Calibration results
====================
Camera-system parameters:
cam0 (/camera/mono_right/image_raw):
type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
distortion: [-0.2177284   0.0645021 -0.00031642 -0.00026383] +- [0.0012675 0.00111883 0.0001877 0.00015885]
projection: [592.20251734 592.15696609 484.55911181 297.18277527] +- [1.75575801 1.83282807 1.37069781 1.80026452]
reprojection error: [-0.000000, -0.000001] +- [0.354753, 0.517075]

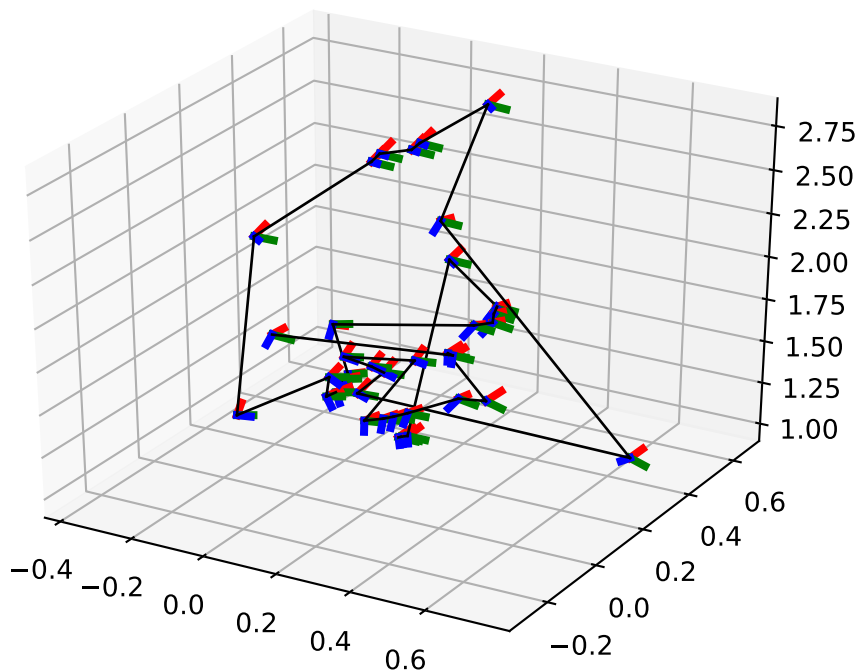Target configuration
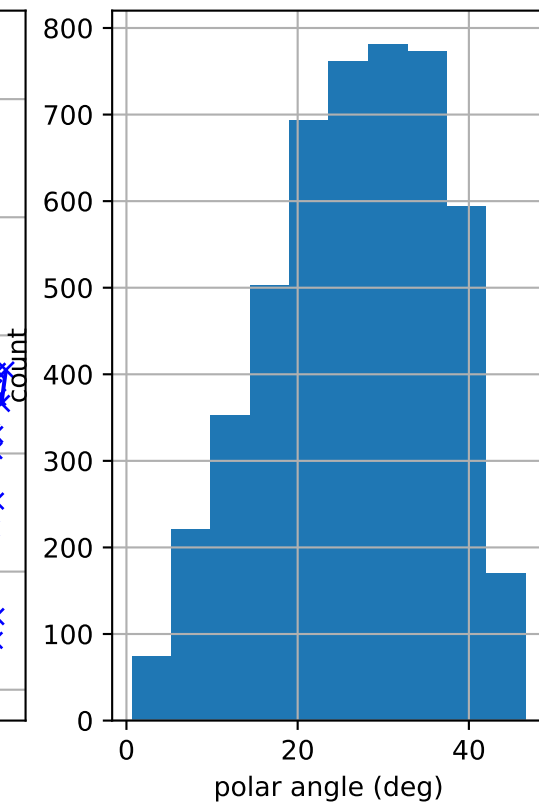====================
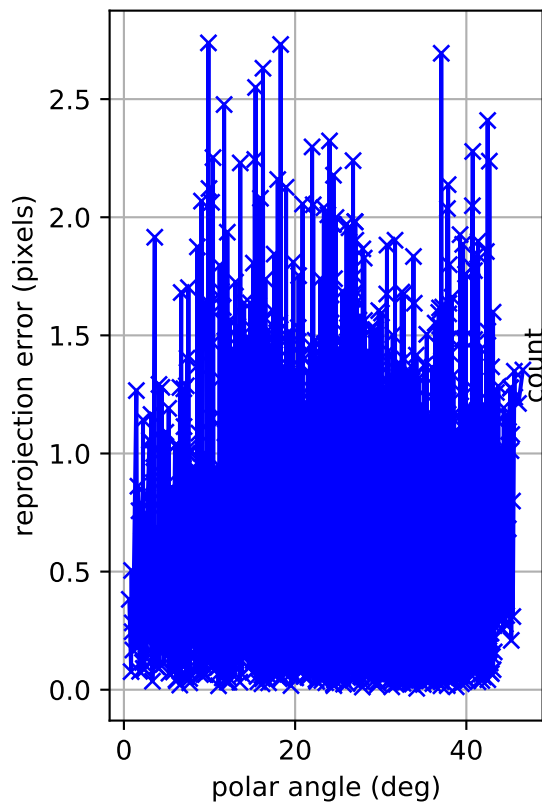
Type: aprilgrid
Tags:
Rows: 6
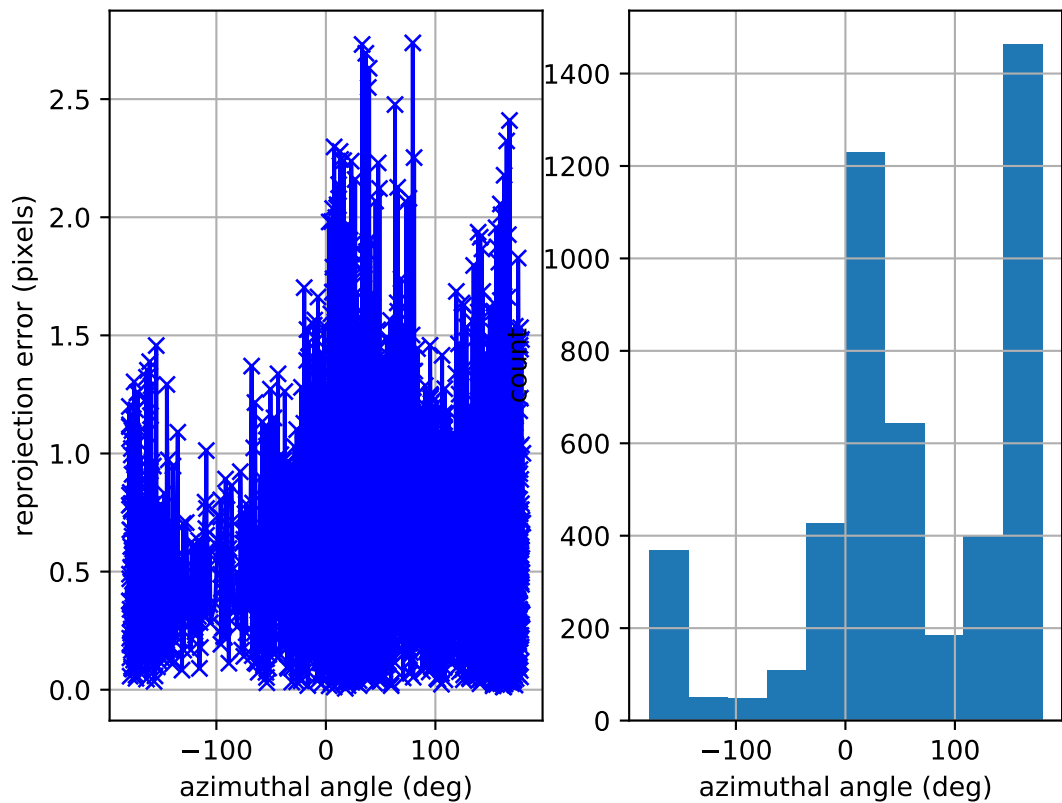Cols: 6
Size: 0.088 [m]
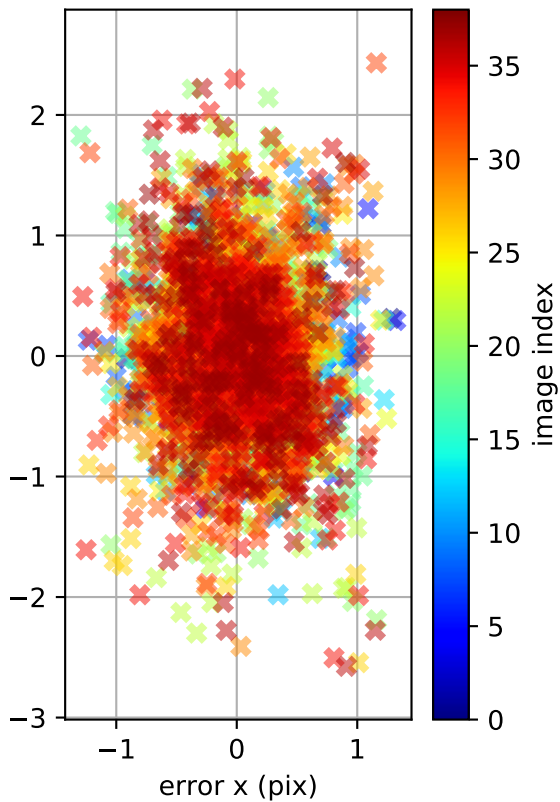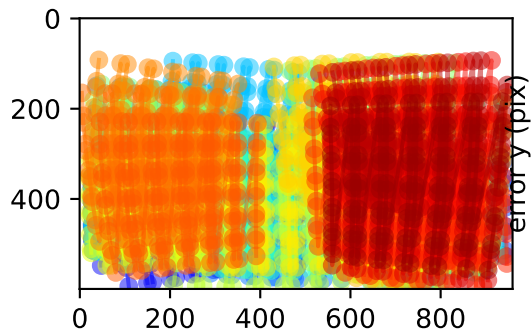Spacing 0.026399999999999996 [m]

cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners

cam0