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DM852

Heuristics & Approximations Algorithms

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Contents

1 Introduction **2**

2 Simulated Annealing **3**
2.1 Complexity and Analysis 4

3 Ant Colony Optimization **9**

4 Discussion **12**

1 Introduction

This project shows metaheuristic algorithms, resolving the Capacitated Vehicle Routing Problem (CVRP). The difference between metaheuristics and heuristics is in the solution part. For heuristics, you are trying your best to find a solution, even though it is not optimal. The algorithm is adapted to the problem in such a greedy approach, it can get stuck in a local optimum. This is fine since it is the idea of heuristics: "just solve the problem".
Metaheuristics are less greedy and tends to be more problem independent. They accept temporary solutions and allow "bad" steps as an attempt to get a better solution. You have a local- and global optimum to keep track of the best solution found. You can say metaheuristics are exploiting heuristics to avoid getting trapped.
In this metaheuristics implementation project, we have chosen to implement two algorithms for CVRP: Simulated Annealing (SA) and Ant Colony Optimization (ACO). The SA algorithm is the one we have uploaded for electronic submission at http://valkyria.imada.sdu.dk/D0App/. The ACO algorithm is implemented but does not perform well. We will compare the algorithms with our previous heuristic / local search project and lastly, show our results of computation for our two algorithms.

— Alexander & Narongrit

2 Simulated Annealing

The Simulated Annealing (SA) algorithm is inspired from the annealing process in metal, where you are altering the physical state of the metal by heating and cooling it. The inspiration can be used in computer science as well. We can use the algorithm on CVRP by starting off by generating a solution to the problem and not "care" about the initial solutions. The better steps we are taking, and better solutions we are finding, the more careful we are going to be in finding a solution. In the beginning we allow random and bad steps to be performed, while later, we make better calculations.
We have developed an algorithm to solve CVRP using Simulated Annealing technique by relating CVRP with existed problems i.e. Bin packing problem and Knapsack problem. Using this approach, we can guarantee maximum amount of vehicles necessary required with approximation analysis on bin packing hueristic algorithm. In this demonstration, we use well studied algorithm First-Fit-Decreasing which is guaranteed to use no more than $\frac{11}{9}\mathrm{OPT} + 1$ number of required vehicles[1]. With combination of simple Traveling Salesman Problem's local search algorithm, 2-opt, we are able create the initial feasible solution. Next step of Simulated Annealing involved creating new feasible solution by altering current solution. Which in CVRP case, is to perform points exchange action between routes. In order to allow as much possibility of exchanges as it could without breaking capacity constrain, we choose simple algorithm to find exchanges possibility based on Knapsack problem. Our implementation of acceptance criterion is based on Metropolis condition which accept new solution by using probability $p = \exp[-\frac{new\_cost - best\_cost}{temp}]$, this leads to $p = 1$ when $new\_cost < best\_cost$ otherwise $p = [0, 1)$. We use geometric cooling scheme in order to update temperature every iteration the algorithm accepts new solution by multiply temperature variables with $alpha$ where $alpha = (0, 1)$. This makes p have lower probability to accept worsen solution after later iteration. All algorithms is described as following.

Algorithm 1 Simulated annealing with First-Fit-Decreasing and Knapsack combination

Require: *customers*: List of customer coordinate with it's capacity
Require: *max_cap*: Maximum capacity for each route
Require: *depot*: Depot point
Require: *is_accept*(*best_cost*, *cost*, *temp*): an acceptance criterion function returns boolean based on Metopolis condition

```
1: function SIMULATED_ANNEALING_FFD(temp, alpha, no_improve_limits)
2:     routes ← CVRP_FIRST_FIT_DECREASING(customers, depot)
3:     best_cost ← total cost of routes
4:     best_routes ← routes
5:     current_cost ← best_cost
6:     current_routes ← routes
7:     curr_no_improve_trying ← 0
8:     while True do
9:         if curr_no_improve_trying == no_improve_limits then break
10:        new_routes ← NEIGHBORS_SELECTION(current_routes)
11:        new_cost ← cost of new_routes
12:        if is_accept(best_cost, new_cost, temp) then
13:            temp ← temp * alpha
14:            curr_no_improve_trying ← 0
15:            update current_routes with new routes
16:            if new_cost < best_cost then
17:                update best_cost and best_routes with new routes
18:        else
19:            curr_no_improve_trying ← curr_no_improve_trying + 1
       return best_routes
```

2.1 Complexity and Analysis

By relating CVRP to other existed problem, we are able to come up with a simple algorithm and use existed technique, Simulated Annealing, to improve the solution. We first analyzing our algorithm to construct our initial routes. Using First-Fit-Decreasing to assign group customer points for a vehicle only have runtime complexity of $O(nlogn)$ but in order to decide customer point sequences for each route, we rely on local search algorithm for traveling salesman problem which dominates runtime complexity of our bin packing algorithm. Using simple 2-opt local search algorithm arrange customer point sequences for each vehicle route yields runtime complexity of $O(n^2)$.

Another key task of Simulated Annealing is the neighbor selection procedure. Our attempt is to find largest possibility of exchanging customer point between routes. The problem is risen when given one customer point chosen by uniform distribution probability, how can we decide other candidate to make exchange action and such candidate should not leads to infeasible solution. Introducing a simple algorithm to

Algorithm 2 First-Fit-Decreasing for CVRP

Require: *customers*: List of customer coordinate with it's capacity
Require: *tsp_local_search*(*route*): performs traveling salesman local search and returns improved route
Require: *max_cap*: Maximum capacity for each route
Require: *depot*: Depot point
Require: *route_cost*(*route*): returns capacity of route
Ensure: *routes*: solution routes

```
1: function CVRP_FIRST_FIT_DECREASING(customers)
2:     sorted_capacity_points ← sort customer points by it's capacity
3:     routes ← []
4:     add new array with depot to routes to create new route
5:     for all point in sorted_capacity_points do
6:         is_fit ← False
7:         for all route in routes do
8:             if route_cost(route) + point.capacity ≤ max_cap then
9:                 add point to route
10:                is_fit ← True
11:                break
12:        if !is_fit then
13:            add new route with depot and point to routes
14:    for all route in routes do
15:        route ← tsp_local_search(route)
       return routes
```

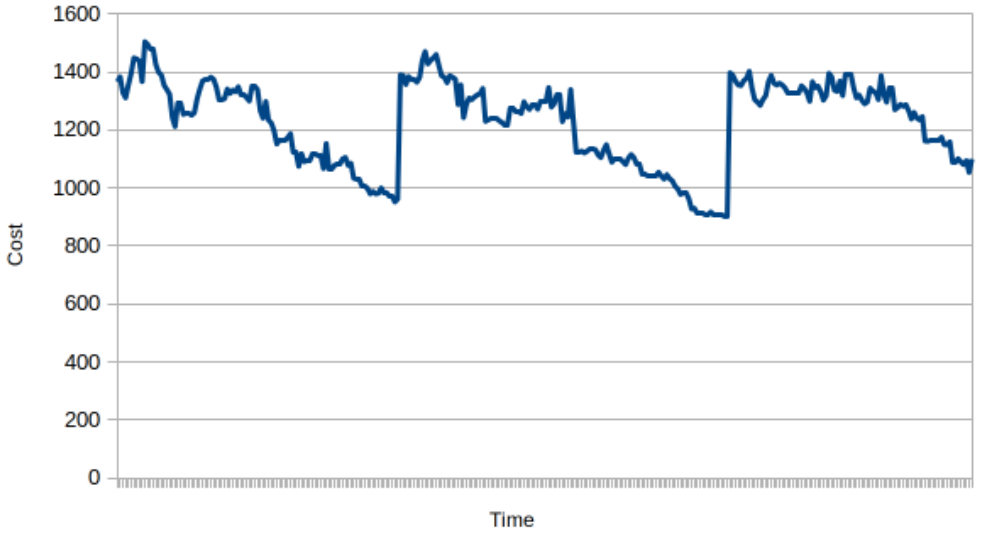
find possibility of packing customer point into one set based on brute force algorithm for Knapsack problem, which explore for every customer points either to include in neighbor exchange candidate or not, allows us to find a list of feasible candidates to make exchange between routes. But tradeoff of this algorithm is the runtime complexity, which is $O(2^n)$ where n is number of customer points in candidate route. In order to keep runtime of each Simulated Annealing iteration footnotesize, we introduce a user-defined variable *max_points_amt* which an algorithm will use to choose number of customer points in candidate route and proceed the algorithm. This indeed reduces the number of possibility on selecting exchange neighbors candidates but in an instance where it consist of many footnotesize capacity point, without limiting such customer point might leads to long runtime for each neighbor selection process. We conclude that for each iteration of our Simulated Annealing the runtime complexity is in $O(2^n)$ where n is maximum number of points allowed to be exchange.

Algorithm 3 Neighbours selection for SA

Require: *routes*: list of routes in solution contains customer coordinate and it's capacity required
Require: *max_cap*: Maximum capacity for each route
Require: *route_cap*(*route*): returns capacity of *route*
Require: *tsp_local_search*(*route*): performs traveling salesman local search and returns improved route
Ensure: *new_routes*: new solution routes

function NEIGHBOR_SELECTION(*routes*)
  repeat
    $origin\_route\_id, target\_route\_id \leftarrow$ randomly pick 2 distinct index of *routes*
    $origin\_route\_point \leftarrow$ randomly pick element from $route[origin\_route\_id]$
    $upper\_bound \leftarrow max\_cap - (route\_cap(routes[origin\_route\_id] - origin\_route\_point.capacity))$
    $lower\_bound \leftarrow route\_cap(routes[target\_route\_id]) - (max\_cap - origin\_route\_point.capacity)$
    $target\_neighbor\_set \leftarrow$ KNAPSACK_COMBINATION($route[target\_route\_id], lower\_bound, upper\_bound$)
  until $len(target\_neighbor\_set) > 0$
  $target\_neighbor \leftarrow$ randomly pick an element from $target\_neighbor\_set$
  $new\_route\_origin, new\_route\_target \leftarrow$ exchange neighbors between two route and assign to new variables
  $new\_route\_origin \leftarrow tsp\_local\_search(new\_route\_origin)$
  $new\_route\_target \leftarrow tsp\_local\_search(new\_route\_target)$
  $new\_routes \leftarrow routes$ where $route[origin\_route\_id]$ and $route[target\_route\_id]$ replaced by new routes
  return *new_routes*

Figure 1: Illustration of the cost per each acceptance iteration of Simulated Annealing for 3 Simulated Annealing schedule on instance A-n32-k05



Algorithm 4 Knapsack Combination

Require: *customers*: List of customer coordinate with it's capacity
Require: *max_cap*: Maximum capacity for each route
Require: *depot*: Depot point
Require: *max_points_amt*: Number of maximum combination points
Require: *route_cap*(*route*): returns capacity of *route*
Ensure: *combination_set*: set of candidates combination of points in *route*

```
1: function KNAPSACK_COMBINATION(route, lower_bound, upper_bound)
2:     points
3:     if len(route) < max_points_amt then
4:         points ← randomly pick len(route) points from route but depot
5:     else
6:         points ← randomly pick max_points_amt points from route but depot
7:     combination_set ← []
8:     function KNAPSACK_COMBINATION_RECUR(current_point_id, current_capacity, knapsack)
9:         if current_point_id == len(points) then
10:            if route_cap(knapsack) > lower_bound then
11:                add knapsack to combination_set
12:        knapsack_combination_recur(
               current_point_id + 1, current_capacity, knapsack)
13:        if current_cap + points[current_point_id] ≤ max_cap then
14:            add points[current_point_id] to knapsack
15:            current_cap ← points[current_point_id].capacity
16:            knapsack_combination_recur(
               current_point_id + 1, current_capacity, knapsack)
17:    knapsack_combination(0, 0, [])
18:    return combination_set
```

instance	Cluster		SA		instance	CHH		SA	
	k	**cost**	**k**	cost		**k**	**cost**	**k**	cost
A-n32-k05	5	867	5	980	CMT01	6	604	5	553
A-n33-k05	5	743	5	661	CMT02	11	920	10	894
A-n33-k06	6	766	6	816	CMT03	8	985	8	987
A-n34-k05	6	889	5	778	CMT04	12	1196	12	1568
A-n36-k05	5	862	5	807	CMT05	17	1496	17	3406
A-n37-k05	5	741	5	669	CMT11	8	1111	7	1517
A-n37-k06	7	1112	6	949	CMT12	10	909	10	1180
A-n38-k05	6	822	5	730	Golden_01	9	6055	9	8796
A-n39-k05	5	883	5	827	Golden_02	10	9121	10	14227
A-n39-k06	6	887	6	999	Golden_03	9	12144	9	17920
A-n44-k06	6	1029	6	939	Golden_04	10	15644	10	24338
A-n45-k06	7	1014	6	978	Golden_05	5	7330	5	10954
A-n45-k07	7	1250	7	1161	Golden_06	7	9698	7	14509
A-n46-k07	7	997	7	1039	Golden_07	9	11655	9	17513
A-n48-k07	7	1232	7	1128	Golden_08	10	12835	10	19443
A-n53-k07	8	1142	7	1054	Golden_09	15	590	14	653
A-n54-k07	8	1258	7	1217	Golden_10	16	763	16	843
A-n55-k09	9	1158	9	1300	Golden_11	18	963	18	1090
A-n60-k09	9	1412	9	1394	Golden_12	20	1192	19	1199
A-n61-k09	11	1300	9	1111	Golden_13	28	972	26	1175
A-n62-k08	8	1379	8	1363	Golden_14	31	1194	30	1471
A-n63-k09	10	1764	9	1676	Golden_15	35	1501	33	1743
A-n63-k10	11	1504	10	1442	Golden_16	39	1880	37	2092
A-n64-k09	9	1530	9	1501	Golden_17	22	774	23	1289
A-n65-k09	10	1274	9	1260	Golden_18	28	1108	29	2350
A-n69-k09	10	1297	9	1266	Golden_19	34	1578	35	3279
A-n80-k10	10	1903	10	1920	Golden_20	39	2084	40	4309

Table 1: Result comparing between Heuristic algorithm and Metahuristic(SA with $max\_points\_amt = 3, temp = 1000, alpha = 0.95$) running with time limit 240 seconds on an Intel(R) Core(TM) i7-2600 CPU @ 3.40GHz with 4 GB allocated RAM running Ubuntu 16.04.

3 Ant Colony Optimization

The Ant Colony Optimization (ACO) algorithm comes from the evolutionary algorithms, where computer science meets nature. In this algorithm, we have led us to be inspired by how ants find food in the nature. They are starting by spreading out in some area, randomly. When they seem to find trails, which could indicate to be good trails to find food, they leave pheromone behind them. The pheromone is used by other ants to determine their probability of taking a trail. If they are standing in a cross-section and they have to choose, they are taking the path with the highest pheromone. At some point in their exploration to find the best trail to obtain food, all the ants are using the same trails to get food and get back safe home.
We can apply the logic of the ants in the CVRP as well. By letting the instance the space of which the requests are "plotted" be the area to find a solution, we can start by sending one "ant" out to a random point. This is going to be our current point. From this point, we are going to calculate every probability of moving to the next point the one with the highest "score". We can calculate the probability of moving by the doing the following:
First we establish the initial pheromone levels from all the points to every counter other point:
This is stored in matrix:

$$M = \begin{bmatrix} 0 & 0.50 & 0.20 \\ 0.125 & 0 & 0.60 \\ 1.20 & 0.355 & 0 \end{bmatrix}$$

We also keep track of the points being visited, so we do not keep visiting the same nodes. Then we start calculating a score for each point from the current point. We do this by the formula:

$$score = \alpha^{\frac{1.0}{distance(i,j)}^{\beta}} \tag{1}$$

The αvalue defines the importance of the pheromone level, where the βvalue defines the importance of the distance between two points. After finding the score for each point from the current point, we can calculate the probability by dividing the score by the summation of all scores:

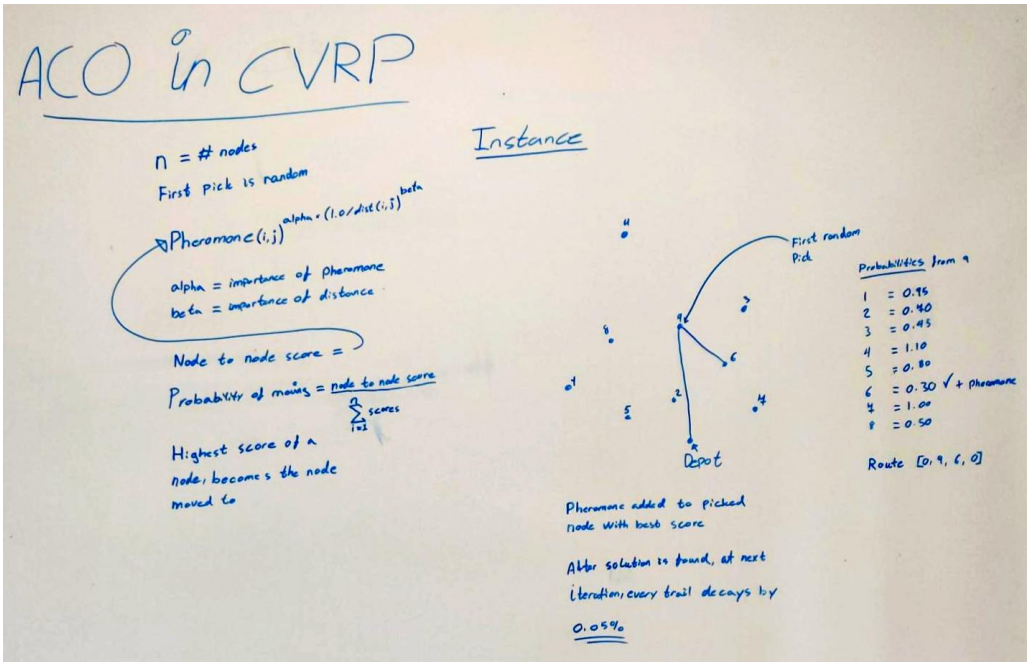
$$prob = \frac{score}{\sum_{i=1}^{n} score_i} \tag{2}$$

Where **n** is equivalent to the number of points. We can now append additional pheromone to the trail from the current point to the next point, by dividing:

$$newpheromone = \frac{1}{distance(i,j)} \tag{3}$$

Now we can continue with our usual CVRP properties, where we ensure the capacity of the vehicle is not breached. We continue finding points with the above algorithm. After the algorithm has found a solution, we are going to run it again, with the same pheromone matrix, but with updated values, where every pheromone in the trails evaporates a footnotesize percentage before each iteration. A timer is being set, which controls for how long the algorithm runs.
In Figure 2 a drawing has been created to visualize the idea of the algorithm:

Figure 2: Illustration of the ACO algorithm, showing how it can be used, and how it process next moves



The complexity of the algorithm is $O(n)$ after initializing the pheromone matrix, due to the amount of checks from the current point it has to perform, which is n

Algorithm 5 Metaheuristic - Ant Colony Optimization

```
1: max_iteration ← number of iteration
2: i ← 0
3: global_best_route ← empty route/array
4: while i < max_iteration or a time limit is not reached do
5:     local_best_route ← empty route/array
6:     current_route ← empty route/array
7:     capacity ← 0
8:     alpha ← A random number
9:     beta ← A random number greater than alpha
10:    evaporation ← Some footnotesize number
11:    pheromone_matrix ← Contains every pheromone for each pair
12:    sum_of_all_pheromone ← The summation of the pheromone_matrix
13:    i++
14:    for first_point ← 0 to length of data do
15:        for second_point ← 0 to length of data do
16:            if first_point ≠ second_point then
17:                pheromone_matrix(first, second) ← 1/distance
18:                sum_of_all_pheromone ← append calculated pheromone to the sum
19:    Pick a random point for the list of points and mark it as visited
20:    Append it to the routes
21:    Keep storage of the previous score
22:    while point ≠ visited in list do
23:        for key in pheromone_matrix do
24:            Calculate and store the Score-equation
25:            Calculate and store the Probability-equation
26:            if the new score ¡ previous score && key is not visited then
27:                Set the key of the request to the point moved to
28:        Append Newpheromone-equation to the trail of the point moved to
29:        if Capacity of picked point ≤ Capacity Constraint then
30:            Capacity capacity of request
31:            Append picked point to current_route
32:            Mark picked point as visited
33:            Set picked point to the current point
34:            Set previous score to 0
35:        else
36:            Reset current_route and append picked point to new route
37:            Mark point as visited
38:            capacity ← capacity of picked point
39:            Set previous score to 0
40:    if current_route is better than local_best_route then
41:        local_best_route ← current_route
42:    if local_best_route is better than global_best_route then
43:        global_best_route ← local_best_route
44:    loop through pheromone_matrix and evaporate every pheromone trail by a footnotesize
       percentage
```

4 Discussion

Metaheuristics takes longer to execute, since they are not stopping until certain criteria is fulfilled. This criteria can be hard to reach and therefore, the algorithm can be running forever. In our two metaheuristic algorithms, the stopping criteria is the timespan of the running process. When the algorithms have been running for the set time, the processís stopped.
Our Simulated Annealing algorithm does run for a long time with an exponential complexity. Looking at our Table 1, we are getting close reaching the cost of the cluster heuristic - picks furthest point from the depot and uses the nearest addition heuristic approach to generate routes in clusters to form a tour - from our first project, is still doing better in most cases. We concluded, allowing more possibilities on developing neighbor selection, is not benefitting the the total cost a lot. An idea to improve the neighbor selection is to create a smarter algorithm to pick a neighbor, such as selecting and exchanging neighbors based on it's proximity. This could allow the Simulated Annealing to be better in obtaining a local optimum earlier in each iteration. Since we did not get the ACO algorithm to work properly, the only comparison we were able to make, was between the first instance: A-n32-k05. Here, the ACO was finding a cost around 1800-1900, where the SA - from Table 1 - found costs at 980. This makes a great win for the SA in our case.

References

[1] Minyi Yue. A simple proof of the inequality ffd(l) $\leq$ 11/9 opt(l) + 1, $\forall$l for the ffd bin-packing algorithm. *Acta Mathematicae Applicatae Sinica*, 7(4):321–331, 1991.