$$x_1 := 4.7$$
 $y_1 := 5.09$ $z_1 := 0.774$ $x_0 := 0$ $x_2 := 1.579$ $y_2 := 0.858$ $z_2 := 0.78$ $y_0 := 0$ $x_3 := 9$ $y_3 := 3.476$ $z_3 := 1.557$ $z_0 := 0$

$$N := 2$$

$$\begin{aligned} \text{QA}_1 &:= \begin{pmatrix} x_1 & y_1 & z_1 \end{pmatrix}^T \\ \text{QA}_2 &:= \begin{pmatrix} x_2 & y_2 & z_2 \end{pmatrix}^T \\ \text{QA}_3 &:= \begin{pmatrix} x_3 & y_3 & z_3 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix}^T \\ \text{QO}_3 &:= \begin{pmatrix} x_0 & y_0 &$$

$$\begin{split} R_{22}(x,y,z) &:= \sqrt{\left(x_2 - x\right)^2 + \left(y_2 - y\right)^2 + \left(z_2 - z\right)^2} \\ R_{33}(x,y,z) &:= \sqrt{\left(x_3 - x\right)^2 + \left(y_3 - y\right)^2 + \left(z_3 - z\right)^2} \end{split}$$

$$f(x,y,z) := \begin{pmatrix} R_{11}(x,y,z) \\ R_{22}(x,y,z) \\ R_{33}(x,y,z) \end{pmatrix}$$

$$\begin{split} & \underbrace{ H\!(x,y,z) \coloneqq \begin{pmatrix} \frac{d}{dx} R_{11}(x,y,z) & \frac{d}{dy} R_{11}(x,y,z) & \frac{d}{dz} R_{11}(x,y,z) \\ \frac{d}{dx} R_{22}(x,y,z) & \frac{d}{dy} R_{22}(x,y,z) & \frac{d}{dz} R_{22}(x,y,z) \\ \frac{d}{dx} R_{33}(x,y,z) & \frac{d}{dy} R_{33}(x,y,z) & \frac{d}{dz} R_{33}(x,y,z) \end{pmatrix} } \end{split}$$

$$\begin{aligned} \mathbf{Q}_{0} &= \begin{pmatrix} \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \end{pmatrix} \\ \mathbf{Q}_{1} &:= \mathbf{Q}_{0} + \left(\mathbf{H} \Big(\mathbf{Q}_{0_{0}}, \mathbf{Q}_{0_{1}}, \mathbf{Q}_{0_{2}} \Big)^{\mathrm{T}} \cdot \mathbf{H} \Big(\mathbf{Q}_{0_{0}}, \mathbf{Q}_{0_{1}}, \mathbf{Q}_{0_{2}} \Big)^{-1} \cdot \mathbf{H} \Big(\mathbf{Q}_{0_{0}}, \mathbf{Q}_{0_{1}}, \mathbf{Q}_{0_{2}} \Big)^{\mathrm{T}} \cdot \left(\mathbf{R} - \mathbf{f} \Big(\mathbf{Q}_{0_{0}}, \mathbf{Q}_{0_{1}}, \mathbf{Q}_{0_{2}} \Big) \right) = \begin{pmatrix} 20.208 \\ -8.752 \\ -51.451 \end{pmatrix} \\ \mathbf{Q}_{2} &:= \mathbf{Q}_{1} + \left(\mathbf{H} \Big(\mathbf{Q}_{1_{0}}, \mathbf{Q}_{1_{1}}, \mathbf{Q}_{1_{2}} \Big)^{\mathrm{T}} \cdot \mathbf{H} \Big(\mathbf{Q}_{1_{0}}, \mathbf{Q}_{1_{1}}, \mathbf{Q}_{1_{2}} \Big)^{-1} \cdot \mathbf{H} \Big(\mathbf{Q}_{1_{0}}, \mathbf{Q}_{1_{1}}, \mathbf{Q}_{1_{2}} \Big)^{\mathrm{T}} \cdot \left(\mathbf{R} - \mathbf{f} \Big(\mathbf{Q}_{1_{0}}, \mathbf{Q}_{1_{1}}, \mathbf{Q}_{1_{2}} \Big) \right) = \begin{pmatrix} 47.186 \\ 30.022 \\ 0.916 \end{pmatrix} \end{aligned}$$

$$\begin{aligned} Q_3 &:= Q_2 + \left(H\left(Q_{Q_0}, Q_{2_1}, Q_{2_2}\right)^T \cdot H\left(Q_{Q_0}, Q_{2_1}, Q_{2_2}\right)^{-1} \cdot H\left(Q_{Q_0}, Q_{2_1}, Q_{2_2}\right)^T \cdot \left(R - f\left(Q_{Q_0}, Q_{2_1}, Q_{2_2}\right)\right) = \begin{pmatrix} 14.406 \\ -0.549 \\ -0.2514 \end{pmatrix} \\ Q_4 &:= Q_3 + \left(H\left(Q_{3_0}, Q_{3_1}, Q_{3_2}\right)^T \cdot H\left(Q_{3_0}, Q_{3_1}, Q_{3_2}\right)^{-1} \cdot H\left(Q_{3_0}, Q_{3_1}, Q_{3_2}\right)^T \cdot \left(R - f\left(Q_{3_0}, Q_{3_1}, Q_{3_2}\right)\right) = \begin{pmatrix} 13.447 \\ 12.746 \\ 0.683 \end{pmatrix} \\ Q_5 &:= Q_4 + \left(H\left(Q_{3_0}, Q_{4_1}, Q_{4_2}\right)^T \cdot H\left(Q_{4_0}, Q_{4_1}, Q_{4_2}\right)^{-1} \cdot H\left(Q_{4_0}, Q_{4_1}, Q_{4_2}\right)^T \cdot \left(R - f\left(Q_{4_0}, Q_{4_1}, Q_{4_2}\right)\right) = \begin{pmatrix} 10.382 \\ 5.588 \\ -2.152 \end{pmatrix} \\ Q_6 &:= Q_5 + \left(H\left(Q_{3_0}, Q_{5_1}, Q_{5_2}\right)^T \cdot H\left(Q_{5_0}, Q_{5_1}, Q_{5_2}\right)^{-1} \cdot H\left(Q_{5_0}, Q_{5_1}, Q_{5_2}\right)^T \cdot \left(R - f\left(Q_{5_0}, Q_{5_1}, Q_{5_2}\right)\right) = \begin{pmatrix} 10.043 \\ 5.809 \\ 0.498 \end{pmatrix} \\ Q_7 &:= Q_6 + \left(H\left(Q_{5_0}, Q_{5_1}, Q_{5_2}\right)^T \cdot H\left(Q_{6_0}, Q_{6_1}, Q_{6_2}\right)^{-1} \cdot H\left(Q_{6_0}, Q_{5_1}, Q_{5_2}\right)^T \cdot \left(R - f\left(Q_{6_0}, Q_{5_1}, Q_{5_2}\right)\right) = \begin{pmatrix} 10.124 \\ 2.034 \end{pmatrix} \\ Q_8 &:= Q_7 + \left(H\left(Q_{7_0}, Q_{7_1}, Q_{7_2}\right)^T \cdot H\left(Q_{6_0}, Q_{7_1}, Q_{7_2}\right)^{-1} \cdot H\left(Q_{6_0}, Q_{6_1}, Q_{6_2}\right)^T \cdot \left(R - f\left(Q_{6_0}, Q_{6_1}, Q_{6_2}\right)\right) = \begin{pmatrix} 10.432 \\ 3.881 \\ -0.053 \end{pmatrix} \\ Q_9 &:= Q_8 + \left(H\left(Q_{9_0}, Q_{7_1}, Q_{7_2}\right)^T \cdot H\left(Q_{8_0}, Q_{7_1}, Q_{7_2}\right)^{-1} \cdot H\left(Q_{8_0}, Q_{8_1}, Q_{8_2}\right)^T \cdot \left(R - f\left(Q_{9_0}, Q_{7_1}, Q_{7_2}\right)\right) = \begin{pmatrix} 10.238 \\ 5.881 \\ -0.053 \end{pmatrix} \\ Q_1 &:= Q_1 + \left(H\left(Q_{10_0}, Q_{11_0}, Q_{11_0}\right)^T \cdot H\left(Q_{10_0}, Q_{11_0}, Q_{10_2}\right)^{-1} \cdot H\left(Q_{10_0}, Q_{11_0}, Q_{10_2}\right)^T \cdot \left(R - f\left(Q_{10_0}, Q_{11_0}, Q_{12_0}\right)\right) = \begin{pmatrix} 10.238 \\ 4.194 \\ -1.5958 \end{pmatrix} \\ Q_1 &:= Q_1 + \left(H\left(Q_{10_0}, Q_{10_1}, Q_{10_2}\right)^T \cdot H\left(Q_{10_0}, Q_{11_0}, Q_{10_2}\right)^{-1} \cdot H\left(Q_{10_0}, Q_{10_1}, Q_{10_2}\right)^T \cdot \left(R - f\left(Q_{10_0}, Q_{10_1}, Q_{10_2}\right)\right) = \begin{pmatrix} 11.8526 \\ 6.892 \\ 3.492 \end{pmatrix} \\ Q_1 &:= Q_1 + \left(H\left(Q_{10_0}, Q_{10_1}, Q_{10_2}\right)^T \cdot H\left(Q_{10_0}, Q_{10_1}, Q_{10_2}\right)^{-1} \cdot H\left(Q_{10_0}, Q_{10_1}, Q_{10_2}\right)^T \cdot \left(R - f\left(Q_{10_0}, Q_{10_1}, Q_{10_2}\right)\right) = \begin{pmatrix} 11.8526 \\ 6.892 \\ 3.492 \end{pmatrix} \\ Q_1 &:= Q_1 + \left(H\left(Q_{10_0}, Q_{10_1}, Q_{10_2}\right)^T \cdot H\left(Q_{10_$$

$$\begin{aligned} &Q_{18} \coloneqq Q_{17} + \left(H\left(Q_{17_0}, Q_{17_1}, Q_{17_2}\right)^T \cdot H\left(Q_{17_0}, Q_{17_1}, Q_{17_2}\right)^{-1} \cdot H\left(Q_{17_0}, Q_{17_1}, Q_{17_2}\right)^T \cdot \left(R - f\left(Q_{17_0}, Q_{17_1}, Q_{17_2}\right) \right) = \begin{pmatrix} 9.811 \\ 6.343 \\ 4.321 \end{pmatrix} \\ &Q_{19} \coloneqq Q_{18} + \left(H\left(Q_{18_0}, Q_{18_1}, Q_{18_2}\right)^T \cdot H\left(Q_{18_0}, Q_{18_1}, Q_{18_2}\right)^{-1} \cdot H\left(Q_{18_0}, Q_{18_1}, Q_{18_2}\right)^T \cdot \left(R - f\left(Q_{18_0}, Q_{18_1}, Q_{18_2}\right) \right) = \begin{pmatrix} 10.281 \\ 6.055 \\ 2.143 \end{pmatrix} \\ &Q_{20} \coloneqq Q_{19} + \left(H\left(Q_{19_0}, Q_{19_1}, Q_{19_2}\right)^T \cdot H\left(Q_{19_0}, Q_{19_1}, Q_{19_2}\right)^{-1} \cdot H\left(Q_{19_0}, Q_{19_1}, Q_{19_2}\right)^T \cdot \left(R - f\left(Q_{19_0}, Q_{19_1}, Q_{19_2}\right) \right) = \begin{pmatrix} 10.394 \\ 5.915 \\ 0.176 \end{pmatrix} \\ &Q_{21} \coloneqq Q_{20} + \left(H\left(Q_{20_0}, Q_{20_1}, Q_{20_2}\right)^T \cdot H\left(Q_{20_0}, Q_{20_1}, Q_{20_2}\right)^{-1} \cdot H\left(Q_{20_0}, Q_{20_1}, Q_{20_2}\right)^T \cdot \left(R - f\left(Q_{20_0}, Q_{20_1}, Q_{20_2}\right) \right) = \begin{pmatrix} 10.196 \\ 6.062 \\ 1.726 \end{pmatrix} \\ &Q_{22} \coloneqq Q_{21} + \left(H\left(Q_{21_0}, Q_{21_1}, Q_{21_2}\right)^T \cdot H\left(Q_{21_0}, Q_{21_1}, Q_{21_2}\right)^{-1} \cdot H\left(Q_{21_0}, Q_{21_1}, Q_{21_2}\right)^T \cdot \left(R - f\left(Q_{20_0}, Q_{20_1}, Q_{20_2}\right) \right) = \begin{pmatrix} 10.74 \\ 5.65 \\ -2.251 \end{pmatrix} \\ &Q_{23} \coloneqq Q_{22} + \left(H\left(Q_{22_0}, Q_{22_1}, Q_{22_2}\right)^T \cdot H\left(Q_{20_0}, Q_{21_1}, Q_{22_2}\right)^{-1} \cdot H\left(Q_{20_0}, Q_{21_1}, Q_{22_2}\right)^T \cdot \left(R - f\left(Q_{20_0}, Q_{21_1}, Q_{21_2}\right) \right) = \begin{pmatrix} 10.74 \\ 5.644 \\ 0.605 \end{pmatrix} \\ &Q_{24} \coloneqq Q_{23} + \left(H\left(Q_{23_0}, Q_{23_1}, Q_{22_2}\right)^T \cdot H\left(Q_{23_0}, Q_{23_1}, Q_{22_2}\right)^{-1} \cdot H\left(Q_{23_0}, Q_{23_1}, Q_{22_2}\right)^T \cdot \left(R - f\left(Q_{23_0}, Q_{23_1}, Q_{22_2}\right) \right) = \begin{pmatrix} 10.103 \\ 6.143 \\ 2.205 \end{pmatrix} \\ &Q_{25} \coloneqq Q_{24} + \left(H\left(Q_{24_0}, Q_{24_1}, Q_{24_2}\right)^T \cdot H\left(Q_{24_0}, Q_{24_1}, Q_{24_2}\right)^{-1} \cdot H\left(Q_{24_0}, Q_{24_1}, Q_{24_2}\right)^T \cdot \left(R - f\left(Q_{24_0}, Q_{24_1}, Q_{24_2}\right) \right) = \begin{pmatrix} 10.367 \\ 5.93 \\ 0.421 \end{pmatrix} \\ &Q_{25} = Q_{24} + \left(H\left(Q_{24_0}, Q_{24_1}, Q_{24_2}\right)^T \cdot H\left(Q_{24_0}, Q_{24_1}, Q_{24_2}\right)^{-1} \cdot H\left(Q_{24_0}, Q_{24_1}, Q_{24_2}\right)^T \cdot \left(R - f\left(Q_{24_0}, Q_{24_1}, Q_{24_2}\right) \right) = \begin{pmatrix} 10.367 \\ 5.93 \\ 0.421 \end{pmatrix}$$