

## Introduction

The manufacturing lifecycle is the process a product will undergo during its production. In REXOS, Products are manufactured by taking each product through series of actions that either involve decision-making by the agents or direct execution of so called services.

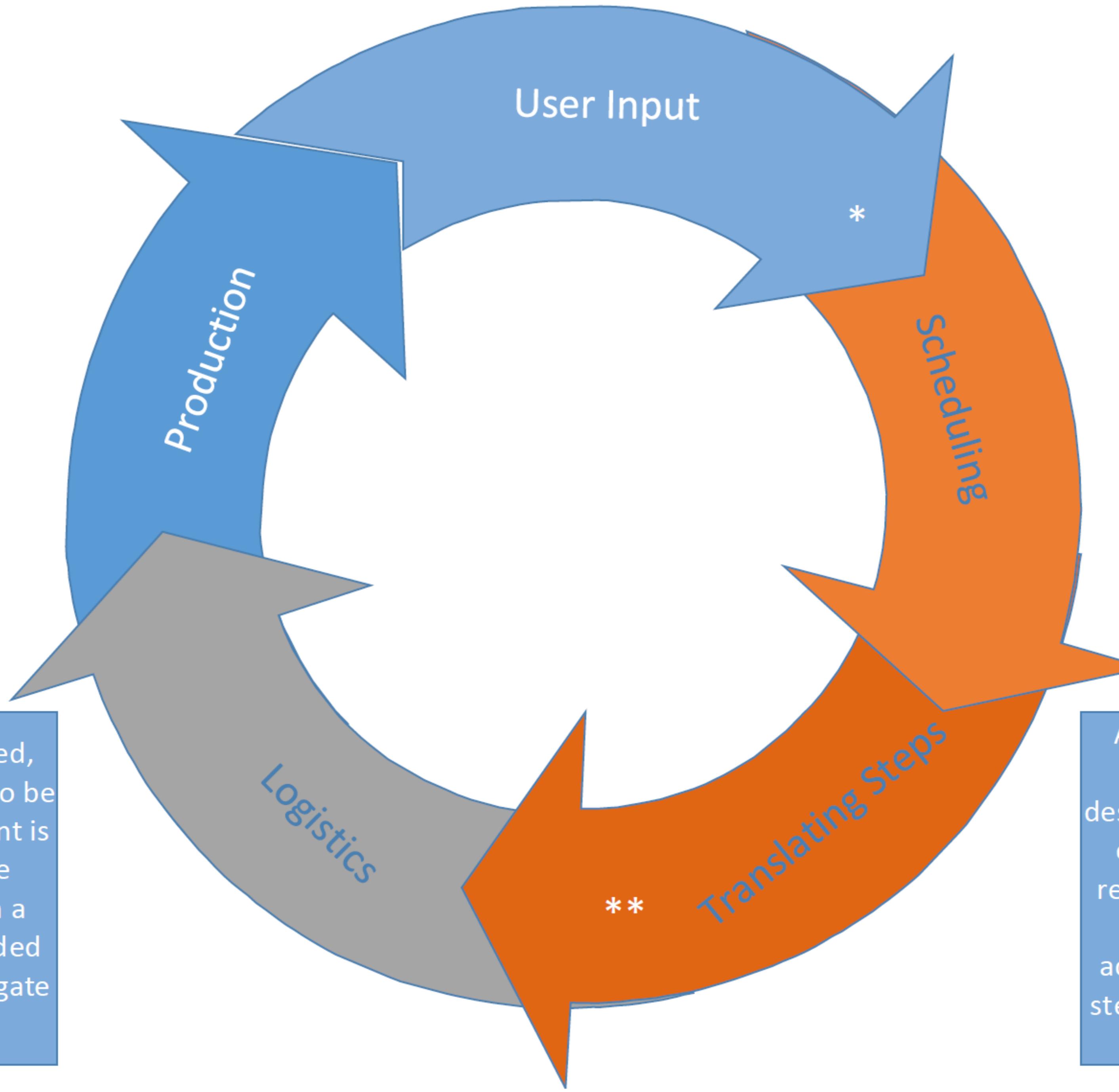
## Finding the Right Equiptlets \*

Once the blueprint for a product is known, it is time for the system to decide where to build it. The system will start by asking each equiptlet in the grid whether it is capable of performing a particular step. The equiptlets have capabilities which are based on the modules attached and therefore the services it provides. If an equiptlet has the right capability to perform a step, it will reply to the message, confirming that it can perform that step.

## Manufacturing Cycle

In order to create a product, we must first receive the blueprints for it. These blueprints find their way into the equiptlets through user input. The most desirable way to do so is using a GUI. In this GUI it should be possible to rebuild a certain blueprint with a set of simple steps; pick, place, paint, glue, etc. Once the design is finished, a product agent will be spawned with this blueprint. From this point onwards it will make sure the product will be fabricated.

After the product and required parts are available at the right equiptlet, the product steps will be executed by the equiptlets. The responsible product agent will receive feedback from the equiptlet containing information about the executed product step.



Once all the feasible equiptlets have been found, the product agent will start the scheduling process. During this process it will create a schedule based on which equiptlet can handle the most (consecutive) product steps, and has the least load. After an equiptlet has been chosen, the equiptlet will be contacted in order to schedule.

Whenever the product is ready to be produced, parts that are needed for production will have to be transported to the equiptlets. The product agent is responsible for transporting the parts to the proper equiptlet. Parts will be transported on a single robot, capable of carrying all parts needed for one complete product. This robot will navigate through the grid autonomously.

A product is defined by a collection of product steps. These product steps are abstract descriptions of manufacturing steps. Product steps can be processed by equiptlets which offer the required service. Services divide product steps in service steps, which are more specific actions. The service steps are divided in equiptlet steps by the modules. Equiptlet steps are concrete steps which ROS can perform.

## Example Translating Steps \*\*

Product Steps (Product Agent → Equiptlet Agent)	Service Steps (Service Agent → Hardware Agent)	Equiptlet Steps (Hardware Agent → ROS)
Place part of type Red Ball into Crate: 1,1,1 relative to Crate	Pickup: 2,1,1.5 relative to crate A, safe movement plane: 6 relative to crate A  Drop: 1,1,1.5 relative to crate B, safe movement plane: 6 relative to crate B	<ul style="list-style-type: none"> <li>Move delta robot to *,*,8 relative to crate A</li> <li>Move delta robot to 2,1,* relative to crate A</li> <li>Move delta robot to *,*,3.5 relative to crate A</li> <li>Activate gripper</li> <li>Move delta robot to *,*,8 relative to crate A</li> <li>Move delta robot to *,*,8 relative to crate B</li> <li>Move delta robot to 1,1,* relative to crate B</li> <li>Move delta robot to *,*,3.5 relative to crate B</li> <li>Deactivate gripper</li> <li>Move delta robot to *,*,8 relative to crate B</li> </ul>

## References

TEXT...

## Product Life after Production

The produced product logs can be used in different situations. When a product has a defect on a specific part, the product logs can be compared to the real product and production can be optimized. Future services like generating reparation schematics can be developed using these detailed production logs.