# **CURS 13**

Cuadripoli

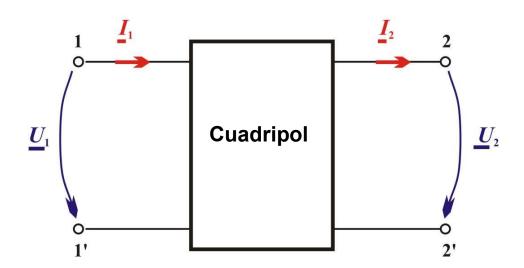
# **CUADRIPOLI**

Circuit cu patru borne de acces

## Poartă:

→ O pereche de borne care are suma curenţilor zero;

→ O pereche de borne pe la care circuitul **primește sau cedează energie** 



Poartă de intrare: bornele 1-1'

Poartă de ieșire: bornele 2-2'

Cuadripol activ: conține surse

Cuadripol pasiv: nu conține surse

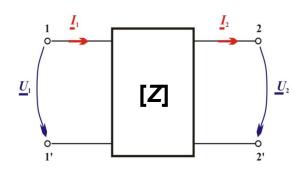
primește energie

cedează energie

# PARAMETRI CUADRIPOLILOR

# Parametrii impedanță Z

$$\begin{cases}
\underline{U}_1 = \underline{Z}_{11} \cdot \underline{I}_1 + \underline{Z}_{12} \cdot \underline{I}_2 \\
\underline{U}_2 = \underline{Z}_{21} \cdot \underline{I}_1 + \underline{Z}_{22} \cdot \underline{I}_2
\end{cases}$$



Matricial:

$$[\underline{U}] = [\underline{Z}] \cdot [\underline{I}]$$

$$\begin{bmatrix} \underline{U}_1 \\ \underline{U}_2 \end{bmatrix} = \begin{bmatrix} \underline{Z}_{11} & \underline{Z}_{12} \\ \underline{Z}_{21} & \underline{Z}_{22} \end{bmatrix} \cdot \begin{bmatrix} \underline{I}_1 \\ \underline{I}_2 \end{bmatrix}$$

#### Impedanța de intrare la mersul în gol

$$\underline{Z}_{11} = \frac{\underline{U}_1}{\underline{I}_1} \bigg|_{\underline{I}_2 = 0}$$

#### Impedanța de transfer la mersul în gol

$$\underline{Z}_{12} = \frac{\underline{U}_1}{\underline{I}_2} \bigg|_{I_1 = 0}$$

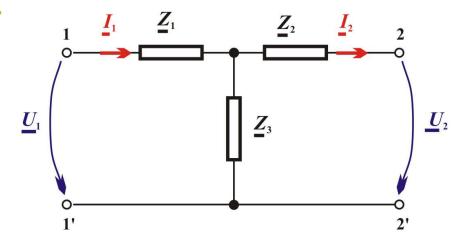
## Impedanța de transfer la mersul în gol

$$\underline{Z}_{21} = \frac{\underline{U}_2}{\underline{I}_1} \bigg|_{\underline{I}_2 = 0}$$

#### Impedanța de ieșire la mersul în gol

$$\underline{Z}_{22} = \frac{\underline{U}_2}{\underline{I}_2} \bigg|_{\underline{I}_1 = 0}$$

# **Exemplu:** cuadripol-T



Impedanța de intrare la mersul în gol

$$\underline{Z}_{11} = \frac{\underline{U}_1}{\underline{I}_1}\bigg|_{I_2 = 0} = \underline{Z}_1 + \underline{Z}_3$$

Impedanța de transfer la mersul în gol

$$\underline{Z}_{12} = \frac{\underline{U}_1}{\underline{I}_2} \bigg|_{\underline{I}_1 = 0} = \underline{Z}_3$$

$$\underline{Z}_{11} - \underline{Z}_{21} = \underline{Z}_1$$

Impedanța de transfer la mersul în gol

$$\underline{Z}_{21} = \frac{\underline{U}_2}{\underline{I}_1} \bigg|_{I_2 = 0} = \underline{Z}_3$$

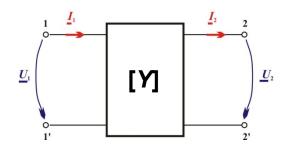
Impedanța de ieșire la mersul în gol

$$\underline{Z}_{22} = \frac{\underline{U}_2}{\underline{I}_2}\bigg|_{I_1=0} = \underline{Z}_2 + \underline{Z}_3$$

$$\underline{Z}_{12} = \underline{Z}_{21} = \underline{Z}_3$$

$$Z_{22} - Z_{21} = Z_2$$

# Parametri admitanță, Y



$$\begin{cases} \underline{I}_1 = \underline{Y}_{11} \cdot \underline{U}_1 + \underline{Y}_{12} \cdot \underline{U}_2 \\ \underline{I}_2 = \underline{Y}_{21} \cdot \underline{U}_1 + \underline{Y}_{22} \cdot \underline{U}_2 \end{cases}$$

Matricial: 
$$[\underline{I}] = [\underline{Y}] \cdot [\underline{U}]$$

$$\begin{bmatrix} \underline{I}_1 \\ \underline{I}_2 \end{bmatrix} = \begin{bmatrix} \underline{Y}_{11} & \underline{Y}_{12} \\ \underline{Y}_{21} & \underline{Y}_{22} \end{bmatrix} \cdot \begin{bmatrix} \underline{U}_1 \\ \underline{U}_2 \end{bmatrix}$$

#### Admitanța de intrare la mersul în scurtcircuit

Admitanţa de transfer la mersul în scurtcircuit

$$\underline{Y}_{11} = \frac{\underline{I}_1}{\underline{U}_1} \bigg|_{\underline{U}_2 = 0}$$

$$\underline{Y}_{21} = \frac{\underline{I}_2}{\underline{U}_1} \bigg|_{\underline{U}_2 = 0}$$

## Admitenţa de transfer la mersul în scurtcircuit

Admitanţa de ieşire la mersul în scurtcircuit

$$\underline{Y}_{12} = \frac{\underline{I}_1}{\underline{U}_2} \bigg|_{\underline{U}_1 = 0}$$

$$\underline{Y}_{22} = \frac{\underline{I}_2}{U_2} \bigg|_{\underline{U}_1 = 0}$$

# Relațiile dintre parametri Z și Y

$$\begin{cases} \underline{U}_1 = \underline{Z}_{11} \cdot \underline{I}_1 + \underline{Z}_{12} \cdot \underline{I}_2 \\ \underline{U}_2 = \underline{Z}_{21} \cdot \underline{I}_1 + \underline{Z}_{22} \cdot \underline{I}_2 \end{cases}$$

$$\begin{cases} \underline{I}_1 = \underline{Y}_{11} \cdot \underline{U}_1 + \underline{Y}_{12} \cdot \underline{U}_2 \\ \underline{I}_2 = \underline{Y}_{21} \cdot \underline{U}_1 + \underline{Y}_{22} \cdot \underline{U}_2 \end{cases}$$

Rezolvând pentru  $\underline{I}_1$  și  $\underline{I}_2$ :

$$\underline{I}_{1} = \frac{\begin{vmatrix} \underline{U}_{1} & \underline{Z}_{12} \\ \underline{U}_{2} & \underline{Z}_{22} \end{vmatrix}}{\begin{vmatrix} \underline{Z}_{11} & \underline{Z}_{12} \\ \underline{Z}_{21} & \underline{Z}_{22} \end{vmatrix}} \qquad \underline{I}_{2} = \frac{\begin{vmatrix} \underline{Z}_{11} & \underline{U}_{1} \\ \underline{Z}_{21} & \underline{U}_{2} \end{vmatrix}}{\begin{vmatrix} \underline{Z}_{11} & \underline{Z}_{12} \\ \underline{Z}_{21} & \underline{Z}_{22} \end{vmatrix}}$$

$$\underline{I}_{1} = \frac{\underline{Z}_{22}}{\Delta_{Z}} \cdot \underline{U}_{1} - \frac{\underline{Z}_{12}}{\Delta_{Z}} \cdot \underline{U}_{2} \qquad \qquad \underline{I}_{2} = -\frac{\underline{Z}_{21}}{\Delta_{Z}} \cdot \underline{U}_{1} + \frac{\underline{Z}_{11}}{\Delta_{Z}} \cdot \underline{U}_{2}$$

Comparând cu sistemul pentru 
$$\boldsymbol{Y}$$
:
$$\begin{bmatrix}
\underline{Y}_{11} & \underline{Y}_{12} \\
\underline{Y}_{21} & \underline{Y}_{22}
\end{bmatrix} = \begin{bmatrix}
\underline{Z}_{22} & -\underline{Z}_{12} \\
\Delta_Z & \Delta_Z \\
\underline{Z}_{21} & \underline{Z}_{11} \\
\Delta_Z & \Delta_Z
\end{bmatrix}$$

# Parametri hibrizi; h

$$\begin{cases}
\underline{U}_1 = \underline{h}_{11} \cdot \underline{I}_1 + \underline{h}_{12} \cdot \underline{U}_2 \\
\underline{I}_2 = \underline{h}_{21} \cdot \underline{I}_1 + \underline{h}_{22} \cdot \underline{U}_2
\end{cases}$$



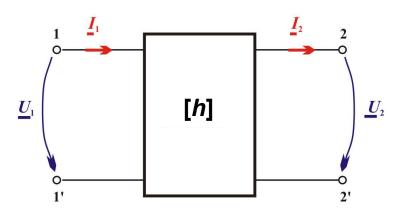
$$\begin{bmatrix} \underline{U}_1 \\ \underline{I}_2 \end{bmatrix} = \begin{bmatrix} \underline{h}_{11} & \underline{h}_{12} \\ \underline{h}_{21} & \underline{h}_{22} \end{bmatrix} \cdot \begin{bmatrix} \underline{I}_1 \\ \underline{U}_2 \end{bmatrix}$$

#### Impedanța de scurcircuit la poarta 1

$$\underline{h}_{11} = \frac{\underline{U}_1}{\underline{I}_1} \bigg|_{U_2 = 0}$$

#### Raportul de transformare al tensiunilor

$$\underline{h}_{12} = \frac{\underline{U}_1}{\underline{U}_2} \bigg|_{\underline{I}_1 = 0}$$



## Raportul de transformare al curenților

$$\underline{h}_{21} = \frac{\underline{I}_2}{\underline{I}_1} \bigg|_{\underline{U}_2 = 0}$$

# Admitanța de mers în gol la poarta 2

$$\underline{h}_{22} = \frac{\underline{I}_2}{\underline{U}_2} \bigg|_{\underline{I}_1 = 0}$$

# Parametri hibrizi; g

$$\begin{cases} \underline{I}_{1} = \underline{g}_{11} \cdot \underline{U}_{1} + \underline{g}_{12} \cdot \underline{I}_{2} \\ \underline{U}_{2} = \underline{g}_{21} \cdot \underline{U}_{1} + \underline{g}_{22} \cdot \underline{I}_{2} \end{cases}$$



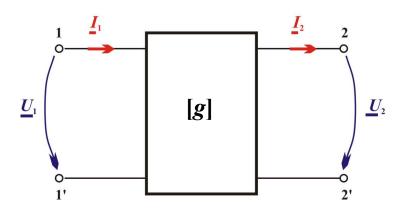
$$\begin{bmatrix} \underline{I}_1 \\ \underline{U}_2 \end{bmatrix} = \begin{bmatrix} \underline{g}_{11} & \underline{g}_{12} \\ \underline{g}_{21} & \underline{g}_{22} \end{bmatrix} \cdot \begin{bmatrix} \underline{U}_1 \\ \underline{I}_2 \end{bmatrix}$$

#### Admitanța de mers în gol la poarta 1

$$\underline{g}_{11} = \frac{\underline{I}_1}{\underline{U}_1} \bigg|_{\underline{I}_2 = 0}$$

#### Raportul de transformare al curenților

$$\underline{g}_{12} = \frac{\underline{I}_1}{\underline{I}_2} \bigg|_{\underline{U}_1 = 0}$$



## Raportul de transformare al tensiunilor

$$\underline{g}_{21} = \frac{\underline{U}_2}{\underline{U}_1} \bigg|_{I_2 = 0}$$

#### Impedanța de scurt circuit la poarta 2

$$\underline{g}_{22} = \frac{\underline{U}_2}{\underline{I}_2} \bigg|_{U_1 = 0}$$

# Relațiile dintre parametri h și Z

Pentru parametri Z:

$$\begin{cases} \underline{U}_1 = \underline{Z}_{11} \cdot \underline{I}_1 + \underline{Z}_{12} \cdot \underline{I}_2 \\ \underline{U}_2 = \underline{Z}_{21} \cdot \underline{I}_1 + \underline{Z}_{22} \cdot \underline{I}_2 \end{cases}$$

$$\underline{h}_{11} = \frac{\underline{U}_1}{\underline{I}_1}$$

$$\underline{h}_{12} = \frac{\underline{U}_1}{\underline{U}_2} \bigg|_{\underline{I}_1 = 0}$$

Pentru parametri *h*:

$$\underline{h}_{21} = \frac{\underline{I}_2}{\underline{I}_1} \bigg|_{U_2 = 0}$$

$$\underline{h}_{11} = \frac{\underline{U}_1}{\underline{I}_1}\Big|_{U_2 = 0} \qquad \underline{h}_{12} = \frac{\underline{U}_1}{\underline{U}_2}\Big|_{I_1 = 0} \qquad \underline{h}_{21} = \frac{\underline{I}_2}{\underline{I}_1}\Big|_{U_2 = 0} \qquad \underline{h}_{22} = \frac{\underline{I}_2}{\underline{U}_2}\Big|_{I_1 = 0}$$

Inlocuim  $\underline{U}_2 = 0$  în ecuația 2:

$$0 = \underline{Z}_{21} \cdot \underline{I}_1 + \underline{Z}_{22} \cdot \underline{I}_2 \quad \Rightarrow \quad \frac{\underline{I}_2}{\underline{I}_1} = -\frac{\underline{Z}_{21}}{\underline{Z}_{22}} = \underline{h}_{21}$$

Substituim  $\frac{\underline{I}_2}{I}$  în ecuația 1:

$$\underline{U}_{1} = \underline{Z}_{11} \cdot \underline{I}_{1} + \underline{Z}_{12} \cdot \left( -\frac{\underline{Z}_{21}}{\underline{Z}_{22}} \underline{I}_{1} \right) \quad \Rightarrow \quad \underline{\underline{U}}_{1} = \underline{Z}_{11} - \underline{\underline{Z}_{12} \cdot \underline{Z}_{21}} = \underline{h}_{11}$$

sau

$$\underline{h}_{11} = \frac{\underline{Z}_{11} \cdot \underline{Z}_{22} - \underline{Z}_{12} \cdot \underline{Z}_{21}}{\underline{Z}_{22}} = \frac{\Delta_Z}{\underline{Z}_{22}}$$

unde:

$$\Delta_Z = \underline{Z}_{11} \cdot \underline{Z}_{22} - \underline{Z}_{12} \cdot \underline{Z}_{21}$$

$$\begin{bmatrix} \underline{h}_{11} & \underline{h}_{12} \\ \underline{h}_{21} & \underline{h}_{22} \end{bmatrix} = \begin{vmatrix} \underline{\Delta}_{Z} & \underline{Z}_{12} \\ \underline{Z}_{22} & \underline{Z}_{22} \\ \underline{Z}_{21} & \underline{1} \\ \underline{Z}_{22} & \underline{Z}_{22} \end{vmatrix}$$

Înlocuim  $\underline{I}_1 = 0$  in ec. 1 şi 2:

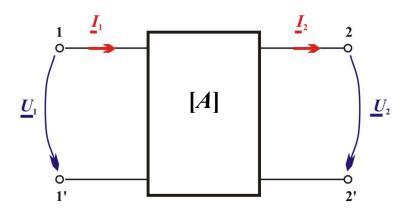
$$\begin{cases} \underline{U}_1 = \underline{Z}_{12} \cdot \underline{I}_2 \\ \underline{U}_2 = \underline{Z}_{22} \cdot \underline{I}_2 \end{cases}$$

$$\underline{h}_{12} = \frac{\underline{U}_1}{\underline{U}_2} \bigg|_{\underline{I}_1 = 0} = \frac{\underline{Z}_{12}}{\underline{Z}_{22}}$$

$$\underline{h}_{22} = \frac{\underline{I}_2}{\underline{U}_2} \bigg|_{I_1 = 0} = \frac{1}{\underline{Z}_{22}}$$

## PARAMETRI FUNDAMENTALI

$$\begin{cases} \underline{U}_1 = \underline{A} \cdot \underline{U}_2 + \underline{B} \cdot \underline{I}_2 \\ \underline{I}_1 = \underline{C} \cdot \underline{U}_2 + \underline{D} \cdot \underline{I}_2 \end{cases}$$



#### matricial:

$$\begin{bmatrix} \underline{U}_1 \\ \underline{I}_1 \end{bmatrix} = \begin{bmatrix} \underline{A} & \underline{B} \\ \underline{C} & \underline{D} \end{bmatrix} \cdot \begin{bmatrix} \underline{U}_2 \\ \underline{I}_2 \end{bmatrix}$$

## Raportul de transformare al tensiunilor

$$\underline{A} = \frac{\underline{U}_1}{\underline{U}_2} \bigg|_{\underline{I}_2 = 0}$$

## Impedanţa de transfer la mers în scurtcircuit

$$\underline{B} = \frac{\underline{U}_1}{\underline{I}_2} \bigg|_{\underline{U}_2 = 0}$$

#### Admitanţa de transfer la mers în gol

$$\underline{C} = \frac{\underline{I}_1}{\underline{U}_2} \bigg|_{\underline{I}_2 = 0}$$

## Raportul de transformare al curenţilor

$$\underline{D} = \frac{\underline{I}_1}{\underline{I}_2} \bigg|_{\underline{U}_2 = 0}$$

# Relațiile dintre *parametri fundamentali* și parametri *Z*

$$\begin{cases}
\underline{U}_1 = \underline{Z}_{11} \cdot \underline{I}_1 + \underline{Z}_{12} \cdot \underline{I}_2 \\
\underline{U}_2 = \underline{Z}_{21} \cdot \underline{I}_1 + \underline{Z}_{22} \cdot \underline{I}_2
\end{cases}$$

$$\begin{cases}
\underline{U}_1 = \underline{A} \cdot \underline{U}_2 + \underline{B} \cdot \underline{I}_2 \\
\underline{I}_1 = \underline{C} \cdot \underline{U}_2 + \underline{D} \cdot \underline{I}_2
\end{cases}$$

$$\underline{U}_2 = \underline{Z}_{21} \cdot \underline{I}_1 + \underline{Z}_{22} \cdot \underline{I}_2 \implies \underline{I}_1 = \frac{\underline{U}_2}{\underline{Z}_{21}} - \frac{\underline{Z}_{22}}{\underline{Z}_{21}} \cdot \underline{I}_2$$

$$\underline{U}_{1} = \underline{Z}_{11} \cdot \underline{I}_{1} + \underline{Z}_{12} \cdot \underline{I}_{2} \implies \underline{U}_{1} = \underline{Z}_{11} \cdot \left(\frac{\underline{U}_{2}}{\underline{Z}_{21}} - \underline{Z}_{22} \cdot \underline{I}_{2}\right) + \underline{Z}_{12} \cdot \underline{I}_{2}$$

deci: 
$$\underline{U}_1 = \frac{\underline{Z}_{11}}{\underline{Z}_{21}} \cdot \underline{U}_2 - \frac{\underline{Z}_{11} \cdot \underline{Z}_{22} - \underline{Z}_{21} \cdot \underline{Z}_{12}}{\underline{Z}_{21}} \cdot \underline{I}_2 = \frac{\underline{Z}_{11}}{\underline{Z}_{21}} \cdot \underline{U}_2 - \frac{\Delta_Z}{\underline{Z}_{21}} \cdot \underline{I}_2$$

rezultă:

$$\underline{A} = \frac{\underline{Z}_{11}}{\underline{Z}_{21}}; \quad \underline{B} = -\frac{\Delta_{Z}}{\underline{Z}_{21}}$$

similar,

$$\underline{I}_1 = \frac{\underline{U}_2}{\underline{Z}_{21}} - \frac{\underline{Z}_{22}}{\underline{Z}_{21}} \cdot \underline{I}_2$$

$$\underline{C} = \frac{1}{\underline{Z}_{21}}; \qquad \underline{D} = -\frac{\underline{Z}_{22}}{\underline{Z}_{21}}$$

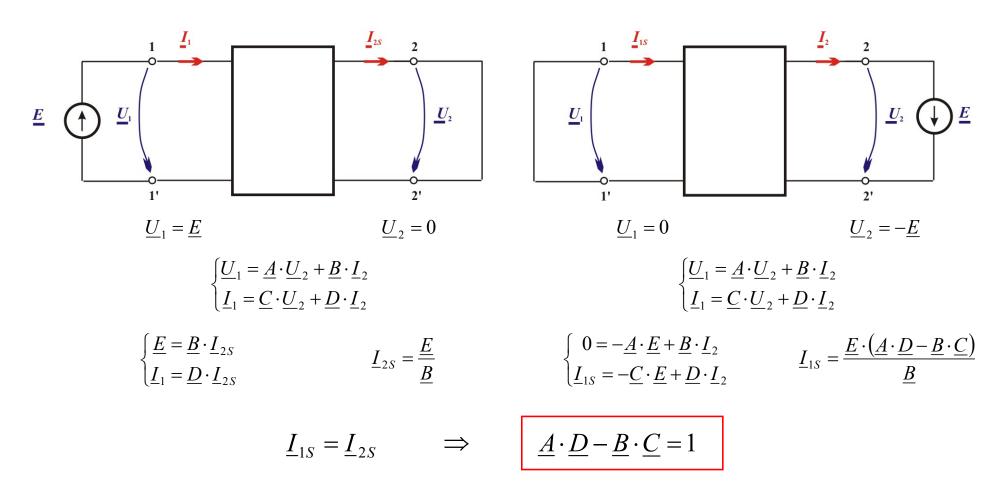
$$\underline{A} \cdot \underline{D} - \underline{B} \cdot \underline{C} = -\frac{\underline{Z}_{11}}{\underline{Z}_{21}} \cdot \frac{\underline{Z}_{22}}{\underline{Z}_{21}} + \frac{1}{\underline{Z}_{21}} \cdot \frac{\underline{Z}_{11} \cdot \underline{Z}_{22} - \underline{Z}_{21} \cdot \underline{Z}_{12}}{\underline{Z}_{21}} = -\frac{\underline{Z}_{12}}{\underline{Z}_{21}}$$

Dacă 
$$\underline{Z}_{12} = -\underline{Z}_{21}$$

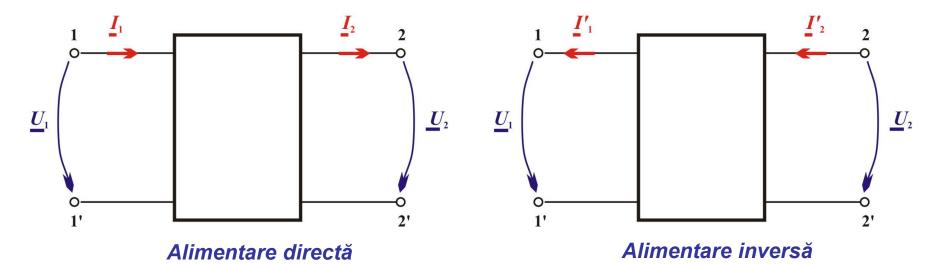
Dacă 
$$\underline{Z}_{12} = -\underline{Z}_{21}$$
 atunci  $\underline{A} \cdot \underline{D} - \underline{B} \cdot \underline{C} = 1$ 

# Teorema reciprocității

Un cuadripol este reciproc: Dacă se aplică o tensiune la una dintre porţi curentul de scurcircuit de la cealaltă poartă este acelaşi indiferent de poarta la care se aplică tensiunea. Condiţia este posibilă numai pentru cuadripoli pasivi.



# Teorema simetriei



$$\begin{cases} \underline{U}_1 = \underline{A} \cdot \underline{U}_2 + \underline{B} \cdot \underline{I}_2 \\ \underline{I}_1 = \underline{C} \cdot \underline{U}_2 + \underline{D} \cdot \underline{I}_2 \end{cases}$$

Se rezolvă sistemul considerând ca necunoscute  $\begin{cases} \underline{U}_2 = \underline{D} \cdot \underline{U}_1 - \underline{B} \cdot \underline{I}_1 \\ -I_2 = C \cdot U_1 - \underline{A} \cdot \underline{I}_1 \end{cases}$ <u>U</u><sub>2</sub> şi <u>I</u><sub>2</sub> :

$$\begin{cases} \underline{U}_2 = \underline{D} \cdot \underline{U}_1 - \underline{B} \cdot \underline{I}_1 \\ -\underline{I}_2 = \underline{C} \cdot \underline{U}_1 - \underline{A} \cdot \underline{I}_1 \end{cases}$$

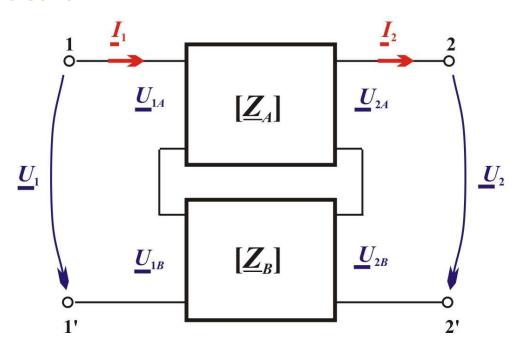
Pentru alimentare inversă rezultă sistemul:

$$\begin{cases} \underline{U}_2 = \underline{D} \cdot \underline{U}_1 + \underline{B} \cdot \underline{I}_1 \\ \underline{I}_2 = \underline{C} \cdot \underline{U}_1 + \underline{A} \cdot \underline{I}_1 \end{cases}$$

În cazul în care A = D coeficienții sistemului vor fi identici pentru alimentare inversă. Un cuadripol care îndeplinește condiția  $\underline{A} = \underline{D}$  este simetric.

## MODURI DE CONECTARE ALE CUADRIPOLILOR

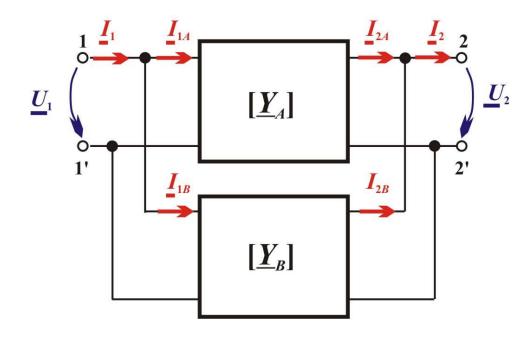
#### Conexiune serie-serie



$$\begin{bmatrix} \underline{U}_{1} \\ \underline{U}_{2} \end{bmatrix} = \begin{bmatrix} \underline{U}_{1A} + \underline{U}_{1B} \\ \underline{U}_{2A} + \underline{U}_{2B} \end{bmatrix} = \begin{bmatrix} \underline{U}_{1A} \\ \underline{U}_{2A} \end{bmatrix} + \begin{bmatrix} \underline{U}_{1B} \\ \underline{U}_{2B} \end{bmatrix} = [\underline{Z}_{A}] \cdot \begin{bmatrix} \underline{I}_{1} \\ \underline{I}_{2} \end{bmatrix} + [\underline{Z}_{B}] \cdot \begin{bmatrix} \underline{I}_{1} \\ \underline{I}_{2} \end{bmatrix} = ([\underline{Z}_{A}] + [\underline{Z}_{B}]) \cdot \begin{bmatrix} \underline{I}_{1} \\ \underline{I}_{2} \end{bmatrix}$$

$$\left[\underline{Z}_{ECHIVALENT}\right] = \left[\underline{Z}_{A}\right] + \left[\underline{Z}_{B}\right]$$

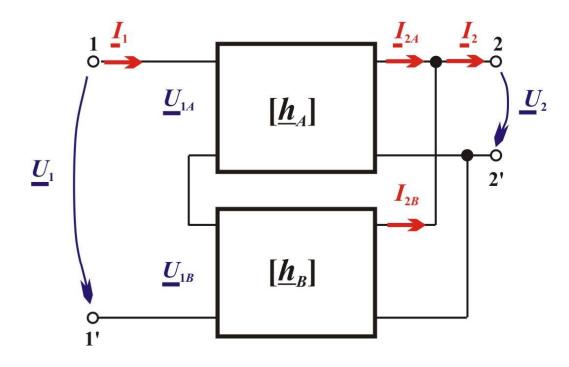
## **Conexiune paralel-paralel**



$$\begin{bmatrix} \underline{I}_{1} \\ \underline{I}_{2} \end{bmatrix} = \begin{bmatrix} \underline{I}_{1A} + \underline{I}_{1B} \\ \underline{I}_{2A} + \underline{I}_{2B} \end{bmatrix} = \begin{bmatrix} \underline{I}_{1A} \\ \underline{I}_{2A} \end{bmatrix} + \begin{bmatrix} \underline{I}_{1B} \\ \underline{I}_{2B} \end{bmatrix} = \begin{bmatrix} \underline{Y}_{A} \end{bmatrix} \cdot \begin{bmatrix} \underline{U}_{1} \\ \underline{U}_{2} \end{bmatrix} + \begin{bmatrix} \underline{Y}_{B} \end{bmatrix} \cdot \begin{bmatrix} \underline{U}_{1} \\ \underline{U}_{2} \end{bmatrix} = (\underbrace{Y}_{A}] + \underbrace{Y}_{B} \underbrace{)} \cdot \underbrace{\begin{bmatrix} \underline{U}_{1} \\ \underline{U}_{2} \end{bmatrix}}$$

$$\left[\underline{Y}_{ECHIVALENT}\right] = \left[\underline{Y}_{A}\right] + \left[\underline{Y}_{B}\right]$$

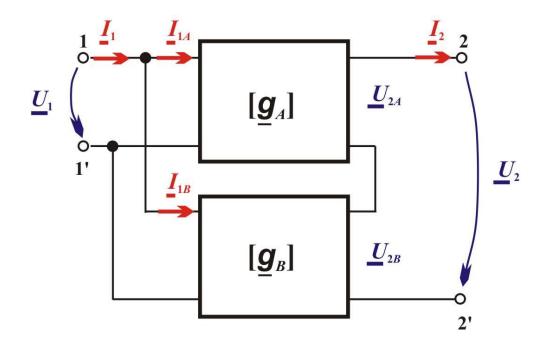
# **Conexiune serie-paralel**



$$\begin{bmatrix} \underline{U}_1 \\ \underline{I}_2 \end{bmatrix} = \begin{bmatrix} \underline{U}_{1A} + \underline{U}_{1B} \\ \underline{I}_{2A} + \underline{I}_{2B} \end{bmatrix} = \begin{bmatrix} \underline{U}_{1A} \\ \underline{I}_{2A} \end{bmatrix} + \begin{bmatrix} \underline{U}_{1B} \\ \underline{I}_{2B} \end{bmatrix} = [\underline{h}_A] \cdot \begin{bmatrix} \underline{I}_1 \\ \underline{U}_2 \end{bmatrix} + [\underline{h}_B] \cdot \begin{bmatrix} \underline{I}_1 \\ \underline{U}_2 \end{bmatrix} = ([\underline{h}_A] + [\underline{h}_B]) \cdot \begin{bmatrix} \underline{I}_1 \\ \underline{U}_2 \end{bmatrix}$$

$$[\underline{h}_{ECHIVALENT}] = [\underline{h}_A] + [\underline{h}_B]$$

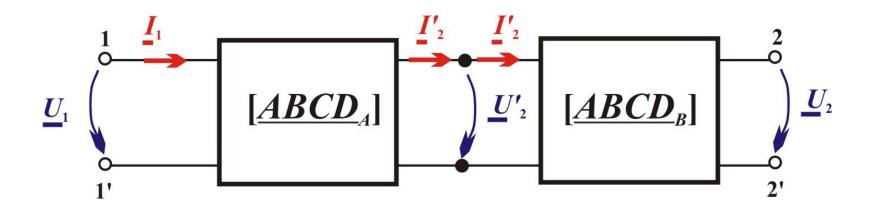
## **Conexiune paralel-serie**



$$\begin{bmatrix} \underline{I}_{1} \\ \underline{U}_{2} \end{bmatrix} = \begin{bmatrix} \underline{I}_{1A} + \underline{I}_{1B} \\ \underline{U}_{2A} + \underline{U}_{2B} \end{bmatrix} = \begin{bmatrix} \underline{I}_{1A} \\ \underline{U}_{2A} \end{bmatrix} + \begin{bmatrix} \underline{I}_{1B} \\ \underline{U}_{2B} \end{bmatrix} = \begin{bmatrix} \underline{g}_{A} \end{bmatrix} \cdot \begin{bmatrix} \underline{U}_{1} \\ \underline{I}_{2} \end{bmatrix} + \begin{bmatrix} \underline{g}_{B} \end{bmatrix} \cdot \begin{bmatrix} \underline{U}_{1} \\ \underline{I}_{2} \end{bmatrix} = (\underline{g}_{A}) + [\underline{g}_{B}] \cdot \begin{bmatrix} \underline{U}_{1} \\ \underline{I}_{2} \end{bmatrix}$$

$$\left[\underline{g}_{ECHIVALENT}\right] = \left[\underline{g}_{A}\right] + \left[\underline{g}_{B}\right]$$

## Conexiune în cascadă



$$\begin{bmatrix} \underline{U}_1 \\ \underline{I}_1 \end{bmatrix} = \begin{bmatrix} \underline{ABCD}_A \end{bmatrix} \cdot \begin{bmatrix} \underline{U}_2 \\ \underline{I}_2 \end{bmatrix} = \begin{bmatrix} \underline{ABCD}_A \end{bmatrix} \cdot \begin{bmatrix} \underline{ABCD}_B \end{bmatrix} \cdot \begin{bmatrix} \underline{U}_2 \\ \underline{I}_2 \end{bmatrix}$$

$$\left[\underline{ABCD}_{ECHIVALENT}\right] = \left[\underline{ABCD}_{A}\right] \cdot \left[\underline{ABCD}_{B}\right]$$

# Subjecte examen

- 1. Parametrii impedanţă Z: matrice, ecuatii.
- 2. Parametrii admitanţă, Y: matrice, ecuatii.
- 3. Parametrii hibrizi, h: matrice, ecuatii.
- 4. Parametrii hibrizi, g: matrice, ecuatii.
- 5. Cand un cuadripol este reciproc.
- 6. Cand un cuadripol este simetric.