

Tudor Vlăduț-Alexandru

## ***Problema 9***

### ***Algoritmul lui Graham***

\*Bonus: Țin să menționez că am fost prezent la activitatea cu numărul 3 – Atelierul Google.

***Rulajul:***

```
Output - problema9 (run) ×  
  
▶▶ Functele care formeaza poligonul sunt:  
▶▶ Point2D.Double[-5.0, 0.0]  
▶▶ Point2D.Double[0.0, 5.0]  
▶▶ Point2D.Double[5.0, 0.0]  
▶▶ Point2D.Double[0.0, -5.0]  
BUILD SUCCESSFUL (total time: 0 seconds)
```

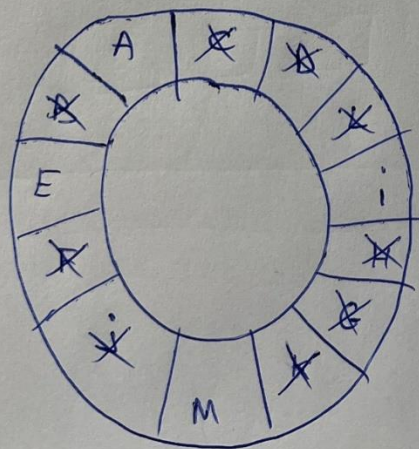
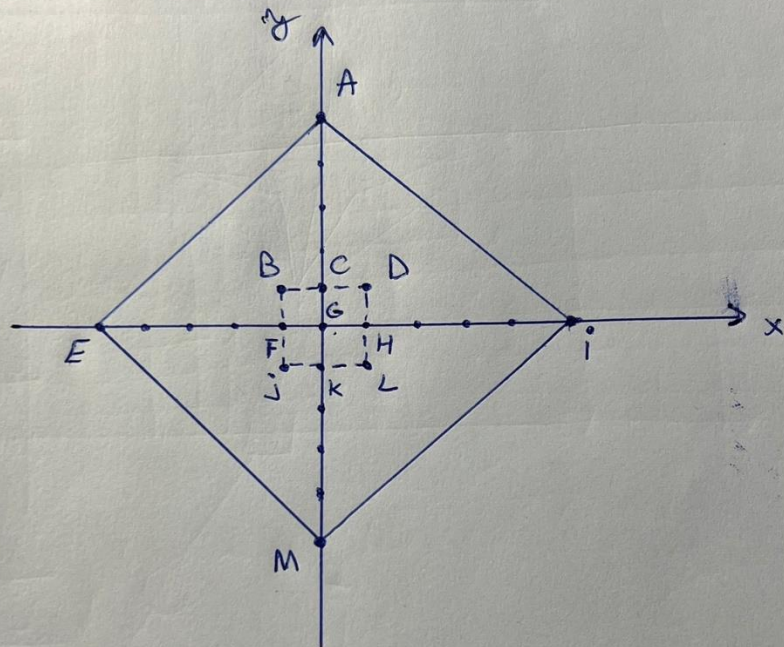
Pe foaie:

Problema 9

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Cerintă: Se dau puncte aleatorii în sistemul de axe  $xOy$ . Se implementează algoritmul lui Graham.

Exemplu:



## Implementare Java:

```
package problema9;
import java.awt.geom.Point2D;
import java.util.*;
public class Problema9 {
    public static Stack<Point2D> crearePoligon(Point2D[] pts) {
        int k1, k2, N = pts.length;
        Stack<Point2D> hull = new Stack<Point2D>();
        Arrays.sort(a:pts, new PointOrder());
        Arrays.sort(a:pts, fromIndex:1, toIndex:N, new PolarOrder(pts[0]));
        hull.push(pts[0]);
        for (k1 = 1; k1 < N; k1++) {
            if (!pts[0].equals(pts[k1])) {
                break;
            }
        }
        if (k1 == N)
            return null;
        for (k2 = k1 + 1; k2 < N; k2++) {
            if (collinear(pts[0], pts[k1], pts[k2]) != 0) {
                break;
            }
        }
        hull.push(pts[k2 - 1]);
        for (int i = k2; i < N; i++) {
            Point2D top = hull.pop();
            while (collinear(a:hull.peek(), b:top, pts[i]) <= 0) {
                top = hull.pop();
            }
            hull.push(item:top);
            hull.push(pts[i]);
        }
        return hull;
    }
}
```

```

private static class PolarOrder implements Comparator<Point2D> {
    Point2D pt;
    public PolarOrder(Point2D pt) {
        this.pt = pt;
    }
    @Override
    public int compare(Point2D q1, Point2D q2) {
        double dx1 = q1.getX() - pt.getX(), dy1 = q1.getY() - pt.getY();
        double dx2 = q2.getX() - pt.getX(), dy2 = q2.getY() - pt.getY();
        if (dy1 >= 0 && dy2 < 0)
            return -1;
        else if (dy2 >= 0 && dy1 < 0)
            return +1;
        else if (dy1 == 0 && dy2 == 0) {
            if (dx1 >= 0 && dx2 < 0)
                return -1;
            else if (dx2 >= 0 && dx1 < 0)
                return +1;
            else
                return 0;
        }
        else return -collinear(a:pt, b:q1, c:q2);
    }
}

private static class PointOrder implements Comparator<Point2D> {
    @Override
    public int compare(Point2D q1, Point2D q2) {
        if (q1.getY() < q2.getY())
            return -1;
        if (q1.getY() == q2.getY()) {
            if (q1.getX() < q2.getX())
                return -1;
            else if (q1.getX() > q2.getX())
                return 1;
            else
                return 0;
        }
        return 1;
    }
}

private static int collinear(Point2D a, Point2D b, Point2D c) {
    double area = (b.getX() - a.getX()) * (c.getY() - a.getY()) - (b.getY() - a.getY()) * (c.getX() - a.getX());
    return (int) Math.signum(d:area);
}

```

```

public static void main(String[] args) {

    Point2D[] pts = new Point2D[13];

    pts[0] = new Point2D.Double( x:0, y:5);
    pts[1] = new Point2D.Double( x:-1, y:1);
    pts[2] = new Point2D.Double( x:0, y:1);
    pts[3] = new Point2D.Double( x:1, y:1);
    pts[4] = new Point2D.Double( x:-5, y:0);
    pts[5] = new Point2D.Double( x:-1, y:0);
    pts[6] = new Point2D.Double( x:0, y:0);
    pts[7] = new Point2D.Double( x:1, y:0);
    pts[8] = new Point2D.Double( x:5, y:0);
    pts[9] = new Point2D.Double( x:-1, y:-1);
    pts[10] = new Point2D.Double( x:0, y:-1);
    pts[11] = new Point2D.Double( x:1, y:-1);
    pts[12] = new Point2D.Double( x:0, y:-5);

    Stack<Point2D> hull = createPoligon(pts);
    System.out.println( x:"Punctele care formeaza poligonul sunt:");
    while (!hull.isEmpty())
        System.out.println( x:hull.pop());
    }
}

```