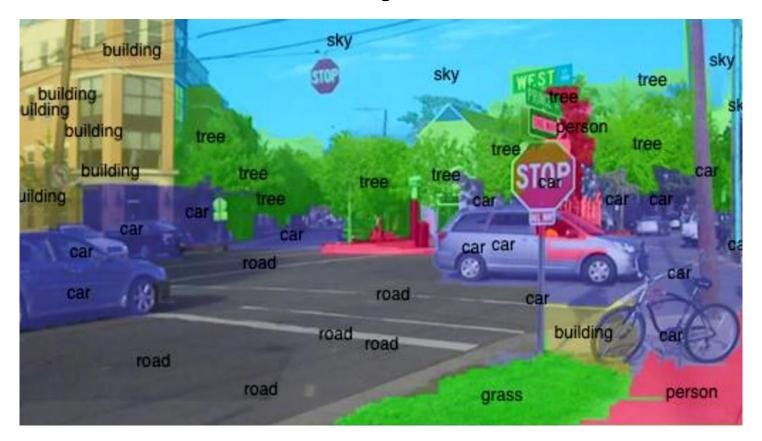
# Intro to Computer Vision



Yoni Chechik Computer Vision course

### contents

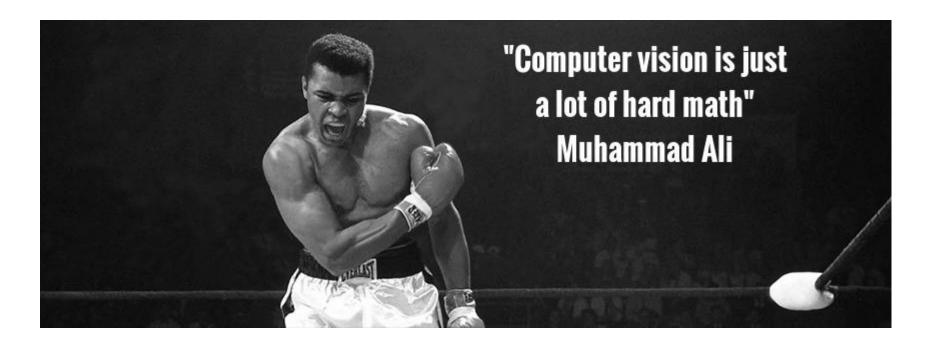
- Course details
- What is computer vision (CV)?
- Course outline
- Intro to Python

### References

Lectures Based on the book: Computer Vision:
 Algorithms and Applications, 2010, Richard Szeliski (<a href="http://szeliski.org/Book/">http://szeliski.org/Book/</a>)

# **Prerequisites**

- No prior knowledge in signal/image processing is assumed.
- Heavy use in algebra and calculus- mathematical maturity is assumed.

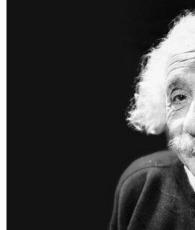


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- Course details
- What is computer vision (CV)?
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Don't believe
everything you read
on the internet just
because there's a
picture with a quote
next to it.

ALBERT EINSTEIN

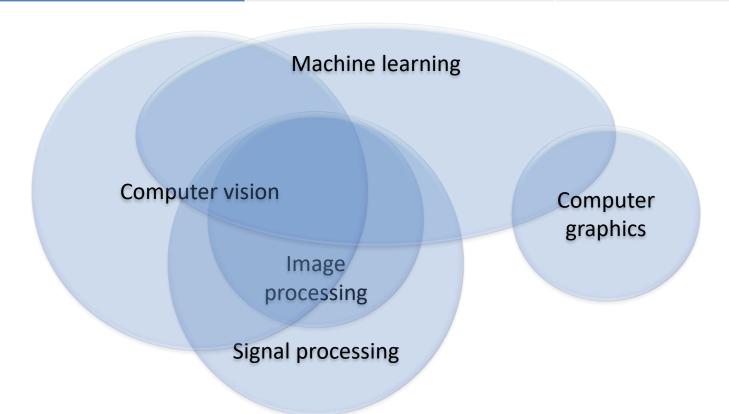


### What is CV?

- Computer vision is an interdisciplinary scientific field that deals with how computers can be made to gain high-level understanding from digital images or videos. [Wikipedia]
- Image processing is an umbrella term for many functions that analyze images or convert one representation of an image into another.

### What is CV?

Output	Data	Image
Input		
Data	Signal processing	Computer graphics
Image	Computer vision	Image processing



# Why CV?



# Why CV?

### **Top Public Company Acquirors**



#### **Embedded Vision/Computer Vision M&A Company** & Moodstocks Alphabet DNNresearch Undecidable! October - 2012 March - 2013 July - 2016 October - 2016 \$45.0M NA NA NA PrimeSense **EMOTIENT** REALFACE November - 2013 January - 2016 February - 2017 January - 2016 \$360.0M NA NA NA Chiaro Assist Ware *Ao ense* COGNEX **Technologies** November - 2016 May - 2005 July - 2008 August-2016 \$115.0M \$3.0M \$2.4M \$4.7M **a**works Movidius 34 MOBILEYE April - 2012 May - 2016 September - 2016 September - 2017 \$31.0M NA \$392.1M \$15,300.0M **EUVISION** kooaba SCYFER



September - 2014

NA

August - 2017

NA

January - 2014

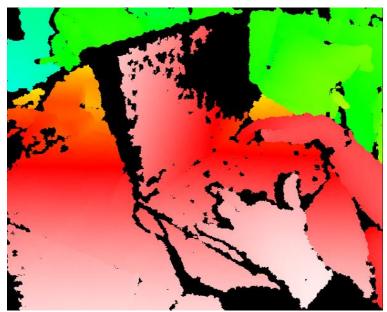
NA

### **PrimeSense == Kinect**

- Kinect for Xbox 360: 3D scanner system using Light
   Coding approach for 3D reconstruction.
- KinectFusion [Newcombe et al., 2011] : <a href="https://www.youtube.com/watch?v=KOUSSIKUJ-A">https://www.youtube.com/watch?v=KOUSSIKUJ-A</a>







# Why CV?

### **Top Public Company Acquirors**



#### **Company**

#### **Embedded Vision/Computer Vision M&A**

### Alphabet









October - 2012 \$45.0M

March - 2013 NA

July - 2016 NA













November - 2013 \$360.0M

January - 2016 NA

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February - 2017 NA





May - 2005 \$115.0M



July - 2008 \$3.0M



August-2016 \$2.4M



November - 2016 \$4.7M





April - 2012 \$31.0M



May - 2016 NA



September - 2016 \$392.1M



September - 2017 \$15,300.0M





January - 2014 NA



September - 2014 NA



August - 2017 NA

# Mobileye

- Mobileye is an Israeli subsidiary of Intel corporation that develops vision-based advanced driver-assistance systems (ADAS) providing warnings for collision prevention and mitigation. [Wikipedia]
- https://www.youtube.com/watch?v=JDUb6CurYJM



# Why CV?

### StartupHub.ai

#### ISRAEL'S COMPUTER VISION STARTUPS

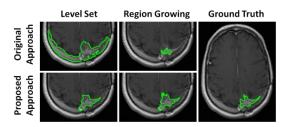


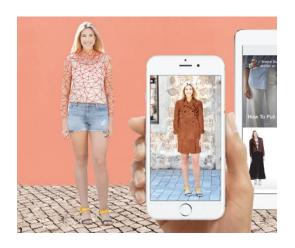
© DANIEL SINGER 2019

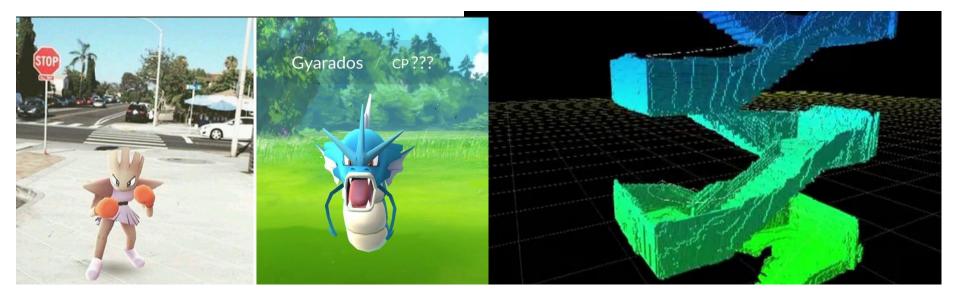
# **More CV related topics**

- Virtual/augmented reality
- navigation
- Gaming
- medicine
- And much more...

### **Segmentation Results**







### contents

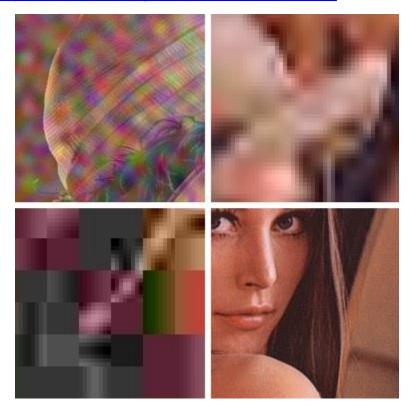
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# **Course outline**

#	subject
1	Introduction to CV + Python: numpy, matplotlib.
2	Image processing recap: convolutions, LPF, HPF, morphology, connected
	components, gamma correction, histogram equalization.
3	Edge detection: gradient (roberts, prewitt, sobel), Laplacian, DoG
	(derivative of Gaussian), canny edge detector.
4	Shape detection: template matching, Hough transform.
5	Digital cameras: image formation, transformation, interpolation.
6	Camera calibration: extrinsic, intrinsic, radial distortion.
7	Stereo vision :dual camera rectification, triangulation.
8	3D cameras: LIDAR, KINECT, structured light, planoptic
9	Line fit: least squares, total least squares, RANSAC,
10	Feature extraction: SIFT, image stitching (scale space).
11	Neural networks: intro, CNN, MNIST, Alexnet.
12	Final project 1
13	Final project 2

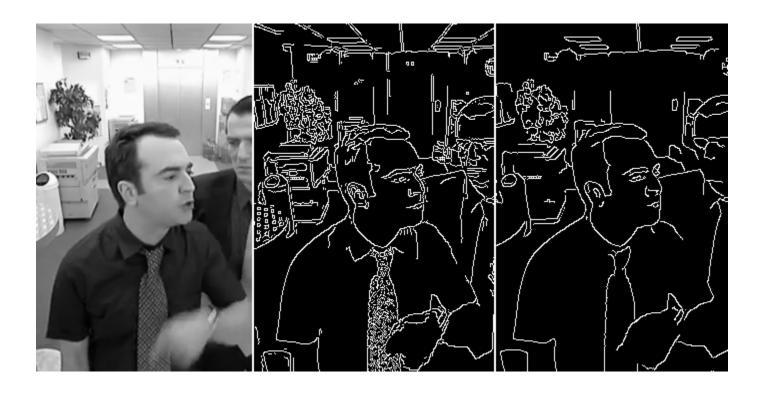
# **Image processing**

 Read more about Lenna – the standard test image: <a href="https://en.wikipedia.org/wiki/Lenna">https://en.wikipedia.org/wiki/Lenna</a>



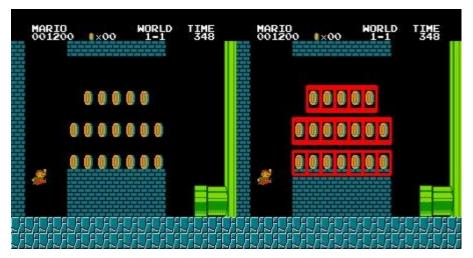
# **Edge Detection**

- https://www.youtube.com/watch?v=hQ-bpfdWQh8
- https://pinetools.com/image-edge-detection



# **Shape detection**

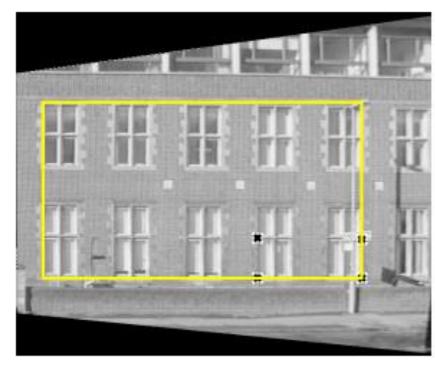




### **Digital cameras**

- Image formation: https://www.youtube.com/watch?v=dY0K65eXhkA
- Transformation and interpolation.





from Hartley & Zisserman

# Image calibration

• Fisheye correction from go-pro for example

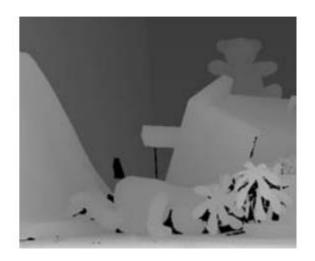


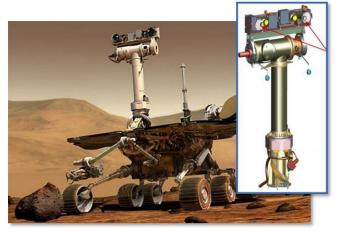
### **Stereo & 3d cameras**

https://www.youtube.com/watch?v=PySBQ8Q\_R8k

















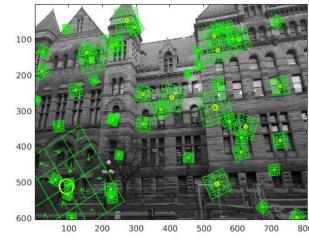




(a)

# Fitting & Feature extraction

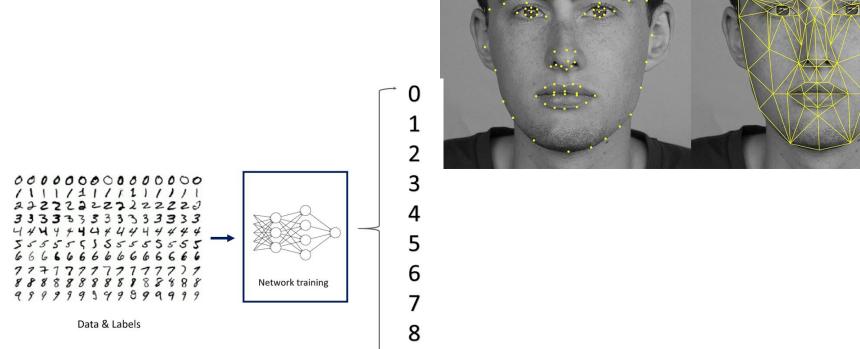
- Extract interesting points from image for later recognition, stitching, learning and more.
- http://www.in2white.com/



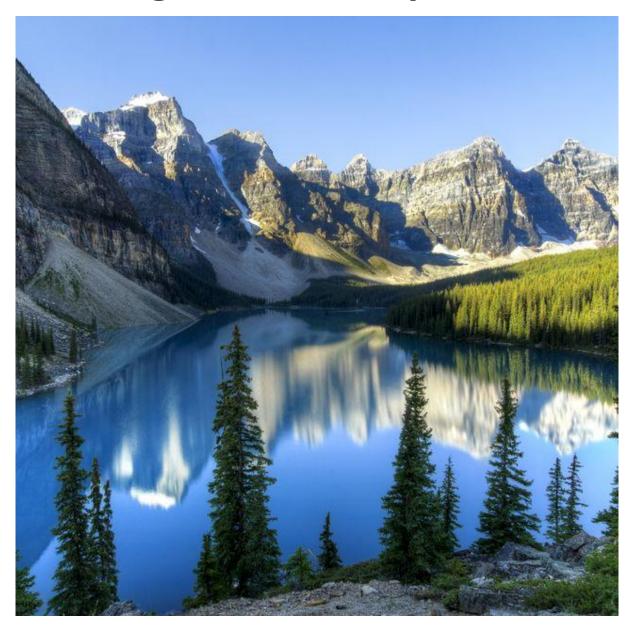


### **Neural networks**

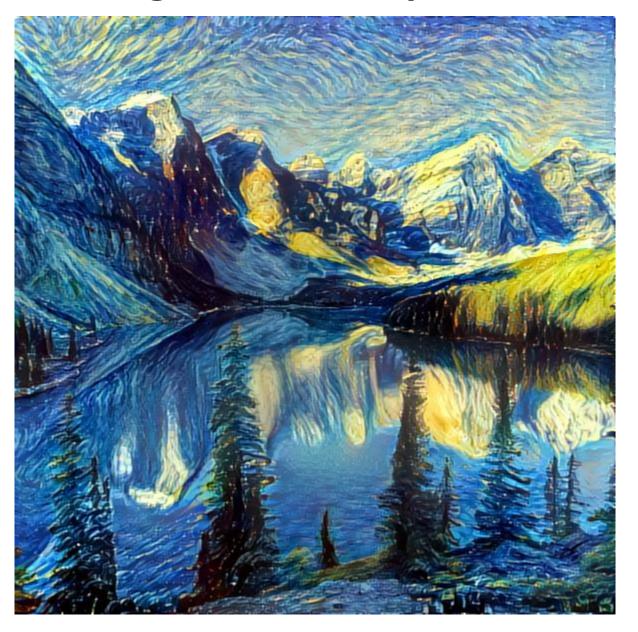
- https://deepdreamgenerator.com/generator
- https://quickdraw.withgoogle.com



# Dream generator- style transfer



# Dream generator- style transfer



### And some more AI stuff

- Deep fake
  - https://www.youtube.com/watch?v=cQ54GDm1eL0
  - https://www.youtube.com/watch?v=-QvIX3cY4lc
- Nvidia GauGAN
  - https://www.youtube.com/watch?v=p5U4NgVGAwg&t=40s
  - http://nvidia-research-mingyuliu.com/gaugan

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