

Generative Adversarial Networks - Part 1

11785 - Introduction to Deep Learning
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Slides Inspired by Akshat Gupta
and Benjamin Striner

“This (GANS), and the variations that are now being proposed is the most interesting idea in the last 10 years in ML, in my opinion”

–Yann LeCun

DeepFake head-swapped Video

- <https://www.youtube.com/watch?v=34AmKPJNfCg>

Contents

- Motivation
- Generative vs Discriminative Models
- GANs vs VAEs
- GANs Introduction
- GANs Theory
- GANs Evaluation

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- **Motivation**
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Motivation

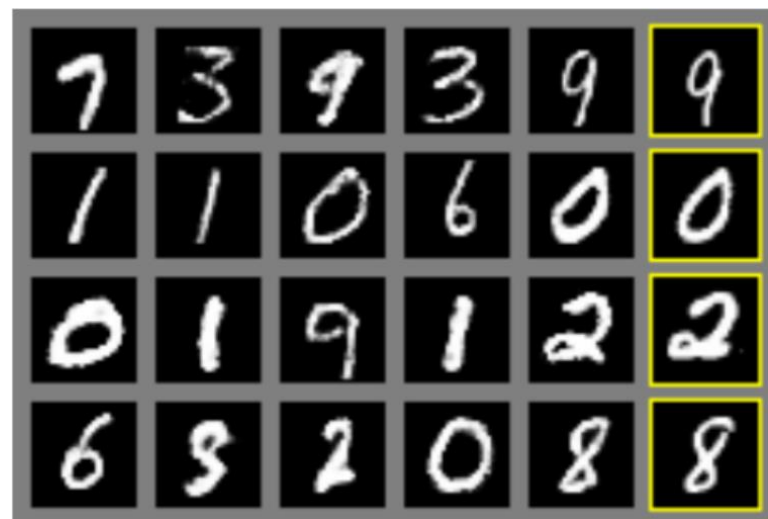
Generative networks are used to generate samples from an unlabeled distribution $P(X)$ given samples X_1, \dots, X_n . For example:

- Learn to generate realistic images given exemplary images
- Learn to generate realistic music given exemplary recordings
- Learn to generate realistic text given exemplary corpus

Let's see some amazing work of GANs

Original paper (GAN, 2014)

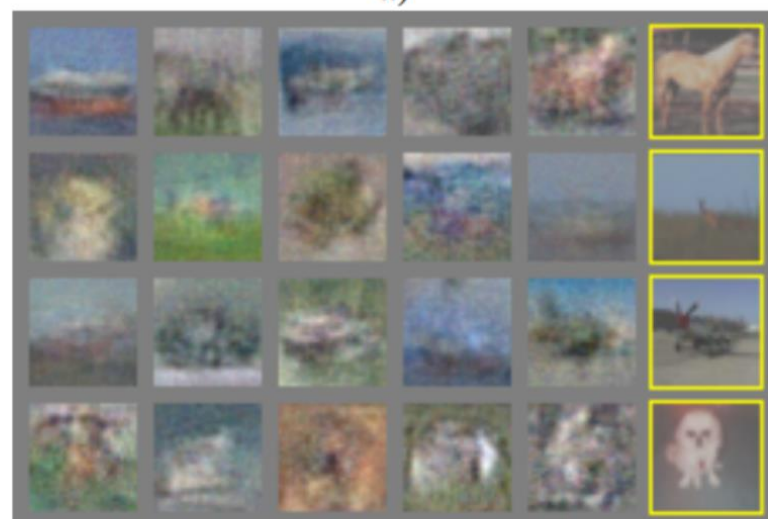
Output of original GAN paper, 2014 [GPM⁺14]



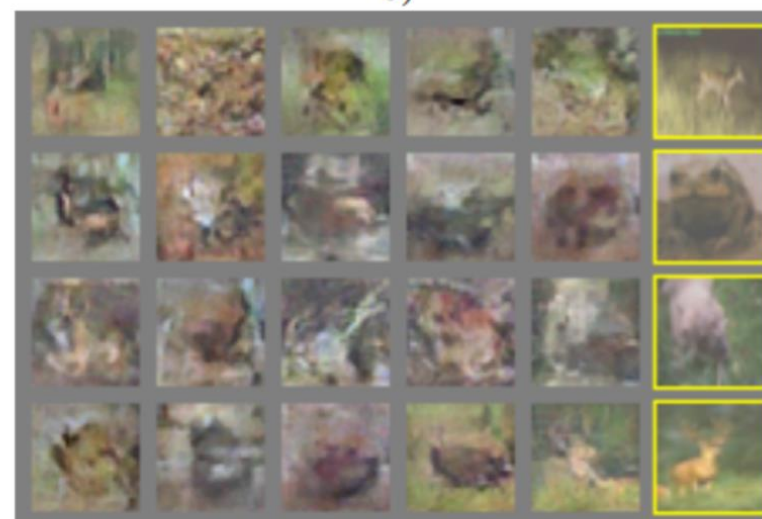
a)



b)



c)



d)

GANs progression

- Better quality
- High Resolution



https://twitter.com/goodfellow_ian/status/1084973596236144640?lang=en

StarGAN(2018)

Manipulating Celebrity Faces [CCK⁺17]

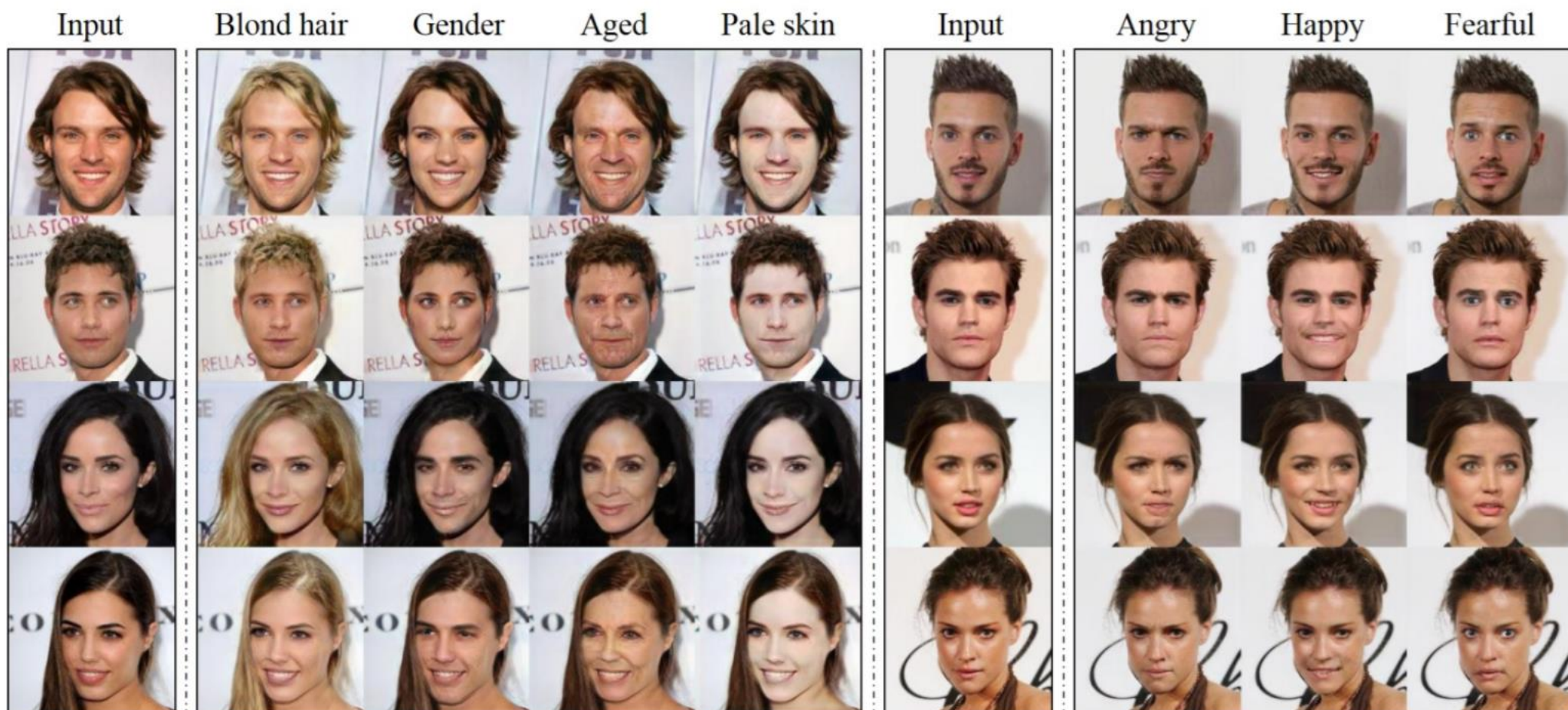


Figure 1. Multi-domain image-to-image translation results on the CelebA dataset via transferring knowledge learned from the RaFD dataset. The first and sixth columns show input images while the remaining columns are images generated by StarGAN. Note that the images are generated by a single generator network, and facial expression labels such as angry, happy, and fearful are from RaFD, not CelebA.

Progressive growing of GANs (2018)



Figure 5: 1024×1024 images generated using the CELEBA-HQ dataset. See Appendix F for a larger set of results, and the accompanying video for latent space interpolations.

High fidelity natural images (2019)

Generating High-Quality Images [BDS18]



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Discriminative vs Generative Models

Given a distribution of inputs X and labels Y .

Discriminative models
learn conditional
distribution $P(Y | X)$

Generative models learn
the joint distribution $P(Y, X)$

Discriminative vs Generative Models

Given a distribution of inputs X and labels Y .

Discriminative models

- Discriminative models learn conditional distribution $P(Y | X)$
- Learns decision boundary between classes.
- Limited scope. Can only be used for classification tasks.
- E.g. Logistic regression, SVM etc.

Generative models

- Generative models learn the joint distribution $P(Y, X)$
- Learns actual probability distribution of data.
- Can do both generative and discriminative tasks.
- E.g. Naïve Bayes, Gaussian Mixture Model etc.
- Harder problem, requires a deeper understanding of the distribution than discriminative models.

Explicit vs Implicit Models

Explicit distribution models

- Calculates $P(x \sim X)$ for all x

Implicit distribution models

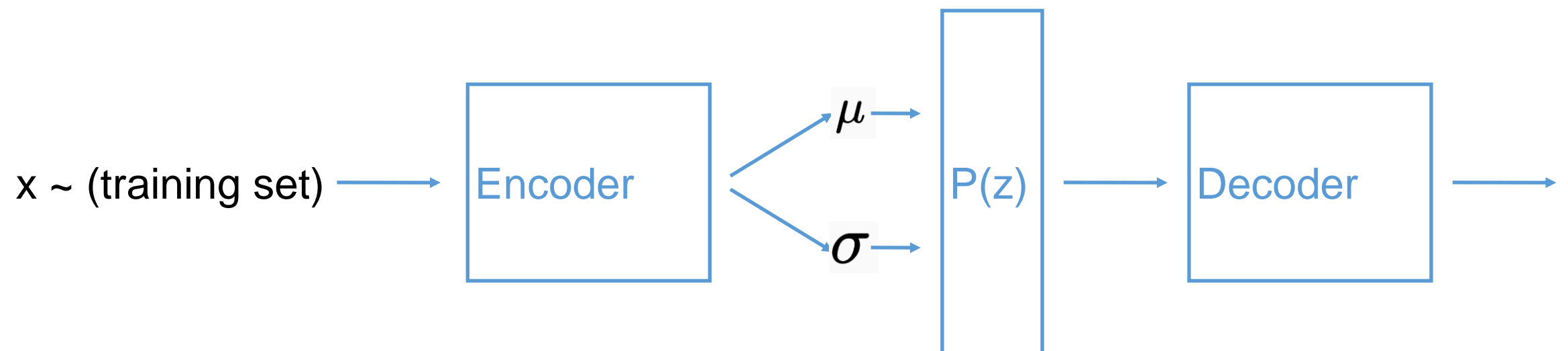
- Generate $x \sim X$

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Variational autoencoders (VAE)

- Encoder models $P(Z|X)$
- Decoder models $P(X|Z)$
- Loss encourages $P(Z|X) \sim Q(Z)$



VAEs vs GANs

VAEs

- Minimizing the KL-divergence
- Minimize a bound on the divergence between generated distribution and target distribution
- Simpler optimization. Trains faster and more reliably
- Results are blurry

GANs

- Minimizing the Jensen-Shannon Divergence
- Minimize divergence between generated distribution and target distribution
- Noisy and difficult optimization
- Sharper results

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What are GANs?

Generative Adversarial Networks

What are GANs?

Generative Adversarial Networks



Generative Models

We try to learn the underlying the distribution from which our dataset comes from.

Eg: Variational AutoEncoders (VAE)

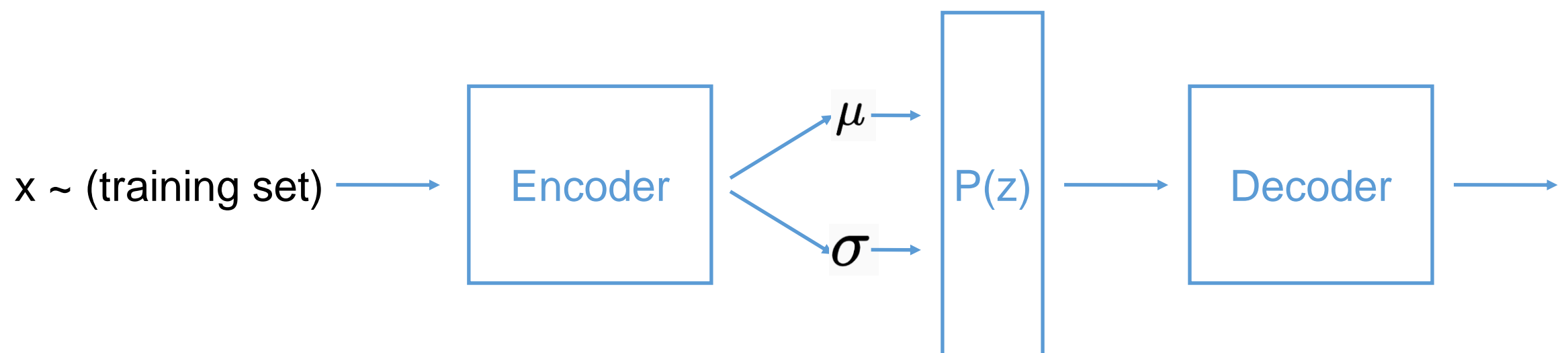
What are GANs?

Generative Adversarial Networks

Generative Models

We try to learn the underlying the distribution from which our dataset comes from.

E.g. Variational Autoencoders (VAE)



What are GANs?

Generative Adversarial Networks

```
graph TD; A([Generative Adversarial Networks]) --> B[Generative Models]; A --> C[Adversarial Training]; A --> D[Neural Networks];
```

Generative Models

We try to learn the underlying the distribution from which our dataset comes from.

E.g. Variational Autoencoders (VAE)

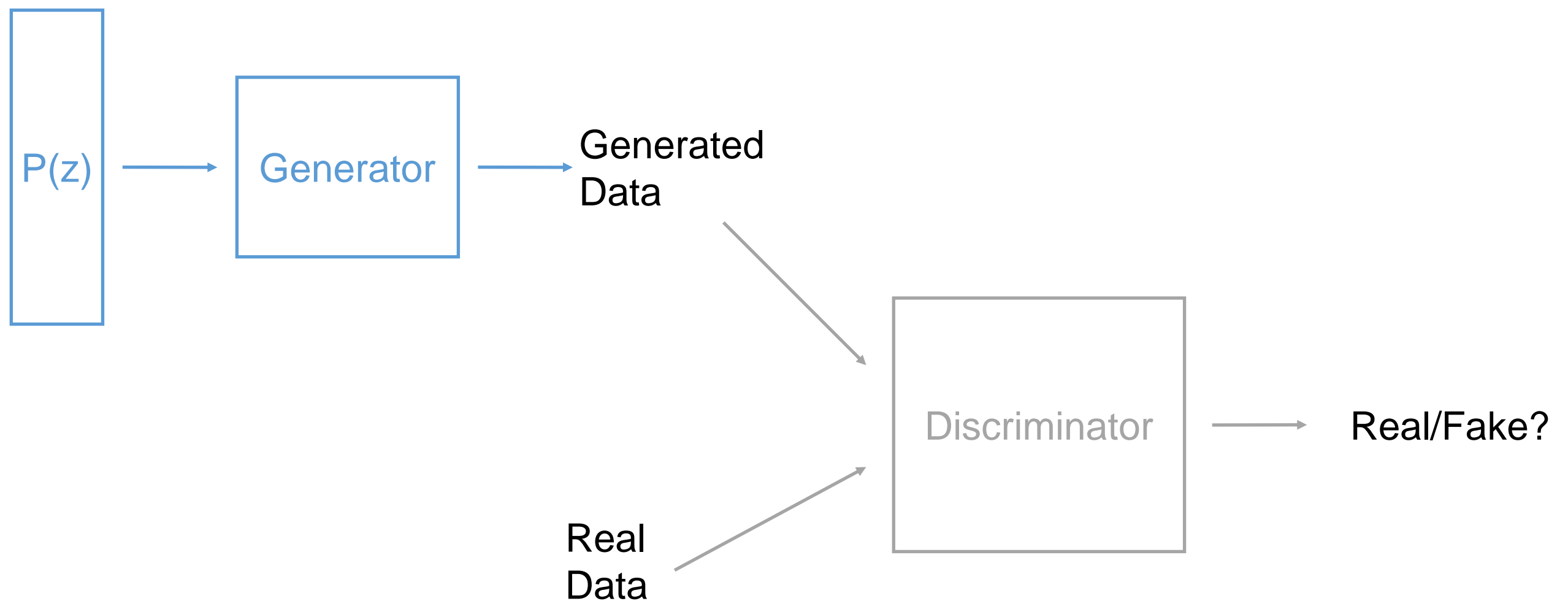
Adversarial Training

GANs are made up of two competing networks (adversaries) that are trying beat each other.

Neural Networks

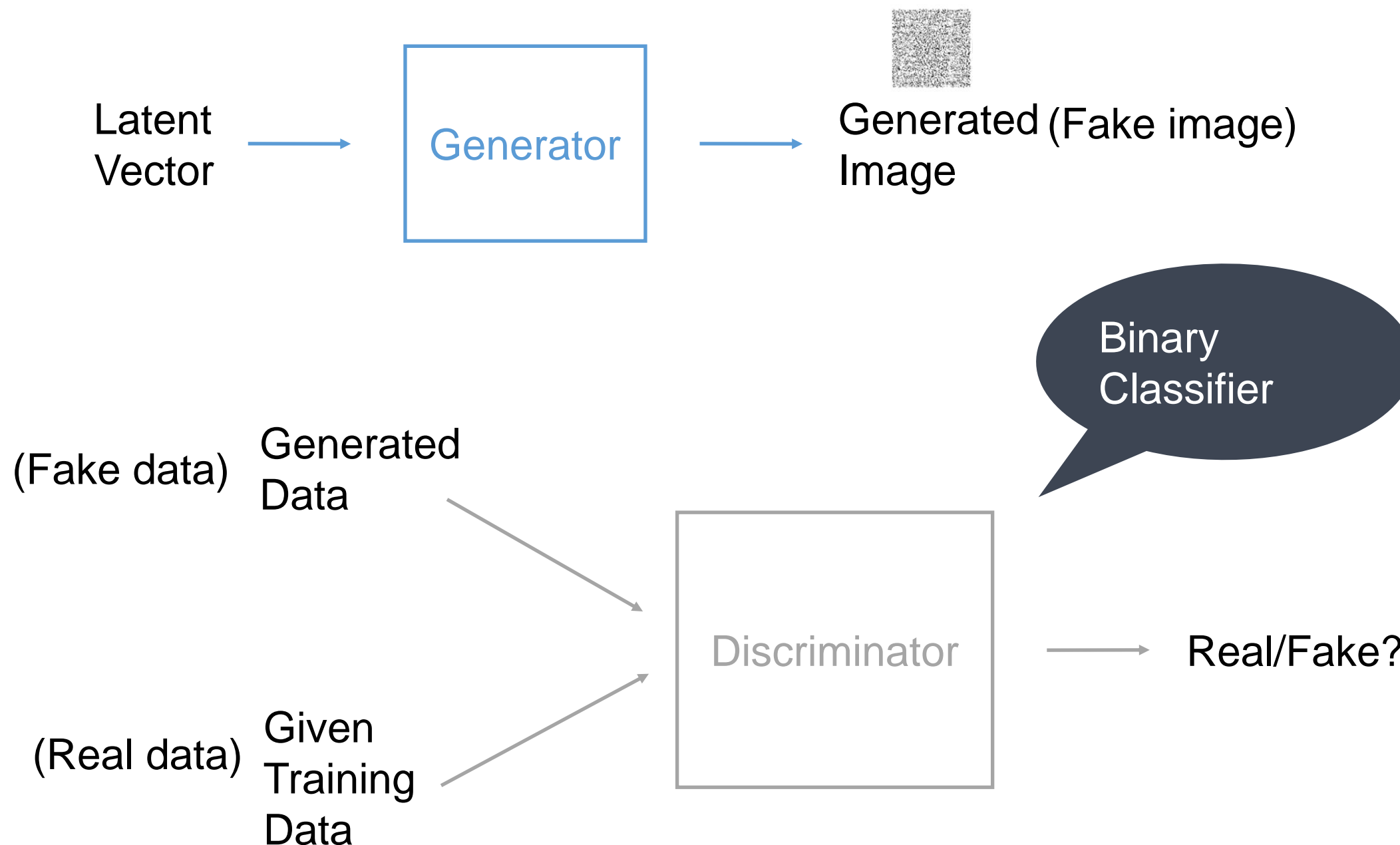
Goal: Generate data from an unlabeled distribution.

What are GANs?



How to Train a GAN?

At $t = 0$,



How to Train a GAN?

Which network should I train first?

Discriminator!

But with what training data?

The Discriminator is a Binary classifier.

The Discriminator has two class - Real and Fake.

The data for Real class is already given: **the training dataset**

The data for Fake class? generate from the Generator

How to Train a GAN?

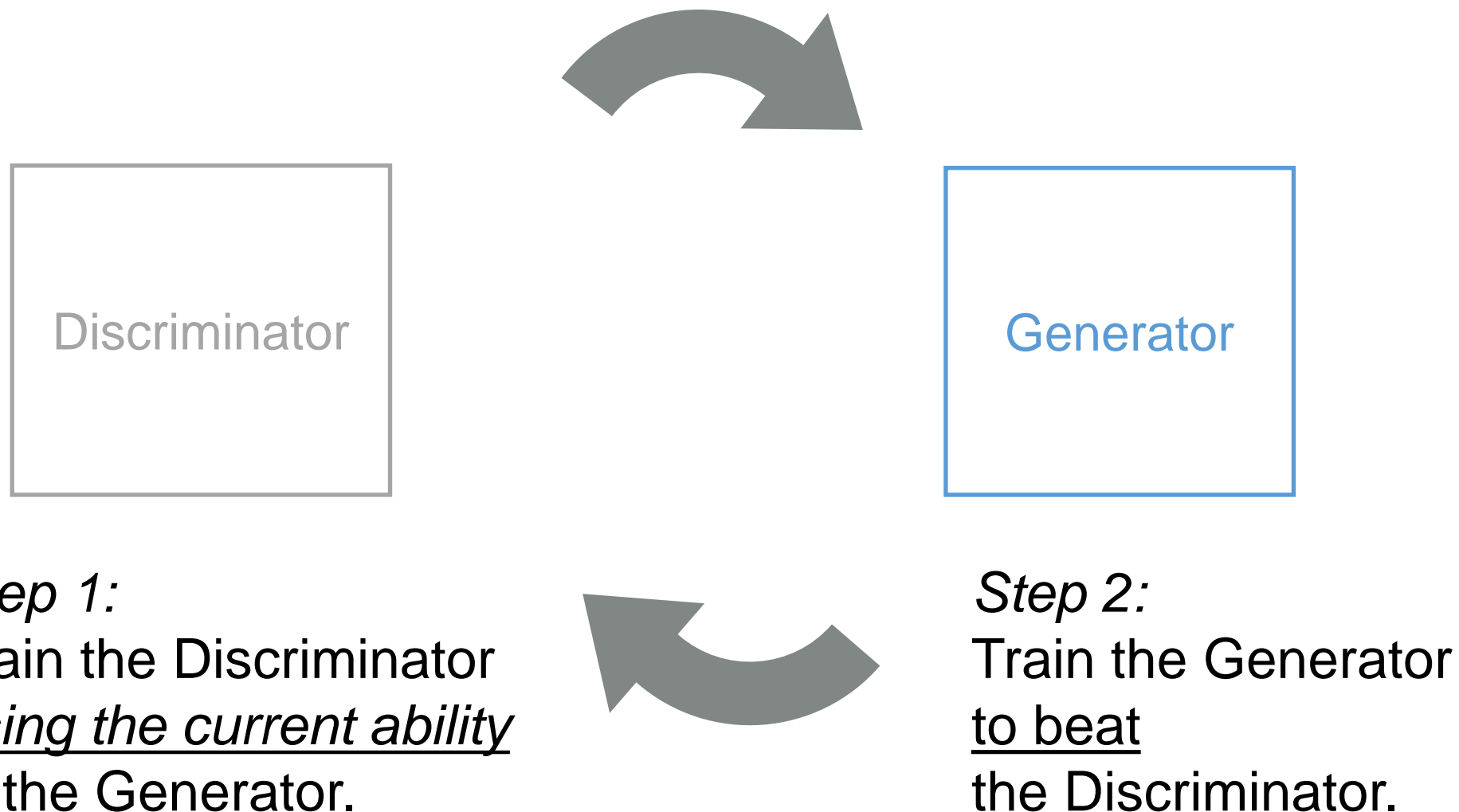
What's next?

Train the Generator!

But how? What's our training objective?

Generate images from the Generator
such that they are classified incorrectly by the Discriminator!

How to Train a GAN?



Generate images from the Generator such that they are classified incorrectly by the Discriminator!

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Generative Adversarial Networks

- Introduced in 2014
- Goal is to model $P(X)$, the distribution of training data
- Model can generate samples from $P(X)$
- Trained using a pair of models acting as “adversaries”

The Generator

- The generator learns $P(X|Z)$: Produces realistic looking data X from a latent vector Z
- Z
 - It can be sampled from a known prior, such as a Gaussian
 - It can also be the input to your desired model, such as processed speech segments in Unsupervised Speech Recognition
- Maps a simple known distribution to a complicated data distribution
- **Goal:** generated distribution, $G(z)$, matches the true data distribution $P(X)$

The Discriminator

- Trained to tell the difference between real and generated (fake) data
- **Loss function / criterion:** backpropagates its expectations to the generator
- “Thrown away” after generator is trained

The Optimal Discriminator

The original GAN formulation is the following min-max game

$$\min_G \max_D V(D, G) = \mathbb{E}_X \log D(X) + \mathbb{E}_Z \log(1 - D(G(Z)))$$

- D wants $D(X) = 1$ and $D(G(Z)) = 0$
- G wants $D(G(Z)) = 1$

The Optimal Discriminator

What is the optimal discriminator?

$$\begin{aligned} f &:= \mathbb{E}_{X \sim P_D} \log D(X) + \mathbb{E}_{X \sim P_G} \log(1 - D(X)) \\ &= \int_X [P_D(X) \log D(X) + P_G(X) \log(1 - D(X))] dX \end{aligned}$$

$$\frac{\partial f}{\partial D(X)} = \frac{P_D(X)}{D(X)} - \frac{P_G(X)}{1 - D(X)} = 0$$

$$\frac{P_D(X)}{D(X)} = \frac{P_G(X)}{1 - D(X)}$$

$$(1 - D(X))P_D(X) = D(X)P_G(X)$$

$$D(X) = \frac{P_D(X)}{P_G(X) + P_D(X)}$$

$D(X)$ = discriminator output

P_D = PDF of actual data distribution

P_G = PDF of generated data distribution

The Optimal Discriminator

$$D(X) = \frac{P_D(X)}{P_D(X) + P_G(X)}$$

$D(X)$ = discriminator output

P_D = PDF of actual data distribution

P_G = PDF of generated data distribution

Case 1: Bad Generator

“There’s no way the input $X = G(Z)$ looks like my data”

$$P_D(X) = 0, P_G(X) = 1$$

$$D(X) = 0$$

The Optimal Discriminator

$$D(X) = \frac{P_D(X)}{P_D(X) + P_G(X)}$$

$D(X)$ = discriminator output

P_D = PDF of actual data distribution

P_G = PDF of generated data distribution

Case 2: Good Generator

“I cannot tell the difference between $X = G(Z)$ and my data”

$$P_D(X) = 1, P_G(X) = 1$$

$$D(X) = 0.5$$

The Optimal Generator

Objective: $\min_G \max_D V(D, G) = \mathbb{E}_X \log D(X) + \mathbb{E}_Z \log(1 - D(G(Z)))$

Minimize:

$$\begin{aligned} f &= \mathbb{E}_{X \sim P_D} \log D(X) + \mathbb{E}_{X \sim P_G} (1 - \log D(X)) \\ &= \mathbb{E}_{X \sim P_D} \log \frac{P_D(X)}{P_D(X) + P_G(X)} + \mathbb{E}_{X \sim P_G} \log \frac{P_G(X)}{P_D(X) + P_G(X)} \\ &= \text{JSD}(P_D || P_G) - \log 4 \end{aligned}$$

$D(X)$ = discriminator output

$G(Z)$ = generator output

P_D = PDF of actual data distribution

P_G = PDF of generated data distribution

The Optimal Generator

$$\begin{aligned} f &= \mathbb{E}_{X \sim P_D} \log D(X) + \mathbb{E}_{X \sim P_G} (1 - \log D(X)) \\ &= \mathbb{E}_{X \sim P_D} \log \frac{P_D(X)}{P_D(X) + P_G(X)} + \mathbb{E}_{X \sim P_G} \log \frac{P_G(X)}{P_D(X) + P_G(X)} \\ &= \text{JSD}(P_D || P_G) - \log 4 \end{aligned}$$

Jenson-Shannon Divergence:

$$m(X) = \frac{P_D(X) + P_G(X)}{2}$$

$$\text{JSD}(P_D || P_G) = \frac{1}{2} \text{KLD}(P_D || m(X)) + \frac{1}{2} \text{KLD}(P_G || m(X))$$

The Optimal Generator

$$\min_G \text{JSD}(P_D || P_G) - \log 4$$

Minimize the Jensen-Shannon divergence between the real and generated distributions

Make the distributions similar

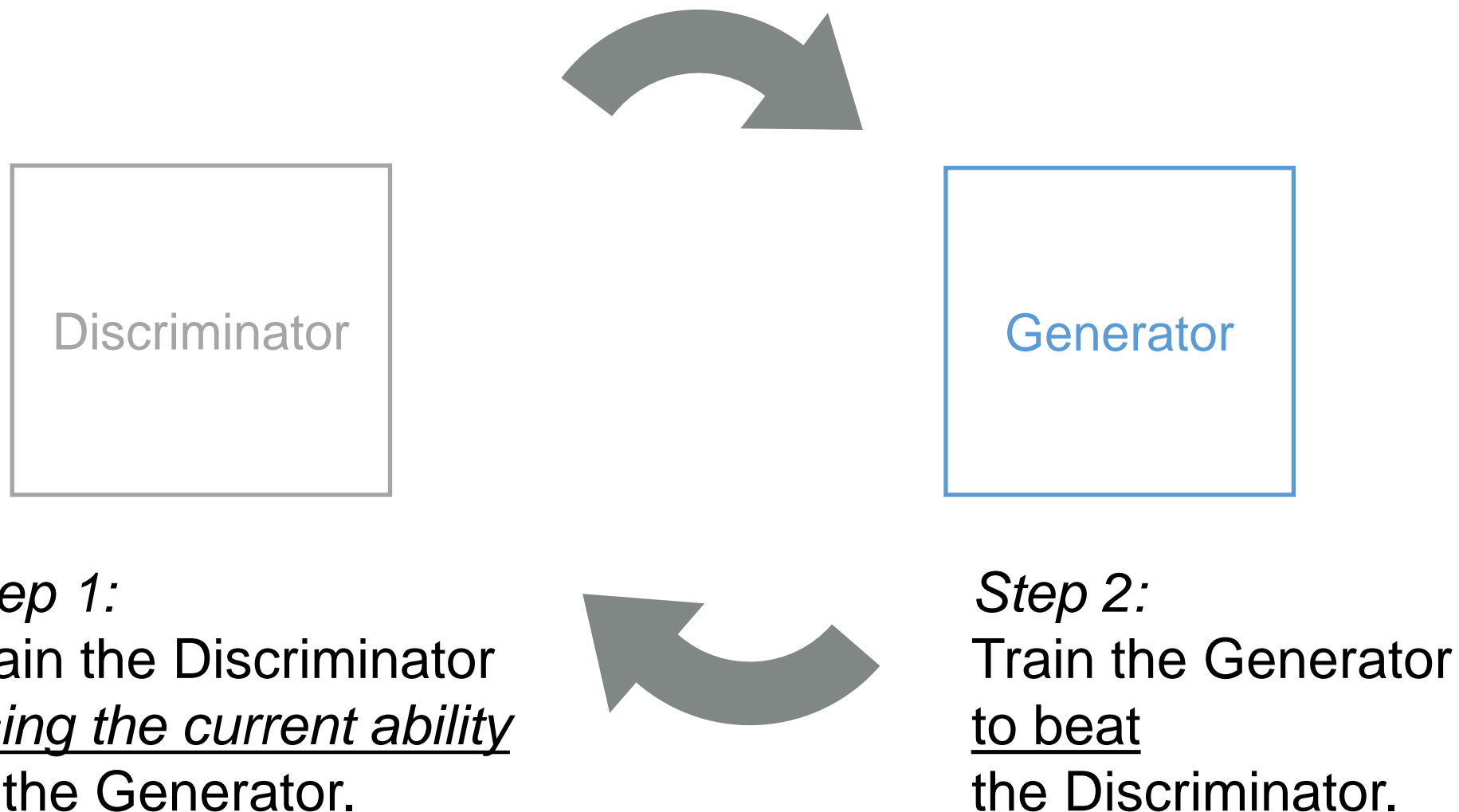
Min-Max Stationary Point

- There exists a stationary point:
 - If the generated data exactly matches the real data, the discriminator outputs 0.5 for all inputs
 - If discriminator outputs 0.5, the gradients for the generator is flat, so generator does not learn
- Stationary points need not be stable (depends on the exact GANs formulation and other factors)
 - Generator may overshoot some values or oscillate around the optimum
 - A discriminator with unlimited capacity can still assign an arbitrarily large distance to 2 similar distributions

Min-Max Optimization

- Generator and the discriminator need to be trained simultaneously
 - If discriminator is undertrained, it provides sub-optimal feedback to the generator
 - If the discriminator is overtrained, there is no local feedback for marginal improvements

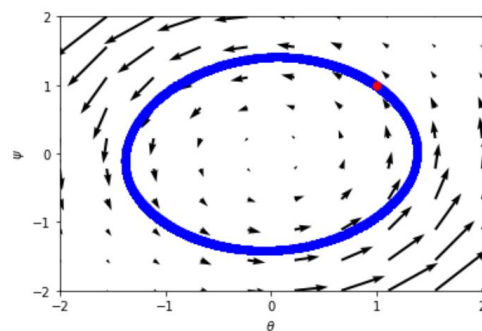
How to Train a GAN?



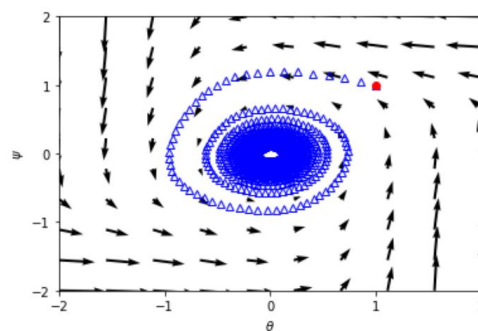
Objective: $\min_G \max_D V(D, G) = \mathbb{E}_X \log D(X) + \mathbb{E}_Z \log(1 - D(G(Z)))$

GAN Stability

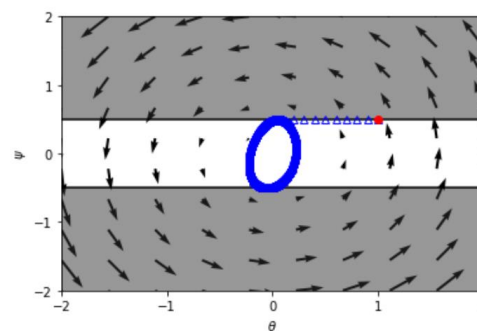
- GANs can be very sensitive to hyperparameters
- There are many variations of GANs that attempt to make the stationary point more stable



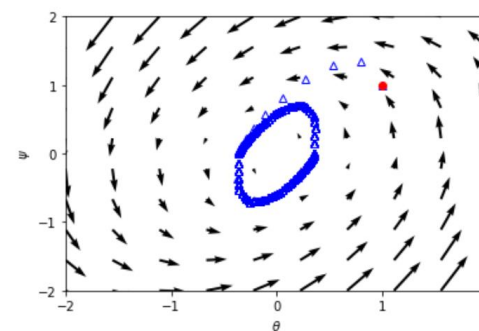
(a) Standard GAN



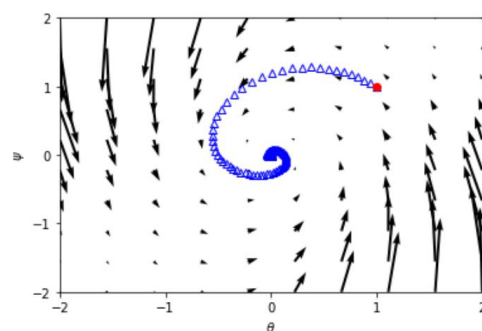
(b) Non-saturating GAN



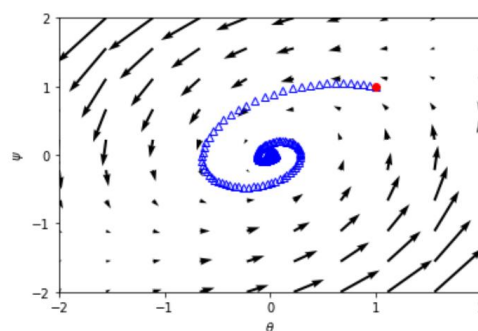
(c) WGAN ($n_d = 5$)



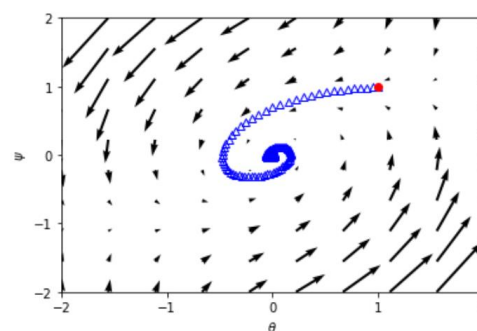
(d) WGAN-GP ($n_d = 5$)



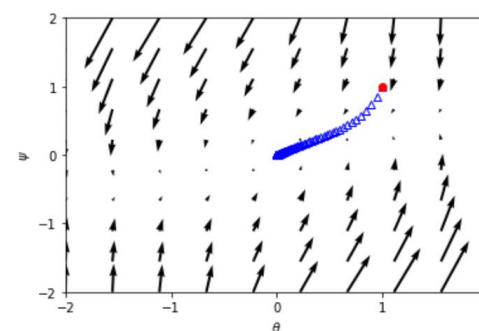
(e) Consensus optimization



(f) Instance noise



(g) Gradient penalty



(h) Gradient penalty (CR)

<https://avg.is.tuebingen.mpg.de/projects/convergence-and-stability-of-gan-training>

Perceptual Loss

- Although an idealized discriminator just calculates the JS divergence, a real discriminator calculates something much more complicated
 - E.g. discriminator loss is shift invariant to inputs if it's a convolutional neural network
- We can ideally choose a loss function to better gauge similarity from humans' perspective instead of simple L_2 loss
 - E.g. Feature Reconstruction Loss and Style Reconstruction Loss from the paper *Perceptual Losses for Real-Time Style Transfer and Super-Resolution*

The Good, the Bad, and the Ugly

- **Good** GANs can produce awesome, crisp results for many problems
- **Bad** GANs have stability issues and open theoretical questions
- Many **ugly** (ad-hoc) tricks and modifications to get GANs to work correctly

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GANs Evaluation

- Some tasks like unsupervised speech recognition have a clearly-defined metric
 - An Generator-equivalent model can be trained in a supervised manner
- Other tasks like generating realistic-looking images is not as easily quantified as a task like correctly labeling images
- Possible evaluation methods for generated distributions
 - Human Evaluation
 - Approximate Test Set likelihood
 - Evaluate with Discriminative Network

Human Evaluation

- Expensive, time-consuming, non-reproducible
- Yet maybe the only justifiable way to claim that the generated images are realistic
- Maybe it's not so bad with MechanicalTurk

Evaluate with Discriminative Network

- Inception Score
 - Use a discriminative network (originally based on Inception v3 Architecture) to classify generated images
 - Inception should produce a variety of labels
 - Each label should have high confidence (low entropy)

Questions?