

Calibration results

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Camera-system parameters:

cam0 (/camera/mono_left/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.21553979 0.06152975 -0.00021479 -0.00008084] +- [0.00115698 0.00109056 0.00018824 0.0001627]

projection: [593.48808371 593.47555132 477.79293906 294.4747175] +- [1.99945696 2.05815704 1.32399957 1.83627243]

reprojection error: [-0.000000, -0.000000] +- [0.368436, 0.507860]

Target configuration

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Type: aprilgrid

Tags:

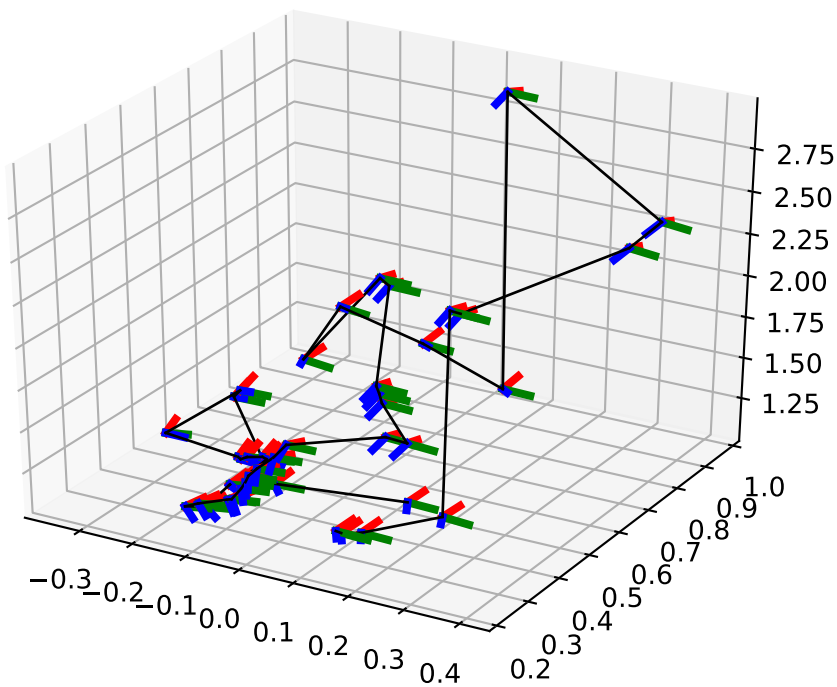
Rows: 6

Cols: 6

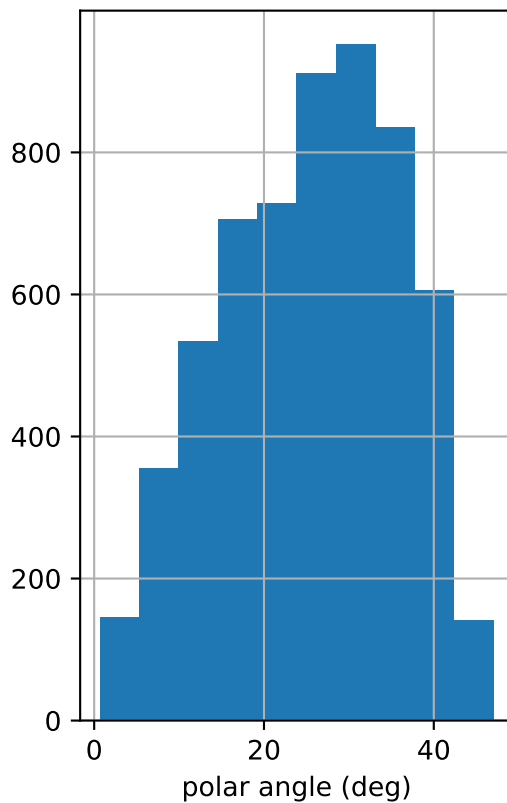
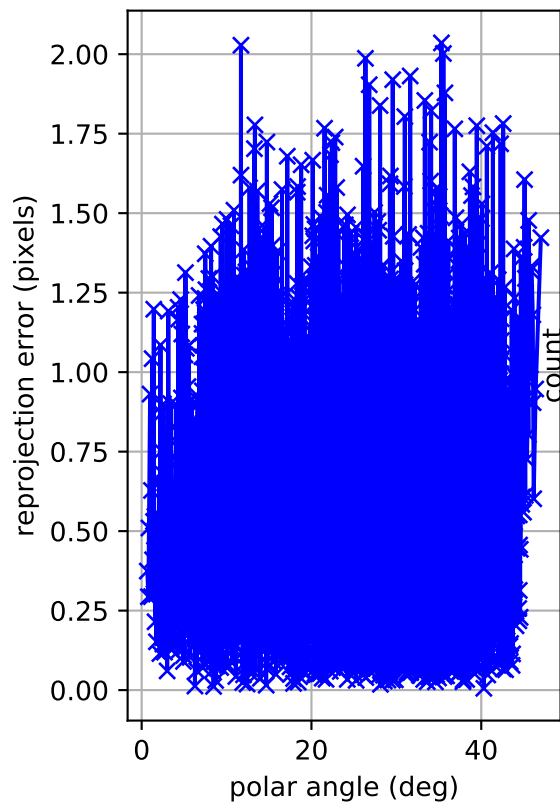
Size: 0.088 [m]

Spacing 0.026399999999999996 [m]

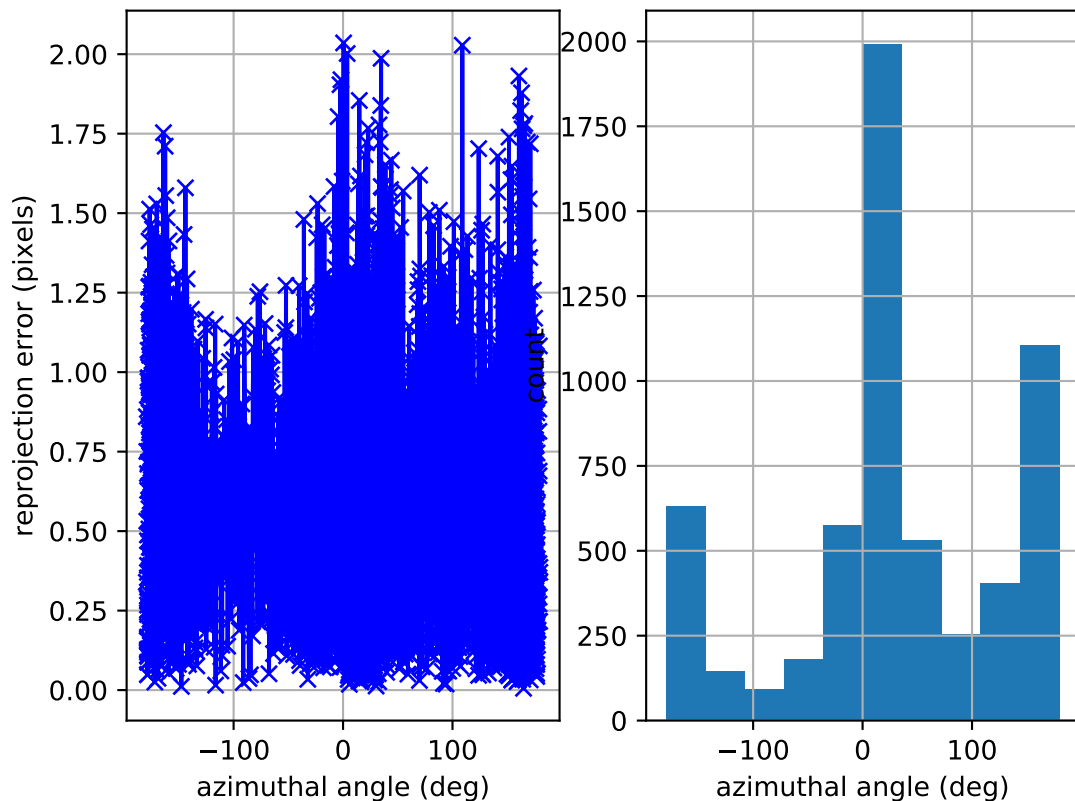
cam0: estimated poses



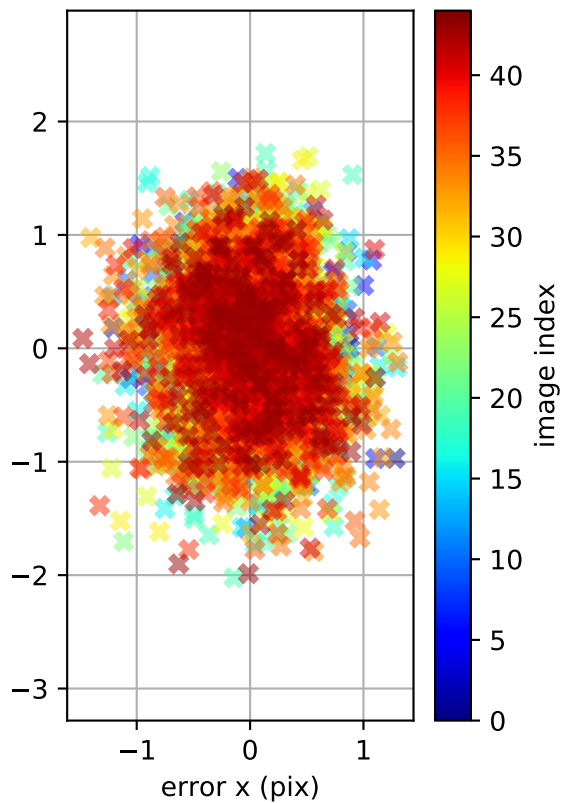
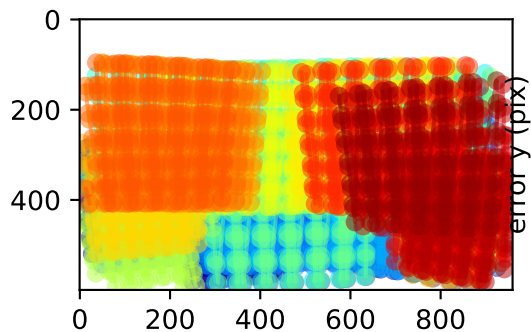
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

