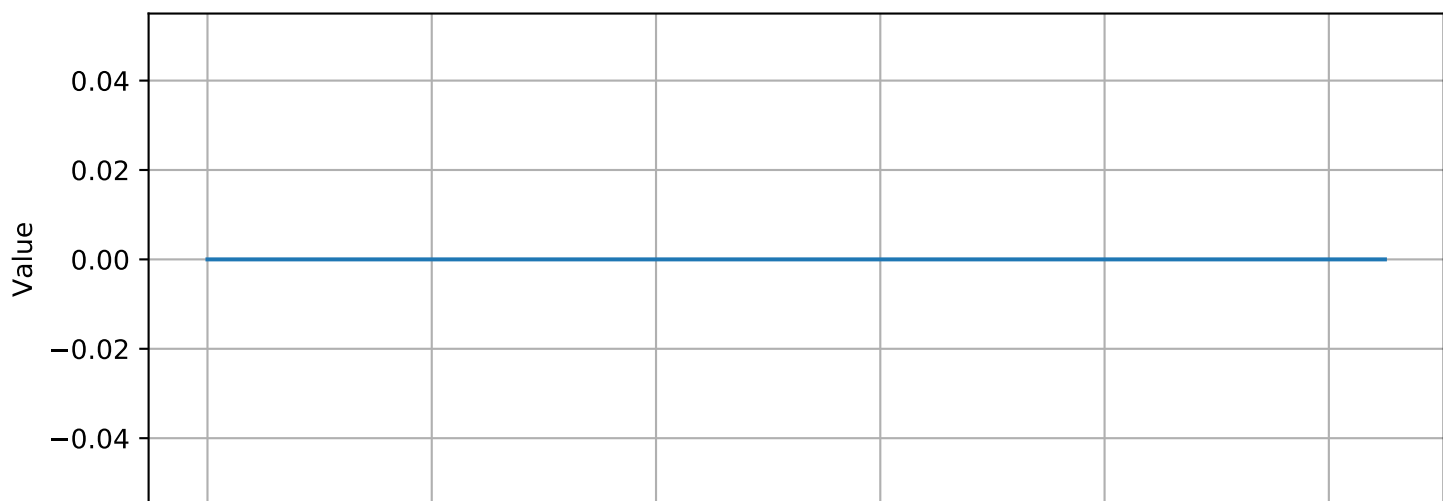
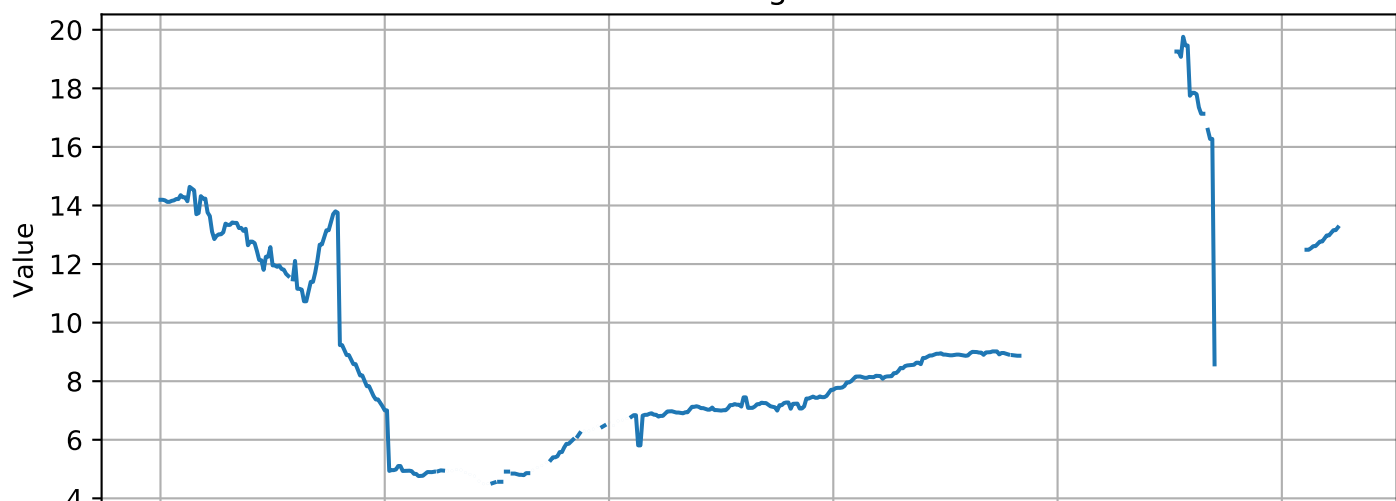


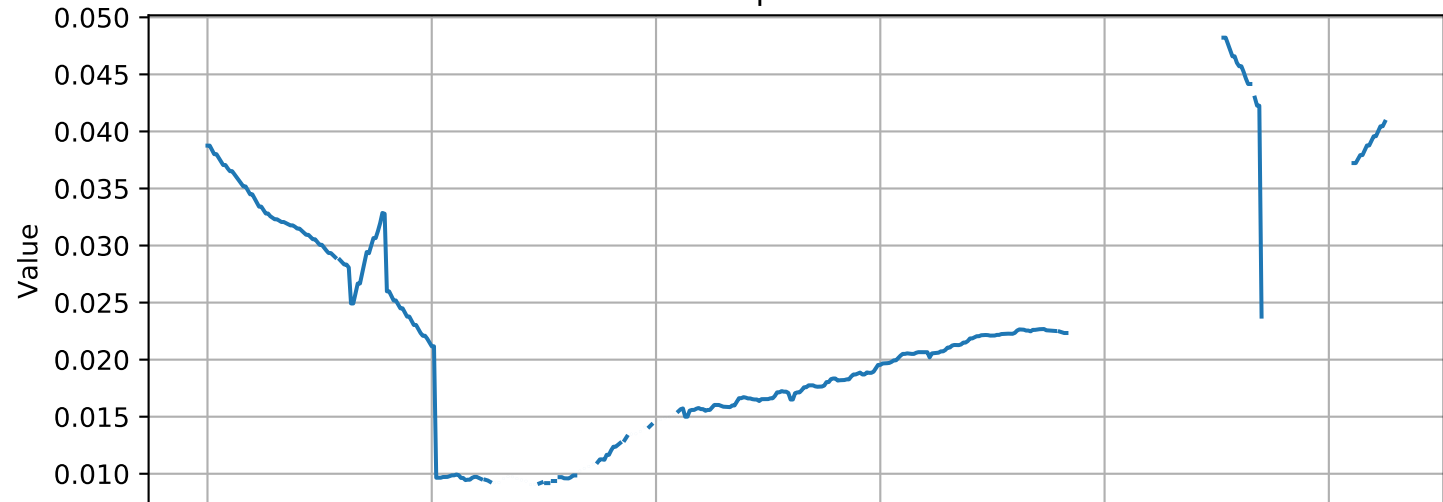
Plot for id



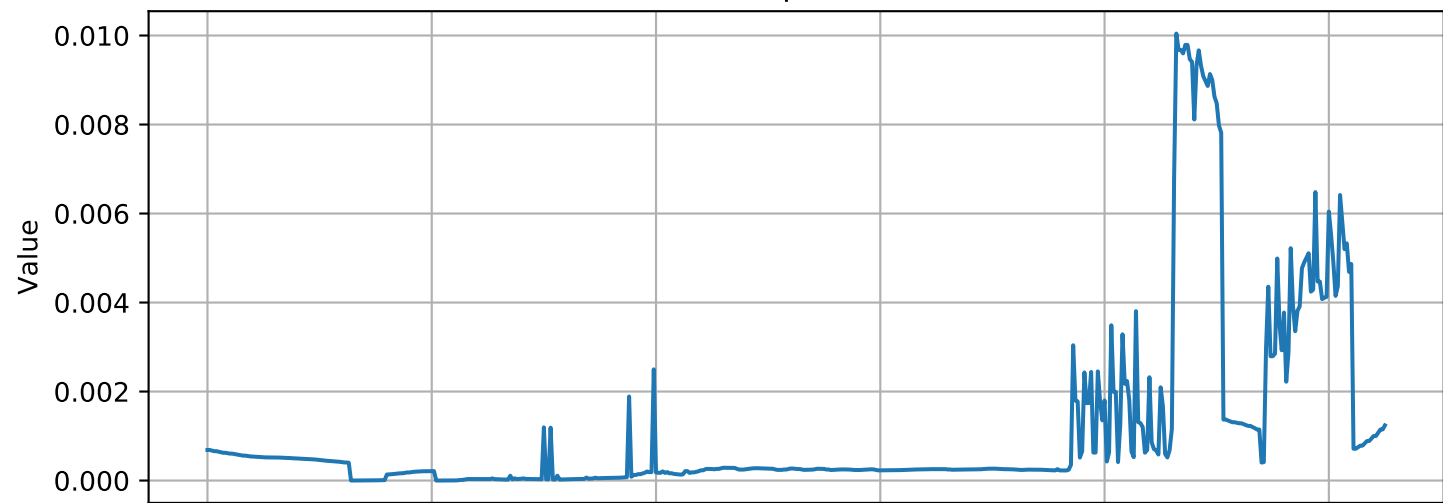
Plot for angleError



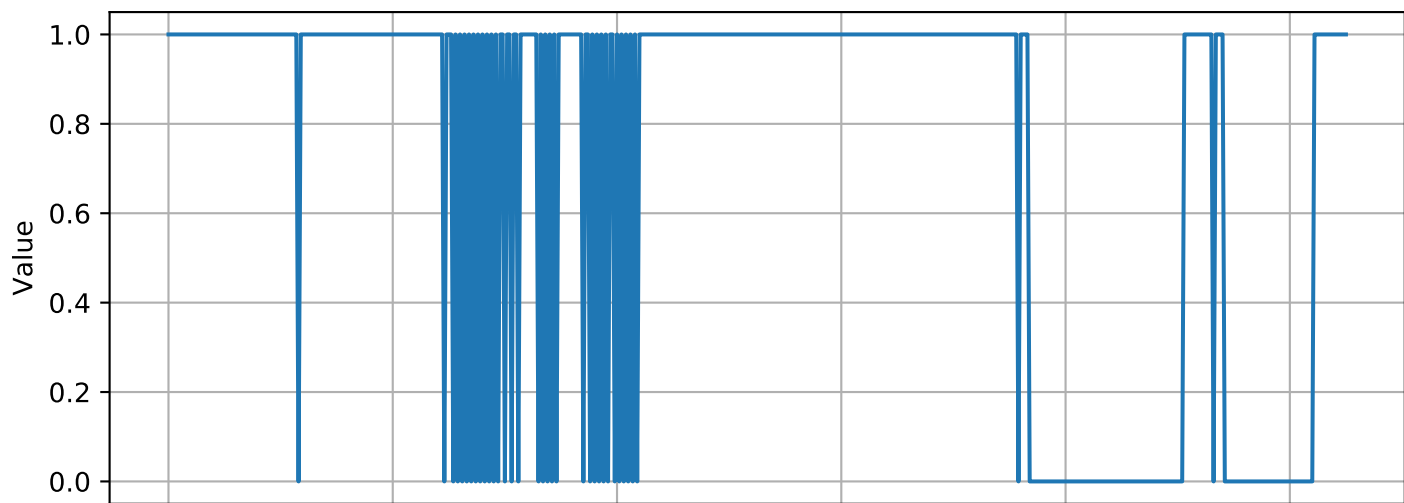
Plot for positionError



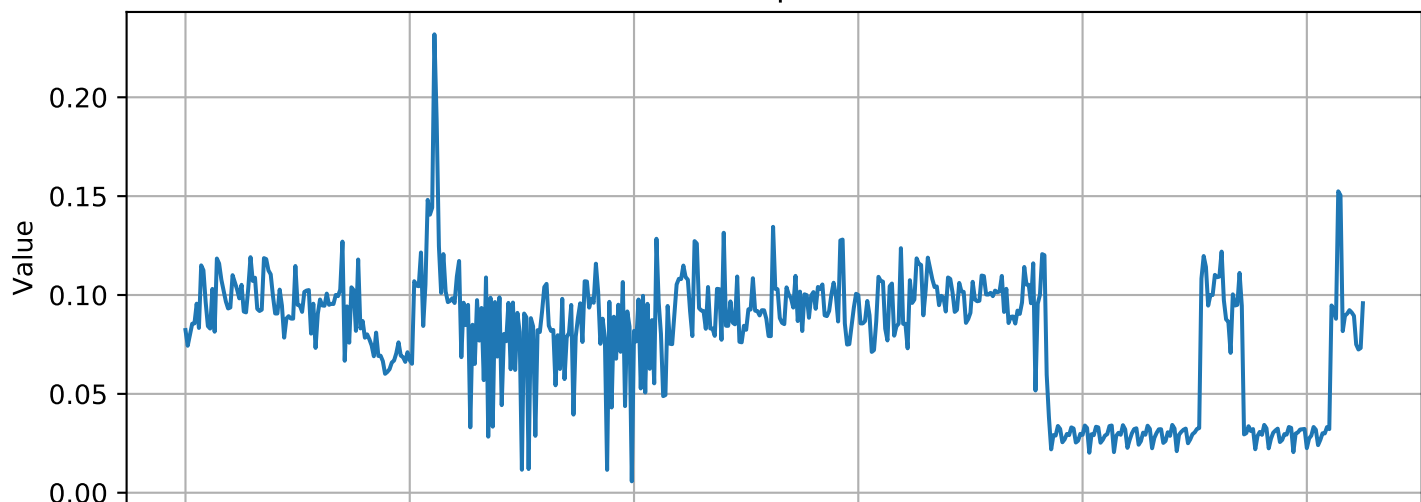
Plot for optimalCost



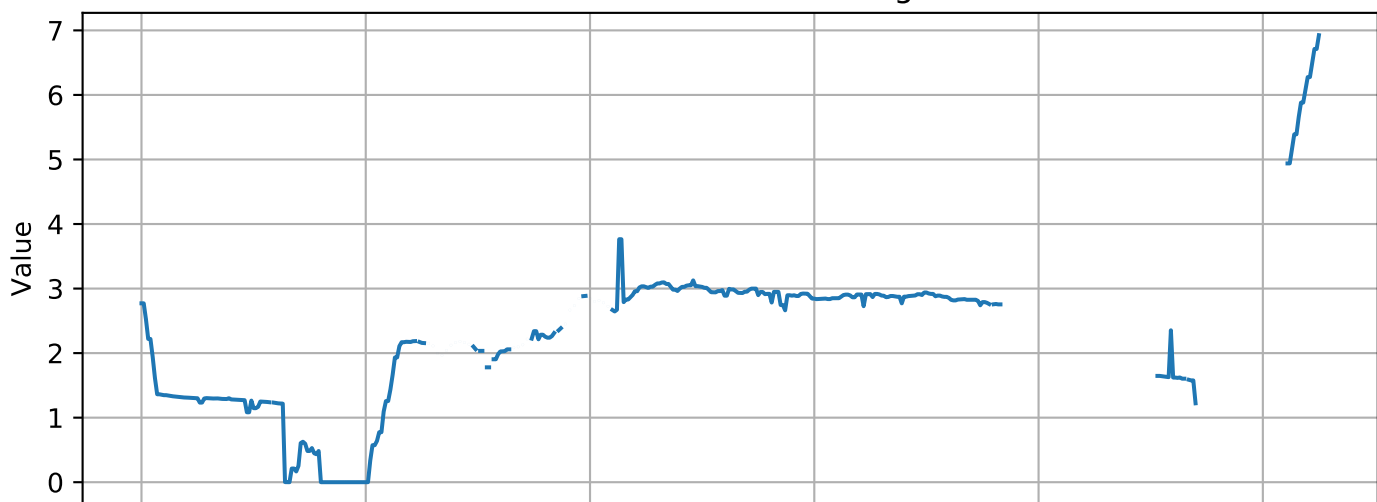
Plot for success



Plot for completionTime

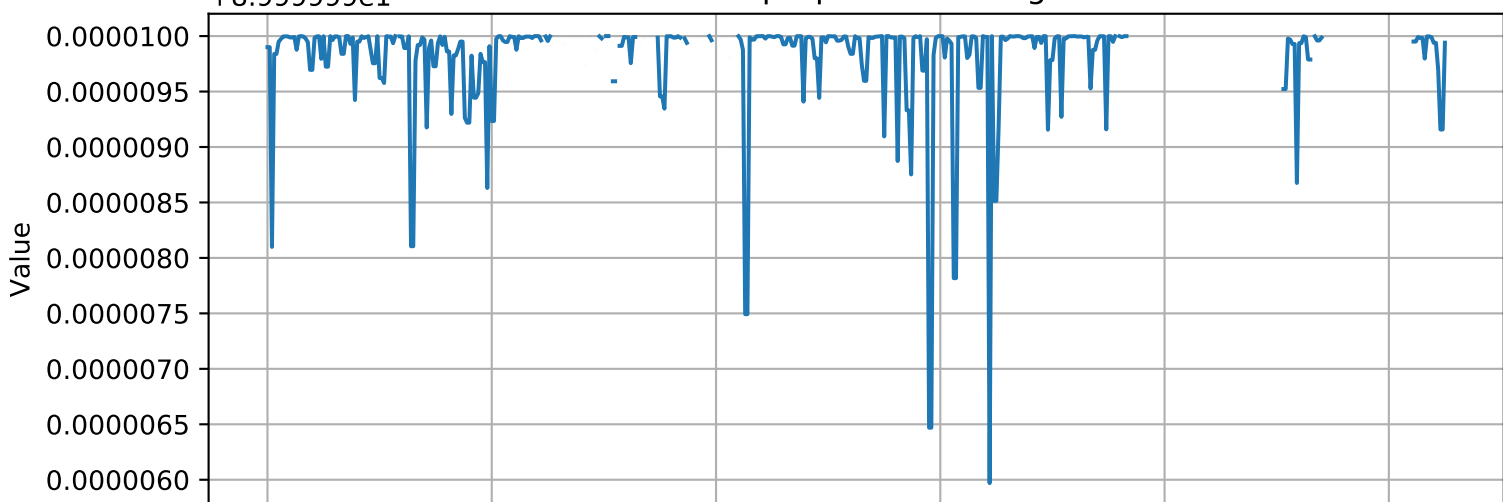


Plot for centroidViewAngle



Plot for perpendicularAngle

+8.999999e1



Plot for viewDistance

