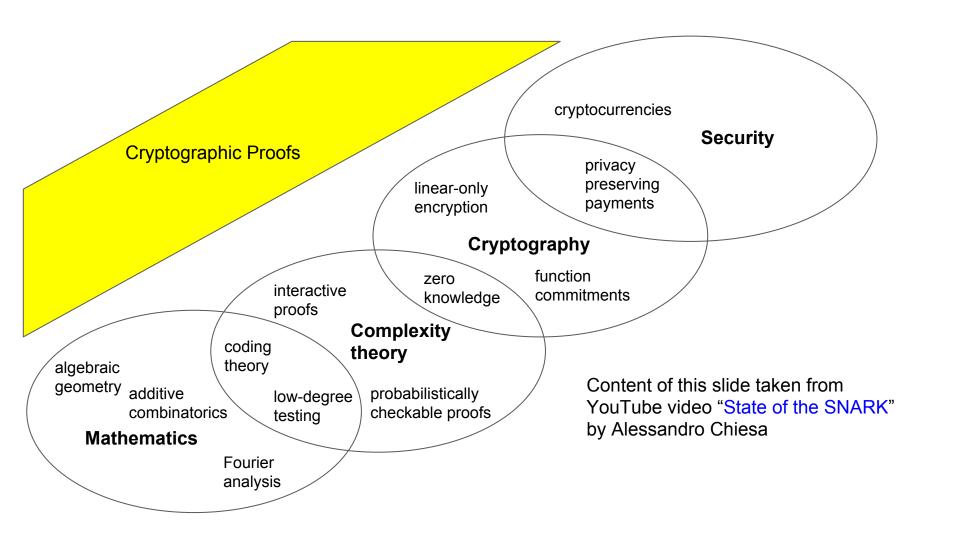
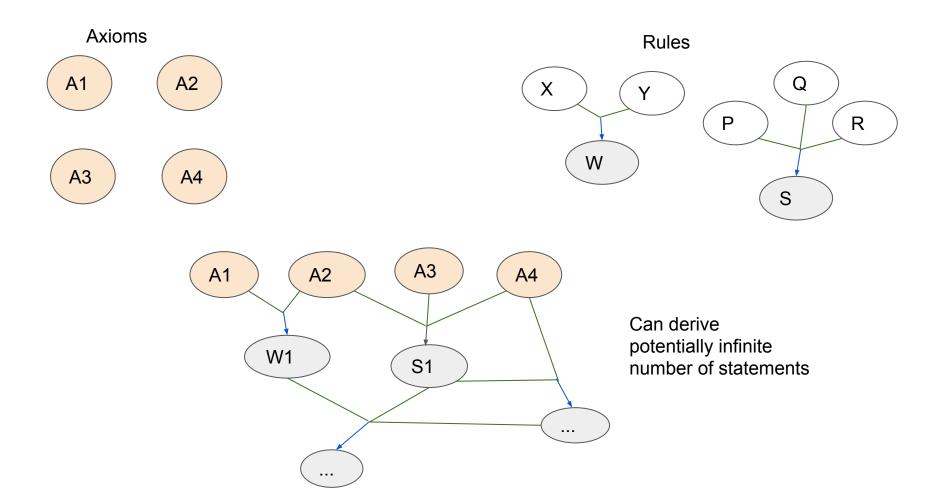
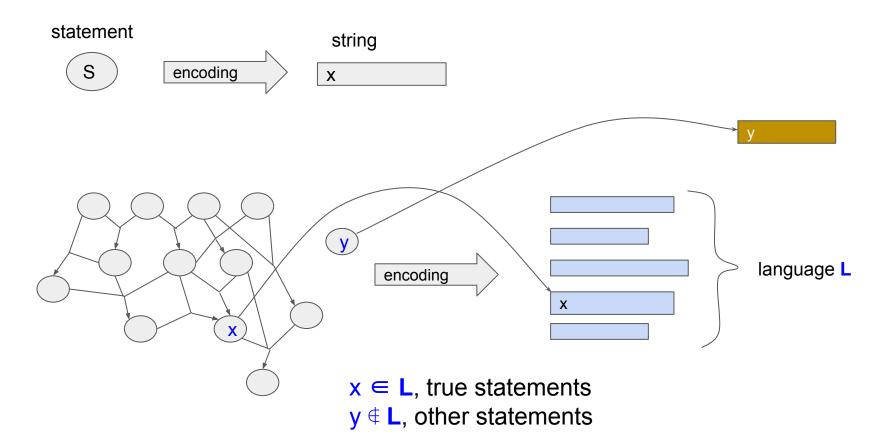
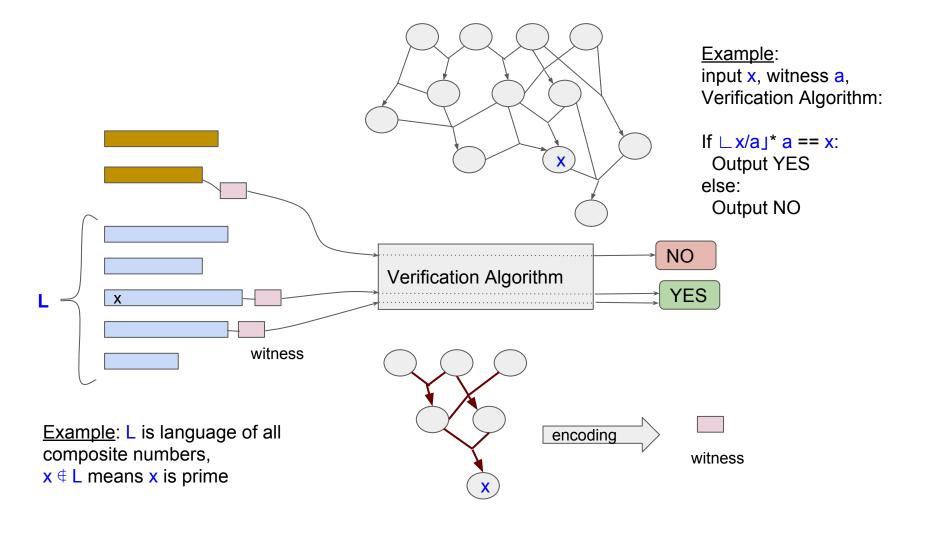
How to prove you solved a puzzle without showing how

Dr Alexey Akhunov, Nov 2016

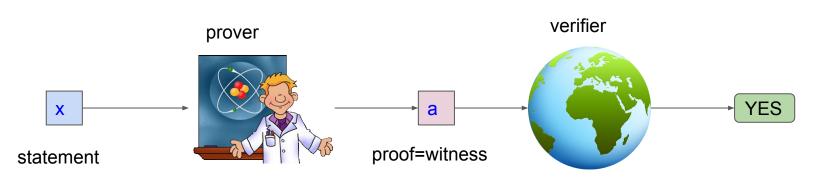






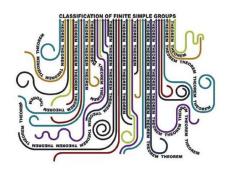


Protocol for "classical" proofs



Some proofs are too large



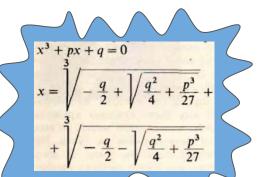


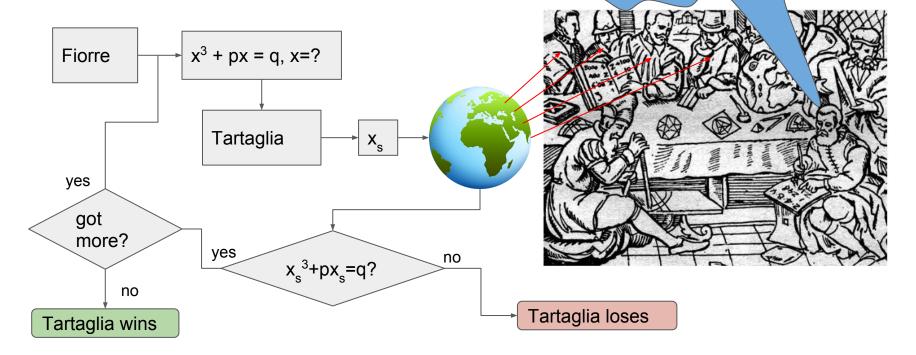
proof ≠ witness?



Another protocol

1535 Mathematical duel Fiorre - Tartaglia





What we want to the proofs to be

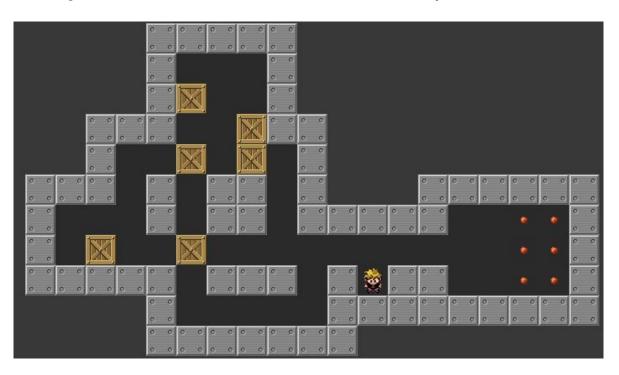
<u>Succinct</u>. Verification time/memory does not depend on the problem size. Allows verifying very large proofs

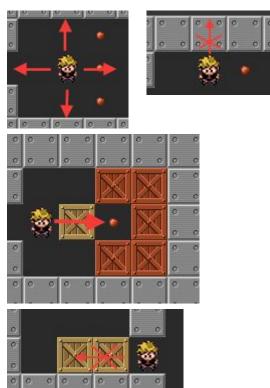
Non-interactive. We do not need a dedicated verifier, anybody can verify any time.

Zero-knowledge. If prover wants to keep the witness secret. Someone who has seen the proof and accepted it, does not learn anything new about the witness.

<u>Proof of knowledge</u>. We want to be sure that the prover must have known the secret if they were able to produce the proof.

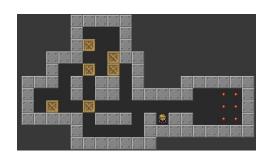
Toy example - Sokoban (Japan, early 80s)





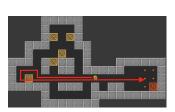
NP-hard problem

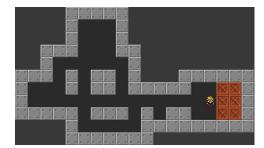
initial state











. . .

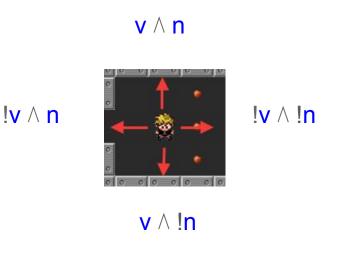
Formalisation

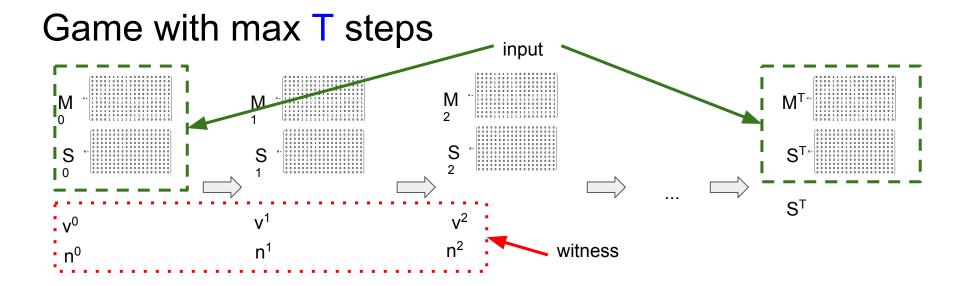
 $m(\text{ovable}), s(\text{olid}), v(\text{ertical}), n(\text{orthwest}) \in \{0,1\}$

For board of size (2, 5), the state is $(M=[m_{ij}], S=[s_{ij}]), 0 \le i < 2, 0 \le j < 5, m_{ij}, s_{ij} \in \{0,1\}.$



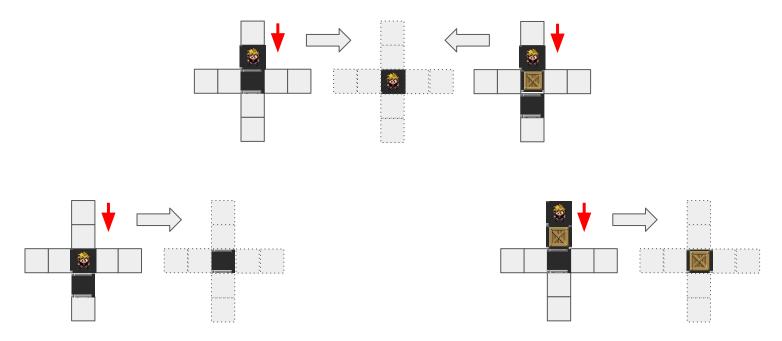




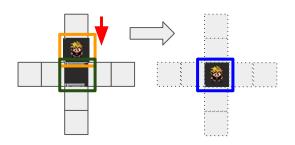


step t to step t+1: $(M^t, S^t, v^t, n^t) \rightarrow (M^{t+1}, S^{t+1})$

Observation: state of the any cell can only depend on the state of 9 cells from the previous step, and on the movement variables. The only 4 ways the state can change (same for all other movement directions):

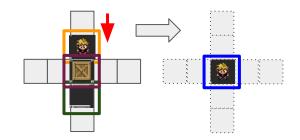




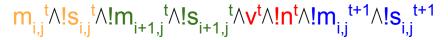


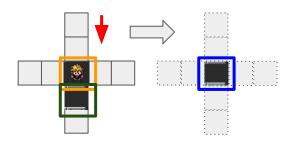
... and 3 more expressions like that for moving up, right, and left ...

$$m_{i-1,j}^{-t} \wedge !s_{i-1,j}^{-t} \wedge m_{i,j}^{-t} \wedge s_{i,j}^{-t} \wedge !m_{i+1,j}^{-t} \wedge \ !s_{i+1,j}^{-t} \wedge v^{t} \wedge !n^{t} \wedge m_{i,j}^{-t+1} \wedge !s_{i,j}^{-t+1}$$



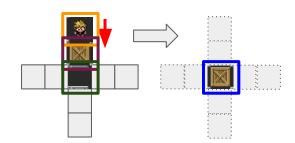
... and 3 more expressions like that for moving up, right, and left ...



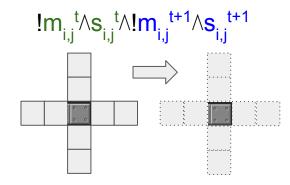


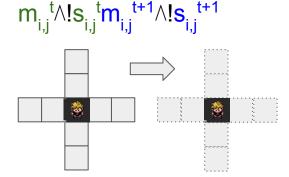
... and 3 more expressions like that for moving up, right, and left ...

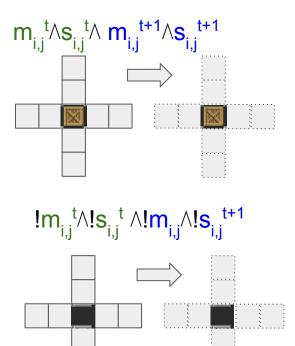
$$m_{i-2,j}{}^t \wedge !s_{i-2,j}{}^t \wedge m_{i-1,j}{}^t \wedge s_{i-1,j}{}^t \wedge !m_{i,j}{}^t \wedge !s_{i,j}{}^t \wedge !v^t \wedge n^t \wedge m_{i,j}{}^{t+1} \wedge s_{i,j}{}^{t+1}$$



... and 3 more expressions like that for moving up, right, and left ...





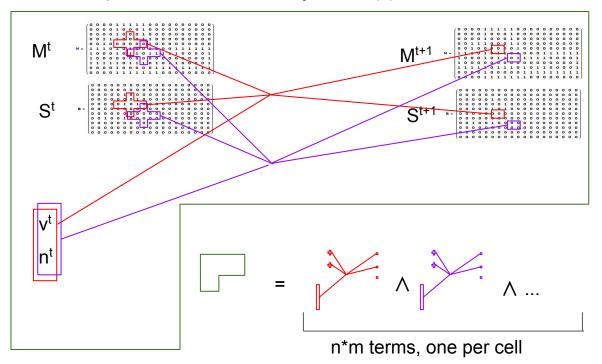


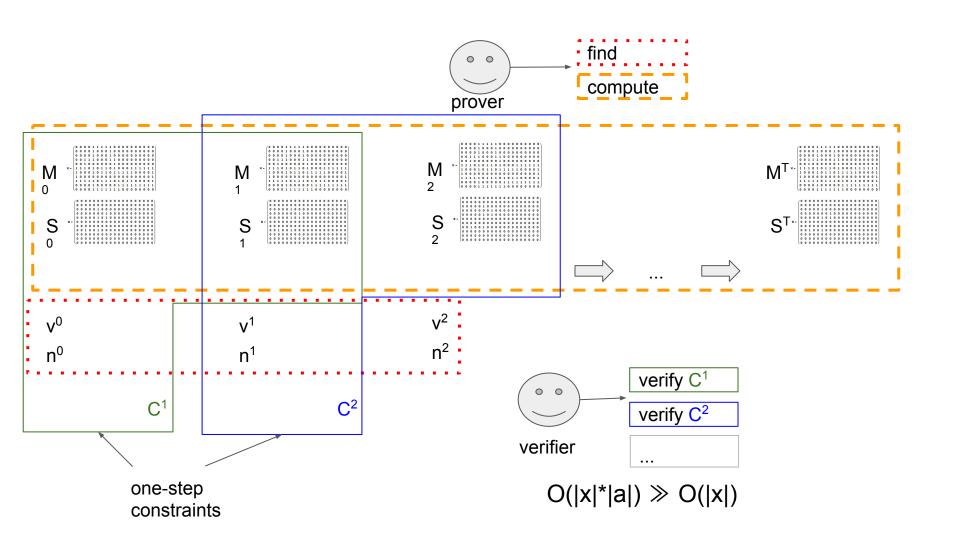
Cell expression (no edge, no corner)

each cell expression binds up to 2*(9+1)+2=22 variables together

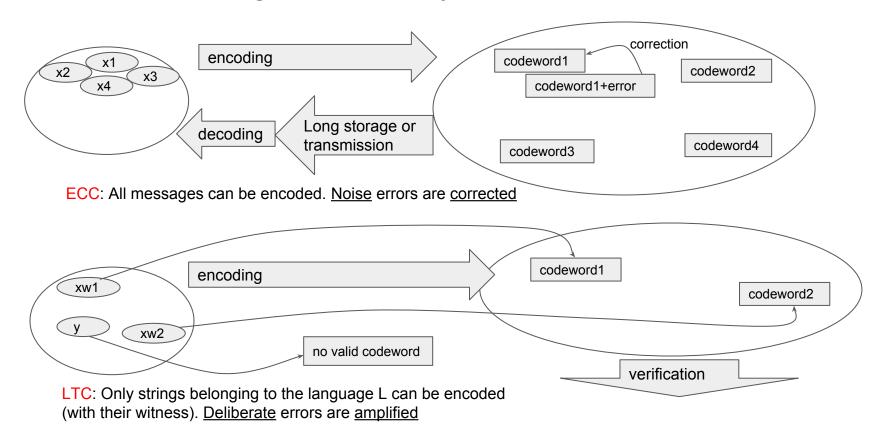
Step constraint

There are n*m cell expressions, and their conjunction (△) binds 4*n*m+2 variables



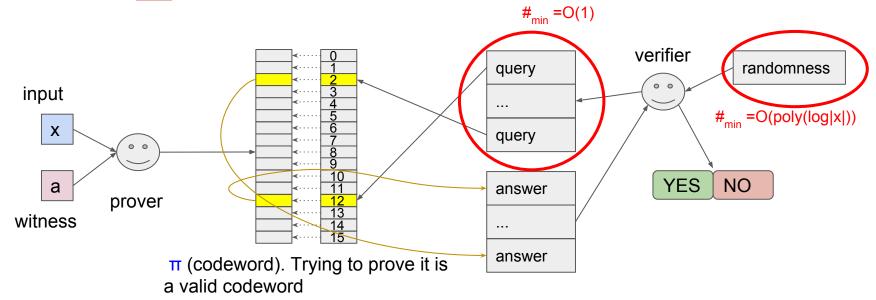


Error correcting and locally testable codes

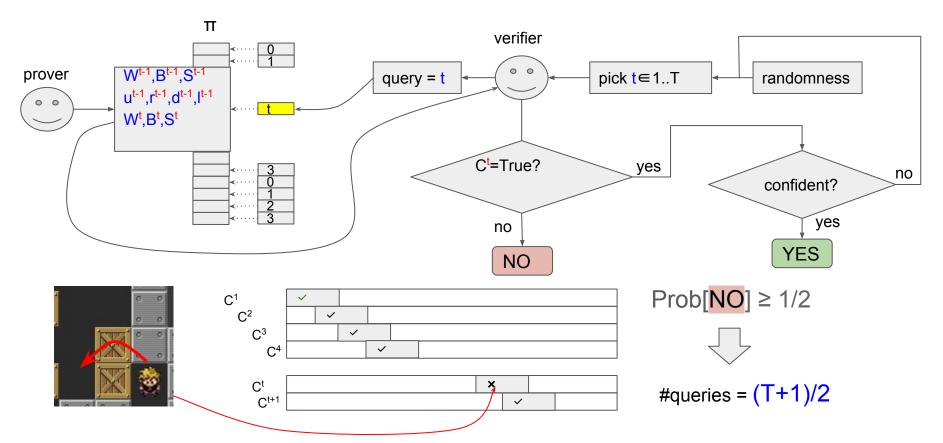


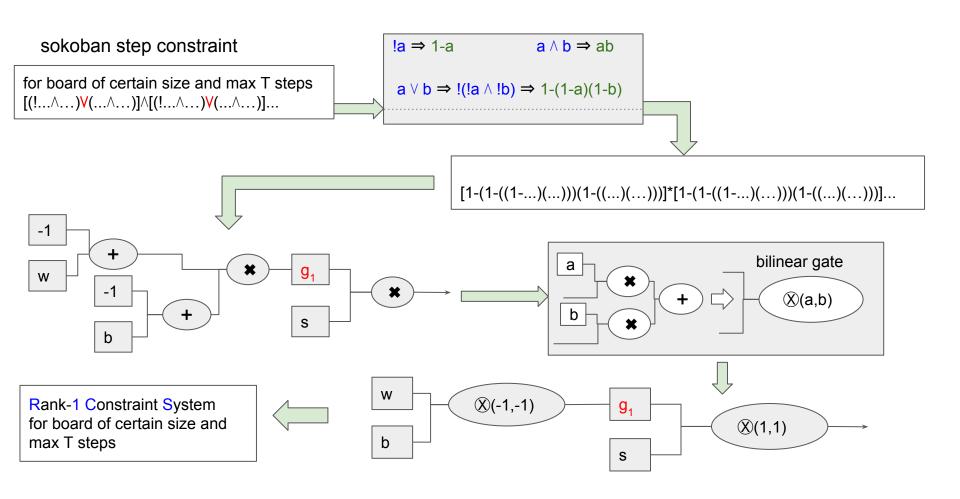
Probabilistically Checkable Proofs

PCP Theorem gives the minimal amount of randomness and number of queries required for this proof system to be complete (If $x \in L$, Prob[YES] = 1) and sound (If $x \notin L$, Prob[NO] $\geq \frac{1}{2}$).



Naive PCP for Sokoban



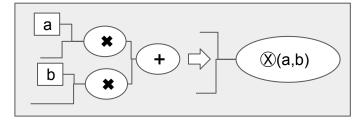


Rank-1 Constraint System (R1CS)

We rename all the variables into a vector $Y=(y_1,y_2,...,y_{Nv})$, Nv - number of variables

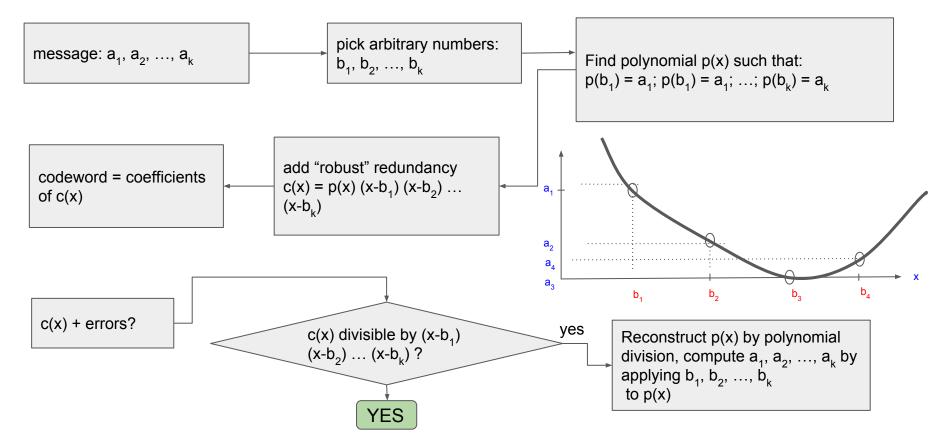
Then, our system of constraints becomes

$$\begin{array}{l} \text{constraint 1: } (a_0^{\ 1} + \sum_i a_i^{\ 1} y_i) \ ^* \ (b_0^{\ 1} + \sum_i b_i^{\ 1} y_i) = c_0^{\ 1} + \sum_i c_i^{\ 1} y_i \\ \\ \text{constraint 2: } (a_0^{\ 2} + \sum_i a_i^{\ 2} y_i) \ ^* \ (b_0^{\ 2} + \sum_i b_i^{\ 2} y_i) = c_0^{\ 2} + \sum_i c_i^{\ 2} y_i \\ \\ \dots \\ \\ \text{constraint Nc: } (a_0^{\ Nc} + \sum_i a_i^{\ Nc} y_i) \ ^* \ (b_0^{\ Nc} + \sum_i b_i^{\ Nc} y_i) = c_0^{\ Nc} + \sum_i c_i^{\ Nc} y_i \\ \end{array}$$

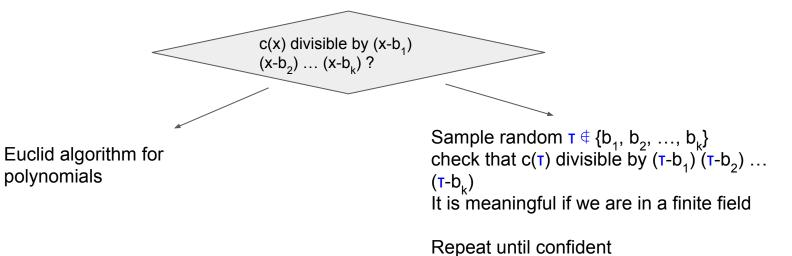


This kind of matrix is of rank 1

Polynomial encoding (for intuition only)



Checking divisibility for the codeword



Interpolation of a, b, c-s: 4 variables, 3 constraints

Pick arbitrary $\alpha_1, \alpha_2, \alpha_3$ constraint 1: $(a_0^{1} + a_1^{1}y_1 + a_2^{2}y_2 + a_3^{1}y_3 + a_4^{2}y_4) * (b_0^{1} + b_1^{1}y_1 + b_2^{1}y_2 + b_3^{1}y_3 + b_4^{1}y_4) = c_0^{1} + c_1^{1}y_1 + c_2^{1}y_2 + c_3^{1}y_3 + c_4^{1}y_4$ constraint 2: $(a_0^2 + a_1^2 y_1 + a_2^2 y_2 + a_3^2 y_3 + a_4^2 y_4) * (b_0^2 + b_1^2 y_1 + b_2^2 y_2 + b_3^2 y_3 + b_4^2 y_4) = c_0^2 + c_1^2 y_1 + c_2^2 y_2 + c_3^2 y_3 + c_4^2 y_4$ constraint 3: $(a_0^3 + a_1^3 y_1 + a_2^3 y_2 + a_3^3 y_3 + a_4^3 y_4) * (b_0^3 + b_1^3 y_1 + b_2^3 y_2 + b_3^3 y_3 + b_4^3 y_4) = c_0^3 + c_1^3 y_1 + c_2^3 y_2 + c_3^3 y_3 + c_4^3 y_4$ constraint 1: $[A_0(\alpha_1) + A_1(\alpha_1)y_1 + A_2(\alpha_1)y_2 + A_3(\alpha_1)y_3 + A_4(\alpha_1)y_4] * [B_0(\alpha_1) + B_1(\alpha_1)y_1 + B_2(\alpha_1)y_2 + B_3(\alpha_1)y_3 + B_4(\alpha_1)y_4] =$ $C_0(\alpha_1)+C_1(\alpha_1)y_1+C_2(\alpha_1)y_2+C_3(\alpha_1)y_3+C_4(\alpha_1)y_4$ constraint 2: $[A_0(\alpha_2) + A_1(\alpha_2)y_1 + A_2(\alpha_2)y_2 + A_3(\alpha_2)y_3 + A_4(\alpha_2)y_4] * [B_0(\alpha_2) + B_1(\alpha_2)y_1 + B_2(\alpha_2)y_2 + B_3(\alpha_2)y_3 + B_4(\alpha_2)y_4] = 0$ $C_0(\alpha_2)+C_1(\alpha_2)y_1+C_2(\alpha_2)y_2+C_3(\alpha_2)y_3+C_4(\alpha_2)y_4$ constraint 3: $[A_0(\alpha_3) + A_1(\alpha_3)y_1 + A_2(\alpha_3)y_2 + A_3(\alpha_3)y_3 + A_4(\alpha_3)y_4] * [B_0(\alpha_3) + B_1(\alpha_3)y_1 + B_2(\alpha_3)y_2 + B_3(\alpha_3)y_3 + B_4(\alpha_3)y_4] = 0$ $C_0(\alpha_3)+C_1(\alpha_2)y_1+C_2(\alpha_2)y_2+C_3(\alpha_2)y_3+C_4(\alpha_2)y_4$

Encoding of all constraints

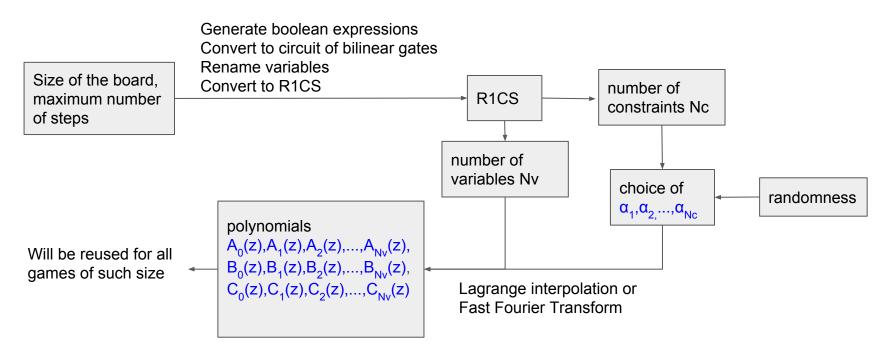
constraint j: $(A_0(\alpha_i) + \sum_i A_i(\alpha_i) y_i) * (B_0(\alpha_i) + \sum_i B_i(\alpha_i) y_i) = C_0(\alpha_i) + \sum_i C_i(\alpha_i) y_i$

<u>Codeword for the whole solution</u>: $(A_0(z) + \sum_i A_i(z)y_i) * (B_0(z) + \sum_i B_i(z)y_i) - C_0(z) + \sum_i C_i(z)y_i$

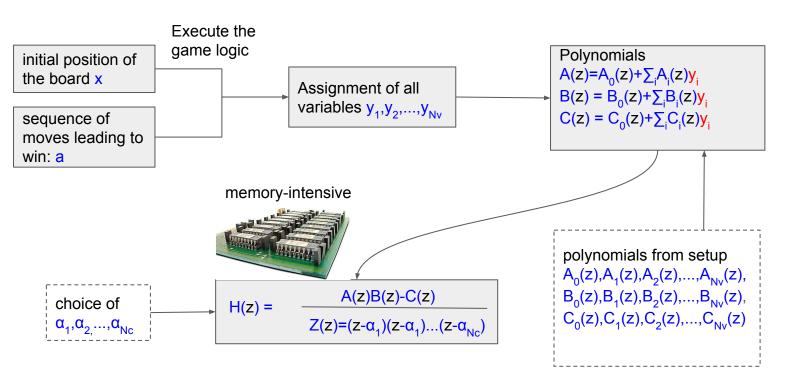
Codeword polynomial turns 0 at points $\{\alpha_1, \alpha_2, ..., \alpha_{Nc}\}$, if all y_i are assigned to correct values.

Therefore, $\alpha_1, \alpha_2, ..., \alpha_{Nc}$ are its roots, and it is divisible by $(z-\alpha_1)(z-\alpha_2)...(z-\alpha_{Nc})!$

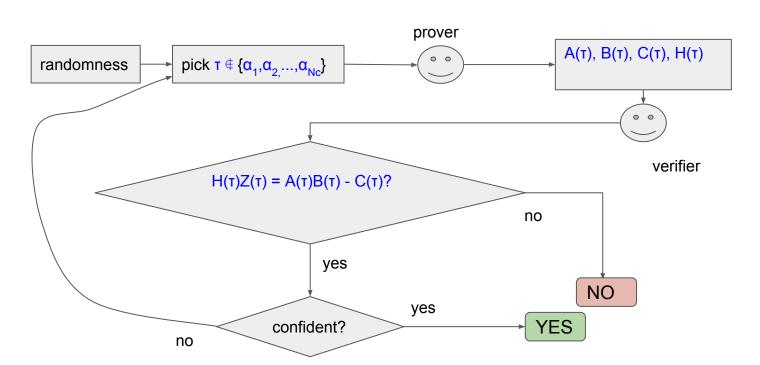
Setup (before initial game position is known)



Prover's preparation (initial position known)

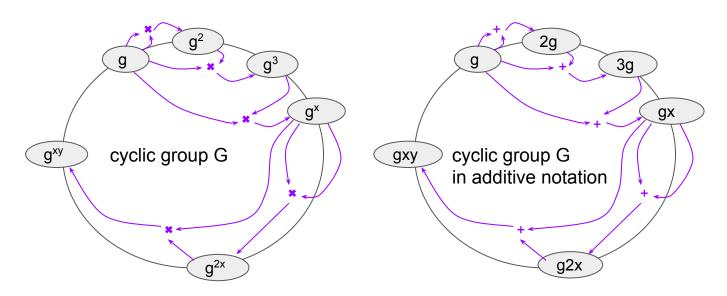


Prover cheats:
$$H(T) = A(T)B(T)-C(T)$$
 $Z(T)$



Linear PCP based on CDH

"Computational Diffie-Hellman" is the assumption that given element of the group: g, g^x , and g^y , it is computationally hard to find g^{xy}



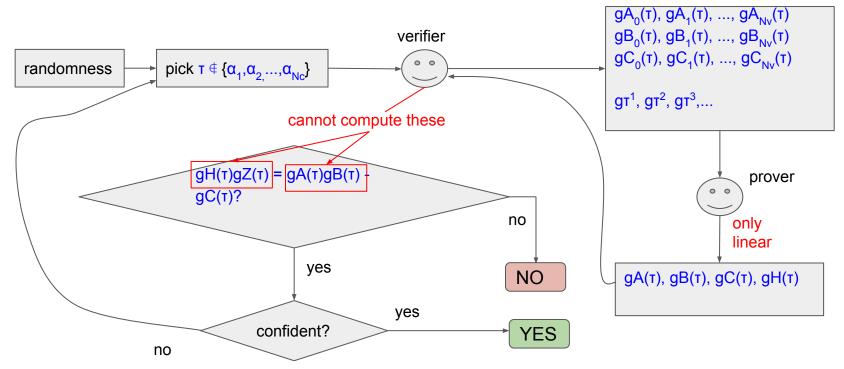
Linear PCP based on CDH

If we accept CDH assumption, we can "hide" numbers by representing them as group elements (kind of "wrapping" them). To "hide" numbers τ^1 , τ^2 ,..., verifier computes $g\tau^1$, $g\tau^2$, ... The same applies to "hiding" $A_0(\tau)$, $A_1(\tau)$,..., $A_{Nv}(\tau)$, $B_0(\tau)$, $B_1(\tau)$,..., $B_{Nv}(\tau)$, $C_0(\tau)$, $C_1(\tau)$,..., $C_{Nv}(\tau)$.

Because the prover does not know the multipliers of $g\tau^1$, $g\tau^2$, ..., $gA_0(\tau)$, $gA_1(\tau)$,..., $gA_0(\tau)$, $gB_0(\tau)$, $gB_0(\tau)$, $gB_0(\tau)$, $gC_0(\tau)$, $gC_0(\tau)$, $gC_1(\tau)$,..., $gC_{Nv}(\tau)$, computationally bounded prover cannot multiply them with each other, but it can multiply them by number and add them together. It cannot solve this equation:

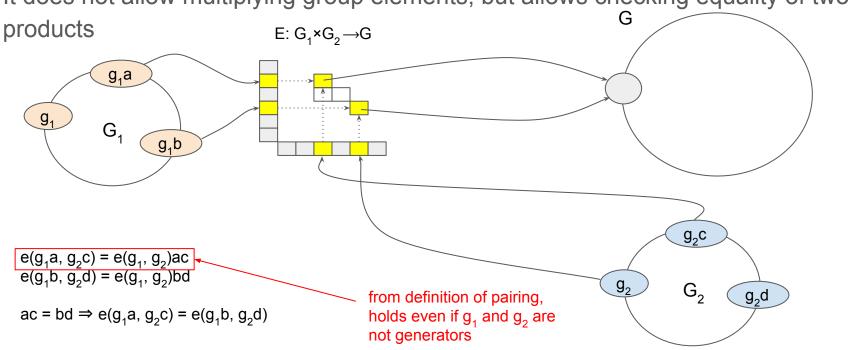
$$H(\tau) = \frac{A(\tau)B(\tau)-C(\tau)}{Z(\tau)}$$

Verifier is restricted too!



Solution - pairing

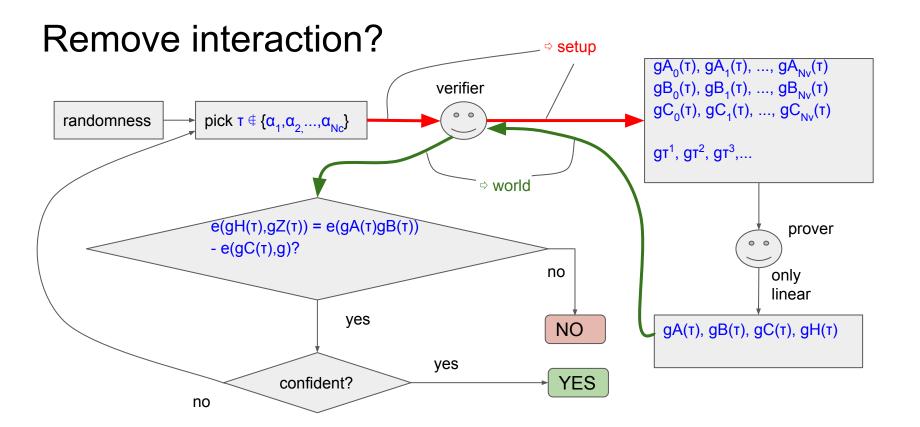
It does not allow multiplying group elements, but allows checking equality of two



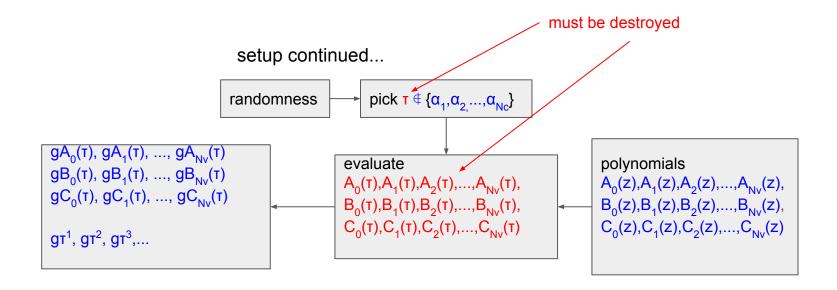
Pairings and elliptic curves

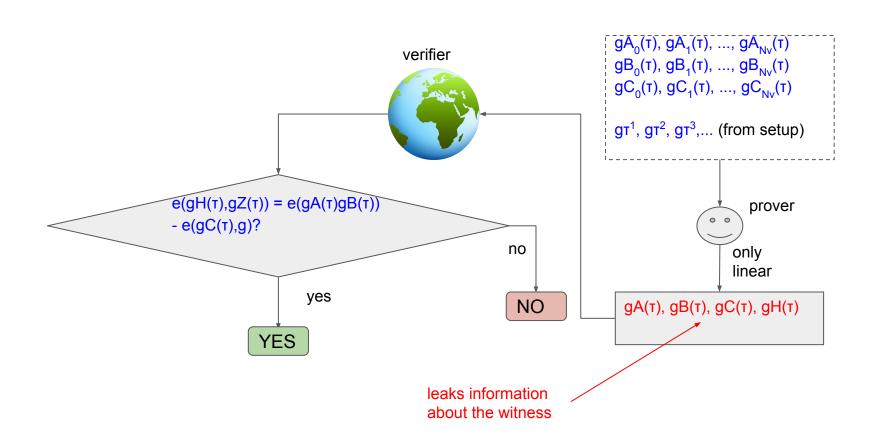
Pairings exist for some classes of groups induced by point arithmetics on elliptic curves. That is one of the reason elliptic curves are using in these constructions

Another reason - discrete logarithm is believed to be solved more easily groups of numbers (versus groups induced by elliptic curves), and solving discrete logarithm is enough to break CDH assumption



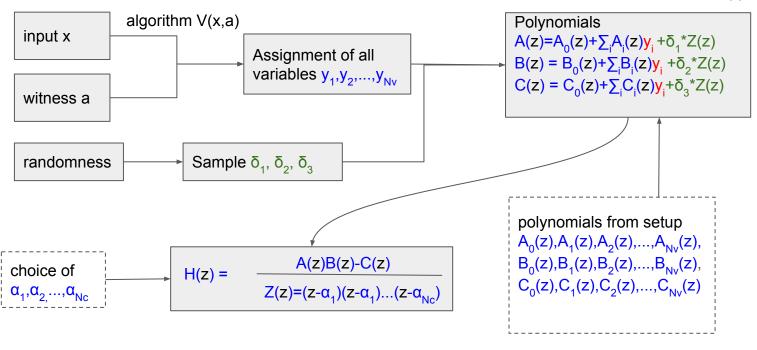
Trusted setup





Prover's preparation (zero knowledge)

Preserve divisibility, but make results appear random



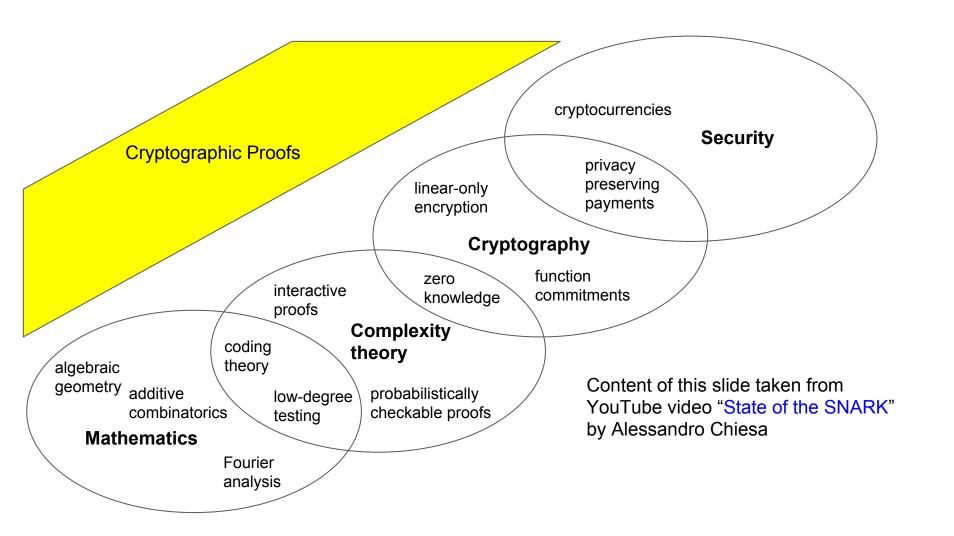
Succinctness

Proof is very short - few points of some elliptic curve: gA(t), gB(t), gC(t), gH(t)

Verification is very efficient - couple of pairings - $e(gH(\tau),gZ(\tau)) = e(gA(\tau)gB(\tau)) - e(gC(\tau),g)$?

Prover's work is proportional to the runtime of verification algorithm V(x,a)

Setup is expensive and has to be trusted - major drawback



THANK YOU