# Infrared communication

# **Outline**

#### 1. Introduction

- a. What is the Infrared?
- b. How do the infrared receiver and emitter work?
- c. Infrared communication protocols
- d. IR communication advantages and disadvantages
- e. HRremote.h library

#### 2. Tutorials

- a. Tutorial 1: Receiving IR signals
- b. Tutorial 2: Emitter
- c. Tutorial 3: IR Chat

### 3. Conclusions

# Introduction

In 1800, <u>William Herschel</u> conducted an experiment measuring the difference in temperature between the colors.

Results showed an increase in temperature from blue to red.

Herschel discovered infrared light noticing an even warmer temperature measurement just beyond the red end of the visible spectrum.



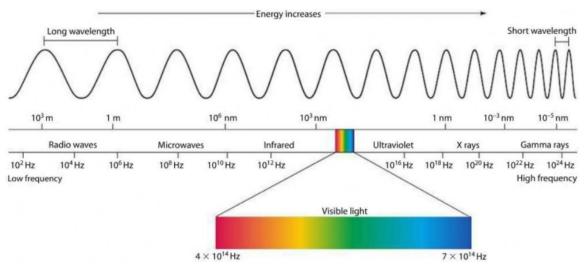
shorturl.at/iIS57

IR light corresponds to a range of the electromagnetic spectrum between 300 GHz to 400 THz.

Common natural sources are solar radiation and fire.

Common artificial sources are lamps and heating devices.

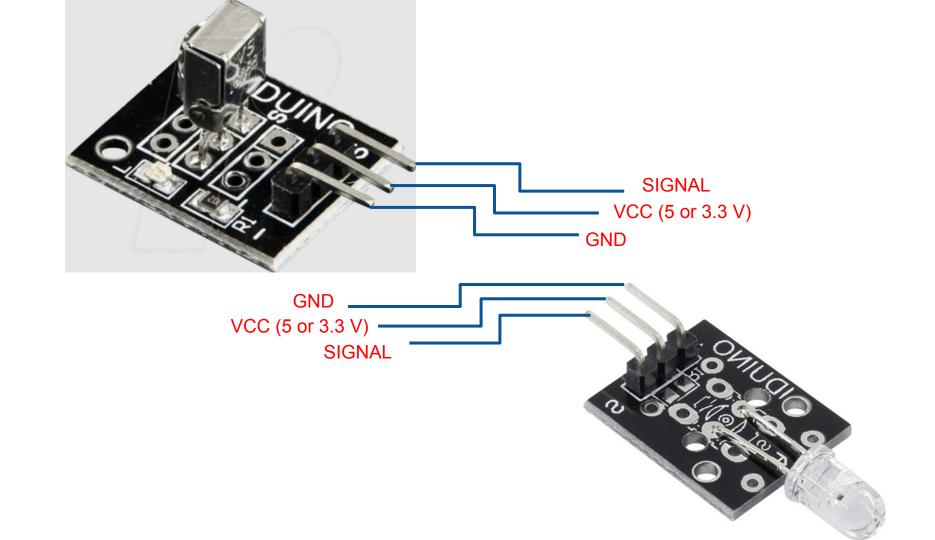
Which means that direct use of the IR receiving sensor may prove faulty if used directly outdoors without special filters.



shorturl.at/gtAQ8

# **Observations**

While working on how to combine the sender and the receiver we found that if both the sensors on the same breadboard are very close in proximity to each other, there is a danger of the signal to be intercepted by the same receiver.



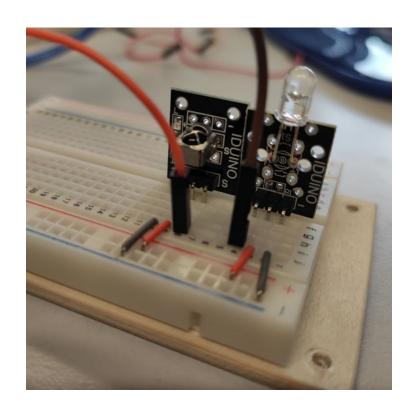
#### Tutorials followed

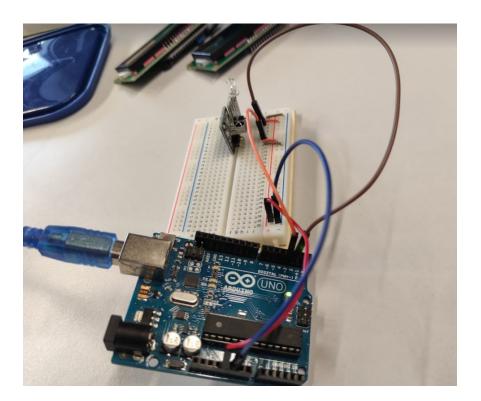
https://mschoeffler.com/2021/05/01/arduino-tutorial-ir-transmitter-and-ir-receiver-hx-m 121-hx-53-ky-005-ky-022-keyes-iduino-open-smart/

https://kogyikaunghtet.com/ir\_text/

#### **IRremote library**

https://arduino-irremote.github.io/Arduino-IRremote/classIRsend.html





# Receiver

```
#include <IRremote.h> // >v3.0.0
#define PIN RECV 5 // Pin connected to the IR receiver
void setup()
 Serial.begin(9600); //initialize serial connection to print on the Serial Monitor of the Arduino IDE
 IrReceiver.begin(PIN RECV); // Initializes the IR receiver object
void loop()
 if (IrReceiver.decode()) {
   Serial.println("Received something...");
   IrReceiver.printIRResultShort(&Serial); // Prints a summary of the received data. The command is received as HEX.
   Serial.println();
   Serial.println((char) IrReceiver.decodedIRData.command); // Converts the ASCII value received as command into a char and prints it.
   Serial.println();
    IrReceiver.resume(); // Important, enables to receive the next IR signal
```

```
#include <IRremote.h> // >v3.0.0
```

void loop()

```
#define PIN_RECV 5 // Pin connected to the IR receiver
```

```
void setup()
{
    Serial.begin(9600); //initialize serial connection to print on the Serial Monitor of the Arduino IDE
    IrReceiver.begin(PIN_RECV); // Initializes the IR receiver object
}
```

```
if (IrReceiver.decode()) {
    Serial.println("Received something...");
    IrReceiver.printIRResultShort(&Serial); // Prints a summary of the received data. The command is received as HEX.
    Serial.println();
    Serial.println((char) IrReceiver.decodedIRData.command); // Converts the ASCII value received as command into a char and prints Serial.println();
    IrReceiver.resume(); // Important, enables to receive the next IR signal
}
```

# Sender

```
#include <IRremote.h> // >v3.0.0
#define PIN SEND 6 // Pin connected to the IR emitter
char input;
void setup()
 IrSender.begin(PIN SEND); // Initializes IR sender
 Serial.begin(9600);
 delay(1000);
 Serial.println("Type something!");
void loop()
   if(Serial.available()){ // Checks if something is written in the serial monitor
       input = Serial.read();
       Serial.print("You typed: " );
       Serial.println(input);
       IrSender.sendNEC(0xFE01D6DE, "abcd", 0); // the address 0xFE01D6DE with the command input and 0 repetitions is sent.
 delay(1000); // wait for one second
```

# Sender

```
#include <IRremote.h> // >v3.0.0

#define PIN_SEND 6 // Pin connected to the IR emitter
char input;
```

```
void setup()
{
   IrSender.begin(PIN_SEND); // Initializes IR sender
   Serial.begin(9600);
   delay(1000);
   Serial.println("Type something!");
}
```

```
void loop()
{

    if(Serial.available()){ // Checks if something is written in the serial monitor
        input = Serial.read();
        Serial.print("You typed: ");
        Serial.println(input);
        IrSender.sendNEC(0xFE01D6DE, "abcd", 0); // the address 0xFE01D6DE with the command input and 0 repetitions is sent.
    }
    delay(1000); // wait for one second
}
```

# Receiver + Sender

```
#include <IRremote.h> // >v3.0.0 | tested on v3.9.0
     #define PIN RECV 3 // Pin connected to the IR receiver
     #define PIN SEND 2 // Pin connected to the IR emitter
     char input; // Related to the emitter
     const uint16 t MY ADDRESS = 0xAAAA; // Addresses must be different from the other emitter-receiver
 8
     void setup() {
       // START CODE FOR THE RECEIVER
11
12
         Serial.begin(9600); //initialize serial connection to print on the Serial Monitor of the Arduino IDE
13
         IrReceiver.begin(PIN RECV); // Initializes the IR receiver object
       // END CODE OF THE RECEIVER
15
      // START CODE FOR THE SENDER
17
       IrSender.begin(PIN SEND); // Initializes IR sender
       delay(1000);
19
       Serial.println("Type something!");
      // END CODE FOR THE SENDER
21
```

```
// START CODE FOR THE RECEIVER
 if (IrReceiver.decode()) {
  if(!IrReceiver.decodedIRData.address == MY ADDRESS){
    Serial.println("Received something...");
    IrReceiver.printIRResultShort(&Serial); // Prints a summary of the received data. The command is received as HEX.
    Serial.println();
    Serial.println((char) IrReceiver.decodedIRData.command); // Converts the ASCII value received as command into a char and prints it.
  Serial.println();
  IrReceiver.resume(); // Important, enables to receive the next IR signal
// END CODE OF THE RECEIVER
  if(Serial.available()){ // Checks if something is written in the serial monitor
    input = Serial.read();
    Serial.print("You typed: " );
    Serial.println(input);
    IrSender.sendNEC(MY ADDRESS, input, 0); // the address 0xFE01D6DE with the command input and 0 repetitions is sent.
delay(50); // wait for one second
```

void loop() {

// END CODE FOR THE SENDER

# LCD without I2C

```
// include the library code:
#include <LiquidCrystal.h>
// initialize the library by associating any needed LCD interface pin
// with the arduino pin number it is connected to
const int rs = 7, en = 6, d4 = 5, d5 = 4, d6 = 3, d7 = 2;
LiquidCrystal lcd(rs, en, d4, d5, d6, d7);
void setup() {
 // set up the LCD's number of columns and rows:
 lcd.begin(16, 2);
 // Print a message to the LCD.
  lcd.print("hello, world!");
void loop() {
 // set the cursor to column 0, line 1
 // (note: line 1 is the second row, since counting begins with 0):
  lcd.setCursor(0, 1);
  // print the number of seconds since reset:
  lcd.print(millis() / 1000);
```

```
The circuit:
* LCD RS pin to digital pin 7
* LCD Enable pin to digital pin 6
* LCD D4 pin to digital pin 5
* LCD D5 pin to digital pin 4
* LCD D6 pin to digital pin 3
* LCD D7 pin to digital pin 2
* LCD R/W pin to ground
* LCD VSS pin to ground
* LCD VCC pin to 5V
* 10K resistor:
* ends to +5V and ground
* wiper to LCD VO pin (pin 3)
```

# LCD with I2C

```
void loop() {
    // Print 'Hello World!' on the first line of the LCD:
    lcd.setCursor(0, 0); // Set the cursor on the first column and first row.
    lcd.print("Hello Sandro!"); // Print the string "Hello World!"

lcd.setCursor(0, 1); //Set the cursor on the first column and the second row (counting starts at 0!).
lcd.print("This Works!");
```