Mesure de H_0 avec le quasar lentillé RXJ1131-1231

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Résumé

1 Introduction

3 Méthodologie

$$c\Delta t_{ij} = D_{\Delta t} \left(\frac{(\boldsymbol{\theta_i} - \boldsymbol{\beta})^2}{2} - \frac{(\boldsymbol{\theta_j} - \boldsymbol{\beta})^2}{2} - \psi(\boldsymbol{\theta_i}) + \phi(\boldsymbol{\theta_j}) \right)$$
(1)

$$D_{\Delta t} \equiv (1 + z_{\ell}) \frac{D_{\ell} D_s}{D_{\ell s}} \propto H_0^{-1}$$
 (2)

2 Théorie

$$\nabla_{\theta}^{2}\psi = 2\kappa(\boldsymbol{\theta}) \tag{3}$$

$$\psi(\boldsymbol{\theta}) = \frac{1}{\pi} \int_{\mathbb{R}^2} \kappa(\boldsymbol{\theta}') \ln(\boldsymbol{\theta} - \boldsymbol{\theta}') d^2 \boldsymbol{\theta}'$$
 (4)

$$\kappa(\boldsymbol{\theta}) \equiv \frac{\Sigma(\boldsymbol{\theta})}{\Sigma_{\rm cr}} \tag{5}$$

$$\Sigma_{\rm cr} \equiv \frac{c^2}{4\pi G} \frac{D_s}{D_\ell D_{\ell s}} \tag{6}$$

$$\beta = \theta - \alpha(\theta) \tag{7}$$

$$\alpha(\boldsymbol{\theta}) = \frac{1}{\pi} \int_{\mathbb{R}^2} \kappa(\boldsymbol{\theta}') \frac{\boldsymbol{\theta} - \boldsymbol{\theta}'}{|\boldsymbol{\theta} - \boldsymbol{\theta}'|} d^2 \boldsymbol{\theta}'$$
 (8)

$$\kappa(\boldsymbol{\theta}) = \frac{3-n}{2} \left(\frac{\theta_E}{\sqrt{\frac{\theta_1^2}{1-e} + \theta_2^2 (1-e)}} \right)^{n-1} \tag{9}$$

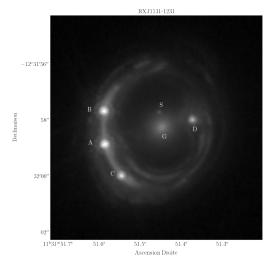


Figure 1

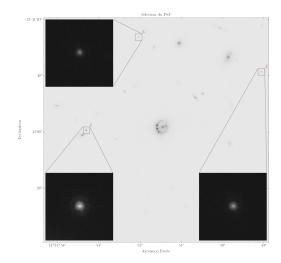


FIGURE 2

Images	$ heta_1 \ ('')$	θ_2 (")
A	1.8998	0.5659
В	1.8717	-0.6207
C	1.2654	-1.7385
D	-1.3217	0.2568

5 Conclusion

$$\log P(\underbrace{\mathbf{d}_{\mathrm{ACS}}}_{\mathcal{D}} | \underbrace{\theta_{E}, e, n, \gamma, \eta, \mathbf{s}}_{\mathcal{M}}) \propto -\frac{1}{2} \sum_{i=1}^{|\mathcal{D}|} \frac{(d_{ACS,i} - d_{\mathcal{M},i})^{2}}{\sigma_{i}^{2}} -\frac{1}{2} \sum_{i< j}^{4} \frac{(\beta_{i} - \beta_{i})^{2}}{(d\theta)^{2}}$$

$$(10)$$

$$\log P(\Delta t | D_{\Delta t}, \mathcal{M}) \propto -\frac{1}{2} \sum_{i} \frac{(\Delta t_{i} - \Delta t (D_{\Delta t, \mathcal{M}}))^{2}}{\sigma_{\Delta t}^{2}} + \log P(\mathbf{d}_{ACS} | \mathcal{M})$$
(11)

4 Résultats et discussion

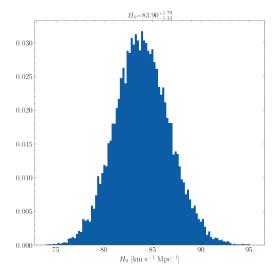


Figure 4

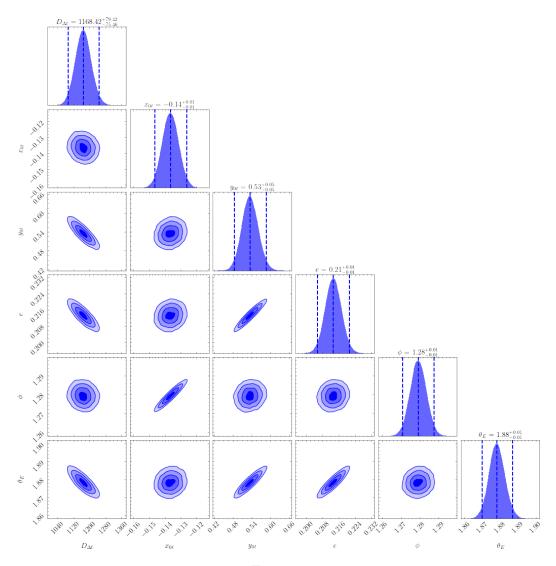


FIGURE 3