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# DS-011 Pixhawk Autopilot v5X Standard

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Revision date: May 25, 2021

#### **Abstract**

This document is the formal version of the Pixhawk industry standard that includes all aspects of the hardware standard required to build compatible autopilots.

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# **Document Revisions**

Revision	Editor	Reviewer	Comments
0.1.0	Lorenz Meier	David Sidrane	Initial specification
0.2.0	Lorenz Meier	David Sidrane	Addition of FMUv6X draft
0.3.0	Lorenz Meier	David Sidrane	Split up into focused documents
0.4.0	Michael Schaeuble	David Sidrane	Correct IO processor type in diagram on page 6
0.5.0	Michael Schaeuble	Lorenz Meier	Update v5X block diagram, sensor description and pinout, Ethernet Phy specification
0.6.0	Lorenz Meier	David Sidrane	Removed the requirement for temperature calibration
0.7.0	Ramón Roche	David Sidrane	Verify the sensor sets match design files and pinouts, update sensor location diagram, and add power requirement specifications

# **Contact and Public Developer Call**

This standard is being developed on a <u>public developer call</u>. For further questions, please contact the maintainer of the standard, <u>lorenz@px4.io</u>.

#### **Trademark Guideline**

Pixhawk is a registered trademark and is used to mark and protect the consistent use of this standard. The requirements for this are covered in this document: <u>Trademark Guideline</u>

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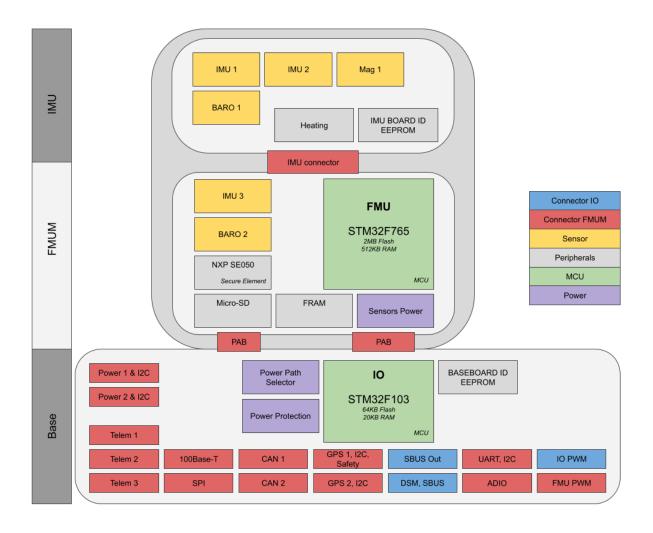
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# **Related Standards**

- DS-009 Pixhawk Connector Standard
- DS-010 Pixhawk Autopilot Bus Standard

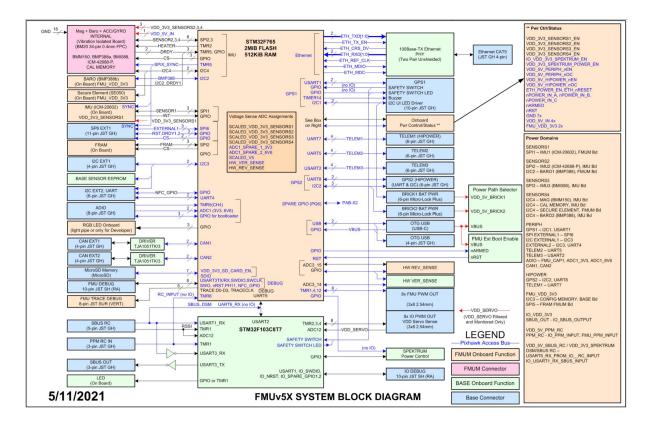
## FMUv5X Summary

#### Overview



**Note:** Please refer to the Sensor Set section for accurate sensor parts

#### **Detailed Block Diagram**



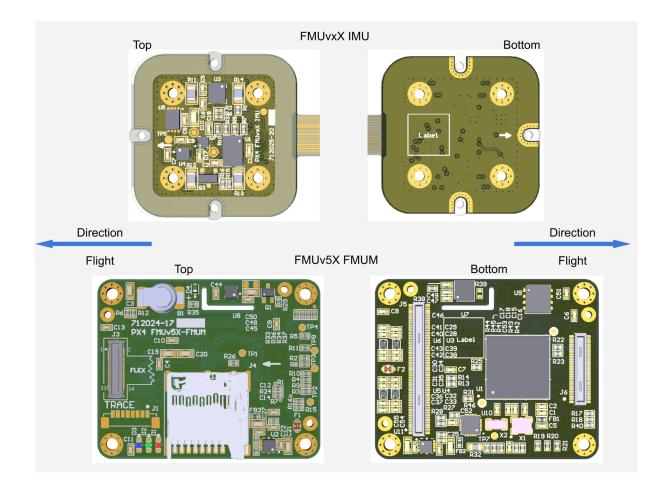
The FMUv5X generation brings the proven features from FMUv5 to a hardened form factor.

- Secure element for secure authentication of the drone (SE050)
- Ethernet interface for high-speed mission computer integration
  - Ethernet PHY: Microchip LAN8742AI-CZ-TR
- Three redundancy domains: Completely isolated sensor domains with separate buses and separate power control.
- It has redundant sensors on separate buses, allowing parallel and continuous operation even in the event of a hardware failure.
  - Some of the possible sensor configurations:
  - Bosch BMI088 accelerometer (vibration isolated)
  - Invensense ICM-20602
  - o TDK Invensense ICM 42688-P
  - Bosch BMM150 compass (vibration isolated)
  - Two Bosch BMP388 pressure sensors
  - GPS external mag + baro #1
  - GPS external mag + baro #2
  - Calibration EEPROM for baseboard sensors
  - On-IMU calibration EEPROM memory for high-accuracy sensors
- Automated sensor calibration eliminating varying signals and temperature
- FRAM memory for configuration data
- Operating temperature -40 to +85°C

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- Extensive power monitoring
  - o Two smart batteries on SMBus or more on UAVCAN
  - 5V rail monitoring
  - $\circ$  3.3V rail monitoring for CPU
  - o 3.3V rail monitoring for each sensor domain
- External sensor bus (SPI6)
- Redundant power supply: The autopilot can be powered from up to two power sources and every sensor set is powered by an independent LDO with independent power control
- Battery-backed real time clock for running security applications without GPS coverage
- For NFC one external I2C port needs to have an additional GPIO line and 5V to supply the external NFC reader.

## FMUv5X Sensors Locations



## **Sensor Sets**

Sensor sets comprised an FMU set of sensors and an IMU set of sensors. These are revisioned in pairs. (Rev 1, Rev 2, Rev 3)

# Sensor Set (Rev 1)

#### FMU Sensor Set (Rev 1)

#### FMU Board

Name	Sensor Type	Bus	Chip Select/ 7 Bit Addr	DRDY	Power Domain
U7 (IMU3)	ICM20602	SPI1	CS1	DRDY1	1
U8 (BARO2)	BMP388	I2C2	0x76 @00=0x50	DRDY1	2
U9 (FRAM)	FM25V02A-DG	SPI5	CS1	NA	FMU VDD 3.3
U10 (SE)	SE050C1HQ1/Z 01SCZ	I2C4	0x48	NA	4

## IMU Sensor Set (Rev 1)

#### **IMU** Board

Name	Sensor Type	Bus	Chip Select/ 7 Bit Addr	DRDY	Power Domain
U1 (IMU1)	BMI088 ACCEL	SPI3	CS1	NA	3
U1 (IMU1)	U1 (IMU1) BMI088 GYRO SPI3		CS2	DRDY2 INT3	3
U2 (MAG2) LIS2MDLTR I2C4 Not installed DNP		I <del>2C4</del>	<del>Oxle</del>	NA	4
U3 (IMU2)	ICM-42688-P	SPI2	CS1	DRDY2 INT2	2
U4 (BARO1)	U4 (BARO1) BMP388 I2C4		0x77 @00=0x50	NA	4
U5	EEPROM	I2C4	0x50	N/A	4
<del>U6 (IMU2)</del> <del>Not installed</del>	ICM20602 <b>DNP</b>	SPI2	CS1	DRDY2 INT2	2
U7 (MAG1)	BMM150	I2C4	0x10	NA	4



# Sensor Set (Rev 2)

## FMU Sensor (Rev 1)

See above.

## IMU Sensor Set (Rev 2)

#### IMU Board

Name	Sensor Type	Bus	Chip Select/ 7 Bit Addr	DRDY	Power Domain
U1 (IMU1)	ICM20649 ACCEL	SPI3	CS1	DRDY2 INT3	3
<del>U2 (MAG2)</del>	VCM5883 DNP	I <del>2C4</del>	<del>0x0C</del>	AA	4
U3 (IMU2)	ICM-42688-P	SPI2	CS1	DRDY2 INT2	2
U4 (BARO1)	BMP388	I2C4	0x77 @00=0x50	NA	4
U5	EEPROM	I2C4	0x50	N/A	4
<del>U6 (IMU2)</del> <del>Not installed</del>	ICM20602 <b>DNP</b>	<del>SPI2</del>	<del>CS1</del>	<del>DRDY2 INT2</del>	2
U7	BMM150	I2C4	0x10	NA	4



# Sensor Set (Rev 3)

## FMU Sensor (Rev 1)

See above.

## IMU Sensor Set (Rev 3)

#### IMU Board

Name	Sensor Type	Bus	Chip Select/ 7 Bit Addr	DRDY	Power Domain
U1 (IMU1)	BMI088 ACCEL	SPI3	CS1	NA	3
U1 (IMU1)	BMI088 GYRO	SPI3	CS2	DRDY2 INT3	3
U2 (MAG1)	RM3100	12C4	0x20	NA	4
U3 (IMU2)	ICM-42688-P	SPI2	CS1	DRDY2 INT2	2
U4 (BARO1)	DPS310	I2C4	0x76 @0x0D=0x10	NA	4
U5	EEPROM	I2C4	0x50	N/A	4
<del>U6 (IMU2)</del> <del>Not installed</del>	ICM20602 DNP	SPI2	CS1	DRDY2 INT2	2
<del>U7</del> (MAG2) <del>Not Installed</del>	BMM150 DNP	I2C4	0x10	NA	4



## Sensor Set (Rev BSP)

#### FMU Sensor (Rev 1)

See above.

## IMU Sensor Set (Rev BSP)

#### **IMU** Board

Name	Sensor Type	Bus	Chip Select/ 7 Bit Addr	DRDY	Power Domain
U1 (IMU1)	ICM-42688-P IMU	SPI3	CS1	NA	3
N/A	BMI088 GYRO	SPI3	CS2	DRDY2 INT3	3
<del>U2 (MAG2)</del> <del>Not installed</del>	LIS2MDLTR DNP	I2C4	Ox1e	NA	4
U3 (IMU2)	ICM-42688-P	SPI2	CS1	DRDY2 INT2	2
U4 (BARO1)	ICP-10110	I2C4	0x63 CMD=0xEFC8	NA	4
U5	EEPROM	I2C4	0x50	N/A	4
<del>U6 (IMU2)</del> <del>Not installed</del>		SPI2	CS1	DRDY2 INT2	2
U7	BMM150	I2C4	0x10	NA	4

**Note:** When referring to the pinout chart the CS Names are formed by BUSn\_CSn\_DEVICE: SPI1\_nCS1\_ICM20602

DRDY Names are formed by BUSn\_DRDYn\_DEVICE\_INTn: SPI2\_DRDY2\_ISM330\_INT2

**Note:** device names may reflect legacy devices names. What matters is the BUSn,CSn,DRDYn and the INTn.



# **Power Requirements**

# Voltage

Parameter	Min	Тур	Max	Unit
VDD_5V_IN	4.6	5.3	5.4	V

## Current

Parameter	Min	<b>Typ</b> @ 5.3V	<b>Max</b> @ 4.6V	Unit
V5X baseT + FMUM + IMU	-	3.88	4.40	А
V5X baseT	-	3.44	3.82	А
FMUM w/o IMU	-	0.21	0.36	А
FMUM w/ IMU	-	0.44	0.58	А

**Note:** Where IMU is listed, the IMU heater is assumed to be on 100% accounting for  $0.184-0.214~A~on~VDD\_5V\_IN$ 

## Full FMUv5X Pinout

At the time of the release of this document the reference pinout was version **RC17**. The current release of the reference pinout is found in this pinout sheet link.

#### FMUV5X\_stm32\_pinout - RC17

**NOTE**: The information contained below is for reference only. See the link above for the complete pinout reference.

			176-pin		
			STM32F765IIK		FMUV5X RC04 USAGE
			Signal		
0	PA	0	ADC1_IN0	Α	SCALED_VDD_3V3_SENSORS1
1	PA	1	ETH_REF_CLK	Ε	ETH_REF_CLK
2	PA	2	ETH_MDIO	Ε	ETH_MDIO
3	PA	3	USART2_RX	U	USART2_RX_TELEM3
4	PA	4	ADC1_IN4	Α	SCALED_VDD_3V3_SENSORS2
5	PA	5	SPI1_SCK	S	SPI1_SCK_SENSOR1_ICM20602
6	PA	6	SPI6_MISO	S	SPI6_MISO_EXTERNAL1
7	PA	7	ETH_CRS_DV	Ε	ETH_CRS_DV
8	PA	8	TIM1_CH1	Т	FMU_CH4
9	PA	9	USB_OTG_FS_VBU S	В	VBUS_SENSE
10	PA	10	TIM1_CH3	Т	FMU_CH2
11	PA	11	USB_OTG_FS_DM	В	USB_D_N
12	PA	12	USB_OTG_FS_DP	В	USB_D_P
13	PA	13	SWDIO	D	FMU_SWDIO
14	PA	14	SWCLK	D	FMU_SWCLK
15	PA	15	PA15	G	SPI6_nCS2_EXTERNAL1
16	РΒ	0	ADC1_IN8	Α	SCALED_VDD_3V3_SENSORS3
17	РΒ	1	ADC1_IN9	Α	SCALED_V5
18	РΒ	2	SPI3_MOSI	S	SPI3_MOSI_SENSOR3_BMI088
19	РВ	3	SPI6_SCK	S	SPI6_SCK_EXTERNAL1
20	РВ	4	SPI1_MISO	S	SPI1_MISO_SENSOR1_ICM20602
21	РΒ	5	SPI1_MOSI	S	SPI1_MOSI_SENSOR1_ICM20602
22	РВ	6	CAN2_TX	С	CAN2_TX
23	РΒ	7	I2C1_SDA	1	I2C1_SDA_BASE_GPS1_MAG_LED_PM1
24	РΒ	8	I2C1_SCL	1	I2C1_SCL_BASE_GPS1_MAG_LED_PM1
25	РΒ	9	UART5_TX	V	UART5_TX_TELEM2
26	ΡВ	10	TIM2_CH3	Т	HEATER
27	РΒ	11	ETH_TX_EN	Ε	ETH_TX_EN
28	ΡВ	12	CAN2_RX	С	CAN2_RX

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29	РВ		ETH_TXD1	Ε	ETH_TXD1
30	РВ		USART1_TX	U	USART1_TX_GPS1
31	РВ		USART1_RX	U	USART1_RX_GPS1
32	PC	0	ADC1_IN10	Α	ADC1_6V6
33	PC	1	ETH_MDC	Ε	ETH_MDC
34	PC	2	ADC1_IN12	Α	SCALED_VDD_3V3_SENSORS4
35	PC	3	ADC1_IN13	Α	ADC1_3V3
36	PC	4	ETH_RXD0	Ε	ETH_RXD0
37	PC	5	ETH_RXD1	Ε	ETH_RXD1
38	PC	6	USART6_TX	U	USART6_TX_TO_IONC
39	PC	7	USART6_RX	U	USART6_RX_FROM_IORC_INPUT
40	PC	8	UART5_RTS	V	UART5_RTS_TELEM2
41	PC	9	UART5_CTS	V	UART5_CTS_TELEM2
42	PC	10	SPI3_SCK	S	SPI3_SCK_SENSOR3_BMI088
43	PC	11	SPI3_MISO	S	SPI3_MISO_SENSOR3_BMI088
44	PC	12	PC12	G	nARMED
45	PC	13	PC13	G	VDD_3V3_SD_CARD_EN
46	PC	14	OSC32_IN	Х	32KHZ_IN
47	PC	15	OSC32_OUT	Х	32KHZ_OUT
48	PD	0	CAN1_RX	С	CAN1_RX
49	PD	1	CAN1_TX	С	CAN1_TX
50	PD	2	UART5_RX	V	UART5_RX_TELEM2
50					
51	PD	3	USART2_CTS	U	USART2_CTS_TELEM3
			USART2_CTS USART2_RTS	U	USART2_CTS_TELEM3 USART2_RTS_TELEM3
51	PD	4		+	<del></del>
51 52	PD PD	4 5	USART2_RTS	U	USART2_RTS_TELEM3
51 52 53	PD PD PD PD	4 5	USART2_RTS USART2_TX	U	USART2_RTS_TELEM3 USART2_TX_TELEM3
51 52 53 54	PD PD PD PD	4 5 6 7	USART2_RTS USART2_TX SDMMC2_CLK	U U SD	USART2_RTS_TELEM3  USART2_TX_TELEM3  SDMMC2_CLK
51 52 53 54 55	PD PD PD PD	4 5 6 7 8	USART2_RTS USART2_TX SDMMC2_CLK SDMMC2_CMD	U U SD SD	USART2_RTS_TELEM3  USART2_TX_TELEM3  SDMMC2_CLK  SDMMC2_CMD
51 52 53 54 55 56	PD PD PD PD PD	4 5 6 7 8 9	USART2_RTS USART2_TX SDMMC2_CLK SDMMC2_CMD USART3_TX	U U SD SD U	USART2_RTS_TELEM3  USART2_TX_TELEM3  SDMMC2_CLK  SDMMC2_CMD  USART3_TX_DEBUG
51 52 53 54 55 56 57	PD PD PD PD PD PD	4 5 6 7 8 9	USART2_RTS USART2_TX SDMMC2_CLK SDMMC2_CMD USART3_TX USART3_RX	U U SD SD U U	USART2_RTS_TELEM3  USART2_TX_TELEM3  SDMMC2_CLK  SDMMC2_CMD  USART3_TX_DEBUG  USART3_RX_DEBUG
51 52 53 54 55 56 57 58	PD PD PD PD PD PD PD	4 5 6 7 8 9 10	USART2_RTS USART2_TX SDMMC2_CLK SDMMC2_CMD USART3_TX USART3_RX PD10 PD11	U U SD SD U U	USART2_RTS_TELEM3  USART2_TX_TELEM3  SDMMC2_CLK  SDMMC2_CMD  USART3_TX_DEBUG  USART3_RX_DEBUG  FMU_nSAFETY_SWITCH_LED_OUT
51 52 53 54 55 56 57 58 59	PD PD PD PD PD PD PD	4 5 6 7 8 9 10 11 12	USART2_RTS USART2_TX SDMMC2_CLK SDMMC2_CMD USART3_TX USART3_RX PD10 PD11	U SD SD U U G	USART2_RTS_TELEM3  USART2_TX_TELEM3  SDMMC2_CLK  SDMMC2_CMD  USART3_TX_DEBUG  USART3_RX_DEBUG  FMU_nSAFETY_SWITCH_LED_OUT  SPI6_DRDY1_EXTERNAL1
51 52 53 54 55 56 57 58 59 60	PD PD PD PD PD PD PD PD	4 5 6 7 8 9 10 11 12 13	USART2_RTS USART2_TX SDMMC2_CLK SDMMC2_CMD USART3_TX USART3_RX PD10 PD11 PD12	U SD SD U U G G	USART2_RTS_TELEM3  USART2_TX_TELEM3  SDMMC2_CLK  SDMMC2_CMD  USART3_TX_DEBUG  USART3_RX_DEBUG  FMU_nSAFETY_SWITCH_LED_OUT  SPI6_DRDY1_EXTERNAL1  SPI6_DRDY2_EXTERNAL1
51 52 53 54 55 56 57 58 59 60 61	PD PD PD PD PD PD PD PD	4 5 6 7 8 9 10 11 12 13	USART2_RTS USART2_TX SDMMC2_CLK SDMMC2_CMD USART3_TX USART3_RX PD10 PD11 PD12 TIM4_CH2	U SD SD U U G G	USART2_RTS_TELEM3  USART2_TX_TELEM3  SDMMC2_CLK  SDMMC2_CMD  USART3_TX_DEBUG  USART3_RX_DEBUG  FMU_nSAFETY_SWITCH_LED_OUT  SPI6_DRDY1_EXTERNAL1  SPI6_DRDY2_EXTERNAL1  FMU_CH5
51 52 53 54 55 56 57 58 59 60 61 62	PD PD PD PD PD PD PD PD PD	4 5 6 7 8 9 10 11 12 13 14 15	USART2_RTS USART2_TX SDMMC2_CLK SDMMC2_CMD USART3_TX USART3_RX PD10 PD11 PD12 TIM4_CH2 TIM4_CH3	U U SD SD U G G T T	USART2_RTS_TELEM3  USART2_TX_TELEM3  SDMMC2_CLK  SDMMC2_CMD  USART3_TX_DEBUG  USART3_RX_DEBUG  FMU_nSAFETY_SWITCH_LED_OUT  SPI6_DRDY1_EXTERNAL1  SPI6_DRDY2_EXTERNAL1  FMU_CH5  FMU_CH6
51 52 53 54 55 56 57 58 59 60 61 62 63	PD P	4 5 6 7 8 9 10 11 12 13 14 15 0	USART2_RTS USART2_TX SDMMC2_CLK SDMMC2_CMD USART3_TX USART3_RX PD10 PD11 PD12 TIM4_CH2 TIM4_CH3 PD15	U U SD SD U U G G G T T G G	USART2_RTS_TELEM3  USART2_TX_TELEM3  SDMMC2_CLK  SDMMC2_CMD  USART3_TX_DEBUG  USART3_RX_DEBUG  FMU_nSAFETY_SWITCH_LED_OUT  SPI6_DRDY1_EXTERNAL1  SPI6_DRDY2_EXTERNAL1  FMU_CH5  FMU_CH6  VDD_3V3_SENSORS2_EN
51 52 53 54 55 56 57 58 59 60 61 62 63 64 65	PD P	4 5 6 7 8 9 10 11 12 13 14 15 0	USART2_RTS USART2_TX SDMMC2_CLK SDMMC2_CMD USART3_TX USART3_RX PD10 PD11 PD12 TIM4_CH2 TIM4_CH2 TIM4_CH3 PD15 UART8_RX UART8_TX	U U SD SD U U G G C V V	USART2_RTS_TELEM3  USART2_TX_TELEM3  SDMMC2_CLK  SDMMC2_CMD  USART3_TX_DEBUG  USART3_RX_DEBUG  FMU_nSAFETY_SWITCH_LED_OUT  SPI6_DRDY1_EXTERNAL1  SPI6_DRDY2_EXTERNAL1  FMU_CH5  FMU_CH5  FMU_CH6  VDD_3V3_SENSORS2_EN  UART8_RX_GPS2  UART8_TX_GPS2
51 52 53 54 55 56 57 58 59 60 61 62 63 64	PD P	4 5 6 7 8 9 10 11 12 13 14 15 0	USART2_RTS USART2_TX SDMMC2_CLK SDMMC2_CMD USART3_TX USART3_RX PD10 PD11 PD12 TIM4_CH2 TIM4_CH3 PD15 UART8_RX	U U SD SD U U G G G V	USART2_RTS_TELEM3  USART2_TX_TELEM3  SDMMC2_CLK  SDMMC2_CMD  USART3_TX_DEBUG  USART3_RX_DEBUG  FMU_nSAFETY_SWITCH_LED_OUT  SPI6_DRDY1_EXTERNAL1  SPI6_DRDY2_EXTERNAL1  FMU_CH5  FMU_CH6  VDD_3V3_SENSORS2_EN  UART8_RX_GPS2
51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66	PD P	4 5 6 7 8 9 10 11 12 13 14 15 0 1	USART2_RTS USART2_TX SDMMC2_CLK SDMMC2_CMD USART3_TX USART3_RX PD10 PD11 PD12 TIM4_CH2 TIM4_CH2 TIM4_CH3 PD15 UART8_RX UART8_TX PE2 PE3	U U SD SD U U G G C V V D	USART2_RTS_TELEM3  USART2_TX_TELEM3  SDMMC2_CLK  SDMMC2_CMD  USART3_TX_DEBUG  USART3_RX_DEBUG  FMU_nSAFETY_SWITCH_LED_OUT  SPI6_DRDY1_EXTERNAL1  SPI6_DRDY2_EXTERNAL1  FMU_CH5  FMU_CH5  FMU_CH6  VDD_3V3_SENSORS2_EN  UART8_RX_GPS2  UART8_TX_GPS2  TRACECLK  nLED_RED
51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67	PD P	4 5 6 7 8 9 10 11 12 13 14 15 0 1 2 3 4	USART2_RTS USART2_TX SDMMC2_CLK SDMMC2_CMD USART3_TX USART3_RX PD10 PD11 PD12 TIM4_CH2 TIM4_CH3 PD15 UART8_RX UART8_TX PE2 PE3 PE4	U U SD SD U U G G C V V D G G G G	USART2_RTS_TELEM3  USART2_TX_TELEM3  SDMMC2_CLK  SDMMC2_CMD  USART3_TX_DEBUG  USART3_RX_DEBUG  FMU_nSAFETY_SWITCH_LED_OUT  SPI6_DRDY1_EXTERNAL1  SPI6_DRDY2_EXTERNAL1  FMU_CH5  FMU_CH6  VDD_3V3_SENSORS2_EN  UART8_RX_GPS2  UART8_TX_GPS2  TRACECLK  nLED_RED  nLED_GREEN
51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68	PD PE PE PE PE	4 5 6 7 8 9 10 11 12 13 14 15 0 1 2 3 4 5	USART2_RTS USART2_TX SDMMC2_CLK SDMMC2_CMD USART3_TX USART3_RX PD10 PD11 PD12 TIM4_CH2 TIM4_CH2 TIM4_CH3 PD15 UART8_RX UART8_TX PE2 PE3 PE4 PE5	UUUSDSDSDUUUGGGGGVVVVDGGGGGGGGGGGGGGGGGG	USART2_RTS_TELEM3  USART2_TX_TELEM3  SDMMC2_CLK  SDMMC2_CMD  USART3_TX_DEBUG  USART3_RX_DEBUG  FMU_nSAFETY_SWITCH_LED_OUT  SPI6_DRDY1_EXTERNAL1  SPI6_DRDY2_EXTERNAL1  FMU_CH5  FMU_CH5  FMU_CH6  VDD_3V3_SENSORS2_EN  UART8_RX_GPS2  UART8_TX_GPS2  TRACECLK  nLED_RED  nLED_GREEN  nLED_BLUE
51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70	PD PD PD PD PD PD PD PD PD PE PE PE PE PE	4 5 6 7 8 9 10 11 12 13 14 15 0 1 2 3 4 5 6	USART2_RTS USART2_TX SDMMC2_CLK SDMMC2_CMD USART3_TX USART3_RX PD10 PD11 PD12 TIM4_CH2 TIM4_CH3 PD15 UART8_RX UART8_TX PE2 PE3 PE4 PE5 SPI4_MOSI	UUUSDSDSDUUUGGGGGVVVDDGGGGGGSSS	USART2_RTS_TELEM3  USART2_TX_TELEM3  SDMMC2_CLK  SDMMC2_CMD  USART3_TX_DEBUG  USART3_RX_DEBUG  FMU_nSAFETY_SWITCH_LED_OUT  SPI6_DRDY1_EXTERNAL1  SPI6_DRDY2_EXTERNAL1  FMU_CH5  FMU_CH5  FMU_CH6  VDD_3V3_SENSORS2_EN  UART8_RX_GPS2  UART8_TX_GPS2  TRACECLK  nLED_RED  nLED_GREEN  nLED_BLUE  SPI4_MOSI_SENSOR4_BMM150
51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68	PD PE PE PE PE	4 5 6 7 8 9 10 11 12 13 14 15 0 1 2 3 4 5 6 7	USART2_RTS USART2_TX SDMMC2_CLK SDMMC2_CMD USART3_TX USART3_RX PD10 PD11 PD12 TIM4_CH2 TIM4_CH2 TIM4_CH3 PD15 UART8_RX UART8_TX PE2 PE3 PE4 PE5	UUUSDSDSDUUUGGGGGVVVVDGGGGGGGGGGGGGGGGGG	USART2_RTS_TELEM3  USART2_TX_TELEM3  SDMMC2_CLK  SDMMC2_CMD  USART3_TX_DEBUG  USART3_RX_DEBUG  FMU_nSAFETY_SWITCH_LED_OUT  SPI6_DRDY1_EXTERNAL1  SPI6_DRDY2_EXTERNAL1  FMU_CH5  FMU_CH6  VDD_3V3_SENSORS2_EN  UART8_RX_GPS2  UART8_TX_GPS2  TRACECLK  nLED_RED  nLED_GREEN  nLED_BLUE

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73	PE	۵	UART7_RTS	V	UART7_RTS_TELEM1
74		10	UART7_KT3	V	
75	PE		TIM1 CH2	T	UART7_CTS_TELEM1  FMU_CH3
76		12		S	_
			SPI4_SCK		SPI4_SCK_SENSOR4_BMM150
77		13	SPI4_MISO	S	SPI4_MISO_SENSOR4_BMM150
78		14	TIM1_CH4	T	FMU_CH1
79		15	PE15	G	VDD_5V_PERIPH_nOC
80	PF		I2C2_SDA	1	I2C2_SDA_BASE_GPS2_MAG_LED_PM2
81	PF	1	I2C2_SCL	I	I2C2_SCL_BASE_GPS2_MAG_LED_PM2
82	PF		PF2	G	SPI1_DRDY1_ICM20602
83	PF		PF3	G	SPI4_DRDY1_BMM150_DRDY
84	PF	4	ADC3_IN14	Α	HW_VER_SENSE
85	PF		ADC3_IN15	Α	HW_REV_SENSE
86	PF	6	UART7_RX	V	UART7_RX_TELEM1
87	PF	7	SPI5_SCK	S	SPI5_SCK_FRAM
88	PF		SPI5_MISO	S	SPI5_MISO_FRAM
89	PF	9	TIM14_CH1	Т	BUZZER_1
90	PF	10	PF10	G	SPI6_nRESET_EXTERNAL1
91	PF	11	SPI5_MOSI	S	SPI5_MOSI_FRAM
92	PF	12	PF12	G	VDD_5V_HIPOWER_nEN
93	PF	13	PF13	G	VDD_5V_HIPOWER_nOC
94	PF	14	I2C4_SCL	1	I2C4_SCL_FMU
95	PF	15	I2C4_SDA	1	I2C4_SDA_FMU
96	PG	0	PG0	G	HW_VER_REV_DRIVE
97	PG	1	PG1	G	nPOWER_IN_A
98	PG	2	PG2	G	nPOWER_IN_B
99	PG	3	PG3	G	nPOWER_IN_C
100	PG	4	PG4	G	VDD_5V_PERIPH_nEN
101	PG	5	PG5	G	I2C2_DRDY1_BMP388
102	PG	6	PG6	G	PG6
103	PG	7	PG7	G	SPI5_nCS1_FRAM
104	PG	8	PG8	G	VDD_3V3_SENSORS4_EN
105	PG	9	SDMMC2_D0	SD	SDMMC2_D0
106	PG	10	SDMMC2 D1	SD	SDMMC2_D1
107	PG	11	SDMMC2_D2	SD	SDMMC2_D2
108			SDMMC2 D3	SD	SDMMC2_D3
109			ETH_TXD0	Ε	ETH TXD0
110			SPI6_MOSI	S	SPI6_MOSI_EXTERNAL1
111			PG15	G	ETH_POWER_EN
112			OSC_IN	Х	16 MHZ IN
113			OSC_OUT	X	16 MHZ OUT
114			PH2	G	VDD 3V3 SPEKTRUM POWER EN
115			PH3	G	NFC GPIO
116			PH4	G	FMU_SAFETY_SWITCH_IN
110	ГΠ	4	гП4	J	FIVIO_SAFETT_SVVITCH_IIV

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117	PH	5	PH5	G	SPI2_nCS1_ISM330
118	РΗ	6	TIM12_CH1	Т	FMU_CH7
119	РН	7	I2C3_SCL	1	I2C3_SCL_BASE_MS5611_BARBED_EXTERNAL1
120	РΗ	8	I2C3_SDA	1	I2C3_SDA_BASE_MS5611_BARBED_EXTERNAL1
121	РН	9	TIM12_CH2	Т	FMU_CH8
122	PH	10	TIM5_CH1	Т	SPIX_SYNC
123	РН	11	PH11	G	PH11
124	PH	12	TIM5_CH3	Т	SPI2_DRDY2_ISM330_INT2
125	PH	13	UART4_TX	V	UART4_TX
126	PH	14	UART4_RX	V	UART4_RX
127	PH	15	PH15	G	SPI4_nCS1_BMM150
128	PI	0	TIM5_CH4	Т	FMU_CAP1
129	PI	1	SPI2_SCK	S	SPI2_SCK_SENSOR2_ISM330
130	PI	2	SPI2_MISO	S	SPI2_MISO_SENSOR2_ISM330
131	PI	3	SPI2_MOSI	S	SPI2_MOSI_SENSOR2_ISM330
132	PI	4	PI4	G	SPI3_nCS1_BMI088_ACCEL
133	PI	5	TIM8_CH1_IN	Т	FMU_PPM_INPUT
134	PI	6	PI6	G	SPI3_DRDY1_BMI088_INT1_ACCEL
135	PI	7	PI7	G	SPI3_DRDY2_BMI088_INT3_GYRO
136	PI	8	PI8	G	SPI3_nCS2_BMI088_GYRO
137	PI	9	PI9	G	SPI1_nCS1_ICM20602
138	PI	10	PI10	G	SPI6_nCS1_EXTERNAL1
139	PI	11	PI11	G	VDD_3V3_SENSORS1_EN