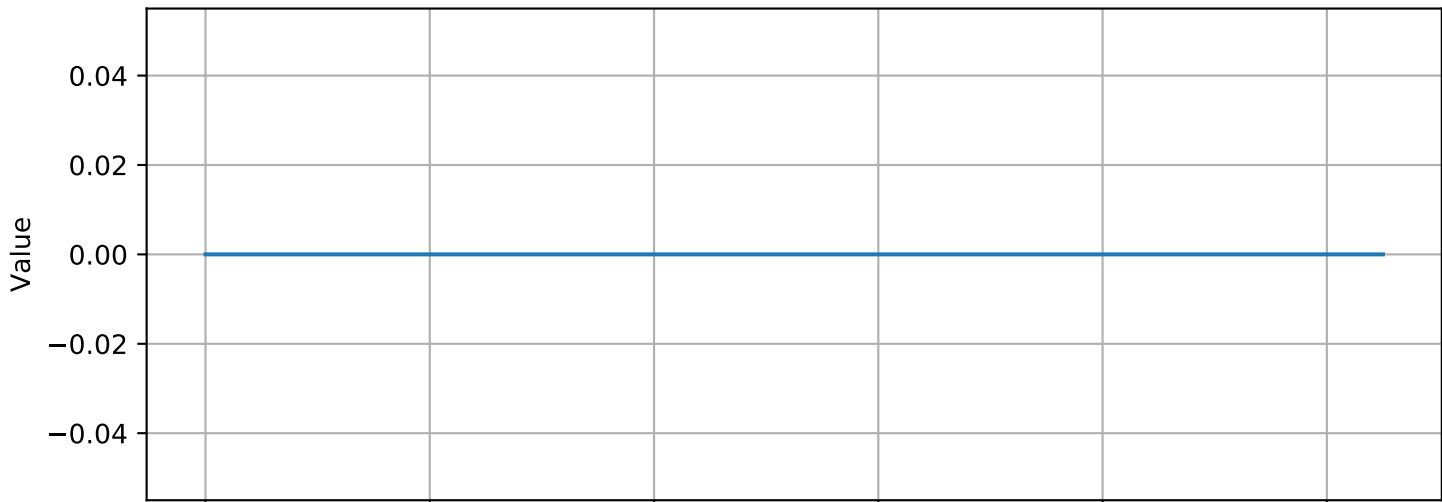
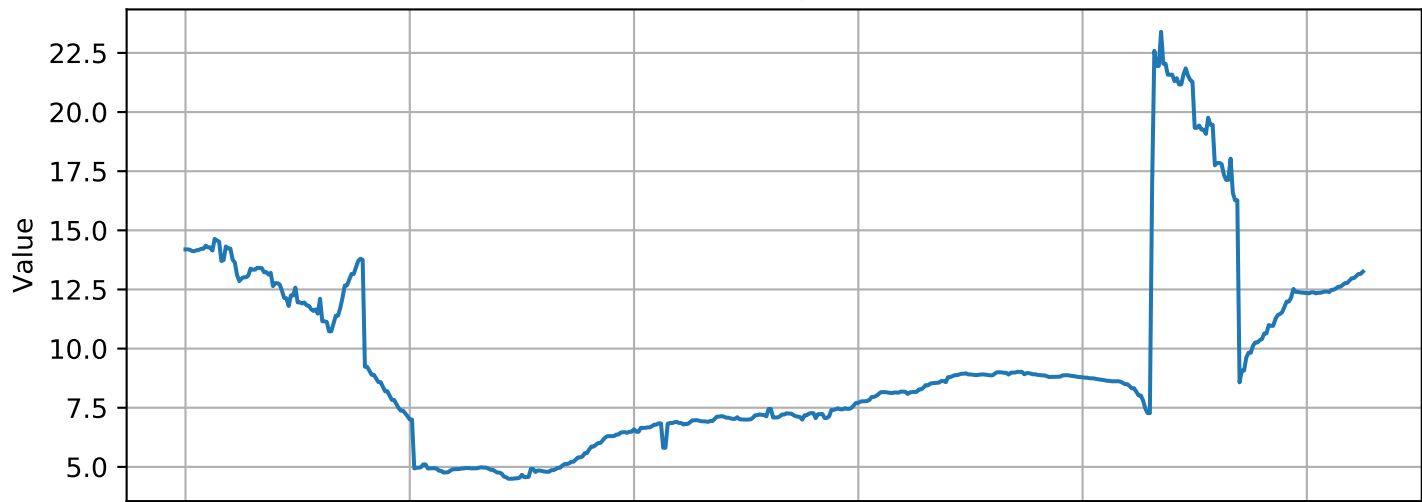


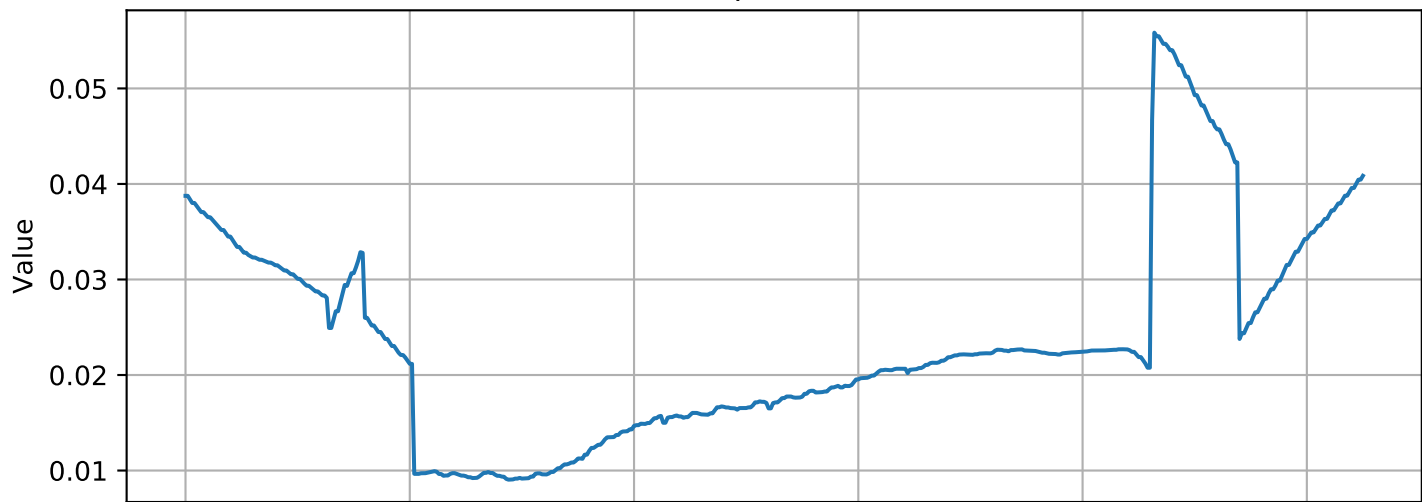
Plot for id



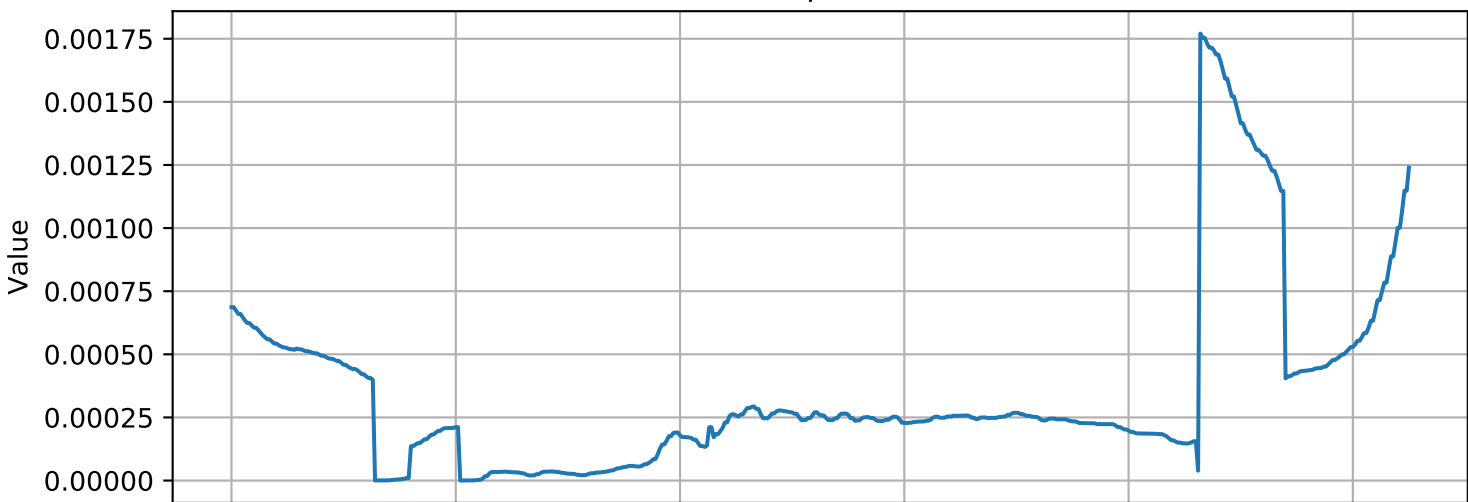
Plot for angleError



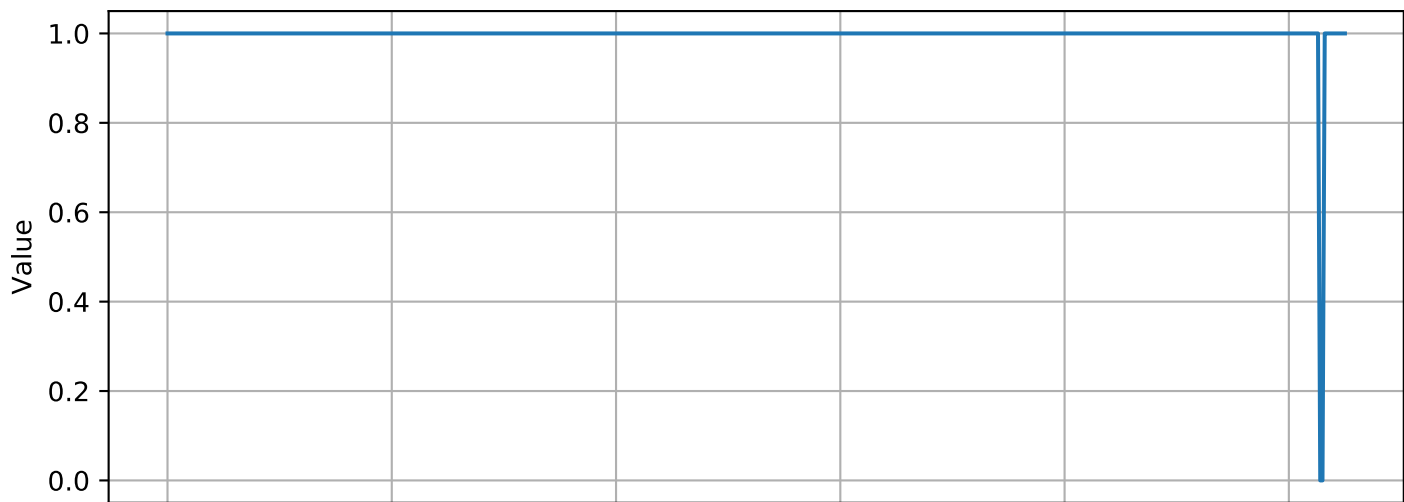
Plot for positionError



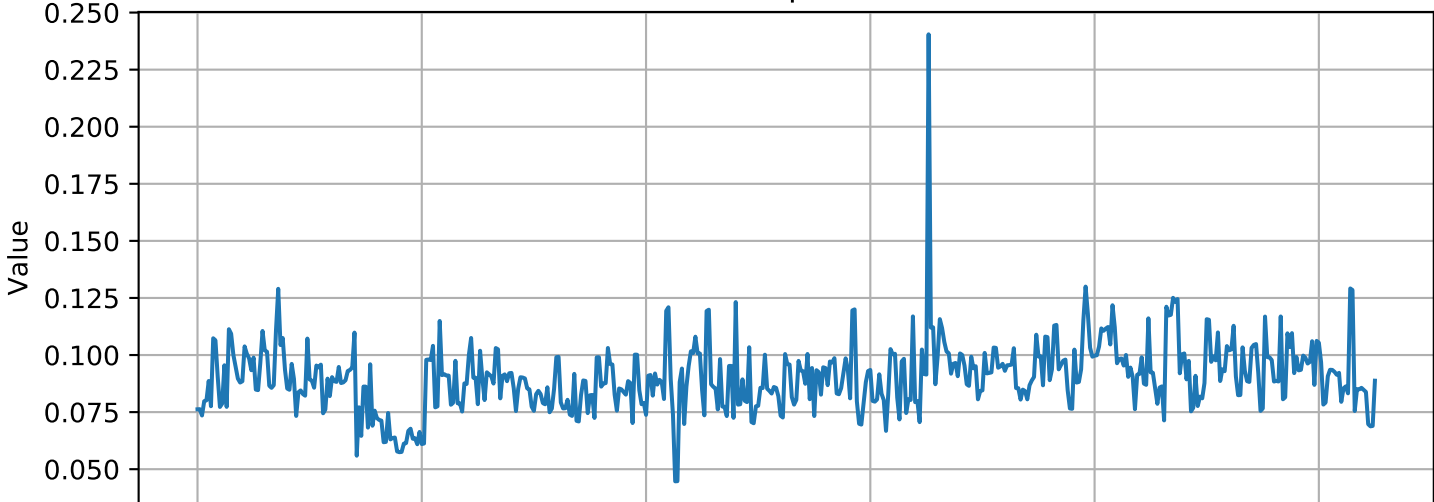
Plot for optimalCost



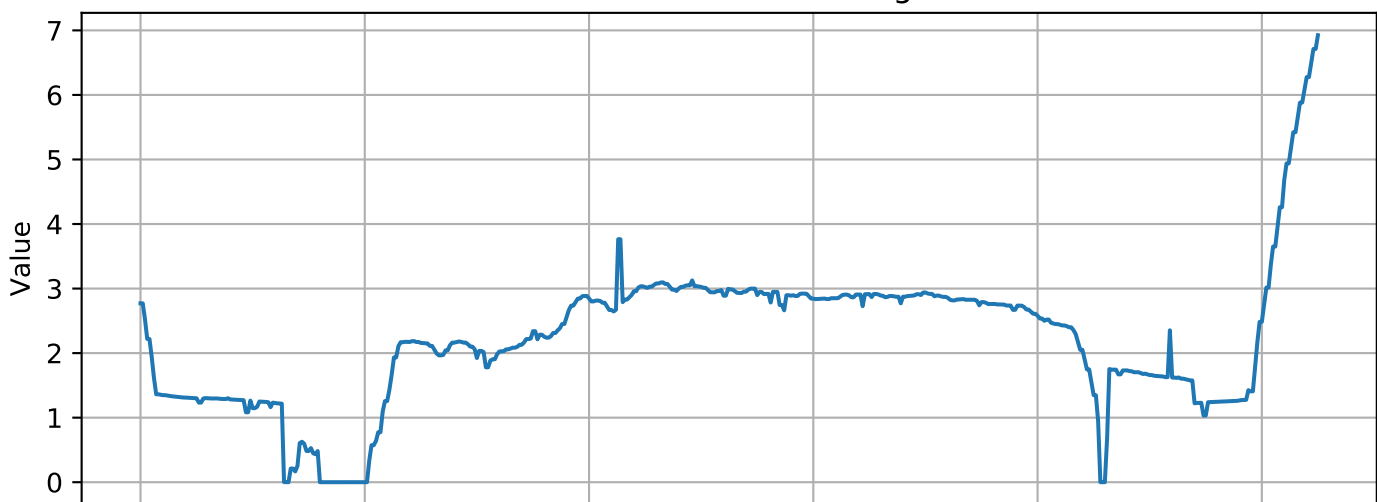
Plot for success



Plot for completionTime

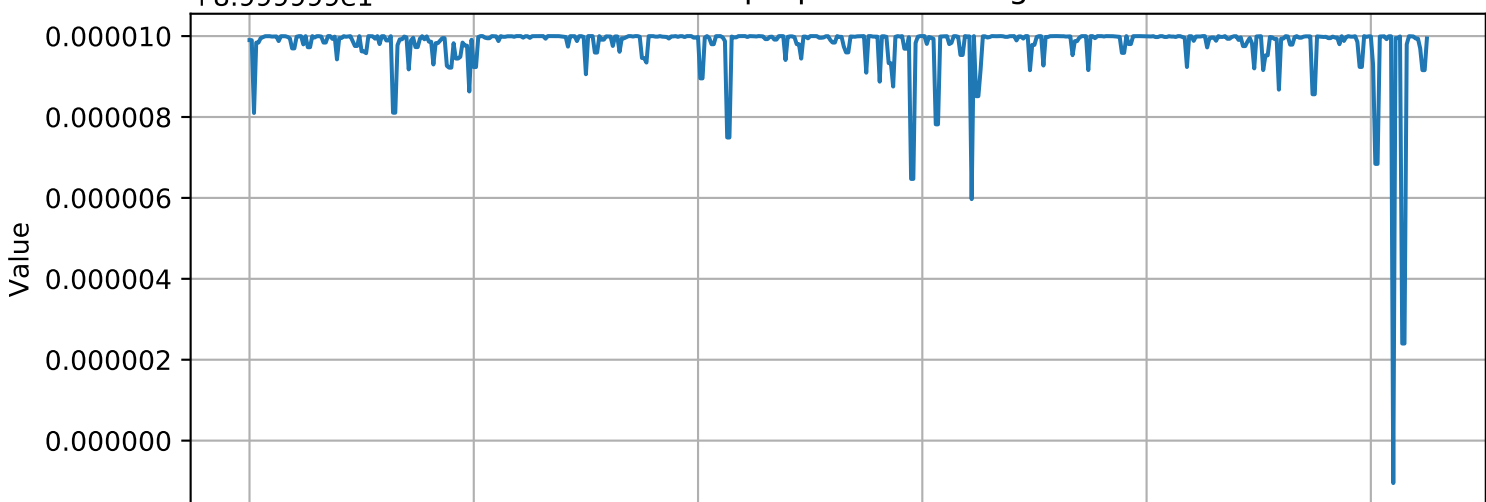


Plot for centroidViewAngle



+8.9999999e1

Plot for perpendicularAngle



Plot for viewDistance

