

CME 213, ME 339—Spring 2021

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“You can either have software quality or you can have pointer arithmetic, but you cannot have both at the same time.” (Bertrand Meyer)

## GPU Optimization



Optimize data transfer from GPU memory

- Caches are used to optimize memory accesses: L1 and L2 caches.
- Cache behavior is complicated and depends on the compute capability of the GPU.
- We will focus on Turing sm\_75

## L1 cache

- Used for local memory (memory local to each thread) and register spills (not enough space for all the registers).
- Data that is read-only for the entire lifetime of the kernel (as determined by the compiler) can be cached in L1.
- Local to an SM.

## L2 cache

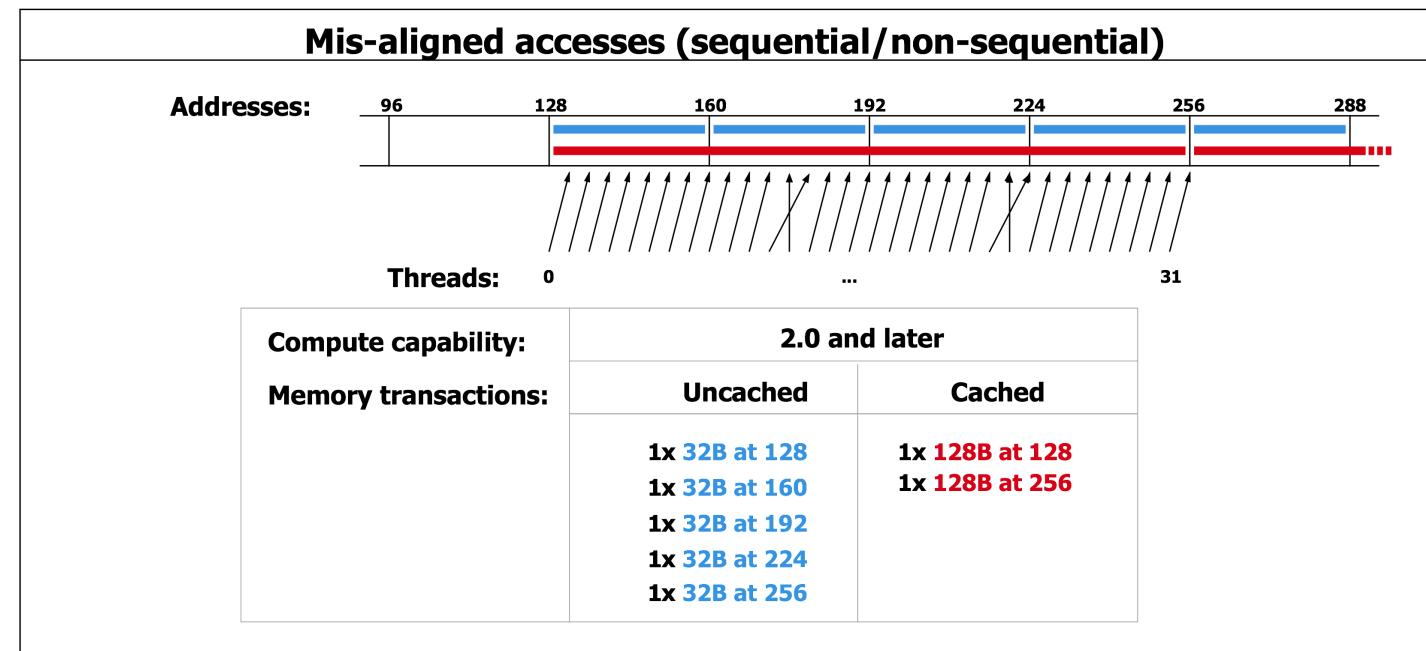
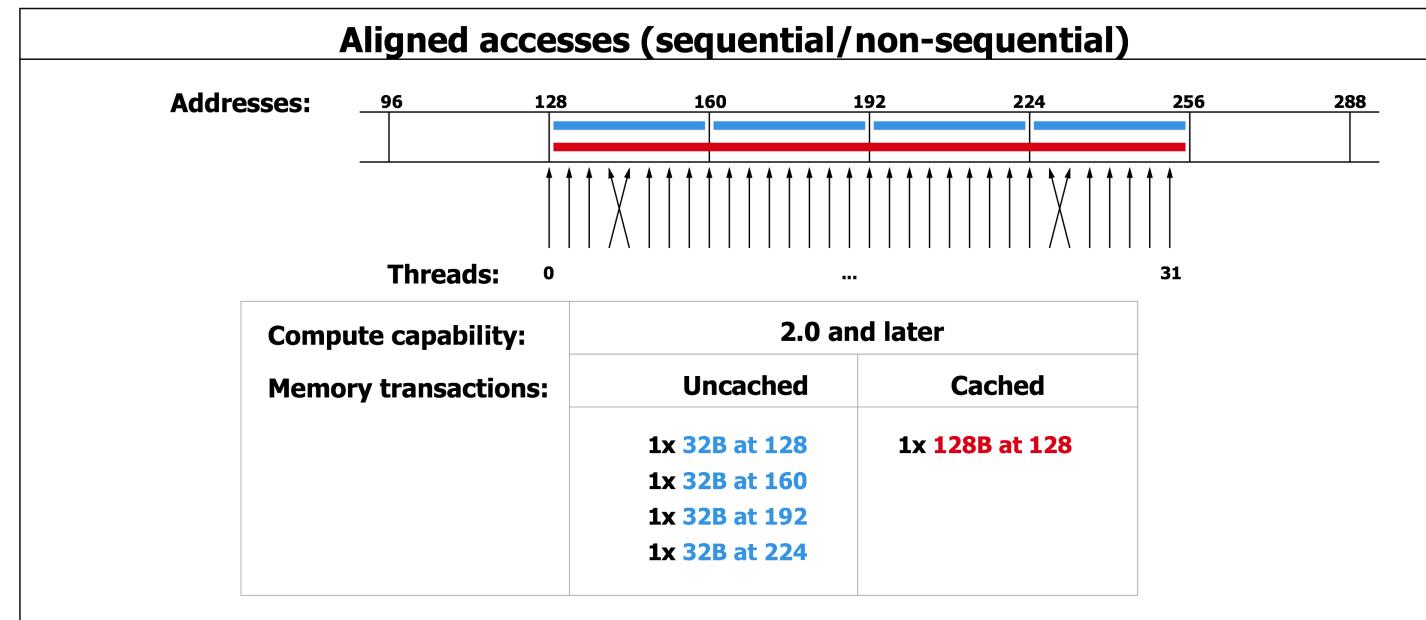
- Cache accesses to local and global memory
- Shared by all SMs on the GPU
- Memory accesses that are cached in L2 only are serviced with 32-byte memory transactions
- That's 8 float or 1 byte per thread in a warp
- If each thread reads a float, that's  $4 \times 32$ -bytes.

- Each memory request from a warp is broken down into cache line requests that are issued independently.
- A cache line request is serviced at the throughput of the L2 cache in case of a cache hit, or at the throughput of device memory, otherwise.

Let's make this concrete with a code

```
int xid = blockIdx.x * blockDim.x + threadIdx.x;  
if (xid < n)  
    odata[xid] = idata[xid];
```

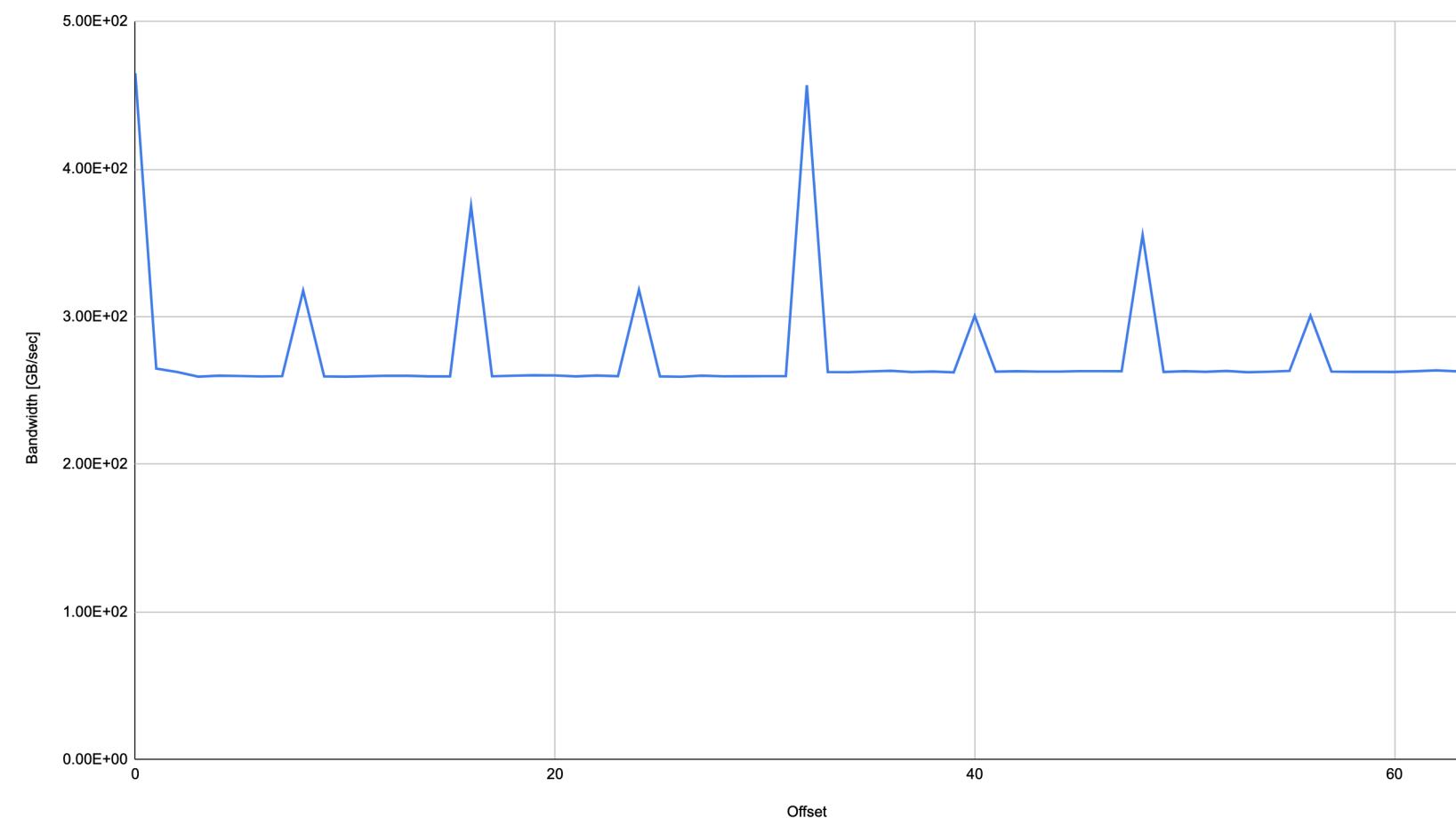
- Warp requests several memory addresses.
- These are translated into cache line requests (with a granularity of 32 bytes).
- Memory requests are serviced.
- **Coalesced access:** for every 32-byte cache line, all 32 bytes are requested and used by the warp.



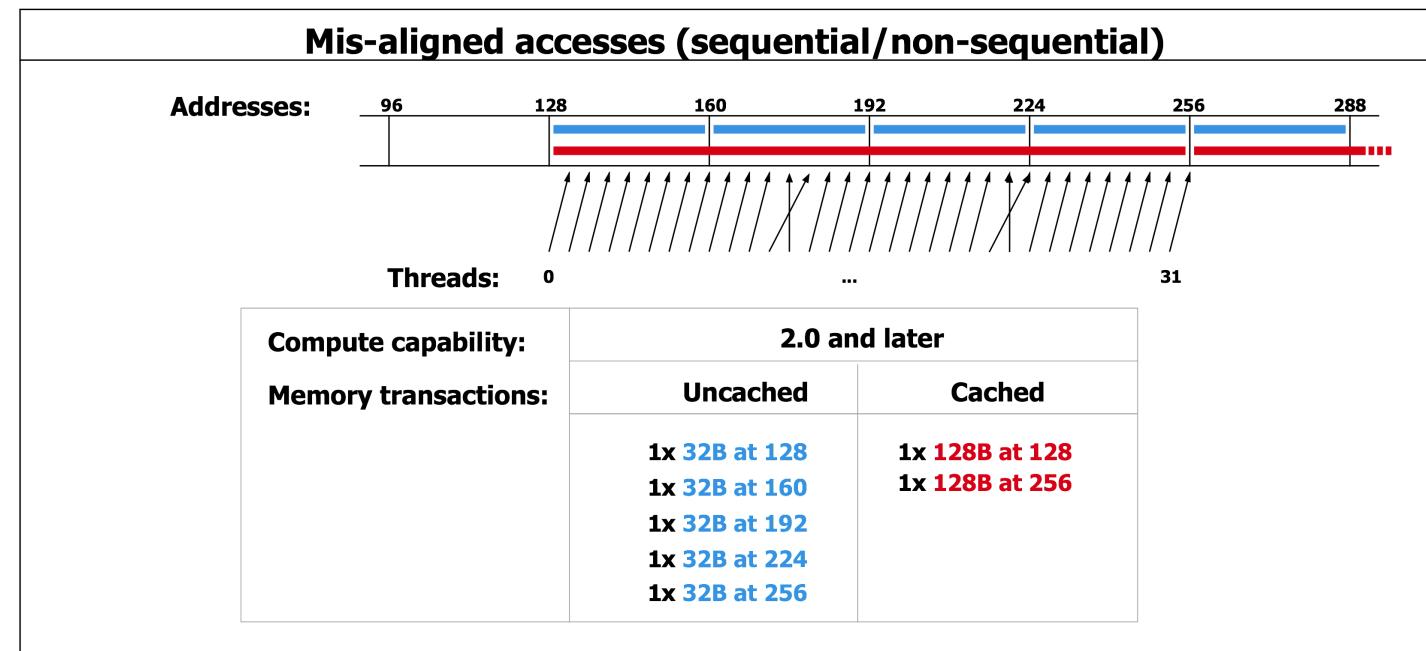
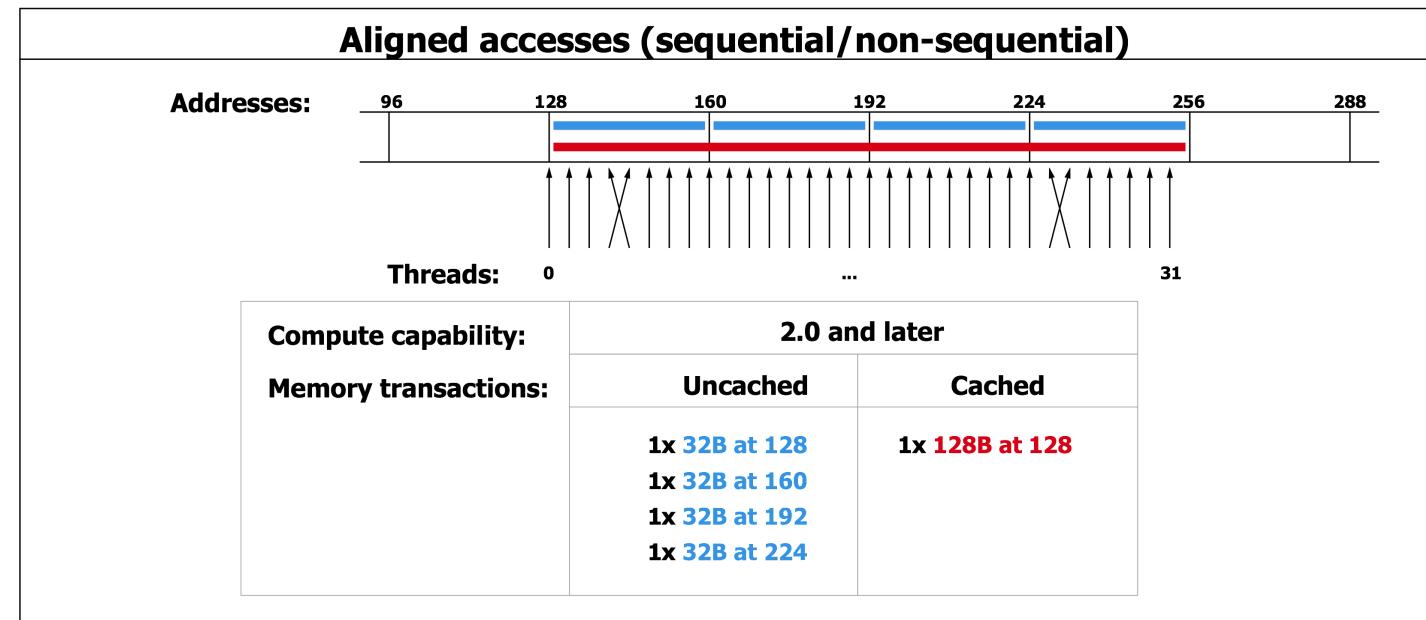
```
int xid = blockIdx.x * blockDim.x + threadIdx.x + offset;
if (xid < n)
    odata[xid] = idata[xid];
```

# Turing icme-gpu Quadro RTX 6000

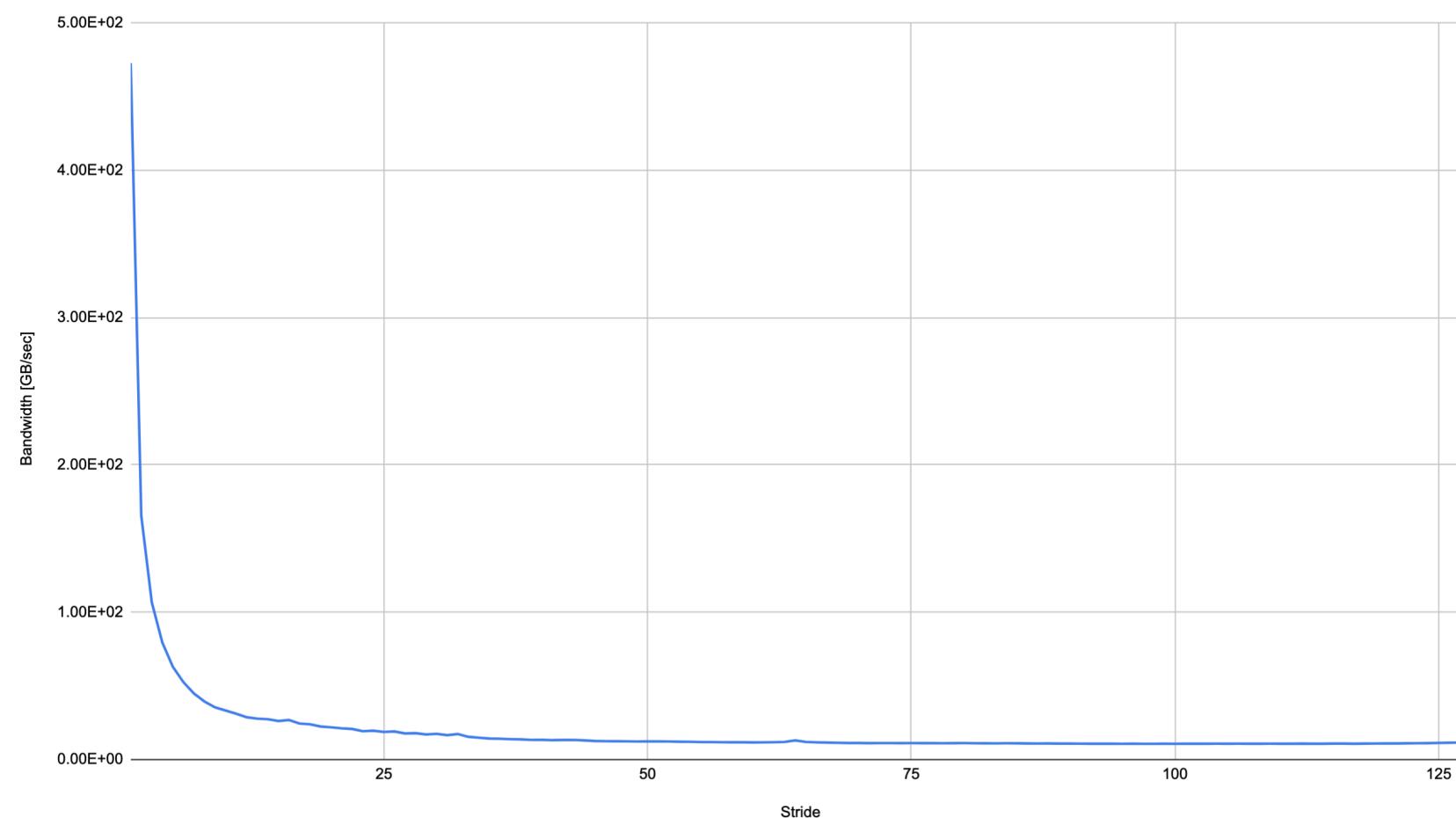
Bandwidth [GB/sec] vs. Offset



```
int xid = stride * (blockIdx.x * blockDim.x + threadIdx.x);
if (xid < n)
    odata[xid] = idata[xid];
```



Bandwidth [GB/sec] vs. Stride



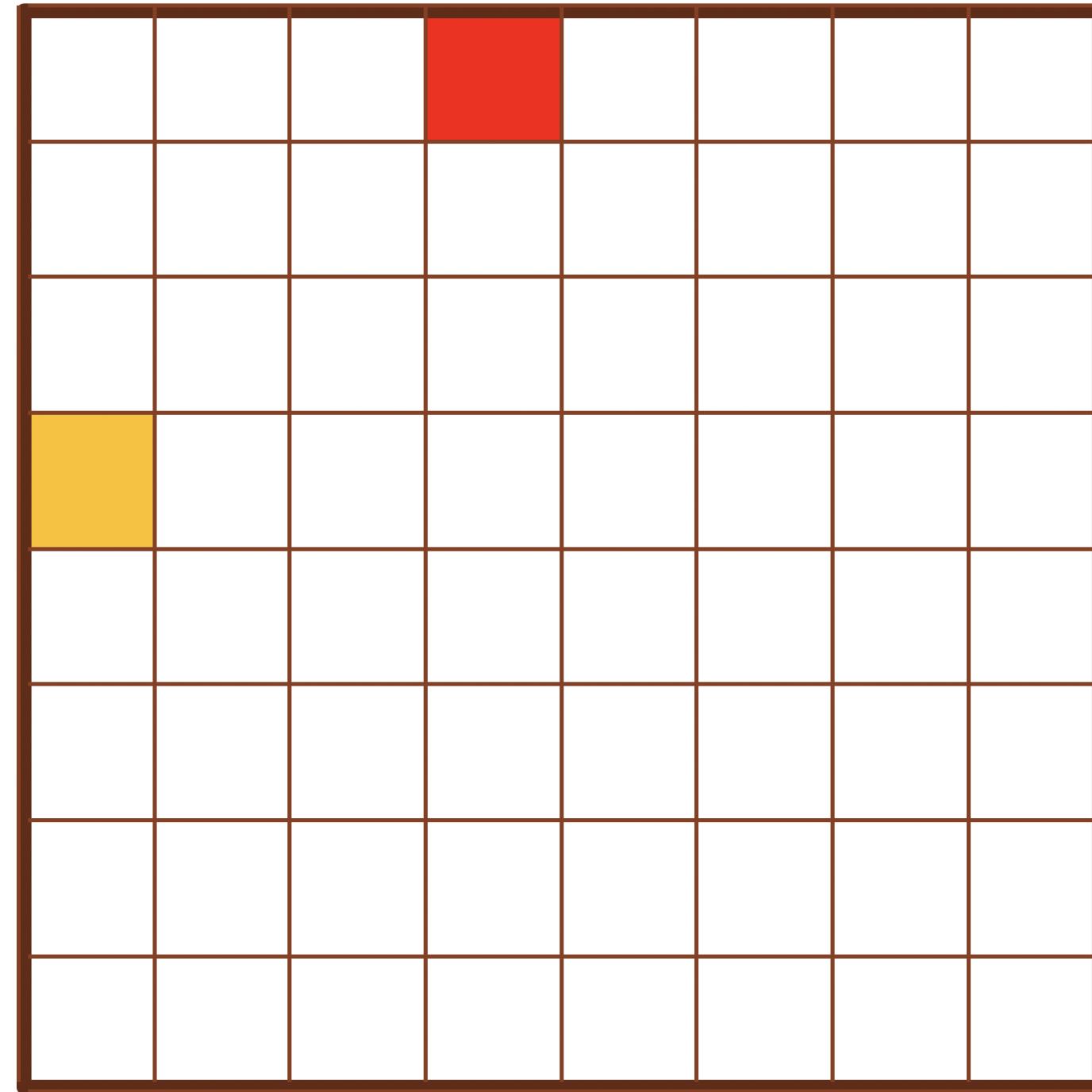
Memory	Location on/off chip	Cached	Access	Scope	Lifetime
Register	On	n/a	R/W	1 thread	Thread
Local	Off	Yes††	R/W	1 thread	Thread
Shared	On	n/a	R/W	All threads in block	Block
Global	Off	†	R/W	All threads + host	Host allocation
Constant	Off	Yes	R	All threads + host	Host allocation
Texture	Off	Yes	R	All threads + host	Host allocation

† Cached in L1 and L2 by default on devices of compute capability 6.0 and 7.x; cached only in L2 by default on devices of lower compute capabilities, though some allow opt-in to caching in L1 as well via compilation flags.

†† Cached in L1 and L2 by default except on devices of compute capability 5.x; devices of compute capability 5.x cache locals only in L2.

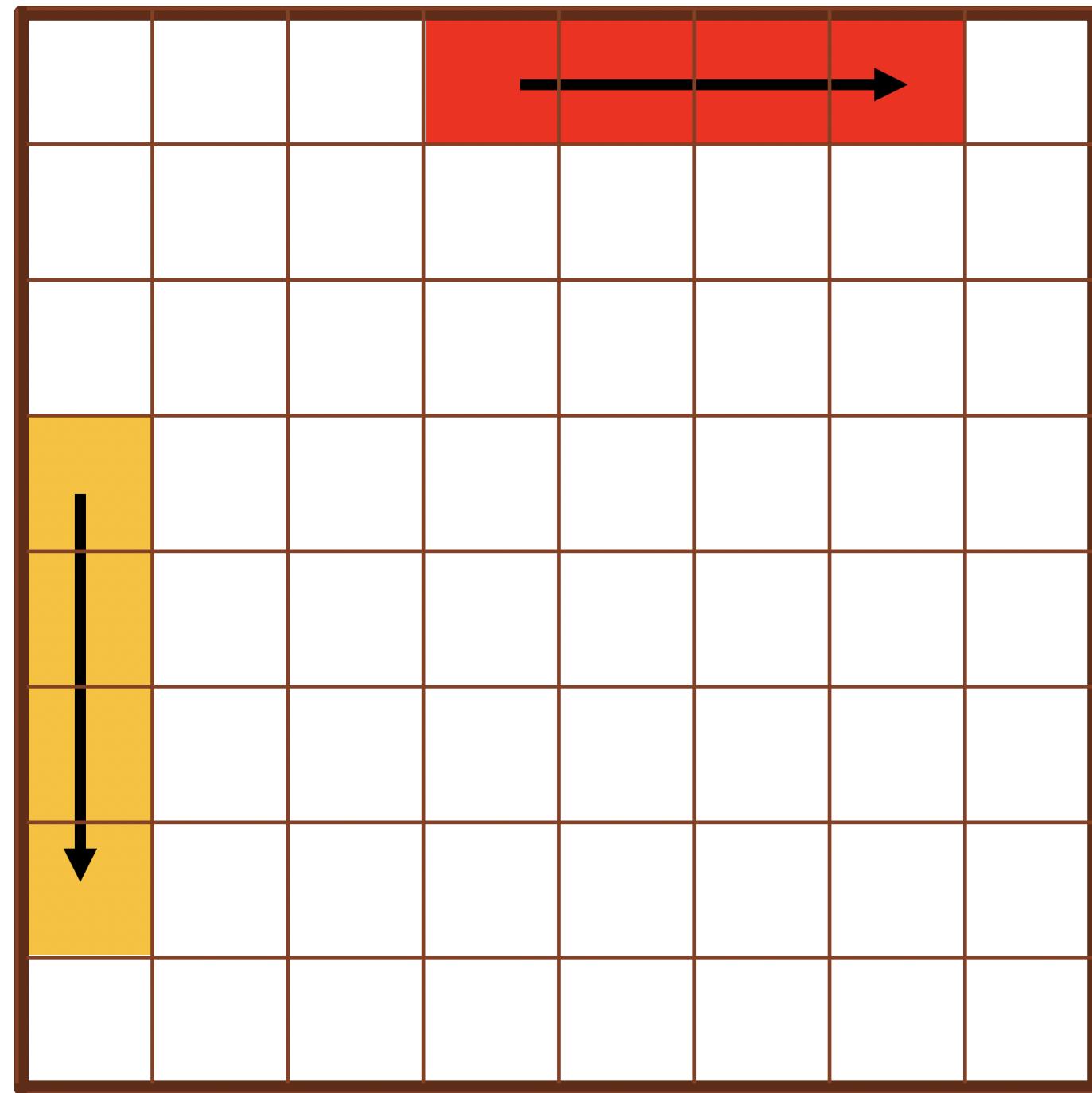
Let's put all these concepts into play through a specific example: a matrix transpose.

It's all about bandwidth!



Even for such a simple calculation, there are many optimizations.

```
const int tid = threadIdx.x + blockDim.x * blockIdx.x;
int col = tid % n_cols;
int row = tid / n_cols;
if(col < n_cols && row < n_rows) {
    array_out[col * n_rows + row] = array_in[row * n_cols + col];
}
```



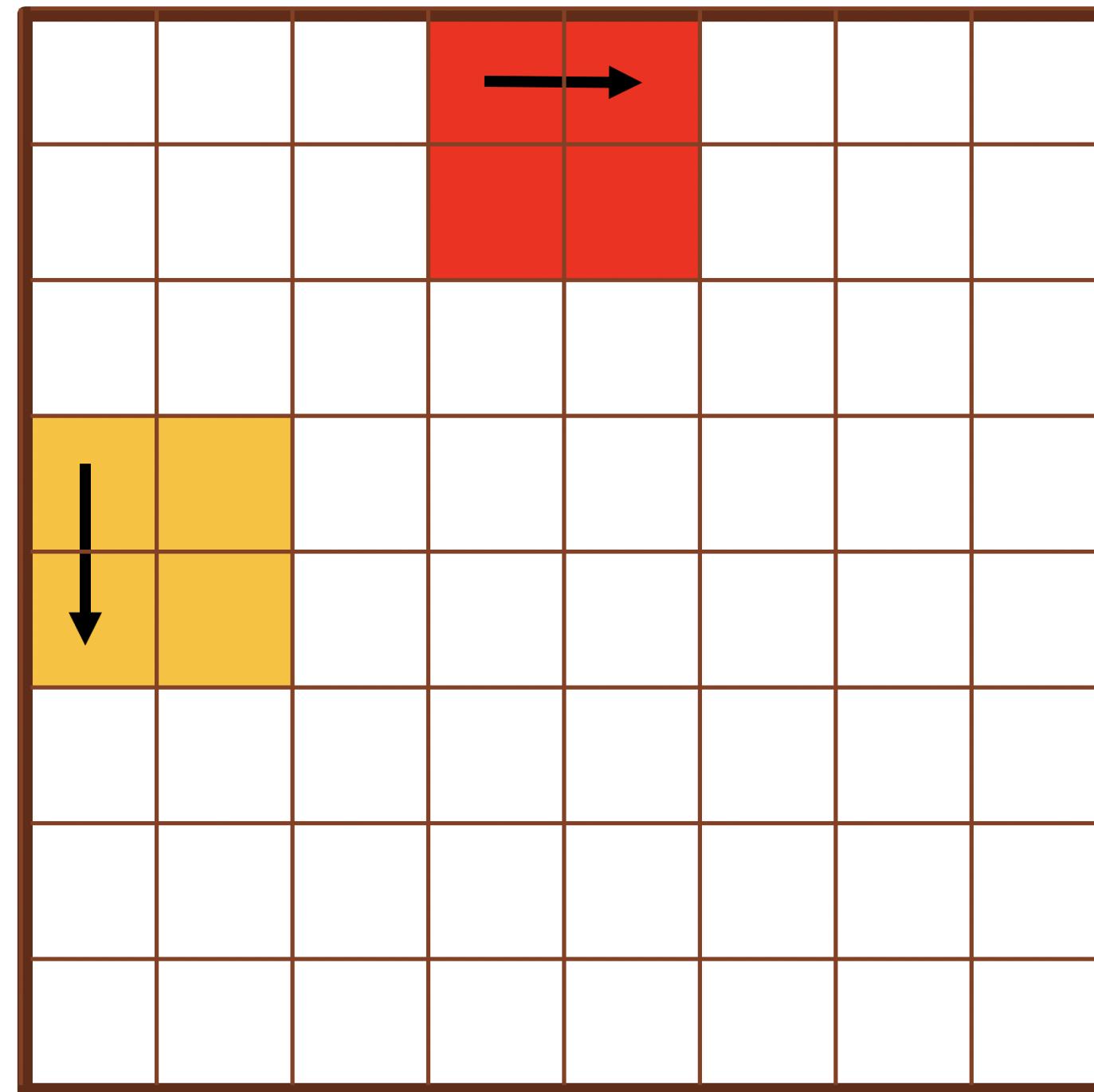


Read



Write

2D kernel



```
const int col = threadIdx.x + blockDim.x * blockIdx.x;
const int row = threadIdx.y + blockDim.y * blockIdx.y;

if(col < n_cols && row < n_rows) {
    array_out[col * n_rows + row] = array_in[row * n_cols + col];
}
```

```
dim3 block_dim(8, 32);
dim3 grid_dim(n / 8, n / 32);
```

For a given warp:

- column: 0 to 7
- row: 0 to 3



Read



Write



## Benchmark

```
darve@icme-gpu:~/\$ make; srun --partition=CME --gres=gpu:1 transpose
nvcc -O3 --gpu-architecture=compute_75 --gpu-code=sm_75 -o transpose transpose.cu
Number of MB to transpose: 4096
```

Bandwidth bench

GPU took 17.7267 ms

Effective bandwidth is 484.577 GB/s

simpleTranspose

GPU took 286.168 ms

Effective bandwidth is 30.0171 GB/s (almost 16x drop)

simpleTranspose2D

GPU took 30.8758 ms

Effective bandwidth is 278.209 GB/s

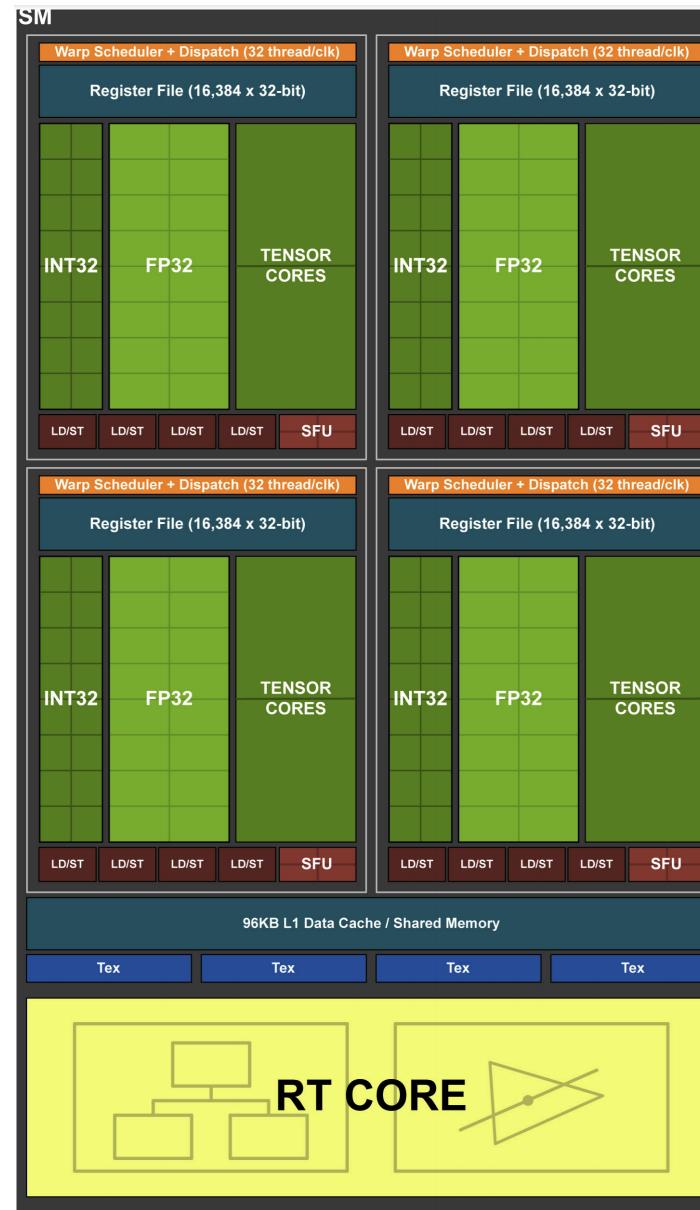
Can we reconcile read and write?



Load in fast **shared memory**

Transpose from **shared memory** is very fast!

## Shared memory



## Facts

On-chip: high bandwidth, low latency

Data in shared memory is only accessible by threads in the same thread block!

```
const int warp_id  = threadIdx.y;
const int lane     = threadIdx.x;

__shared__ int block[warp_size][warp_size];
```

lane: id of thread inside warp

block: variable allocated in shared memory

## Load data

```
int gc = bc * warp_size + lane; // Global column index
for(int i = 0; i < warp_size / num_warps; ++i) {
    int gr = br * warp_size + i * num_warps + warp_id; // Global row index
    block[i * num_warps + warp_id][lane] = array_in[gr * n_cols + gc];
}
__syncthreads();
```

## Store

```
int gr = br * warp_size + lane;  
  
for(int i = 0; i < warp_size / num_warps; ++i) {  
    int gc = bc * warp_size + i * num_warps + warp_id;  
    array_out[gc * n_rows + gr] = block[lane][i * num_warps + warp_id];  
}
```

## Performance

Bandwidth bench

GPU took **17.7267** ms

Effective bandwidth is **484.577** GB/s

simpleTranspose

GPU took **286.168** ms

Effective bandwidth is **30.0171** GB/s

simpleTranspose2D

GPU took **30.8758** ms

Effective bandwidth is **278.209** GB/s

fastTranspose

GPU took **29.64** ms

Effective bandwidth is **289.809** GB/s



Shared memory suffers from bank conflicts.

The shared memory is divided into equally-sized memory modules, called banks, which can be accessed simultaneously.

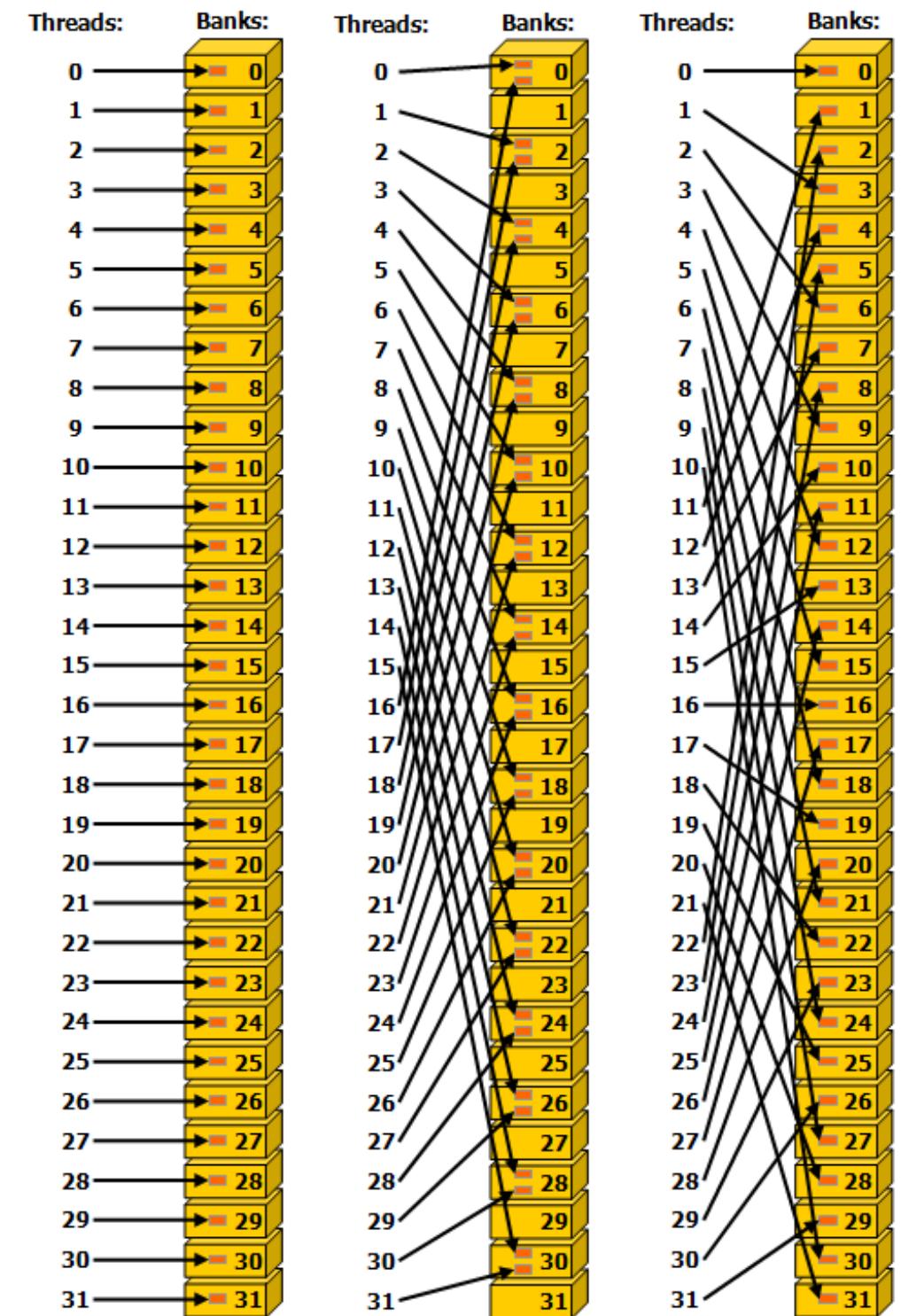


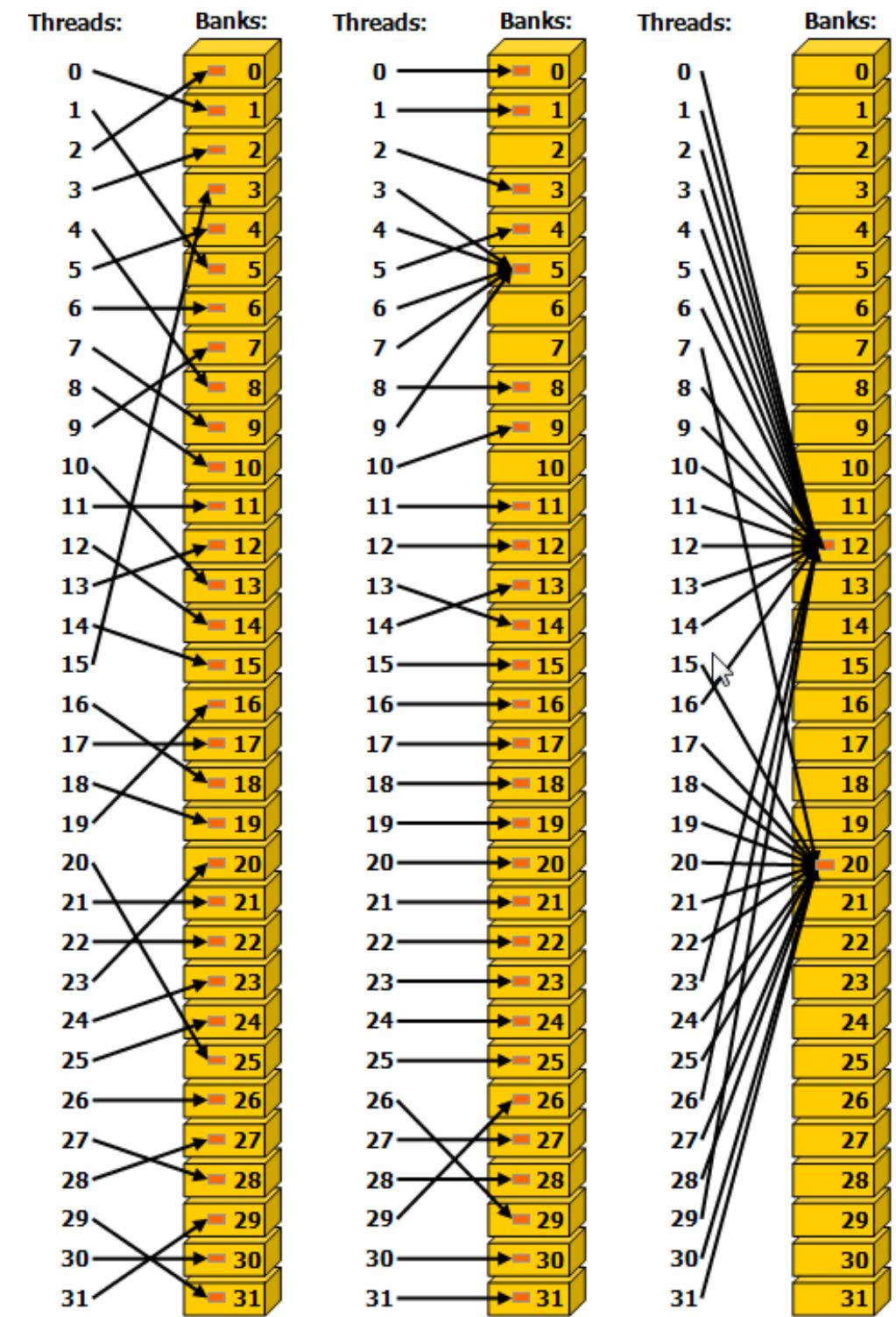
Any memory read or write request made of  $n$  addresses that fall in  $n$  distinct memory banks can be serviced simultaneously, yielding an overall bandwidth that is  $n$  times as high as the bandwidth of a single module.



If two addresses of a memory request fall in the same memory bank, there is a bank conflict and the access has to be serialized.

Each bank has a bandwidth of 4 bytes per two clock cycles.





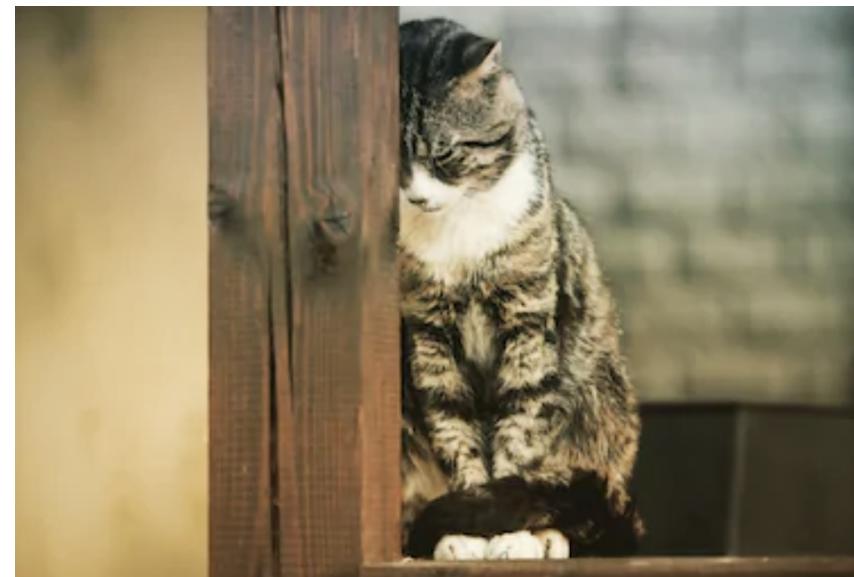
```
block[i * num_warps + warp_id][lane] = array_in[gr * n_cols + gc];
```

Stride of 1

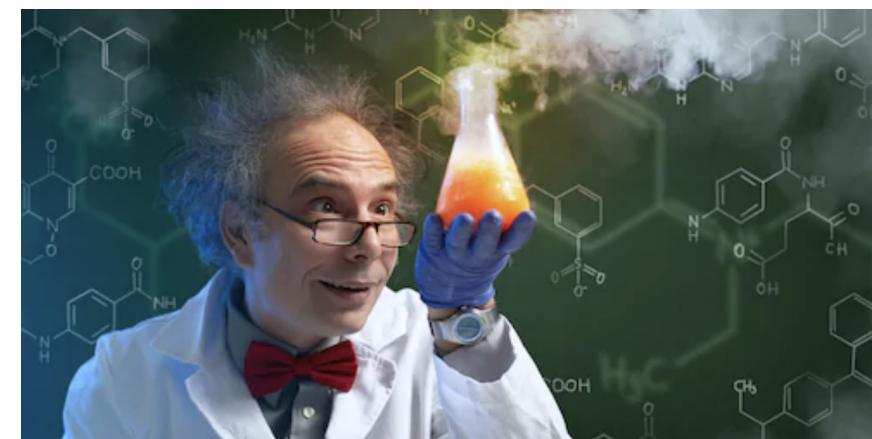


```
array_out[gc * n_rows + gr] = block[lane][i * num_warps + warp_id];
```

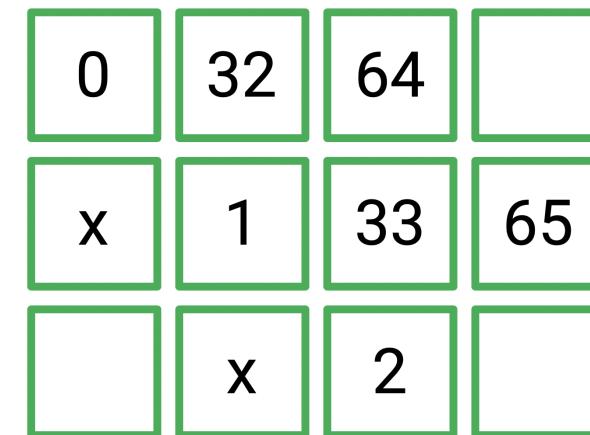
Stride of 32



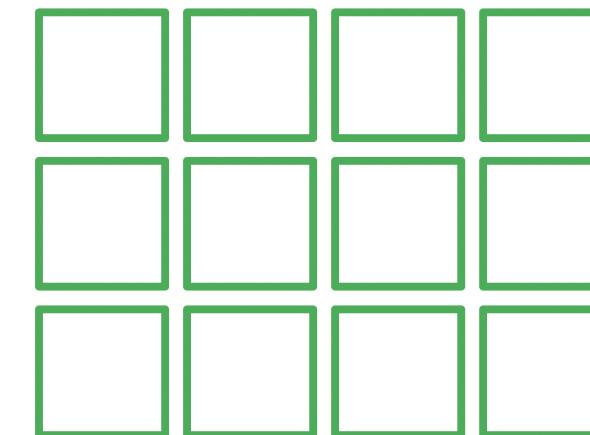
The cure!



```
__shared__ int block[warp_size][warp_size+1];
```



...



...

...

```
array_out[gc * n_rows + gr] = block[lane][i * num_warps + warp_id];
```

## fastTranspose

Bandwidth bench

GPU took **17.7381** ms

Effective bandwidth is **484.263** GB/s

simpleTranspose

GPU took **286.166** ms

Effective bandwidth is **30.0173** GB/s

simpleTranspose2D

GPU took **29.9896** ms

Effective bandwidth is **286.431** GB/s

fastTranspose

GPU took **24.389** ms

Effective bandwidth is **352.205** GB/s