



Politecnico di Torino

Dipartimento di Elettronica e Telecomunicazioni

Laboratory #1

Integrated Systems Architecture

Design and Implementation of a Digital Filter

Master Degree in Electronic Engineering

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1 Setting up

First of all, filter order N and the bit-width n_b corresponding to group number and group participants must be computed, using the following equations:

$$N = 2^p [(x \bmod 2) + 1] + 6p \quad (1)$$

$$n_b = (y \bmod 7) + 8 \quad (2)$$

The parameters are $x = 6$ (from Aimaro) and $y = 9$ (from Bussolino), with $p = 1$ (since the group is the first one so it is in odd position). The final results are $N = 8$ and $n_b = 10$, with the filter to be designed being a Finite-Impulse-Response filter. Resulting coefficients are:

$$[-4 \quad -7 \quad 26 \quad 136 \quad 207 \quad 136 \quad 26 \quad -7 \quad -4]$$

Firstly, the filter is modeled using provided MATLAB and C codes, as described in the next section.

2 MATLAB/C Models for the Filter

Given codes are used as a basis to develop specific models, which are presented in the appendices.

C code is adapted to handle overflow, that doesn't happen when working with 32-bits integers but must be taken into account to correctly dimension adders of the filter.

Number are represented in Q1.9 format; when performing a multiplication, the result is in Q1.18 format and must be right-shifted of 9 positions ($n_b - 1$) to restore original representation.

Performing nine sums using 10-bits numbers that can assume any value in possible range, it is necessary to add four bits to avoid overflow. However, using C model with worst case inputs (all samples equal to 511/-512), it is find out that a 1-bit extension is sufficient to handle overflow. In C model, 32-bits integer are used, therefore no sign extension needs to be specified; however, final result must be right shifted of one position and truncated to be representable on 10 bits.

```

1  /// shift and insert new sample in x shift register
2  for (i=NT-1; i>0; i--)
3  sx[i] = sx[i-1];
4  sx[0] = x;
5
6  /// make the convolution
7  /// Moving average part
8  y = 0;
9  for (i=0; i<NT; i++)
10 y += (sx[i]*b[i]) >> (NB-1) ;
11
12 /// update the y shift register
13 for (i=NT-2; i>0; i--)
14 sy[i] = sy[i-1];
15 sy[0] = y;
16
17 return y>>1;

```

Reported code represents the behavior of the filter. At line 10 results of multiplication are shifted of $n_b-1=9$ positions. At line 17, returned result is shifted of one position, to handle overflow.

3 VHDL Implementation of the FIR Filter

3.1 Design

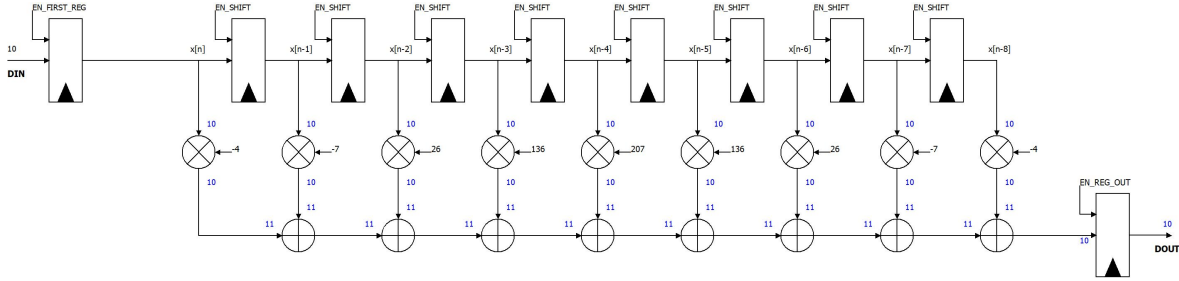


Figure 1: Base architecture for FIR filter of order 8 with 10 bits signals

After checking all the results given by C model, the hardware architecture for the filter is implemented, following a standard FIR architecture. A Control Unit is included in the project to control the flow of the filter, mostly forecasting its use in the optimized architecture.

In VHDL description of filter:

- A bank of registers is instantiated; these registers have a synchronous reset, to avoid glitch-related problems.
- Signals are instantiated of SIGNED type, to easily handle sums and multiplications. In *numeric_std* library, the output of a multiplication between two numbers of length N is represented with 2N bits. However, since numbers are in Q1.9 format, only 2N-1 least significant bits can be used to correctly represent the result. Therefore, the most significant bit can be eliminated and then the result can be right shifted to return to Q1.9 representation (N-1 least significant bits truncated);
- As explained in previous section, one single guard bit is necessary to avoid overflows. Adding this bit is implemented practically by not removing the most significant bit after multiplication.
- Output samples, before output register, must then be right shifted of one position (least significant bit truncated) to return the result with 10 bits. In figure, the numbers of bits used are represented in blue.
- Input and output registers are introduced to synchronize the filter with external world; they introduce a delay of two clock cycles.

In Figure 2 is shown the connection between the filter and its control unit.

In Figure 3 is reported the ASM chart of the control unit. In IDLE state, input register is update with new values at each clock cycle, while registers of the shift array keep old values. If input data is valid (VIN=1), then output register and registers of the array are updated (DATA_CYCLE1). In the next clock cycle, data is valid in output and VOUT is asserted. After DATA_CYCLE1, the control unit moves to LAST_DATA1 if there are no other data to process and then returns in idle or to DATA_CYCLE2 if there are new values.

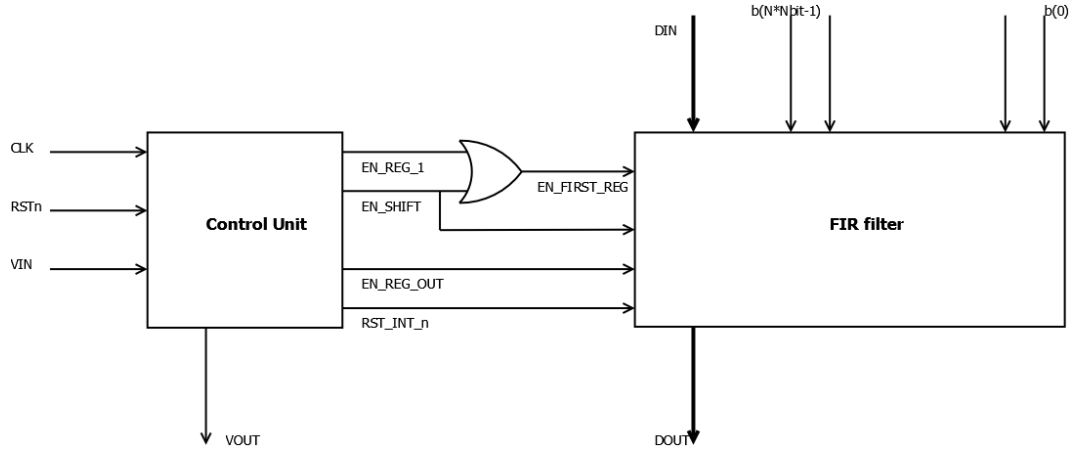


Figure 2: Control Unit and FIR Filter

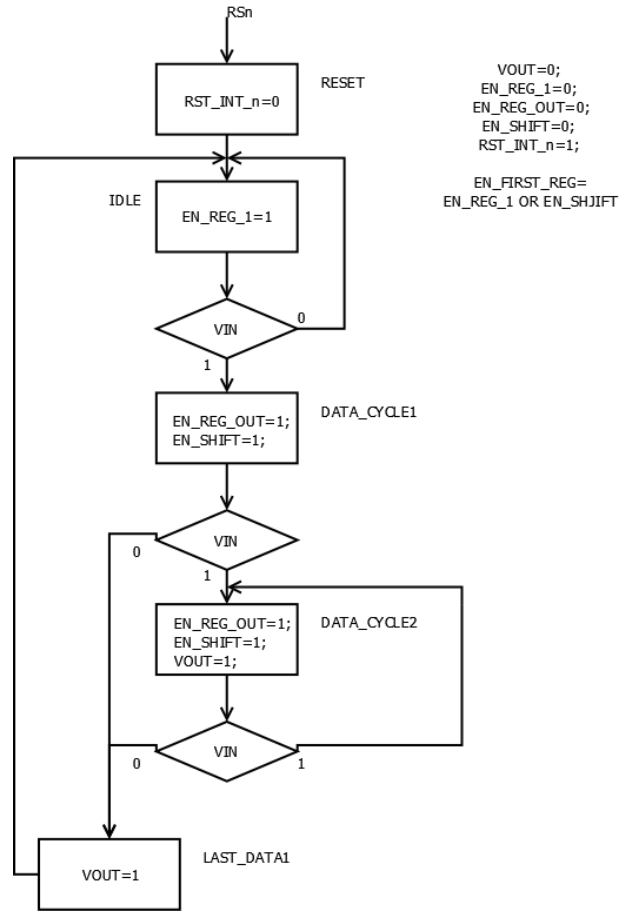


Figure 3: ASM chart of FIR filter control unit

3.2 Physical Implementation

3.2.1 Synthesis

After checking the correctness of the simulation, the architecture is synthesized with the 70nm cells present in the Nangate Open Cell Library. Initially, target period is set to 0ns to find the maximum

achievable frequency. Then many other synthesis are repeated increasing target period until finding a slack time equal to zero (Figure 4). In Table 1 maximum frequency is reported with corresponding cell area.

data required time	2.85
data arrival time	-2.85
slack (MET)	0.00

Figure 4: Slack time equal to 0 met

		Area
T_{min}	2.96ns	5157.739746 μm^2
f_{max}	337.84MHz	
$4 \cdot T_{min}$	11.84ns	4889.080078 μm^2
$f_{max}/4$	84.46MHz	

Table 1: Maximum frequency achievable and corresponding cell area; maximum frequency divided by four and corresponding cell area

Frequency is then set at $f_{max}/4$; again, obtained area of the cell is reported in Table 1. As expected, the area of the cell with target frequency f_{max} is larger, as the synthesizer needs to do more optimizations to respect the imposed limit.

After synthesis, it is possible to obtain an estimation of power consumption of the cell.

Cell Internal Power	=	278.0258 uW	(55%)
Net Switching Power	=	229.0841 uW	(45%)
Total Dynamic Power	=	507.1099 uW	(100%)
Cell Leakage Power	=	113.0839 uW	

Figure 5: Obtained power report at $f = f_{max}/4$

3.2.2 Place and Route

The filter is placed and routed with Cadence SOC Innovus with $f = f_{max}/4$ and the resulting area is 4879.5 μm^2 (Figure 6).

The behavior of the filter is then tested including the delay file (.sdf file) generated by Cadence Innovus: power report obtained is shown in Figure 7 (power units: mW).

3.3 Simulation

To the testbench model provided in course material, a section is added to test also the start-stop behavior depending on the input signal VIN. The signal generator is modified too, to better fit the specific design, but the final result is the same.

The differences between provided signal generator and the modified version consist in how data are processed. In the modified signal generator there is a process which runs through all the data to

```

Gate area 0.7980 um^2

Level 0 Module FIR_filter

Gates=      6114
Cells=      3592
Area=       4879.5 um^2

```

Figure 6: Obtained area after place & route

```

Total Power
-----
Total Internal Power:    0.68929791    48.7703%
Total Switching Power:  0.61138734    43.2579%
Total Leakage Power:    0.11267000     7.9718%
Total Power:            1.41335525
-----

```

Figure 7: Obtained power report at $f = f_{max}/4$, after place and route

be sent as input to the Unit Under Test and saves them, while the other one sends the data following the standard pattern and ending the simulation once it is done. In `data_maker_new` instead there is a process reading and sending all the data to the UUT at run-time, while the other process is used to correctly end the simulation.

The only encountered problem was related to matching the Verilog connections in the top test-bench, because Verilog does not allow custom types; thus, all the custom connections for coefficients (at the beginning written as an array of `std_logic_vector`) and input/output had to be converted to single long `std_logic_vector` and multiplexed inside the components.

Three simulations are performed:

1. Behavioral simulation
2. Post synthesis simulation
3. Post place and route simulation

All produced results are compared with those generated by C model. The correctness of simulations can be checked from Figure 8.

In Figure 9 it is possible to see that the latency is of one clock cycle, while the throughput is 1 data/cycle.

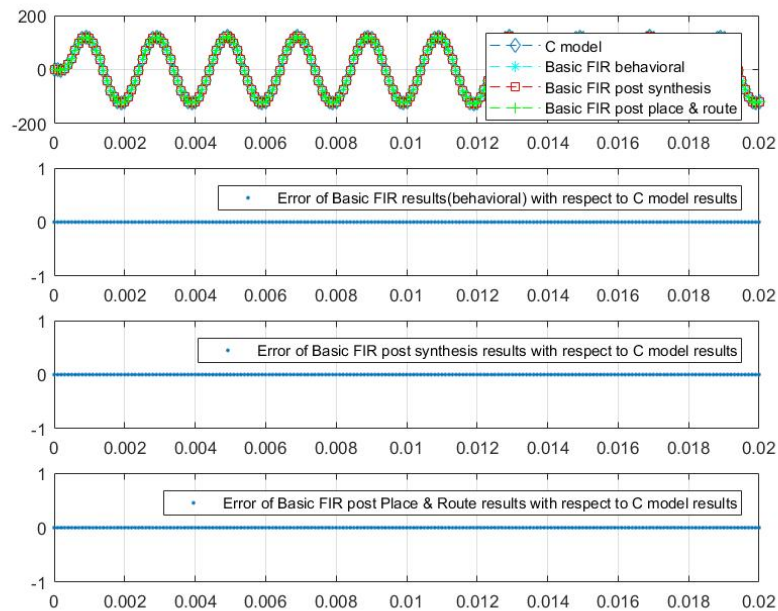


Figure 8: Top: The results from C model and from the three simulations are plotted together, to show their equality; Bottom: the three bottom plots show the error between simulation results and C model results

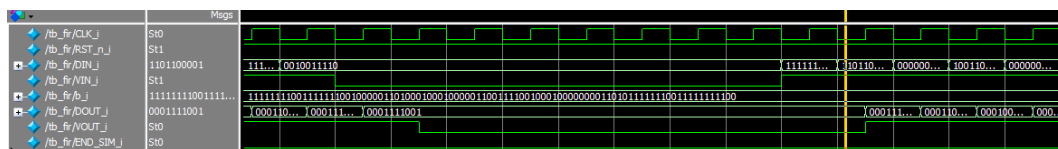


Figure 9: Some simulation signals from behavioral simulation, showing the start-stop behavior and the latency.

4 Optimization of designed Filter

4.1 Design

FIR filter is optimized with unfolding and pipelining, to improve both throughput and maximum frequency at the expense of higher area, caused by replication of the architecture and insertion of registers to split critical paths.

The system is unfolded with order 3; firstly, the architecture is replicated, then these relations are applied:

$$j = \text{mod} \left(\frac{i + w}{P} \right) \quad (3)$$

$$w_i = \left\lfloor \frac{i + w}{P} \right\rfloor \quad (4)$$

where i is the starting copy of the graph (in this case 0, 1 or 2), j is the arrival copy, w is the number of registers present on the original arc and P is the unfolding order, in particular 3. Following these expressions, for each arc connecting two nodes (which are the operators plus inputs and outputs) a new arc for each copy (i from 0 to 2) is generated. The final structure can be seen in Figure 10.

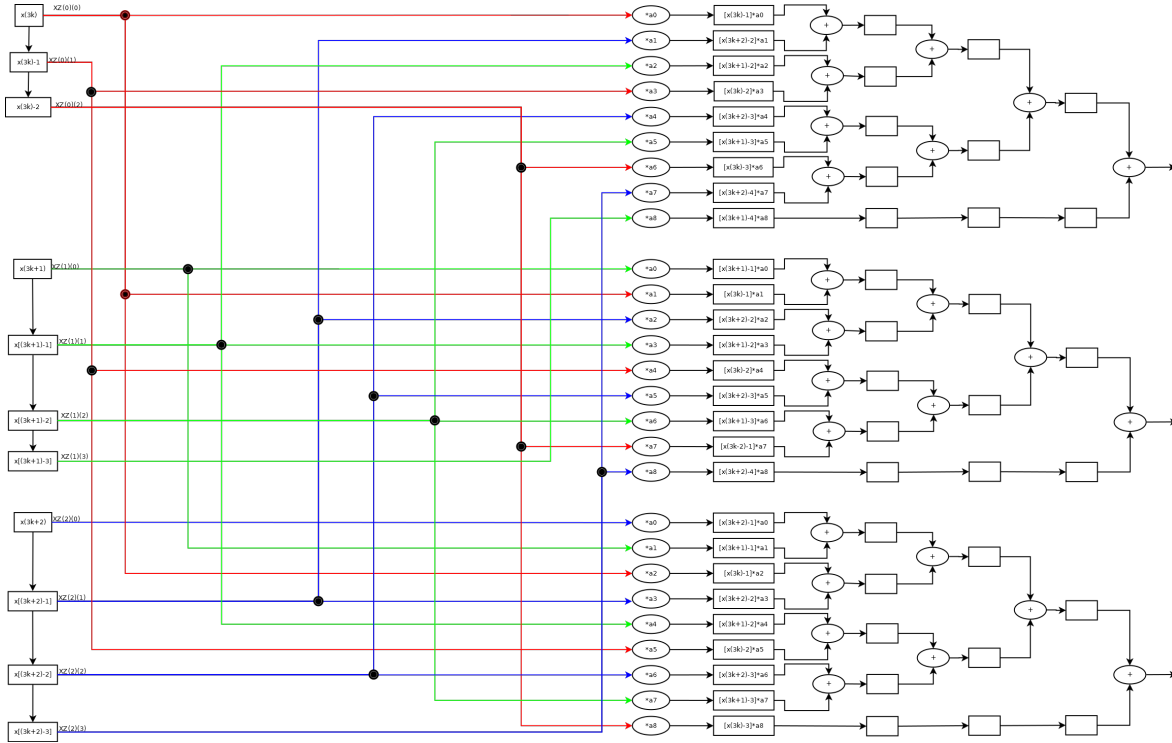


Figure 10: Final scheme of FIR filter after unfolding

After properly connecting the whole architecture, pipeline registers can be added. Adding registers to the standard FIR graph is not very useful: a possibility would be splitting all the cascaded sums in different clock cycles but the result would be only an increased area consumption, without improving performances, that are mostly limited by the multipliers. In fact, it is found out that the delay of 1 multiplier is roughly equal to that of 7/8 adders.

Thus a slightly different architecture is tested, a tree structure with all the multiplications in parallel in the first cycle, then four additions in parallel, later only two and then two final stages

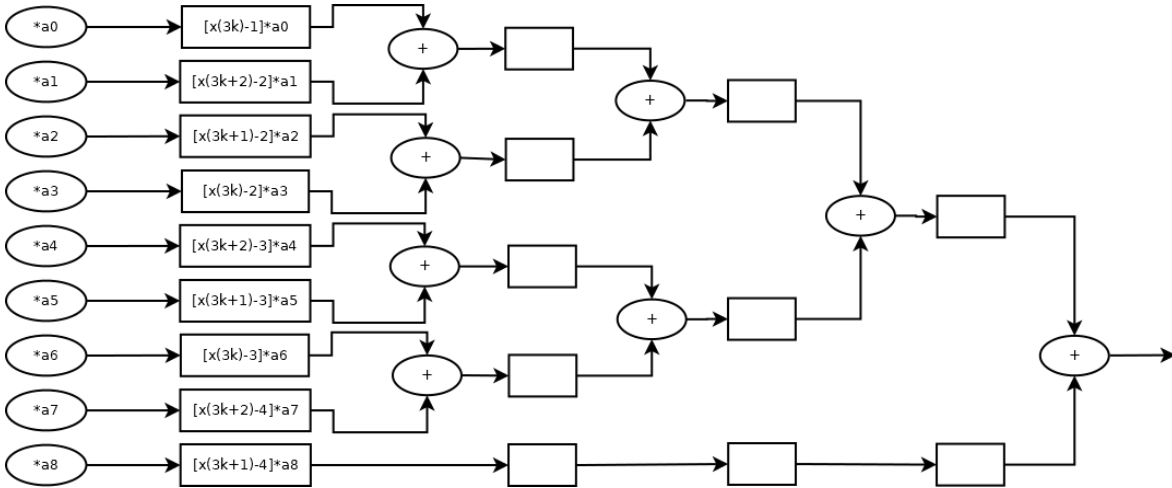


Figure 11: Final scheme of FIR filter after unfolding - zoom on computation elements

with one sum each, the last one needed to add the ninth term. The stages are in-between each two operands, to maximize performances at cost of more latency and slightly more area. However, the improvement should be bounded by the presence of multipliers also in this case.

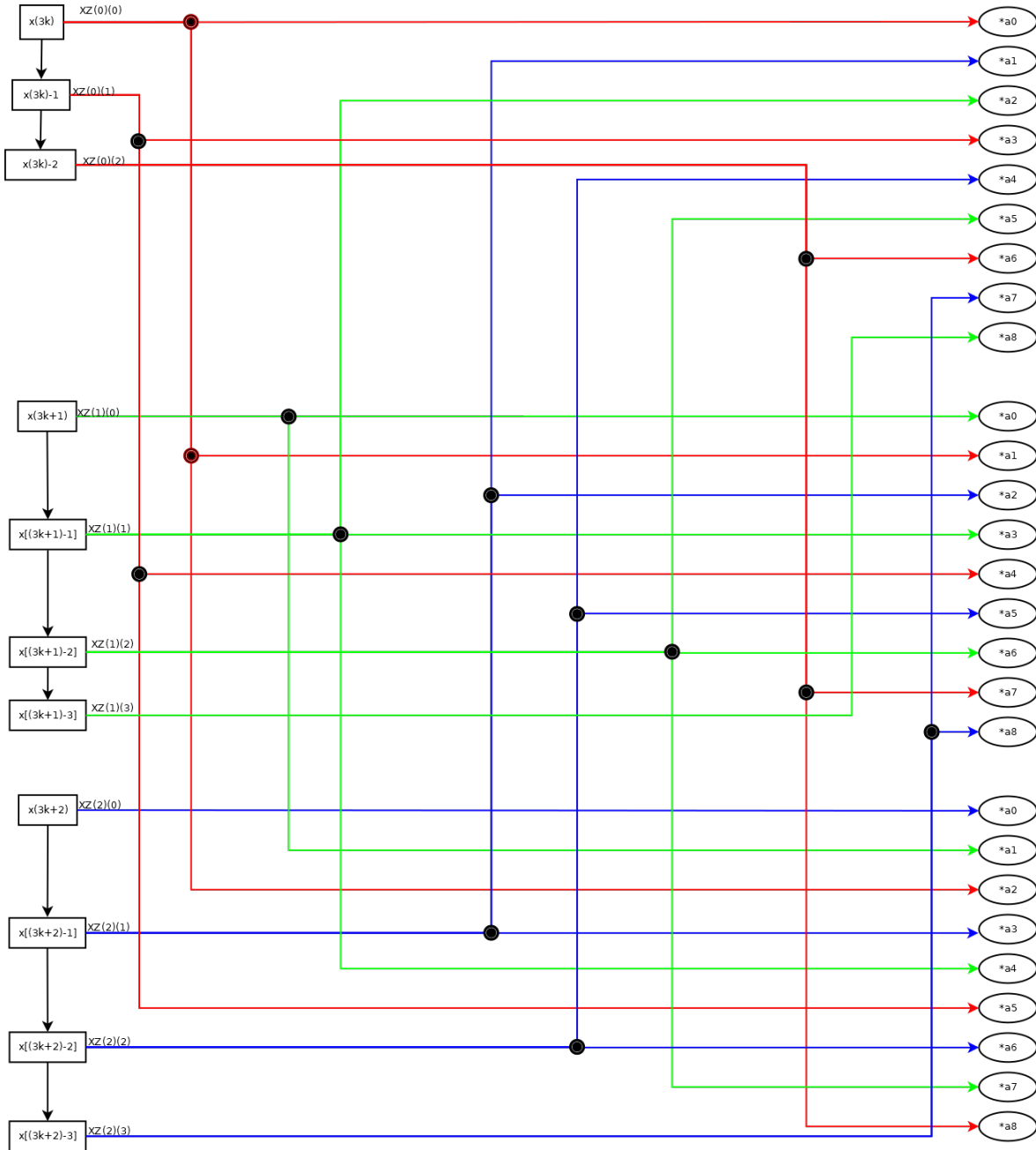


Figure 12: Final scheme of FIR filter after unfolding - zoom on interconnections

4.2 Physical Implementation

4.2.1 Synthesis

After checking the correctness of the behavioral simulation, the architecture is synthesized with the same technology used for unoptimized design (70nm cells present in the Nangate Open Cell Library). Again, target period is set to 0ns to find the maximum achievable frequency and then increased until finding a slack time equal to zero. In Table 1 maximum frequency is reported with corresponding cell area.

		Area
T_{min}	2ns	18444.173828 μm^2
f_{max}	500MHz	
$4 \cdot T_{min}$	8ns	18244.408203 μm^2
$f_{max}/4$	125MHz	

Table 2: Maximum frequency achievable and corresponding cell area; maximum frequency divided by four and corresponding cell area

Frequency is then set at $f_{max}/4$; again, obtained area of the cell is reported in Table 2. As for unoptimized design, a lower target frequency implies a smaller area.

The after synthesis power estimation is here reported:

Cell Internal Power	=	1.7219 mW	(58%)
Net Switching Power	=	1.2622 mW	(42%)

Total Dynamic Power	=	2.9841 mW	(100%)
Cell Leakage Power	=	421.1755 uW	

Figure 13: Obtained power report at $f = f_{max}/4$

4.2.2 Place And Route

The filter is placed and routed with Cadence SOC Innovus with $f = f_{max}/4$ and the resulting area is 18043.0 μm^2 (Figure 14).

Gate area	0.7980 μm^2
Level 0 Module	FIR_filter
Gates=	22610
Cells=	12591
Area=	18043.0 μm^2

Figure 14: Obtained power report at $f = f_{max}/4$

The behavior of the filter is then tested including the delay file (.sdf file) generated by Cadence Innovus: power report obtained is shown in Figure 15 (power units: mW).

Total Power		

Total Internal Power:	3.39771481	51.4597%
Total Switching Power:	2.79317273	42.3036%
Total Leakage Power:	0.41178826	6.2367%
Total Power:	6.60267580	

Figure 15: Obtained power report at $f = f_{max}/4$, after place and route

4.3 Simulation

The simulation for the new architecture is very similar to the previous one, but three inputs and three outputs at a time are used, in the correct order.

Three simulations are performed: behavioral, after synthesis and after place and route. As for the basic filter, the results are compared with those produced by the C model and the equality is checked (Figure 16).

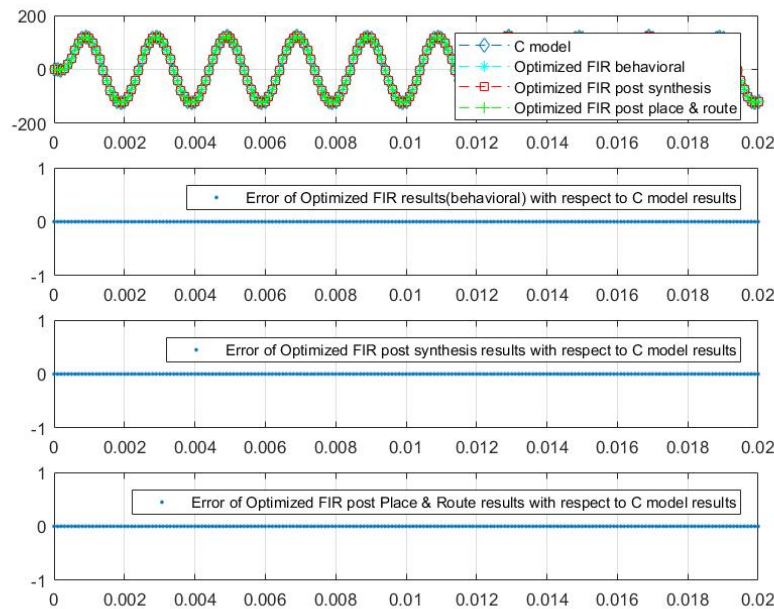


Figure 16: Top: The results from C model and from the three simulations are plotted together, to show their equality; Bottom: the three bottom plots show the error between simulation results and C model results

5 Comparison of optimized and un-optimized designs

In Table 3 is reported a comparison between the Basic FIR and its successive optimization. The unfolding of level three leads to a throughput three times higher and the pipelining allows to increase the maximum clock frequency. However, the critical path of the design is in the multipliers.

To unfold the system, the original architecture is triplicated and this explains the increase of area and power. The increase of dynamic power is associated also to the higher frequency.

	Basic FIR	Optimized FIR
T_{min}	2.96 ns	2 ns
f_{max}	337.84MHz	500MHz
$4 T_{min}$	11.84 ns	8 ns
$f_{max}/4$	84.46MHz	125MHz
Throughput	1	3
Synthesis		
Area	4889.080078 μm^2	18244.408203 μm^2
Internal Power	278.0258 μW	1.7219 mW
Switching Power	229.0841 μW	1.2622 mW
Total Dynamic Power	507.1099 μW	2.9841 mW
Leakage Power	113.0839 μW	421.1755 μW
Total Power	620.1938 μW	3.4053 mW
Place and Route		
Area	4879.5 μm^2	18043.0 μm^2
Internal Power	689.29791 μW	3.39771 mW
Switching Power	611.38734 μW	2.79317 mW
Leakage Power	112.67000 μW	0.41179 mW
Total Power	1.41336 mW	6.60268 mW

Table 3: Comparison between Basic FIR and Optimized FIR

Appendices

Models

These are the models of the filter in MATLAB and C languages.

MATLAB code

./code/models/my_fir_filter.m

```

1 fs=10000 %% sampling frequency
2 f1=500; %% first sinewave freq (in band)
3 f2=4500; %% second sinewave freq (out band)
4
5 N=8; %% filter order
6 nb=10; %% number of bits
7
8 T=1/500; %% maximum period
9 tt=0:1/fs:10*T; %% time samples
10
11 x1=sin(2*pi*f1*tt); %% first sinewave
12 x2=sin(2*pi*f2*tt); %% second sinewave
13
14 x=(x1+x2)/2; %% input signal
15
16 [bi, bq]=myfir_design(N, nb); %% filter design
17
18 y=filter(bq, 1, x); %% apply filter
19
20 %% plots
21 figure
22 plot(tt, x1, '—d');
23 hold on
24 plot(tt, x2, 'r—s');
25 plot(tt, x, 'g—+');
26 plot(tt, y, 'c—o');
27
28 legend('x1', 'x2', 'x', 'y')
29
30 %% quantize input and output
31 xq=floor(x*2^(nb));
32 idx=find(xq==2^(nb));
33 xq(idx)=2^(nb)-1;
34
35 yq=floor(y*2^(nb));
36 idy=find(yq==2^(nb));
37 yq(idy)=2^(nb)-1;
38
39 %% save input and output
40 fp=fopen('samples.txt', 'w');
41 fprintf(fp, '%d\n', xq);
42 fclose(fp);
43
44 fp=fopen('resultsm.txt', 'w');
45 fprintf(fp, '%d\n', yq);
46 fclose(fp);

```

C code

./code/models/my_fir.c

```

1 #include<stdio.h>
2 #include<stdlib.h>
3
4 #define NT 9 /// number of coeffs
5 #define NB 10 /// number of bits
6
7 const int b[NT]={-4, -7, 26, 136, 207, 136, 26, -7, -4}; /// b array
8 //const int a[NT-1]={-147, 52}; /// a array
9
10 /// Perform fixed point filtering assming direct form I
11 ///\param x is the new input sample
12 ///\return the new output sample
13 int myfilter(int x)
14 {
15     static int sx[NT]; /// x shift register
16     static int sy[NT-1]; /// y shift register
17     static int first_run = 0; /// for cleaning shift registers
18     int i; /// index
19     int y; /// output sample
20
21     /// clean the buffers
22     if (first_run == 0)
23     {
24         first_run = 1;
25         for (i=0; i<NT; i++)
26             sx[i] = 0;
27         for (i=0; i<NT-1; i++)
28             sy[i] = 0;
29     }
30
31     /// shift and insert new sample in x shift register
32     for (i=NT-1; i>0; i--)
33         sx[i] = sx[i-1];
34     sx[0] = x;
35
36     /// make the convolution
37     /// Moving average part
38     y = 0;
39     for (i=0; i<NT; i++)
40         y += (sx[i]*b[i]) >> (NB-1) ;
41     /// Auto regressive part
42     //for (i=0; i<NT-1; i++)
43     // y -= (sy[i]*a[i]) >> (NB-1);
44
45     /// update the y shift register
46     for (i=NT-2; i>0; i--)
47         sy[i] = sy[i-1];
48     sy[0] = y;
49
50     return y;
51 }
52
53 int main (int argc, char **argv)
54 {
55     FILE *fp_in;
56     FILE *fp_out;
57
58     int x;
59     int y;
60
61     /// check the command line

```



```

62  if (argc != 3)
63  {
64      printf("Use: %s <input_file> <output_file>\n", argv[0]);
65      exit(1);
66  }
67
68  /// open files
69  fp_in = fopen(argv[1], "r");
70  if (fp_in == NULL)
71  {
72      printf("Error: cannot open %s\n");
73      exit(2);
74  }
75  fp_out = fopen(argv[2], "w");
76
77  /// get samples and apply filter
78  fscanf(fp_in, "%d", &x);
79  do{
80      y = myfilter(x);
81      fprintf(fp_out, "%d\n", y);
82      fscanf(fp_in, "%d", &x);
83  } while (!feof(fp_in));
84
85  fclose(fp_in);
86  fclose(fp_out);
87
88  return 0;
89
90 }

```

VHDL code - non optimized FIR filter

This is the code of the unoptimized filter; codes of the testbench and of basic elements (eg. registers) are not included.

Package util

./code/fir_unoptimized/util.vhd

```

1  LIBRARY ieee;
2  USE ieee.std_logic_1164.all;
3  USE ieee.numeric_std.all;
4  use ieee.math_real.all;
5
6  PACKAGE util IS
7
8  CONSTANT Nbit: INTEGER := 10;
9  CONSTANT N: INTEGER := 9;
10  --CONSTANT Nbit_result: INTEGER := Nbit+integer(ceil(log2(real(N))));
11  CONSTANT Nbit_result: INTEGER := Nbit;
12
13  CONSTANT FINAL_DELAY : integer := N + 5;
14
15  CONSTANT T: time := 20 ns; -- Clock period
16  CONSTANT start_time: time := 101 ns; -- Start time of simulation
17
18  TYPE LIST_N IS ARRAY (0 to N-1) OF SIGNED(Nbit-1 downto 0);
19  TYPE LIST_mult IS ARRAY (0 to N-1) OF SIGNED(Nbit+Nbit-1 downto 0);
20  TYPE LIST_mult_resize IS ARRAY (0 to N-1) OF SIGNED(Nbit_result downto 0);
21  TYPE LIST_sum IS ARRAY (0 to N-2) OF SIGNED(Nbit_result downto 0);

```



```

54 out_reg: regn    generic map (N => Nbit)
55                port map (D => sum(N-2)(Nbit_result downto Nbit_result-Nbit+1), Clock
=> CLK, Resetn => RST_INT_n, EN => EN_REG_OUT, Q => DOUT);
56
57 shift_reg: for i in 0 to N-2 generate
58     reg_i: regn generic map (N => Nbit)
59            port map (D => xz(i), Q => xz(i+1), Clock => CLK, Resetn => RST_INT_n,
EN => EN_SHIFT);
60 end generate shift_reg;
61
62 multipliers: for i in 0 to N-1 generate
63     mult(i) <= signed(b((i + 1) * Nbit - 1 downto i * Nbit)) * xz(i);
64     mult_resize(i)(Nbit_result downto 0) <= mult(i)(Nbit+Nbit-1 downto Nbit-1);
65
66 adders: for i in 0 to N-2 generate
67     i_0:    if (i=0) generate sum(i)<=mult_resize(i)+mult_resize(i+1); end generate;
68     i_etc:  if (i>0) generate sum(i)<=sum(i-1)+mult_resize(i+1); end generate;
69 end generate adders;
70
71 -----CONTROL UNIT-----
72 state_process: PROCESS (CLK, RST_n, VIN)
73 BEGIN
74 IF (RST_n='0') THEN present_state<=RESET;
75 ELIF (CLK'EVENT AND CLK='1') THEN
76     CASE (present_state) IS
77         -- reset
78         WHEN RESET => present_state<= IDLE;
79         WHEN IDLE => IF (VIN='1') THEN present_state <= DATA_CYCLE1;
80                     ELSE present_state <= IDLE;
81                     END IF;
82         WHEN DATA_CYCLE1 => IF (VIN='0') THEN present_state <= LAST_DATA1;
83                             ELSE present_state<=DATA_CYCLE2;
84                             END IF;
85         WHEN DATA_CYCLE2 => IF (VIN='0') THEN present_state <= LAST_DATA1;
86                             ELSE present_state<=DATA_CYCLE2;
87                             END IF;
88         WHEN LAST_DATA1 => present_state <= IDLE;
89
90     END CASE;
91 END IF;
92 END PROCESS state_process;
93
94 output_process: PROCESS (present_state)
95 BEGIN
96 VOUT<='0';
97 EN_REG_1<='0';
98 EN_REG_OUT<='0';
99 EN_SHIFT<='0';
100 RST_INT_n<='1';
101     CASE (present_state) IS
102         -- reset
103         WHEN RESET => RST_INT_n<='0';
104         WHEN IDLE => EN_REG_1<='1';
105         WHEN DATA_CYCLE1 => EN_REG_OUT<='1';
106                             EN_SHIFT<='1';
107         WHEN DATA_CYCLE2 => EN_REG_OUT<='1';
108                             EN_SHIFT<='1';
109                             VOUT<='1';
110         WHEN LAST_DATA1 => VOUT<='1';
111     END CASE;
112 END PROCESS output_process;
113

```

```

114 EN_FIRST_REG<=(EN_REG_1 or EN_SHIFT);
115
116 END ARCHITECTURE behavior;

```

VHDL code - optimized FIR filter

This is the code of the optimized filter, without the files that are in common with the standard filter.

Package util

./code/fir_optimized/util.vhd

```

1  LIBRARY ieee;
2  USE ieee.std_logic_1164.all;
3  USE ieee.numeric_std.all;
4  use ieee.math_real.all;
5
6  PACKAGE util IS
7
8  CONSTANT Nbit: INTEGER := 10;
9  CONSTANT N: INTEGER := 9; — number of coefficients
10 CONSTANT P: INTEGER := 3; — unfolding factor
11 CONSTANT W1: INTEGER := 2; — MAX NUMBER OF INTERMEDIATE REGISTER FOR DIN(P*K)
12 CONSTANT W2: INTEGER := 3; — MAX NUMBER OF INTERMEDIATE REGISTER FOR DIN(P*K+1)
13 CONSTANT W3: INTEGER := 3; — MAX NUMBER OF INTERMEDIATE REGISTER FOR DIN(P*K+2)
14
15 CONSTANT Nbit_result: INTEGER := Nbit;
16
17 CONSTANT FINAL_DELAY : integer := N + 5;
18
19 CONSTANT T: time := 20 ns; — Clock period
20 CONSTANT start_time: time := 101 ns; —Start time of simulation
21
22 TYPE LIST_N IS ARRAY (0 to W3) OF SIGNED(Nbit-1 downto 0);
23 TYPE LIST_mult IS ARRAY (0 to N-1) OF SIGNED(Nbit+Nbit-1 downto 0);
24 TYPE LIST_mult_resize IS ARRAY (0 to N-1) OF SIGNED(Nbit downto 0);
25
26 TYPE LIST_sum_1 IS ARRAY (0 to (N/2)-1) OF SIGNED((Nbit+1)-1 downto 0);
27 TYPE LIST_sum_2 IS ARRAY (0 to (((N*P)/2)-1)/2+1) OF SIGNED(Nbit downto 0);
28 —array used in folding structure—
29 TYPE input_format_type IS ARRAY (0 to P-1) OF SIGNED(Nbit-1 downto 0);
30 TYPE OUT_PIPES_TYPE IS ARRAY (0 TO P-1) OF LIST_N;
31 TYPE mult_array_TYPE IS ARRAY (0 TO P-1) OF LIST_mult;
32 TYPE mult_resize_array_TYPE IS ARRAY (0 TO P-1) OF LIST_mult_resize;
33
34 END util;

```

FIR filter code

./code/fir_optimized/FIR_filter.vhd

```

1  LIBRARY ieee;
2  USE ieee.std_logic_1164.all;
3  USE ieee.numeric_std.all;
4
5  library std;
6  USE work.util.all;
7
8  ENTITY FIR_filter IS

```

```

9
10 PORT(  CLK:    in  std_logic;
11         RST_n: in  std_logic;
12
13         VIN:    in  std_logic;
14         VOUT:   out std_logic;
15
16         -- we have Nbit * P types for Verilog, which does not support custom types
17         DIN:    in  std_logic_vector(Nbit * P - 1 downto 0);
18         DOUT:   out std_logic_vector(Nbit * P - 1 downto 0);
19
20         b:      in  std_logic_vector(N * Nbit - 1 downto 0));
21
22 END ENTITY FIR_filter;
23
24 ARCHITECTURE behavior OF FIR_filter IS
25
26 COMPONENT regn IS
27   GENERIC (N: INTEGER := 16);
28   PORT (D : IN SIGNED (N-1 DOWNT0 0);      -- input
29         Clock, Resetn, EN : IN STD_LOGIC; -- clock, reset, enable
30         Q : OUT SIGNED (N-1 DOWNT0 0));    -- output
31 END COMPONENT regn;
32
33 component dff IS
34   PORT (D : IN STD_LOGIC;      -- input
35         Clock, Resetn, EN : IN STD_LOGIC; -- clock, reset, enable
36         Q : OUT STD_LOGIC);    -- output
37 END component;
38
39 -- From util:
40 -- TYPE LIST_N IS ARRAY (0 to W3) OF SIGNED(Nbit-1 downto 0);
41 -- TYPE LIST_mult IS ARRAY (0 to N-1) OF SIGNED(Nbit+Nbit-1 downto 0);
42 -- TYPE LIST_mult_resize IS ARRAY (0 to N-1) OF SIGNED(Nbit downto 0);
43 -- TYPE OUT_PIPES_TYPE      IS ARRAY (0 TO P-1) OF LIST_N;
44 -- TYPE mult_array_TYPE     IS ARRAY (0 TO P-1) OF LIST_mult;
45 -- TYPE mult_resize_array_TYPE IS ARRAY (0 TO P-1) OF LIST_mult_resize;
46
47 SIGNAL xz: OUT_PIPES_TYPE;
48 SIGNAL mult: mult_array_TYPE;
49 SIGNAL mult_out_pipe: mult_resize_array_TYPE;
50
51 SIGNAL mult_resize: LIST_mult_resize;
52 SIGNAL sum_1_in, sum_2_in, sum_3_in, sum_1_out, sum_2_out, sum_3_out: LIST_sum_1;
53 SIGNAL PIPE_REG_MULT_2_8: SIGNED(Nbit+1-1 downto 0);
54
55 TYPE sum1_reg_type is array (0 to 4-1) of SIGNED((Nbit+1)-1 downto 0);
56 TYPE sum1_type is array (0 to P-1) of sum1_reg_type;
57 SIGNAL sum1_reg_in, sum1_reg_out : sum1_type;
58
59 TYPE sum2_reg_type is array (0 to 2-1) of SIGNED((Nbit+2)-1 downto 0);
60 TYPE sum2_type is array (0 to P-1) of sum2_reg_type;
61 SIGNAL sum2_reg_in, sum2_reg_out : sum2_type;
62
63 TYPE sum3_type is array (0 to P-1) of SIGNED((Nbit+3)-1 downto 0);
64 SIGNAL sum3_reg_in, sum3_reg_out : sum3_type;
65 SIGNAL REG8_EXTENDED : SIGNED(Nbit+3-1 DOWNT0 0);
66
67 TYPE sum_final_type is array (0 to P-1) of SIGNED((Nbit+4)-1 downto 0);
68 SIGNAL sum_final : sum_final_type;
69
70 TYPE reg_8_reg_type is array (0 to 4-1) of SIGNED((Nbit+1)-1 downto 0);

```

```

71 TYPE reg_8_type is array (0 to P-1) of reg_8_reg_type;
72 SIGNAL reg_8_value : reg_8_type;
73 SIGNAL reg_8_value_not_aggregate: signed(Nbit-1 downto 0);
74
75 TYPE pipelined_type is array (0 to 4) of std_logic;
76 SIGNAL en_shift_p, vout_p : pipelined_type;
77
78 SIGNAL VIN_retard : std_logic;
79
80 TYPE state IS (RESET, IDLE, DATA_CYCLE1, DATA_CYCLE2, LAST_DATA1);
81 SIGNAL present_state : state;
82 SIGNAL EN_REG_1, EN_REG_OUT, EN_SHIFT, RST_INT_n, EN_FIRST_REG, VOUT1 : STD_LOGIC;
83
84 SIGNAL DOUT1, DOUT2, DOUT3 : SIGNED(Nbit-1 DOWNTO 0 );
85
86 BEGIN
87   ----- DATAPATH -----
88   EN_FIRST_REG <= (EN_REG_1 or EN_SHIFT);
89
90   -- 3 INPUT REGISTERS
91   in_reg_3k: regn generic map (N => Nbit)
92     port map (D => signed(DIN(3 * Nbit - 1 downto 2 * Nbit)), Clock => CLK
93       , Resetn => RST_INT_n, EN => EN_FIRST_REG , Q => xz(0)(0));
94   in_reg_3k_plus_1: regn generic map (N => Nbit)
95     port map (D => signed(DIN(2 * Nbit - 1 downto Nbit)), Clock => CLK,
96       Resetn => RST_INT_n, EN => EN_FIRST_REG , Q => xz(1)(0));
97   in_reg_3k_plus_2: regn generic map (N => Nbit)
98     port map (D => signed(DIN(Nbit - 1 downto 0)), Clock => CLK, Resetn =>
99       RST_INT_n, EN => EN_FIRST_REG , Q => xz(2)(0));
100
101   -- 3 OUTPUT REGISTERS
102   out_reg_1: regn generic map (N => Nbit)
103     port map (D => sum_final(0)((Nbit+1)-1 downto (Nbit+1)-1-Nbit+1),
104       Clock => CLK, Resetn => RST_INT_n, EN => en_shift_p(4), Q => DOUT1(Nbit - 1 downto
105       0));
106   out_reg_2: regn generic map (N => Nbit)
107     port map (D => sum_final(1)((Nbit+1)-1 downto (Nbit+1)-1-Nbit+1),
108       Clock => CLK, Resetn => RST_INT_n, EN => en_shift_p(4), Q => DOUT2(Nbit - 1 downto
109       0));
110   out_reg_3: regn generic map (N => Nbit)
111     port map (D => sum_final(2)((Nbit+1)-1 downto (Nbit+1)-1-Nbit+1),
112       Clock => CLK, Resetn => RST_INT_n, EN => en_shift_p(4), Q => DOUT3(Nbit - 1 downto
113       0));
114
115   -- 3 output data are aligned in a single vector
116   DOUT(Nbit - 1 downto 0) <= std_logic_vector(DOUT3);
117   DOUT(2 * Nbit - 1 downto Nbit) <= std_logic_vector(DOUT2);
118   DOUT(3 * Nbit - 1 downto 2 * Nbit) <= std_logic_vector(DOUT1);
119
120   -- registers for xn[3k]
121   shift_reg_3k: for i in 0 to W1-1 generate
122     reg_i: regn generic map (N => Nbit)
123       port map (D => xz(0)(i), Q => xz(0)(i+1), Clock => CLK, Resetn =>
124         RST_INT_n, EN => EN_SHIFT);
125   end generate shift_reg_3k;
126
127   -- registers for xn[3k+1]
128   shift_reg_3k_plus_1: for i in 0 to W2-1 generate
129     reg_i: regn generic map (N => Nbit)
130       port map (D => xz(1)(i), Q => xz(1)(i+1), Clock => CLK, Resetn =>
131         RST_INT_n, EN => EN_SHIFT);
132   end generate shift_reg_3k_plus_1;
133
134

```

```

122 -- registers for xn[3k+2]
123 shift_reg_3k_plus_2: for i in 0 to W3-1 generate
124     reg_i: regn generic map (N => Nbit)
125         port map (D => xz(2)(i), Q => xz(2)(i+1), Clock => CLK, Resetn =>
126             RST_INT_n, EN => EN_SHIFT);
127 end generate shift_reg_3k_plus_2;
128
129 -- All the nine multiplications are performed in parallel in the three
130 -- replicas of the original datapath
131 mult(0)(0) <= signed(b((0 + 1) * Nbit - 1 downto 0 * Nbit)) * xz(0)(0);
132 mult(0)(1) <= signed(b((1 + 1) * Nbit - 1 downto 1 * Nbit)) * xz(2)(1);
133 mult(0)(2) <= signed(b((2 + 1) * Nbit - 1 downto 2 * Nbit)) * xz(1)(1);
134 mult(0)(3) <= signed(b((3 + 1) * Nbit - 1 downto 3 * Nbit)) * xz(0)(1);
135 mult(0)(4) <= signed(b((4 + 1) * Nbit - 1 downto 4 * Nbit)) * xz(2)(2);
136 mult(0)(5) <= signed(b((5 + 1) * Nbit - 1 downto 5 * Nbit)) * xz(1)(2);
137 mult(0)(6) <= signed(b((6 + 1) * Nbit - 1 downto 6 * Nbit)) * xz(0)(2);
138 mult(0)(7) <= signed(b((7 + 1) * Nbit - 1 downto 7 * Nbit)) * xz(2)(3);
139 mult(0)(8) <= signed(b((8 + 1) * Nbit - 1 downto 8 * Nbit)) * xz(1)(3);
140
141 mult(1)(0) <= signed(b((0 + 1) * Nbit - 1 downto 0 * Nbit)) * xz(1)(0);
142 mult(1)(1) <= signed(b((1 + 1) * Nbit - 1 downto 1 * Nbit)) * xz(0)(0);
143 mult(1)(2) <= signed(b((2 + 1) * Nbit - 1 downto 2 * Nbit)) * xz(2)(1);
144 mult(1)(3) <= signed(b((3 + 1) * Nbit - 1 downto 3 * Nbit)) * xz(1)(1);
145 mult(1)(4) <= signed(b((4 + 1) * Nbit - 1 downto 4 * Nbit)) * xz(0)(1);
146 mult(1)(5) <= signed(b((5 + 1) * Nbit - 1 downto 5 * Nbit)) * xz(2)(2);
147 mult(1)(6) <= signed(b((6 + 1) * Nbit - 1 downto 6 * Nbit)) * xz(1)(2);
148 mult(1)(7) <= signed(b((7 + 1) * Nbit - 1 downto 7 * Nbit)) * xz(0)(2);
149 mult(1)(8) <= signed(b((8 + 1) * Nbit - 1 downto 8 * Nbit)) * xz(2)(3);
150
151 mult(2)(0) <= signed(b((0 + 1) * Nbit - 1 downto 0 * Nbit)) * xz(2)(0);
152 mult(2)(1) <= signed(b((1 + 1) * Nbit - 1 downto 1 * Nbit)) * xz(1)(0);
153 mult(2)(2) <= signed(b((2 + 1) * Nbit - 1 downto 2 * Nbit)) * xz(0)(0);
154 mult(2)(3) <= signed(b((3 + 1) * Nbit - 1 downto 3 * Nbit)) * xz(2)(1);
155 mult(2)(4) <= signed(b((4 + 1) * Nbit - 1 downto 4 * Nbit)) * xz(1)(1);
156 mult(2)(5) <= signed(b((5 + 1) * Nbit - 1 downto 5 * Nbit)) * xz(0)(1);
157 mult(2)(6) <= signed(b((6 + 1) * Nbit - 1 downto 6 * Nbit)) * xz(2)(2);
158 mult(2)(7) <= signed(b((7 + 1) * Nbit - 1 downto 7 * Nbit)) * xz(1)(2);
159 mult(2)(8) <= signed(b((8 + 1) * Nbit - 1 downto 8 * Nbit)) * xz(0)(2);
160
161 -- registers at the output of multipliers
162 mult_reg: for i in 0 to P-1 generate
163     sec: for k in 0 to N-1 generate
164         mult_reg_i: regn generic map (N => Nbit+1)
165             port map (D => mult(i)(k)(Nbit+Nbit-1 downto Nbit
166                 -1), Q => mult_out_pipe(i)(k), Clock => CLK, Resetn => RST_INT_n, EN =>
167                 en_shift_p(0));
168     end generate;
169 end generate mult_reg;
170
171 ----- first layer of adders -----
172 adders_1_1: process(mult_out_pipe)
173     variable temp1, temp2, temp3: integer;
174     begin
175         for i in 0 to P-1 loop
176             for k in 0 to 3 loop
177                 temp1 := to_integer(mult_out_pipe(i)(2*k+1));
178                 temp2 := to_integer(mult_out_pipe(i)(2*k));
179                 temp3 := temp1 + temp2;
180                 sum1_reg_in(i)(k) <= to_signed(temp3, Nbit+1);
181             end loop;
182         end loop;
183     end process;

```

```

181
182 -----second layer of adders-----
183 adders_2: process(sum1_reg_out)
184     variable temp1,temp2,temp3: integer;
185     begin
186         for i in 0 to P-1 loop
187             for k in 0 to 1 loop
188                 temp1:=to_integer(sum1_reg_out(i)(2*k+1));
189                 temp2:=to_integer(sum1_reg_out(i)(2*k));
190                 temp3:=temp1+temp2;
191                 sum2_reg_in(i)(k)<=to_signed(temp3,Nbit+2);
192             end loop;
193         end loop;
194     end process;
195
196 ----- third layer of adders-----
197 adders_3: process(sum2_reg_out)
198     variable temp1,temp2,temp3: integer;
199     begin
200         for i in 0 to P-1 loop
201             temp1:=to_integer(sum2_reg_out(i)(0));
202             temp2:=to_integer(sum2_reg_out(i)(1));
203             temp3:=temp1+temp2;
204             sum3_reg_in(i)<=to_signed(temp3,Nbit+3);
205
206         end loop;
207     end process;
208
209 -----fourth layer of adders-----
210
211 adders_4: process(reg_8_value,sum3_reg_out)
212     variable temp1,temp2,temp3: integer;
213     begin
214         for i in 0 to P-1 loop
215             temp1:=to_integer(reg_8_value(i)(3));
216             temp2:=to_integer(sum3_reg_out(i));
217             temp3:=temp1+temp2;
218             sum_final(i)<=to_signed(temp3,Nbit+4);
219
220         end loop;
221     end process;
222
223
224
225 -----reg_8 shift register-----
226 shift_reg8: for i in 0 to P-1 generate
227     reg_8_value(i)(0)<=mult_out_pipe(i)(8);
228     sec: for k in 0 to 2 generate
229         shift_reg_8: regn generic map (N => Nbit+1)
230             port map (D => reg_8_value(i)(k), Q => reg_8_value(i)(k+1), Clock =>
231                 CLK, Resetn => RST_INT_n, EN => en_shift_p(k+1));
232             end generate;
233         end generate shift_reg8;
234
235 -----registers between adders-----
236 registri_vari: for i in 0 to P-1 generate
237     sum1_cycle: for k in 0 to 3 generate
238         sum1_reg: regn generic map (N => Nbit+1)
239             port map (D => sum1_reg_in(i)(k), Q => sum1_reg_out(i)(k), Clock =>
240                 CLK, Resetn => RST_INT_n, EN => en_shift_p(1));
241             end generate;
242         sum2_cycle: for k in 0 to 1 generate

```

```

241         sum2_reg: regn generic map (N => Nbit+2)
242         port map (D => sum2_reg_in(i)(k), Q => sum2_reg_out(i)(k), Clock =>
CLK, Resetn => RST_INT_n, EN => en_shift_p(2));
243         end generate;
244
245         sum3_reg: regn generic map (N => Nbit+3)
246         port map (D => sum3_reg_in(i), Q => sum3_reg_out(i), Clock => CLK,
Resetn => RST_INT_n, EN => en_shift_p(3));
247
248         end generate registri_vari;
249
250 -----PIPE OF CONTROL SIGNALS-----
251 -- registers to shift enable signal
252 pipe_registers_en_shift: for i in 0 to 3 generate
253     reg_i: dff port map (D => en_shift_p(i), Q => en_shift_p(i+1), Clock => CLK,
Resetn => RST_INT_n, EN => '1');
254 end generate pipe_registers_en_shift;
255
256 -- registers to shift vout signal
257 pipe_registers_vout: for i in 0 to 3 generate
258     reg_i: dff port map (D => vout_p(i), Q => vout_p(i+1), Clock => CLK, Resetn =>
RST_INT_n, EN => '1');
259 end generate pipe_registers_vout;
260
261 en_shift_p(0) <= EN_SHIFT;
262 vout_p(0) <= VOUT1;
263 VOUT <= vout_p(4);
264
265 -----CONTROL UNIT-----
266
267 state_process: PROCESS (CLK, RST_n, VIN)
268 BEGIN
269 IF (RST_n = '0') THEN present_state <= RESET;
270 ELSIF (CLK'EVENT AND CLK = '1') THEN
271     CASE (present_state) IS
272         -- reset
273         WHEN RESET => present_state <= IDLE;
274         WHEN IDLE => IF (VIN = '1') THEN present_state <= DATA_CYCLE1;
275                     ELSE present_state <= IDLE;
276                     END IF;
277         WHEN DATA_CYCLE1 => IF (VIN = '0') THEN present_state <= LAST_DATA1;
278                             ELSE present_state <= DATA_CYCLE2;
279                             END IF;
280         WHEN DATA_CYCLE2 => IF (VIN = '0') THEN present_state <= LAST_DATA1;
281                             ELSE present_state <= DATA_CYCLE2;
282                             END IF;
283         WHEN LAST_DATA1 => present_state <= IDLE;
284
285     END CASE;
286 END IF;
287 END PROCESS state_process;
288
289 output_process: PROCESS (present_state)
290 BEGIN
291 VOUT1 <= '0';
292 EN_REG_1 <= '0';
293 EN_REG_OUT <= '0';
294 EN_SHIFT <= '0';
295 RST_INT_n <= '1';
296     CASE (present_state) IS
297         -- reset
298         WHEN RESET => RST_INT_n <= '0';

```

```
299     WHEN IDLE => EN_REG_1<='1';
300     WHEN DATA_CYCLE1 => EN_REG_OUT<='1';
301                           EN_SHIFT<='1';
302     WHEN DATA_CYCLE2 => EN_REG_OUT<='1';
303                           EN_SHIFT<='1';
304                           VOUT1<='1';
305     WHEN LAST_DATA1 => VOUT1<='1';
306     END CASE;
307 END PROCESS output_process;
308
309 END ARCHITECTURE behavior;
```