

CFD General Notation System Mid-Level Library

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1 Introduction

This document outlines a CGNS library designed to ease implementation of CGNS by providing developers with a collection of handy I/O functions. Since knowledge of database manager and file structure is not required to use this library, it greatly facilitates the task of interfacing with CGNS.

The CGNS Mid-Level Library is based on the SIDS File Mapping Manual. It allows reading and writing all of the information described in that manual including grid coordinates, block interfaces, flow solutions, and boundary conditions. Use of the mid-level library functions insures efficient communication between the user application and the internal representation of the CGNS data.

It is assumed that the reader is familiar with the information in the CGNS Standard Interface Data Structures (SIDS), as well as the SIDS File Mapping Manual. The reader is also strongly encouraged to read the User's Guide to CGNS, which contains coding examples using the Mid-Level Library to write and read simple files containing CGNS databases.

2 General Remarks

2.1 Acquiring the Software and Documentation

The CGNS Mid-Level Library may be downloaded from SourceForge, at http://sourceforge.net/
projects/cgns. This manual, as well as the other CGNS documentation, is available in both HTML and PDF format from the CGNS documentation web site, at http://www.grc.nasa.gov/www/cgns/CGNS_docs_current/.

2.2 Organization of This Manual

The sections that follow describe the Mid-Level Library functions in detail. The first three sections cover some basic file operations (i.e., opening and closing a CGNS file, and some configuration options) (Section 3), accessing a specific node in a CGNS database (Section 4), and error handling (Section 5). The remaining sections describe the functions used to read, write, and modify nodes and data in a CGNS database. These sections basically follow the organization used in the "Detailed CGNS Node Descriptions" section of the SIDS File Mapping manual.

At the start of each sub-section is a *Node* line, listing the the applicable CGNS node label.

Next is a table illustrating the syntax for the Mid-Level Library functions. The C functions are shown in the top half of the table, followed by the corresponding Fortran routines in the bottom half of the table. Input variables are shown in an upright blue font, and output variables are shown in a slanted red font. As of Version 3.1, some of the arguments to the Mid-Level Library have changed from int to cgsize_t in order to support 64-bit data. For each function, the right-hand column lists the modes (read, write, and/or modify) applicable to that function.

The input and output variables are then listed and defined.

2.3 Language

The CGNS Mid-Level Library is written in C, but each function has a Fortran counterpart. All function names start with "cg_". The Fortran functions have the same name as their C counterpart with the addition of the suffix "_f".

2.4 Character Strings

All data structure names and labels in CGNS are limited to 32 characters. When reading a file, it is advised to pre-allocate the character string variables to 32 characters in Fortran, and 33 in C (to include the string terminator). Other character strings, such as the CGNS file name or descriptor text, are unlimited in length. The space for unlimited length character strings will be created by the Mid-Level Library; it is then the responsibility of the application to release this space by a call to cg_free, described in Section 10.6.

2.5 Error Status

All C functions return an integer value representing the error status. All Fortran functions have an additional parameter, ier, which contains the value of the error status. An error status different

from zero implies that an error occured. The error message can be printed using the error handling functions of the CGNS library, described in Section 5. The error codes are coded in the C and Fortran include files cgnslib.h and cgnslib-f.h.

2.6 Typedefs

Beginning with version 3.1, two new typedef variables have been introduced to support 64-bit mode. The cglong_t typedef is always a 64-bit integer, and cgsize_t will be either a 32-bit or 64-bit integer depending on how the library was built. Many of the C functions in the MLL have been changed to to use cgsize_t instead of int in the arguments. These functions include any that may exceed the 2Gb limit of an int, e.g. zone dimensions, element data, boundary conditions, and connectivity. In Fortran, all integer data is taken to be integer*4 for 32-bit and integer*8 for 64-bit builds.

Several types of variables are defined using typedefs in the *cgnslib.h* file. These are intended to facilitate the implementation of CGNS in C. These variable types are defined as an enumeration of key words admissible for any variable of these types. The file *cgnslib.h* must be included in any C application programs which use these data types.

In Fortran, the same key words are defined as integer parameters in the include file *cgnslib_f.h.* Such variables should be declared as **integer** in Fortran applications. The file *cgnslib_f.h* must be included in any Fortran application using these key words.

Note that the first two enumerated values in these lists, xxxNull and xxxUserDefined, are only available in the C interface, and are provided in the advent that your C compiler does strict type checking. In Fortran, these values are replaced by the numerically equivalent CG_Null and CG_UserDefined. These values are also defined in the C interface, thus either form may be used. The function prototypes for the MLL use CG_Null and CG_UserDefined, rather than the more specific values.

The list of enumerated values (key words) for each of these variable types (typedefs) are:

ZoneType_t	ZoneTypeNull, ZoneTypeUserDefined, Structured, Unstructured
ElementType_t	ElementTypeNull, ElementTypeUserDefined, NODE, BAR_2, BAR_3, TRI_3, TRI_6, QUAD_4, QUAD_8, QUAD_9, TETRA_4, TETRA_10, PYRA_5, PYRA_14, PENTA_6, PENTA_15, PENTA_18, HEXA_8, HEXA_20, HEXA_27, MIXED, PYRA_13, NGON_n, NFACE_n
DataType_t	<pre>DataTypeNull, DataTypeUserDefined, Integer, RealSingle, RealDouble, Character</pre>
DataClass_t	DataClassNull, DataClassUserDefined, Dimensional, NormalizedByDimensional, NormalizedByUnknownDimensional, NondimensionalParameter, DimensionlessConstant
MassUnits_t	MassUnitsNull, MassUnitsNullUserDefined, Kilogram, Gram, Slug, PoundMass
LengthUnits_t	LengthUnitsNull, LengthUnitsUserDefined, Meter, Centimeter, Millimeter, Foot, Inch

TimeUnits_t TimeUnitsNull, TimeUnitsUserDefined, Second

TemperatureUnits_t TemperatureUnitsNull, TemperatureUnitsUserDefined,

Kelvin, Celsius, Rankine, Fahrenheit

AngleUnits_t AngleUnitsNull, AngleUnitsUserDefined, Degree, Radian

ElectricCurrentUnits_t ElectricCurrentUnitsNull,

ElectricCurrentUnitsUserDefined, Ampere, Abampere,

Statampere, Edison, auCurrent

SubstanceAmountUnits_t SubstanceAmountUnitsNull,

SubstanceAmountUnitsUserDefined, Mole, Entities,

StandardCubicFoot, StandardCubicMeter

LuminousIntensityUnits_t

LuminousIntensityUnitsNull,

LuminousIntensityUnitsUserDefined, Candela, Candle,

Carcel, Hefner, Violle

GoverningEquationsType_t

GoverningEquationsTypeNull,

GoverningEquationsTypeUserDefined, FullPotential,

Euler, NSLaminar, NSTurbulent, NSLaminarIncompressible,

NSTurbulentIncompressible

ModelType_t ModelTypeNull, ModelTypeUserDefined, Ideal,

VanderWaals, Constant, PowerLaw, SutherlandLaw, ConstantPrandtl, EddyViscosity, ReynoldsStress, ReynoldsStressAlgebraic, Algebraic_BaldwinLomax, Algebraic_CebeciSmith, HalfEquation_JohnsonKing, OneEquation_BaldwinBarth, OneEquation_SpalartAllmaras,

TwoEquation_JonesLaunder, TwoEquation_MenterSST,

TwoEquation_Wilcox, CaloricallyPerfect,

ThermallyPerfect, ConstantDensity, RedlichKwong,

Frozen, ThermalEquilib, ThermalNonequilib,

ChemicalEquilibCurveFit, ChemicalEquilibMinimization, ChemicalNonequilib, EMElectricField, EMMagneticField,

EMConductivity, Voltage, Interpolated,

Equilibrium_LinRessler, Chemistry_LinRessler

GridLocation_t GridLocationNull, GridLocationUserDefined, Vertex,

IFaceCenter, CellCenter, JFaceCenter, FaceCenter,

KFaceCenter, EdgeCenter

GridConnectivityType_t GridConnectivityTypeNull,

GridConnectivityTypeUserDefined, Overset, Abutting,

Abutting1to1

PointSetType_t PointSetTypeNull, PointSetTypeUserDefined, PointList,

PointRange, PointListDonor, PointRangeDonor, ElementList, ElementRange, CellListDonor

BCType_t BCTypeNull, BCTypeUserDefined, BCAxisymmetricWedge,

BCDegenerateLine, BCExtrapolate, BCDegeneratePoint,

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BCDirichlet, BCFarfield, BCNeumann, BCGeneral,

BCInflow, BCOutflow, BCInflowSubsonic, BCOutflowSubsonic, BCInflowSupersonic,

BCOutflowSupersonic, BCSymmetryPlane, BCTunnelInflow, BCSymmetryPolar, BCTunnelOutflow, BCWallViscous, BCWall, BCWallViscousHeatFlux, BCWallInviscid, BCWallViscousIsothermal, FamilySpecified

BCDataType_t BCDataTypeNull, BCDataTypeUserDefined, Dirichlet,

Neumann

RigidGridMotionType_t RigidGridMotionTypeNull,

RigidGridMotionTypeUserDefined, ConstantRate,

VariableRate

ArbitraryGridMotionType_t

ArbitraryGridMotionTypeNull,

ArbitraryGridMotionTypeUserDefined, NonDeformingGrid,

DeformingGrid

SimulationType_t SimulationTypeNull, SimulationTypeUserDefined,

TimeAccurate, NonTimeAccurate

WallFunctionType_t WallFunctionTypeNull, WallFunctionTypeUserDefined,

Generic

AreaType_t AreaTypeNull, AreaTypeUserDefined, BleedArea,

CaptureArea

AverageInterfaceType_t AverageInterfaceTypeNull,

AverageInterfaceTypeUserDefined, AverageAll, AverageCircumferential, AverageRadial, AverageI,

AverageJ, AverageK

2.7 Character Names For Typedefs

The CGNS library defines character arrays which map the typedefs above to character strings. These are global arrays dimensioned to the size of each list of typedefs. To retrieve a character string representation of a typedef, use the typedef value as an index to the appropriate character array. For example, to retrieve the string "Meter" for the LengthUnits_t Meter typedef, use LengthUnits_sName[Meter]. Functions are available to retrieve these names without the need for direct global data access. These functions also do bounds checking on the input, and if out of range, will return the string "<invalid>". An additional benefit is that these will work from within a Windows DLL, and are thus the recommended access technique. The routines have the same name as the global data arrays, but with a "cg_" prepended. For the example above, use "cg_LengthUnitsName(Meter)".

```
Typedef Name Access Functions
const char *name = cg_MassUnitsName(MassUnits_t type);
const char *name = cg_LengthUnitsName(LengthUnits_t type);
const char *name = cg_TimeUnitsName(TimeUnits_t type);
const char *name = cg_TemperatureUnitsName(TemperatureUnits_t type);
const char *name = cg_ElectricCurrentUnitsName(ElectricCurrentUnits_t type);
const char *name = cg_SubstanceAmountUnitsName(SubstanceAmountUnits_t type);
const char *name = cg_LuminousIntensityUnitsName(LuminousIntensityUnits_t type);
const char *name = cg_DataClassName(DataClass_t type);
const char *name = cg_GridLocationName(GridLocation_t type);
const char *name = cg_BCDataTypeName(BCDataType_t type);
const char *name = cg_GridConnectivityTypeName(GridConnectivityType_t type);
const char *name = cg_PointSetTypeName(PointSetType_t type);
const char *name = cg_GoverningEquationsTypeName(GoverningEquationsType_t type);
const char *name = cg_ModelTypeName(ModelType_t type);
const char *name = cg_BCTypeName(BCType_t type);
const char *name = cg_DataTypeName(DataType_t type);
const char *name = cg_ElementTypeName(ElementType_t type);
const char *name = cg_ZoneTypeName(ZoneType_t type);
const char *name = cg_RigidGridMotionTypeName(RigidGridMotionType_t type);
const char *name = cg_ArbitraryGridMotionTypeName(ArbitraryGridMotionType_t type);
const char *name = cg_SimulationTypeName(SimulationType_t type);
const char *name = cg_WallFunctionTypeName(WallFunctionType_t type);
const char *name = cg_AreaTypeName(AreaType_t type);
const char *name = cg_AverageInterfaceTypeName(AverageInterfaceType_t type);
```

2.8 64-bit C Portability and Issues

If you use the cgsize_t data type in new code, it will work in both 32 and 64-bit compilation modes. In order to support CGNS versions prior to 3.1, you may also want to add something like this to your code:

```
#if CGNS_VERSION < 3100
#define cgsize_t int
#endif</pre>
```

Existing code that uses int will not work with a CGNS 3.1 library compiled in 64-bit mode. You may want to add something like this to your code:

```
#if CGNS_VERSION >= 3100 && CG_BUILD_64BIT
#error does not work in 64 bit mode
#endif
or modify your code to use cgsize_t.
```

2.9 64-bit Fortran Portability and Issues

All integer arguments in the Fortran interface - including enumerated values (enums) - are taken to be integer*4 in 32-bit mode and integer*8 in 64-bit mode. If you have used default or implicit integers in your Fortran code, it should port to 64-bit mode in most cases by simply turning on your compiler option that promotes implicit integers to integer*8. If you have explicitly defined your integers as integer*4, your code will not work in 64-bit mode. In that case, you will either need to change them to integer (recommended for portability) or integer*8.

A new integer parameter has been added to the *cgnslib_f.h* header, CG_BUILD_64BIT, which will be set to 1 in 64-bit mode and 0 otherwise. You may use this parameter to check at run time if the CGNS library has been compiled in 64-bit mode or not, as in:

```
if (CG_BUILD_64BIT .ne. 0) then
  print ,'will not work in 64-bit mode'
  stop
endif
```

If you are using a CGNS library prior to version 3.1, this parameter will not be defined and you will need to rely on your compiler initializing all undefined values to 0 (not always the case) for this test to work.

If your compiler supports automatic promotion of integers, and you use implicit integers, your code should port to 64-bit with the following exception.

If you use an Integer data type in any routine that takes a data type specification, and an implicit integer for the data, the code will fail when compiled in 64-bit mode with automatic integer promotion. An example of this would be:

```
integer dim
integer data(dim)
call cg_array_write_f('array',Integer,1,dim,data)
```

This is because the MLL interprets the Integer data type as integer*4 regardless of the compilation mode. The compiler, however, has automatically promoted data to be integer*8. What

you will need to do to prevent this problem, is to either explicitly define data as in:

```
integer dim
integer*4 data(dim)
call cg_array_write_f('array',Integer,1,dim,data)

or
integer dim
integer*8 data(dim)
call cg_array_write_f('array',LongInteger,1,dim,data)

or test on CG_BUILD_64BIT as in:
integer dim
integer data(dim)
if (CG_BUILD_64BIT .eq. 0) then
    call cg_array_write_f('array',Integer,1,dim,data)
else
    call cg_array_write_f('array',LongInteger,1,dim,data)
endif
```

The last 2 options will only work with CGNS Version 3.1, since LongInteger and CG_BUILD_64BIT are not defined in previous versions.

You may also need to be careful when using integer constants as arguments in 64-bit mode. If your compiler automatically promotes integer constants to integer*8, then there is no problem. This is probably the case if your compiler supports implicit integer promotion. If not, then the constants will be integer*4, and your code will not work in 64-bit mode. In that case you will need to do something like:

```
integer*8 one,dim
integer*4 data(dim)
one = 1
call cg_array_write_f('array',Integer,one,dim,data)
```

3 File Operations

3.1 Opening and Closing a CGNS File

Functions	Modes
<pre>ier = cg_open(char *filename, int mode, int *fn);</pre>	r w m
<pre>ier = cg_version(int fn, float *version);</pre>	rwm
<pre>ier = cg_close(int fn);</pre>	rwm
<pre>ier = cg_is_cgns(const char *filename, int *file_type);</pre>	rwm
<pre>ier = cg_save_as(int fn, const char *filename, int file_type,</pre>	rwm
<pre>int follow_links);</pre>	
<pre>ier = cg_set_file_type(int file_type);</pre>	r w m
<pre>ier = cg_get_file_type(int fn, int *file_type);</pre>	rwm
call cg_open_f(filename, mode, fn, ier)	rwm
call cg_version_f(fn, version, ier)	r w m
call cg_close_f(fn, ier)	rwm
call cg_is_cgns_f(filename, file_type, ier)	rwm
call cg_save_as_f(fn, filename, file_type, follow_links, ier)	rwm
<pre>call cg_set_file_type_f(file_type, ier)</pre>	rwm
<pre>call cg_get_file_type_f(fn, file_type, ier)</pre>	rwm

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

filename	Name of the CGNS file, including path name if necessary. There is no limit on the length of this character variable. (Input)
mode	Mode used for opening the file. The modes currently supported are CG_MODE_READ, CG_MODE_WRITE, and CG_MODE_MODIFY. (Input)
fn	CGNS file index number. (Input for cg_version and cg_close; $output$ for cg_open)
version	CGNS version number. $(Output)$
file_type	Type of CGNS file. This will typically be either CG_FILE_ADF or CG_FILE_HDF5 depending on the underlying file format. (Input for cg_save_as and cg_set_file_type; output for cg_get_file_type) However, note that when built in 32-bit, there is also an option to create a Version 2.5 CGNS file by setting the file type to CG_FILE_ADF2.
follow_links	This flag determines whether links are left intact when saving a CGNS file. If non-zero, then the links will be removed and the data associated with the linked files copied to the new file. (Input)
ier	Error status. (Output)

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The function cg_open must always be the first one called. It opens a CGNS file for reading and/or writing and returns an index number fn. The index number serves to identify the CGNS file in subsequent function calls. Several CGNS files can be opened simultaneously. The current limit on the number of files opened at once depends on the platform. On an SGI workstation, this limit is set at 100 (parameter FOPEN_MAX in stdio.h).

The file can be opened in one of the following modes:

CG_MODE_READ Read only mode.
CG_MODE_WRITE Write only mode.

CG_MODE_MODIFY Reading and/or writing is allowed.

When the file is opened, if no CGNSLibraryVersion_t node is found, a default value of 1.05 is assumed for the CGNS version number. Note that this corresponds to an old version of the CGNS standard, that doesn't include many data structures supported by the current standard.

The function cg_close must always be the last one called. It closes the CGNS file designated by the index number fn and frees the memory where the CGNS data was kept. When a file is opened for writing, cg_close writes all the CGNS data in memory onto disk prior to closing the file. Consequently, if is omitted, the CGNS file is not written properly.

In order to reduce memory usage and improve execution speed, large arrays such as grid coordinates or flow solutions are not actually stored in memory. Instead, only basic information about the node is kept, while reads and writes of the data is directly to and from the application's memory. An attempt is also made to do the same with unstructured mesh element data.

The function cg_is_cgns may be used to determine if a file is a CGNS file or not, and the type of file (CG_FILE_ADF or CG_FILE_HDF5). If the file is a CGNS file, cg_is_cgns returns CG_OK, otherwise CG_ERROR is returned and file_type is set to CG_FILE_NONE.

The CGNS file identified by fn may be saved to a different filename and type using cg_save_as. In order to save as an HDF5 file, the library must have been built with HDF5 support. ADF support is always built. The function cg_set_file_type sets the default file type for newly created CGNS files. The function cg_get_file_type returns the file type for the CGNS file identified by fn. If the CGNS library is built as 32-bit, the additional file type, CG_FILE_ADF2, is available. This allows creation of a 2.5 compatible CGNS file.

Configuring CGNS Internals 3.2

Functions	Modes
<pre>ier = cg_configure(int option, void *value);</pre>	rwm
<pre>ier = cg_error_handler(void (*)(int, char *));</pre>	rwm
<pre>ier = cg_set_compress(int compress);</pre>	r w m
<pre>ier = cg_get_compress(int *compress);</pre>	rwm
<pre>ier = cg_set_path(const char *path);</pre>	rwm
<pre>ier = cg_add_path(const char *path);</pre>	rwm
<pre>call cg_set_compress_f(compress, ier)</pre>	rwm
<pre>call cg_get_compress_f(compress, ier)</pre>	rwm
<pre>call cg_set_path_f(path, ier)</pre>	rwm
<pre>call cg_add_path_f(path, ier)</pre>	rwm

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

```
The option to configure, currently one of CG_CONFIG_ERROR, CG_CONFIG_COMPRESS,
option
          CG_CONFIG_SET_PATH, CG_CONFIG_ADD_PATH, or CG_CONFIG_HDF5_COMPRESS as
          defined in cqnslib.h. (Input)
value
          The value to set, type cast as void *. (Input)
compress
          CGNS compress (rewrite) setting). (Input for cg_set_compress; output for
          cg_get_compress)
path
          Pathname to search for linked to files when opening a file with external links. (Input)
ier
          Error status. (Output)
```

The function cg_configure allows certain CGNS library internal options to be configured. The currently supported options and expected values are:

CG_CONFIG_ERROR This allows an error call-back function to be defined by the user. The

value should be a pointer to a function to receive the error. The function is defined as void err_callback(int is_error, char *errmsg), and will be called for errors and warnings. The first argument, is_error, will be 0 for warning messages, 1 for error messages, and -1if the program is going to terminate (i.e., a call to cg_error_exit()). The second argument is the error or warning message. If this is defined, warning and error messages will go to the function, rather than the terminal. A value of NULL will remove the call-back function.

CG_CONFIG_COMPRESS When a CGNS file is closed after being opened in modify mode, the normal operation of the CGNS library is to rewrite the file if there is unused space. This happens when nodes have been rewritten or deleted. Setting value to 0 will prevent the library from rewriting the file, and

setting it to 1 will force the rewrite. The default value is -1.

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CG_CONFIG_SET_PATH Sets the search path for locating linked-to files. The argument value

should be a character string containing one or more directories, formatted the same as for the PATH environment variable. This will replace any current settings. Setting value to NULL will remove all paths.

CG_CONFIG_ADD_PATH Adds a directory, or list of directories, to the linked-to file search path.

This is the same as ${\tt CG_CONFIG_SET_PATH},$ but adds to the path instead

of replacing it.

CG_CONFIG_HDF5_COMPRESS

Sets the compression level for data written from HDF5. The default is no compression. Setting value to -1, will use the default compression level of 6. The acceptable values are 0 to 9, corresponding to gzip compression levels.

The routines cg_error_handler, cg_set_compress, cg_set_path, and cg_add_path are convenience functions built on top of cg_configure.

There is no Fortran counterpart to function cg_configure or cg_error_handler.

Note: The HDF5 implementation does not support search paths for linked files. The links need to be either absolute or relative pathnames. As a result, it is recommended that the search path options not be used as they may be removed in future versions.

4 Navigating a CGNS File

4.1 Accessing a Node

Functions	Modes
<pre>ier = cg_goto(int fn, int B,, "end");</pre>	r w m
<pre>ier = cg_gorel(int fn,, "end");</pre>	rwm
<pre>ier = cg_gopath(int fn, const char *path);</pre>	r w m
<pre>ier = cg_golist(int fn, int B, int depth, char **label, int *index);</pre>	r w m
<pre>ier = cg_gowhere(int *fn, int *B, int *depth, char **label,</pre>	r w m
<pre>int *index);</pre>	
call cg_goto_f(fn, B, ier,, 'end')	rwm
call cg_gorel_f(fn, ier,, 'end')	rwm
call cg_gopath_f(fn, path, ier)	rwm

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

- fn CGNS file index number. (Input)
- B Base index number, where $1 \le B \le nbases$. (Input)
- ... Variable argument list used to specify the path to a node. It is composed of an unlimited list of pair-arguments identifying each node in the path. Nodes may be identified by their label or name. Thus, a pair-argument may be of the form

```
"CGNS_NodeLabel", NodeIndex
```

where CGNS_NodeLabel is the node label and NodeIndex is the node index, or

```
"CGNS_NodeName", 0
```

where CGNS_NodeName is the node name. The 0 in the second form is required, to indicate that a node name is being specified rather than a node label. In addition, a pair-argument may be specified as

```
"..", 0
```

indicating the parent of the current node. The different pair-argument forms may be intermixed in the same function call.

There is one exception to this rule. When accessing a BCData_t node, the index must be set to either Dirichlet or Neumann since only these two types are allowed. (Note that Dirichlet and Neumann are defined in the include files cgnslib.h and $cgnslib_f.h$). Since "Dirichlet" and "Neuman" are also the names for these nodes, you may also use the "Dirichlet", 0 or "Neuman", 0 to access the node. See the example below. (Input)

- end The character string "end" (or 'end' for the Fortran function) must be the last argument. It is used to indicate the end of the argument list. You may also use the empty string, "" ('' for Fortran), or the NULL string in C, to terminate the list. (Input)
- The pathname for the node to go to. If a position has been already set, this may be a relative path, otherwise it is an absolute path name, starting with "/Basename", where Basename is the base under which you wish to move. (Input)
- depth Depth of the path list. The maximum depth is defined in *cgnslib.h* by CG_MAX_GOTO_DEPTH, and is currently equal to 20. (Input for cg_golist; *output* for cg_gowhere)
- label Array of node labels for the path. This argument may be passed as NULL to cg_where(), otherwise it must be dimensioned by the calling program. The maximum size required is label[MAX_GO_TO_DEPTH][33]. You may call cg_where() with both label and index set to NULL in order to get the current depth, then dimension to that value. (Input for cg_golist; output for cg_gowhere)
- index Array of node indices for the path. This argument may be passed as NULL to cg_where(), otherwise it must be dimensioned by the calling program. The maximum size required is index[MAX_GO_TO_DEPTH]. You may call cg_where() with both label and index set to NULL in order to get the current depth, then dimension to that value. (Input for cg_golist; output for cg_gowhere)
- ier Error status. The possible values, with the corresponding C names (or Fortran parameters) defined in *cgnslib.h* (or *cgnslib_f.h*) are listed below.

```
        Value
        Name/Parameter

        0
        CG_OK

        1
        CG_ERROR

        2
        CG_NODE_NOT_FOUND

        3
        CG_INCORRECT_PATH
```

For non-zero values, an error message may be printed using cg_error_print(), as described in Section 5. (Output)

This function allows access to any parent-type nodes in a CGNS file. A parent-type node is one that can have children. Nodes that cannot have children, like Descriptor_t, are not supported by this function.

Examples

To illustrate the use of the above routines, assume you have a file with CGNS index number filenum, a base node named Base with index number basenum, 2 zones (named Zone1 and Zone2, with indices 1 and 2), and user-defined data (User, index 1) below each zone. To move to the user-defined data node under zone 1, you may use any of the following:

```
cg_goto(filenum, basenum, "Zone_t", 1, "UserDefinedData_t", 1, NULL);
cg_goto(filenum, basenum "Zone1", 0, "UserDefinedData_t", 1, NULL);
cg_goto(filenum, basenum, "Zone_t", 1, "User", 0, NULL);
cg_goto(filenum, basenum, "Zone1", 0, "User", 0, NULL);
cg_gopath(filenum, "/Base/Zone1/User");
```

Now, to change to the user-defined data node under zone 2, you may use the full path specification as above, or else a relative path, using one of the following:

```
cg_gorel(filenum, "..", 0, "..", 0, "Zone_t", 2, "UserDefinedData_t", 1, NULL);
cg_gorel(filenum, "..", 0, "..", 0, "Zone2", 0, "UserDefinedData_t", 1, NULL);
cg_gorel(filenum, "..", 0, "..", 0, "Zone_t", 2, "User", 0, NULL);
cg_gorel(filenum, "..", 0, "..", 0, "Zone2", 0, "User", 0, NULL);
cg_gopath(filenum, ".../../Zone2/User");
```

Shown below are some additional examples of various uses of these routines, in both C and Fortran, where fn, B, Z, etc., are index numbers.

4.2 Deleting a Node

Functions	Modes
<pre>ier = cg_delete_node(char *NodeName);</pre>	m
<pre>call cg_delete_node_f(NodeName, ier)</pre>	m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

```
NodeName Name of the child to be deleted. (Input) ier Error status. (Output)
```

The function cg_delete_node is used is conjunction with cg_goto. Once positioned at a parent node with cg_goto, a child of this node can be deleted with cg_delete_node. This function requires a single argument, NodeName, which is the name of the child to be deleted.

Mid-Level Library

Since the highest level that can be pointed to with cg_goto is a base node for a CGNS database (CGNSBase_t), the highest-level nodes that can be deleted are the children of a CGNSBase_t node. In other words, nodes located directly under the ADF (or HDF) root node (CGNSBase_t and CGNSLibraryVersion_t) can not be deleted with cg_delete.

A few other nodes are not allowed to be deleted from the database because these are required nodes as defined by the SIDS, and deleting them would make the file non-CGNS compliant. These are:

- Under Zone_t: ZoneType
- Under GridConnectivity1to1_t: PointRange, PointRangeDonor, Transform
- Under OversetHoles_t: PointList and any IndexRange_t
- Under GridConnectivity_t: PointRange, PointList, CellListDonor, PointListDonor
- Under BC_t: PointList, PointRange
- Under GeometryReference_t: GeometryFile, GeometryFormat
- Under Elements_t: ElementRange, ElementConnectivity
- Under Gravity_t: GravityVector
- Under Axisymmetry_t: AxisymmetryReferencePoint, AxisymmetryAxisVector
- Under RotatingCoordinates_t: RotationCenter, RotationRateVector
- Under Periodic_t: RotationCenter, RotationAngle, Translation
- Under AverageInterface_t: AverageInterfaceType
- Under WallFunction_t: WallFunctionType
- Under Area_t: AreaType, SurfaceArea, RegionName

When a child node is deleted, both the database and the file on disk are updated to remove the node. One must be careful not to delete a node from within a loop of that node type. For example, if the number of zones below a CGNSBase_t node is nzones, a zone should never be deleted from within a zone loop! By deleting a zone, the total number of zones (nzones) changes, as well as the zone indexing. Suppose for example that nzones is 5, and that the third zone is deleted. After calling cg_delete_node, nzones is changed to 4, and the zones originally indexed 4 and 5 are now indexed 3 and 4.

5 Error Handling

Functions	Modes
<pre>error_message = const char *cg_get_error();</pre>	rwm
<pre>void cg_error_exit();</pre>	rwm
<pre>void cg_error_print();</pre>	rwm
<pre>call cg_get_error_f(error_message)</pre>	rwm
<pre>call cg_error_exit_f()</pre>	rwm
<pre>call cg_error_print_f()</pre>	rwm

If an error occurs during the execution of a CGNS library function, signified by a non-zero value of the error status variable <code>ier</code>, an error message may be retrieved using the function <code>cg_get_error</code>. The function <code>cg_error_exit</code> may then be used to print the error message and stop the execution of the program. Alternatively, <code>cg_error_print</code> may be used to print the error message and continue execution of the program.

In C, you may define a function to be called automatically in the case of a warning or error using the cg_configure routine. The function is of the form void err_func(int is_error, char *errmsg), and will be called whenever an error or warning occurs. The first argument, is_error, will be 0 for warning messages, 1 for error messages, and -1 if the program is going to terminate (i.e., a call to cg_error_exit). The second argument is the error or warning message.

6 Structural Nodes

6.1 CGNS Base Information

Node: CGNSBase_t

Functions	Modes
<pre>ier = cg_base_write(int fn, char *basename, int cell_dim, int phys_dim,</pre>	- w m
int *B);	
<pre>ier = cg_nbases(int fn, int *nbases);</pre>	r - m
<pre>ier = cg_base_read(int fn, int B, char *basename, int *cell_dim,</pre>	r - m
<pre>int *phys_dim);</pre>	
<pre>ier = cg_cell_dim(int fn, int B, int *cell_dim);</pre>	r - m
call cg_base_write_f(fn, basename, cell_dim, phys_dim, B, ier)	- w m
call cg_nbases_f(fn, nbases, ier)	r - m
call cg_base_read_f(fn, B, basename, cell_dim, phys_dim, ier)	r - m
call cg_cell_dim_f(fn, B, cell_dim, ier)	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

```
fn
            CGNS file index number. (Input)
В
            Base index number, where 1 \le B \le nbases. (Input for cg_base_read; output for
            cg_base_write)
nbases
            Number of bases present in the CGNS file fn. (Output)
            Name of the base. (Input for cg_base_write; output for cg_base_read)
basename
            Dimension of the cells; 3 for volume cells, 2 for surface cells and 1 for line cells.
cell_dim
            (Input for cg_base_write; output for cg_base_read and cg_cell_dim)
            Number of coordinates required to define a vector in the field. (Input for
phys_dim
            cg_base_write; output for cg_base_read)
            Error status. (Output)
ier
```

6.2 Zone Information

Node: Zone_t

Functions	Modes
<pre>ier = cg_zone_write(int fn, int B, char *zonename, cgsize_t *size,</pre>	- w m
<pre>ZoneType_t zonetype, int *Z);</pre>	
<pre>ier = cg_nzones(int fn, int B, int *nzones);</pre>	r - m
<pre>ier = cg_zone_read(int fn, int B, int Z, char *zonename,</pre>	r - m
cgsize_t *size);	
<pre>ier = cg_zone_type(int fn, int B, int Z, ZoneType_t *zonetype);</pre>	r - m
<pre>ier = cg_index_dim(int fn, int B, int Z, int *index_dim);</pre>	r - m
call cg_zone_write_f(fn, B, zonename, size, zonetype, Z, ier)	
call cg_nzones_f(fn, B, nzones, ier)	r - m
call cg_zone_read_f(fn, B, Z, zonename, size, ier)	r - m
call cg_zone_type_f(fn, B, Z, zonetype, ier)	r - m
<pre>call cg_index_dim_f(fn, B, Z, index_dim, ier)</pre>	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

fn	CGNS file index number. (Input)
В	Base index number, where $1 \le B \le nbases$. (Input)
Z	Zone index number, where $1 \le Z \le nzones$. (Input for cg_zone_read, cg_zone_type; $output$ for cg_zone_write)
nzones	Number of zones present in base B. (Output)
zonename	Name of the zone. (Input for cg_zone_write; output for cg_zone_read)
size	Number of vertices, cells, and boundary vertices in each (<i>index</i>)-dimension. Note that for unstructured grids, the number of cells is the number of highest order elements. Thus, in three dimensions it's the number of 3-D cells, and in two dimensions it's the number of 2-D cells.
	Also for unstructured grids, if the nodes are sorted between internal nodes and boundary nodes, the optional parameter NBoundVertex must be set equal to the number of boundary nodes. By default, NBoundVertex equals zero, meaning that

the nodes are unsorted.

Note that a non-zero value for $\mathtt{NBoundVertex}$ only applies to unstructured grids. For structured grids, the $\mathtt{NBoundVertex}$ parameter always equals 0 in all directions.

```
Mesh Type
                                Size
             3D structured
                                NVertexI, NVertexJ, NVertexK
                                NCellI, NCellJ, NCellK
                                \texttt{NBoundVertexI} = 0, \texttt{NBoundVertexJ} = 0,
                                NBoundVertexK
             2D structured
                                NVertexI, NVertexJ
                                NCellI, NCellJ
                                \texttt{NBoundVertexI} = 0, \texttt{NBoundVertexJ} = 0
             3D unstructured
                               NVertex, NCell3D, NBoundVertex
             2D unstructured
                               NVertex, NCell2D, NBoundVertex
             (Input for cg_zone_write; output for cg_zone_read)
             Type of the zone. The admissible types are Structured and Unstructured.
zonetype
             (Input for cg_zone_write; output for cg_zone_type)
index_dim
             Index dimension for the zone. For Structured zones, this will be the base cell
             dimension and for Unstructured zones it will be 1. (output)
ier
             Error status. (Output)
```

Note that the zones are sorted alphanumerically to insure that they can always be retrieved in the same order (for the same model). Therefore, users must name their zones alphanumerically to ensure proper retrieval.

6.3 Simulation Type

Node: SimulationType_t

Functions	Modes
<pre>ier = cg_simulation_type_write(int fn, int B,</pre>	- w m
<pre>SimulationType_t SimulationType);</pre>	
<pre>ier = cg_simulation_type_read(int fn, int B,</pre>	r - m
SimulationType_t SimulationType);	
<pre>call cg_simulation_type_write_f(fn, B, SimulationType, ier)</pre>	- w m
<pre>call cg_simulation_type_read_f(fn, B, SimulationType, ier)</pre>	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

fn	CGNS file index number. (Input)
В	Base index number, where $1 \le \mathtt{B} \le \mathtt{nbases}$. (Input)
SimulationType	Type of simulation. Valid types are CG_Null, CG_UserDefined, TimeAccurate, and NonTimeAccurate. (Input for cg_simulation_type_write; output for cg_simulation_type_read)
ier	Error status. (Output)

7 Descriptors

7.1 Descriptive Text

Node: Descriptor_t

Functions	Modes
<pre>ier = cg_descriptor_write(char *name, char *text);</pre>	- w m
<pre>ier = cg_ndescriptors(int *ndescriptors);</pre>	r - m
<pre>ier = cg_descriptor_read(int D, char *name, char **text);</pre>	r - m
<pre>call cg_descriptor_write_f(name, text, ier)</pre>	- w m
<pre>call cg_ndescriptors_f(ndescriptors, ier)</pre>	r - m
<pre>call cg_descriptor_size_f(D, size, ier)</pre>	r - m
<pre>call cg_descriptor_read_f(D, name, text, ier)</pre>	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

ndescriptors	Number of Descriptor_t nodes under the current node. (Output)
D	Descriptor index number, where $1 \le \mathtt{D} \le \mathtt{ndescriptors}$. (Input)
name	Name of the Descriptor_t node. (Input for cg_descriptor_write; $\it output$ for cg_descriptor_read)
text	Description held in the Descriptor_t node. (Input for cg_descriptor_write; output for cg_descriptor_read)
size	Size of the descriptor data (Fortran interface only). (${\it Output})$
ier	Error status. (Output)

Note that with cg_descriptor_read the memory for the descriptor character string, text, will be allocated by the Mid-Level Library. The application code is responsible for releasing this memory when it is no longer needed by calling cg_free(text), described in Section 10.6.

7.2 Ordinal Value

 $Node: {\tt Ordinal_t}$

Functions	
<pre>ier = cg_ordinal_write(int Ordinal);</pre>	- w m
<pre>ier = cg_ordinal_read(int *Ordinal);</pre>	r - m
call cg_ordinal_write_f(Ordinal, ier)	- w m
call cg_ordinal_read_f(Ordinal, ier)	r - m

Mid-Level Library

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

```
Ordinal Any integer value. (Input for cg_ordinal_write; output for cg_ordinal_read)
ier Error status. (Output)
```

8 Physical Data

8.1 Data Arrays

 $Node: {\tt DataArray_t}$

Functions	Modes
<pre>ier = cg_array_write(char *ArrayName, DataType_t DataType,</pre>	- w m
<pre>int DataDimension, cgsize_t *DimensionVector, void *Data);</pre>	
<pre>ier = cg_narrays(int *narrays);</pre>	r - m
<pre>ier = cg_array_info(int A, char *ArrayName, DataType_t *DataType,</pre>	r - m
<pre>int *DataDimension, cgsize_t *DimensionVector);</pre>	
<pre>ier = cg_array_read(int A, void *Data);</pre>	r - m
<pre>ier = cg_array_read_as(int A, DataType_t DataType, void *Data);</pre>	r - m
<pre>call cg_array_write_f(ArrayName, DataType, DataDimension,</pre>	- w m
DimensionVector, Data, ier)	
call cg_narrays_f(narrays, ier)	r - m
call cg_array_info_f(A, ArrayName, DataType, DataDimension,	r - m
DimensionVector, ier)	
call cg_array_read_f(A, Data, ier)	r - m
<pre>call cg_array_read_as_f(A, DataType, Data, ier)</pre>	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

narrays	Number of DataArray_t nodes under the current node. $(Output)$
A	Data array index, where $1 \le \mathtt{A} \le \mathtt{narrays}$. (Input)
ArrayName	Name of the DataArray_t node. (Input for cg_array_write; $output$ for cg_array_info)
DataType	Type of data held in the DataArray_t node. The admissible types are Integer, LongInteger, RealSingle, RealDouble, and Character. (Input for cg_array_write, cg_array_read_as; output for cg_array_info)
DataDimension	Number of dimensions. (Input for cg_array_write; output for cg_array_info)
DimensionVector	Number of data elements in each dimension. (Input for cg_array_write ; output for cg_array_info)
Data	The data array. (Input for cg_array_write; output for cg_array_read, cg_array_read_as)
ier	Error status. (Output)

8.2 Data Class

 $Node: {\tt DataClass_t}$

Functions	
<pre>ier = cg_dataclass_write(DataClass_t dataclass);</pre>	- w m
<pre>ier = cg_dataclass_read(DataClass_t *dataclass);</pre>	r - m
<pre>call cg_dataclass_write_f(dataclass, ier)</pre>	- w m
call cg_dataclass_read_f(dataclass, ier)	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

dataclass	Data class for the nodes at this level. See below for the data classes currently
	supported in CGNS. (Input for cg_dataclass_write; output for
	cg_dataclass_read)
ier	Error status. (Output)

The data classes currently supported in CGNS are:

Dimensional	Regular dimensional data.
NormalizedByDimensional	Nondimensional data that is normalized by dimensional reference quantities.
${\tt NormalizedByUnknownDimensional}$	All fields and reference data are nondimensional.
NondimensionalParameter	Nondimensional parameters such as Mach number and lift coefficient.
DimensionlessConstant	Constant such as π .

These classes are declared within typedef DataClass_t in cgnslib.h, and as parameters in cgnslib_f.h.

8.3 Data Conversion Factors

 $Node: {\tt DataConversion_t}$

Functions	Modes
<pre>ier = cg_conversion_write(DataType_t DataType,</pre>	- w m
<pre>void *ConversionFactors);</pre>	
<pre>ier = cg_conversion_info(DataType_t *DataType);</pre>	r - m
<pre>ier = cg_conversion_read(void *ConversionFactors);</pre>	r - m
call cg_conversion_write_f(DataType, ConversionFactors, ier)	- w m
call cg_conversion_info_f(DataType, ier)	r - m
call cg_conversion_read_f(ConversionFactors, ier)	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

Data type in which the conversion factors are recorded. Admissible data

types for conversion factors are RealSingle and RealDouble. (Input for

cg_conversion_write; output for cg_conversion_info)

ConversionFactors Two-element array containing the scaling and offset factors. (Input for

cg_conversion_write; output for cg_conversion_read)

ier Error status. (Output)

The DataConversion_t data structure contains factors to convert the nondimensional data to "raw" dimensional data. The scaling and offset factors are contained in the two-element array ConversionFactors. In pseudo-Fortran, the conversion process is as follows:

```
ConversionScale = ConversionFactors(1)
ConversionOffset = ConversionFactors(2)
Data(raw) = Data(nondimensional)*ConversionScale + ConversionOffset
```

8.4 Dimensional Units

Node: DimensionalUnits_t

Functions	Modes
<pre>ier = cg_units_write(MassUnits_t mass, LengthUnits_t length,</pre>	- w m
<pre>TimeUnits_t time, TemperatureUnits_t temperature,</pre>	
AngleUnits_t angle);	
<pre>ier = cg_unitsfull_write(MassUnits_t mass, LengthUnits_t length,</pre>	- w m
TimeUnits_t time, TemperatureUnits_t temperature,	
AngleUnits_t angle, ElectricCurrentUnits_t current,	
SubstanceAmountUnits_t amount,	
LuminousIntensityUnits_t intensity);	
<pre>ier = cg_nunits(int *nunits);</pre>	r - m
<pre>ier = cg_units_read(MassUnits_t *mass, LengthUnits_t *length,</pre>	r - m
<pre>TimeUnits_t *time, TemperatureUnits_t *temperature,</pre>	
AngleUnits_t *angle);	
<pre>ier = cg_unitsfull_read(MassUnits_t *mass, LengthUnits_t *length,</pre>	r - m
<pre>TimeUnits_t *time, TemperatureUnits_t *temperature,</pre>	
AngleUnits_t *angle, ElectricCurrentUnits_t *current,	
SubstanceAmountUnits_t *amount,	
LuminousIntensityUnits_t *intensity);	
call cg_units_write_f(mass, length, time, temperature, angle, ier)	- w m
<pre>call cg_unitsfull_write_f(mass, length, time, temperature, angle,</pre>	- w m
current, amount, intensity, ier)	
call cg_nunits_f(int *nunits)	r - m
call cg_units_read(mass, length, time, temperature, angle, ier)	r - m
call cg_unitsfull_read_f(mass, length, time, temperature, angle,	r - m
current, amount, intensity, ier)	

Input/Output

(Note that for Fortran calls, all integer arguments are integer *4 in 32-bit mode and integer *8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

mass	Mass units. Admissible values are CG_Null, CG_UserDefined, Kilogram, Gram, Slug, and PoundMass. (Input for cg_units_write, cg_unitsfull_write; output for cg_units_read, cg_unitsfull_read)
length	Length units. Admissible values are CG_Null, CG_UserDefined, Meter, Centimeter, Millimeter, Foot, and Inch. (Input for cg_units_write, cg_unitsfull_write; output for cg_units_read, cg_unitsfull_read)
time	Time units. Admissible values are CG_Null, CG_UserDefined, and Second. (Input for cg_units_write, cg_unitsfull_write; output for cg_units_read, cg_unitsfull_read)
temperature	Temperature units. Admissible values are CG_Null, CG_UserDefined, Kelvin, Celsius, Rankine, and Fahrenheit. (Input for cg_units_write, cg_unitsfull_write; output for cg_units_read, cg_unitsfull_read)
angle	Angle units. Admissible values are CG_Null, CG_UserDefined, Degree, and

Radian. (Input for cg_units_write, cg_unitsfull_write; output for

cg_units_read, cg_unitsfull_read)

Ampere, Abampere, Statampere, Edison, and auCurrent. (Input for

cg_unitsfull_write; output for cg_unitsfull_read)

amount Substance amount units. Admissible values are CG_Null, CG_UserDefined,

Mole, Entities, StandardCubicFoot, and StandardCubicMeter. (Input for

cg_unitsfull_write; output for cg_unitsfull_read)

Candela, Candle, Carcel, Hefner, and Violle. (Input for cg_unitsfull_write; output for cg_unitsfull_read)

nunits Number of units used in the file (i.e., either 5 or 8). (Output)

ier Error status. (Output)

The supported units are declared within typedefs in cgnslib.h and as parameters in cgnslib_f.h.

When reading units data, either cg_units_read or cg_unitsfull_read may be used, regardless of the number of units used in the file. If cg_unitsfull_read is used, but only five units are used in the file, the returned values of current, amount, and intensity will be CG_Null.

8.5 Dimensional Exponents

 $Node {:}\ {\tt DimensionalExponents_t}$

Functions	Modes
<pre>ier = cg_exponents_write(DataType_t DataType, void *exponents);</pre>	- w m
<pre>ier = cg_expfull_write(DataType_t DataType, void *exponents);</pre>	- w m
<pre>ier = cg_nexponents(int *nexponents);</pre>	r - m
<pre>ier = cg_exponents_info(DataType_t *DataType);</pre>	r - m
<pre>ier = cg_exponents_read(void *exponents);</pre>	r - m
<pre>ier = cg_expfull_read(void *exponents);</pre>	r - m
<pre>call cg_exponents_write_f(DataType, exponents, ier)</pre>	- w m
<pre>call cg_expfull_write_f(DataType, exponents, ier)</pre>	- w m
call cg_nexponents_f(nexponents, ier)	r - m
call cg_exponents_info_f(DataType, ier)	r - m
call cg_exponents_read_f(exponents, ier)	r - m
call cg_expfull_read_f(exponents, ier)	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

DataType	Data type in which the exponents are recorded. Admissible data types for the exponents are RealSingle and RealDouble. (Input for cg_exponents_write; output for cg_exponents_info)
exponents	Exponents for the dimensional units for mass, length, time, temperature, angle, electric current, substance amount, and luminous intensity, in that order. (Input for cg_exponents_write, cg_expfull_write; output for cg_exponents_read, cg_expfull_read)
nexponents	Number of exponents used in the file (i.e., either 5 or 8). ($Output$)
ier	Error status. (Output)

When reading exponent data, either cg_exponents_read or cg_expfull_read may be used, regardless of the number of exponents used in the file. If cg_exponents_read is used, but all eight exponents are used in the file, only the first five exponents are returned. If cg_expfull_read is used, but only five exponents are used in the file, the returned values of the exponents for electric current, substance amount, and luminous intensity will be zero.

9 Location and Position

9.1 Grid Location

Node: GridLocation_t

Functions	Modes
<pre>ier = cg_gridlocation_write(GridLocation_t GridLocation);</pre>	- w m
<pre>ier = cg_gridlocation_read(GridLocation_t *GridLocation);</pre>	r - m
<pre>call cg_gridlocation_write_f(GridLocation, ier)</pre>	- w m
call cg_gridlocation_read_f(GridLocation, ier)	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

GridLocation Location in the grid. The admissible locations are CG_Null, CG_UserDefined,
Vertex, CellCenter, FaceCenter, IFaceCenter, JFaceCenter,
KFaceCenter, and EdgeCenter. (Input for cg_gridlocation_write; output
for cg_gridlocation_read)

ier Error status. (Output)

9.2 Point Sets

Node: IndexArray_t, IndexRange_t

Functions	Modes
<pre>ier = cg_ptset_write(PointSetType_t *ptset_type, cgsize_t npnts,</pre>	- w m
cgsize_t *pnts);	
<pre>ier = cg_ptset_info(PointSetType_t *ptset_type, cgsize_t *npnts);</pre>	r - m
<pre>ier = cg_ptset_read(cgsize_t *pnts);</pre>	r - m
<pre>call cg_ptset_write_f(ptset_type, npnts, pnts, ier)</pre>	- w m
<pre>call cg_ptset_info_f(ptset_type, npnts, ier)</pre>	r - m
<pre>call cg_ptset_read_f(pnts, ier)</pre>	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

```
the number of points or cells in the list. (Input for cg_ptset_write; output for cg_ptset_info)

pnts

The array of point or cell indices defining the point set. There should be npnts values, each of dimension IndexDimension (i.e., 1 for unstructured grids, and 2 or 3 for structured grids with 2-D or 3-D elements, respectively). (Input for cg_ptset_write; output for cg_ptset_read)

ier

Error status. (Output)
```

These functions may be used to write and read point set data (i.e., an IndexArray_t node named PointList, or an IndexRange_t node named PointRange). They are only applicable at nodes that are descendents of a Zone_t node.

9.3 Rind Layers

Node: Rind_t

Functions	Modes
<pre>ier = cg_rind_write(int *RindData);</pre>	- w m
<pre>ier = cg_rind_read(int *RindData);</pre>	r - m
call cg_rind_write_f(RindData, ier)	- w m
call cg_rind_read_f(RindData, ier)	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

```
RindData Number of rind layers for each computational direction (structured grid) or number of rind points or elements (unstructured grid). (Input for cg_rind_write; output for cg_rind_read)

ier Error status. (Output)
```

When writing rind data for elements, cg_section_write must be called first (see Section 11.2), followed by cg_goto (Section 4) to access the Elements_t node, and then cg_rind_write.

10 Auxiliary Data

10.1 Reference State

Node: ReferenceState_t

Functions	Modes
<pre>ier = cg_state_write(char *StateDescription);</pre>	- w m
<pre>ier = cg_state_read(char **StateDescription);</pre>	r - m
call cg_state_write_f(StateDescription, ier)	- w m
call cg_state_size_f(Size, ier)	r - m
call cg_state_read_f(StateDescription, ier)	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

StateDescription	Text description of reference state. (Input for cg_state_write; output for cg_state_read)
Size	Number of characters in the ${\tt StateDescription}$ string (Fortran interface only). $({\it Output})$
ier	Error status. (Output)

The function cg_state_write creates the ReferenceState_t node and must be called even if StateDescription is undefined (i.e., a blank string). The descriptors, data arrays, data class, and dimensional units characterizing the ReferenceState_t data structure may be added to this data structure after its creation.

The function cg_state_read reads the StateDescription of the local ReferenceState_t node. If StateDescription is undefined in the CGNS database, this function returns a null string. If StateDescription exists, the library will allocate the space to store the description string, and return the description string to the application. It is the responsibility of the application to free this space when it is no longer needed by a call to cg_free(StateDescription), described in Section 10.6.

10.2 Gravity

Node: Gravity_t

Functions	Modes
<pre>ier = cg_gravity_write(int fn, int B, float *GravityVector);</pre>	- w m
<pre>ier = cg_gravity_read(int fn, int B, float *GravityVector);</pre>	r - m
<pre>call cg_gravity_write_f(fn, B, GravityVector, ier)</pre>	- w m
call cg_gravity_read_f(fn, B, GravityVector, ier)	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

```
fn CGNS file index number. (Input)

B Base index number, where 1 ≤ B ≤ nbases. (Input)

GravityVector Components of the gravity vector. The number of components must equal PhysicalDimension. (In Fortran, this is an array of Real*4 values.) (Input for cg_gravity_write; output for cg_gravity_read)

ier Error status. (Output)
```

10.3 Convergence History

Node: ConvergenceHistory_t

Functions	Modes
<pre>ier = cg_convergence_write(int niterations, char *NormDefinitions);</pre>	- w m
<pre>ier = cg_convergence_read(int *niterations, char **NormDefinitions);</pre>	r - m
call cg_convergence_write_f(niterations, NormDefinitions, ier)	- w m
call cg_convergence_read_f(niterations, NormDefinitions, ier)	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

```
Number of iterations for which convergence information is recorded.

(Input for cg_convergence_write; output for cg_convergence_read)

NormDefinitions Description of the convergence information recorded in the data arrays.

(Input for cg_convergence_write; output for cg_convergence_read)

ier Error status. (Output)
```

The function cg_convergence_write creates a ConvergenceHistory_t node. It must be the first one called when recording convergence history data. The NormDefinitions may be left undefined (i.e., a blank string). After creation of this node, the descriptors, data arrays, data class, and dimensional units characterizing the ConvergenceHistory_t data structure may be added.

The function cg_convergence_read reads a ConvergenceHistory_t node. If NormDefinitions is not defined in the CGNS database, this function returns a null string. If NormDefinitions exists, the library will allocate the space to store the description string, and return the description string to the application. It is the responsibility of the application to free this space when it is no longer needed by a call to cg_free(NormDefinitions), described in Section 10.6.

10.4 Integral Data

 $Node: {\tt IntegralData_t}$

Functions	Modes
<pre>ier = cg_integral_write(char *Name);</pre>	- w m
<pre>ier = cg_nintegrals(int *nintegrals);</pre>	r - m
<pre>ier = cg_integral_read(int Index, char *Name);</pre>	r - m
call cg_integral_write_f(Name, ier)	- w m
call cg_nintegrals_f(nintegrals, ier)	r - m
call cg_integral_read_f(Index, Name, ier)	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

Name	Name of the IntegralData_t data structure. (Input for cg_integral_write; output for cg_integral_read)
nintegrals	Number of $IntegralData_t$ nodes under current node. ($Output$)
Index	Integral data index number, where $1 \leq \mathtt{Index} \leq \mathtt{nintegrals}$. (Input)
ier	Error status. (Output)

10.5 User-Defined Data

 $Node : {\tt UserDefinedData_t}$

Functions	Modes
<pre>ier = cg_user_data_write(char *Name);</pre>	- w m
<pre>ier = cg_nuser_data(int *nuserdata);</pre>	r - m
<pre>ier = cg_user_data_read(int Index, char *Name);</pre>	r - m
<pre>call cg_user_data_write_f(Name, ier)</pre>	- w m
call cg_nuser_data_f(nuserdata, ier)	r - m
<pre>call cg_user_data_read_f(Index, Name, ier)</pre>	r - m

Input/Output

nuserdata	Number of $UserDefinedData_t$ nodes under current node. ($Output$)
Name	Name of the UserDefinedData_t node. (Input for cg_user_data_write; $output$ for cg_user_data_read)
Index	User-defined data index number, where 1 < Index < nuserdata. (Input)

```
ier Error status. (Output)
```

After accessing a particular UserDefinedData_t node using cg_goto, the Point Set functions described in Section 9.2 may be used to read or write point set information for the node. The function cg_gridlocation_write may also be used to specify the location of the data with respect to the grid (e.g., Vertex or FaceCenter).

Multiple levels of UserDefinedData_t nodes may be written and retrieved by positioning via cg_goto. E.g.,

10.6 Freeing Memory

Functions	Modes
<pre>ier = cg_free(void *data);</pre>	r w m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

```
data Data allocated by the Mid-Level Library. (Input) ier Error status. (Output)
```

This function does not affect the structure of a CGNS file; it is provided as a convenience to free memory allocated by the Mid-Level Library when using C. This isn't necessary in Fortran, and thus an equivalent Fortran function is not provided.

The functions that are used to allocate memory for return values are cg_descriptor_read, cg_convergence_read, cg_geo_read, cg_link_read, and cg_state_read. Each of these may allocate space to contain the data returned to the application. It is the responsibility of the application to free this data when it is no longer needed. Calling cg_free is identical to calling the standard C function free, however it is probably safer in that the memory is freed in the same module in which it is created, particularly when the Mid-Level Library is a shared library or DLL. The routine checks for NULL data and will return CG_ERROR in this case, otherwise it returns CG_OK.

11 Grid Specification

11.1 Zone Grid Coordinates

Node: GridCoordinates_t

GridCoordinates_t nodes are used to describe grids associated with a particular zone. The original grid must be described by a GridCoordinates_t node named GridCoordinates. Additional GridCoordinates_t nodes may be used, with user-defined names, to store grids at multiple time steps or iterations. In addition to the discussion of the GridCoordinates_t node in the SIDS and File Mapping manuals, see the discussion of the ZoneIterativeData_t and ArbitraryGridMotion_t nodes in the SIDS manual.

Functions	Modes
<pre>ier = cg_grid_write(int fn, int B, int Z, char *GridCoordName,</pre>	- w m
int *G);	
<pre>ier = cg_ngrids(int fn, int B, int Z, int *ngrids);</pre>	- w m
<pre>ier = cg_grid_read(int fn, int B, int Z, int G, char *GridCoordName);</pre>	r - m
call cg_grid_write_f(fn, B, Z, GridCoordName, G, ier)	- w m
call cg_ngrids_f(fn, B, Z, ngrids, ier)	- w m
call cg_grid_read_f(fn, B, Z, G, GridCoordName, ier)	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

fn	CGNS file index number. (Input)
В	Base index number, where $1 \le B \le nbases$. (Input)
Z	Zone index number, where $1 \le Z \le nzones.$ (Input)
G	Grid index number, where $1 \le \texttt{G} \le \texttt{ngrids}$. (Input for cg_grid_read; output for cg_grid_write)
ngrids	Number of $GridCoordinates_t$ nodes for zone Z. ($Output$)
GridCoordinateName	Name of the GridCoordinates_t node. Note that the name "GridCoordinates" is reserved for the original grid and must be the first GridCoordinates_t node to be defined. (Input for cg_grid_write; output for cg_grid_read)
ier	Error status. (Output)

The above functions are applicable to any GridCoordinates_t node.

Functions	Modes
<pre>ier = cg_coord_write(int fn, int B, int Z, DataType_t datatype,</pre>	- w m
<pre>char *coordname, void *coord_array, int *C);</pre>	
<pre>ier = cg_coord_partial_write(int fn, int B, int Z,</pre>	- w m
DataType_t datatype, char *coordname, cgsize_t *range_min,	
<pre>cgsize_t *range_max, void *coord_array, int *C);</pre>	
<pre>ier = cg_ncoords(int fn, int B, int Z, int *ncoords);</pre>	r - m
<pre>ier = cg_coord_info(int fn, int B, int Z, int C, DataType_t *datatype,</pre>	r - m
<pre>char *coordname);</pre>	
<pre>ier = cg_coord_read(int fn, int B, int Z, char *coordname,</pre>	r - m
DataType_t datatype, cgsize_t *range_min, cgsize_t *range_max,	
<pre>void *coord_array);</pre>	
<pre>call cg_coord_write_f(fn, B, Z, datatype, coordname, coord_array, C,</pre>	- w m
ier)	
<pre>call cg_coord_partial_write_f(fn, B, Z, datatype, coordname, range_min,</pre>	- w m
range_max, coord_array, C, ier)	
call cg_ncoords_f(fn, B, Z, ncoords, ier)	r - m
<pre>call cg_coord_info_f(fn, B, Z, C, datatype, coordname, ier)</pre>	r - m
<pre>call cg_coord_read_f(fn, B, Z, coordname, datatype, range_min,</pre>	r - m
range_max, coord_array, ier)	

Input/Output

fn	CGNS file index number. (Input)
В	Base index number, where $1 \le B \le nbases$. (Input)
Z	Zone index number, where $1 \le Z \le nzones$. (Input)
С	Coordinate array index number, where $1 \le \texttt{C} \le \texttt{ncoords}$. (Input for cg_coord_info; output for cg_coord_write)
ncoords	Number of coordinate arrays for zone Z. (Output)
datatype	Data type in which the coordinate array is written. Admissible data types for a coordinate array are RealSingle and RealDouble. (Input for cg_coord_write, cg_coord_partial_write, cg_coord_read; output for cg_coord_info)
coordname	Name of the coordinate array. It is strongly advised to use the SIDS nomenclature conventions when naming the coordinate arrays to insure file compatibility. (Input for cg_coord_write, cg_coord_partial_write, cg_coord_read; output for cg_coord_info)
range_min	Lower range index (eg., imin, jmin, kmin). (Input)
range_max	Upper range index (eg., imax, jmax, kmax). (Input)

```
coord_array Array of coordinate values for the range prescribed. (Input for cg_coord_write; cg_coord_partial_write, output for cg_coord_read)

ier Error status. (Output)
```

The above functions are applicable *only* to the GridCoordinates_t node named GridCoordinates, used for the original grid in a zone. Coordinates for additional GridCoordinates_t nodes in a zone must be read and written using the cg_array_xxx functions described in Section 8.1.

When writing, the function cg_coord_write will automatically write the full range of coordinates (i.e., the entire coord_array). The function cg_coord_partial_write may be used to write only a subset of coord_array. When using the partial write, any existing data as defined by range_min and range_max will be overwritten by the new values. All other values will not be affected.

The function cg_coord_read returns the coordinate array coord_array, for the range prescribed by range_min and range_max. The array is returned to the application in the data type requested in datatype. This data type does not need to be the same as the one in which the coordinates are stored in the file. A coordinate array stored as double precision in the CGNS file can be returned to the application as single precision, or vice versa.

In Fortran, when using cg_coord_read_f to read 2D or 3D coordinates, the extent of each dimension of coord_array must be consistent with the requested range. When reading a 1D solution, the declared size can be larger than the requested range. For example, for a 2D zone with 100×50 vertices, if range_min and range_max are set to (11,11) and (20,20) to read a subset of the coordinates, then coord_array must be dimensioned (10,10). If coord_array is declared larger (e.g., (100,50)) the indices for the returned coordinates will be wrong.

11.2 Element Connectivity

Node: Elements_t

Functions	Modes
<pre>ier = cg_section_write(int fn, int B, int Z, char *ElementSectionName,</pre>	- w m
<pre>ElementType_t type, cgsize_t start, cgsize_t end, int nbndry,</pre>	
cgsize_t *Elements, int *S);	
<pre>ier = cg_section_partial_write(int fn, int B, int Z,</pre>	- w m
<pre>char *ElementSectionName, ElementType_t type, cgsize_t start,</pre>	
<pre>cgsize_t end, int nbndry, int *S);</pre>	
<pre>ier = cg_elements_partial_write(int fn, int B, int Z, int S,</pre>	- w m
<pre>cgsize_t start, cgsize_t end, cgsize_t *Elements);</pre>	
<pre>ier = cg_parent_data_write(int fn, int B, int Z, int S,</pre>	- w m
<pre>cgsize_t *ParentData);</pre>	
<pre>ier = cg_parent_data_partial_write(int fn, int B, int Z, int S,</pre>	- w m
<pre>cgsize_t start, cgsize_t end, cgsize_t *ParentData);</pre>	
<pre>ier = cg_nsections(int fn, int B, int Z, int *nsections);</pre>	r - m
<pre>ier = cg_section_read(int fn, int B, int Z, int S,</pre>	r - m
$char *ElementSectionName$, $ElementType_t *type$, $cgsize_t *start$,	
<pre>cgsize_t *end, int *nbndry, int *parent_flag);</pre>	
<pre>ier = cg_ElementDataSize(int fn, int B, int Z, int S,</pre>	r - m
cgsize_t *ElementDataSize);	
<pre>ier = cg_ElementPartialSize(int fn, int B, int Z, int S,</pre>	r - m
<pre>cgsize_t start, cgsize_t end, cgsize_t *ElementDataSize);</pre>	
<pre>ier = cg_elements_read(int fn, int B, int Z, int S,</pre>	r - m
cgsize_t *Elements, cgsize_t *ParentData);	
<pre>ier = cg_elements_partial_read(int fn, int B, int Z, int S,</pre>	r - m
<pre>cgsize_t start, cgsize_t end, cgsize_t *Elements,</pre>	
cgsize_t *ParentData);	
<pre>ier = cg_npe(ElementType_t type, int *npe);</pre>	rwm

Functions	Modes
<pre>call cg_section_write_f(fn, B, Z, ElementSectionName, type, start, end,</pre>	- w m
nbndry, Elements, S, ier)	
<pre>call cg_section_partial_write_f(fn, B, Z, ElementSectionName, type,</pre>	- w m
start, end, nbndry, S, ier)	
call cg_elements_partial_write_f(fn, B, Z, S,	- w m
start, end, Elements, ier);	
<pre>call cg_parent_data_write_f(fn, B, Z, S, ParentData, ier)</pre>	- w m
<pre>call cg_parent_data_partial_write_f(fn, B, Z, S, start,</pre>	- w m
end, ParentData, ier)	
call cg_nsections_f(fn, B, Z, nsections, ier)	r - m
call cg_section_read_f(fn, B, Z, S, ElementSectionName, type,	r - m
start, end, nbndry, parent_flag, ier)	
call cg_ElementDataSize_f(fn, B, Z, S, ElementDataSize, ier)	r - m
call cg_ElementPartialSize_f(fn, B, Z, S, start, end, <i>ElementDataSize</i> ,	r - m
ier)	
call cg_elements_read_f(fn, B, Z, S, Elements, ParentData, ier)	r - m
call cg_elements_partial_read_f(fn, B, Z, S, start, end, <i>Elements</i> ,	r - m
ParentData, ier)	
<pre>call cg_npe_f(type, npe, ier)</pre>	rwm

Input/Output

fn	CGNS file index number. (Input)
В	Base index number, where $1 \le B \le nbases$. (Input)
Z	Zone index number, where $1 \le Z \le nzones.$ (Input)
ElementSectionName	Name of the Elements_t node. (Input for cg_section_write; $output$ for cg_section_read)
type	Type of element. See the eligible types for ElementType_t in Section 2.6. (Input for cg_section_write, cg_npe; output for cg_section_read)
start	Index of first element in the section. (Input for cg_section_write, cg_section_partial_write, cg_parent_data_partial_write, cg_ElementPartialSize, cg_elements_partial_write; output for cg_section_read)
end	Index of last element in the section. (Input for cg_section_write, cg_section_partial_write, cg_parent_data_partial_write, cg_ElementPartialSize, cg_elements_partial_write; output for cg_section_read)

nbndry Index of last boundary element in the section. Set to zero if the

elements are unsorted. (Input for cg_section_write; output for

cg_section_read)

nsections Lower range index (eg., imin, jmin, kmin). (Output)

S Element section index, where $1 \le S \le nsections$. (Input for

cg_parent_data_write, cg_section_read, cg_ElementDataSize,

cg_elements_read; output for cg_section_write)

parent_flag Flag indicating if the parent data are defined. If the parent data exist,

parent_flag is set to 1; otherwise it is set to 0. (Output)

ElementDataSize Number of element connectivity data values. (Output)

Elements Element connectivity data. (Input for cg_section_write; output for

cg_elements_read)

ParentData For boundary or interface elements, this array contains information on

the cell(s) and cell face(s) sharing the element. If you do not need to read the ParentData when reading the ElementData, you may set the

value to NULL. (Output)

npe Number of nodes for an element of type type. (Output)

ier Error status. (Output)

It is important to note that each element under a given Zone_t – including all cells, faces, edges, boundary elements, etc. – must have a unique element index number. The numbering should be consecutive (i.e., no gaps). This global numbering system insures that each and every element within a zone is uniquely identified by its number.

If the specified Elements_t node doesn't yet exist, it may be created using either cg_section_write or cg_section_partial_write. The function cg_section_write writes the full range as indicated by start and end and supplied by the element connectivity array Elements. The cg_section_partial_write function will create the element section data for the range start to end with the element data intialized to 0. To add elements to the section, use cg_elements_partial_write and parent data (it it exists) using cg_parent_data_partial_write. Both of these functions will replace the data for the range as indicated by start and end with the new values. In most cases, the data is not duplicated in the mid-level library, but written directly from the user data to disk. The exception to this is in the case of MIXED, NGON_n, and NFACE_n element sets. Since the size of the element connectivity array is not known directly, the MLL will keep a copy of the data in memory for the partial writes.

The function cg_elements_read returns all of the element connectivity and parent data. Specified subsets of the element connectivity and parent data may be read using cg_elements_partial_read.

11.3 Axisymmetry

Node: Axisymmetry_t

Functions	Modes
<pre>ier = cg_axisym_write(int fn, int B, float *ReferencePoint,</pre>	- w m
<pre>float *AxisVector);</pre>	
<pre>ier = cg_axisym_read(int fn, int B, float *ReferencePoint,</pre>	r - m
float *AxisVector);	
call cg_axisym_write_f(fn, B, ReferencePoint, AxisVector, ier)	- w m
call cg_axisym_read_f(fn, B, ReferencePoint, AxisVector, ier)	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

fn	CGNS file index number. $(Input)$
В	Base index number, where $1 \leq B \leq nbases$. (Input)
ReferencePoint	Origin used for defining the axis of rotation. (In Fortran, this is an array of Real*4 values.) (Input for cg_axisym_write; output for cg_axisym_read)
AxisVector	Direction cosines of the axis of rotation, through the reference point. (In Fortran, this is an array of Real*4 values.) (Input for cg_axisym_write; output for cg_axisym_read)
ier	Error status. (Output)

This node can only be used for a bi-dimensional model, i.e., PhysicalDimension must equal two.

11.4 Rotating Coordinates

Node: RotatingCoordinates_t

Functions	Modes
<pre>ier = cg_rotating_write(float *RotationRateVector,</pre>	- w m
<pre>float *RotationCenter);</pre>	
<pre>ier = cg_rotating_read(float *RotationRateVector,</pre>	r - m
<pre>float *RotationCenter);</pre>	
call cg_rotating_write_f(RotationRateVector, RotationCenter, ier)	- w m
call cg_rotating_read_f(RotationRateVector, RotationCenter, ier)	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

RotationRateVector Components of the angular velocity of the grid about the center of rotation. (In Fortran, this is an array of Real*4 values.) (Input for cg_rotating_write; output for cg_rotating_read)

RotationCenter Coordinates of the center of rotation. (In Fortran, this is an array of

Real*4 values.) (Input for cg_rotating_write; output for

cg_rotating_read)

ier Error status. (Output)

12 Solution Data

12.1 Flow Solution

Node: FlowSolution_t

Functions	Modes
<pre>ier = cg_sol_write(int fn, int B, int Z, char *solname,</pre>	- w m
<pre>GridLocation_t location, int *S);</pre>	
<pre>ier = cg_nsols(int fn, int B, int Z, int *nsols);</pre>	r - m
<pre>ier = cg_sol_info(int fn, int B, int Z, int S, char *solname,</pre>	r - m
<pre>GridLocation_t *location);</pre>	
<pre>ier = cg_sol_ptset_write(int fn, int B, int Z, char *solname,</pre>	- w m
<pre>GridLocation_t location, PointSetType_t ptset_type,</pre>	
<pre>cgsize_t npnts, cgsize_t *pnts, int *S);</pre>	
<pre>ier = cg_sol_ptset_info(int fn, int B, int Z, int S,</pre>	r - m
PointSetType_t *ptset_type, cgsize_t *npnts);	
<pre>ier = cg_sol_ptset_read(int fn, int B, int Z, int S, cgsize_t *pnts);</pre>	r - m
<pre>ier = cg_sol_size(int fn, int B, int Z, int S, int *data_dim,</pre>	r - m
cgsize_t *dim_vals);	
call cg_sol_write_f(fn, B, Z, solname, location, S, ier)	- w m
call cg_nsols_f(fn, B, Z, nsols, ier)	r - m
call cg_sol_info_f(fn, B, Z, S, solname, location, ier)	r - m
<pre>call cg_sol_ptset_write_f(fn, B, Z, solname, location, ptset_type,</pre>	- w m
$ ext{npnts}, ext{pnts}, ext{S}, ext{ier})$	
call cg_sol_ptset_info_f(fn, B, Z, S, ptset_type, npnts, ier)	r - m
call cg_sol_ptset_read_f(fn, B, Z, S, pnts, ier)	r - m
call cg_sol_size_f(fn, B, Z, S, data_dim, dim_vals, ier)	r - m

Input/Output

```
fn
              CGNS file index number. (Input)
В
               Base index number, where 1 \le B \le nbases. (Input)
               Zone index number, where 1 \le Z \le nzones. (Input)
Z
S
               Flow solution index number, where 1 \le S \le nsols. (Input for cg_sol_info;
               output for cg_sol_write)
nsols
              Number of flow solutions for zone Z. (Output)
solname
              Name of the flow solution. (Input for cg_sol_write; output for cg_sol_info)
location
              Grid location where the solution is recorded. The current admissible locations
               are Vertex, CellCenter, IFaceCenter, JFaceCenter, and KFaceCenter.
               (Input for cg_sol_write and cg_sol_ptset_write; output for cg_sol_info)
```

ptset_type	Type of point set defining the interface in the current solution; either PointRange or PointList. (Input for cg_sol_ptset_write; output for cg_sol_ptset_info)
npnts	Number of points defining the interface in the current solution. For a ptset_type of PointRange, npnts is always two. For a ptset_type of PointList, npnts is the number of points in the list. (Input for cg_sol_ptset_write; output for cg_sol_ptset_info)
pnts	Array of points defining the interface in the current solution. (Input for cg_sol_ptset_write; output for cg_sol_ptset_read)
data_dim	Number of dimensions defining the solution data. If a point set has been defined, this will be 1, otherwise this will be the current zone index dimension. (<i>Output</i>)
dim_vals	The array of $\mathtt{data_dim}$ dimensions for the solution data. (Output)
ier	Error status. ($Output$)

The above functions are used to create, and get information about, FlowSolution_t nodes.

Solution data may be specified over the entire zone, as in previous versions of the library, using cg_sol_write or over a patch region of the zone using cg_sol_ptset_write. The two are mutually exclusive. In the first case, the size of the solution data is determined by the size of the zone, the grid location, and rind data (if any) as in previous versions. In the second case the solution data size is entirely determined by the PointList/PointRange patch. In order to determine which of the two forms in which the solution data was written, use cg_sol_ptset_info. If the solution is over the entire zone, ptset_type will be returned as CG_Null and npnts as 0. Otherwise, ptset_type will be either PointList or PointRange, and the number of points will be returned in npnts.

To assist in determining the size of the solution data, the function cg_sol_size has been added. For a solution defined over the full zone, data_dim returns the index dimension for the zone, and dim_vals specifies the dimensions of the data, corrected for the grid location type and rind data. If a point set patch has been specified, data_dim will be 1 and dim_vals will contain the total size of the patch.

Acceptable values of GridLocation_t are Vertex and CellCenter. If the base cell dimension is 2 or greater (surface or volume), then EdgeCenter is also allowed. For 3 dimensional bases, FaceCenter, and for structured zones, IFaceCenter, JFaceCenter and KFaceCenter, are also acceptable.

12.2 Flow Solution Data

Functions	Modes
<pre>ier = cg_field_write(int fn, int B, int Z, int S, DataType_t datatype,</pre>	- w m
<pre>char *fieldname, void *solution_array, int *F);</pre>	
<pre>ier = cg_field_partial_write(int fn, int B, int Z, int S,</pre>	- w m
DataType_t datatype, char *fieldname, cgsize_t *range_min,	
<pre>cgsize_t *range_max, void *solution_array, int *F);</pre>	
<pre>ier = cg_nfields(int fn, int B, int Z, int S, int *nfields);</pre>	r - m
<pre>ier = cg_field_info(int fn, int B, int Z, int S, int F,</pre>	r - m
DataType_t *datatype, char *fieldname);	
<pre>ier = cg_field_read(int fn, int B, int Z, int S, char *fieldname,</pre>	r - m
DataType_t datatype, cgsize_t *range_min, cgsize_t *range_max,	
<pre>void *solution_array);</pre>	
<pre>call cg_field_write_f(fn, B, Z, S, datatype, fieldname, solution_array,</pre>	- w m
F, ier)	
<pre>call cg_field_partial_write_f(fn, B, Z, S, datatype, fieldname,</pre>	
range_min, range_max, solution_array, F, ier)	
call cg_nfields_f(fn, B, Z, S, nfields, ier)	r - m
call cg_field_info_f(fn, B, Z, S, F, datatype, fieldname, ier)	r - m
<pre>call cg_field_read_f(fn, B, Z, S, fieldname, datatype, range_min,</pre>	r - m
range_max, solution_array, ier)	

Input/Output

fn	CGNS file index number. (Input)
В	Base index number, where $1 \le B \le nbases$. (Input)
Z	Zone index number, where $1 \le Z \le nzones$. (Input)
S	Flow solution index number, where $1 \le S \le nsols$. (Input)
F	Solution array index number, where $1 \le F \le nfields$. (Input for cg_field_info; output for cg_field_write)
nfields	Number of data arrays in flow solution S. ($Output$)
datatype	Data type in which the solution array is written. Admissible data types for a solution array are Integer, LongInteger, RealSingle, and RealDouble. (Input for cg_field_write, cg_field_read; output for cg_field_info)
fieldname	Name of the solution array. It is strongly advised to use the SIDS nomenclature conventions when naming the solution arrays to insure file compatibility. (Input for cg_field_write, cg_field_read; output for cg_field_info)

```
range_min Lower range index (eg., imin, jmin, kmin). (Input)
range_max Upper range index (eg., imax, jmax, kmax). (Input)
solution_array Array of solution values for the range prescribed. (Input for cg_field_write; output for cg_field_read)
ier Error status. (Output)
```

The above functions are used to read and write solution arrays stored below a FlowSolution_t node.

When writing, the function cg_field_write will automatically write the full range of the solution (i.e., the entire solution_array). The function cg_field_partial_write may be used to write only a subset of solution_array. When using the partial write, any existing data from range_min to range_max will be overwritten by the new values. All other values will not be affected.

The function cg_field_read returns the solution array fieldname, for the range prescribed by range_min and range_max. The array is returned to the application in the data type requested in datatype. This data type does not need to be the same as the one in which the data is stored in the file. A solution array stored as double precision in the CGNS file can be returned to the application as single precision, or vice versa.

In Fortran, when using $cg_field_read_f$ to read a 2D or 3D solution, the extent of each dimension of solution_array must be consistent with the requested range. When reading a 1D solution, the declared size can be larger than the requested range. For example, for a 2D zone with 100×50 vertices, if range_min and range_max are set to (11,11) and (20,20) to read a subset of the solution, then solution_array must be dimensioned (10,10). If solution_array is declared larger (e.g., (100,50)) the indices for the returned array values will be wrong.

12.3 Discrete Data

 $Node: {\tt DiscreteData_t}$

Functions	Modes
<pre>ier = cg_discrete_write(int fn, int B, int Z, char *DiscreteName,</pre>	- w m
<pre>int *D);</pre>	
<pre>ier = cg_ndiscrete(int fn, int B, int Z, int *ndiscrete);</pre>	r - m
<pre>ier = cg_discrete_read(int fn, int B, int Z, int D,</pre>	r - m
<pre>char *DiscreteName);</pre>	
<pre>ier = cg_discrete_ptset_write(int fn, int B, int Z, char *DiscreteName,</pre>	- w m
<pre>GridLocation_t location, PointSetType_t ptset_type,</pre>	
<pre>cgsize_t npnts, cgsize_t *pnts, int *D);</pre>	
<pre>ier = cg_discrete_ptset_info(int fn, int B, int Z, int D,</pre>	r - m
PointSetType_t *ptset_type, cgsize_t *npnts);	
<pre>ier = cg_discrete_ptset_read(int fn, int B, int Z, int D,</pre>	r - m
cgsize_t *pnts);	
<pre>ier = cg_discrete_size(int fn, int B, int Z, int D, int *data_dim,</pre>	r - m
cgsize_t *dim_vals);	
call cg_discrete_write_f(fn, B, Z, DiscreteName, D, ier)	- w m
<pre>call cg_ndiscrete_f(fn, B, Z, ndiscrete, ier)</pre>	r - m
<pre>call cg_discrete_read_f(fn, B, Z, D, DiscreteName, ier)</pre>	r - m
<pre>call cg_discrete_ptset_write_f(fn, B, Z, DiscreteName, location,</pre>	- w m
<pre>ptset_type, npnts, pnts, D, ier)</pre>	
<pre>call cg_discrete_ptset_info_f(fn, B, Z, D, ptset_type, npnts, ier)</pre>	r - m
<pre>call cg_discrete_ptset_read_f(fn, B, Z, D, pnts, ier)</pre>	r - m
call cg_discrete_size_f(fn, B, Z, D, data_dim, dim_vals, ier)	r - m

$\underline{Input}/Output$

fn	CGNS file index number. (Input)
В	Base index number, where $1 \le B \le nbases$. (Input)
Z	Zone index number, where $1 \le Z \le nzones$. (Input)
D	Discrete data index number, where $1 \le \mathtt{D} \le \mathtt{ndiscrete}$. (Input for cg_discrete_read; output for cg_discrete_write)
ndiscrete	Number of DiscreteData_t data structures under zone Z. ($Output$)
DiscreteName	Name of DiscreteData_t data structure. (Input for cg_discrete_write; $output$ for cg_discrete_read)
location	Grid location where the discrete data is recorded. The current admissible locations are Vertex, CellCenter, IFaceCenter, JFaceCenter, and

	$\label{eq:KFaceCenter} \mbox{KFaceCenter. (Input for cg_discrete_ptset_write; } \mbox{$output$ for cg_sol_info)} $
ptset_type	Type of point set defining the interface for the discrete data; either PointRange or PointList. (Input for cg_sol_ptset_write; output for cg_sol_ptset_info)
npnts	Number of points defining the interface for the discrete data. For a ptset_type of PointRange, npnts is always two. For a ptset_type of PointList, npnts is the number of points in the list. (Input for cg_sol_ptset_write; output for cg_sol_ptset_info)
pnts	Array of points defining the interface for the discrete data. (Input for cg_sol_ptset_write; output for cg_sol_ptset_read)
data_dim	Number of dimensions defining the discrete data. If a point set has been defined, this will be 1, otherwise this will be the current zone index dimension. $(Output)$
dim_vals	The array of $\mathtt{data_dim}$ dimensions for the discrete data. (\underbrace{Output})
ier	Error status. ($Output$)

DiscreteData_t nodes are intended for the storage of fields of data not usually identified as part of the flow solution, such as fluxes or equation residuals.

The description for these functions is similar to the FlowSolution_t node (Section 12.1). To read and write the discrete data, use cg_goto (Section 4) to access the DiscreteData_t node, then cg_array_read and cg_array_write (Section 8.1).

12.4 Zone Subregions

 $Node: {\tt ZoneSubRegion_t}$

Functions	Modes
<pre>ier = cg_nsubregs(int fn, int B, int Z, int *nsubregs);</pre>	r - m
<pre>ier = cg_subreg_info(int fn, int B, int Z, int S, char *regname,</pre>	r - m
<pre>int *dimension, GridLocation_t *location,</pre>	
PointSetType_t *ptset_type, cgsize_t *npnts,	
<pre>int *bcname_len, int *bcname_len);</pre>	
<pre>ier = cg_subreg_ptset_read(int fn, int B, int Z, int S,</pre>	r - m
cgsize_t *pnts);	
<pre>ier = cg_subreg_bcname_read(int fn, int B, int Z, int S,</pre>	r - m
<pre>char *bcname);</pre>	
<pre>ier = cg_subreg_gcname_read(int fn, int B, int Z, int S,</pre>	r - m
char *gcname);	
<pre>ier = cg_subreg_ptset_write(int fn, int B, int Z, const char *regname,</pre>	- w m
int dimension, GridLocation_t location,	
PointSetType_t ptset_type, cgsize_t npnts,	
<pre>cgsize_t *pnts, int *S);</pre>	
<pre>ier = cg_subreg_bcname_write(int fn, int B, int Z, const char *regname,</pre>	- w m
<pre>int dimension, const char *bcname, int *S);</pre>	
<pre>ier = cg_subreg_gcname_write(int fn, int B, int Z, const char *regname,</pre>	- w m
<pre>int dimension, const char *gcname, int *S);</pre>	
call cg_nsubregs_f(fn, B, Z, nsubregs, ier)	r - m
call cg_subreg_info_f(fn, B, Z, S, regname, dimension, location,	r - m
<pre>ptset_type, npnts, bcname_len, bcname_len, ier)</pre>	
call cg_subreg_ptset_read_f(fn, B, Z, S, pnts, ier)	r - m
call cg_subreg_bcname_read_f(fn, B, Z, S, bcname, ier)	r - m
call cg_subreg_gcname_read_f(fn, B, Z, S, gcname, ier)	r - m
<pre>call cg_subreg_ptset_write_f(fn, B, Z, regname, dimension, location,</pre>	- w m
<pre>ptset_type, npnts, pnts, S, ier)</pre>	
<pre>call cg_subreg_bcname_write_f(fn, B, Z, regname, dimension, bcname,</pre>	- w m
S, ier)	
<pre>call cg_subreg_gcname_write_f(fn, B, Z, regname, dimension, gcname,</pre>	- w m
S, ier)	

Input/Output

```
fn CGNS file index number. (Input)  Base index number, where <math>1 \leq B \leq nbases. (Input)   Zone index number, where <math>1 \leq Z \leq nzones. (Input)
```

ZoneSubRegion index number, where $1 \le S \le nsubregs$. (Input for cg_subreg_info, cg_subreg_ptset_read, cg_subreg_bcname_read and cg_subreg_gcname_read; output for cg_subreg_ptset_write, cg_subreg_bcname_write and cg_subreg_gcname_write)
Number of ZoneSubRegion_t nodes under Zone Z. $(Output)$
Name of the ZoneSubRegion_t node. (Input for cg_subreg_ptset_write, cg_subreg_bcname_write, and cg_subreg_gcname_write; output for cg_subreg_info)
Dimensionality of the subregion. 1 for lines, 2 for faces, 3 for volumes. (Input for cg_subreg_ptset_write, cg_subreg_bcname_write, and cg_subreg_gcname_write; output for cg_subreg_info)
Grid location used in the definition of the point set. The current admissible locations are Vertex and CellCenter. (Input for cg_subreg_ptset_write; output for cg_subreg_info)
Type of point set defining the interface for the subregion data; either PointRange or PointList. (Input for cg_subreg_ptset_write; output for cg_subreg_info)
Number of points defining the interface for the subregion data. For a ptset_type of PointRange, npnts is always two. For a ptset_type of PointList, npnts is the number of points in the list. (Input for cg_subreg_ptset_write; output for cg_subreg_info)
Array of points defining the interface for the subregion data. (Input for cg_subreg_ptset_write; output for cg_subreg_ptset_read)
The name of a BC_t node which defines the subregion. (Input for cg_subreg_bcname_write; output for cg_subreg_bcname_read)
The name of a GridConnectivity_t or GridConnectivity1to1_t node which defines the subregion. (Input for cg_subreg_gcname_write; output for cg_subreg_gcname_read)
String length of bcname. (Output)
String length of gcname. (Output)
Error status. (Output)

These functions allow for the specification of Zone subregions. The subregion may be specified as either the name of an existing BC_t node (cg_subreg_bcname_write), an existing GridConnectivity_t or GridConnectivity_tol_t node (cg_subreg_gcname_write), or as a PointSet/PointRange (cg_subreg_ptset_write). These specifications are mutually exclusive. To determine the type of the subregion, use cg_subreg_info. If the subregion is a point set, then ptset_type will indicate the point set type (either PointList or PointRange) and npts will be set to the number of points to define the region. Otherwise, ptset_type will be set to CG_Null and npnts will be 0. In this case, one of bcname_len or gcname_len will be non-zero, indicating whether the subregion references a BC_t node (bcname_len non-zero) or GridConnectivity_t node (gcname_len non-zero).

13 Grid Connectivity

13.1 One-to-One Connectivity

 $Node : {\tt GridConnectivity1to1_t}$

Functions	Modes
<pre>ier = cg_n1to1_global(int fn, int B, int *n1to1_global);</pre>	r - m
<pre>ier = cg_1to1_read_global(int fn, int B, char **connectname,</pre>	r - m
char **zonename, char **donorname, cgsize_t **range,	
<pre>cgsize_t **donor_range, int **transform);</pre>	
call cg_n1to1_global_f(fn, B, n1to1_global, ier)	
call cg_1to1_read_global_f(fn, B, connectname, zonename, donorname,	
range, donor_range, transform, ier)	

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

fn	CGNS file index number. (Input)
В	Base index number, where $1 \le B \le nbases$. (Input)
n1to1_global	Total number of one-to-one interfaces in base B, stored under <code>GridConnectivity1to1_t</code> nodes. (I.e., this does not include one-to-one interfaces that may be stored under <code>GridConnectivity_t</code> nodes, used for generalized zone interfaces.) Note that the function <code>cg_n1to1</code> (described below) may be used to get the number of one-to-one interfaces in a specific zone. (<code>Output</code>)
connectname	Name of the interface. (Output)
zonename	Name of the first zone, for all one-to-one interfaces in base B. $(Output)$
donorname	Name of the second zone, for all one-to-one interfaces in base B. $(Output)$
range	Range of points for the first zone, for all one-to-one interfaces in base B. $(Output)$
donor_range	Range of points for the current zone, for all one-to-one interfaces in base B. $(Output)$
transform	Short hand notation for the transformation matrix defining the relative orientation of the two zones. This transformation is given for all one-to-one interfaces in base B. See the description of <code>GridConnectivity1to1_t</code> in the <code>SIDS</code> manual for details. (<code>Output</code>)
ier	Error status. (Output)

The above functions may be used to get information about all the one-to-one zone interfaces in a CGNS database.

Functions	Modes
<pre>ier = cg_1to1_write(int fn, int B, int Z, char *connectname,</pre>	- w m
<pre>char *donorname, cgsize_t *range, cgsize_t *donor_range,</pre>	
<pre>int *transform, int *I);</pre>	
<pre>ier = cg_n1to1(int fn, int B, int Z, int *n1to1);</pre>	r - m
<pre>ier = cg_1to1_read(int fn, int B, int Z, int I, char *connectname,</pre>	r - m
char *donorname, cgsize_t *range, cgsize_t *donor_range,	
<pre>int *transform);</pre>	
call cg_1to1_write_f(fn, B, Z, connectname, donorname, range,	
donor_range, transform, <i>I</i> , <i>ier</i>)	
call cg_n1to1_f(fn, B, Z, n1to1, ier)	
call cg_1to1_read_f(fn, B, Z, I, connectname, donorname, range,	
donor_range, transform, ier)	

Input/Output

(Note that for Fortran calls, all integer arguments are integer *4 in 32-bit mode and integer *8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

fn	CGNS file index number. (Input)
В	Base index number, where $1 \le B \le nbases$. (Input)
Z	Zone index number, where $1 \le Z \le nzones$. (Input)
I	Interface index number, where $1 \le I \le n1to1$. (Input for cg_1to1_read; output for cg_1to1_write)
n1to1	Number of one-to-one interfaces in zone Z, stored under GridConnectivity1to1_t nodes. (I.e., this does not include one-to-one interfaces that may be stored under GridConnectivity_t nodes, used for generalized zone interfaces.) (Output)
connectname	Name of the interface. (Input for cg_1to1_write; output for cg_1to1_read)
donorname	Name of the zone interfacing with the current zone. (Input for cg_1to1_write; output for cg_1to1_read)
range	Range of points for the current zone. (Input for cg_1to1_write; $output$ for cg_1to1_read)
donor_range	Range of points for the donor zone. (Input for cg_1to1_write; $output$ for cg_1to1_read)
transform	Short hand notation for the transformation matrix defining the relative orientation of the two zones. See the description of GridConnectivity1to1_t in the SIDS manual for details. (Input for cg_1to1_write; output for cg_1to1_read)
ier	Error status. (Output)

The above functions are used to read and write one-to-one connectivity data for a specific zone.

13.2 Generalized Connectivity

 $Node \colon {\tt GridConnectivity_t}$

Functions	Modes
<pre>ier = cg_conn_write(int fn, int B, int Z, char *connectname,</pre>	- w m
<pre>GridLocation_t location, GridConnectivityType_t connect_type,</pre>	
PointSetType_t ptset_type, cgsize_t npnts, cgsize_t *pnts,	
char *donorname, ZoneType_t donor_zonetype,	
PointSetType_t donor_ptset_type, DataType_t donor_datatype,	
<pre>cgsize_t ndata_donor, cgsize_t *donor_data, int *I);</pre>	
<pre>ier = cg_conn_write_short(int fn, int B, int Z, char *connectname,</pre>	- w m
<pre>GridLocation_t location, GridConnectivityType_t connect_type,</pre>	
PointSetType_t ptset_type, cgsize_t npnts, cgsize_t *pnts,	
<pre>char *donorname, int *I);</pre>	
<pre>ier = cg_nconns(int fn, int B, int Z, int *nconns);</pre>	r - m
<pre>ier = cg_conn_info(int fn, int B, int Z, int I, char *connectname,</pre>	r - m
${\it GridLocation_t\ *location}$, ${\it GridConnectivityType_t\ *connect_type}$,	
PointSetType_t *ptset_type, cgsize_t *npnts, char *donorname,	
${\it ZoneType_t\ *donor_zonetype}$, ${\it PointSetType_t\ *donor_ptset_type}$,	
DataType_t *donor_datatype, cgsize_t *ndata_donor);	
<pre>ier = cg_conn_read(int fn, int B, int Z, int I, cgsize_t *pnts,</pre>	r - m
DataType_t donor_datatype, cgsize_t *donor_data);	
<pre>ier = cg_conn_read_short(int fn, int B, int Z, int I, cgsize_t *pnts);</pre>	r - m
<pre>call cg_conn_write_f(fn, B, Z, connectname, location, connect_type,</pre>	- w m
<pre>ptset_type, npnts, pnts, donorname, donor_zonetype,</pre>	
$ ext{donor_ptset_type, donor_datatype, ndata_donor, donor_data, I,}$	
ier)	
<pre>call cg_conn_write_short_f(fn, B, Z, connectname, location,</pre>	- w m
<pre>connect_type, ptset_type, npnts, pnts, donorname, I, ier)</pre>	
call cg_nconns_f(fn, B, Z, nconns, ier)	r - m
call cg_conn_info_f(fn, B, Z, I, connectname, location, connect_type,	r - m
$ptset_type$, $npnts$, $donorname$, $donor_zonetype$, $donor_ptset_type$,	
donor_datatype, ndata_donor, ier)	
call cg_conn_read_f(fn, B, Z, I, pnts, donor_datatype, donor_data,	r - m
ier)	
<pre>call cg_conn_read_short_f(fn, B, Z, I, pnts, ier)</pre>	

Input/Output

```
fn CGNS file index number. (Input)  Base index number, where 1 \leq B \leq nbases. (Input)
```

Z Zone index number, where $1 \le Z \le nzones$. (Input) Ι Discrete data index number, where $1 \le I \le nconns$. (Input for cg_conn_info, cg_conn_read; output for cg_conn_write, cg_conn_write_short) Number of interfaces for zone Z. (Output) nconns Name of the interface. (Input for cg_conn_write, connectname cg_conn_write_short; output for cg_conn_info) location Grid location used in the definition of the point set. The currently admissible locations are Vertex and CellCenter. (Input for cg_conn_write, cg_conn_write_short; output for cg_conn_info) Type of interface being defined. The admissible types are Overset, connect_type Abutting, and Abutting1to1. (Input for cg_conn_write, cg_conn_write_short; output for cg_conn_info) Type of point set defining the interface in the current zone; either ptset_type PointRange or PointList. (Input for cg_conn_write, cg_conn_write_short; output for cg_conn_info) Type of point set defining the interface in the donor zone; either donor_ptset_type PointListDonor or CellListDonor. (Input for cg_conn_write; output for cg_conn_info) npnts Number of points defining the interface in the current zone. For a ptset_type of PointRange, npnts is always two. For a ptset_type of PointList, npnts is the number of points in the PointList. (Input for cg_conn_write, cg_conn_write_short; output for cg_conn_info) Number of points or cells in the current zone. These are paired with ndata_donor points, cells, or fractions thereof in the donor zone. (Input for cg_conn_write; output for cg_conn_info) donorname Name of the zone interfacing with the current zone. (Input for cg_conn_write; output for cg_conn_info) donor_datatype Data type in which the donor points are stored in the file. As of Version 3.0, this value is ignored when writing, and on reading it will return either Integer or LongInteger depending on whether the file was written using 32 or 64-bit. The donor_datatype argument was left in these functions only for backward compatibility. The donot data is always read as cgsize_t. (Input for cg_conn_write, cg_conn_read; output for cg_conn_info) Array of points defining the interface in the current zone. (Input for pnts cg_conn_write, cg_conn_write_short; output for cg_conn_read) Array of donor points or cells corresponding to ndata_donor. Note that donor_data it is possible that the same donor point or cell may be used multiple times. (Input for cg_conn_write; output for cg_conn_read) Type of the donor zone. The admissible types are Structured and donor_zonetype Unstructured. (Input for cg_conn_write; output for cg_conn_info)

ier Error status. (Output)

Note that the interpolation factors stored in the InterpolantsDonor data array are accessed using the cg_goto and cg_array_xxx functions, described in Section 4 and Section 8.1, respectively.

13.3 Special Grid Connectivity Properties

 $Node {:} \ {\tt GridConnectivityProperty_t}$

Functions	Modes
<pre>ier = cg_conn_periodic_write(int fn, int B, int Z, int I,</pre>	- w m
<pre>float *RotationCenter, float *RotationAngle, float *Translation);</pre>	
<pre>ier = cg_conn_average_write(int fn, int B, int Z, int I,</pre>	- w m
<pre>AverageInterfaceType_t AverageInterfaceType);</pre>	
<pre>ier = cg_1to1_periodic_write(int fn, int B, int Z, int I,</pre>	- w m
<pre>float *RotationCenter, float *RotationAngle, float *Translation);</pre>	
<pre>ier = cg_1to1_average_write(int fn, int B, int Z, int I,</pre>	- w m
<pre>AverageInterfaceType_t AverageInterfaceType);</pre>	
<pre>ier = cg_conn_periodic_read(int fn, int B, int Z, int I,</pre>	r - m
<pre>float *RotationCenter, float *RotationAngle,</pre>	
<pre>float *Translation);</pre>	
<pre>ier = cg_conn_average_read(int fn, int B, int Z, int I,</pre>	r - m
<pre>AverageInterfaceType_t *AverageInterfaceType);</pre>	
<pre>ier = cg_1to1_periodic_read(int fn, int B, int Z, int I,</pre>	r - m
<pre>float *RotationCenter, float *RotationAngle,</pre>	
<pre>float *Translation);</pre>	
<pre>ier = cg_1to1_average_read(int fn, int B, int Z, int I,</pre>	r - m
<pre>AverageInterfaceType_t *AverageInterfaceType);</pre>	
<pre>call cg_conn_periodic_write_f(fn, B, Z, I, RotationCenter,</pre>	- w m
RotationAngle, Translation, ier)	
<pre>call cg_conn_average_write_f(fn, B, Z, I, AverageInterfaceType, ier)</pre>	- w m
<pre>call cg_1to1_periodic_write_f(fn, B, Z, I, RotationCenter,</pre>	- w m
RotationAngle, Translation, ier)	
<pre>call cg_1to1_average_write_f(fn, B, Z, I, AverageInterfaceType, ier)</pre>	- w m
<pre>call cg_conn_periodic_read_f(fn, B, Z, I, RotationCenter,</pre>	r - m
RotationAngle, Translation, ier)	
<pre>call cg_conn_average_read_f(fn, B, Z, I, AverageInterfaceType, ier)</pre>	r - m
<pre>call cg_1to1_periodic_read_f(fn, B, Z, I, RotationCenter,</pre>	r - m
RotationAngle, Translation, ier)	
<pre>call cg_1to1_average_read_f(fn, B, Z, I, AverageInterfaceType, ier)</pre>	r - m

Input/Output

```
fn CGNS file index number. (Input)  Base index number, where 1 \leq B \leq nbases. (Input)   Zone index number, where 1 \leq Z \leq nzones. (Input)
```

I Grid connectivity index number, where $1 \le I \le nconns$ for the

"cg_conn" functions, and $1 \le I \le n1to1$ for the "cg_1to1"

functions. (Input)

RotationCenter An array of size phys_dim defining the coordinates of the origin for

defining the rotation angle between the periodic interfaces.

(phys_dim is the number of coordinates required to define a vector in the field.) (In Fortran, this is an array of Real*4 values.) (Input for cg_conn_periodic_write, cg_1to1_periodic_write; output

for cg_conn_periodic_read, cg_1to1_periodic_read)

RotationAngle An array of size phys_dim defining the rotation angle from the

current interface to the connecting interface. If rotating about more than one axis, the rotation is performed first about the x-axis, then the y-axis, then the z-axis. (In Fortran, this is an array of Real*4

values.) (Input for cg_conn_periodic_write,

cg_1to1_periodic_write; output for cg_conn_periodic_read,

cg_1to1_periodic_read)

Translation An array of size phys_dim defining the translation from the current

interface to the connecting interface. (In Fortran, this is an array of

Real*4 values.) (Input for cg_conn_periodic_write,

cg_1to1_periodic_write; output for cg_conn_periodic_read,

cg_1to1_periodic_read)

AverageInterfaceType The type of averaging to be done. Valid types are CG_Null,

CG_UserDefined, AverageAll, AverageCircumferential, AverageRadial, AverageI, AverageJ, and AverageK. (Input for cg_conn_average_write, cg_1to1_average_write; output for

cg_conn_average_read, cg_1to1_average_read)

ier Error status. (Output)

These functions may be used to store special grid connectivity properties. The "cg_conn" functions apply to generalized grid connectivity nodes (i.e., GridConnectivity_t), and the "cg_1to1" functions apply to 1-to-1 grid connectivity nodes (i.e., GridConnectivity1to1_t).

The "write" functions will create the GridConnectivityProperty_t node if it doesn't already exist, then add the appropriate connectivity property. Multiple connectivity properties may be recorded under the same GridConnectivityProperty_t node.

The "read" functions will return with $ier = 2 = CG_NODE_NOT_FOUND$ if the requested connectivity property, or the GridConnectivityProperty_t node itself, doesn't exist.

13.4 Overset Holes

 $Node : {\tt OversetHoles_t}$

Functions	Modes
<pre>ier = cg_hole_write(int fn, int B, int Z, char *holename,</pre>	- w m
<pre>GridLocation_t location, PointSetType_t ptset_type, int nptsets,</pre>	
cgsize_t npnts, cgsize_t *pnts, int *I);	
<pre>ier = cg_nholes(int fn, int B, int Z, int *nholes);</pre>	r - m
<pre>ier = cg_hole_info(int fn, int B, int Z, int I, char *holename,</pre>	r - m
<pre>GridLocation_t *location, PointSetType_t *ptset_type,</pre>	
<pre>int *nptsets, cgsize_t *npnts);</pre>	
<pre>ier = cg_hole_read(int fn, int B, int Z, int I, cgsize_t *pnts);</pre>	r - m
<pre>call cg_hole_write_f(fn, B, Z, holename, location, ptset_type,</pre>	- w m
nptsets, npnts, pnts, I, ier)	
call cg_nholes_f(fn, B, Z, nholes, ier)	
call cg_hole_info_f(fn, B, Z, I, holename, location, ptset_type,	r - m
nptsets, npnts, ier)	
<pre>call cg_hole_read_f(fn, B, Z, I, pnts, ier)</pre>	r - m

Input/Output

fn	CGNS file index number. (Input)
В	Base index number, where $1 \le B \le nbases$. (Input)
Z	Zone index number, where $1 \le Z \le nzones$. (Input)
I	Overset hole index number, where $1 \le I \le nholes$. (Input for cg_hole_info, cg_hole_read; output for cg_hole_write)
nholes	Number of overset holes in zone Z. (Output)
holename	Name of the overset hole. (Input for cg_hole_write; output for cg_hole_info)
location	Grid location used in the definition of the point set. The currently admissible locations are Vertex and CellCenter. (Input for cg_hole_write; output for cg_hole_info)
ptset_type	The extent of the overset hole may be defined using a range of points or cells, or using a discrete list of all points or cells in the overset hole. If a range of points or cells is used, ptset_type is set to PointRange. When a discrete list of points or cells is used, ptset_type equals PointList. (Input for cg_hole_write; output for cg_hole_info)
nptsets	Number of point sets used to define the hole. If ptset_type is PointRange, several point sets may be used. If ptset_type is PointList, only one point set is allowed. (Input for cg_hole_write; output for cg_hole_info)

Number of points (or cells) in the point set. For a ptset_type of PointRange,
npnts is always two. For a ptset_type of PointList, npnts is the number of
points or cells in the PointList. (Input for cg_hole_write; output for
cg_hole_info)

pnts
Array of points or cells in the point set. (Input for cg_hole_write; output for
cg_hole_read)

Error status. (Output)

ier

14 Boundary Conditions

14.1 Boundary Condition Type and Location

 $Node: BC_t$

Functions	Modes
<pre>ier = cg_boco_write(int fn, int B, int Z, char *boconame,</pre>	- w m
BCType_t bocotype, PointSetType_t ptset_type, cgsize_t npnts,	
cgsize_t *pnts, int *BC);	
<pre>ier = cg_boco_normal_write(int fn, int B, int Z, int BC,</pre>	- w m
<pre>int *NormalIndex, int NormalListFlag,</pre>	
<pre>DataType_t NormalDataType, void *NormalList);</pre>	
<pre>ier = cg_boco_gridlocation_write(int fn, int B, int Z, int BC,</pre>	- w m
<pre>GridLocation_t location);</pre>	
<pre>ier = cg_nbocos(int fn, int B, int Z, int *nbocos);</pre>	r - m
<pre>ier = cg_boco_info(int fn, int B, int Z, int BC, char *boconame,</pre>	r - m
$BCType_t *bocotype, PointSetType_t *ptset_type, cgsize_t *npnts,$	
$int *NormalIndex$, $cgsize_t *NormalListSize$,	
<pre>DataType_t *NormalDataType, int *ndataset);</pre>	
<pre>ier = cg_boco_read(int fn, int B, int Z, int BC, cgsize_t *pnts,</pre>	r - m
<pre>void *NormalList);</pre>	
<pre>ier = cg_boco_gridlocation_read(int fn, int B, int Z, int BC,</pre>	r - m
<pre>GridLocation_t *location);</pre>	
<pre>call cg_boco_write_f(fn, B, Z, boconame, bocotype, ptset_type, npnts,</pre>	- w m
pnts, BC, ier)	
call cg_boco_normal_write_f(fn, B, Z, BC, NormalIndex, NormalListFlag,	- w m
NormalDataType, NormalList, <i>ier</i>)	
call cg_boco_gridlocation_write_f(fn, B, Z, BC, location, ier);	- w m
call cg_nbocos_f(fn, B, Z, nbocos, ier)	r - m
call cg_boco_info_f(fn, B, Z, BC, boconame, bocotype, ptset_type,	r - m
<pre>npnts, NormalIndex, NormalListSize, NormalDataType, ndataset,</pre>	
ier)	
call cg_boco_read_f(fn, B, Z, BC, pnts, NormalList, ier)	r - m
<pre>call cg_boco_gridlocation_read_f(fn, B, Z, BC, location, ier);</pre>	r - m

Input/Output

BC Boundary condition index number, where $1 \leq BC \leq nbocos$. (Input for cg_boco_normal_write, cg_boco_info, cg_boco_read; output for cg_boco_write) Number of boundary conditions in zone Z. (Output) nbocos Name of the boundary condition. (Input for cg_boco_write; output for boconame cg_boco_info) Type of boundary condition defined. See the eligible types for BCType_t in bocotype Section 2.6. Note that if bocotype is FamilySpecified the boundary condition type is being specified for the family to which the boundary belongs. The boundary condition type for the family may be read and written using cg_fambc_read and cg_fambc_write, as described in Section 16.3. (Input for cg_boco_write; output for cg_boco_info) The extent of the boundary condition may be defined using a range of ptset_type points or elements using PointRange, or using a discrete list of all points or elements at which the boundary condition is applied using PointList. When the boundary condition is to be applied anywhere other than points, then GridLocation_t under the BC_t node must be used to indicate this. The value of GridLocation_t may be read or written by cg_boco_gridlocation_read and cg_boco_gridlocation_write. As in previous versions of the library, this may also be done by first using cg_goto (Section 4) to access the BC_t node, then using cg_gridlocation_read or cg_gridlocation_write (Section 9.1). (Input for cg_boco_write; output for cg_boco_info) Number of points or elements defining the boundary condition region. For npnts a ptset_type of PointRange, npnts is always two. For a ptset_type of PointList, npnts is the number of points or elements in the list. (Input for cg_boco_write; output for cg_boco_info) Array of point or element indices defining the boundary condition region. pnts There should be npnts values, each of dimension IndexDimension (i.e., 1 for unstructured grids, and 2 or 3 for structured grids with 2-D or 3-D elements, respectively). (Input for cg_boco_write; output for cg_boco_read) NormalIndex Index vector indicating the computational coordinate direction of the boundary condition patch normal. (Input for cg_boco_normal_write; output for cg_boco_info) Flag indicating if the normals are defined in NormalList and are to be NormalListFlag written out; 1 if they are defined, 0 if they're not. (Input) NormalListSize If the normals are defined in NormalList, NormalListSize is the number of points in the patch times phys_dim, the number of coordinates required to define a vector in the field. If the normals are not defined in NormalList, NormalListSize is 0. (Output) Data type used in the definition of the normals. Admissible data types for NormalDataType the normals are RealSingle and RealDouble. (Input for cg_boco_normal_write; output for cg_boco_info)

NormalList	List of vectors normal to the boundary condition patch pointing into the interior of the zone. (Input for cg_boco_normal_write; output for cg_boco_read)
ndataset	Number of boundary condition datasets for the current boundary condition. ($\underline{Output})$
location	Grid location used in the definition of the point set. The currently admissible locations are Vertex (the default if not given). For 2-D grids, EdgeCenter is also allowed, and for 3-D grids, the additional values of FaceCenter, IFaceCenter, JFaceCenter, and KFaceCenter may be used. (Input for cg_boco_gridlocation_write; output for cg_boco_gridlocation_read)
ier	Error status. (Output)

Notes: (see CPEX 0031)

- The use of ElementList and ElementRange for ptset_type is deprecated and should not be used in new code. These are still currently accepted, but will be internally replaced with the appropriate values of PointList/PointRange and GridLocation_t.
- CellCenter for GridLocation_t is also deprecated. If used, the value will be replaced by EdgeCenter for 2-D grids or FaceCenter for 3-D grids.

14.2 Boundary Condition Datasets

Node: BCDataSet_t

Functions	Modes
<pre>ier = cg_dataset_write(int fn, int B, int Z, int BC, char *DatasetName,</pre>	- w m
<pre>BCType_t BCType, int *Dset);</pre>	
<pre>ier = cg_dataset_read(int fn, int B, int Z, int BC, int Dset,</pre>	r - m
<pre>char *DatasetName, BCType_t *BCType, int *DirichletFlag,</pre>	
<pre>int *NeumannFlag);</pre>	
call cg_dataset_write_f(fn, B, Z, BC, DatasetName, BCType, Dset, ier)	- w m
call cg_dataset_read_f(fn, B, Z, BC, Dset, DatasetName, BCType,	r - m
DirichletFlag, NeumannFlag, ier)	

Input/Output

```
fn CGNS file index number. (Input)

Base index number, where 1 \le B \le nbases. (Input)

Zone index number, where 1 \le Z \le nzones. (Input)

BC Boundary condition index number, where 1 \le BC \le nbocos. (Input)
```

Dset	Dataset index number, where $1 \le \mathtt{Dset} \le \mathtt{ndataset}$. (Input for cg_dataset_read; $output$ for cg_dataset_write)
DatasetName	Name of dataset. (Input for cg_dataset_write; output for cg_dataset_read)
ВСТуре	Simple boundary condition type for the dataset. The supported types are listed in the table of "Simple Boundary Condition Types" in the SIDS manual, but note that FamilySpecified does not apply here. (Input for cg_dataset_write; output for cg_dataset_read)
${\tt DirichletFlag}$	Flag indicating if the dataset contains Dirichlet data. (${\it Output})$
NeumannFlag	Flag indicating if the dataset contains Neumann data. (${\it Output})$
ier	Error status. (Output)

The above functions are applicable to BCDataSet_t nodes that are children of BC_t nodes.

For BCDataSet_t nodes that are children of a BC_t node, after accessing a particular BCDataSet_t node using cg_goto, the Point Set functions described in Section 9.2 may be used to read or write the locations at which the boundary conditions are to be applied. This is only applicable when the boundary conditions are to be applied at locations different from those used with cg_boco_write to define the boundary condition region (e.g., when the region is being defined by specification of vertices, but the boundary conditions are to be applied at face centers).

When writing point set data to a BCDataSet_t node, in addition to the specification of the indices using cg_ptset_write, the function cg_gridlocation_write must also be used to specify the location of the data with respect to the grid (e.g., Vertex or FaceCenter).

Functions	Modes
<pre>ier = cg_bcdataset_write(char *DatasetName, BCType_t BCType,</pre>	- w m
<pre>BCDataType_t BCDataType);</pre>	
<pre>ier = cg_bcdataset_info(int *ndataset);</pre>	
<pre>ier = cg_bcdataset_read(int Dset, char *DatasetName, BCType_t *BCType,</pre>	r - m
<pre>int *DirichletFlag, int *NeumannFlag);</pre>	
<pre>call cg_bcdataset_write_f(DatasetName, BCType, BCDataType_t BCDataType,</pre>	- w m
ier)	
call cg_bcdataset_info_f(int *ndataset, ier)	
<pre>call cg_bcdataset_read_f(Dset, DatasetName, BCType, DirichletFlag,</pre>	r - m
${\it NeumannFlag}$, $ier)$	

Input/Output

```
Dataset index number, where 1 \le \mathtt{Dset} \le \mathtt{ndataset}. (Input)

DatasetName Name of dataset. (Input for cg_bcdataset_write; output for cg_bcdataset_read)
```

ВСТуре	Simple boundary condition type for the dataset. The supported types are listed in the table of "Simple Boundary Condition Types" in the SIDS manual, but note that FamilySpecified does not apply here. (Input for cg_bcdataset_write; output for cg_bcdataset_read)
BCDataType	Type of boundary condition in the dataset (i.e., for a BCData_t child node). Admissible types are Dirichlet and Neumann. (Input)
ndataset	Number of BCDataSet nodes under the current FamilyBC_t node. ($Output$)
DirichletFlag	Flag indicating if the dataset contains Dirichlet data. (${\it Output}$)
NeumannFlag	Flag indicating if the dataset contains Neumann data. (${\it Output})$
ier	Error status. (Output)

The above functions are applicable to BCDataSet_t nodes that are used to define boundary conditions for a CFD family, and thus are children of a FamilyBC_t node. The FamilyBC_t node must first be accessed using cg_goto.

The first time cg_bcdataset_write is called with a particular DatasetName, BCType, and BC-DataType, a new BCDataSet_t node is created, with a child BCData_t node. Subsequent calls with the same DatasetName and BCType may be made to add additional BCData_t nodes, of type BCDataType, to the existing BCDataSet_t node.

14.3 Boundary Condition Data

 $Node : {\tt BCData_t}$

Functions	
<pre>ier = cg_bcdata_write(int fn, int B, int Z, int BC, int Dset,</pre>	- w m
<pre>BCDataType_t BCDataType);</pre>	
<pre>call cg_bcdata_write_f(fn, B, Z, BC, Dset, BCDataType, ier)</pre>	- w m

Input/Output

fn	CGNS file index number. (Input)
В	Base index number, where $1 \le B \le nbases$. (Input)
Z	Zone index number, where $1 \le Z \le nzones$. (Input)
BC	Boundary condition index number, where $1 \leq \mathtt{BC} \leq \mathtt{nbocos}$. (Input)
Dset	Dataset index number, where $1 \leq \mathtt{Dset} \leq \mathtt{ndataset}$. (Input)
BCDataType	Type of boundary condition in the dataset. Admissible boundary condition types are $\tt Dirichlet$ and $\tt Neumann.$ ($\tt Input$)
ier	Error status. (Output)

To write the boundary condition data itself, after creating the BCData_t node using the function cg_bcdata_write, use cg_goto to access the node, then cg_array_write to write the data. Note that when using cg_goto to access a BCData_t node, the node index should be specified as either Dirichlet or Neumann, depending on the type of boundary condition. See the description of cg_goto in Section 4 for details.

14.4 Special Boundary Condition Properties

 $Node : {\tt BCProperty_t}$

Functions	Modes
<pre>ier = cg_bc_wallfunction_write(int fn, int B, int Z, int BC,</pre>	- w m
<pre>WallFunctionType_t WallFunctionType);</pre>	
<pre>ier = cg_bc_area_write(int fn, int B, int Z, int BC,</pre>	- w m
<pre>AreaType_t AreaType, float SurfaceArea, char *RegionName);</pre>	
<pre>ier = cg_bc_wallfunction_read(int fn, int B, int Z, int BC,</pre>	r - m
<pre>WallFunctionType_t *WallFunctionType);</pre>	
<pre>ier = cg_bc_area_read(int fn, int B, int Z, int BC,</pre>	r - m
AreaType_t *AreaType, float *SurfaceArea, char *RegionName);	
call cg_bc_wallfunction_write_f(fn, B, Z, BC, WallFunctionType, ier)	- w m
<pre>call cg_bc_area_write_f(fn, B, Z, BC, AreaType, SurfaceArea,</pre>	- w m
RegionName, ier)	
call cg_bc_wallfunction_read_f(fn, B, Z, BC, WallFunctionType, ier)	r - m
call cg_bc_area_read_f(fn, B, Z, BC, AreaType, SurfaceArea,	r - m
RegionName, ier)	

Input/Output

(Note that for Fortran calls, all integer arguments are integer *4 in 32-bit mode and integer *8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

fn	CGNS file index number. (Input)
В	Base index number, where $1 \le \mathtt{B} \le \mathtt{nbases}$. (Input)
Z	Zone index number, where $1 \le Z \le nzones$. (Input)
BC	Boundary condition index number, where $1 \leq \mathtt{BC} \leq \mathtt{nbocos}$. (Input)
WallFunctionType	The wall function type. Valid types are CG_Null, CG_UserDefined, and Generic. (Input for cg_bc_wallfunction_write; output for cg_bc_wallfunction_read)
AreaType	The type of area. Valid types are CG_Null, CG_UserDefined, BleedArea, and CaptureArea. (Input for cg_bc_area_write; output for cg_bc_area_read)
SurfaceArea	The size of the area. (In Fortran, this is a Real*4 value.) (Input for cg_bc_area_write; output for cg_bc_area_read)
RegionName	The name of the region, 32 characters max. (Input for cg_bc_area_write; output for cg_bc_area_read)
ier	Error status. (Output)

The "write" functions will create the BCProperty_t node if it doesn't already exist, then add the appropriate boundary condition property. Multiple boundary condition properties may be recorded under the same BCProperty_t node.

The "read" functions will return with $ier = 2 = CG_NODE_NOT_FOUND$ if the requested boundary condition property, or the BCProperty_t node itself, doesn't exist.

15 Equation Specification

15.1 Flow Equation Set

 $Node : {\tt FlowEquationSet_t}$

Functions	Modes
<pre>ier = cg_equationset_write(int EquationDimension);</pre>	- w m
<pre>ier = cg_equationset_read(int *EquationDimension,</pre>	r - m
int * Governing Equations Flag, $int * Gas Model Flag$,	
$int \ *Viscosity Model Flag$, $int \ *Thermal Conduct Model Flag$,	
<pre>int *TurbulenceClosureFlag, int *TurbulenceModelFlag);</pre>	
<pre>ier = cg_equationset_chemistry_read(int *ThermalRelaxationFlag,</pre>	r - m
<pre>int *ChemicalKineticsFlag);</pre>	
<pre>ier = cg_equationset_elecmagn_read(int *ElecFldModelFlag,</pre>	r - m
int * MagnFldModelFlag, $ConductivityModelFlag$);	
<pre>call cg_equationset_write_f(EquationDimension, ier)</pre>	- w m
<pre>call cg_equationset_read_f(EquationDimension,</pre>	r - m
${\it Governing Equations Flag}\;,\;{\it Gas Model Flag}\;,\;{\it Viscosity Model Flag}\;,$	
${\it Thermal Conduct Model Flag}$, ${\it Turbulence Closure Flag}$,	
TurbulenceModelFlag, ier)	
call cg_equationset_chemistry_read_f(ThermalRelaxationFlag,	r - m
ChemicalKineticsFlag, ier)	
call cg_equationset_elecmagn_read_f(<i>ElecFldModelFlag</i> ,	r - m
${\it MagnFldModelFlag}$, ${\it ConductivityModelFlag}$, ${\it ier}$)	

Input/Output

EquationDimension	Dimensionality of the governing equations; it is the number of spatial variables describing the flow. (Input for cg_equationset_write; output for cg_equationset_info)
GoverningEquationsFlag	Flag indicating whether or not this FlowEquationSet_t node includes the definition of the governing equations; 0 if it doesn't, 1 if it does. (<i>Output</i>)
GasModelFlag	Flag indicating whether or not this FlowEquationSet_t node includes the definition of a gas model; 0 if it doesn't, 1 if it does. (<i>Output</i>)
ViscosityModelFlag	Flag indicating whether or not this $FlowEquationSet_t$ node includes the definition of a viscosity model; 0 if it doesn't, 1 if it does. ($Output$)
${\tt ThermalConductModelFlag}$	Flag indicating whether or not this FlowEquationSet_t node includes the definition of a thermal conductivity model; 0 if it doesn't, 1 if it does. (Output)

TurbulenceClosureFlag	Flag indicating whether or not this FlowEquationSet_t node includes the definition of the turbulence closure; 0 if it doesn't, 1 if it does. ($Output$)
TurbulenceModelFlag	Flag indicating whether or not this FlowEquationSet_t node includes the definition of a turbulence model; 0 if it doesn't, 1 if it does. (<i>Output</i>)
ThermalRelaxationFlag	Flag indicating whether or not this FlowEquationSet_t node includes the definition of that thermal relaxation model; 0 if it doesn't, 1 if it does. (<i>Output</i>)
ChemicalKineticsFlag	Flag indicating whether or not this FlowEquationSet_t node includes the definition of a chemical kinetics model; 0 if it doesn't, 1 if it does. (<i>Output</i>)
ElecFldModelFlag	Flag indicating whether or not this FlowEquationSet_t node includes the definition of an electric field model for electromagnetic flows; 0 if it doesn't, 1 if it does. (<i>Output</i>)
MagnFldModelFlag	Flag indicating whether or not this FlowEquationSet_t node includes the definition of a magnetic field model for electromagnetic flows; 0 if it doesn't, 1 if it does. (<i>Output</i>)
ConductivityModelFlag	Flag indicating whether or not this FlowEquationSet_t node includes the definition of a conductivity model for electromagnetic flows; 0 if it doesn't, 1 if it does. (<i>Output</i>)
ier	Error status. ($Output$)

15.2 Governing Equations

 $Node : {\tt GoverningEquations_t}$

Functions	Modes
<pre>ier = cg_governing_write(GoverningEquationsType_t Equationstype);</pre>	- w m
<pre>ier = cg_governing_read(GoverningEquationsType_t *EquationsType);</pre>	r - m
<pre>ier = cg_diffusion_write(int *diffusion_model);</pre>	- w m
<pre>ier = cg_diffusion_read(int *diffusion_model);</pre>	r - m
call cg_governing_write_f(EquationsType, ier)	- w m
call cg_governing_read_f(EquationsType, ier)	r - m
call cg_diffusion_write_f(diffusion_model, ier)	- w m
call cg_diffusion_read_f(diffusion_model, ier)	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

EquationsType Type of governing equations. The admissible types are CG_Null, CG_UserDefined, FullPotential, Euler, NSLaminar, NSTurbulent,

```
NSLaminarIncompressible, and NSTurbulentIncompressible. (Input
for cg_governing_write; output for cg_governing_read)
```

diffusion_model

ier

Flags defining which diffusion terms are included in the governing equations. This is only applicable to the Navier-Stokes equations with structured grids. See the discussion of GoverningEquations_t in the SIDS manual for details. (Input for cg_diffusion_write; output for cg_diffusion_read)

Error status. (Output)

15.3 **Auxiliary Models**

Nodes: GasModel_t, ViscosityModel_t, ThermalConductivityModel_t, TurbulenceClosure_t, TurbulenceModel_t, ThermalRelaxationModel_t, ChemicalKineticsModel_t, EMElectricField-Model_t, EMMagneticFieldModel_t, EMConductivityModel_t

Functions	Modes
<pre>ier = cg_model_write(char *ModelLabel, ModelType_t ModelType);</pre>	- w m
<pre>ier = cg_model_read(char *ModelLabel, ModelType_t *ModelType);</pre>	r - m
call cg_model_write_f(ModelLabel, ModelType, ier)	- w m
call cg_model_read_f(ModelLabel, ModelType, ier)	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer *4 in 32-bit mode and integer *8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

The CGNS label for the model being defined. The models supported by CGNS ModelLabel are:

- GasModel_t
- ViscosityModel_t
- ThermalConductivityModel_t
- TurbulenceClosure_t
- TurbulenceModel_t
- ThermalRelaxationModel_t
- ChemicalKineticsModel_t
- EMElectricFieldModel_t
- EMMagneticFieldModel_t
- EMConductivityModel_t

(Input)

One of the model types (listed below) allowed for the ModelLabel selected. ModelType (Input for cg_model_write; output for cg_model_read)

Error status. (Output) ier

The types allowed for the various models are:

EMConductivityModel_t

CG_Null, CG_UserDefined, Ideal, VanderWaals, GasModel_t CaloricallyPerfect, ThermallyPerfect, ConstantDensity, RedlichKwong ViscosityModel_t CG_Null, CG_UserDefined, Constant, PowerLaw, SutherlandLawThermalConductivityModel_t CG_Null, CG_UserDefined, PowerLaw, SutherlandLaw, ConstantPrandtl CG_Null, CG_UserDefined, Algebraic_BaldwinLomax, TurbulenceModel_t Algebraic_CebeciSmith, HalfEquation_JohnsonKing, OneEquation_BaldwinBarth, OneEquation_SpalartAllmaras, TwoEquation_JonesLaunder, TwoEquation_MenterSST, TwoEquation_Wilcox TurbulenceClosure_t CG_Null, CG_UserDefined, EddyViscosity, ReynoldsStress, ReynoldsStressAlgebraic ThermalRelaxationModel_t CG_Null, CG_UserDefined, Frozen, ThermalEquilib, ThermalNonequilib ChemicalKineticsModel_t CG_Null, CG_UserDefined, Frozen, ChemicalEquilibCurveFit, ChemicalEquilibMinimization, ChemicalNonequilib EMElectricFieldModel_t CG_Null, CG_UserDefined, Constant, Frozen, Interpolated, Voltage CG_Null, CG_UserDefined, Constant, Frozen, EMMagneticFieldModel_t Interpolated

CG_Null, CG_UserDefined, Constant, Frozen, Equilibrium_LinRessler, Chemistry_LinRessler

16 Families

16.1 Family Definition

 $Node \colon {\tt Family_t}$

Functions	
<pre>ier = cg_family_write(int fn, int B, char *FamilyName, int *Fam);</pre>	- w m
<pre>ier = cg_nfamilies(int fn, int B, int *nfamilies);</pre>	r - m
<pre>ier = cg_family_read(int fn, int B, int Fam, char *FamilyName,</pre>	r - m
<pre>int *nFamBC, int *nGeo);</pre>	
call cg_family_write_f(fn, B, FamilyName, Fam, ier)	- w m
call cg_nfamilies_f(fn, B, nfamilies, ier)	r - m
call cg_family_read_f(fn, B, Fam, FamilyName, nFamBC, nGeo, ier)	r - m

Input/Output

fn	CGNS file index number. (Input)
В	Base index number, where $1 \le B \le nbases$. (Input)
nfamilies	Number of families in base B. (Output)
Fam	Family index number, where $1 \le Fam \le nfamilies$. (Input for cg_family_read; $output$ for cg_family_write)
FamilyName	Name of the family. (Input for cg_family_write; output for cg_family_read)
nFamBC	Number of boundary conditions for this family. This should be either 0 or 1. $({\it Output})$
nGeo	Number of geometry references for this family. $(Output)$
ier	Error status. (Output)

16.2 Geometry Reference

Node: GeometryReference_t

Functions	Modes
<pre>ier = cg_geo_write(int fn, int B, int Fam, char *GeoName,</pre>	- w m
<pre>char *FileName, char *CADSystem, int *G);</pre>	
<pre>ier = cg_geo_read(int fn, int B, int Fam, int G, char *GeoName,</pre>	r - m
<pre>char **FileName, char *CADSystem, int *nparts);</pre>	
<pre>ier = cg_part_write(int fn, int B, int Fam, int G, char *PartName,</pre>	- w m
<pre>int *P);</pre>	
<pre>ier = cg_part_read(int fn, int B, int Fam, int G, int P,</pre>	r - m
<pre>char *PartName);</pre>	
call cg_geo_write_f(fn, B, Fam, GeoName, FileName, CADSystem, G, ier)	- w m
call cg_geo_read_f(fn, B, Fam, G, GeoName, FileName, CADSystem,	r - m
nparts, ier)	
call cg_part_write_f(fn, B, Fam, G, PartName, P, ier)	- w m
<pre>call cg_part_read_f(fn, B, Fam, G, P, PartName, ier)</pre>	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

fn	CGNS file index number. (Input)
В	Base index number, where $1 \le B \le nbases$. (Input)
Fam	Family index number, where $1 \le \mathtt{Fam} \le \mathtt{nfamilies}$. (Input)
G	Geometry reference index number, where $1 \le G \le nGeo$. (Input for cg_geo_read, cg_part_write, cg_part_read; $output$ for cg_geo_write)
P	Geometry entity index number, where $1 \le P \le nparts$. (Input for cg_part_read; output for cg_part_write)
GeoName	Name of GeometryReference_t node. (Input for cg_geo_write; $output$ for cg_geo_read)
FileName	Name of geometry file. (Input for cg_geo_write; output for cg_geo_read)
CADSystem	Geometry format. (Input for cg_geo_write ; $output$ for cg_geo_read)
nparts	Number of geometry entities. (Output)
PartName	Name of a geometry entity in the file FileName. (Input for cg_part_write; $output$ for cg_part_read)
ier	Error status. (Output)

Note that with cg_geo_read the memory for the filename character string, FileName, will be allocated by the Mid-Level Library. The application code is responsible for releasing this memory when it is no longer needed by calling cg_free(FileName), described in Section 10.6.

16.3 Family Boundary Condition

 $Node : {\tt FamilyBC_t}$

Functions	Modes
<pre>ier = cg_fambc_write(int fn, int B, int Fam, char *FamBCName,</pre>	- w m
BCType_t BCType, int *BC);	
<pre>ier = cg_fambc_read(int fn, int B, int Fam, int BC, char *FamBCName,</pre>	r - m
BCType_t *BCType);	
call cg_fambc_write_f(fn, B, Fam, FamBCName, BCType, BC, ier)	- w m
call cg_fambc_read_f(fn, B, Fam, BC, FamBCName, BCType, ier)	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

fn	CGNS file index number. (Input)
В	Base index number, where $1 \le B \le nbases$. (Input)
Fam	Family index number, where $1 \le \mathtt{Fam} \le \mathtt{nfamilies}$. (Input)
BC	Family boundary condition index number. This must be equal to 1. (Input for cg_fambc_read ; $output$ for cg_fambc_write)
FamBCName	Name of the FamilyBC_t node. (Input for cg_fambc_write; output for cg_fambc_read)
BCType	Boundary condition type for the family. See the eligible types for BCType_t in Section 2.6. (Input for cg_fambc_write; output for cg_fambc_read)
ier	Error status. (Output)

16.4 Family Name

Node: FamilyName_t

Functions	Modes
<pre>ier = cg_famname_write(char *FamilyName);</pre>	- w m
<pre>ier = cg_famname_read(char *FamilyName);</pre>	r - m
<pre>call cg_famname_write_f(FamilyName, ier)</pre>	- w m
<pre>call cg_famname_read_f(FamilyName, ier)</pre>	r - m

Input/Output

```
FamilyName Family name. (Input for cg_famname_write; output for cg_famname_read) ier Error status. (Output)
```

17 Time-Dependent Data

17.1 Base Iterative Data

Node: BaseIterativeData_t

Functions	Modes
<pre>ier = cg_biter_write(int fn, int B, char *BaseIterName, int Nsteps);</pre>	- w m
<pre>ier = cg_biter_read(int fn, int B, char *BaseIterName, int *Nsteps);</pre>	r - m
call cg_biter_write_f(fn, B, BaseIterName, Nsteps, ier)	- w m
call cg_biter_read_f(fn, B, BaseIterName, Nsteps, ier)	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

17.2 Zone Iterative Data

Node: ZoneIterativeData_t

Functions	Modes
<pre>ier = cg_ziter_write(int fn, int B, int Z, char *ZoneIterName);</pre>	- w m
<pre>ier = cg_ziter_read(int fn, int B, int Z, char *ZoneIterName);</pre>	r - m
call cg_ziter_write_f(fn, B, Z, ZoneIterName, ier)	- w m
<pre>call cg_ziter_read_f(fn, B, Z, ZoneIterName, ier)</pre>	r - m

Input/Output

```
fn CGNS file index number. (Input)

Base index number, where 1 \le B \le nbases. (Input)

Z Family index number, where 1 \le Z \le nzones. (Input)
```

```
ZoneIterName Name of the ZoneIterativeData_t node. (Input for cg_ziter_write; output for cg_ziter_read)

ier Error status. (Output)
```

17.3 Rigid Grid Motion

 $Node: {\tt RigidGridMotion_t}$

Functions	Modes
<pre>ier = cg_rigid_motion_write(int fn, int B, int Z,</pre>	- w m
char *RigidGridMotionName,	
<pre>RigidGridMotionType_t RigidGridMotionType, int *R);</pre>	
<pre>ier = cg_n_rigid_motions(int fn, int B, int Z, int *n_rigid_motions);</pre>	r - m
<pre>ier = cg_rigid_motion_read(int fn, int B, int Z, int R,</pre>	r - m
char *RigitGrithMotionName,	
<pre>RigidGridMotionType_t RigidGridMotionType);</pre>	
<pre>call cg_rigid_motion_write_f(fn, B, Z, RigidGridMotionName,</pre>	- w m
RigidGridMotionType, R, ier)	
call cg_n_rigid_motions_f(fn, B, Z, n_rigid_motions, ier)	r - m
call cg_rigid_motion_read_f(fn, B, Z, R, RigidGridMotionName,	r - m
RigidGridMotionType, ier)	

Input/Output

fn	CGNS file index number. (Input)
В	Base index number, where $1 \le \mathtt{B} \le \mathtt{nbases}$. (Input)
Z	Family index number, where $1 \le Z \le nzones.$ (Input)
RigidGridMotionName	Name of the RigidGridMotion_t node. (Input for cg_rigid_motion_write; output for cg_rigid_motion_read)
RigidGridMotionType	Type of rigid grid motion. The admissible types are CG_Null, CG_UserDefined, ConstantRate, and VariableRate. (Input for cg_rigid_motion_write; output for cg_rigid_motion_read)
n_rigid_motions	Number of RigidGridMotion_t nodes under zone Z. (${\it Output}$)
R	Rigid rotation index number, where $1 \le R \le n_rigid_motions$. (Input for cg_rigid_motion_read; output for cg_rigid_motion_write)
ier	Error status. (Output)

17.4 Arbitrary Grid Motion

 $Node {:}\ {\tt ArbitraryGridMotion_t}$

Functions	Modes
<pre>ier = cg_arbitrary_motion_write(int fn, int B, int Z,</pre>	- w m
char *ArbitraryGridMotionName,	
ArbitraryGridMotionType_t ArbitraryGridMotionType, int *A);	
<pre>ier = cg_n_arbitrary_motions(int fn, int B, int Z,</pre>	r - m
<pre>int *n_arbitrary_motions);</pre>	
<pre>ier = cg_arbitrary_motion_read(int fn, int B, int Z, int A,</pre>	r - m
<pre>char *ArbitraryGridMotionName,</pre>	
ArbitraryGridMotionType_t ArbitraryGridMotionType);	
call cg_arbitrary_motion_write_f(fn, B, Z, ArbitraryGridMotionName,	- w m
ArbitraryGridMotionType, A, ier)	
call cg_n_arbitrary_motions_f(fn, B, Z, n_arbitrary_motions, ier)	r - m
call cg_arbitrary_motion_read_f(fn, B, Z, A, ArbitraryGridMotionName,	r - m
ArbitraryGridMotionType, ier)	

Input/Output

fn	CGNS file index number. (Input)
В	Base index number, where $1 \le \mathtt{B} \le \mathtt{nbases}$. (Input)
Z	Family index number, where $1 \le Z \le nzones$. (Input)
ArbitraryGridMotionName	Name of the ArbitraryGridMotion_t node. (Input for cg_arbitrary_motion_write; output for cg_arbitrary_motion_read)
ArbitraryGridMotionType	Type of arbitrary grid motion. The admissible types are CG_Null, CG_UserDefined, NonDeformingGrid, and DeformingGrid. (Input for cg_arbitrary_motion_write; output for cg_arbitrary_motion_read)
n_arbitrary_motions	Number of ArbitraryGridMotion_t nodes under zone Z. $(Output)$
A	Arbitrary grid motion index number, where $1 \le A \le n_a$ rbitrary_motions. (Input for cg_arbitrary_motion_read; output for cg_arbitrary_motion_write)
ier	Error status. (Output)

17.5 Zone Grid Connectivity

Node: ZoneGridConnectivity_t

```
Functions
                                                                           Modes
ier = cg_nzconns(int fn, int B, int Z, int *nzconns);
                                                                           r - m
ier = cg_zconn_read(int fn, int B, int Z, int ZC, char *zcname);
                                                                             - m
ier = cg_zconn_write(int fn, int B, int Z, const char *zcname,
                                                                             w m
      int *ZC);
ier = cg_zconn_set(int fn, int B, int Z, int ZC);
                                                                           r w m
ier = cg_zconn_get(int fn, int B, int Z, int *ZC);
                                                                             w m
call cg_nzconns_f(fn, B, Z, nzconns, ier)
                                                                           r - m
call cg_zconn_read_f(fn, B, Z, ZC, zcname, ier)
                                                                               m
call cg_zconn_write_f(fn, B, Z, zcname, ZC, ier)
                                                                             w m
call cg_zconn_set_f(fn, B, Z, ZC, ier)
                                                                           r w m
call cg_zconn_get_f(fn, B, Z, ZC, ier)
                                                                           r w m
```

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

```
CGNS file index number. (Input)
fn
В
           Base index number, where 1 \le B \le nbases. (Input)
           Family index number, where 1 \le Z \le nzones. (Input)
Ζ
ZC
           Zone grid connectivity index number, where 1 \le ZC \le nzconns. (Input for
           cg_zconn_read and cg_zconn_set; output for cg_zconn_write and
           cg_zconn_get)
           Number of ZoneGridConnectivity_t nodes under Zone Z. (Output)
nzconns
           Name of the ZoneGridConnectivity_t node. (Input for cg_zconn_write; output
zcname
           for cg_zconn_read)
           Error status. (Output)
ier
```

This allows for the specification of multiple ZoneGridConnectivity_t nodes. If these functions are not used, or cg_zconn_write is called once with a zcname of ZoneGridConnectivity, then there will be no differences from previous versions of the CGNS library. However, with multiple ZoneGridConnectivity_t nodes, there is an implicit current ZoneGridConnectivity_t node on which subsequent grid connectivity functions will operate, i.e. cg_conn_read/write (Section 13.2) or cg_1to1_read/write (Section 13.1).

The functions cg_zconn_read and cg_zconn_write will implicity set the *current* ZoneGrid-Connectivity_t node, while cg_zconn_set explicitly sets it. The functions cg_nzconns and cg_zconn_get do not change it.

The time-dependent changes to the connectivities may then be recorded in the ZoneInterative-Data_t (Section 17.2) node as an array of ZoneGridConnectivityPointers.

18 Links

Functions	Modes
<pre>ier = cg_link_write(char *nodename, char *filename,</pre>	- w m
<pre>char *name_in_file);</pre>	
<pre>ier = cg_is_link(int *path_length);</pre>	r - m
<pre>ier = cg_link_read(char **filename, char **link_path);</pre>	r - m
<pre>call cg_link_write_f(nodename, filename, name_in_file, ier)</pre>	- w m
call cg_is_link_f(path_length, ier)	r - m
<pre>call cg_link_read_f(filename, link_path, ier)</pre>	r - m

Input/Output

(Note that for Fortran calls, all integer arguments are integer*4 in 32-bit mode and integer*8 in 64-bit mode. See "64-bit Fortran Portability and Issues" section.)

nodename	Name of the link node to create, e.g., GridCoordinates. (Input)
filename	Name of the linked file, or empty string if the link is within the same file. (Input for cg_link_write; output for cg_link_read)
name_in_file	Path name of the node which the link points to. This can be a simple or a compound name, e.g., Base/Zone $1/GridCoordinates$. (Input)
path_length	Length of the path name of the linked node. The value 0 is returned if the node is not a link. $(Output)$
link_path	Path name of the node which the link points to. $(Output)$
ier	Error status. (Output)

Use cg_goto(_f), described in Section 4, to position to a location in the file prior to calling these routines.

When using cg_link_write, the node being linked to does not have to exist when the link is created. However, when the link is used, an error will occur if the linked-to node does not exist.

Only nodes that support child nodes will support links.

It is assumed that the CGNS version for the file containing the link, as determined by the CGNSLibraryVersion_t node, is also applicable to filename, the file containing the linked node.

Memory is allocated by the library for the return values of the C function cg_link_read. This memory should be freed by the user when no longer needed by calling cg_free(filename) and cg_free(link_path), described in Section 10.6.