

Fisher sim

0.0.1

Generated by Doxygen 1.8.9.1

Sat Mar 28 2015 13:08:30



# Contents

<b>1</b>	<b>Hierarchical Index</b>	<b>1</b>
1.1	Class Hierarchy . . . . .	1
<b>2</b>	<b>Class Index</b>	<b>3</b>
2.1	Class List . . . . .	3
<b>3</b>	<b>Class Documentation</b>	<b>5</b>
3.1	Graphview Class Reference . . . . .	5
3.1.1	Detailed Description . . . . .	6
3.1.2	Member Function Documentation . . . . .	6
3.1.2.1	setupPlot . . . . .	6
3.2	MainWindow Class Reference . . . . .	6
3.2.1	Detailed Description . . . . .	7
3.3	UserSettings Class Reference . . . . .	7
3.3.1	Detailed Description . . . . .	8
3.3.2	Member Function Documentation . . . . .	8
3.3.2.1	getfishLoc . . . . .	8
3.3.2.2	getfishPop . . . . .	8
3.3.2.3	getfishTemp . . . . .	8
3.3.2.4	getfishType . . . . .	9
3.3.2.5	getRuntime . . . . .	9
3.3.3	Member Data Documentation . . . . .	9
3.3.3.1	fisherNum . . . . .	9
3.3.3.2	fishLoc . . . . .	9
3.3.3.3	fishPop . . . . .	9
3.3.3.4	fishTemp . . . . .	9
3.3.3.5	fishType . . . . .	9
3.3.3.6	runtime . . . . .	9
	<b>Index</b>	<b>11</b>



# Chapter 1

## Hierarchical Index

### 1.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

QMainWindow	
Graphview . . . . .	5
MainWindow . . . . .	6
UserSettings . . . . .	7
MainWindow . . . . .	6



## Chapter 2

# Class Index

### 2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

<a href="#">Graphview</a>	.....	5
<a href="#">MainWindow</a>		
The <a href="#">MainWindow</a> class	Provides the Main windows for the Fisher sim project	6
<a href="#">UserSettings</a>		
Records the global simulation settings	.....	7





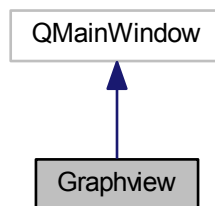
## Chapter 3

# Class Documentation

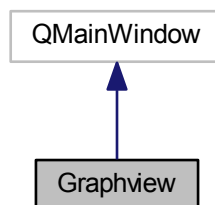
### 3.1 Graphview Class Reference

```
#include <graphview.h>
```

Inheritance diagram for Graphview:



Collaboration diagram for Graphview:



#### Public Member Functions

- [Graphview](#) (QWidget \*parent=0)

*Graphview::setupPlot.*

- void `setupPlot` ()

*setupPlot*

### 3.1.1 Detailed Description

provides a view that shows the collected graphs and allows them to be inserted into a report.

`Graphview` is intended to be used after the simulation has finished. It will accept data from the simulation module defining plots and display them to the users. There is also a report view on the left side that allows users to insert selected graphs to compile a final report.

### 3.1.2 Member Function Documentation

#### 3.1.2.1 void `Graphview::setupPlot` ( )

`setupPlot`

configures the plots

Here is the caller graph for this function:



The documentation for this class was generated from the following files:

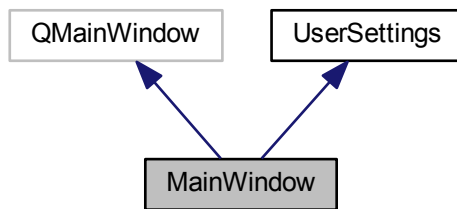
- `graphview.h`
- `graphview.cpp`

## 3.2 MainWindow Class Reference

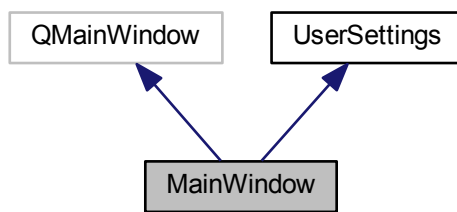
The `MainWindow` class Provides the Main windows for the Fisher sim project.

```
#include <mainwindow.h>
```

Inheritance diagram for MainWindow:



Collaboration diagram for MainWindow:



### Public Member Functions

- **MainWindow** (QWidget \*parent=0)
- void **log** (const QString &text)

### Additional Inherited Members

#### 3.2.1 Detailed Description

The [MainWindow](#) class Provides the Main windows for the Fisher sim project.

The documentation for this class was generated from the following files:

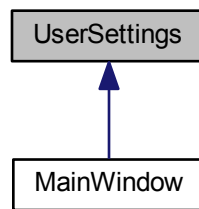
- mainwindow.h
- mainwindow.cpp

## 3.3 UserSettings Class Reference

Records the global simulation settings.

```
#include <UserSettings.h>
```

Inheritance diagram for UserSettings:



### Public Member Functions

- int **getfisherNum** ()
- int [getfishLoc](#) ()
- int [getfishType](#) ()
- int [getfishPop](#) ()
- int [getfishTemp](#) ()
- int [getRuntime](#) ()

### Protected Attributes

- int [fisherNum](#)
- int [fishLoc](#)
- int [fishType](#)
- int [fishPop](#)
- int [fishTemp](#)
- int [runtime](#)

#### 3.3.1 Detailed Description

Records the global simulation settings.

#### 3.3.2 Member Function Documentation

##### 3.3.2.1 int UserSettings::getfishLoc ( )

Returns the number of Fishers to use in the simulation

##### 3.3.2.2 int UserSettings::getfishPop ( )

Returns the number of fish types.

##### 3.3.2.3 int UserSettings::getfishTemp ( )

Returns the initial population of fish when the simulation starts.

#### 3.3.2.4 int UserSettings::getfishType ( )

Returns the number of different locations

#### 3.3.2.5 int UserSettings::getRuntime ( )

Returns the conditions: overcast, snow, rain.

### 3.3.3 Member Data Documentation

#### 3.3.3.1 int UserSettings::fisherNum [protected]

Returns the number of days to run the simulation.

#### 3.3.3.2 int UserSettings::fishLoc [protected]

The number of Fishers to use in the simulation

#### 3.3.3.3 int UserSettings::fishPop [protected]

The number of fish types.

#### 3.3.3.4 int UserSettings::fishTemp [protected]

The initial population of fish when the simulation starts.

#### 3.3.3.5 int UserSettings::fishType [protected]

The number of different locations

#### 3.3.3.6 int UserSettings::runtime [protected]

The conditions: overcast, snow, rain

The documentation for this class was generated from the following files:

- UserSettings.h
- UserSettings.cpp



# Index

- fishLoc
  - UserSettings, [9](#)
- fishPop
  - UserSettings, [9](#)
- fishTemp
  - UserSettings, [9](#)
- fishType
  - UserSettings, [9](#)
- fisherNum
  - UserSettings, [9](#)
- getRuntime
  - UserSettings, [9](#)
- getfishLoc
  - UserSettings, [8](#)
- getfishPop
  - UserSettings, [8](#)
- getfishTemp
  - UserSettings, [8](#)
- getfishType
  - UserSettings, [8](#)
- Graphview, [5](#)
  - setupPlot, [6](#)
- MainWindow, [6](#)
- runtime
  - UserSettings, [9](#)
- setupPlot
  - Graphview, [6](#)
- UserSettings, [7](#)
  - fishLoc, [9](#)
  - fishPop, [9](#)
  - fishTemp, [9](#)
  - fishType, [9](#)
  - fisherNum, [9](#)
  - getRuntime, [9](#)
  - getfishLoc, [8](#)
  - getfishPop, [8](#)
  - getfishTemp, [8](#)
  - getfishType, [8](#)
  - runtime, [9](#)