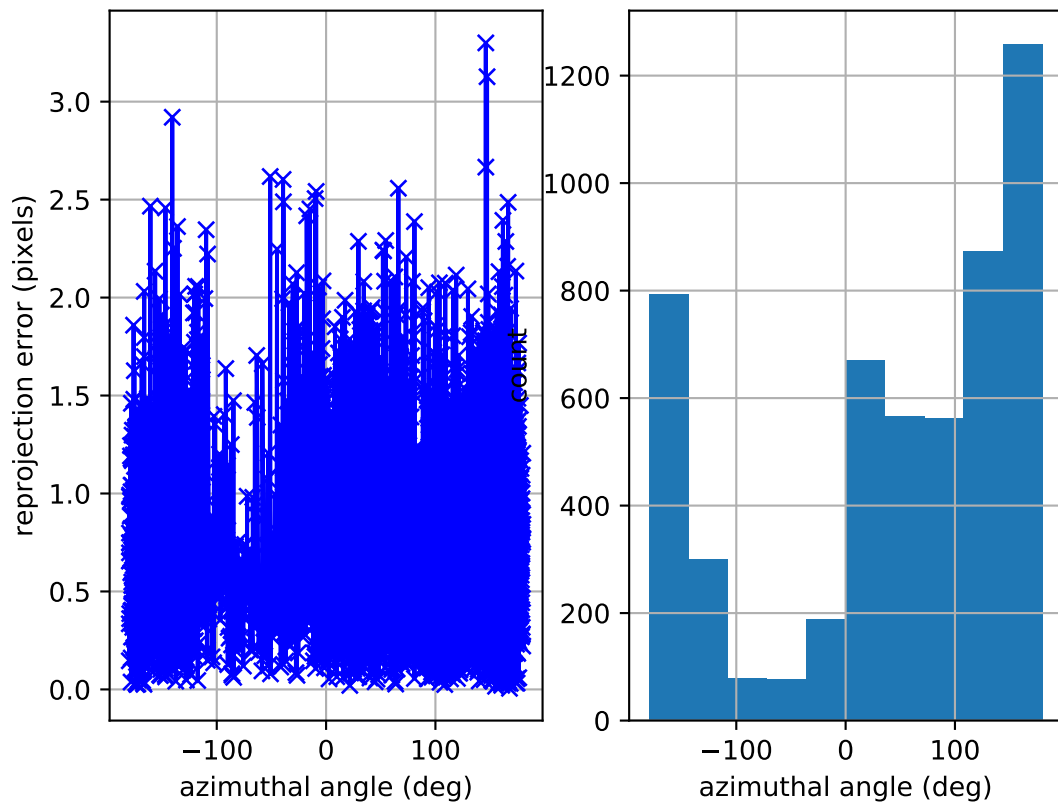
cam0: estimated poses



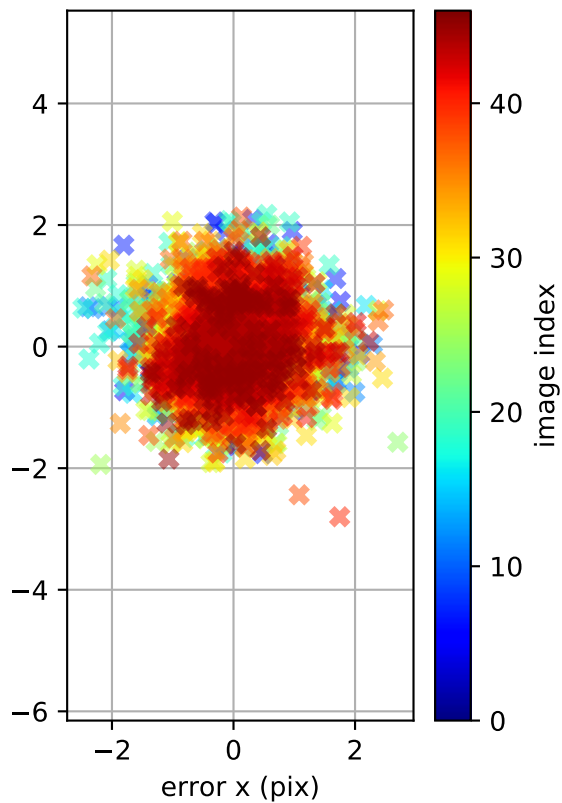
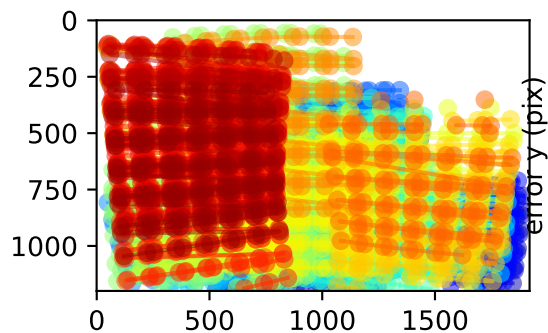
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

cam0

