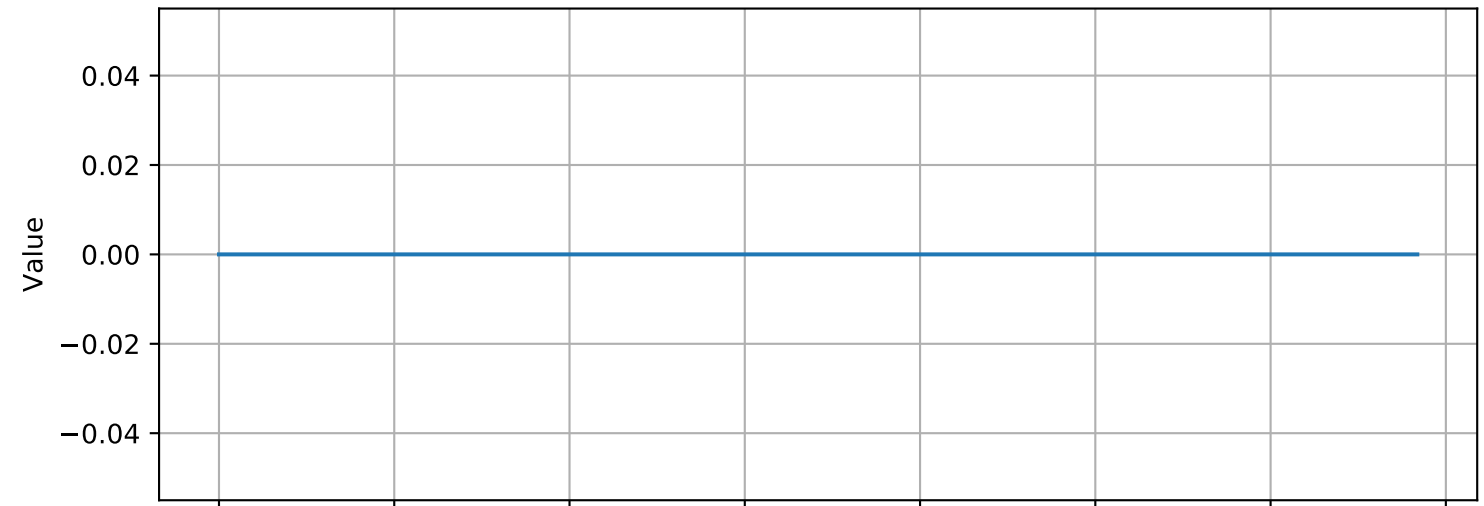
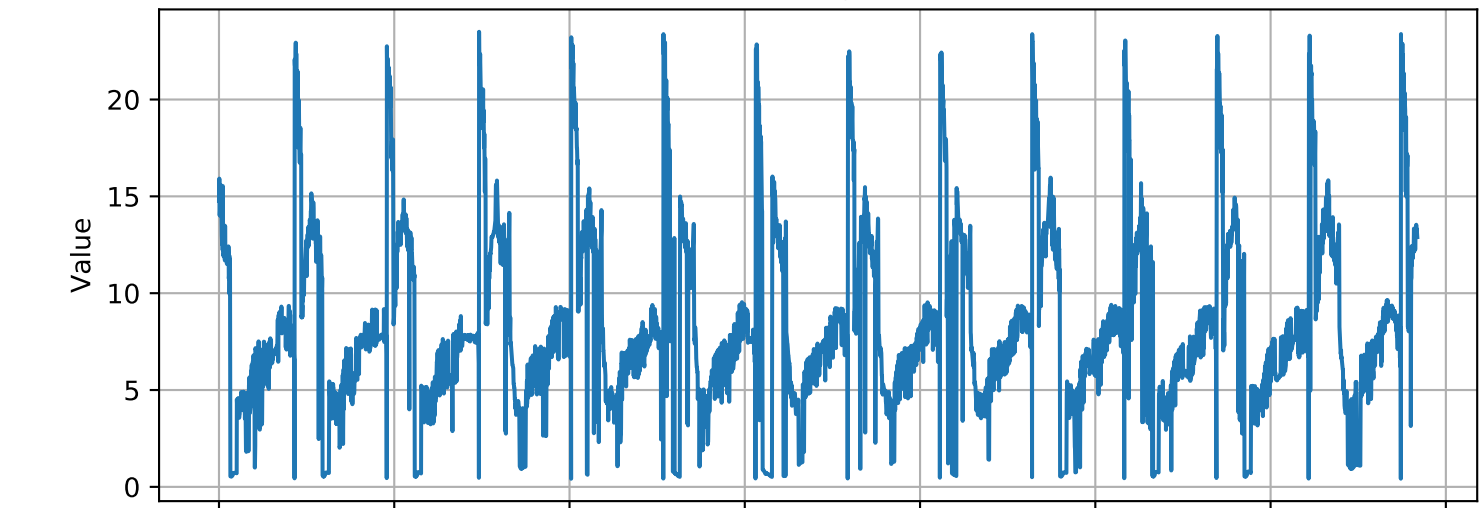


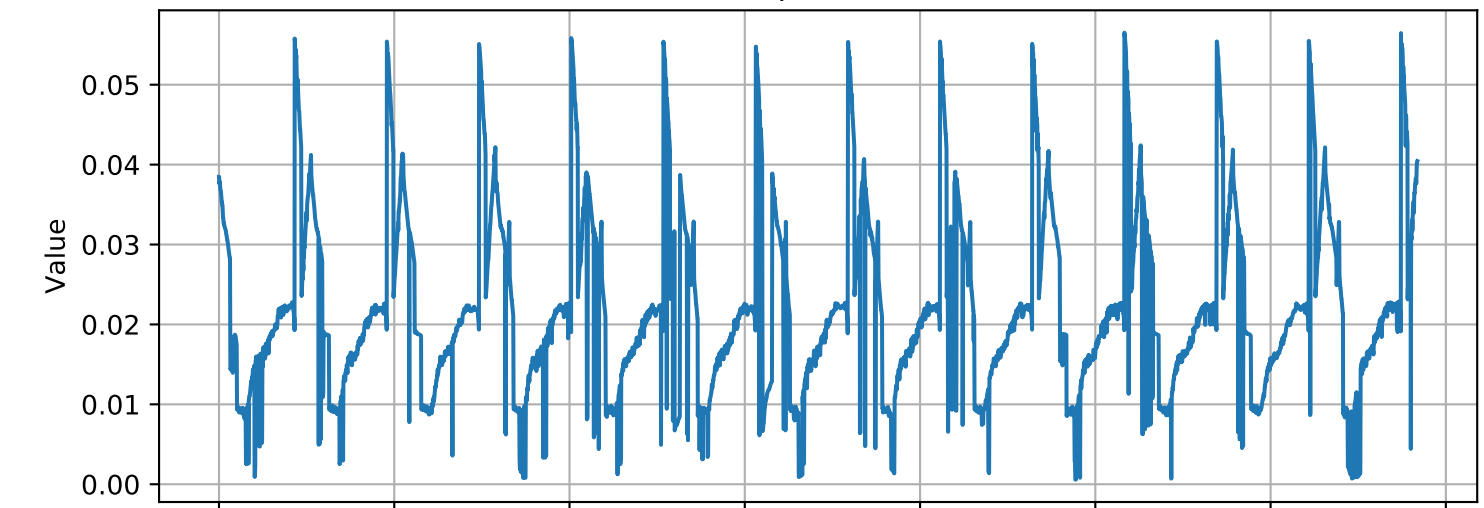
Plot for id



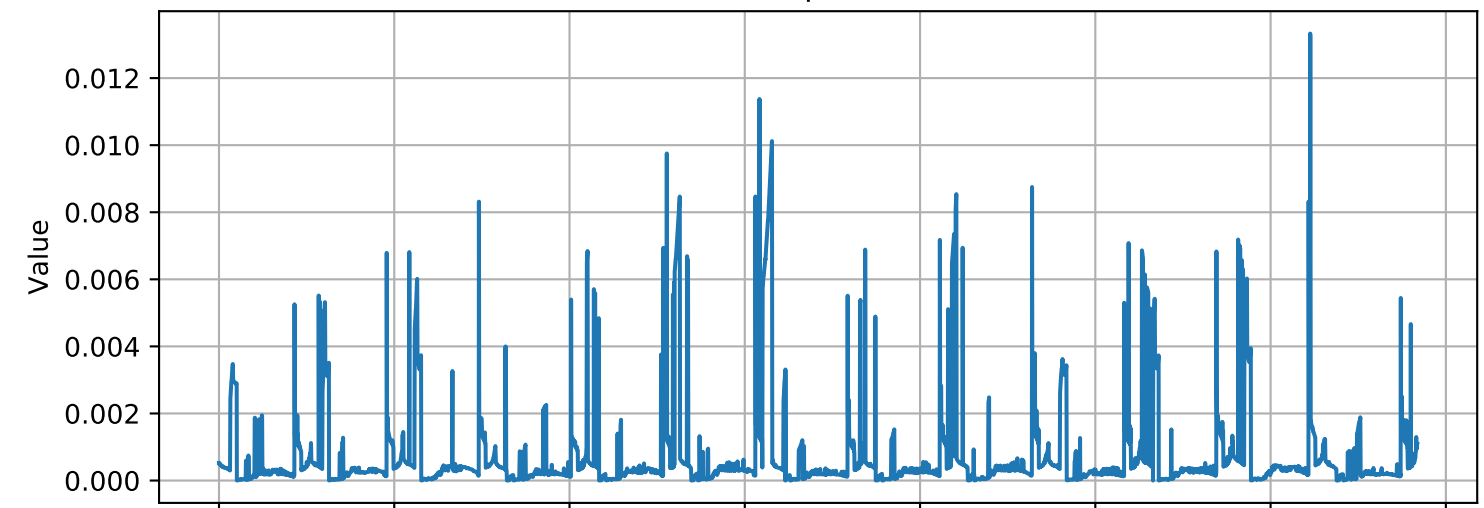
Plot for angleError



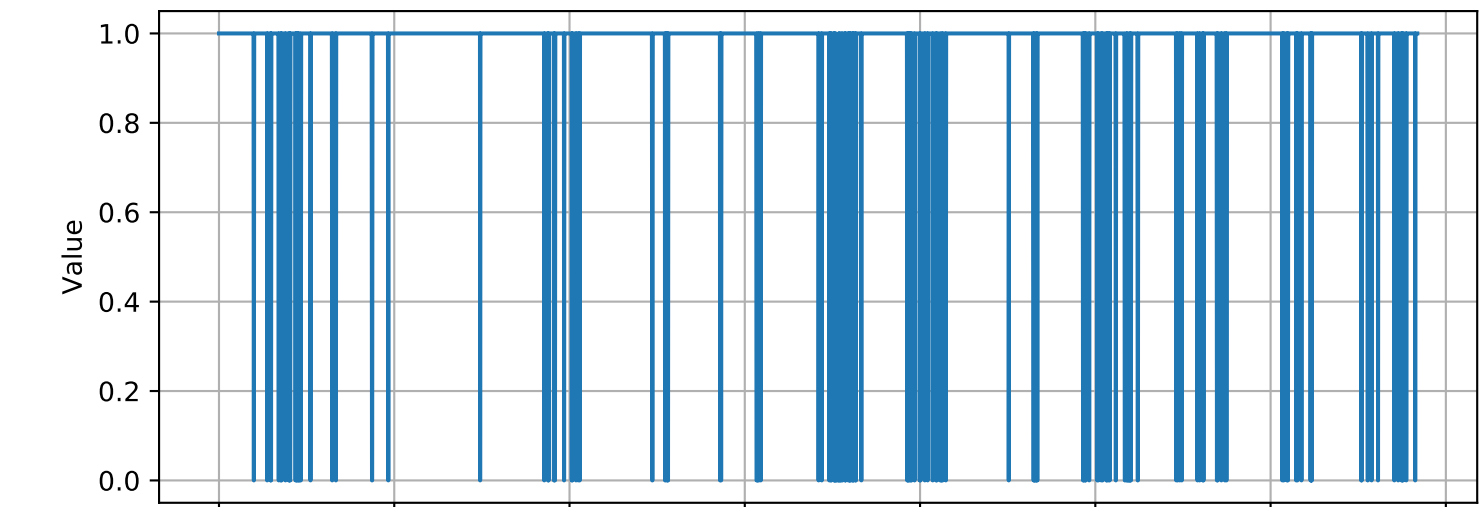
Plot for positionError



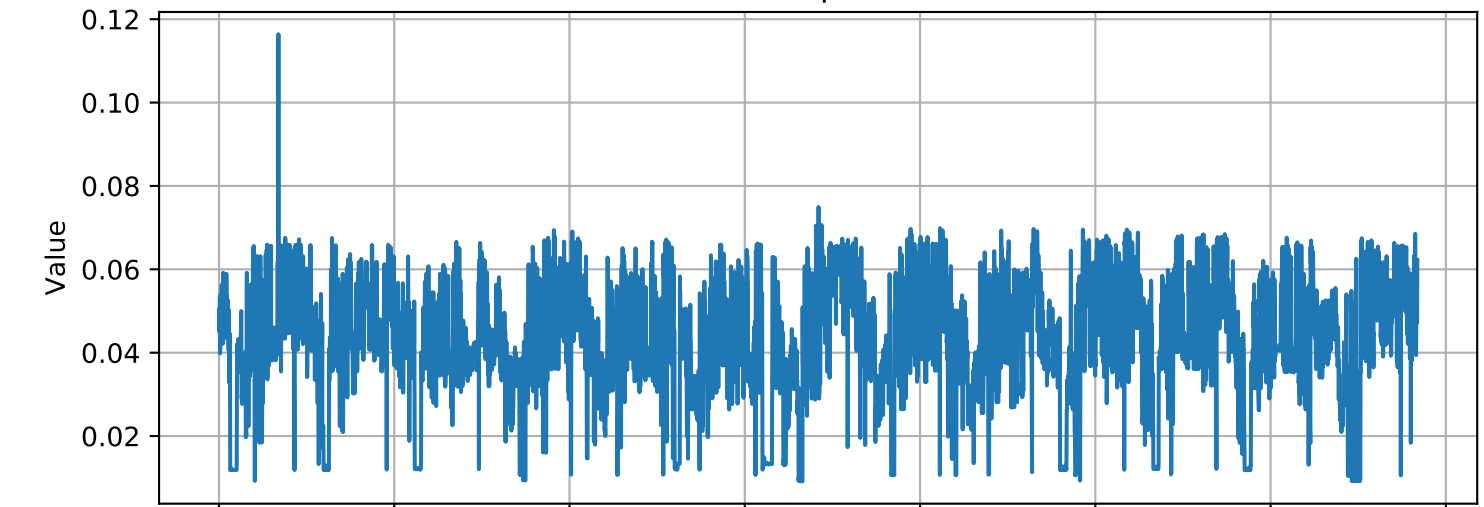
Plot for optimalCost



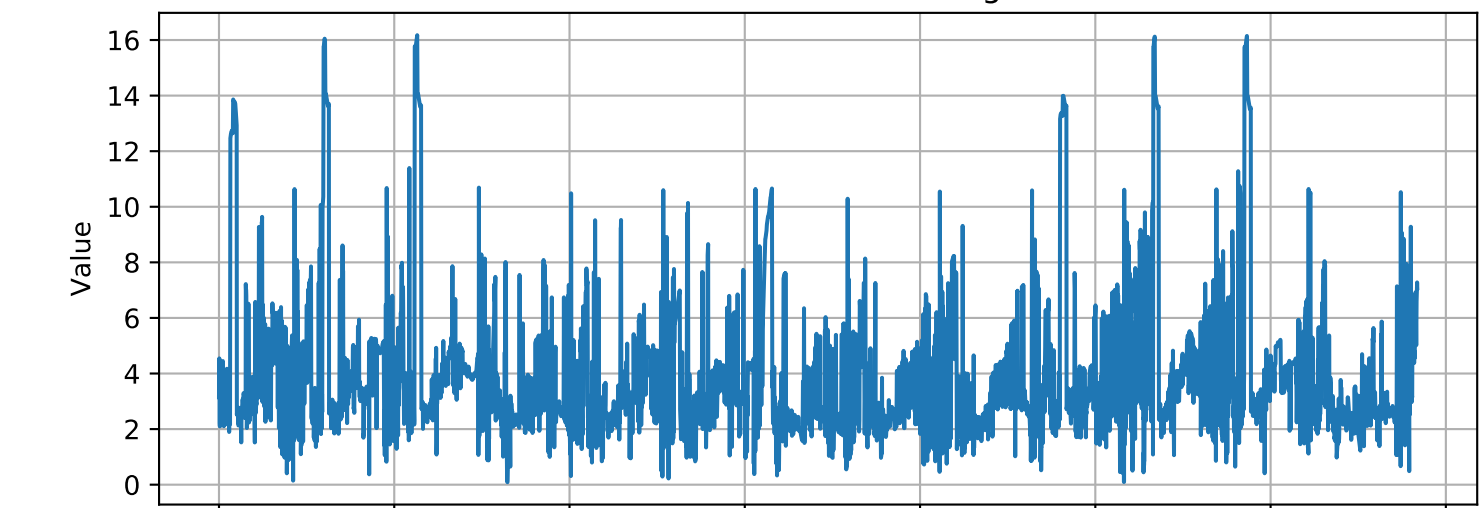
Plot for success



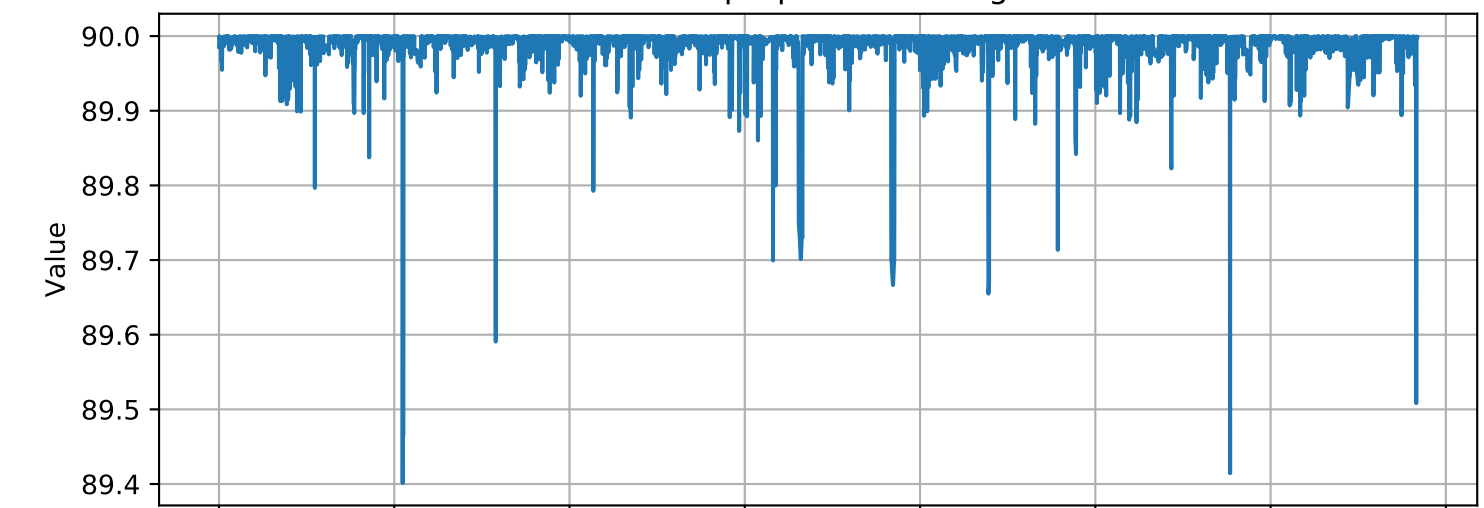
Plot for completionTime



Plot for centroidViewAngle



Plot for perpendicularAngle



Plot for viewDistance

