Product Steps (Product Agent → Equiplet Agent)	Service Steps (Service Agent → Hardware Agent)	Equiplet Steps (Hardware Agent → ROS)
Place part of type Red Ball into Crate: 1,1,1 relative to Crate	Pickup: 2,1,1.5 relative to crate A, safe movement plane: 6 relative to crate A	Move delta robot to *,*,8 relative to crate A
		Move delta robot to 2,1,* relative to crate A
		Move delta robot to *,*,3.5 relative to crate A
		Activate gripper
		Move delta robot to *,*,8 relative to crate A
	Drop: 1,1,1.5 relative to crate B, safe movement plane: 6 relative to crate B	Move delta robot to *,*,8 relative to crate B
		Move delta robot to 1,1,* relative to crate B
		Move delta robot to *,*,3.5 relative to crate B
		Deactivate gripper
		Move delta robot to *,*,8 relative to crate B