

# Supplemental material

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## Abstract

*In this document, we present the proof of Proposition 3.1. We also illustrate how the property is used in our work for control points with curvature objectives of opposing signs.*

## 1. Proof of Proposition 3.1

The equation of the normal clothoid shell function is given by

$$s_n : \Phi \in [0, 2\pi] \rightarrow 2\Phi \begin{pmatrix} \int_0^1 \cos(\Phi(-u^2 + 2u)) du \\ \int_0^1 \sin(\Phi(-u^2 + 2u)) du \end{pmatrix} \quad (1)$$

We defined the clothoid shell of the point  $p_i$  with tangent angle condition  $\theta_i$  and curvature  $\kappa_i$  through the normal shell clothoid  $s_n$  via the formula

$$s_i(\Phi) = p_i + \frac{1}{\kappa_i} R(\theta_i) s_n(\Phi - \theta_i).$$

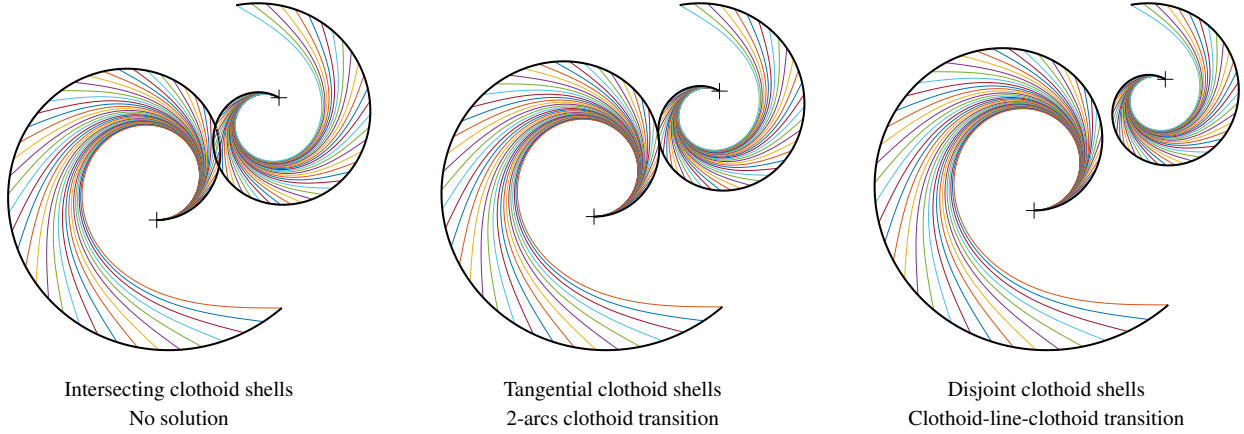
This formula is valid for  $\Phi \in [\theta_i, 2\pi + \theta_i]$ , but the function can be extended to  $\Phi \in \mathbb{R}$  by taking the angle corresponding to the angle in  $[\theta_i, 2\pi + \theta_i]$ . Therefore  $s_i$  is discontinuous on  $\mathbb{R}$  at  $\theta_i + 2k\pi$  with  $k \in \mathbb{Z}$ .

**Proposition 3.1.** Let  $p_0, p_1$  be two distinct points and  $\theta_0$  and  $\theta_1$  two angles. There exist curvature bounds  $K_0, K_1$ , such that for any  $\kappa_0 \geq K_0, \kappa_1 \geq K_1$ , there exists an angle  $\Phi$  such that the line segment  $[s_0(\Phi), s_1(\Phi + \pi)]$  makes an angle  $\Phi$  with the  $x$ -axis, where the starting conditions for the two clothoids are  $(p_0, \theta_0, \kappa_0)$  and  $(p_1, \theta_1, \kappa_1)$ , respectively.

**Proof.** Let  $s_0$  and  $s_1$  be the clothoid shells related to points  $(p_0, \theta_0, \kappa_0)$  and  $(p_1, \theta_1, \kappa_1)$ , respectively. Let  $\Sigma_0$  and  $\Sigma_1$  be the traces of curves  $s_0$  and  $s_1$  and  $L_{\Sigma_0, \Sigma_1} = \bigcup_{p \in \Sigma_0, q \in \Sigma_1} [p, q]$  be the set of segments whose two end points are in  $\Sigma_0$  and  $\Sigma_1$ , respectively. Let  $[\Phi_a, \Phi_b]$  be the set of angles between the  $x$ -axis and the lines  $[p, q] \in L_{\Sigma_0, \Sigma_1}$ . This set is simply connected and can be noted as an interval because  $\Sigma_0$  and  $\Sigma_1$  are simply connected.

We know that for all  $\Phi$  in  $[0, 2\pi]$ ,  $\|s_i(\Phi) - p_i\| \leq \frac{4\pi}{\kappa_i}$ . Therefore, when both curvatures  $\kappa_0$  and  $\kappa_1$  converge towards  $+\infty$ ,  $s_0$  and  $s_1$  converge uniformly towards  $p_0$  and  $p_1$  and the set  $[\Phi_a, \Phi_b]$  is actually converging to the singleton  $\{\Phi_{0,1}\}$ , which is the angle formed by the  $x$ -axis and the segment  $[p_0, p_1]$ . We define  $v(\Phi) := s_1(\Phi - \pi) - s_0(\Phi)$ . We distinguish between several cases:

- If  $\Phi_{0,1} = \theta_0 = \theta_1 - \pi$ , then  $v(\theta_0) = s_1(\theta_1) - s_0(\theta_0) = p_1 - p_0$  makes an angle  $\theta_0$  with the  $x$ -axis.
- Otherwise, we recall that  $s_i$  is continuous except on the set of points  $\{\theta_i + 2k\pi \mid k \in \mathbb{Z}\}$ . We have again two cases to consider:
  - If  $\Phi_{0,1}$  is not equal to  $\theta_1 - \pi$  or  $\theta_0$ , then there exists an  $\varepsilon > 0$  such that there are  $K_0$  and  $K_1$ , such that for  $\kappa_0 > K_0, \kappa_1 > K_1$ ,  $[\Phi_a, \Phi_b] \subset [\Phi_{0,1} - \varepsilon, \Phi_{0,1} + \varepsilon]$  and both  $\theta_1 - \pi$  and  $\theta_0$  are not in  $[\Phi_a, \Phi_b]$ . Therefore, both  $s_0$  and  $s_1 \circ \tau_{-\pi}$  are continuous on such an interval  $[\Phi_a, \Phi_b]$  ( $\tau_{-\pi}$  is a shift by  $-\pi$ ). By continuity, there is  $\Phi \in [\Phi_a, \Phi_b]$  such that  $v(\Phi)$  makes an angle  $\Phi$  with the  $x$ -axis.
  - We suppose that  $\Phi_{0,1} = \theta_0$  but  $\Phi_{0,1} \neq \theta_1 - \pi$  (by symmetry of the problem, the case in which  $\Phi_{0,1} = \theta_1 - \pi$  and  $\Phi_{0,1} \neq \theta_0$  is similar). Without loss of generality, since the situation is the same up to a rotation and translation, we can consider  $\theta_0 = 0 = \Phi_{0,1}$  and  $p_0 = (0, 0)$ . In this setting,  $p_1$  has necessarily a positive  $x$ -coordinate and vanishing  $y$ -coordinate. We consider  $\varepsilon > 0$  such that  $\varepsilon < \theta_1 \pm \pi$ , where  $\theta_1 \pm \pi$  is the value of the angle  $\theta_1 + \pi$  in  $[0, 2\pi]$ . Let  $K_0, K_1$  be such that  $\forall \kappa_0 > K_0, \kappa_1 > K_1, [\Phi_a, \Phi_b] \subset [-\varepsilon, \varepsilon]$ . We cannot conclude as before because we do not have continuity of  $s_0$  at 0. We must prove that the angle with the  $x$ -axis of  $v(\Phi) = s_1(\Phi \pm \pi) - s_0(\Phi)$  is positive for  $\Phi \in [0, \varepsilon]$ . To do so, we prove that  $s_1(\pi)$  has a  $y$ -coordinate that is always positive. Indeed, we know that if  $\theta_1 \in [0, \pi)$ , then
 
$$s_1(\pi)_y = \frac{2(\pi - \theta_1)}{\kappa_1} \int_0^1 \sin((\pi - \theta_1)(-u^2 + 2u) + \theta_1) du > 0$$
 and if  $\theta_1 \in (\pi, 2\pi)$ ,
 
$$s_1(\pi)_y = \frac{2(3\pi - \theta_1)}{\kappa_1} \int_0^1 \sin((3\pi - \theta_1)(-u^2 + 2u) + \theta_1) du > 0$$
    - If  $\theta_1 \in [0, \pi)$ : since  $u \in [0, 1] \rightarrow -u^2 + 2u$  is an increasing function with values in  $[0, 1]$ , we know that  $\forall \theta_1 \in [0, \pi), \forall u \in [0, 1], 0 \leq \theta_1 \leq (\pi - \theta_1)(-u^2 + 2u) + \theta_1 \leq \pi$ . This means that,  $\forall \theta_1 \in [0, \pi), \forall u \in [0, 1], \sin((\pi - \theta_1)(-u^2 + 2u) + \theta_1) \geq 0$ . Since the sine function is not constantly equal to 0 on  $[\theta_1, \pi]$ , this shows that  $\int_0^1 \sin((\pi - \theta_1)(-u^2 + 2u) + \theta_1) du > 0$ .
    - If  $\theta_1 \in (\pi, 2\pi)$ , let us take  $\Theta_1 = \theta_1 - \pi \in (0, \pi)$ . We



**Figure 1:** Clothoid shells (black curves) for clothoid-line-clothoid (CLC) transition between points with given curvatures of opposite signs.  $p_0 = (0, 0)$ ,  $\theta_0 = 0$ ,  $\kappa_0 = 1$ ,  $p_1 = (3, 3)$ ,  $\theta_1 = -\frac{\pi}{6}$  and  $\kappa_1$  is equal to 1.5 (left), 1.655 (middle) and 2.0 (right). The function  $s_1$  has been produced with positive curvature: we are looking for the point  $p_{e,1} = s_1(\Phi)$  that makes  $v(\Phi)$  have an angle  $\Phi$  with the  $x$ -axis. But the second part of the CLC transition goes from  $p_{e,1}$  to  $p_1$  and therefore has curvature  $-\kappa_1$  at  $p_1$ . Colored curves represent the shortest clothoids joining  $(p, \theta, K)$  and a line of slope angle  $\Phi$ .

want to prove that  $\int_0^1 \sin((3\pi - \theta_1)(-u^2 + 2u) + \theta_1) du > 0$ , i.e.,  $\int_0^1 \sin((2\pi - \theta_1)(-u^2 + 2u) + \theta_1 + \pi) du > 0$ , i.e., that

$$\int_0^1 \sin((2\pi - \theta_1)(-u^2 + 2u) + \theta_1) du < 0 \quad (2)$$

We therefore show that:

$$\begin{aligned} & \int_0^1 \sin((2\pi - \theta_1)(-u^2 + 2u) + \theta_1) du \\ &= \int_0^1 \sin(-(2\pi - \theta_1)(u^2 - 2u + 1) + 2\pi - \theta_1 + \theta_1) du \\ &= - \int_0^1 \sin((2\pi - \theta_1)(1 - u)^2) du \\ &= - \int_0^1 \sin((2\pi - \theta_1)u^2) du \\ &= - \frac{\int_0^{\sqrt{2\pi - \theta_1}} \sin(x^2) dx}{\sqrt{2\pi - \theta_1}} \\ &= - \frac{S(\sqrt{2\pi - \theta_1})}{\sqrt{2\pi - \theta_1}}, \end{aligned}$$

where  $S$  is the Fresnel integral  $S : t \rightarrow \int_0^t \sin(x^2) dx$ . It is known that  $S$  is positive on  $\mathbb{R}_{>0}^+$ , therefore we have proved the statement in (2).

Hence the angle  $\psi$  between the  $x$ -axis and  $v(0) = s_1(\pi) - s_0(0)$  is positive. This angle  $\psi$  is smaller than  $\epsilon$  since  $[\Phi_a, \Phi_b] \subset [-\epsilon, \epsilon]$  and  $s_1 \circ \tau_{-\pi}$  is continuous on  $[0, \epsilon]$ . By continuity, there exists  $\Phi \in [0, \psi] \subset [0, \epsilon]$  such that  $v(\Phi) = s_1(\Phi - \pi) - s_0(\Phi)$  makes an angle  $\Phi$  with the  $x$ -axis.

□

**Interpretations of Proposition 3.1.** In our method, the tangent is computed based on a hybrid circular-elliptical interpolation of three successive points  $p_{i-1}$ ,  $p_i$  and  $p_{i+1}$  [Yuk20]. Therefore, the angles  $\theta_0$  and  $\theta_1$  are always such that the vector  $p_1 - p_0$  is making a positive angle smaller than  $\pi/2$  with the line  $(p_0, \theta_0)$  (respectively, the vector  $p_0 - p_1$  and the line  $(p_1, \pi + \theta_1)$ ). This situation is illustrated in Figure 1. We can see in this figure that three cases can happen:

1. The clothoid shells intersect twice. The angle with the  $x$ -axis of  $v(\Phi)$  therefore makes a whole round and is never equal to  $\Phi$ .
2. The clothoid shells are tangent. The unique intersection point  $p$  is such that there exists  $\Phi$  such that  $s_0(\Phi) = s_1(\Phi + \pi) = p$ . Therefore, the line part of the CLC transition vanishes, and we have a 2-arcs clothoid transition.
3. The clothoid shells are disjoint. Let  $\psi$  be the angle that  $v(\Phi)$  makes with the  $x$ -axis. In this situation, the difference  $\psi - \Phi$  is first positive around  $\Phi = 0$  and then negative around  $\Phi = \pi$ . Therefore there is a  $\Phi$  such that  $\psi - \Phi = 0$ .

Note that in the case of same-sign curvature, the situation can be different. It is possible to find  $K_0, K_1$  such that there exists a CLC transition from  $(p_0, \theta_0, K_0)$  to  $(p_1, \theta_1, K_1)$ , but not every  $\kappa_0 > K_0$  and  $\kappa_1 > K_1$  makes the existence of a CLC transition persist (Section 5.2 in the paper).

## References

- [Yuk20] YUKSEL C.: A class of  $C^2$  interpolating splines. *ACM Transactions on Graphics* 39, 5 (jul 2020), 160:1–160:14. URL: <http://doi.acm.org/10.1145/3400301>, doi:10.1145/3400301. 2